Mixed Finite Element Methods for Non-Linear Fokker-Planck Equations

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IPAM, April 2008





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1 Non-Linear Fokker-Planck Equations

2 Mixed finite element method

3 Patlak-Keller-Segel Model

4 Porous Medium Equation

5 There's always a point you get in trouble - the Relativistic Heat Equation

Non-Linear Fokker-Planck Equations I

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Consider the following minimization problem:

Given a density
$$\rho_{n-1}$$
, find ρ_n such that

$$\inf_{\rho,\rho_n,u} \left(E(\rho_n) + \int_{t_{n-1}}^{t_n} \int_{\mathbb{R}^d} c(u(x,t)) \rho(x,t) \, dx dt \right)$$
under the constraint that

$$\frac{\partial \rho}{\partial t} + \nabla \cdot (\rho u) = 0$$

$$\rho(\cdot, t_{n-1}) = \rho_{n-1}, \quad \rho(\cdot, t_n) = \rho_n.$$

Non-Linear Fokker-Planck Equations II

The optimality condition for the minimization problem is given by

$$\frac{\partial \rho}{\partial t} = \nabla \cdot \left[\rho \left(\nabla c^* \right) \left(\nabla \frac{\delta E}{\delta \rho} \right) \right]$$
$$\rho(x, 0) = \rho_0(x).$$

with no-flux boundary conditions. The energy E is given by

$$E = \underbrace{\mathcal{U}}_{\text{internal energy}} + \underbrace{\mathcal{V}}_{\text{potential energy}} + \underbrace{\mathcal{W}}_{\text{interaction energy}}$$
$$\mathcal{U}(\rho) = \int_{\mathbb{R}^n} U(\rho(x)) \, dx$$
$$\mathcal{V}(\rho) = \int_{\mathbb{R}^n} \rho(x) V(x) \, dx$$

$$\mathcal{W}(\rho) = \frac{1}{2} \int_{\mathbb{R}^n \times \mathbb{R}^n} W(x - y) \rho(x) \rho(y) dx dy$$

Quadratic Cost

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Classical examples with cost functional $c(x) = \frac{|x|^2}{2}$

$$U(s) = s \log s, V = 0, W = 0$$
heat equation $U(s) = \frac{s^m}{m-1}, V = 0, W = 0$ porous-medium type equation $U(s) = s \log s, V$ given potentiallinear Fokker-Planck equation $U = 0, V = 0, W(z) = \frac{|z|}{3}$ model for granular flow $W(z)$ non-local kernelcontinuous swarming models

Non-Quadratic Costs

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The relativistic cost is given by

$$egin{aligned} \mathsf{c}(x) = egin{cases} 1 - \sqrt{1 - rac{1}{c^2} |x|^2} & |x| < c \ \infty & |x| \geq c \end{aligned}$$

where c > 0 can be interpreted as a maximal speed. The corresponding optimality condition with $U(s) = s \log(s) - s$ is the so-called relativistic heat equation

$$\frac{\partial \rho}{\partial t} = \nabla \cdot \left(\frac{\rho \nabla \rho}{\sqrt{\rho^2 + \frac{1}{c^2} |\nabla \rho|}} \right)$$

The cost functional $c(x) = \frac{|x|^p}{p}$ gives the well-known *p*-Laplace equation

$$\frac{\partial \rho}{\partial t} = \nabla \cdot \left(|\nabla \rho|^{\rho-2} \nabla \rho \right).$$

Linearization I

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Consider the linearized minimization problem

Given a density
$$\rho_{n-1}$$
, find ρ_n such that

$$\inf_{\rho,\rho_n,u} \left(E(\rho_n) + \int_{t_{n-1}}^{t_n} \int_{\mathbb{R}^d} c(u(x,t)) \rho_{n-1}(x,t) \, dx dt \right)$$
under the constraint that

$$\frac{\partial \rho}{\partial t} + \nabla \cdot (\rho_{n-1}u) = 0$$

$$\rho(\cdot, t_{n-1}) = \rho_{n-1}, \quad \rho(\cdot, t_n) = \rho_n.$$

The optimality condition is given by

$$\frac{\partial \rho}{\partial t} = \operatorname{div}\left(\rho_{n-1}\nabla\left(\frac{\partial E}{\partial \rho}\right)\right)$$
$$\rho(x,0) = \rho_0(x)$$

and no flux boundary conditions.

