

Dislocation dynamics: from microscopic models to macroscopic crystal plasticity

Régis Monneau

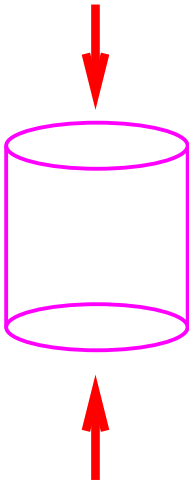
Paris-Est University

UCLA; February 29, 2012

Physical motivation

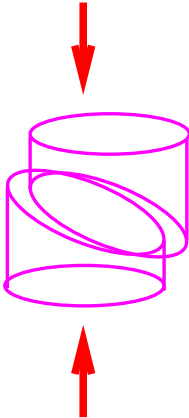
Plasticity of metals

compression of a cylinder



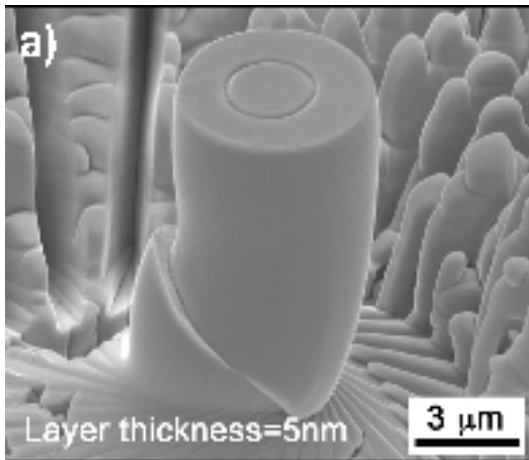
Plasticity of metals

compression of a cylinder



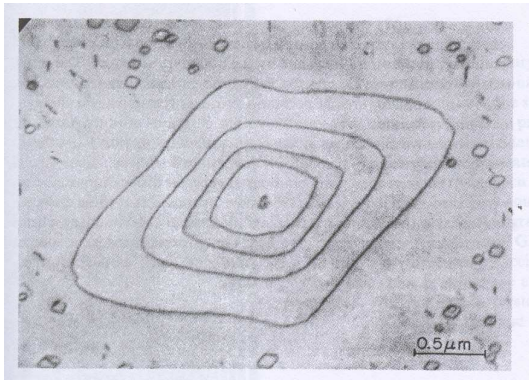
Plasticity of metals

compression of a micro-pillar



Dislocations

Defects in crystal = dislocation loops



Non local, non monotone dynamics

$$u_t = |Du| (c_0 \star 1_{\{u \geq 0\}}) \quad \text{on} \quad \mathbb{R}^N \times (0, T)$$

- “Dynamics of sets”

(Interior ball)

[Alvarez, Cardaliaguet, M. (2005)], [Cardaliaguet, Marchi (2006)],

(Interior cone)

[Barles, Cardaliaguet, Ley, Monteillet (2009)]

- Level sets

[Barles, Ley (2006)],

(Notion of very weak solutions)

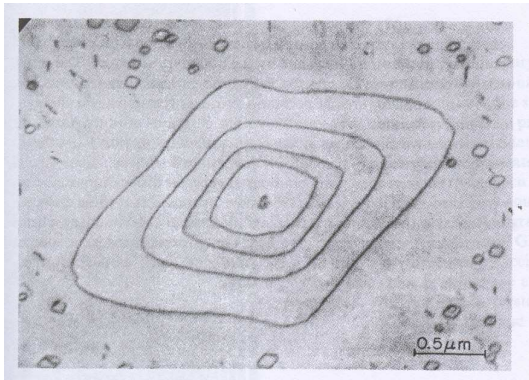
[Barles, Cardaliaguet, Ley, M. (2008)],

[Barles, Cardaliaguet, Ley, Monteillet (2009)],

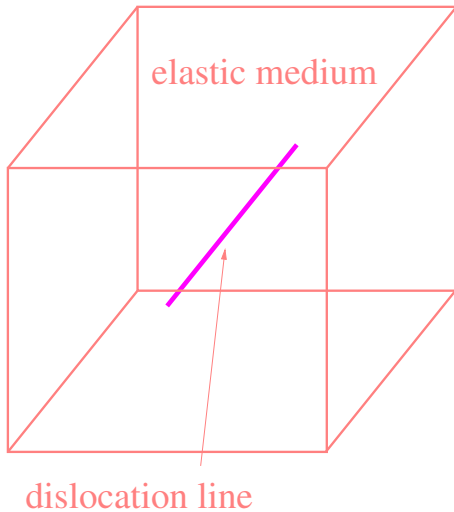
- Numerics : Generalized Fast Marching Method

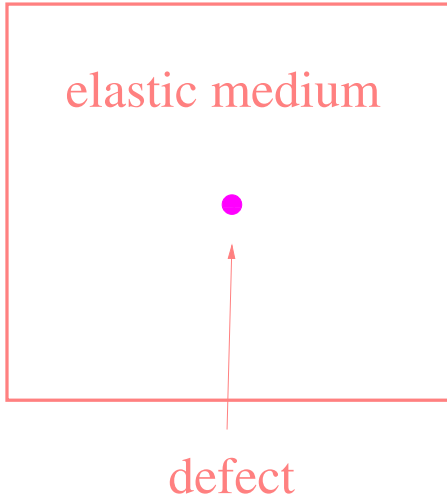
[Carlini, Forcadel, M. (2011)]

Dislocations

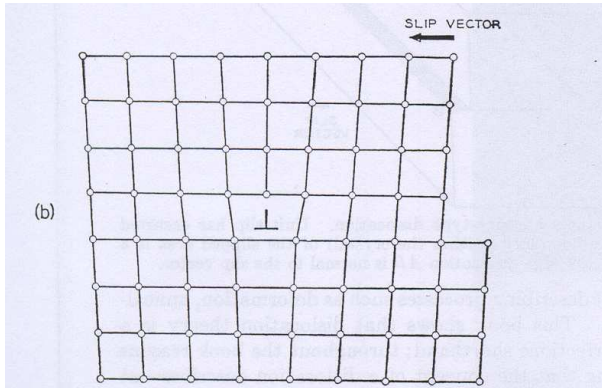


3D continuous model





2D atomic model



Plan of the talk : Hierarchy of scales

(1) Frenkel-Kontorova (atomic)

