

Swarm dynamics and equilibria for a nonlocal aggregation model

Razvan C. Fetecau

Department of Mathematics, Simon Fraser University

<http://www.math.sfu.ca/~van/>

work with Y. Huang (Simon Fraser Univ.) and T. Kolokolnikov (Dalhousie Univ.)

Self-organizing animal aggregations

- Animal groups with a high structural order
- The behaviour of individuals is so coordinated, that the group moves as a single coherent entity
- Examples of self-organizing biological groups
 - schooling fish
 - herds of ungulates
 - swarming insects
 - zigzagging flocks of birds

Mathematical models

- The existing models fall into 2 categories: **Lagrangian** and **Eulerian**
- **Lagrangian** models: trajectories of all individuals of a species are tracked according to a set of interaction and decision rules
 - a large set of coupled ODE's
 - a large set of coupled difference equations (discrete time)
- **Eulerian** models: the problem is cast as an evolution equation for the population density field
 - parabolic
 - hyperbolic

A nonlocal Eulerian PDE swarming model

- We study the PDE aggregation model in \mathbb{R}^n :

- continuity equation for the density ρ :

$$\rho_t + \nabla \cdot (\rho v) = 0$$

- the velocity v is assumed to have a functional dependence on the density

$$v = -\nabla K * \rho$$

- the potential K incorporates social interactions: attraction and repulsion

- The model was first suggested by Mogilner and Keshet, *J. Math. Biol.* [1999]
- Literature on this model has been very rich in recent years

Lagrangian description

N individuals; $X_i(t)$ = spatial location of the i -th individual at time t

$$\frac{dX_i}{dt} = -\frac{1}{N} \sum_{\substack{j=1 \dots N \\ j \neq i}} \nabla_i K(X_i - X_j), \quad i = 1 \dots N$$

PDE: continuum approximation, as $N \rightarrow \infty$

Assumption: social interactions depend only on the relative distance between the individuals

$$K(x) = K(|x|)$$

Notation: $F(r) = -K'(r)$

$$\frac{dX_i}{dt} = \frac{1}{N} \sum_{\substack{j=1 \dots N \\ j \neq i}} F(|X_i - X_j|) \frac{X_i - X_j}{|X_i - X_j|}, \quad i = 1 \dots N$$

$F(|X_i - X_j|)$ = magnitude of the force that the individual X_j exerts on the individual X_i , along $X_i - X_j$.

Repulsion ($F(r) > 0$) acts at **short** ranges, **attraction** ($F(r) < 0$) at **long** ranges.

Motivation for this work

- **Equilibria** of the model should have biologically relevant features:
 - finite densities
 - sharp boundaries
 - relatively constant internal population
- The main **motivation** for this work is to
 - **design** interaction potentials K which lead to such equilibria
 - investigate analytically and numerically the well-posedness and long time behaviour of solutions

Interaction potential K

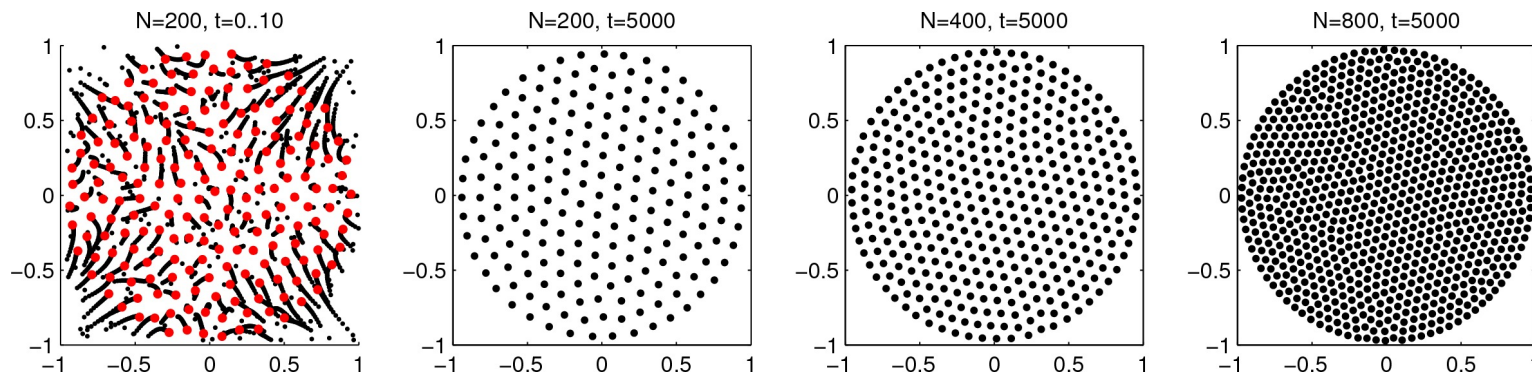
$$\begin{aligned} K(x) &= K_r + K_a \\ &= \phi(x) + \frac{1}{q}|x|^q, \quad q > 2 - n \end{aligned}$$

$\phi(x)$ = the free-space Green's function for $-\Delta$:

$$\phi(x) = \begin{cases} -\frac{1}{2\pi} \ln |x|, & n = 2 \\ \frac{1}{n(n-2)\omega_n} \frac{1}{|x|^{n-2}}, & n \geq 3 \end{cases}$$

