Parallel Replica algorithm for Langevin dynamics and Adaptative Metadynamics

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Introduction

- Metastability in molecular dynamics and the Parallel Replica algorithm
- Quasi-stationary distribution and Parallel Replica justification

2 Langevin process and kinetic Fokker-Planck equation

- Transition density of the absorbed semigroup
- Compactness of the absorbed semigroup

Quasi-stationary distributions and overdamped limit of the Langevin process

- Existence and long-time convergence
- Overdamped limit of the QSD

Metadynamics

- Description of the algorithm
- Adaptative Metadynamics

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- Molecular Dynamics methods are used in Biology, Material Science, Nuclear Physics (protein folding, nuclear fuels propagation inside the nuclear reactor).
- The Underdamped Langevin dynamics model the evolution of thermostated molecular systems.

Let N particles described by **position** $q_t^i \in \mathbb{R}^3$, and **momentum** $p_t^i \in \mathbb{R}^3$. The process $(X_t = (q_t, p_t))_{t \geq 0} := (q_t^1, \dots, q_t^N, p_t^1, \dots, p_t^N)_{t \geq 0}$ is solution of

$$\begin{cases} \mathrm{d}\boldsymbol{q}_t = \boldsymbol{M}^{-1}\boldsymbol{p}_t \mathrm{d}t, \\ \mathrm{d}\boldsymbol{p}_t = -\nabla \boldsymbol{V}(\boldsymbol{q}_t) \mathrm{d}t - \gamma \boldsymbol{M}^{-1}\boldsymbol{p}_t \mathrm{d}t + \sqrt{2\gamma\beta^{-1}} \mathrm{d}\boldsymbol{B}_t, \end{cases}$$

with $V : \mathbb{R}^{3N} \mapsto \mathbb{R}$ the interaction potential, $\gamma > 0$ the friction parameter, M the mass matrix and $\beta^{-1} = k_B T$.

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with $V : \mathbb{R}^{3N} \mapsto \mathbb{R}$ the interaction potential, $\gamma > 0$ the friction parameter, M the mass matrix and $\beta^{-1} = k_B T$.

Numerical discretization: $(q_{n\Delta t}, p_{n\Delta t}) \sim (\hat{q}_n, \hat{p}_n)$ such that (Velocity-Verlet integrator)

$$(\widehat{q}_{n+1},\widehat{p}_{n+1})=\Phi_{\Delta_t}(\widehat{q}_n,\widehat{p}_n).$$

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$$(\widehat{q}_{n+1},\widehat{p}_{n+1})=\Phi_{\Delta_t}(\widehat{q}_n,\widehat{p}_n).$$

Problem: The sampling of some physical events takes too many iterations! (Typically 10^{-6} s with $\Delta t = 10^{-15}$ s).

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An example in dimension 2



Figure: Sampling in a double well potential. 100 000 iterations

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An example in dimension 2



Figure: Sampling in a double well potential. 100 000 iterations

- Oscillation inside basins of attraction of the potential.
- Transition events take a very long time: metastability because the system needs to overcome an energetic gap.
- Problem in large dimension where metastability correspond to entropic effects (narrow escapes).

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Figure: Sampling in a double well potential. 100 000 iterations

- Oscillation inside basins of attraction of the potential.
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- Problem in large dimension where metastability correspond to entropic effects (narrow escapes).

How to sample precisely these transition events?

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Image: A matched a matc

Parallel Replica algorithm

Conceived by Arthur Voter (Los Alamos National Laboratory) in 1998.

Objective: Parallelize the sampling of the first exit event (first exit time, exit point) from a domain D for the process $(X_t)_{t\geq 0}$.

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Parallel Replica: Assume that $(X_t)_{t\geq 0}$ stayed in D during τ_c "long enough". Let $\tau_{\partial} := \inf\{t > \tau_c : X_t \notin D\}.$

- Initialize N independent replicas $(X_t^1)_{t \ge 0}, \ldots, (X_t^N)_{t \ge 0}$ starting from X_{τ_c} and following the same dynamics as $(X_t)_{t \ge 0}$.
- **2** Make the N replicas evolve in D during τ_c (rejection sampling).

$$\textbf{O} \text{ Let } \tau^i_\partial = \inf\{t > 0 : X^i_{t+\tau_c} \notin D\} \text{ and } i^* = \arg\min_{1 \le i \le N} \tau^i_\partial. \text{ Define}$$

$$\left(au_{\partial}, X_{ au_{\partial}}\right) := \left(N au_{\partial}^{i^{*}}, X_{ au_{\partial}^{i^{*}}}^{i^{*}}\right).$$

If justified, the last step would ensure a speed-up of N in wall-clock time.

