88 ABW-12-0578

#### Wide Angle, Staring Synthetic Aperture Radar Feb 2012



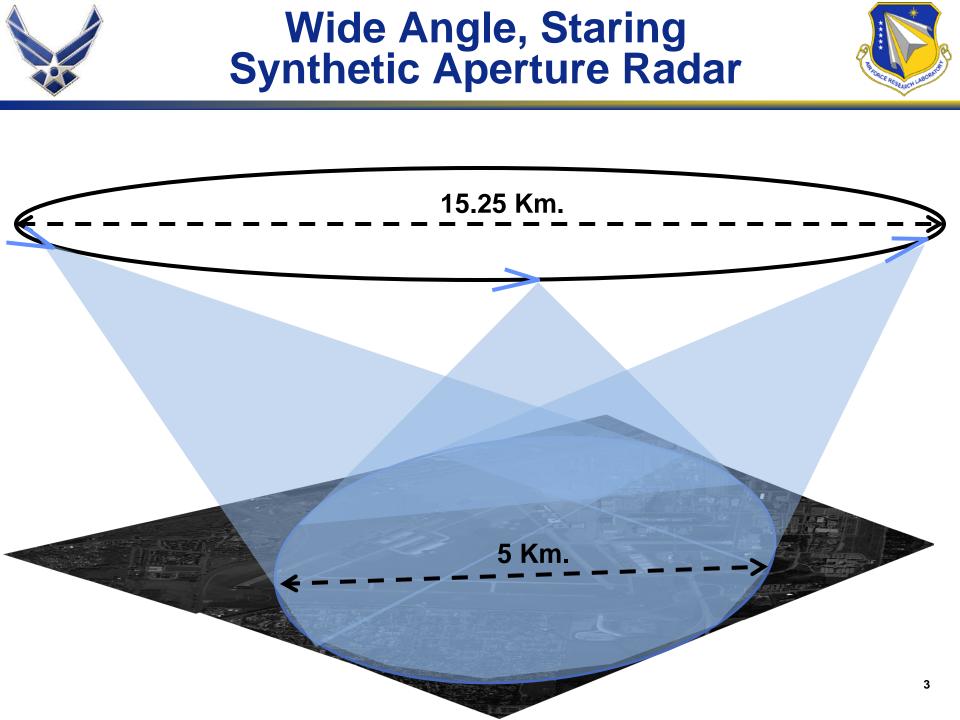
Ed Zelnio Sensors Directorate Air Force Research Laboratory







- Review SAR Focus on Wide Angle, Staring SAR (90%)
- Technology Challenges (10%)



Gotcha Radar Program Michael Minardi, et al Processing and Data Products June 2008 (Oral Presentation)



# **Synthetic Aperture Radar**



- Geometry
  - SAR Projection
  - Layover v Parallax v Shadow
- Energy Scattering
  - Diffuse v Specular v Scintillation / Speckle
  - Man-made v Natural
  - Military v Civilian
  - Scalar v Polarization
  - High Frequency v Low Frequency
  - Modulus v Phase
  - Standard v Wide Angle
- Tomography / Aperture
  - Range (Frequency) v Azimuth v Elevation (Angle)
  - Far Field v Near Field
  - Image v Phase History
  - Coherent v Incoherent
  - Stationary v Moving