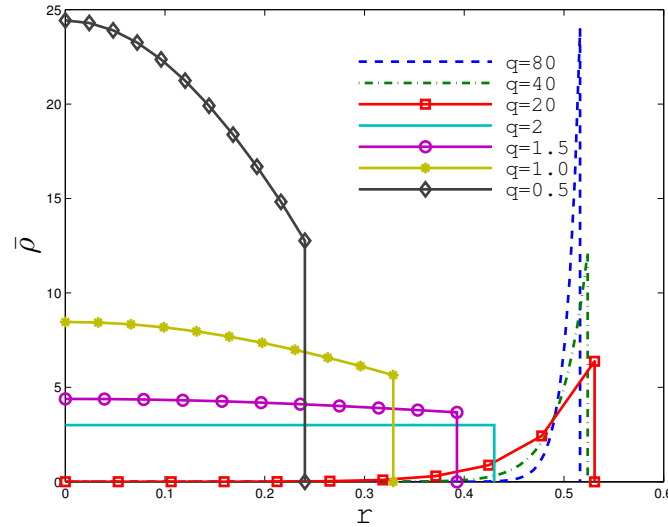
Example a. $n = 2, q = 2$: $K(x) = -\ln |x| + \frac{1}{2}|x|^2$; $F(r) = \underbrace{\frac{1}{r}}_{\text{repulsion}} - \underbrace{r}_{\text{attraction}}$

Random initial conditions inside the unit square. The solution approaches a constant density in the unit disk.



Example b. $n = 3$, various q

$$K(x) = \frac{1}{4\pi|x|} + \frac{1}{q}|x|^q, \quad q > -1$$



- The equilibria are monotone in the radial coordinate: decreasing about the origin for $2 - n < q < 2$, increasing for $q > 2$, and constant for $q = 2$.
- As $q \rightarrow \infty$, the radii of the equilibria approach a constant, and mass aggregates toward the edge of the swarm.
- As $q \searrow 2 - n$, the radii of equilibria approach 0 and mass concentrates at the origin.
- Numerics suggests that all these equilibria are global attractors for the dynamics.

Benefits of the Newtonian repulsion

Our model:

$$\rho_t + \nabla \cdot (\rho v) = 0, \quad v = -\nabla K * \rho$$

$$K(x) = \phi(x) + \frac{1}{q}|x|^q, \quad q > 2 - n$$

Expand $\nabla \cdot$ in the equation: $\rho_t + v \cdot \nabla \rho = -\rho \operatorname{div} v$

Calculate $\operatorname{div} v$:

$$\begin{aligned} \operatorname{div} v &= \operatorname{div}(-\nabla K * \rho) \\ &= -\Delta K * \rho \\ &= \rho - \Delta\left(\frac{1}{q}|x|^q\right) * \rho \end{aligned}$$

The repulsion term has become **local**!

Lagrangian approach

Characteristic curves: $\frac{d}{dt}X(\alpha, t) = v(X(\alpha, t), t), \quad X(\alpha, 0) = \alpha$

Evolution equation for $\rho(X(\alpha, t), t)$:

$$\frac{D\rho}{Dt} = -\rho^2 + \rho \Delta\left(\frac{1}{q}|x|^q\right) * \rho$$

Special case $q = 2$: explicit calculations

$$\Delta\left(\frac{1}{2}|x|^2\right) = n, \quad \Delta\left(\frac{1}{2}|x|^2\right) * \rho = n \underbrace{\int_{\mathbb{R}^n} \rho(y) dy}_{=M}$$

ODE along characteristics: $\frac{D\rho}{Dt} = -\rho(\rho - nM)$

Exact solution: $\rho(X(\alpha, t), t) = \frac{nM}{1 + \left(\frac{nM}{\rho_0(\alpha)} - 1\right)e^{-nMt}}$

Asymptotic behaviour as $t \rightarrow \infty$?

Asymptotic behaviour $t \rightarrow \infty$

Density: $\rho(X, t) \rightarrow nM$, as $t \rightarrow \infty$, along particle paths with $\rho_0(\alpha) \neq 0$

Asymptotic behaviour of trajectories: $R_\alpha = \lim_{t \rightarrow \infty} |X(\alpha, t)|$

For radial solutions, it can be proved that trajectories are mapped into the ball of \mathbb{R}^n of radius $R_\alpha = \frac{1}{(n\omega_n)^{\frac{1}{n}}}$.

Numerics suggest that *all* solutions have this asymptotic behaviour.

Global attractor: constant, compactly supported density:

$$\bar{\rho}(x) = \begin{cases} nM & \text{if } |x| < \frac{1}{(n\omega_n)^{\frac{1}{n}}} \\ 0 & \text{otherwise} \end{cases}$$

Global existence of particle paths

$$v(x) = \int_{\mathbb{R}^n} k(x - y) \rho(y) dy - Mx, \quad (1)$$

where
$$k(x) = \frac{1}{n\omega_n} \frac{x}{|x|^n}$$

The convolution kernel k is singular, homogeneous of degree $1 - n$.

Equation (1) is analogous to Biot-Savart law, where vorticity ω is now replaced by density ρ .

Existence and uniqueness of particle paths follow similarly to that for incompressible Euler equations.

