lighly Oscillatory Dynamics	Our work (qHOP)	
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Time-dependent Hamiltonian Simulation of Highly Oscillatory Dynamics

Di Fang

Department of Mathematics Challenge Institute of Quantum Computing University of California, Berkeley

Based on joint work with Dong An (U Maryland) and Lin Lin (UC Berkeley)

Workshop on "Quantum Numerical Linear Algebra" IPAM, 2022

Highly Oscillatory Dynamics	Our work (qHOP)	
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Outline



- First source of oscillations
- Second source of oscillations
- 2 Major Question
- Our work (qHOP)
 - Idea of the algorithm
 - Interaction Picture and Superconvergence
- 4 Conclusion and Remarks

Highly Oscillatory Dynamics	Our work (qHOP)	
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First source of oscillations		

Hamiltonian Simulation Problem: Given a description of the Hamiltonian H(t), an evolution time t and an initial state $|\psi(0)\rangle$, to produce the final state $|\psi(t)\rangle$ within in some error tolerance ϵ .

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$$\begin{split} \mathrm{i}\partial_t \left| \psi(t) \right\rangle &= H(t) \left| \psi(t) \right\rangle, \quad \left| \psi(0) \right\rangle = \left| \psi_0 \right\rangle \\ H(t) &\equiv H, \quad \left\| \mathcal{U}_{\mathsf{app}} - e^{-\mathrm{i}Ht} \right\| \leq \epsilon. \\ \\ &\left\| \mathcal{U}_{\mathsf{app}} - \mathcal{T} e^{-\mathrm{i}\int_0^t H(s) \, ds} \right\| \leq \epsilon. \end{split}$$

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$$H(t) \equiv H, \quad \left\| \mathcal{U}_{\mathsf{app}} - e^{-\mathrm{i}Ht} \right\| \leq \epsilon.$$

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The difficulties of the simulation increase as the underlying unitary becomes **highly oscillatory**.

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• 1st source: ||H|| is large.

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The difficulties of the simulation increase as the underlying unitary becomes **highly oscillatory**.

- 1st source: ||H|| is large.
- 2nd source: *H*(*t*) oscillates itself!

Our work (qHOP) 00 0000000000 Conclusion and Remarks

First source of oscillations

Highly Oscillatory Dynamics are Ubiquitous!



Highly Oscillatory Dynamics are Ubiquitous!

Highly Oscillatory Dynamics	Our work (qHOP)	
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First source of oscillations		

• Trotterization:

1st-order Trotter formula

$$e^{-iHt} = \left(e^{-iH_1t/L}e^{-iH_2t/L}\right)^L + \mathcal{O}(\|[H_1, H_2]\|t^2/L)$$

High order (*p*-th) generalization depending on nested commutators. [Childs-Su-et al. 2021] $\mathcal{O}(\|\mathsf{Comm}\|^{1/p} t^{1+1/p})$

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• LCU, e.g. Truncated Taylor series:

$$\mathcal{O}\left(\|H\|t\frac{\log(1/\epsilon)}{\log\log(1/\epsilon)}\right).$$

- Qubitization/QSP/QSVT: $O(||H||t + \log(1/\epsilon))$
- Randomized algorithms e.g., qDRIFT: Weak Convergence wrt the diamond norm of Quantum channels

$$\mathcal{O}\left(\|\boldsymbol{H}\|t^2/\epsilon\right).$$

Highly Oscillatory Dynamics	Our work (qHOP)	
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Second source of oscillations		

Commutator scaling gives great cancellation. [Childs-Su-et al. 2021]

Question: Can one explore the commutator scaling in the time-dependent case H(t)?

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Additional Challenge for time-dependent case: High oscillations caused by the rapid change of H(t).

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Second Source of Oscillations

e.g. interaction picture $e^{iAs}Be^{-iAs}$ with $||A|| \gg 1$.