#### • SAR v Visible v CAT

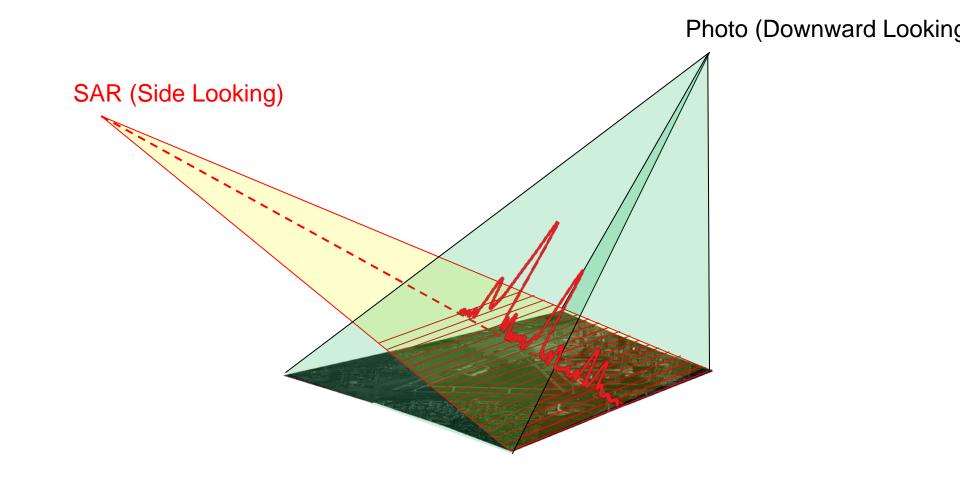


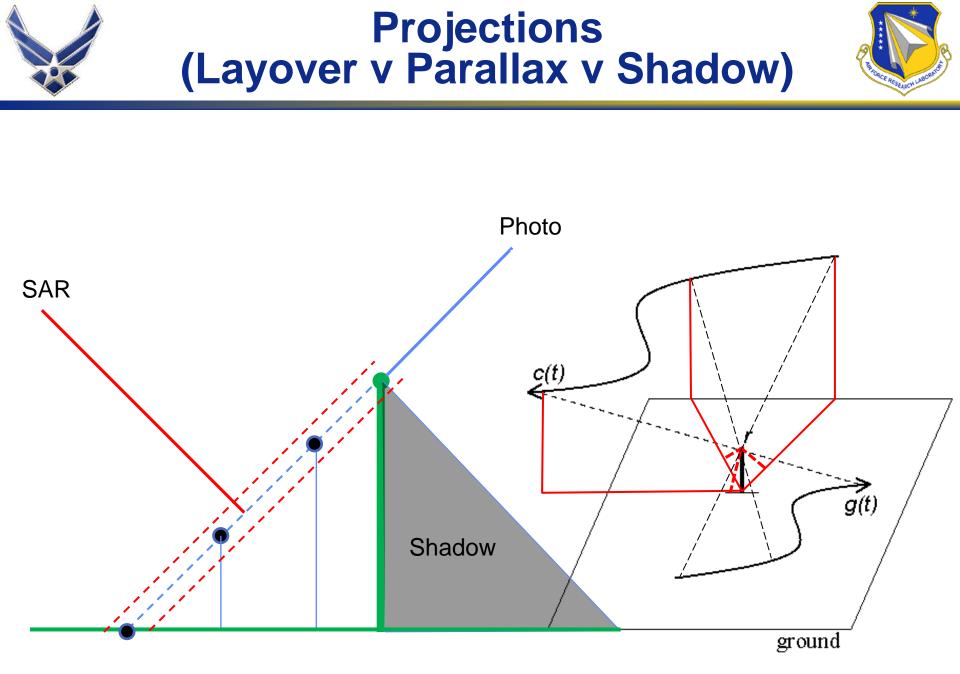


	SAR	Visible	CAT (e.g., X-ray)
Elemental Projection	<ul> <li>1D</li> <li>Orthogonal to Line of Sight</li> <li>Ranging (Time / Frequency)</li> </ul>	<ul> <li>2D</li> <li>Along line of Sight</li> <li>Angle / Angle</li> </ul>	<ul> <li>2D</li> <li>Along line of Sight</li> <li>Angle / Angle</li> </ul>
Energy / Scattering	<ul> <li>Active (Waveform)</li> <li>Diffuse Scattering <ul> <li>Natural</li> </ul> </li> <li>Specular Scattering <ul> <li>Man-made</li> </ul> </li> </ul>	<ul> <li>Passive</li> <li>Diffuse Scattering</li> </ul>	<ul> <li>Active</li> <li>Diffuse Transmission</li> </ul>
Tomography \Aperture	<ul> <li>Coherent (t,angle)</li> <li>Frequency / Azimuth</li> <li>/ Sparse Elevation</li> <li>Phase History</li> <li>Carrier Frequency</li> </ul>	<ul> <li>Non-Coherent</li> <li>2D Angle / Azimuth</li> <li>/ Elevation</li> <li>Image</li> <li>Base band</li> </ul>	<ul> <li>Non- Coherent</li> <li>2D Angle / Azimuth / Elevation</li> <li>Image</li> <li>Base band</li> </ul>





