

# Bending admissible continuum approximation for mono-layered 2D materials

Xingjie Helen Li

University of North Carolina at Charlotte

Presenting at: IPAM: Theory and Computation for 2D Models 2020

Collaborators: Julian Braun (University of Warwick, UK)  
Derek Olson (Rensselaer Polytechnic Institute)

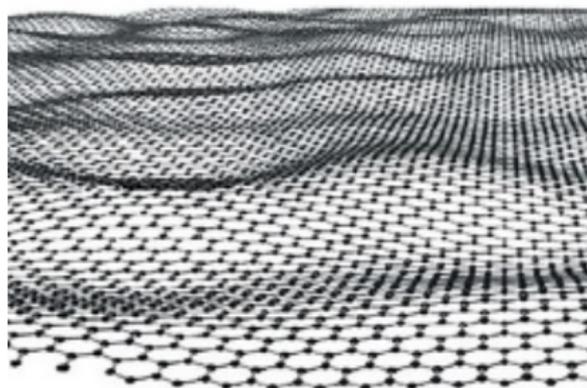
Jan 14, 2020

# Outline

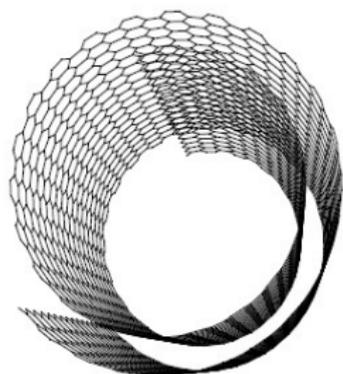
- Motivation: non-flat configuration
- Continuum model: von-Kármán for mono-layered system
  - assumptions on the empirical atomistic energy
  - scaling rules of the displacement fields
  - appropriate norm that reflects the observed stability
- Stability and error analysis
  - linear stability analysis
  - force consistency analysis
  - displacement fields error estimate
- Ongoing work
- Summary

# Experimental observations

Graphene is locally two-dimensional but **not flat**. Nanoscale **ripples** appear in suspended samples and **rolling up** often occurs when boundaries are not fixed. <sup>1 2</sup>



(a) Ripple<sup>3</sup>



(b) Rolling up<sup>4</sup>

**Need an appropriate continuum model for multiscale modelings.**

<sup>1</sup>Novoselov et. al. Nature, 446, 60-63, (2007)

<sup>2</sup>U. Stefanelli, et. al. U. Z. Angew. Math. Phys. 69:70, (2018)

<sup>3</sup>Deng and Berry, Materials Today, Volume 19 (4), (2016)

<sup>4</sup>P. Lambin et. al. Applied Sciences, 4, 282-304, (2014)

# A few existing continuum models

- **Based on Cauchy–Born rule**

- Exponential Cauchy–Born rule; <sup>5</sup>
- High order Cauchy–Born rule. <sup>6 7</sup>

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<sup>6</sup>Yang and E, PRB 74, 184110, (2006)

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<sup>9</sup>Yang and Tewary, PRB 77, 245442, (2008)

<sup>10</sup>Xiaojie Wu and Xiantao Li, manuscript

<sup>11</sup>Nelson et al. *Int J Numer Meth Eng* 30, 517-539, (1990)

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- Iterative method by using force corrections;<sup>8</sup>
- Discrete lattice Green function and obtain the linear **Kirchhoff plate** theory for the far-field considering a point defect/ point force loading.<sup>9 10</sup>

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For example, using the **von-Kármán plate** theory.<sup>11 12</sup>

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Some of them **do not target for modeling ripples.**

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# Literatures related to the von-Kármán theory

- **Applicational point of view:** The von-Kármán has been used for modeling and computational simulations of **ripples and wrinkles**, see for example, Kumar et. al. (2015)<sup>13</sup> and Gao et. al. (2019).<sup>14</sup>

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<sup>14</sup>Gao et. al. Handbook of Graphene: 2, 1-44, (2019)

<sup>15</sup>Braun et. al. arXiv:1907.00197, (2019)

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- **Multilayered graphene system:** Braun et. al. rigorously derived the von-Kármán model via analyzing scaling of energy in terms of the **lattice constant  $\varepsilon$**  and **the layer distance  $h$** .<sup>15</sup>
- **Continuum plate theories:** Friesecke et. al. rigorously studied different plate models by scaling of the elastic energy per unit volume in terms of the thickness  $h$  of plates<sup>16</sup>
  - $f^{\text{ext}}$  and total energy  $\sim h^2$ : Kirchhoff plate
  - $f^{\text{ext}}$  and total energy  $\sim h^4$ : von-Kármán plate
  - general case with external force  $\sim h^\alpha$  with  $\alpha > 0$ , summarized in Table 1 of Friesecke et. al. (2006)

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# Goal

- 1 Rigorously derive the continuum von-Kármán model which captures the governing out-of-plane rippling type deformations in a mono-layered system.
- 2 Prove rigorous stability and error analysis.