↓ ($\varepsilon_1 \rightarrow 0$)

(2) Peierls-Nabarro (micro)

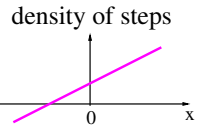
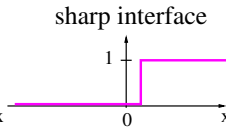
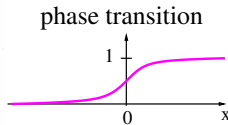
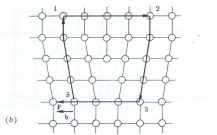
↓ ($\varepsilon_2 \rightarrow 0$)

(3) Dynamics of dislocations (meso)

↓ ($\varepsilon_3 \rightarrow 0$)

(4) Crystal plasticity (macro)

Hierarchy of scales and models



“FK”



PN



DD

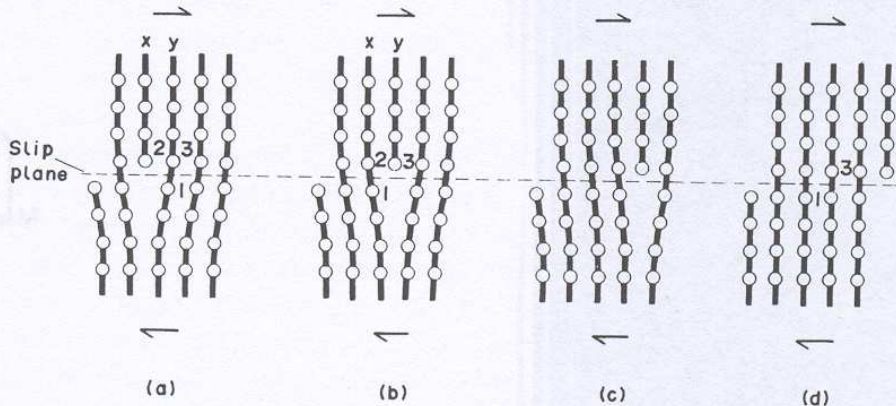


Crystal
plasticity

2D Frenkel-Kontorova model

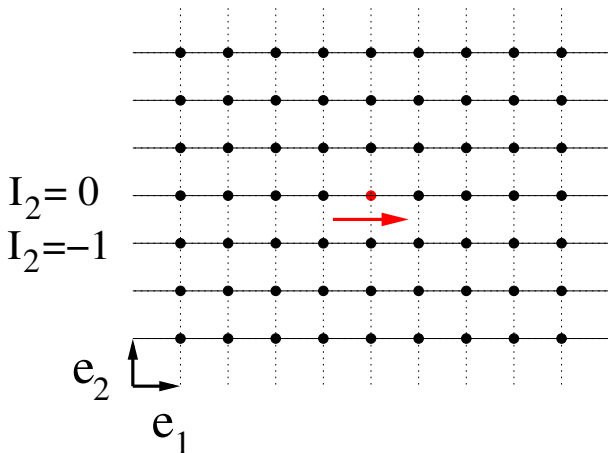
$$(\varepsilon = \varepsilon_1)$$

Motion of a dislocation



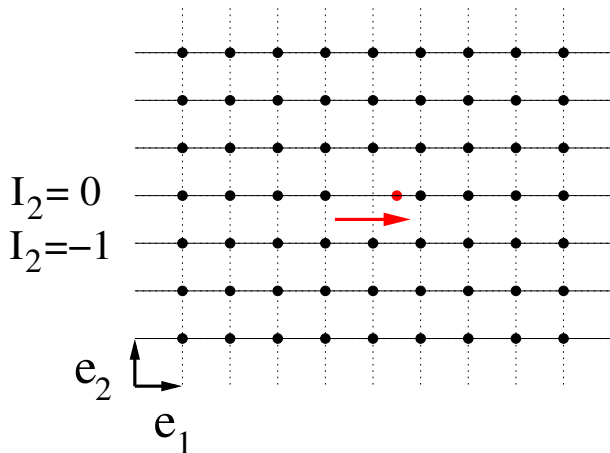
2D Frenkel-Kontorova

Points only move on the **horizontal** axis with $I = (I_1, I_2) \in \mathbb{Z}^2$



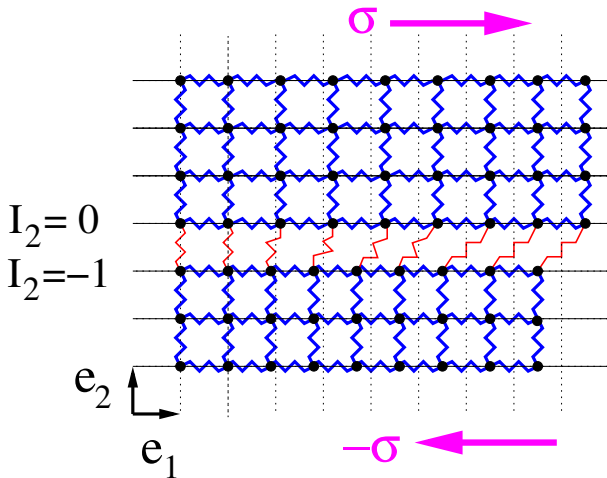
2D Frenkel-Kontorova

Points only move on the **horizontal** axis with $I = (I_1, I_2) \in \mathbb{Z}^2$