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Second source of oscillations		

• Trotterization: $H = H_1(t) + H_2(t)$

$$\mathcal{T}e^{-\mathrm{i}\int_{t_j}^{t_{j+1}}H(s)\,ds}\approx e^{-\mathrm{i}hH_2(\tau_j)}e^{-\mathrm{i}hH_1(\tau_j)},$$

where $\tau_j \in [t_j, t_{j+1}]$ are chosen according to Suzuki construction. The number of unitaries depends on $\|\partial_t H(t)\|$.

¹[Wiebe-Berry-Hoyer-Sanders 2010]

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 $\text{High-order ($p$-th) generalization} \left(\sum_{j=1}^m \|\partial_t^p H_j\| \right)^{1/(p+1)} \mathbf{1}$

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The dependence on $\partial_t^p H(t)$ are suppressed!

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The dependence on $\partial_t^p H(t)$ are suppressed! But no commutator scaling! Applying to interaction picture (IP)?

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e.g., truncated Dyson series, rescaled Dyson series, etc.

Interaction Picture: Best asymptotic scaling. The circuit requires complicated quantum control logic for time clocking, which can lead to undesirable constant factor.²

[[]Wiebe-Berry-Hoyer-Sanders 2010]

²[Su-Berry-Wiebe-Rubin-Babbush PRX Quantum 2021]

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- Randomized algorithms (first-order accuracy and weak conv)
 e.g., [Poulin-Qarry-Somma-Verstraete 2011], continuous qDRIFT. Interaction Picture: hybridized methods (first order)²
- Dyson series (LCU) based

e.g., truncated Dyson series, rescaled Dyson series, etc. Interaction Picture: Best asymptotic scaling. The circuit requires complicated quantum control logic for time clocking, which can lead to undesirable constant factor.³

¹[Wiebe-Berry-Hoyer-Sanders 2010]

²[Rajput-Roggero-Wiebe 2021]

³[Su-Berry-Wiebe-Rubin-Babbush PRX Quantum 2021]

Highly Oscillatory Dynamics	Major Question	Our work (qHOP)	
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- Two challenges: ||H|| large; rapid change of H.
- Two desirable features: commutator scaling (like Trotter for time-independent); weak dependence on derivatives (e.g. randomized/ Dyson-based methods).
- Question: Can we get both?

	Major Question	Our work (qHOP)	
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Ideal: An algorithm

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Ideal: An algorithm

- Simple to implement
- exploring commutator scaling
- remaining insensitive to the rapid change of the Hamiltonian
- is high-order (in accuracy).

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Simple to implement

(no time-clocking related control units)

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Ideal: An algorithm

- Simple to implement
 (no time-clocking related control units)
- exploring commutator scaling
 (in high precision limit)
- remaining insensitive to the rapid change of the Hamiltonian
- is high-order (in accuracy).

	Major Question	Our work (qHOP)	
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Ideal: An algorithm

- Simple to implement
 - (no time-clocking related control units)
- exploring commutator scaling
 (in high precision limit)
- remaining insensitive to the rapid change of the Hamiltonian
 (log dependence on derivative)
- is high-order (in accuracy).

Question	Our work (qHOP)	Conclusion and Remarks
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	Question	Ouestion Our work (dHOP) OO 00000000000

Ideal: An algorithm

Simple to implement

(no time-clocking related control units)

- exploring commutator scaling
 (in high precision limit)
- is high-order (in accuracy).
- achieves superconvergence in the digital simulation of Schrödinger equation, yielding a surprising second order convergence rate.

	Major Question	Our work (qHOP)	
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A naive (but insufficient) attempt for commutator bound

• Standard Trotter: As an example, take the special controlled form

 $H(t) = f_1(t)H_1 + f_2(t)H_2$

with f_1 and f_2 smooth and scalar, and the second order time discretization. (step size: *h*) [Lloyd 1996]

$$U_s(t+h,t) = e^{-\frac{ih}{2}f_1(t+\frac{h}{2})H_1}e^{-ihf_2(t+\frac{h}{2})H_2}e^{-\frac{ih}{2}f_1(t+\frac{h}{2})H_1}$$
Highly Oscillatory Dynamics	Major Question	Our work (qHOP)	
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Take the case $[H_1, H_2] = 0.$

Error is not machine precision! \Rightarrow No commutator scaling.