Extension to global existence: [Beale-Kato-Majda criterion](#)

$$\int_0^t \|\rho(\cdot, s)\|_{L^\infty} ds < \infty, \text{ for all finite times } t$$

Analysis extends to general exponent $q > 2 - n$.

Case $q \neq 2$: Non-constant steady states

Assume (based on numerics) that the model admits a steady state supported on a ball $B(0, R)$.

Recall formula for $\operatorname{div} v$: $\operatorname{div} v = \rho - \Delta\left(\frac{1}{q}|x|^q\right) * \rho$

Equilibria supported on $B(0, R)$:

$$v = 0, \text{ hence } \operatorname{div} v = 0 \text{ in } B(0, R)$$

A steady state $\bar{\rho}$ satisfies:

$$\bar{\rho} - (n + q - 2) \int_{\mathbb{R}^n} |x - y|^{q-2} \bar{\rho}(y) dy = 0 \quad \text{in } B(0, R)$$

Define operator T_R : $T_R \bar{\rho}(x) = (n + q - 2) \int_{B(0, R)} |x - y|^{q-2} \bar{\rho}(y) dy$

Solutions $\bar{\rho}$ are eigenfunctions of T_R corresp. to eigenvalue 1:

$$T_R \bar{\rho} = \bar{\rho}$$

Existence and uniqueness of equilibria

Theorem. For every $q > 2 - n$ and $M > 0$, there exists a unique radius R (that depends on q and n only) and a unique steady state $\bar{\rho}$ that is supported on $B(0, R)$, has mass M and is continuous on its support.

Sketch of **proof**: Consider case $R = 1$ first.

$$T_1 \bar{\rho}(x) = (n + q - 2) \int_{B(0,1)} |x - y|^{q-2} \bar{\rho}(y) dy$$

T_1 is a linear, strongly positive, compact operator that maps the space of continuous functions $C([0, 1], \mathbb{R})$ into itself.

Krein-Rutman theorem: there exists a *positive* eigenfunction $\bar{\rho}_1$ such that

$$T_1 \bar{\rho}_1 = \lambda \bar{\rho}_1 \tag{2}$$

$\lambda(q, n)$ is the spectral radius of T_1 ; it is a simple eigenvalue and there is no other eigenvalue with a positive eigenvector.

Define, by rescaling: $\bar{\rho}(r) = \bar{\rho}_1(r/R)$, introduce in (2):

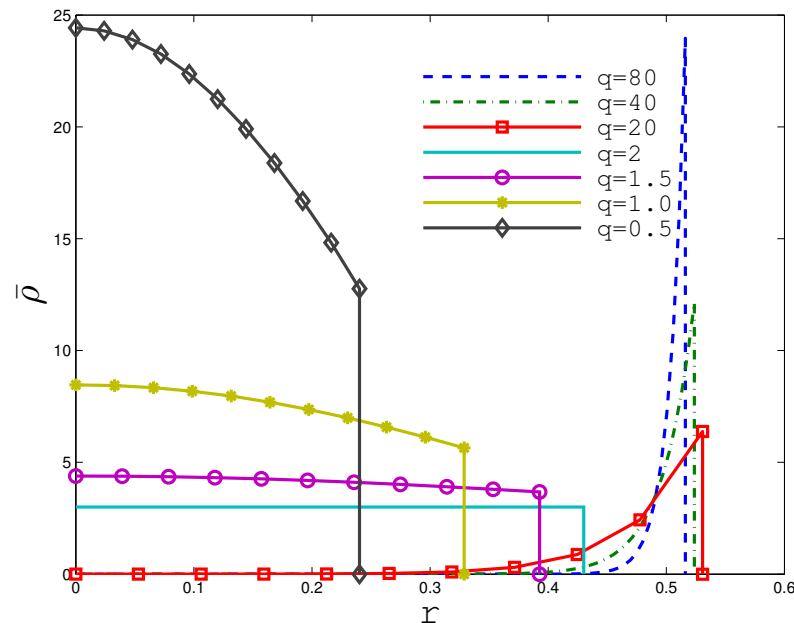
$$T_R \bar{\rho}(r) = \underbrace{R^{n+q-2}}_{=1} \lambda \bar{\rho}(r)$$

Find $R = \lambda^{-\frac{1}{n+q-2}}$.

Qualitative properties of equilibria

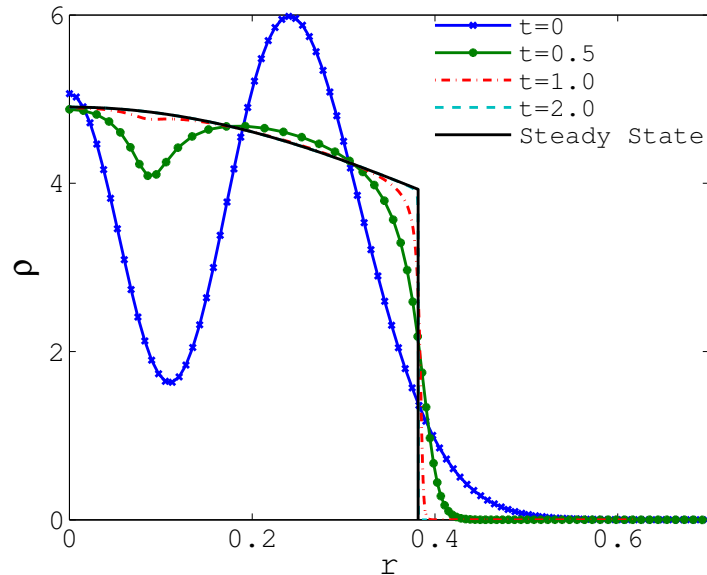
Theorem. Consider a bounded steady state $\bar{\rho}(x)$ that is supported in a ball $B(0, R)$ of \mathbb{R}^n . Then, $\bar{\rho}$ is **radially symmetric** and **monotone** about the origin. More specifically, we distinguish two cases: (i) $2 - n < q < 2$, when $\bar{\rho}$ is decreasing about the origin, and (ii) $q > 2$, when $\bar{\rho}$ is increasing.