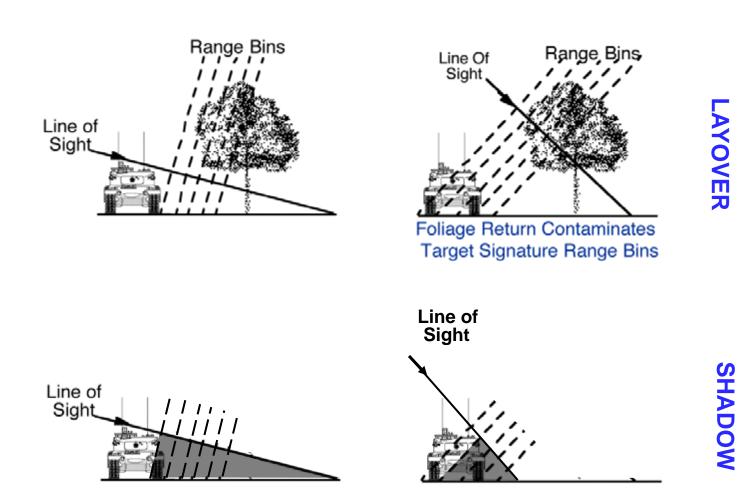






#### **Layover and Shadow**





#### Fourier Processed Flat Plane Projection



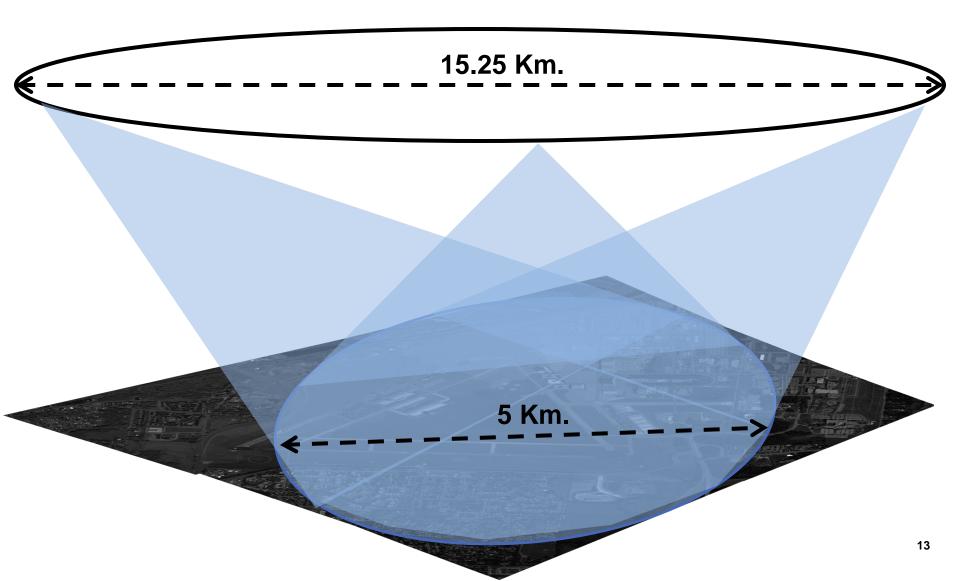






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#### Improved Image Quality Single-Look vs. Multi-Look