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• Generalized Trotter [Huyghebaert–De Raedt 1990] For general $H_1(t) + H_2(t)$,

$$\mathcal{T}e^{-\mathrm{i}\int_{t_{j}}^{t_{j+1}}H(s)\,ds} = \mathcal{T}e^{-\mathrm{i}\int_{t_{j}}^{t_{j+1}}H_{1}(s)\,ds}\mathcal{T}e^{-\mathrm{i}\int_{t_{j}}^{t_{j+1}}H_{2}(s)\,ds} + \mathcal{O}(\max_{s,\tau\in[t_{j},t_{j+1}]}\|[H_{1}(s),H_{2}(\tau)]\|\,h^{2}).$$

NOT an algorithm yet! Two time-dependent Ham. sim. problems still need to implement!

Highly Oscillatory Dynamics	Our work (qHOP)	
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Idea of the algorithm		

$$U(t_{n+1}, t_n) = \mathcal{T}e^{-i\int_{t_n}^{t_{n+1}} H(s)ds} \approx e^{-i\int_{t_n}^{t_{n+1}} H(s)ds} \quad 4$$

⁴widely used in Trotter for time-dependent Ham., randomized product formula, e.g. [Poulin-Qarry-Somma-Verstraete 2011], classical Magnus integrator, etc

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• Rectangular quadrature (*aka* Riemann sum with *M* quadrature points).



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 Due to LCU, cost ~ log(M) ⇒ This is the most "intrinsically quantum" part in qHOP.



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- share the spirit of multi-scale integrator with $\Delta T = t_{j+1} - t_j$ and Δt for quadrature within each time step.

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- share the spirit of multi-scale integrator with $\Delta T = t_{j+1} - t_j$ and Δt for quadrature within each time step.
- Time-dependent Ham. Sim
 ⇒ Time-independent!
 can use QSVT and OAA.

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Questions:

- 1. How to implement?
- 2. What are the approximation errors?

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- 2. What are the approximation errors?

Answer to Q1:



⁴widely used in Trotter for time-dependent Ham., randomized product formula, e.g. [Poulin-Qarry-Somma-Verstraete 2011], classical Magnus integrator, etc

Highly Oscillatory Dynamics	Our work (qHOP)	
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Idea of the algorithm		

$$U(t_{n+1}, t_n) = \mathcal{T}e^{-i\int_{t_n}^{t_{n+1}} H(s)ds} \approx e^{-i\int_{t_n}^{t_{n+1}} H(s)ds} 4$$

$$\approx e^{-\mathrm{i}h\frac{1}{M}\sum_{k=0}^{M-1}H(jh+kh/M)}$$

Questions:

- 1. How to implement?
- 2. What are the approximation errors?

Answer to Q2: (h: step size)

$$\begin{aligned} \|U_{\text{exact}}(t_{j+1},t_j) - U_{\text{num}}(t_{j+1},t_j)\| \\ \leq h^2 \Big(\underbrace{\frac{1}{2} \max_{s,\tau \in [jh,(j+1)h]} \|[H(\tau),H(s)]\|}_{\text{Dropping time-ordering}} + \underbrace{\frac{1}{M} \max_{s \in [jh,(j+1)h]} \|H'(s)\|}_{\text{numerical quadrature error} \Rightarrow \log \text{(LCU)}} \Big). \end{aligned}$$

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Highly Oscillatory Dynamics	Our work (qHOP)	
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$$\approx e^{-ih\frac{1}{M}\sum_{k=0}^{M-1} H(jh+kh/M)}$$