Proof uses the **method of moving planes**.

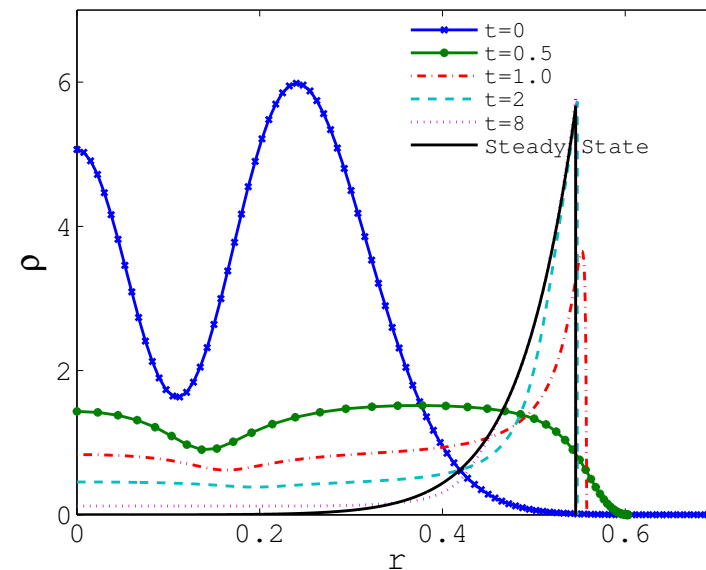


Dynamic evolution to equilibria

Numerical results in $n = 3$ dimensions:



(a) $q = 1.5$



(b) $q = 20$

The solutions approach asymptotically the steady states studied and shown in previous slides.

Numerics with a variety of other initial conditions suggests that these equilibria are global attractors for the dynamics.

Asymptotic behavior of equilibria: $q \rightarrow \infty$ and $q \searrow 2 - n$

First consider case $R = 1$ and the eigenvalue problem

$$T_1 \bar{\rho}_1(x) = \lambda \bar{\rho}_1(x), \quad \text{for } x \in B(0, 1),$$

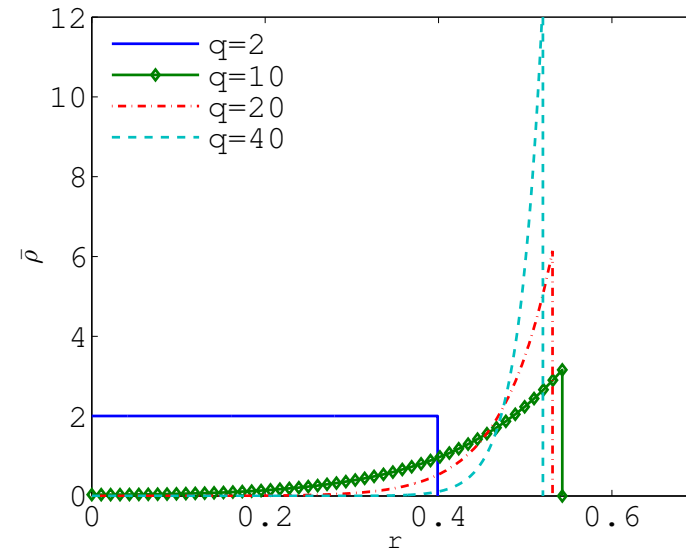
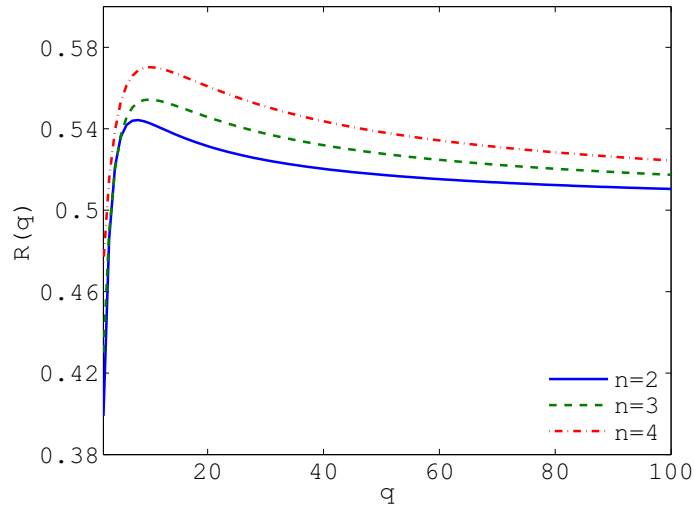
with

$$T_1 \bar{\rho}_1(x) = (n + q - 2) \int_{B(0,1)} |x - y|^{q-2} \bar{\rho}_1(y) dy$$

Goal: Use [perturbation methods](#) to find approximations for λ (spectral radius of T_1) and $\bar{\rho}_1$ (corresponding eigenvector).