2D Frenkel-Kontorova

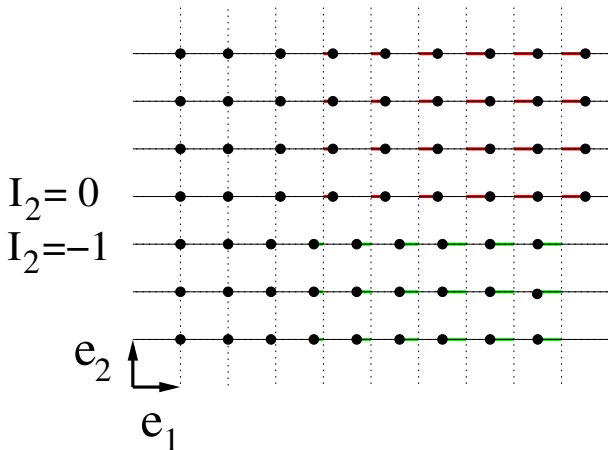
strong springs / weak springs, stress σ



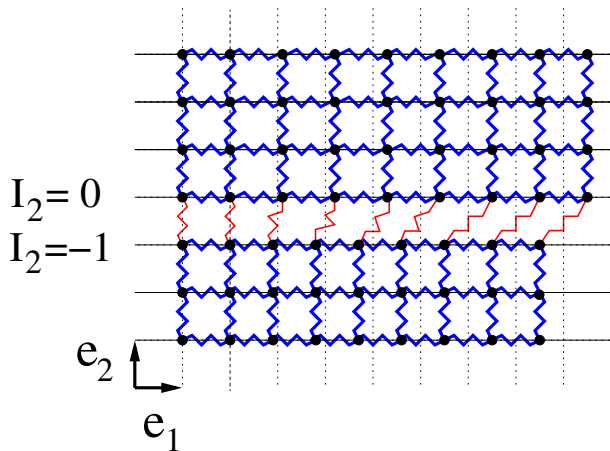
2D Frenkel-Kontorova

Assumption : **antisymmetric horizontal displacement**

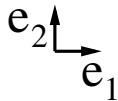
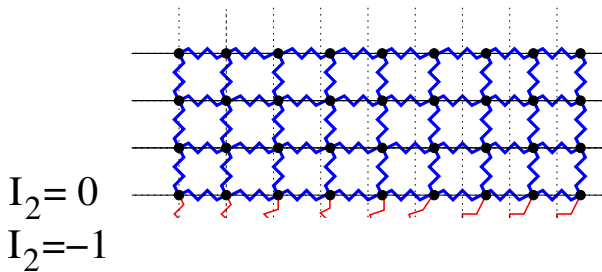
$$U_{(I_1, I_2)} = -U_{(I_1, -I_2 - 1)}$$



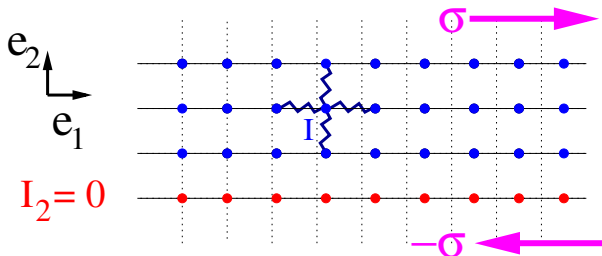
2D Frenkel-Kontorova



Half plane



Equilibrium of the blue points



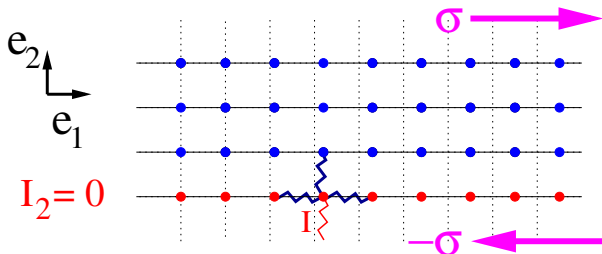
$$I_2 = 0$$

For $I = (I_1, I_2)$ with $I_2 \geq 1$

$$\sum_{J \in \mathbb{Z}^2, |J-I|=1} (U_J - U_I) = 0$$

(harmonic blue springs)

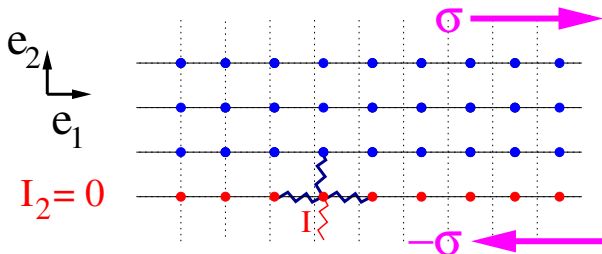
Dynamics of the red points



For $I = (I_1, I_2)$ with $I_2 = 0$

$$\frac{d}{dt}U_I = -\varepsilon W'(U_I) + \sum_{\substack{J \in \mathbb{Z}^2, J_2 \geq 0, \\ |J - I| = 1}} (U_J - U_I)$$

Dynamics of the red points



$$I_2 = 0$$

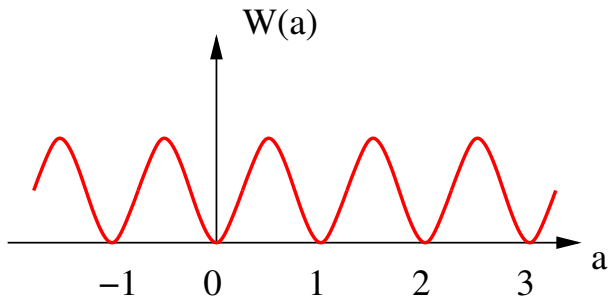
$$I_1$$

For $I = (I_1, I_2)$ with $I_2 = 0$

$$\frac{d}{dt} U_I = \varepsilon \varepsilon_2 \sigma - \varepsilon W'(U_I) + \sum_{\substack{J \in \mathbb{Z}^2, J_2 \geq 0, \\ |J - I| = 1}} (U_J - U_I)$$

$$\left\{ \begin{array}{ll} \sum_{J \in \mathbb{Z}^2, |J-I|=1} (U_J - U_I) = 0 & \text{for } I_2 \geq 1 \\ \frac{d}{dt} U_I = \varepsilon \varepsilon_2 \sigma - \varepsilon W'(U_I) + \sum_{\substack{J \in \mathbb{Z}^2, J_2 \geq 0, \\ |J-I|=1}} (U_J - U_I) & \text{for } I_2 = 0 \end{array} \right. \quad (1)$$

smooth periodic potential $W(a + 1) = W(a)$



W describes the misfit between the two half planes.