Query Complexity:

$$\widetilde{\mathcal{O}}(f) = \mathcal{O}(f \mathsf{polylog} f)$$

Highly Oscillatory Dynamics	Our work (qHOP)	
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$$U(t_{n+1}, t_n) = \mathcal{T}e^{-i\int_{t_n}^{t_{n+1}} H(s)ds} \approx e^{-i\int_{t_n}^{t_{n+1}} H(s)ds}$$
$$\approx e^{-ih\frac{1}{M}\sum_{k=0}^{M-1} H(jh+kh/M)}$$

Query Complexity:

$$\widetilde{\mathcal{O}}\left(\max_{s,t\in[0,T]} \left\| \left[H(s),H(t)\right] \right\| \frac{T^2}{\epsilon} + \max_{s\in[0,T]} \left\|H(s)\right\| T\right)$$

 $\widetilde{\mathcal{O}}(f) = \mathcal{O}(f \mathsf{polylog} f)$

Highly Oscillatory Dynamics	Our work (qHOP)	
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Interaction Picture and Superconvergence		

H = A + B and A has a much larger norm but fast-forwardable. $\mathrm{i}\partial_t\psi = H\psi = (A+B)\psi$

Highly Oscillatory Dynamics		Our work (qHOP)	
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Interaction Picture and Superconvergence	e		

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 $i\partial_t \psi = H\psi = (A+B)\psi$

Motivation: e.g., Schrödinger equation

$$H = -\frac{1}{2}\Delta + V(x), \quad \|\Delta_h\| \gg \|V\|$$

Highly Oscillatory Dynamics		Our work (qHOP)	
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Interaction Picture and Superconvergence	3		

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Interaction Picture [Low-Wiebe 2018]:

Highly Oscillatory Dynamics		Our work (qHOP)	
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Interaction Picture and Superconvergence	e.		

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Interaction Picture [Low-Wiebe 2018]:

$$H_I(t) := e^{iAt}Be^{-iAt}, \psi_I := e^{iAt}\psi$$
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Highly Oscillatory Dynamics		Our work (qHOP)	
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Interaction Picture and Superconvergence	3		

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Highly Oscillatory Dynamics		Our work (qHOP)	
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Interaction Picture and Superconvergence	ne -		

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Interaction Picture [Low-Wiebe 2018]:

 $H_I(t) := e^{iAt}Be^{-iAt}, \psi_I := e^{iAt}\psi$ and $i\partial_t\psi_I = H_I\psi_I$ Why is this any good? $||H_I|| = ||B|| \ll ||H||$. Challenges? highly oscillatory time-dependent problem

Highly Oscillatory Dynamics	Our work (qHOP)	
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Interaction Picture A + B(t)

Take A + B for simplicity. It also works for A + B(t)(and even f(t)A + B(t)) given $O_A(s) := e^{-iAs}$ fast-forwardable.

$$H_I(s) = e^{iAs}Be^{-iAs}$$



Highly Oscillatory Dynamics		Our work (qHOP)	
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Interaction Picture and Superconvergence	e		

Schrödinger equation (Unbounded/Real-space Ham. Sim.)

 $H = -\Delta + V(x)$

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Time-dependent Hamiltonian Simulation of Highly Oscillatory Dynamics

⁵similar for spectral methods and other Galerkin approximations.

Highly Oscillatory Dynamics	Our work (qHOP)	
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Interaction Picture and Superconvergence		

Schrödinger equation (Unbounded/Real-space Ham. Sim.)

 $H = -\Delta + V(x)$

Take one-spatial dimension with domain $\left[0,1\right]$ for simplicity. Using N spatial grids,

$$\Delta_h^{\text{per}} := N^2 \begin{pmatrix} -2 & 1 & & 1 \\ 1 & -2 & 1 & & \\ & \ddots & \ddots & \ddots & \\ & & 1 & -2 & 1 \\ 1 & & & 1 & -2 \end{pmatrix},$$

for finite difference. 5

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Interaction Picture and Superconvergence		

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for finite difference. 5

After discretization using N spatial grids, $||A|| = ||-\Delta_h|| = O(N^2)!$ But gate $\sim O(||H|| n^k)$, where n is the number of qubits and $2^n = N$.

