Geodesic Embeddings of Path Complexes

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work with Deza, Hua, Holt, Klee, Schewe

Motivation

• diameter of simple polytopes

- computational/exhaustive approach
- enumerate combinatorial types of paths instead of combinatorial types of polytopes.

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From Simple Polytopes to Simplicial Complexes

Edge paths and Facet Paths





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Simplicial complexes

- A *path complex* is a pure simplicial complex whose dual graph (with edges defined by ridges) is a path.
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- A path complex is *end disjoint* if the two facets of dual-degree 1 are disjoint (complementary, prismatoid).



Directed Path Complexes

- A *directed* path complex is a path complex with distinguished *start facet*
- Every path complex corresponds to at most two non-isomorphic *orientations* (directed path complexes)



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Revisits



Directed Non-Revisiting Paths

- pivots and pivot sequences
 (3,4)(1,5)(4,6)(2,7)(6,8)
- Table representation



• index sequence $\langle 3, 1, 3, 2, 3 \rangle$



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canonical index seq. indicies in order. $\langle 1,2,1,3,1\rangle$

recursion No index occurs twice in a row

$$t(d, l) = (d - 1)t(d, l - 1) + t(d - 1, l - 1).$$

restricted growth func. indices occur in order

 $\langle 1,1,2,1
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stirling numbers
$$t(d, l) = {\binom{l-1}{d-1}}$$
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Geodesic Embeddings of Path Complexes

Necessary conditions for revisits

 $\langle 1,2,[1,3,1,2]\rangle$



• No new ridges: 3 distinct symbols in the loop between vertices

• No violation of end disjointness: identification is not on both end facets.

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Breaking Symmetry of Path Complexes

Generically Reduction to graph isomorphism, solve with partition backtracking

Vecessary Conditions

 Lexicographic, or
 No revisit on first facet



 $\langle 1, 2, 1, 3 \rangle$ $\langle 1, 2, 3, 2 \rangle$

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Images of paths

Lemma

If $\Delta(d-1, n-1) < l-1$, then a canonical index sequence of length l on d symbols in which the symbol 1 appears uniquely at the beginning or in which d appears uniquely at the end cannot correspond to a shortest path.

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Shortcut free embedding.

- Q is a *shortcut* for P if it shares end facets with P and has a shorter dual graph.
- A geodesic embedding of a path complex P is a simplicial sphere S containing P as a sub-complex and not containing any shortcut for P as a subcomplex.



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Exhaustive generation of shortcuts.

- Path π = v₀, v₁... v_k is inclusion-minimal if no proper subset of v₀... v_k is a path from v₀ to v_k.
- *Pivot graph* nodes are *d*-sets, edges are pivots.
- All inclusion-minimal paths from s to t in the pivot graph can be generated by backtracking.



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Shortcut free embeddings

Incremental discovery of shortcuts.

Incremental Construction

Find candidate embedding

Pind shortcuts (BFS)

3 Add constraint ¬ (facet(A) ∧ facet(B) ∧ facet(B)



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B

0

Α

Given
$$\{x_1 \dots x_{d-1}, y_1, y_2, y_3, y_4\} \in \mathbb{R}^{d+1}$$

$$0 = \det(x_1 \dots x_{d-1}, y_1, y_2) \cdot \det(x_1 \dots x_{d-1}, y_3, y_4) + \det(x_1 \dots x_{d-1}, y_1, y_4) \cdot \det(x_1 \dots x_{d-1}, y_2, y_3) - \det(x_1 \dots x_{d-1}, y_1, y_3) \cdot \det(x_1 \dots x_{d-1}, y_2, y_4)$$

$$\chi(i_1,\ldots,i_{d+1}) := \text{sign det } x_{i_1},\ldots,x_{i_{d+1}})$$

$$\begin{split} \chi(1,2,3)\chi(1,4,5) &= +1\\ \chi(1,2,4)\chi(1,3,5) &= -1\\ \chi(1,2,5)\chi(1,3,4) &= +1 \end{split}$$

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Determining facets and non-facets

F is a *facet* iff for all $x, y \notin F$

$$\chi(F x) = \chi(F y)$$

• no interior points

- Facet constraints are two variable equations.
- Non-facet constraints are "not-all-equal" constaints.



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- Let τ(Y) = (-1)^k where k transpositions are required to sort tuple Y.
 For i > 1, let e_i = F_i \ F_{i-1}, l_i = F_{i-1} \ F_i.
- Let $\sigma_1 = 1$, and for i > 1 let $\sigma_i = \tau(F_{i-1}, e_i)\tau(F_i, l_i)\sigma_{i-1}$. If F_i and F_{i-1} are both facets, then

$$\sigma_i \chi(F_i, x) = \sigma_{i-1} \chi(F_{i-1}, y) \qquad x \notin F_i, y \notin F_{i-1}$$



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How many cases?

d	п	length	rev.	drops							
d	п	k	т	Ι	#	,			I	,	<i>1</i> 1
4	11	7	0	0	50	a	n 10			1	#
4	11	7	1	1	200	0	12	1		0	11
4	11	7	2	2	354	6	13	8		0	293
4	11	7	3	3	96	6	13	8	2	T	452
4	12	8	0	0	160						
4	12	8	1	1	1258						
4	12	8	2	2	5172	hard cases					
4	12	0	2	3	7308	u		K		1	#
	12	0	J	5	1350	/	10				0
4	12	8	4	4	1512	4	12	8	0		2
4	12 12 11	8 7	3 4 1	4 0	1512 98	4 5 5	12 12 12		0 1 2	0 0 1	2 15 6
4 5 5	12 12 11 11	8 7 7	4 1 2	4 0 1	1512 98 98	4 5 5	12 12 12		0 1 2	0 0 1	2 15 6
4 5 5 5	12 12 11 11 12	8 7 7 8	4 1 2 1	4 0 1 0	1512 98 98 1079	4 5 6	12 12 12 13		0 1 2 1	0 0 1 0	2 15 6 138
4 5 5 5 5 5	12 11 11 12 12 12	8 7 7 8 8	4 1 2 1 2	4 0 1 0 1	1512 98 98 1079 3184	4 5 6 6	12 12 12 13 13		0 1 2 1 2	0 0 1 0 1	2 15 6 138 63

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d	п	length	rev.	drops									
d	п	k	m	1	#		,			I	,	<i>1</i> 1	
4	11	7	0	0	50		a	n	K	m	1	#	
4	11	7	1	1	200		6	12	7	1	0	11	
4	11	7	2	2	354		6	13	8		0	293	
4	11	7	3	3	96		6	13	8	2	1	452	
4	12	8	0	0	160								
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Δ	12	8	3	3	7308	_	d	n	ĸ	т	1	#	
т 4	10	0		1	1510		4	12	8	0	0	2	
	12	ð	4	4	1512		5	12	8	1	0	15	
5	11	7	1	0	98		5	12	8	2	1	6	
5	11	7	2	1	98		6	13	8	1	0	138	
5	12	8	1	0	1079		6	12	0	1 1	1	62	
5	12	8	2	1	3184		U	12	Ó	Ζ	1	03	
5	12	8	3	2	2904								

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Parallel Backtracking

b, g, d, c, h, e, a, f

$$\underbrace{\begin{matrix} b, g, d, c, h, e, a, f \\ +, -, +, -, -, -, +, - \\ i \end{matrix}}_{i}$$











Updated Bounds