Then, consider general R and find approximations to equilibrium solution $\bar{\rho}(r) = \bar{\rho}_1(r/R)$ and its radius of support $R = \lambda^{-\frac{1}{n+q-2}}$.

Asymptotic behavior $q \rightarrow \infty$



Numerics suggests: the radius of the support R approaches a constant, as $q \rightarrow \infty$ (left).

As q increases, mass aggregates toward the edge of the swarm, creating an increasingly void region in the centre (right).

$$\begin{aligned} \lambda \bar{\rho}_1(x) &= (n + q - 2) \int_{B(0,1)} |x - y|^{q-2} \bar{\rho}_1(y) dy \\ &\approx (n + q - 2) \bar{\rho}_1(1) \int_{B(0,1)} |x - y|^{q-2} dy. \end{aligned}$$

Evaluate at $x = 1$, cancel $\bar{\rho}_1(1)$ and find a *coarse* approximation to λ .

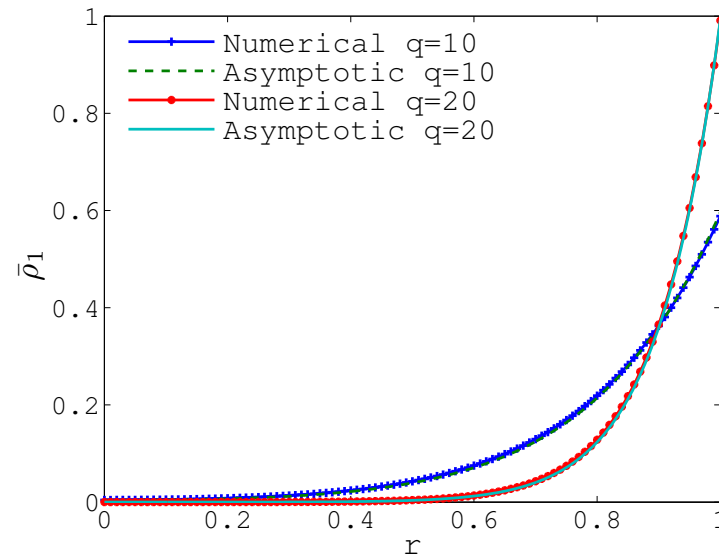
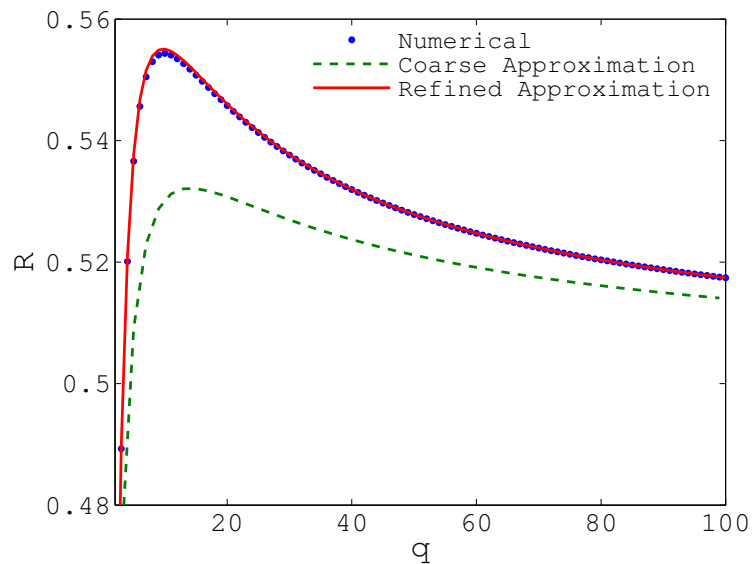
$$\lambda \approx (n-1)\omega_{n-1}2^{n+q-3}\Gamma(\frac{n-1}{2})\Gamma(\frac{n+q-1}{2})/\Gamma(n-1+\frac{q}{2})$$

Approximate $\bar{\rho}_1$:

$$\bar{\rho}_1(r) \approx C \int_0^\pi \sin^{n-2} \theta (\sqrt{1-r^2 \sin^2 \theta} - r \cos \theta)^{n+q-2} d\theta,$$

Iterate the procedure to find a *refined* approximation for λ .

Find approximations for R .



$n = 3$: Numerical and asymptotic solutions, as $q \rightarrow \infty$. There is excellent agreement between the two solutions.

Asymptotic behavior $q \searrow 2 - n$

Denote $q = 2 - n + \epsilon$, $\epsilon > 0$

Asymptotic study in the small ϵ regime

$$\lambda_\epsilon \bar{\rho}_1^\epsilon(x) = \epsilon \int_{B(0,1)} \frac{1}{|x-y|^{n-\epsilon}} \bar{\rho}_1^\epsilon(y) dy, \quad \epsilon = q - 1. \quad (3)$$

Asymptotic expansion (suggested by numerical simulations)

$$\lambda_\epsilon = \lambda_0 + \lambda_1 \epsilon + \lambda_2 \epsilon^2 + \dots$$

$$\bar{\rho}_1^\epsilon(x) = \bar{\rho}^{(0)}(x) + \epsilon \bar{\rho}^{(1)}(x) + \epsilon^2 \bar{\rho}^{(2)}(x) + \dots$$

The kernel $\frac{1}{|x-y|^{n-\epsilon}}$ is not integrable for $\epsilon = 0$, so we can not substitute the formal expansions into (3) directly.