Linearization II

We introduce the new variables

$$\mu = \frac{\delta E}{\delta \rho}$$
 and $\mathbf{j} = \rho_{n-1} \nabla \mu$

We replace the time derivative by a finite difference quotient and obtain:

$$\mu_n = \frac{\delta E}{\delta \rho_n}(\rho_n)$$
$$\rho_n - \sqrt{\tau} \operatorname{div} \mathbf{j}_n = \rho_{n-1}$$
$$\sqrt{\tau} \nabla \mu_n - \frac{1}{\rho_{n-1}} \mathbf{j}_n = \mathbf{0}$$

Problem is still non-linear, therefore we linearize E, for example

$$E(\rho_n) = \rho_n \log \rho_n \qquad \qquad \tilde{E}(\rho_n) = \rho_n \left(\log \rho_{n-1} + \frac{\rho_n - \rho_{n-1}}{\rho_{n-1}} \right)$$

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Maximum Principle

Proposition

Let $0 < c_1 \le \rho_{n-1}(x) \le c_2$ for all $x \in \Omega$. Then the solution ρ_n of

$$ho_n - \sqrt{ au} \operatorname{div} \mathbf{j}_n =
ho_{n-1}$$
 $\sqrt{ au}
abla \mu_n - \frac{1}{
ho_{n-1}} \mathbf{j}_n = \mathbf{0}.$

with $\mu_n = \frac{\delta E}{\delta \rho_n}(\rho_n)$ satisfies

$$c_1 \leq \rho_n(x) \leq c_2 \quad \forall x \in \Omega.$$

Long time behavior of the Fokker-Planck Equation: Linearization with $\mu = \frac{\delta E}{\delta \rho_n}$ guarantees decay of the numerical entropy, using a similar argument as in

 A. Arnold, A. Unterreiter, Entropy Decay of Discretized Fokker-Planck Equations I - Temporal Semi-Discretization, Comp. Math. Appl. 46, No. 10-11, 2003

Variational formulation

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Then the weak formulation is given by

Find
$$\rho_n, \mu_n \in L^2(\Omega)$$
 and $\mathbf{j}_n \in H(\operatorname{div}, \Omega)$ such that:

$$\int_{\Omega} a(\rho_{n-1})\rho v dx + \int_{\Omega} \mu_n v dx = \int_{\Omega} f(\rho_{n-1}) v dx \qquad \forall v \in L^2(\Omega)$$

$$\int_{\Omega} \rho_n w dx - \int_{\Omega} \sqrt{\tau} \operatorname{div} \mathbf{j}_n w \ dx = \int_{\Omega} \rho_{n-1} w dx \qquad \forall w \in L^2(\Omega)$$

$$- \int_{\Omega} \sqrt{\tau} \mu_n \operatorname{div} \mathbf{q} dx - \int_{\Omega} \frac{1}{\rho_{n-1}} \mathbf{j}_n \mathbf{q} dx = 0 \qquad \forall \mathbf{q} \in H(\operatorname{div}, \Omega)$$

Abstract formulation: Find $u \in V$ and $p \in Q$ solutions of

$$egin{aligned} \mathsf{a}(u,v) + \mathsf{b}(v,p) &= \langle f,v
angle & orall v \in V \ \mathsf{b}(u,q) - \mathsf{c}(p,q) &= \langle g,q
angle & orall q \in Q. \end{aligned}$$

where a, b, c are continuous bilinear forms.

Existence and Uniqueness

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If the following conditions hold:

• a is a bounded and coercive, i.e.

$$\begin{aligned} |a(u,v)| &\leq \|a\| \|u\|_V \|v\|_V \qquad \forall \ u,v \in V \\ \exists \ \alpha > 0 \qquad a(v,v) \geq \alpha \|v\|_V^2 \qquad \forall \ v \in V_0 \end{aligned}$$

with $V_0 = \{v \in V | b(v, p) = 0 \forall p \in Q\}$,

• *b* is bounded and satisfies the inf-sup-condition, i.e.

$$\begin{split} |b(v,q)| &\leq \|b\| \|v\|_V \|q\|_Q \qquad \forall v \in V, \ q \in Q \\ \exists \ \beta > 0 \quad \sup_{v \in V} \frac{b(v,q)}{\|v\|_V} &\geq \beta \|q\|_Q \qquad \forall p \in Q \end{split}$$

• c is bounded and coercive, i.e.

$$egin{aligned} |c(p,q)| &\leq \|c\|\|\|_Q \|q\|_Q & orall p, q \in Q \ \exists \ \gamma > 0 \quad c(q,q) &\geq \gamma \|q\|_Q^2 & orall q \in Q \end{aligned}$$

Then the system has a unique solution.