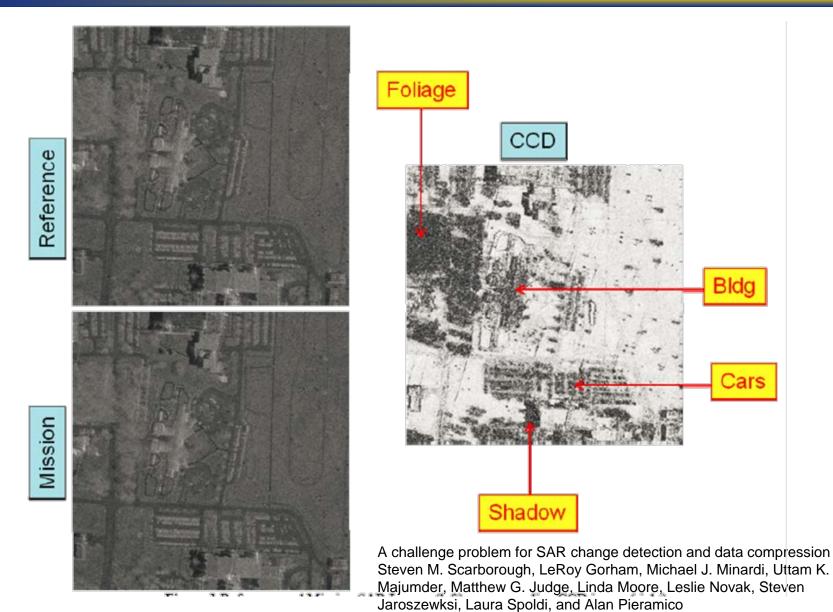
#### Single-Look SAR

**Multi-Look SAR** 



## **Coherent Change Detection**

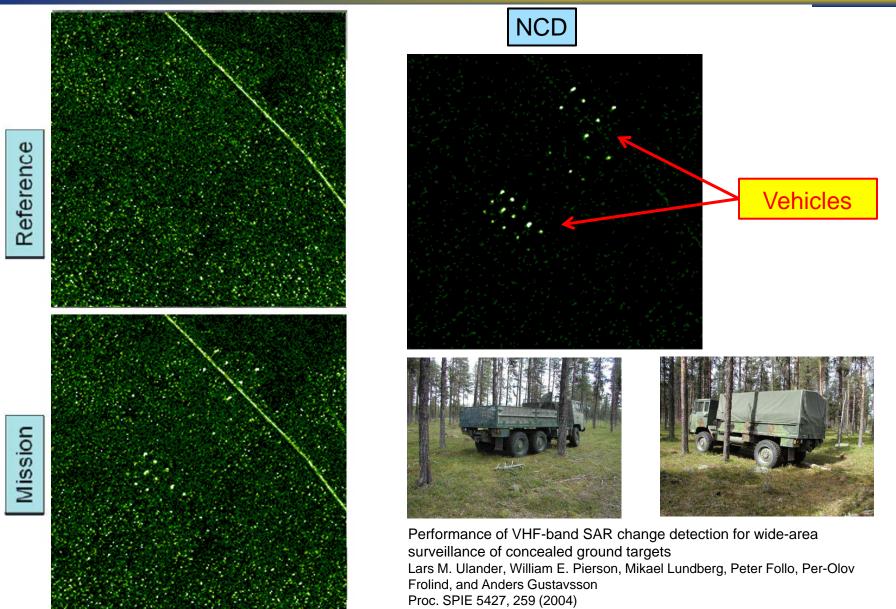






#### VHF Change Detection in Dense Foliage





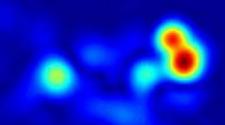
#### Tank v Honda Civic

**3 Degrees Aperture** 

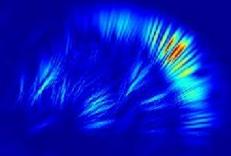
**110 Degrees Aperture** 

110 Degrees Aperture (Enhanced)

**5 Degree Aperture** 

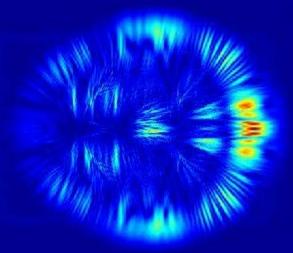


#### **110 Degrees Aperture**



Top Row Images by Moses, Cetin

#### **360 Degrees Aperture**

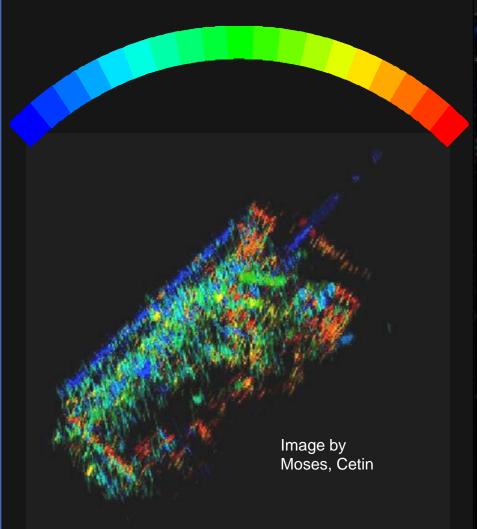