Subtract on both sides $k_\epsilon(|x|)\bar{\rho}_1^\epsilon(x)$, where

$$k_\epsilon(|x|) = \epsilon \int_{B(0,1)} \frac{1}{|y-x|^{\epsilon-n}} dy$$

$$(\lambda_\epsilon - k_\epsilon(|x|))\bar{\rho}_1^\epsilon(x) = \epsilon \int_{B(0,1)} \frac{\bar{\rho}_1^\epsilon(y) - \bar{\rho}_1^\epsilon(x)}{|y-x|^{n-\epsilon}} dy, \quad r = |x|,$$

The integral in RHS is now $O(1)$ for $\epsilon = 0$, provided $\bar{\rho}^{(0)}$ is Hölder continuous

Expand: $k_\epsilon(r) = n\omega_n + \frac{n\omega_n}{2} \ln(1-r^2)\epsilon + k^{(2)}(r)\epsilon^2 + O(\epsilon^3)$

Match powers of ϵ on both sides:

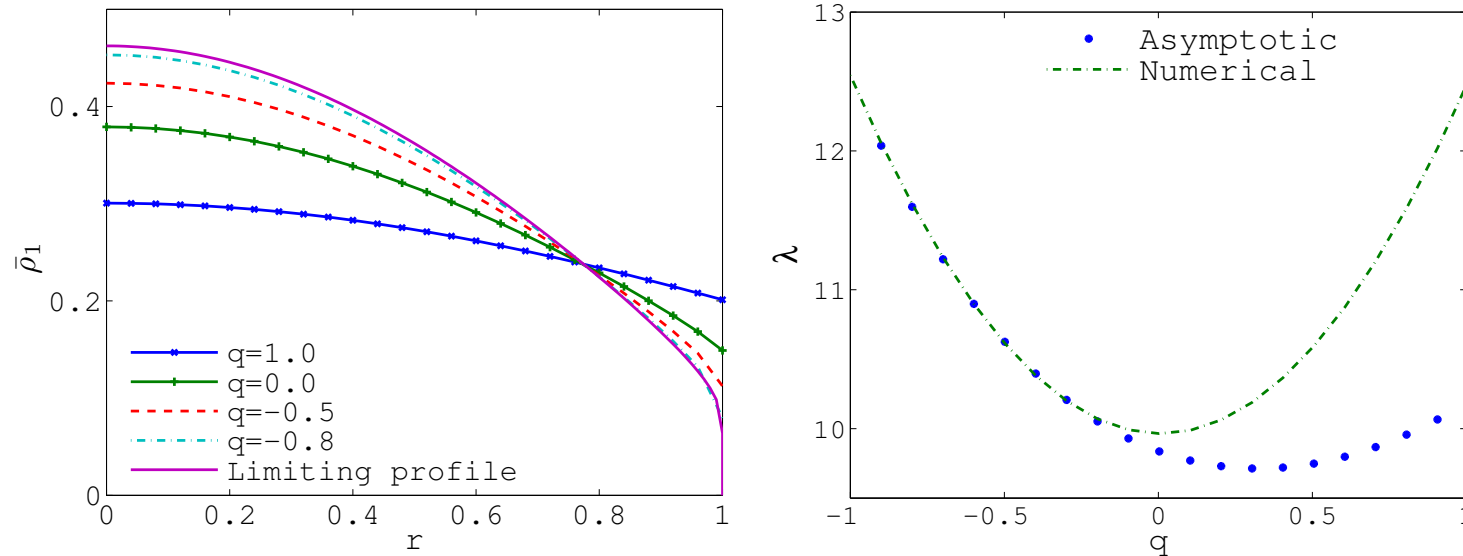
$$O(1) : \quad \lambda_0 - n\omega_n = 0$$

$$O(\epsilon) : \quad \int_{B(0,1)} \frac{\bar{\rho}^{(0)}(x) - \bar{\rho}^{(0)}(y)}{|y-x|^n} dy - \left(\lambda_1 - \frac{1}{2}n\omega_n \ln(1-|x|^2)\right)\bar{\rho}^{(0)}(x) = 0$$

Leading order: $\lambda_0 = \text{const.}$ and limiting profile $\bar{\rho}^{(0)}$ (solved by inverse iteration)

$q \searrow 2 - n$: Numerics \sim asymptotics

$n = 3$ (critical value $q = -1$)



Left: Equilibria $\bar{\rho}_1^\epsilon$ for $\epsilon = 2, 1, 0.5, 0.2$ ($q = 1, 0, -0.5, -0.8$).

The plain solid line is the **limiting profile** $\bar{\rho}^{(0)}$ found from asymptotics. As $\epsilon \rightarrow 0$, $\bar{\rho}_1^\epsilon$ approaches the limiting profile, confirming the asymptotic expansion.

Right: Eigenvalues obtained numerically (dots) and from the asymptotic expansion valid at order $O(\epsilon^2)$. Excellent agreement for small ϵ ($q \approx -1$).

