Utilizing full waveform inversion from shallow to deep.

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FWI in the forefront of Production

A more detailed look at what's down there



Original rendering drawn by hand guesstimating data on salt dome.

Source: BP



Salt dome more Ocean Sea accurately rendered bed

Houston Chronicle

In 2004, scientists had to guess at the size and shape of the salt dome beneath Atlantis, and knew little about the earth under the dome. Then, last year, BP scientists developed a new algorithm and used the company's supercomputer to produce a more accurate image of the salt dome and minerals under it.

British oil major BP has discovered 200 million barrels of oil in a hidden cache in the Gulf of Mexico, thanks to a technological breakthrough allowing the company to see beneath geological formations that had befuddled oil exploration for decades.



3-Dimensional Problem of Subsalt Imaging



- Full Azimuth Acquisition
- Accurate Structural Picture
- Best imaging of Salt-Sediment Interface





Prospecting Without Seismic and Depth Imaging

What will you find?





Prospecting Without Seismic and Depth Imaging

What will you find?





This

Prospecting Without Seismic and Depth Imaging

What will you find?



or This



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This

Full Waveform Inversion (FWI)

FWI: data fitting based model building process

- > applicable to data with rich transmission (long-offset)
 - ✓ plenty successful FWI applications in field
 - × limited penetration depth
- > more challenging with reflection, mainly because:
 - reflection-driven gradient not amenable for kinematic update
 - strong nonlinearity & many false local minima



Two Modes of FWI Gradient

FWI gradient has both **low- & high-wavenumber** components



Key Challenges to Successful Inversion

 \succ Key to inversion with transmission:

How to mitigate local-minima issue? (objective selection)

Keys to inversion with reflection:

(1) How to promote low-wavenumber updates?

(2) How to mitigate local-minima issue?



Method: Reflection based FWI (RFWI)

Two essential components:

Born modeling based gradient kernel

✓ to explicitly compute low-wavenumber components from reflection

Kinematics oriented objective functions

 \checkmark to achieve correct updating direction



Low-wavenumber Gradient from Reflection



$$\left(rac{\partial \delta p}{\partial v}
ight)^T d_r = \texttt{src_bg} \star \texttt{rcv_scat} \ + \ \texttt{rcv_bg} \star \texttt{src_scat}$$



Difference between FWI approaches





Initial Velocity Provided



Adjustive FWI Inverted Vp (up to 5 Hz)



Adjustive RFWI Inverted Vp (5 and 7 Hz)



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LS-FWI Inverted Vp (7 and 10 Hz)



Velocity Model Building Approach





Regional Lines with 1D initial model for FWI



Regional Lines with Adjustive FWI update from 1D initial velocity model



Velocity Model Building Approach





Input velocity to RFWI





RFWI Update with Velocity Overlay





Summary & Conclusion

> Two essential components of RFWI:

- 1. model decomposition & Born modeling based optimization
- 2. objective function: emphasize on measuring kinematic difference between observed and predicted reflections
- Reflections can be used to build macro model
- Robust inversion workflow (Cycle skip mitigation {FWI + RFWI} + LS FWI)

for velocity model determination.