Homogenization of 1D FK models

- Fully overdamped FK
[Forcadel, Imbert, M., (2009)]
- FK with acceleration
[Forcadel, Imbert, M., (preprint 2010)]
- FK with parabolic rescaling
[Alibaud, Briani, M. (2010)]

Traveling waves for 1D FK models

- Fully overdamped FK
[work in progress]

Convergence to the Peierls-Nabarro model

$$(\varepsilon = \varepsilon_1 \rightarrow 0)$$

$$u^\varepsilon(X, t) = U_{\frac{X}{\varepsilon}} \left(\begin{array}{c} t \\ \varepsilon \end{array} \right) \quad \text{for } X = (X_1, X_2) \in (\varepsilon\mathbb{Z}) \times (\varepsilon\mathbb{N})$$

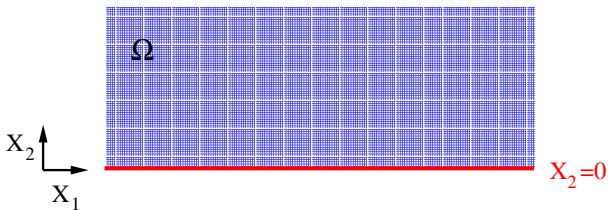
Thm 1 (convergence FK \rightarrow PN) [Fino, Ibrahim, M. (2012)]

As $\varepsilon \rightarrow 0$, we have

$$u^\varepsilon \rightarrow u^0 \quad \text{in} \quad L_{loc}^\infty(\mathbb{R}_+^2 \times [0, +\infty))$$

with u^0 solution of the PN model.

Peierls-Nabarro model



For $u^0(X_1, X_2, t)$:

$$\left\{ \begin{array}{ll} 0 = \Delta u^0 & \text{on } \Omega = \{X_2 > 0\} \\ u_t^0 = \varepsilon_2 \sigma - W'(u^0) + \frac{\partial u^0}{\partial X_2} & \text{for } \partial\Omega = \{X_2 = 0\} \end{array} \right.$$

Reformulation of the PN model

$$\left\{ \begin{array}{ll} 0 = \Delta u^0 & \text{on } \Omega \\ u_t^0 = \varepsilon_2 \sigma - W'(u^0) + \frac{\partial u^0}{\partial X_2} & \text{on } \partial\Omega \end{array} \right.$$

$$\begin{cases} 0 = \Delta u^0 & \text{on } \Omega \\ u_t^0 = \varepsilon_2 \sigma - W'(u^0) + \frac{\partial u^0}{\partial X_2} & \text{on } \partial\Omega \end{cases}$$

$\implies v(x, t) := u^0(x, 0, t)$ satisfies with $\varepsilon = \varepsilon_2$

$$v_t = \varepsilon \sigma - W'(v) + \Delta^{\frac{1}{2}} v \quad \text{for } x \in \mathbb{R} \quad (2)$$

with the **Lévy-Khintchine formula**

$$(\Delta^{\frac{1}{2}} w)(x) = \frac{1}{\pi} \int_{\mathbb{R}} \frac{dz}{z^2} (w(x+z) - w(x) - zw'(x)1_{\{|z| \leq 1\}})$$

$$v_t = \varepsilon\sigma - W'(v) + \Delta^{\frac{1}{2}}v$$

Homogenization of PN on \mathbb{R}^N : [M., Patrizi (2012)]

$$v_t = \varepsilon\sigma - W'(v) + \Delta^{\frac{1}{2}}v$$

Homogenization of PN on \mathbb{R}^N : [M., Patrizi (2012)]

Traveling waves for PN : [Gui, Zhao (2012)]

$$v_t = \varepsilon \sigma - W'(v) + \Delta^{\frac{1}{2}} v$$

Homogenization of PN on \mathbb{R}^N : [M., Patrizi (2012)]

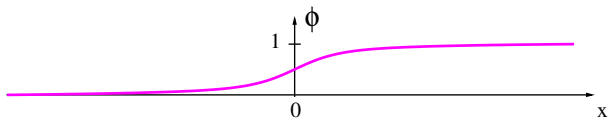
Traveling waves for PN : [Gui, Zhao (2012)]

Rescaling to curvature models :

- MCM : [Imbert, Souganidis (2009)]
[Caffarelli, Souganidis (2010)]
- Variational : [Garroni, Müller (2006)]

The layer solution

[Cabré, Solà-Morales, (2005)]



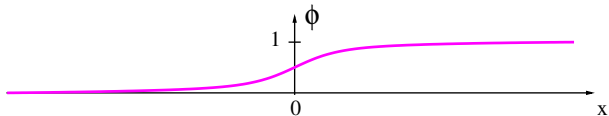
$$\begin{cases} 0 = -W'(\phi) + \Delta^{\frac{1}{2}}\phi & \text{on } \mathbb{R} \\ \phi' > 0, \quad \phi(-\infty) = 0, \quad \phi(+\infty) = 1, \quad \phi(0) = \frac{1}{2} \end{cases}$$

assuming

$$W''(0) > 0$$

The layer solution

[Cabré, Solà-Morales, (2005)]



$$\begin{cases} 0 = -W'(\phi) + \Delta^{\frac{1}{2}}\phi & \text{on } \mathbb{R} \\ \phi' > 0, \quad \phi(-\infty) = 0, \quad \phi(+\infty) = 1, \quad \phi(0) = \frac{1}{2} \end{cases}$$

assuming

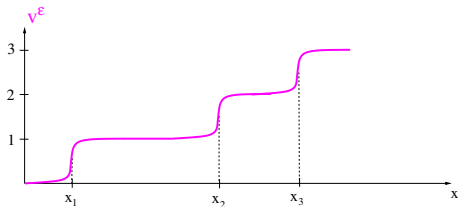
$$W''(0) = 1$$

Convergence to Dislocation points dynamics

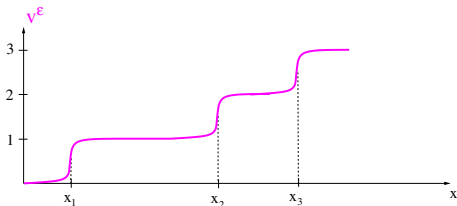
$$(\varepsilon = \varepsilon_2 \rightarrow 0)$$

Parabolic rescaling

$$v^\varepsilon(x, t) = v\left(\frac{x}{\varepsilon}, \frac{t}{\varepsilon^2}\right) \quad \text{for } x \in \mathbb{R}$$



$$v^\varepsilon(x, t) = v\left(\frac{x}{\varepsilon}, \frac{t}{\varepsilon^2}\right) \quad \text{for } x \in \mathbb{R}$$



