Non-Commutative Optimization

Peter Bürgisser

IPAM workshop IV: Efficient Tensor Representations for Learning and Computational Complexity

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based on joint work with Cole Franks, Ankit Garg, Rafael Oliveira, Michael Walter, Avi Wigderson ITCS 2018, FOCS 2018, FOCS 2019

Full version at arXiv:1910.12375, ca. 100 pages







General setting

Tensor Action (main example): Action of group $G = \operatorname{SL}_{m_1} \times \cdots \times \operatorname{SL}_{m_p}$ on space of tensors $V = \mathbb{C}^{m_1} \otimes \cdots \otimes \mathbb{C}^{m_p}$ via tensor product

Baby example: conj. action of $G = GL_n$ on $V = \mathbb{C}^{n \times n}$, $\pi(g)(A) = gAg^{-1}$

General setting:

- Algebraic subgroup G ≤ GL_n closed under g → g^{*} (complex reductive group), e.g., T_n := (C^{*})ⁿ, GL_n, SL_n or products
- Regular representation π: G → GL(V) on f.d. C-Hilbert space V: G acts on V by linear transformations
- Maximal compact subgroup $K = G \cap U_n$ of G
- Assume K acts isometrically on V
- Orbit $Gv := \{\pi(g)v \mid g \in G\}$ of $v \in V$ has closure \overline{Gv}

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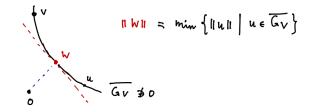
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Norm minimization

For given v ∈ V (approximately) compute g ∈ G such that π(g)v has minimal norm:

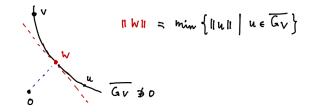


• Capacity of v: $cap(v) \coloneqq inf_{g \in G} ||\pi(g)v||$

- Conj. of matrices: diagonal matrix w with same eigenvalues as v minimizes norm
- Shortest vector w is uniquely determined up to unitary action (Kempf-Ness 1978)

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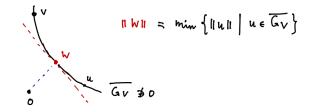
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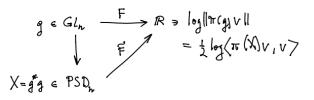
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Geodesic convexity

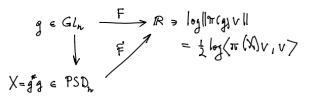
- Use techniques from convex optimization on Riemannian manifolds
- Riemannian geometry induced by Lie group symmetry
- For simplicity: $G = GL_n, K = U_n$
- Want to minimize $F_{v}: G \to \mathbb{R}, g \mapsto \log \|\pi(g)v\|$



- Cone PSD_n of hermitian psd matrices has natural Riemannian metric (invariant under conjugation)
- ▶ Induced map \tilde{F}_{v} : $PSD_{n} \to \mathbb{R}, X \mapsto \frac{1}{2} \log \langle \pi(X)v, v \rangle$ is geodesically convex (implicit in Kemp-Ness 1978)

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We want to minimize

$$F_{v}: G \to \mathbb{R}, g \mapsto \log \|\pi(g)v\|$$

- ▶ Consider derivative or gradient $\mu(v) \in \text{Lie}(G) \subseteq \mathbb{C}^{n \times n}$ at $g_0 = I$ of F_v
- Conj. of matrices: $\mu(A) = ||A||_F^{-2}(AA^* A^*A)$
- ▶ Tensor action: for $v \in \mathbb{C}^{m_1} \otimes \cdots \otimes \mathbb{C}^{m_p}$, have $\mu(v) = (\rho_1, \dots, \rho_p)$, where $\rho_k = \operatorname{tr}_k(vv^*) \in \mathbb{C}^{m_i \times m_i}$ is *k*th partial trace, e.g.,

$$(\rho_1)_{ij} = \sum_{i_2,\ldots,i_p} v_{ii_2\ldots i_p} \overline{v}_{ji_2\ldots i_p}.$$

- Dual norm minimization: For given v ∈ V (approximately) compute g ∈ G such that ||μ(π(g)v)||_F has minimal norm
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Developed gradient descent algorithm: given v ∈ V such that cap(v) > 0, it outputs g ∈ G such that ||µ(π(g)v)||_F ≤ ε, with number of iterations

$$\frac{4N(\pi)^2}{\varepsilon^2}\log\frac{\|v\|}{\operatorname{cap}(v)}$$

• Hilbert associated with a representation π its null cone

 $\mathscr{N}(\pi) \coloneqq \{ v \in V \mid \operatorname{cap}(v) = 0 \} = \{ v \in V \mid 0 \in \overline{Gv} \}$

- Can use above algorithm for testing membership to the null cone.
- This is a special case of moment polytope membership problem, of relevance in quantum information theory.
- Developed and analyzed gradient descent algorithm for *p*-scaling and deciding (approximate) membership to moment polytopes.