# Problem setup and notations



- Consider a simple lattice with reference configuration

$$\mathcal{L} := \varepsilon F \mathbb{Z}^d, \text{ for some } F \in \mathbb{R}^{d \times d}, \det(F) = 1, d \in \{1, 2\},$$

where  $\varepsilon$  is the lattice constant. It is deformed into  $\mathbf{y} : \mathcal{L} \rightarrow \mathbb{R}^{d+1}$ .

- For simplicity, consider a 1D periodic chain of  $N \in \mathbb{N}$  atoms. Assume  $\varepsilon N = 1$ , thus the reference atomic chain is  $\mathcal{L} = (0, 1]$ . Denote the physical displacement field by  $\mathbf{u} : \mathcal{L} \rightarrow \mathbb{R}^2$  where

$$\mathbf{u}(\varepsilon i) := \mathbf{y}(\varepsilon i) - \begin{pmatrix} \varepsilon i \\ 0 \end{pmatrix} = \begin{pmatrix} u_1(\varepsilon i) \\ u_2(\varepsilon i) \end{pmatrix} = \begin{pmatrix} u_{i,1} \\ u_{i,2} \end{pmatrix}.$$



# Atomistic energy

The total atomistic energy for 1D chain is

$$E^a(\mathbf{y}) = E_{pp}^a(\mathbf{y}) + E_{ap}^a(\mathbf{y}) = \varepsilon \sum_{i=1}^N \left[ V \left( \frac{|\mathbf{y}_{i+1} - \mathbf{y}_i|}{\varepsilon} \right) + f(\theta_i) \right].$$

$E_{pp}^a$  denotes the **pairwise potential** and  $E_{ap}^a$  denotes the **angular potential**.

We assume the following properties:

- $V(s)$  **behaves like a quadratic function**, it reaches local minimum at  $s = 1$  with  $V(1) = V'(1) = 0$  and  $V''(1) > 0$ ;
- $\theta_i := \theta(i)$  measures the angle between vector  $\{\mathbf{y}_i - \mathbf{y}_{i-1}\}$  and vector  $\{\mathbf{y}_{i+1} - \mathbf{y}_i\}$  and  $0 < \theta_i \ll 1$ ;
- $f(\theta)$  denotes the angular potential **that also behaves like a quadratic function** with local minimum at  $\theta = 0$ , and  $f(0) = f'(0) = 0$ ,  $f''(0) > 0$ ,  $f(\theta) \approx \theta^2$  when  $0 < \theta \ll 1$ .

# Scaling of displacement field

- Total energy is scaled as  $\sim \varepsilon^4$  for the von-Kármán plate:

$$E^a(\mathbf{y}) \leq C\varepsilon^4.$$

We then proved that the deformed configuration  $\mathbf{y}$  is close to a rigid motion:  $\mathbf{x} \rightarrow R(\mathbf{x} + \mathbf{c})$ , where  $\mathbf{c}$  denotes a translation and  $R$  denotes a rotation.

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- Hence, the displacement field  $\mathbf{u}$  must be scaled as

$$\mathbf{u} = \begin{pmatrix} u_1 \\ u_2 \end{pmatrix} = \begin{pmatrix} \varepsilon^2 \tilde{u}_1 \\ \varepsilon \tilde{u}_2 \end{pmatrix},$$

where  $\tilde{u}_1, \tilde{u}_2$  are scalar functions and are independent of  $\varepsilon$ .

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where  $\tilde{u}_1, \tilde{u}_2$  are scalar functions and are independent of  $\varepsilon$ .

- Hence  $\frac{1}{\varepsilon^4} E^a$  is  $\Gamma$ -convergent to the von-Kármán energy as  $\varepsilon \rightarrow 0$

$$E^c(\hat{\mathbf{u}}) = E^c(\hat{u}_1(x), \hat{u}_2(x)) = \int_0^1 \left[ \frac{1}{2} V''(1) \left( \hat{u}'_1(x) + \frac{1}{2} (\hat{u}'_2(x))^2 \right)^2 + \frac{1}{2} f''(0) (\hat{u}'_2(x))^2 \right] dx.$$

$\hat{u}_1(x)$  and  $\hat{u}_2(x)$  are smooth interpolation of the scaled displacements  $\tilde{u}_1$  and  $\tilde{u}_2$  from  $\mathcal{L} \rightarrow \mathbb{R}$ .