⁵similar for spectral methods and other Galerkin approximations.

Highly Oscillatory Dynamics	Our work (qHOP)	
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Interaction Picture and Superconvergence		

Commutator reductions?

 $\|[A,B]\| \sim N, \quad \|[B,[A,B]]\| \sim N, \quad \|[A,[A,B]]\| \sim N^2$

⁶[An-Fang-Lin arXiv 2012.13105]

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Time-dependent Hamiltonian Simulation of Highly Oscillatory Dynamics

Highly Oscillatory Dynamics	Our work (qHOP)	
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Interaction Ricture and Superconvergence		

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When applying Trotter-type algorithm,

• NOT enough for *N*-independent when measuring operator norm error of unitary evolutions.

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Time-dependent Hamiltonian Simulation of Highly Oscillatory Dynamics

Highly Oscillatory Dynamics	Our work (qHOP)	
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Interaction Picture and Superconvergence		

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- It can be fixed by vector norm analysis ⁶ if assuming good regularity on initial condition and measuring in vector norm

$$\left| U_{\mathsf{exact}}(T,0)\vec{\psi}(0) - U_{\mathsf{num}}(T,0)\vec{\psi}(0) \right|$$
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 \Rightarrow *N*-independent vector norm scaling.

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Highly Oscillatory Dynamics	Our work (qHOP)	
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Interaction Picture and Superconvergence		

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 \Rightarrow N-independent vector norm scaling.

N-independent operator norm scaling? \Rightarrow Interaction Picture!

⁶[An-Fang-Lin arXiv 2012.13105]

Highly Oscillatory Dynamics	Our work (qHOP)	
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Interaction Picture and Superconvergence		

$$h \max_{s \in [-h,h]} \left\| [B, e^{iAs}Be^{-iAs}] \right\| \le 2h \left\| B \right\|^2$$

 \Rightarrow First order scheme with N independent error preconstant.

Highly Oscillatory Dynamics		Our work (qHOP)	
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Interaction Ricture and Superconvergence	20		

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Claim: It is in fact of second order with error preconstant independent of *N*! **Superconvergence**!

Highly Oscillatory Dynamics	Our work (qHOP)	
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Interaction Picture and Superconvergence		

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Claim: It is in fact of second order with error preconstant independent of *N*! **Superconvergence**!

Theorem (An-Fang-Lin arXiv:2111.03103)

For a smooth function V bounded together with all of its derivatives and $0 < h \leq 1$, we have

$$\max_{s\in[-h,h]} \left\| [V(x), e^{\mathrm{i}s\Delta}V(x)e^{-\mathrm{i}s\Delta}] \right\|_{\mathcal{L}(L^2)} \le C_V h,$$

where C_V depending only on V and its the derivatives (and independent of the number of spatial grids N!).

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Highly Oscillatory Dynamics	Our work (qHOP)	
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Interaction Picture and Superconvergence		

Numerical Evidence of Superconvergence



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High Level Idea of the Proof of Superconvergence

 $[B, e^{\mathrm{i}As}Be^{-\mathrm{i}As}].$

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High Level Idea of the Proof of Superconvergence

$$[B, e^{\mathrm{i}As}Be^{-\mathrm{i}As}].$$

False Approach:

Imagine Taylor expand $e^{iAs} = I + iAs + \cdots$ and e^{-iAs} .

Highly Oscillatory Dynamics	Our work (qHOP)	
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High Level Idea of the Proof of Superconvergence

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Second term $[B, [A, B]]s \sim N$

Highly Oscillatory Dynamics	Our work (qHOP)	
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• But this still depend on A which depends on the number of spatial grids N!
Highly Oscillatory Dynamics	Our work (qHOP)	
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High Level Idea of the Proof of Superconvergence

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False Approach:

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Second term $[B, [A, B]]s \sim N$

- But this still depend on *A* which depends on the number of spatial grids *N*!
- Note this indeed resembles Trotter, where second order Trotter depends on [B, [A, B]] ∼ N and [A, [A, B]] ∼ N².