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Algorithm for deciding null cone membership

• We shall identify gap parameters $\gamma(\pi)$ and $c(\pi)$ such that

$$\forall v \in V \setminus 0 \quad \operatorname{cap}(v) = 0 \Longrightarrow \inf_{g \in G} \|\mu(\pi(g)v)\|_F \ge \gamma(\pi)$$

$\forall v \in V(\mathbb{Z}[i]) \quad \operatorname{cap}(v) > 0 \Longrightarrow \operatorname{cap}(v) \ge c(\pi)$

- ▶ Run gradient descent on v for $T = \frac{16N(\pi)}{\gamma(\pi)^2} \log\left(\frac{\|v\|}{c(\pi)}\right)$ iterations, producing g_1, \ldots, g_T .
- ▶ If $\|\mu(\pi(g_t)v)\|_F \leq \frac{1}{2}\gamma(\pi)$ for some $t \leq T$, then output "cap(v) > 0". Otherwise, output "cap(v) = 0".

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Critical complexity parameter

• Gradient descent decides membership to null cone with # iterations

$$T = \frac{16N(\pi)}{\gamma(\pi)^2} \log\left(\frac{\|\mathbf{v}\|}{c(\pi)}\right)$$

- ▶ # iterations is poly bounded in weight norm $N(\pi) \leq \text{degree}$, $\log ||v||$, $\log c(\pi)^{-1}$, and $\gamma(\pi)^{-1}$.
- ▶ Thm. log $c(\pi)^{-1} \le poly(m, n, d)$ for homogeneous polynomial representations π : SL $(n) \rightarrow$ GL(m) of degree d, e.g., when π given in Gelfand-Tsetlin basis.
- Proof based on deep general results from invariant theory: (1)
 Derksen's general degree bound for a system of generators of ring of invariants. (2) Analysis of Cayley's Ω-process for SL_n.
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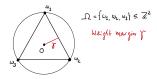
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Weight margin

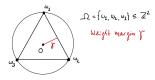
- Can cleanly identify a dual gap parameter $\gamma(\pi)$
- For simplicity assume $G = GL_n$ or $G = T_n$
- Let $\Omega(\pi) \subseteq \mathbb{Z}^n$ be the set of weights of π
- Define the weight margin γ(π) as the minimum distance between 0 and the convex hull of any subset of Ω(π) which does not contain 0



- **Prop.** The weight margin $\gamma(\pi)$ is a dual gap parameter.
- Thm. GL-representations of quivers (e.g. L/R action) have inverse polynomial lower bounds for γ(π). (Key insight: totally unimodular matrix of weights.) Scaling algorithm for null cone is poly time.
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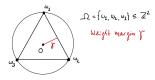
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Quantitative duality

Thm.
For
$$v \in V \setminus 0$$
 we have
$$1 - \frac{\|\mu(v)\|_F}{\gamma(\pi)} \leq \frac{\operatorname{cap}(v)^2}{\|v\|^2} \leq 1 - \frac{\|\mu(v)\|_F^2}{4N(\pi)^2}$$

This again shows " $\mu(v) = 0 \Rightarrow ||v|| = cap(v)$ ", but turns this into a quantitative statement.

Another consequence: weight margin indeed gives dual gap. If cap(v) = 0, then

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• Simultaneous LR-action: $G = SL_n \times SL_n$ acts on $V = (\mathbb{C}^{n \times n})^m$:

$$\pi(g,h)(A_1,\ldots,A_m) \coloneqq (gA_1h^T,\ldots,gA_mh^T)$$

- Alternating minimization algorithm by [Gurvits 2004)], generalizing Sinkhorn's algorithm, shown to be poly time in [Garg, Gurvits, Oliveira, Wigderson 2016] using invariant theory
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Second order algorithm

Generalize [Allen-Zhu, Garg, Li, Oliveira, Wigderson 18] from L/R action.

For given $v \in V \setminus 0$ and $\kappa, \varepsilon > 0$, add to F_v a regularizing term $F(g) := F_v(g) + \frac{\varepsilon}{\kappa} \operatorname{reg}(g)$, where $\operatorname{reg}(g) := \|g\|_F^2 + \|g^{-1}\|_F^2$ upper bounds condition number $\kappa_F(g) \le \operatorname{reg}(g)$. **Algorithm:**

▶ Set *g*₀ = *I*.