Conforming Finite Elements

Properties of $H(\operatorname{div}, \Omega)$ and $L^2(\Omega)$:

- $\sigma \in H(\operatorname{div}, \Omega) \Rightarrow \sigma \cdot n$ has to be continuous
- $v \in L^2(\Omega) \Rightarrow$ no continuity requirements

The cheapest $H(\operatorname{div}, \Omega)$ conforming finite element is the Raviart Thomas element defined by

$$V_h = \left\{ \begin{pmatrix} a \\ b \end{pmatrix} + c \begin{pmatrix} x \\ y \end{pmatrix} : a, b, c \in \mathbb{R} \right\}$$

Degrees of freedom are associated to the edges e_i of the triangle:

$$\int_{e_i} \phi_j \cdot \mathbf{n}_{e_i} ds = \delta_{i,j} \quad i = 1, 2, 3$$

The lowest order $L^2(\Omega)$ conforming finite element space Q_h contains the element-wise constant functions.

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Low Order Raviart-Thomas Elements

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Degrees of freedom:



The De-Rham sequence:



Patlak-Keller-Segel Model I

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PKS Model is used for describing the motion of cells attracted by a self-emitted chemical substrate.

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abla \left(\log
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ight)
ight) \ &
ho(x,0) &=
ho_0(x) \geq 0 \end{aligned}$$

with no-flux boundary conditions. Here

- c denotes the concentration of the chemo-attractant
- ρ represents the cell density and
- χ is the sensitivity of the bacteria to the chemo-attractant.

Patlak-Keller-Segel Model II

Total mass of system:

$$M:=\int_{\mathbb{R}^2}\rho_0dx=\int_{\mathbb{R}^2}\rho(x,t)dx.$$

Blow up behavior for $\chi M > M_C$,

$$M_{c} = \begin{cases} 8\pi & \text{for unbounded domains } \Omega \subset \mathbb{R}^{2} \\ 4\pi & \text{for bounded, connected domains } \Omega \subset \mathbb{R}^{2} \end{cases}$$

- A. Blanchet, J. A. Carrillo and N. Masmoudi, Infinite Time Aggregation For The Critical Patlak-Keller-Segel Model in ℝ², Preprint UAB
- V. Calvez and J. A. Carrillo, Volume effects in the Keller-Segel model: energy estimates preventing blow up, Journal Mathématiques Pures et Appliquées 86, 155-175, 2006

Mixed Finite Element Method I

We introduce new variables

- Concentration gradient: $\mathbf{e} = \nabla c$
- Flux: $\mathbf{j} = \rho \nabla \mu$ with $\mu = \frac{\delta E}{\delta \rho} = \log \rho \chi c$

and the following linearization $\mu \approx \log \rho_{n-1} + \frac{\rho_n - \rho_{n-1}}{\rho_{n-1}} - \chi c$.

Find
$$c, \rho_n, \mu_n \in L^2(\Omega)$$
 and $\mathbf{e}, \mathbf{j}_n \in H(\operatorname{div}, \Omega)$ such that

$$\begin{aligned} &-\int_{\Omega} \mathbf{e} \cdot \mathbf{p} dx + \int_{\Omega} c \operatorname{div} \mathbf{p} dx = 0 & \forall \mathbf{e} \in H(\operatorname{div}, \Omega) \\ &\int_{\Omega} \operatorname{div} \mathbf{e} r dx - \int_{\Omega} \rho_n r dx = -\int_{\Omega} \langle \rho_0 \rangle r dx & \forall r \in L^2(\Omega) \\ &-\int_{\Omega} \chi c u dx + \int_{\Omega} \frac{\rho_n}{\rho_{n-1}} u dx - \int_{\Omega} \mu_n u dx = -\int_{\Omega} (\log \rho_{n-1} + 1) u dx & \forall u \in L^2(\Omega) \\ &-\int_{\Omega} \rho_n v dx + \int_{\Omega} \sqrt{\tau} \operatorname{div} \mathbf{j}_n v dx = -\int_{\Omega} \rho_{n-1} v dx & \forall v \in L^2(\Omega) \\ &\int_{\Omega} \sqrt{\tau} \mu_n \operatorname{div} \mathbf{q} dx + \int_{\Omega} \frac{1}{\rho_{n-1}} \mathbf{j}_n \cdot \mathbf{q} dx = 0 & \forall \mathbf{q} \in H(\operatorname{div}, \Omega). \end{aligned}$$