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High Level Idea of the Proof of Superconvergence

 $[B, e^{iAs}Be^{-iAs}]$

Highly Oscillatory Dynamics		Our work (qHOP)	
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Interaction Picture and Superconvergence	e		

High Level Idea of the Proof of Superconvergence

$$[B, e^{iAs}Be^{-iAs}]$$

Real Approach:

No truncations! Borrow from pseudo-differential calculus.

Highly Oscillatory Dynamics	Our work (qHOP)	
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High Level Idea of the Proof of Superconvergence

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Real Approach:

No truncations! Borrow from pseudo-differential calculus.

op(a(x, p)) is a so-called quantization:

$$\mathsf{op}(x) = x, \quad \mathsf{op}(p) = -\mathrm{i}\partial_x$$

$$e^{i\Delta s}V(x)e^{-i\Delta s} = \mathsf{op}(V(x-2ps))$$

Exact! No truncation of series!

$$[B, e^{\mathrm{i}As}Be^{-\mathrm{i}As}] = [\mathsf{op}(V), \mathsf{op}(V(x-2ps))]$$

Highly Oscillatory Dynamics	Our work (qHOP)	
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$$e^{i\Delta s}V(x)e^{-i\Delta s} = \mathsf{op}(V(x-2ps))$$

Exact! No truncation of series!

$$[B, e^{\mathrm{i}As}Be^{-\mathrm{i}As}] = [\mathsf{op}(V), \mathsf{op}(V(x-2ps))]$$

$$\sim \{V(x), V(x-2ps)\} \sim \nabla_x V(x) \cdot \nabla_x V(x-2ps)s$$

Highly Oscillatory Dynamics	Our work (qHOP)	
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Interaction Picture and Superconvergence		

Numerical results: superconvergence



Highly Oscillatory Dynamics	Our work (qHOP)	
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Interaction Picture and Superconvergence		

qHOP can be viewed as a generalization of the first and second order Trotter formulae.

$$e^{-\mathrm{i}At_n}\mathcal{T}e^{-\mathrm{i}\int_{t_{n-1}}^{t_n}H_I(s)\,ds}\cdots\mathcal{T}e^{-\mathrm{i}\int_0^hH_I(s)\,ds}$$
$$\approx e^{-\mathrm{i}At_n}e^{-\mathrm{i}\int_{t_{n-1}}^{t_n}H_I(s)\,ds}\cdots e^{-\mathrm{i}\int_0^hH_I(s)\,ds}$$

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Use midpoint quadrature rule (remember $H_I(s) = e^{iAs}Be^{-iAs}$)

$$\int_{a}^{b} f(x) dx \approx f\left((a+b)/2\right)(b-a)$$

Highly Oscillatory Dynamics	Our work (qHOP)	
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Interaction Picture and Superconvergence		

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$$e^{-iAt_{n}}e^{-iH_{I}(t_{n+1/2})h}\cdots e^{-iH_{I}(h/2)h}$$

$$=e^{-iAt_{n}}e^{-ie^{iAt_{n+1/2}}Be^{-iAt_{n+1/2}h}}\cdots e^{-ie^{iAh/2}Be^{-iAh/2}h}$$

$$=e^{-iAt_{n}}e^{iAt_{n+1/2}}e^{-iBh}e^{-iAt_{n+1/2}}\cdots e^{iAh/2}e^{-iBh}e^{-iAh/2}$$

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Highly Oscillatory Dynamics		Our work (qHOP)	
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Interaction Picture and Superconvergence	A		

qHOP can be viewed as a generalization of the first and second order Trotter formulae.