# Appropriate norm for the observed stability

Define the first order differentiation operator

$$D_1^\epsilon v_\ell = \frac{v_{\ell+1} - v_\ell}{\epsilon},$$

and the second order differentiation operator

$$D_1^{(2),\epsilon} v_\ell = \frac{D_1^\epsilon v_\ell - D_1^\epsilon v_{\ell-1}}{\epsilon} = \frac{v_{\ell+1} - 2v_\ell + v_{\ell-1}}{\epsilon^2}$$

For a **physical displacement field**  $\mathbf{u}$ , the semi-norm is defined as

$$\|\mathbf{u}\|_*^2 := \|D_1^\epsilon u_1\|_{\ell_\epsilon^2}^2 + \epsilon^2 \|D_1^{(2),\epsilon} u_2\|_{\ell_\epsilon^2}^2,$$

where for any scalar function  $v$

$$\|v\|_{\ell_\epsilon^2}^2 = \epsilon \sum_{i=1}^N |v_i|^2.$$

For a **continuum scaled displacement field**  $\hat{\mathbf{u}}$ , the semi-norm is defined as

$$\|\hat{\mathbf{u}}\|_{*c}^2 := \int_0^1 [(\hat{u}'_1)^2 + (\hat{u}''_2)^2] dx.$$

# Linear stability

- The atomistic model is linear stable wrt to the  $\|\cdot\|_*$ :

$$\langle \delta^2 E^a(\mathbf{0})\mathbf{v}, \mathbf{v} \rangle \geq \gamma^a \|\mathbf{v}\|_*^2.$$

- The continuum model is linear stable wrt to the  $\|\cdot\|_{*^c}$ :

$$\langle \delta^2 E^c(\mathbf{0})\hat{\mathbf{v}}, \hat{\mathbf{v}} \rangle \geq (1 + \varepsilon^2)\gamma^a \|\hat{\mathbf{v}}\|_{*^c}^2.$$

- Consequently, both atomistic and continuum models are linear stable and with similar stability constants.

# Approximation error

## Approximation error in terms of energy difference.

- Applying Taylor expansion to the atomic site energy of site  $i$ :  
Pair interaction:

$$\begin{aligned}V(\mathbf{u}_i) &= V\left(\sqrt{(1 + D_1^\varepsilon u_{i,1})^2 + (D_1^\varepsilon u_{i,2})^2}\right) \\&\approx \frac{1}{2}V''(1)\left(D_1^\varepsilon u_{i,1} + \frac{1}{2}(D_1^\varepsilon u_{i,2})^2\right)^2 + O(\varepsilon^6) \\&= \varepsilon^4 \frac{1}{2}V''(1)\left(D_1^\varepsilon \tilde{u}_{i,1} + \frac{1}{2}(D_1^\varepsilon \tilde{u}_{i,2})^2\right)^2 + O(\varepsilon^6).\end{aligned}$$

Angular interaction:

$$\begin{aligned}f(\theta_i) &\approx f''(0)\theta_i^2 \approx \varepsilon^2 f''(0)\left(D_1^{(2),\varepsilon} u_{i,2}\right)^2 + O(\varepsilon^6) \\&= \varepsilon^4 f''(0)\left(D_1^{(2),\varepsilon} \tilde{u}_{i,2}\right)^2 + O(\varepsilon^6).\end{aligned}$$

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- Hence, **the continuum total energy is of second order consistent comparing to the scaled atomic total energy.**

# Approximation error

## Approximation error in terms of force difference.

- Compute  $\mathbf{F}_i^a(\mathbf{u})$  and get

$$\begin{aligned}\mathbf{F}_i^a(\mathbf{u}) &= -\frac{1}{\varepsilon} \frac{\partial E^a}{\partial \mathbf{u}_i} \\ &= V''(1) \begin{pmatrix} \varepsilon^2 (\tilde{u}'_{i,1} + \tilde{u}'_{i,2} \tilde{u}''_{i,2} + O(\varepsilon)) \\ \varepsilon^3 (\tilde{u}''_{i,2} \tilde{u}'_{i,1} + \tilde{u}'_{i,2} \tilde{u}''_{i,1} + \frac{3}{2} \tilde{u}''_{i,2} (\tilde{u}'_{i,2})^2 + O(\varepsilon)) \end{pmatrix} \\ &\quad + f''(0) \begin{pmatrix} 0 + O(\varepsilon^3) \\ \varepsilon^3 (\tilde{u}_{i,2}^{(4)} + O(\varepsilon)) \end{pmatrix} \\ &= \begin{pmatrix} \varepsilon^2 (\mathbf{F}_{i,1}^c(\tilde{\mathbf{u}}) + O(\varepsilon)) \\ \varepsilon^3 (\mathbf{F}_{i,2}^c(\tilde{\mathbf{u}}) + O(\varepsilon)) \end{pmatrix}.\end{aligned}$$