# **Deconvolution + Angle Diversity**



- 110 Degree Angle Change, 20 Degree Coherent Aperture
- Center Every 5 degrees and Map Max Value to Corresponding Angle Color

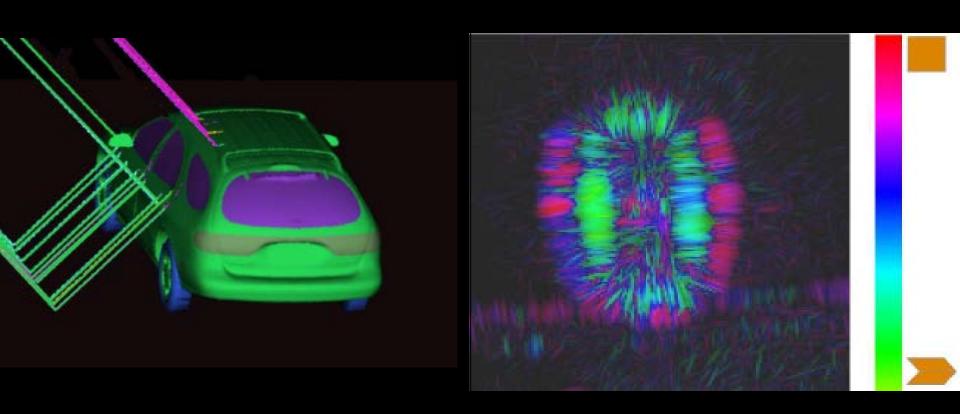


GOTCHA experience report: three-dimensional SAR imaging with complete circular apertures Emre Ertin, Christian D. Austin, Samir Sharma, Randolph L. Moses, and Lee C. Potter Proc. SPIE 6568, 656802 (2007)



#### **Use of Polarization**





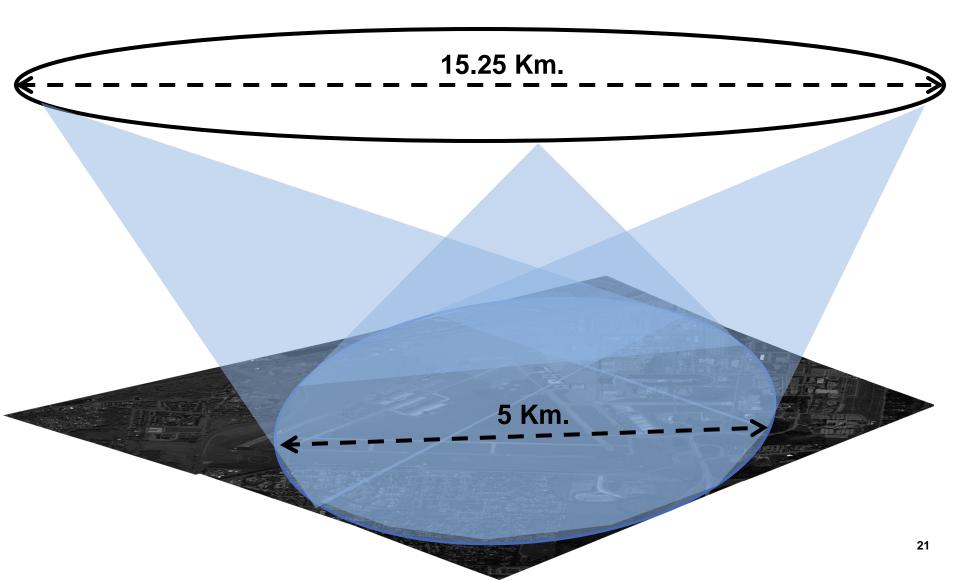
GOTCHA experience report: three-dimensional SAR imaging with complete circular apertures Emre Ertin, Christian D. Austin, Samir Sharma, Randolph L. Moses, and Lee C. Potter Proc. SPIE 6568, 656802 (2007)