Problem Setup

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• Initial density:

$$\rho_0(x,y) = \frac{c}{2\pi} e^{-\frac{(x-x_0)^2 + (y-y_0)^2}{2}}$$

- Domain: Square of size $[-5,5]\times[-5,5]$ with discretization of 10348 triangles
- · Hp-mesh refinement in corner of expected blow up
- replace

$$rac{1}{
ho_{n-1}}pproxrac{1}{\max(
ho_{n-1},h)}$$

where h is the mesh size

Evolution of ρ with mass $M = 10\pi$



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Evolution of ρ with mass $M = 10\pi$



Evolution of ρ with mass $M = 6\pi$



Evolution of 4 densities ρ_i with masses $m_i = 0.9\pi$



Figure: Evolution of four densities ρ with four masses $m_i = 0.9\pi$

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Porous Medium Equations

We consider the porous medium type equations

$$\rho_t = \operatorname{div} (\nabla \rho^m) = \operatorname{div} \left(\frac{m}{m-1} \rho \nabla \rho^{m-1} \right)$$
$$\rho(x, 0) = \rho_0(x)$$

for $m \ge 2$ with homogenous Neumann boundary conditions. For m < 1 this equation is known as the Fast Diffusion Equation (FDE).

Applications:

- Flow of a gas through a porous medium for m > 2,
- thin films with no surface tension for m = 4,
- and many other applications in physics ...
- J. L. Vazquez, The Porous Medium Equation, Oxford University Press

Barenblatt-Pattle Solutions

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Solution of the porous medium equation is given by the Barenblatt-Pattle profile

$$V(|x|,t) = t^{-kN} \left(C_1 - \frac{k(m-1)}{2m} |x|^2 t^{-2k} \right)_+^{\frac{1}{m-1}}$$

where $k = (N(m-1)+2)^{-1}$.



Linearization of Porous Medium Equations

Introduce a new variable

$$\mu = \frac{m}{m-1}\rho^{m-1}$$
$$\approx \frac{m}{m-1} \left(\rho_{n-1}^{m-1} + (m-1)\tilde{\rho}^{m-2}(\rho - \rho_{n-1})\right)$$

The flux is given by

$$\mathbf{j} = \rho \nabla \mu \approx \rho_{n-1} \nabla \mu.$$

The linearized system then reads as

$$m\rho_{n-1}^{m-2}\rho_n - \mu_n = -\frac{m(m-2)}{m-1}\rho_{n-1}^{m-1}$$
$$-\rho_n + \sqrt{\tau}\operatorname{div}\mathbf{j}_n = -\rho_{n-1}$$
$$-\sqrt{\tau}\nabla\mu_n + \frac{1}{\rho_{n-1}}\mathbf{j}_n = 0.$$

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Porous Medium Equations

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The variational formulation is given by:

Find
$$\rho_n, \mu_n \in L^2(\Omega)$$
 and $\mathbf{j}_n \in H(\operatorname{div}, \Omega)$ such that

$$\int_{\Omega} m\rho_{n-1}^{m-2}\rho_n \omega dx - \int \mu_n \omega dx = -\int \frac{m(m-2)}{m-1}\rho_{n-1}^{m-1} \omega dx \quad \text{for all } \omega \in L^2(\Omega)$$

$$-\int_{\Omega} \rho_n \xi dx + \int \sqrt{\tau} \operatorname{div} \mathbf{j}_n \xi dx = -\int \rho_{n-1} \xi dx \quad \text{for all } \xi \in L^2(\Omega)$$

$$\int_{\Omega} \sqrt{\tau} \mu_n \operatorname{div} \theta + \int \frac{1}{\tilde{\rho}} \mathbf{j} \theta dx = 0 \quad \text{for all } \theta \in H(\operatorname{div}, \Omega)$$

Numerical Discretization

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For the numerical computations we

replace

$$rac{1}{
ho_{n-1}^{2-m}}pproxrac{1}{\max(
ho_{n-1},h)^{2-m}}$$

where h is the mesh size

• and do a back-projection after each time step

$$\rho = max(\rho, 0).$$

Problem Setup:

- Circle of radius r = 2
- Time steps: $au = 10^{-1}$ for PME, $au = 10^{-3}$ for FDE
- Initial Guess: Barenblatt Profile at t = 0.1

Numerical Simulation for m = 3



Numerical Simulation for m = 5



Numerical Simulation for m = 3





Numerical Simulation for m = 0.8



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Relativistic Heat Equation I

Relativistic heat equation (RHE) is given by

$$\frac{\partial \rho}{\partial t} = \nu \operatorname{div} \left(\frac{\rho \nabla \rho}{\sqrt{\rho^2 + \frac{\nu^2}{c^2} |\nabla \rho|^2}} \right)$$
$$\rho(x, 0) = \rho_0(x)$$

where $\nu > 0$ is a constant representing a kinematic viscosity and c is the speed of light.