Well-prepared initial data

$$\begin{cases} x_1^0 < x_2^0 < \dots < x_N^0 \\ v_0^\varepsilon(x) = \varepsilon\sigma + \sum_{i=1}^N \phi\left(\frac{x - x_i^0}{\varepsilon}\right) \end{cases}$$

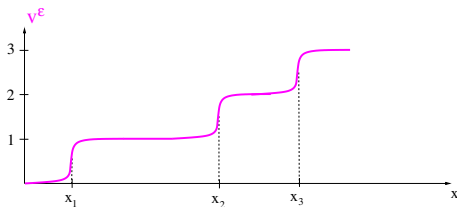
Thm 2 (Convergence PN \rightarrow DP) [Gonzalez, M. (2012)]

As $\varepsilon \rightarrow 0$, we have

$$v^\varepsilon \rightarrow v^0 \quad \text{in} \quad L^1_{loc}(\mathbb{R} \times [0, +\infty))$$

with

$$v^0(x, t) = \sum_{i=1}^N H(x - x_i(t)), \quad (H = \text{Heaviside function})$$



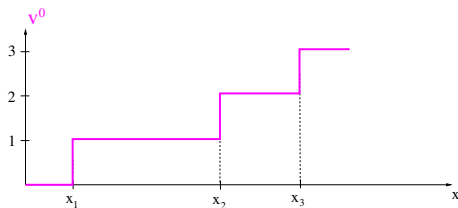
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Dislocation points dynamics

$$\left\{ \begin{array}{l} \frac{dx_i}{dt} = -\gamma \left(\sigma + \sum_{j \neq i} V'(x_i - x_j) \right) \\ x_i(0) = x_i^0 \end{array} \right. \quad \text{for } i = 1, \dots, N$$

with

$$\left\{ \begin{array}{l} \gamma = \left(\int_{\mathbb{R}} (\phi')^2 \right)^{-1} \\ V(x) = -\frac{1}{\pi} \ln |x| \end{array} \right.$$

Dislocation points dynamics

$$\left\{ \begin{array}{l} \frac{dx_i}{dt} = - \left(\sigma + \sum_{j \neq i} V'(x_i - x_j) \right) \\ x_i(0) = x_i^0 \end{array} \right. \quad \text{for } i = 1, \dots, N$$

with

$$\left\{ \begin{array}{l} \gamma = 1 \\ V(x) = -\frac{1}{\pi} \ln |x| \end{array} \right.$$

$$\left\{ \begin{array}{l} \frac{dx_i}{dt} = - \left(\sigma + \sum_{j \neq i} V'(x_i - x_j) \right) \\ x_i(0) = x_i^0 \end{array} \right. \quad \text{for } i = 1, \dots, N$$

with

$$\left\{ \begin{array}{l} \gamma = 1 \\ V(x) = -\frac{1}{\pi} \ln |x| \end{array} \right.$$

$$\phi(x) - H(x) \sim -\frac{1}{\pi x} \quad \text{as } |x| \rightarrow +\infty$$

- Micromagnetic thin films (gradient flow) : [Kurzke (2007)]
- Slow motion for non linear heat equation
 - Energy approach : [Bronsard, Kohn (1990)]
[Kalies, Van der Vorst, Wanner (2001)]
 - Invariant manifold : [Car, Pego (1989)]
[Chen (2004)]
[Ei (2002)]
[Fusco, Hale (1989)]

Ansatz

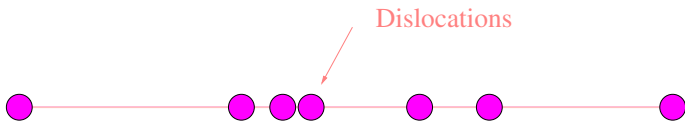
$$\tilde{v}^\varepsilon(x, t) = \varepsilon\sigma + \sum_{i=1}^N \left\{ \phi \left(\frac{x - x_i(t)}{\varepsilon} \right) \right\}$$

Ansatz

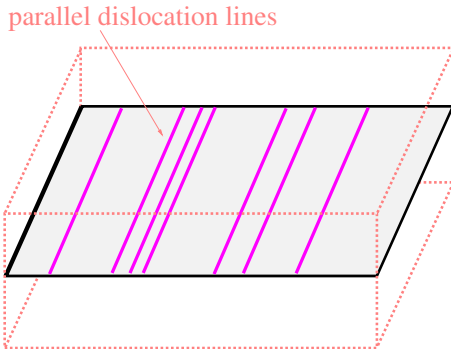
$$\tilde{v}^\varepsilon(x, t) = \varepsilon\sigma + \sum_{i=1}^N \left\{ \phi\left(\frac{x - x_i(t)}{\varepsilon}\right) - \varepsilon\dot{x}_i(t)\psi\left(\frac{x - x_i(t)}{\varepsilon}\right) \right\}$$

with the corrector ψ solving

$$\Delta^{\frac{1}{2}}\psi - W''(\phi)\psi = \phi' + W''(\phi) - W''(0)$$



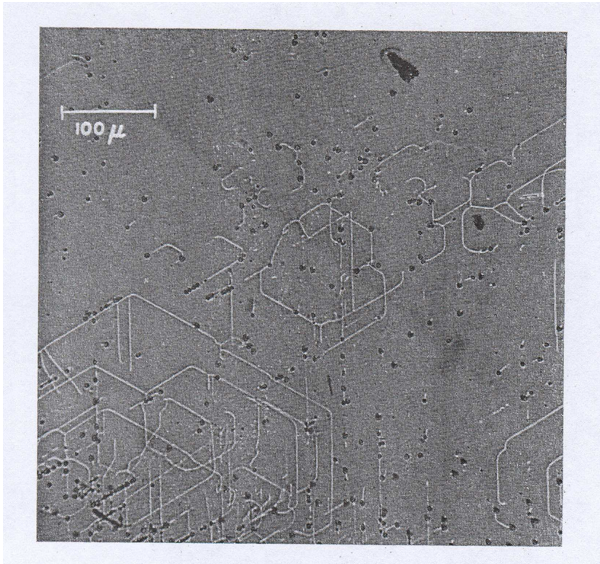
Straight dislocation lines



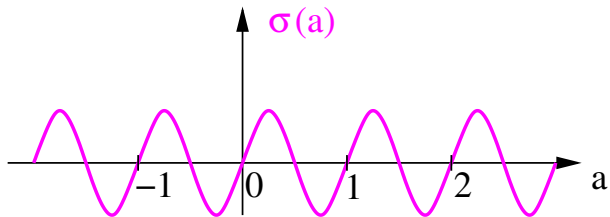
Dislocation dynamics with periodic obstacles