- Hence, the pointwise error between **the scaled  $\mathbf{F}_i^a$**  and the  $\mathbf{F}_i^c$  is of first order.
- As a result, **the scaled continuum displacement field has first order modeling error wrt atomistic  $\|\cdot\|_*$ .**

## Extension to 2D

- Suppose  $\mathbf{y} : \varepsilon\mathbb{Z}^2 \rightarrow \mathbb{R}^3$  and  $E^a \leq C\varepsilon^4$  with

$$E^a(\mathbf{y}) = \varepsilon^2 \sum_i (V(D_1^\varepsilon \mathbf{y}_i) + f(\theta_i) + g(\omega_i)),$$

where  $V$  denotes the pair potential,  $f$  denotes the bond angle  $\theta$  potential and  $g$  denotes torsion angle  $\omega$  (angle between two triangles) potential.

- Assume a similar scaling rule of displacement field

$$\mathbf{u} = \begin{pmatrix} u_1 \\ u_2 \\ u_3 \end{pmatrix} = \begin{pmatrix} \varepsilon^2 \tilde{u}_1 \\ \varepsilon^2 u_2 \\ \varepsilon u_3 \end{pmatrix}.$$

- So  $\frac{1}{\varepsilon^4} E^a$  is  $\Gamma$ -convergent to the von-Kármán model

$$\begin{aligned} E^c(\tilde{\mathbf{u}}) &= \int \mathbb{C} \left( \text{sym}(\nabla \tilde{\mathbf{u}}_{1,2}) + \frac{1}{2} \nabla \tilde{u}_3 \otimes \nabla u_3 \right) \\ &\quad : \left( \text{sym}(\nabla \tilde{\mathbf{u}}_{1,2}) + \frac{1}{2} \nabla \tilde{u}_3 \otimes \nabla \tilde{u}_3 \right) dx_1 dx_2 \\ &\quad + \int \frac{\kappa}{2} |\nabla^2 \tilde{u}_3|^2 dx_1 dx_2. \end{aligned}$$

# Extension to 2D

**Four-body interactions must be included; and Tersoff and Brenner type interatomic potentials satisfy the assumptions.**

Analysis is similar to the 1D case.

- The continuum total energy is **second order consistent** comparing to the **scaled** atomic total energy.
- The continuum force is pointwisely **first order consistent** comparing to the **scaled** atomic total energy.
- The **scaled** continuum displacement field has **first order** modeling error wrt the atomistic  $\| \cdot \|_*$ .

# Physical continuum boundary conditions

- In a 1D atomistic model, Stefanelli proved that the boundary needs to specify the length of the chain in direction  $e_1$  <sup>17</sup>

$$y_{N,1} - y_{1,1} = \mu(N - 1)\varepsilon, \quad \mu \in (2/3, 1).$$

In direction  $e_2$ , simply apply the clamped condition

$$y_{1,2} = D_1^\varepsilon y_{1,2} = y_{N,2} = D_1^\varepsilon y_{N,2} = 0.$$

This corresponds to suspending the atomistic sample. <sup>18</sup>

- In the 2D continuum simulations, Zhang et al. 2014 obtained ripples with clamped boundary conditions applied to direction  $e_3$ . <sup>19</sup>

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<sup>18</sup>Novoselov et. al. Nature, 446, 60-63, (2007).

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# Summary

- A continuum von-Kármán model is derived from atomistic descriptions by carefully specifying the scaling rules and homogenization.
- The continuum model is proved to be of second order in terms of energy, is of first order in terms of forces and displacement fields.
- A rigorous study of physical continuum boundary conditions is needed for both 1D and 2D atomistic and continuum models.
- Development of multiscale model is an ongoing project.

Thank you for your attention!

Braun is supported by ERC starting grant 335120.

Li is supported by NSF-DMS CAREER 1847770.

Olson is supported by the NSF PIRE Grant OISE-0967140 and NSF RTG program.