Asymptotic behavior :

- For $c \to \infty$ the solutions of the RHE converge to the solution of the heat equation $\rho_t = \nu \Delta \rho$.
- For $\nu \to \infty$ the solutions of the RHE converge to the solution of

$$\frac{\partial \rho}{\partial t} = c \operatorname{div} \left(\rho \frac{\nabla \rho}{|\nabla \rho|} \right).$$

Relativistic Heat Equation II

The solution of the limiting equation with initial data $\rho_0(x) = \alpha \chi_C(x), \ \alpha > 0$ is given by

$$\rho(x,t) = \alpha \frac{|C|}{|C(t)|} \chi_{C(t)}(x)$$

where

$$C(t):=\{x\in\mathbb{R}^N:d(x,C)\leq t\}.$$

For further information

- F. Andreu, V. Caselles, J.M. Manzon and S. Moll, On The Relativistic Heat Equations And An Asymptotic Regime Of It, Preprint
- V. Caselles, Convergence Of The Relativistic Heat Equations To The Heat Equations As $c \rightarrow \infty$, Publ. Mat. 51 (2007), 121-142
- R. J. McCann, M. Puel, *Constructing A Relativistic Heat Flow By Transport Time Steps*

Relativistic Heat Equation III

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Consider

$$\frac{\partial \rho}{\partial t} = \nu \operatorname{div} \left(\frac{\nabla \rho}{\sqrt{1 + \frac{\nu^2}{c^2} \frac{|\nabla \rho|^2}{\rho^2}}} \right)$$

and introduce new variables $\mu = \log \rho$ and the flux $\mathbf{j} = \rho \nabla \mu$. Using the same linearization as for the Keller-Segel model we obtain

$$\begin{aligned} \frac{1}{\rho_{n-1}}\rho_n - \mu_n &= 1 - \log \rho_{n-1} \\ -\rho_n + \sqrt{\tau} \operatorname{div} \mathbf{j}_n &= -\rho_{n-1} \\ \frac{\sqrt{\tau}}{\sqrt{1 + |\nabla \mu_{n-1}|^2}} \nabla \mu_n + \frac{\mathbf{j}_n}{\rho_{n-1}} &= 0 \end{aligned}$$

Problem: Higher order basis functions for μ

1D Discretization

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Introduce a new variable $\sigma=\rho_{\rm x}$ - then the linearized system is given by

$$\sigma -
ho_x = 0$$

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ho}{\partial t} + \partial_x \left(rac{\sigma}{\sqrt{1 + rac{
u^2}{c^2} rac{| ilde{\sigma}|^2}{ ilde{
ho}^2}}}
ight) = 0.$

Find
$$\sigma \in L^{2}(\Omega)$$
 and $\rho \in H^{1}(\Omega)$ such that

$$\int \sigma \omega dx - \int \rho_{x} \omega dx = 0 \qquad \text{for all } \omega \in L^{2}(\Omega)$$

$$-\int \frac{1}{\sqrt{1 + \frac{\nu^{2}}{c^{2}} \frac{|\tilde{\sigma}|^{2}}{\tilde{\rho}^{2}}}} \sigma \xi_{x} dx - \int \frac{1}{\tau} \rho \xi dx = -\int \frac{1}{\tau} \tilde{\rho} \xi dx \qquad \text{for all } \xi \in H^{1}(\Omega).$$

Relativistic Heat Equation c = 1.0 and $\nu = 1.0$

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Time evolution of rho according to the relativistic heat equation



Relativistic Heat Equation c = 1e10 and $\nu = 1.0$

Time evolution of rho according to the relativistic heat equation







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Relativistic Heat Equation c = 1.0 and $\nu = 1e20$

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Time evolution of rho with v=1e20

Exact Solution: $\rho(x, 0.5) = \frac{1}{2}\chi_{[-1,1]}$

What's still left to do

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- Extension of the numerical scheme to use higher order basis functions
- Long-time behavior of numerical scheme
- Newton method after linearization of Wasserstein distance

Software: NETGEN/NGSolve developed by Joachim Schöberl, RWTH Aachen

Thank you very much for your attention !

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