$$(\varepsilon = \varepsilon_3)$$

Precipitates = obstacles

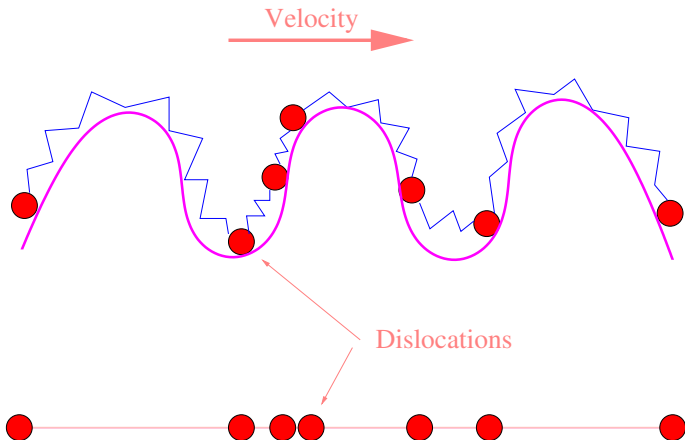


smooth periodic stress $\sigma(a + 1) = \sigma(a)$



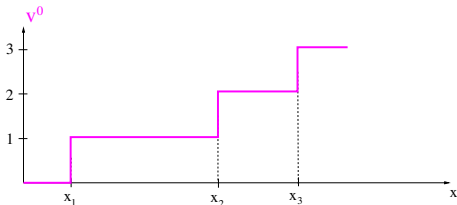
σ describes the **obstacles** to the motion of dislocations

Dynamics with two-body interactions



$$\left\{ \begin{array}{l} N_\varepsilon \text{ dislocations } x_1^0 < \dots < x_{N_\varepsilon}^0 \\ \frac{dx_i}{dt} = - \left(\sigma(x_i) + \sum_{j \neq i} V'(x_i - x_j) \right) \\ x_i(0) = x_i^0 \end{array} \right. \quad (3)$$

$$v^0(x, t) = \sum_{i=1}^{N_\varepsilon} H(x - x_i(t))$$



Convergence to crystal plasticity

$$(\varepsilon = \varepsilon_3 \rightarrow 0)$$

$$w^\varepsilon(x, t) = \varepsilon v^0\left(\frac{x}{\varepsilon}, \frac{t}{\varepsilon}\right)$$

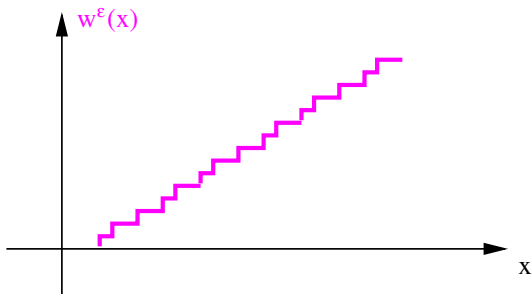
Convergence $\varepsilon \rightarrow 0$

Thm 3 (Convergence DD \rightarrow CP) [Forcadel, Imbert, M. (2009)]

As $\varepsilon \rightarrow 0$, we have

$$w^\varepsilon \rightarrow w^0 \quad \text{in} \quad L_{loc}^\infty(\mathbb{R} \times [0, +\infty))$$

where w^0 is a solution to the crystal plasticity model.



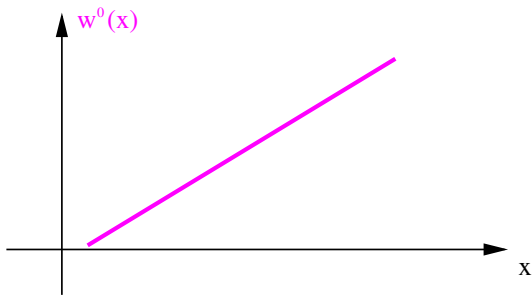
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Crystal (elasto-visco-) plasticity

$$w_t^0 = \bar{H}(w_x^0, \Delta^{\frac{1}{2}} w^0) \quad (4)$$

Crystal (elasto-visco-) plasticity

$$w_t^0 = \bar{H}(w_x^0, \Delta^{\frac{1}{2}} w^0) \quad (4)$$

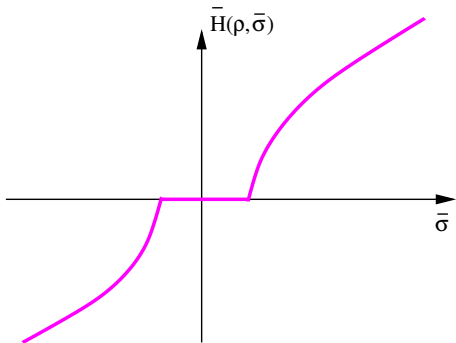
Mechanical interpretation

$$\left\{ \begin{array}{l} w^0 = \text{plastic strain} \\ w_t^0 = \text{plastic strain velocity} \\ w_x^0 = \text{density of dislocations} \\ \Delta^{\frac{1}{2}} w^0 = \text{self-stress created by the density of dislocations} \\ w_t^0 = \bar{H}(w_x^0, \Delta^{\frac{1}{2}} w^0) \text{ is the visco-plastic law} \end{array} \right.$$

Dynamics for densities of dislocations

Crystal (elasto-visco-) plasticity

$$w_t^0 = \bar{H}(w_x^0, \Delta^{\frac{1}{2}} w^0)$$



Orowan's law if no mesoscopic obstacles ($\sigma = 0$)

$$\bar{H}(\rho, \bar{\sigma}) = |\rho| \bar{\sigma}$$

\implies

$$w_t = (\Delta^{\frac{1}{2}} w) |w_x|$$

Study of self-similar solutions

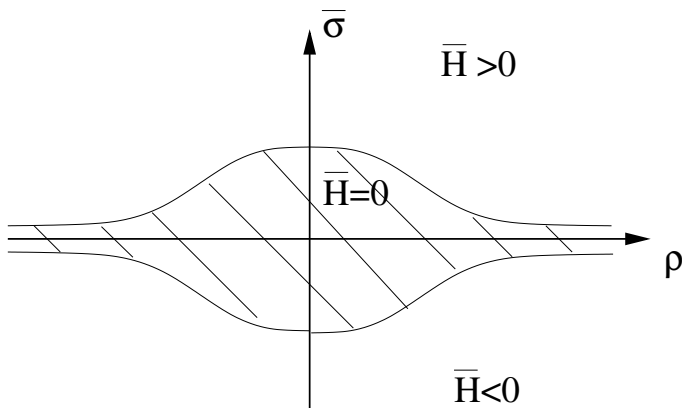
[Biler, Karch, M. (2010)]