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Quasi-stationary distribution

If $(X_t)_{t\geq 0}$ stays long enough in a state D it reaches a "local equilibrium", called **quasi-stationary** distribution (QSD).

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Definition: Let $\tau_{\partial} := \inf\{t > 0 : X_t \notin D\}$. A probability measure ν on D is said to be a **QSD** on D of the process $(X_t)_{t>0}$, if for all $A \subset D$,

$$rac{\mathbb{P}_
u(X_t\in A, au_\partial>t)}{\mathbb{P}_
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u(A).$$

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First exit event starting from the QSD and justification of ParRep

Assume that $X_0 \stackrel{\mathcal{L}}{=} QSD$, then, see Collet, Martinez, San Martin (2013),

- au_{∂} follows the exponential law,
- τ_{∂} is independent of $X_{\tau_{\partial}}$.

Let (X_0^N, \ldots, X_0^N) be i.i.d. according to the QSD and $i^* := \arg \min_{1 \le i \le N} \tau_{\partial}^i$, then

$$(N\tau_{\partial}^{i^*}, X_{\tau_{\partial}^{i^*}}^{i^*}) \stackrel{\mathcal{L}}{=} (\tau_{\partial}, X_{\tau_{\partial}}).$$

Parallel Replica: Existence of a QSD and long time convergence to the QSD ?

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Overdamped case

QSDs have been investigated for the overdamped Langevin dynamics $(\overline{q}_t)_{t\geq 0}$

$$\mathrm{d}\overline{q}_t = -\nabla V(\overline{q}_t)\mathrm{d}t + \sqrt{2\beta^{-1}}\mathrm{d}B_t,$$

on a C^2 bounded connected set \mathcal{O} of \mathbb{R}^d , where $\beta^{-1} = k_B T > 0$, $V \in C^{\infty}(\mathbb{R}^d, \mathbb{R}^d)$ (see Gong, Qian and Zhao (1988), Le Bris, Lelièvre, Luskin, Perez (2012)).

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- (Lebesgue density) $\overline{\mu}(\mathrm{d} q) = \overline{\psi}(q)\mathrm{d} q$,
- (Spectral interpretation) $\overline{\psi}$ is the unique non-negative, normalized, classical solution in $\mathcal{C}^2(\mathcal{O}) \cap \mathcal{C}^b(\overline{\mathcal{O}})$ of the following eigenvalue problem

$$\left\{egin{aligned} \overline{\mathcal{L}}^*\overline{\psi}&=-\overline{\lambda}\,\overline{\psi}, & ext{ on }\mathcal{O}, \ \overline{\psi}&=0, & ext{ on }\partial\mathcal{O}, \end{aligned}
ight.$$

where $\overline{\mathcal{L}}^* = \operatorname{div}(\nabla V \cdot) + \beta^{-1} \Delta$,

(Convergence) $\exists C > 0, \exists \alpha > 0 \text{ s.t. } \forall t \ge 0, \forall \theta \text{ probability on } \mathcal{O},$

$$\left\|\mathbb{P}_{\theta}(\overline{q}_t \in \cdot | \overline{\tau}_{\partial} > t) - \overline{\mu}(\cdot) \right\|_{TV} \leq C \mathrm{e}^{-\alpha t},$$

where $\overline{\tau}_{\partial} = \inf\{t > 0 : \overline{q}_t \notin \mathcal{O}\}.$

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Question: Extension to the Langevin process on $D := \mathcal{O} \times \mathbb{R}^d$?

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Langevin process

Let $F \in \mathcal{C}^{\infty}(\mathbb{R}^d, \mathbb{R}^d)$, $\gamma \in \mathbb{R}$, $\sigma > 0$. Consider the Langevin process $(X_t = (q_t, p_t))_{t \ge 0}$ on \mathbb{R}^{2d}

$$\begin{cases} \mathrm{d}\boldsymbol{q}_t = \boldsymbol{p}_t \mathrm{d}\boldsymbol{t}, \\ \mathrm{d}\boldsymbol{p}_t = \boldsymbol{F}(\boldsymbol{q}_t) \mathrm{d}\boldsymbol{t} - \gamma \boldsymbol{p}_t \mathrm{d}\boldsymbol{t} + \sigma \mathrm{d}\boldsymbol{B}_t. \end{cases}$$

The infinitesimal generator \mathcal{L} of $(q_t, p_t)_{t \geq 0}$ on \mathbb{R}^{2d} (kinetic Fokker-Planck operator) is given by

$$\mathcal{L} = p \cdot
abla_q + F(q) \cdot
abla_p - \gamma p \cdot
abla_p + rac{\sigma^2}{2} \Delta_p.$$

Differences between the study of $(\overline{q}_t)_{t\geq 0}$ in \mathcal{O} and $(q_t, p_t)_{t\geq 0}$ in $D = \mathcal{O} \times \mathbb{R}^d$:

- \mathcal{L} is only **hypoelliptic** on \mathbb{R}^{2d} but not elliptic,
- \mathcal{O} is bounded but $D = \mathcal{O} \times \mathbb{R}^d$ is not.