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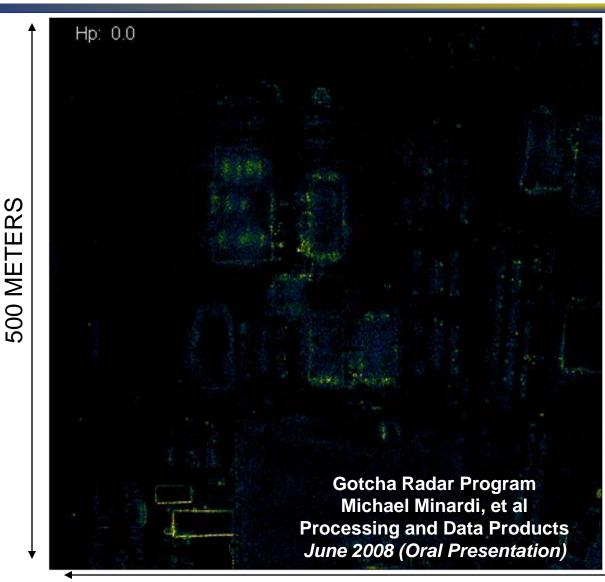






## **Depth from Focus**





#### **500 METERS**





8\_BrightBuilding\_500m\_0p5m\_360deg



8\_BrightBuilding\_500m\_0p5m\_360deg

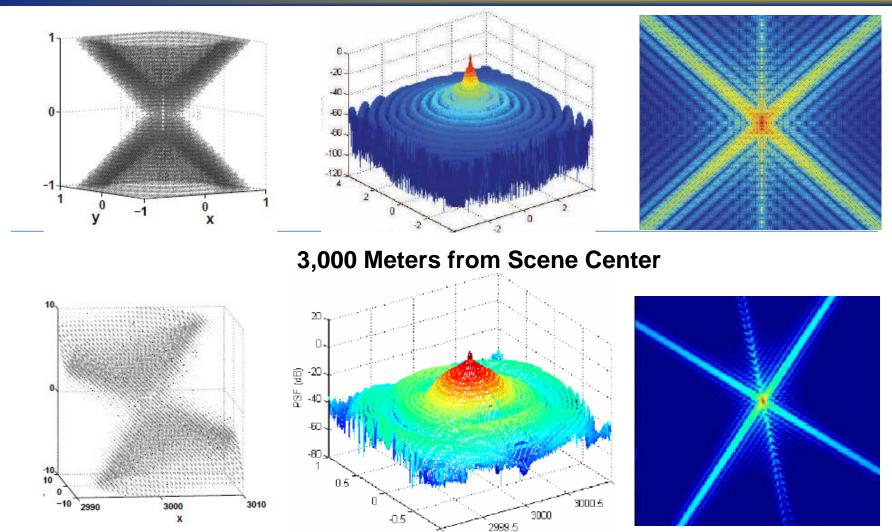






## **Synthetic Aperture Near Field**





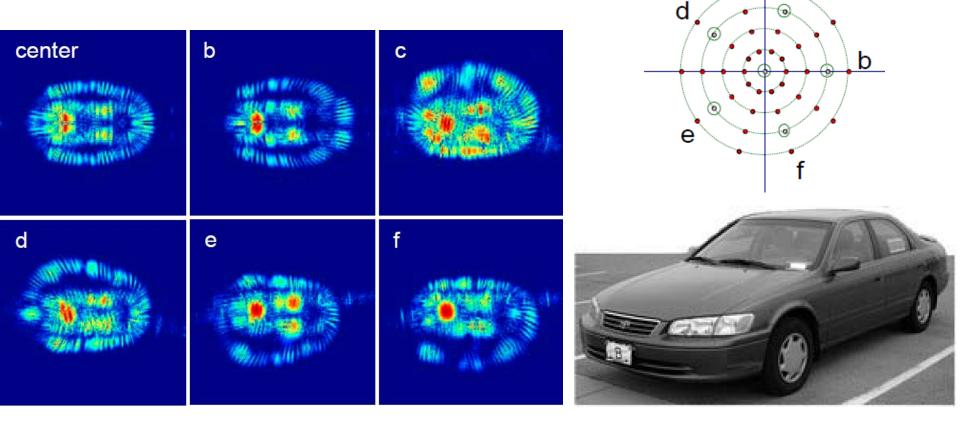
An analytical expression for the three-dimensional response of a point scatterer for circular synthetic aperture radar Linda J. Moore and Uttam K. Majumder Proc. SPIE 7699, 769907 (2010)





С

.4 \* flight path radius = 3000 m from scene center



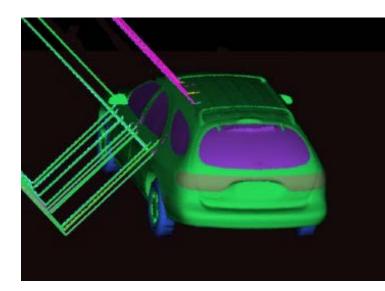
Classifying civilian vehicles using a wide-field circular SAR Kerry E. Dungan and Lee C. Potter Proc. SPIE 7337, 73370R (2009)

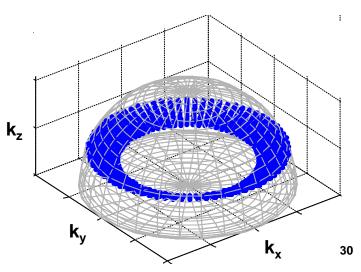


#### Range x Elevation x Azimuth (Phase History)



- Range
  - Change in lambda
  - Very little amplitude and phase center change at high frequency
- Azimuth
  - Change in angle