Conservation law for $\rho = w_x^0$ and $\bar{\sigma} = \Delta^{\frac{1}{2}} w^0$, $\bar{H}(\rho, \bar{\sigma}) = |\rho| \bar{\sigma}$

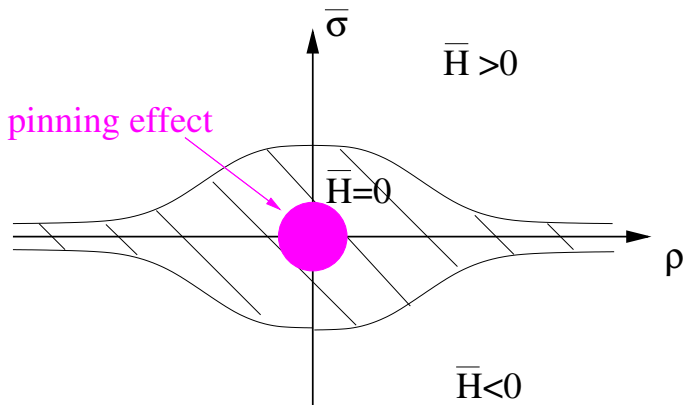
$$\rho_t = -(|\rho| \mathcal{H} \rho)_x \quad \text{with} \quad \mathcal{H} = \text{Hilbert transform}$$

- Quasi-Geostrophic type equation
[Córdoba, Córdoba, Fontelos (2005)]
- Gradient flow approach with Wasserstein metric
[Carrillo, Ferreira, Precioso (2011)]
- Fractional porous medium equation
[Biler, Karch, Imbert (2011)]
[Caffarelli, Vazquez (2011)]

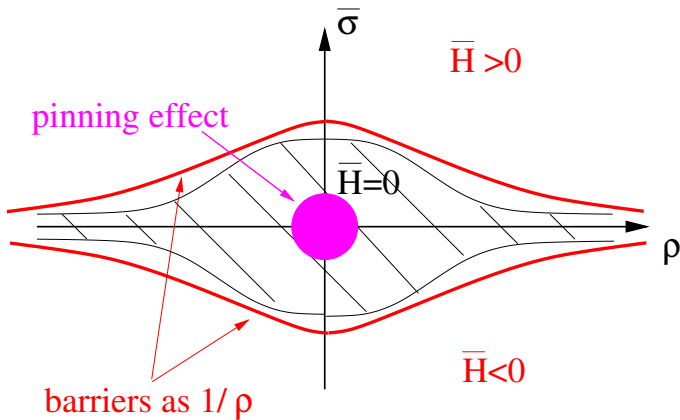
Effective Hamiltonian $\bar{H}(\rho, \bar{\sigma})$

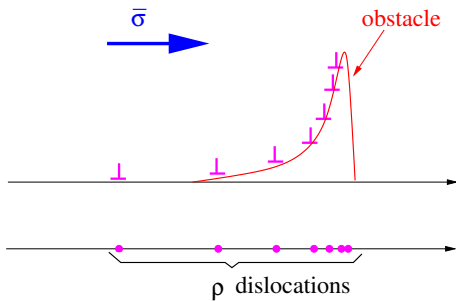


Pinning effect if $\int_{[0,1)} \sigma = 0$



Barriers for smooth enough interactions



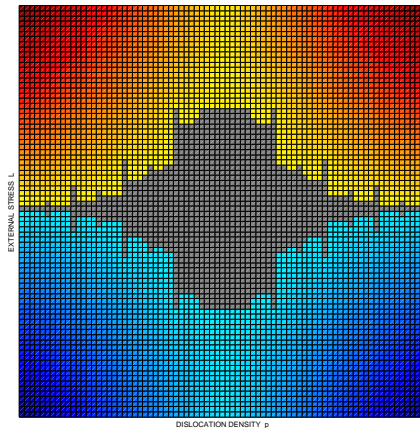


$$\bar{\sigma} = \frac{\sigma^{\text{obst}}}{\rho}$$

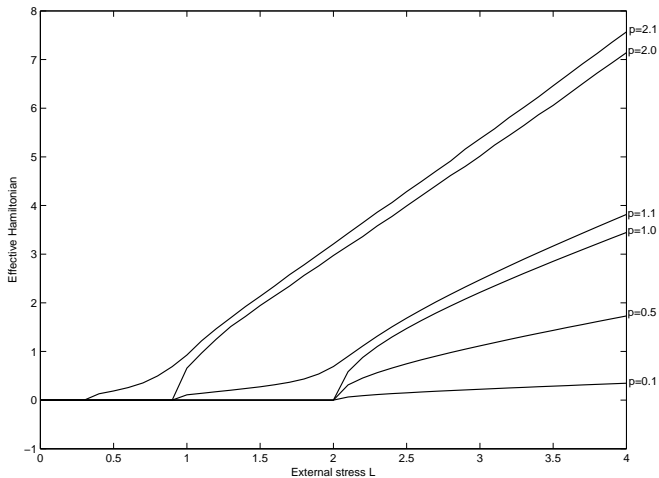
[Hirth, Lothe (1992), p. 766]

Effective Hamiltonian $\bar{H}(\rho, \bar{\sigma})$ (Numerics)

[Cacace, Chambolle, M. (2012)]