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$$=e^{-iAh/2}e^{-iBh}e^{-iAh}e^{-iBh}\cdots e^{-iAh}e^{-iBh}e^{-iAh/2}.$$

This is the second order Trotter formula!

Highly Oscillatory Dynamics		Our work (qHOP)	
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Interaction Picture and Superconvergence	A		

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This is the second order Trotter formula! (Similarly, end-point quadrature rule gives the first order Trotter.)

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Major Question	Our work (qHOP)	Conclusion and Remarks
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	Major Question	Major Question Our work (qHOP) 000 00 0000000000 0000000000

Conclusion and Remark

We propose a simple algorithm, called quantum Highly Oscillatory Protocol (qHOP), which does not require complicated quantum control logic for handling time-ordering operators.

This new algorithm:

- to our knowledge, is the **first** quantum algorithm that is proved to simultaneously exhibit commutator scaling (in high precision limit) and remain insensitive to fast oscillations of *H*(*t*).
- when applying to the interaction picture, can be viewed as a generalization of the first and second order Trotter formulae.
- achieves superconvergence for the digital simulation of the Schrödinger equation, achieving a surprising second order convergence *independent* of the number of spatial grids N.

	Our work (qHOP)	Conclusion and Remarks
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Superconvergence for other A and B? What is the criterion for general A and B to achieve such superconvergence? Is there simpler argument/proofs?

Highly Oscillatory Dynamics	Our work (qHOP)	Conclusion and Remarks
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- Superconvergence for other A and B? What is the criterion for general A and B to achieve such superconvergence? Is there simpler argument/proofs?
- Asymptotically, high-order generalization?

 $\mathcal{T}e^{-\mathrm{i}\int_{0}^{t}H(s)\,ds} = e^{\mathrm{i}\int_{0}^{t}H(t_{1})\,\,\mathrm{d}t_{1} - \frac{1}{2}\int_{0}^{t}\mathrm{d}t_{1}\int_{0}^{t_{1}}\mathrm{d}t_{2}\,\,[H(t_{1}),H(t_{2})] + \cdots$

Conjecture: It keeps the best asymptotic scaling as the truncated Dyson series and exhibits commutator scaling at the same time.

Highly Oscillatory Dynamics	Our work (qHOP)	Conclusion and Remarks
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Practical implementation: other low order algorithms.

Highly Oscillatory Dynamics	Our work (qHOP)	Conclusion and Remarks
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Conjecture: It keeps the best asymptotic scaling as the truncated Dyson series and exhibits commutator scaling at the same time.

 Practical implementation: other low order algorithms.
 Conjecture: Superconvergence for low order truncations. (observed numerically; proof ongoing)

Highly Oscillatory Dynamics	Our work (qHOP)	Conclusion and Remarks
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- Superconvergence for other A and B? What is the criterion for general A and B to achieve such superconvergence? Is there simpler argument/proofs?
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- Practical implementation: other low order algorithms.
 Conjecture: Superconvergence for low order truncations. (observed numerically; proof ongoing)
- Problem set-up with physical/chemical applications.
- Explicit dimension dependence.

	Our work (qHOP)	Conclusion and Remarks
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References

1. Time-dependent Hamiltonian Simulation of Highly Oscillatory Dynamics, (with Dong An and Lin Lin) [arXiv:2111.03103].

2. Time-dependent unbounded Hamiltonian simulation with vector norm scaling, (with Dong An and Lin Lin), Quantum, 2021 [arXiv 2012.13105].

Thank you for your attention! (and ...)

IPAM long program "Mathematical and Computational Challenges in Quantum Computing", Fall 2023



Workshop 1: Quantum algorithms for scientific computation

Workshop 2: Mathematical aspects of quantum learning

Workshop 3: Many-body quantum systems via classical and quantum computation

Workshop 4: Topology, quantum error correction and quantum gravity

Lecture Notes on "Quantum Algorithms for Scientific Computation" by Lin Lin [arXiv:2201.08309]