  - Scatterers dense in beam, significant amplitude and phase center change for man-made objects
- Elevation
  - Change in angle
  - Gravity → Scatterers sparse in beam, many right angles result in little amplitude and phase center change







# High-Resolution SAR Image (1 inch vs. 1 foot resolution)

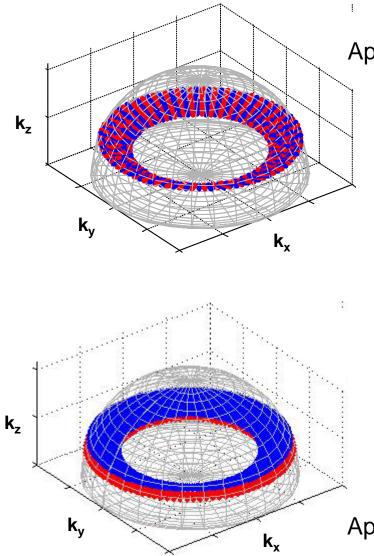






## Coherency





Aperture for Coherent Change Detection



Aperture for Interferometric SAR

#### Angle / Time / Integration Times (Moving Objects)



**Gotcha Radar Program** Michael Minardi, et al **Processing and Data Products** June 2008 (Oral Presentation)

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#### • SAR v Visible v CAT





- Application
  - Moving object (vehicle, pedestrian) detection, tracking and geolocation
  - Computation / Transmission (Phase History Compression) / Storage
  - Target Recognition
- Underpinning Technology
  - Scattering Characterization (Anisotropy, Polarization, Statistical)
  - Under-sampled Sensing (Sensing Diversity)
  - Forward and Inverse Scattering