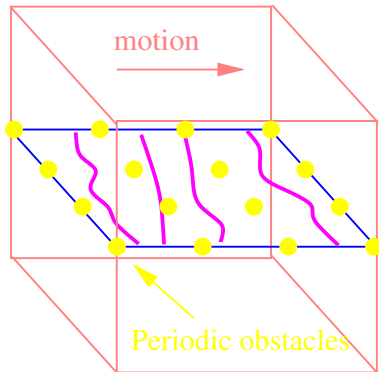


Effective Hamiltonian $\bar{\sigma} \mapsto \overline{H}(\rho, \bar{\sigma})$



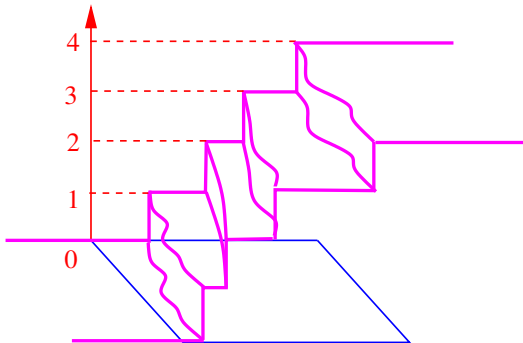
Homogenization of dislocation curves

Homogenization for curves



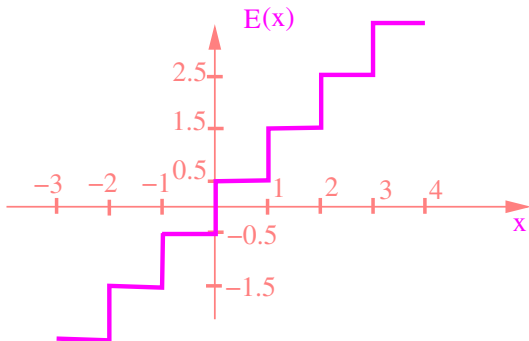
Limit for density of curves?

Plastic displacement



Odd integer part

$$E(w) = l + \frac{1}{2} \quad \text{for } l \leq w < l+1, \quad l \in \mathbb{Z}$$



$$w_t = |\nabla w| c[w] \quad \text{on} \quad \mathbb{R}^N \times (0, +\infty)$$

with

$$(c[w])(x) = c(x) + (J \star E \{w(\cdot, t) - w(x, t)\})(x)$$

$$w_t = |\nabla w| c[w] \quad \text{on} \quad \mathbb{R}^N \times (0, +\infty)$$

with

$$(c[w])(x) = c(x) + (J \star E \{w(\cdot, t) - w(x, t)\})(x)$$

where $c(x)$ represents the (periodic) **obstacles** :

$$c(x + k) = c(x) \quad \text{for all} \quad k \in \mathbb{Z}^N$$

and

$$J(z) = \frac{1}{|z|^{N+1}} \cdot 1_{\{|z| \geq \delta\}} \quad \text{for some fixed} \quad \delta > 0$$

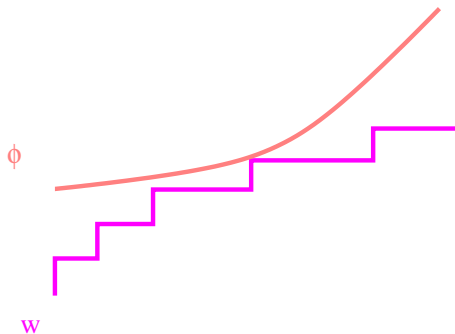
"Slepčev viscosity solution"

$$c[w] = c + J \star E \{w(\cdot, t) - w(x, t)\}$$

We set

$$\begin{cases} c^*[w] := c + J \star E^* \{...\} \\ c_*[w] := c + J \star E_* \{...\} \end{cases}$$

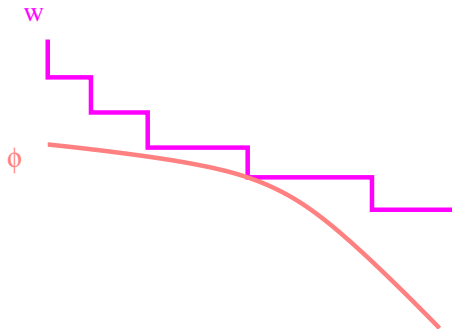
"Slepčev viscosity solution"



subsolution :

$$\phi_t \leq |\nabla\phi| \cdot c^*[w] \quad \text{at the contact point}$$

"Slepčev viscosity solution"



supersolution :

$$\phi_t \geq |\nabla\phi| \cdot c_*[w] \quad \text{at the contact point}$$

Let

$$w^\varepsilon(x, t) = \varepsilon w\left(\frac{x}{\varepsilon}, \frac{t}{\varepsilon}\right)$$

Thm 3' (Convergence DD \rightarrow CP) [Forcadel, Imbert, M. (2009)]

As $\varepsilon \rightarrow 0$, we have

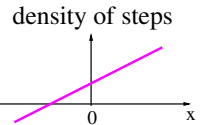
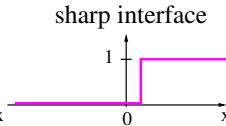
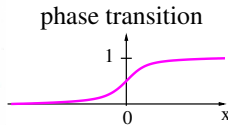
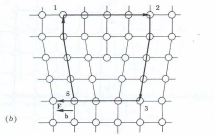
$$w^\varepsilon \rightarrow w^0 \quad \text{in} \quad L_{loc}^\infty(\mathbb{R}^N \times [0, +\infty))$$

where w^0 is the solution of the limit equation for some suitable function \bar{H} :

$$w_t^0 = \bar{H}(\nabla w^0, \Delta^{\frac{1}{2}} w^0) \quad \text{on} \quad \mathbb{R}^N \times (0, +\infty)$$

Conclusion

Hierarchy of scales and models



“FK”



PN

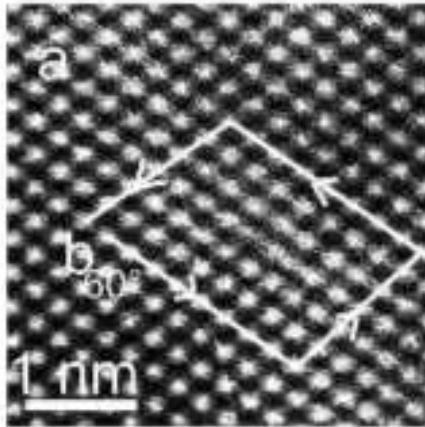


DD



Crystal
plasticity

A dislocation in cubic Boron Nitride



High Resolution Transmission Electronic Microscopy