Remark. As $q \searrow 2 - n$, radius $R = \lambda^{-1/(n+q-2)} = \lambda^{-1/\epsilon}$ of support approaches 0 exponentially fast and $\bar{\rho}(r) = \bar{\rho}_1(r/R)$ converges to a Dirac delta.

Even q : polynomial steady states

Integral equation for $\bar{\rho}$ in radial coordinates:

$$\bar{\rho}(r) = c(q, n) \int_0^R (r')^{n-1} \bar{\rho}(r') I(r, r') dr', \quad 0 \leq r < R$$

$$I(r, r') = \int_0^\pi (r^2 + (r')^2 - 2rr' \cos \theta)^{q/2-1} \sin^{n-2} \theta d\theta.$$

Kernel $I(r, r')$ is separable when q is even.

Define the i -th order moments of the density ($m_0 = M$):

$$m_i = n\omega_n \int_0^R r^{n+i-1} \bar{\rho}(r) dr. \quad (4)$$

Example: $q = 4$

$$I(r, r') = (r^2 + (r')^2) \int_0^\pi \sin^{n-2} \theta d\theta$$

$$\bar{\rho}(r) = (n+2)m_0 r^2 + (n+2)m_2 \quad (5)$$

Plug (5) into (4): find a linear system to solve for m_0 and m_2

General q even: $\bar{\rho}(r)$ is a polynomial of **even** powers, of degree $q - 2$

Inverse problem: custom designed potentials

Inverse problem: given a density $\bar{\rho}(x)$, can we find a potential K for which $\bar{\rho}(x)$ is a steady state of the model?

Answer: Yes, provided $\bar{\rho}(x)$ is radial and is a polynomial in $|x|$.

Theorem: In dimensions $n = 2$ or $n = 3$, consider a radially symmetric density $\bar{\rho}(x) = \bar{\rho}(|x|)$ of the form

$$\bar{\rho}(r) = \begin{cases} b_0 + b_2 r^2 + b_4 r^4 + \dots + b_{2d} r^{2d} & |x| < R \\ 0 & \text{otherwise.} \end{cases}$$

Then $\bar{\rho}(r)$ is the steady state corresponding to the force

$$F(r) = \frac{1}{n\omega_n} \frac{1}{r^{n-1}} - \sum_{i=0}^d \frac{a_{2i}}{2i+n} r^{2i+1},$$

where the constants a_0, a_2, \dots, a_{2d} , are computed uniquely from b_0, b_2, \dots, b_{2d} by solving a linear system.

Remark: Case $d = 0$ corresponds to family $q = 2$ from previous slides:

$$\bar{\rho}(r) = \text{const.}, \quad F(r) = \frac{1}{n\omega_n} \frac{1}{r^{n-1}} - Cr$$

Inverse problem: examples

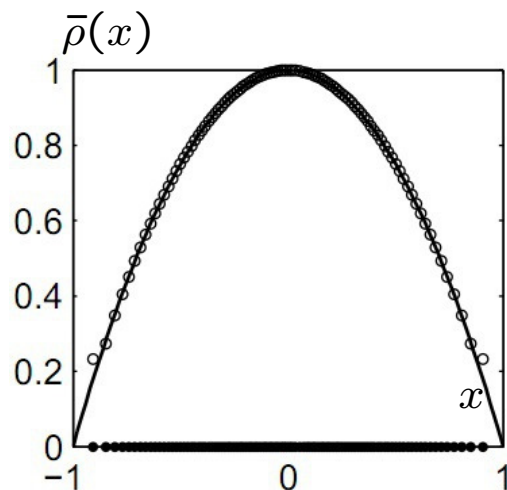
Examples: $n = 1$, $R = 1$

$$(a) \quad \bar{\rho}(x) = 1 - x^2; \quad (b) \quad \bar{\rho}(x) = x^2; \quad (c) \quad \bar{\rho}(x) = \frac{1}{2} + x^2 - x^4$$

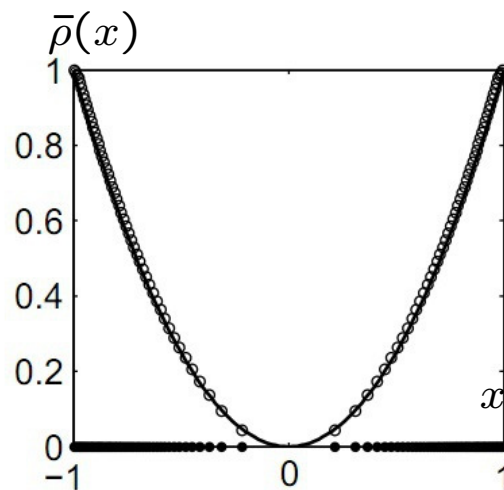
The corresponding forces given by the Theorem are:

$$(a) \quad F(x) = \frac{1}{2} - \frac{9}{10}x + \frac{1}{4}x^3; \quad (b) \quad F(x) = \frac{1}{2} + \frac{9}{10}x - \frac{1}{2}x^3;$$