• For
$$t = 0, ..., T - 1$$
:

- Compute the geodesic gradient L := ∇F(gt) and Hessian Q := ∇²F(gt) at gt.
- Solve the following (Euclidean) convex quadratic optimization problem:

$$H_t := \operatorname{argmin} \left\{ \operatorname{tr}[LH] + \frac{1}{2e} \operatorname{tr}[Q(H \otimes H)] : H \in i \operatorname{Lie}(K), \, \|H\|_F \leq \frac{1}{4N(\pi)} \right\}$$

3 Set
$$g_{t+1} \coloneqq e^{H_t/e^2}g_t$$
.

Return *g*_{*T*}.

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For given $v \in V \setminus 0$ and $\kappa, \varepsilon > 0$, add to F_v a regularizing term $F(g) \coloneqq F_v(g) + \frac{\varepsilon}{\kappa} \operatorname{reg}(g)$, where $\operatorname{reg}(g) \coloneqq \|g\|_F^2 + \|g^{-1}\|_F^2$ upper bounds condition number $\kappa_F(g) \le \operatorname{reg}(g)$.

Algorithm

• Set $g_0 = I$.

- Ocompute the geodesic gradient L := ∇F(gt) and Hessian Q := ∇²F(gt) at gt.
- Solve the following (Euclidean) convex quadratic optimization problem:

$$H_t := \operatorname{argmin} \left\{ \operatorname{tr}[LH] + \frac{1}{2e} \operatorname{tr}[Q(H \otimes H)] : H \in i \operatorname{Lie}(K), \, \|H\|_F \leq \frac{1}{4N(\pi)} \right\}$$

3 Set
$$g_{t+1} \coloneqq e^{H_t/e^2}g_t$$
.

Return *g*_{*T*}.

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Algorithm:

Set g₀ = 1.

- Compute the geodesic gradient L := ∇F(g_t) and Hessian Q := ∇²F(g_t) at g_t.
- Solve the following (Euclidean) convex quadratic optimization problem:

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3 Set
$$g_{t+1} \coloneqq e^{H_t/e^2}g_t$$

• Return g_T .

Analysis of second order algorithm

- Assume cap(v) > 0 and put C := log(||v||/cap(v)).
- Suppose there is a well-conditioned approximate minimizer g_* s.t.

$$\log \|\pi(g_\star)v\| \leq \log \operatorname{cap}(v) + \varepsilon, \quad \operatorname{reg}(g_\star) \leq \kappa.$$

Then the second order algorithm, with #iterations

$$T \ge 8e^2 N(\pi) \sqrt{n} \left(\log \kappa + \log \left(1 + \frac{C}{\varepsilon} \right) \right) \log \left(\frac{C}{\varepsilon} \right)$$

returns a group element $g \in G = \operatorname{GL}_n$ such that

$$\log \|\pi(g)v\| \le \log \operatorname{cap}(v) + 3\varepsilon.$$

- Show existence of well-conditioned approximate minimizer by analyzing the flow of gradient vector field of G → ℝ, g ↦ ¹/₂ ||π(g)v||².
- Obtain running time polynomial in $\gamma(\pi)^{-1}$, $\log \varepsilon^{-1}$, while gradient descent had polynomials dependence on ε^{-1} .
- Due to γ(π)⁻¹ dependence still don't get poly time for null cone membership.

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- Show existence of well-conditioned approximate minimizer by analyzing the flow of gradient vector field of G → ℝ, g ↦ ¹/₂ ||π(g)v||².
- Obtain running time polynomial in γ(π)⁻¹, log ε⁻¹, while gradient descent had polynomials dependence on ε⁻¹.
- Due to γ(π)⁻¹ dependence still don't get poly time for null cone membership.

Open problems

- Is the null cone membership problem for general group actions in P? E.g., for tensor action?
- Intermediate goal: in NP \cap coNP?
- Same question may be asked about the moment polytope membership problem for general group actions. Note that membership in "global moment polytopes" is known to be in NP ∩ coNP [BCMW17].
- In the non-commutative case, our algorithms' guarantees do not match those of ellipsoid or interior point methods.
- Can we extend non-commutative/geodesic optimization to include interior point methods? (Possible in the commutative case [B, Li, Nieuwboer, Walter 2020].)
- Can geodesic optimization lead to new efficient algorithms in combinatorial optimization?

Non-Commutative Optimization

Thank you for listening