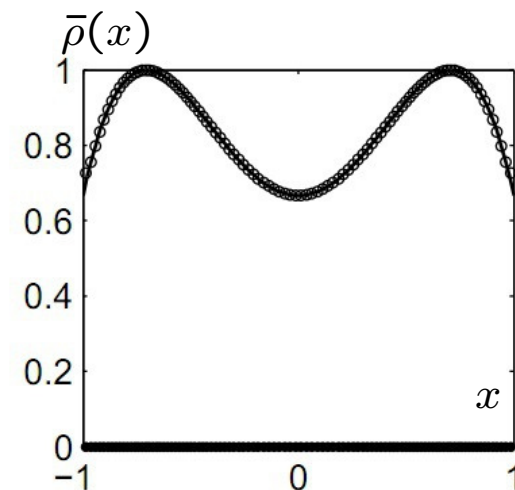
$$(c) \quad F(x) = \frac{1}{2} + \frac{209425}{672182}x - \frac{2075}{2527}x^3 + \frac{3}{19}x^5.$$



(a)



(b)

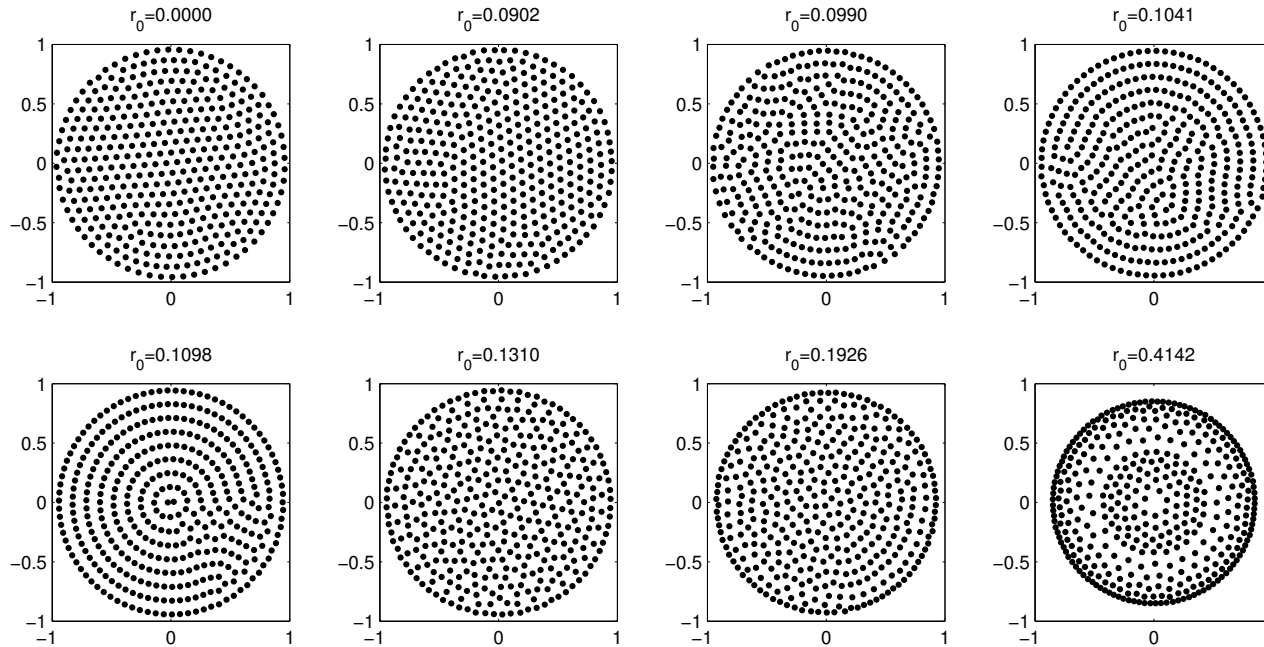
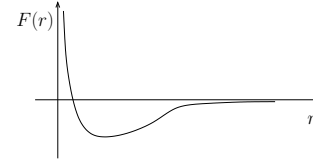


(c)

Filled circles along the x -axis: the steady states reached by numerical time evolution. Empty circles: density function as computed from the filled circles. Solid line: analytical expression for $\bar{\rho}$.

Regularized potentials

$$F(r) = \frac{1}{r} - r \xrightarrow{\text{regularize}} F(r) = \begin{cases} C_1, & 0 \leq r < r_0 \\ \frac{1}{r} - r, & r_0 \leq r \leq 2 \\ -C_2 \exp(-r), & 2 < r \end{cases} \quad (6)$$



Equilibrium states for the regularized interaction force (6). Initial conditions were chosen at random in the unit square. For $r_0 < 0.09$, the steady state is the same as for $r_0 = 0$ (uniform density in the unit circle).

Bibliography

1. R.C. Fetecau, Y. Huang and T. Kolokolnikov [2011]. Swarm dynamics and equilibria for a nonlocal aggregation model, *Nonlinearity*, Vol. 24, No. 10, pp. 2681-2716 (featured article)
2. R.C. Fetecau and Y. Huang [2012]. Equilibria of biological aggregations with nonlocal repulsive-attractive interactions, submitted

Future Directions

Energy considerations: local/ global minima

$$E[\rho] = \frac{1}{2} \int_{\mathbb{R}^n} \int_{\mathbb{R}^n} K(x - y) \rho(x) \rho(y) dy dx$$

The model is a gradient flow with respect to this energy:

$$\frac{d}{dt} E[\rho] = - \int_{\mathbb{R}^n} \rho(x) |\nabla K * \rho(x)|^2 dx \leq 0$$