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Boundary of D

Partition of ∂D :

- $\Gamma^+ := \{(q, p) \in \partial \mathcal{O} \times \mathbb{R}^d : \langle p, n(q) \rangle > 0\}$ (exiting velocities),
- $\Gamma^- := \{(q, p) \in \partial \mathcal{O} \times \mathbb{R}^d : \langle p, n(q) \rangle < 0\}$ (entering velocities),
- $\Gamma^0 := \{(q, p) \in \partial \mathcal{O} \times \mathbb{R}^d : \langle p, n(q) \rangle = 0\}$ (tangential velocities),

where n(q) is the unitary outward normal vector to \mathcal{O} at $q \in \partial \mathcal{O}$.

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Figure: Boundary of $D = (-1, 1) \times \mathbb{R}$

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1. Transition density

Theorem (Transition density)

There exists a smooth function

$$(t, x, y) \mapsto \mathrm{p}_t^D(x, y) \in \mathcal{C}^\infty(\mathbb{R}^*_+ \times D \times D) \times \mathcal{C}(\mathbb{R}^*_+ \times \overline{D} \times \overline{D})$$

such that for all t > 0, $x \in \overline{D}$ and $f \in L^{\infty}(D)$,

$$\mathcal{P}_t^D f(x) := \mathbb{E}_x \left[\mathbb{1}_{\tau_\partial > t} f(X_t) \right] = \int_D \mathrm{p}_t^D(x, y) f(y) \mathrm{d}y,$$

where $\tau_{\partial} = \inf\{t > 0 : X_t \notin D\}.$

Besides,

•
$$\forall t > 0, x \in D, \ \partial_t \mathbf{p}_t^D(x, y) = \mathcal{L}_x \mathbf{p}_t^D(x, y) = \mathcal{L}_y^* \mathbf{p}_t^D(x, y),$$

•
$$p_t^D(x, y) = 0$$
 if $x \in \Gamma^+ \cup \Gamma^0$ or $y \in \Gamma^- \cup \Gamma^0$,

• $p_t^D(x, y) > 0$ if $x \notin \Gamma^+ \cup \Gamma^0$ and $y \notin \Gamma^- \cup \Gamma^0$.

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1. Transition density

For any $\alpha \in (0,1]$, let $(\widehat{X}_t^{(\alpha)} = (\widehat{q}_t^{(\alpha)}, \widehat{p}_t^{(\alpha)}))_{t \ge 0}$ be the solution on \mathbb{R}^{2d} of

$$\begin{cases} \mathrm{d}\widehat{q}_{t}^{(\alpha)} = \widehat{p}_{t}^{(\alpha)} \mathrm{d}t, \\ \mathrm{d}\widehat{p}_{t}^{(\alpha)} = -\gamma \widehat{p}_{t}^{(\alpha)} \mathrm{d}t + \frac{\sigma}{\sqrt{\alpha}} \mathrm{d}B_{t}. \end{cases}$$

Let $\widehat{p}_t^{(\alpha)}(x, y)$ be its transition density.

Theorem (Gaussian upper-bound)

For any $\alpha \in (0,1)$, T > 0, there exists C > 0 such that for all $t \in (0,T]$, for all $x, y \in D$,

$$p_t^D(x,y) \leq C \widehat{p}_t^{(\alpha)}(x,y).$$

This result is inspired from work on the parametrix method by Konakov, Menozzi, Molchanov (2010). One can show that $\widehat{p}_t^{(\alpha)} \in L^{\infty}(D \times D) \cap L^1(D \times D)$ (thus in any $L^p(D \times D)$ for $p \ge 1$).

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2. Compactness

Compactness of the semigroup

For any $p \in [1, +\infty]$ and t > 0, the operator P_t^D is compact from $\mathcal{C}^b(\overline{D})$ to $\mathcal{C}^b(\overline{D})$.

Proof:

- $\widehat{p}_t^{(\alpha)} \in L^2(D \times D) \Rightarrow P_t^D$ is a Hilbert-Schmidt integral operator, hence compact in $L^2(D)$.
- Propagate to $\mathcal{C}^{b}(\overline{D})$ using the Gaussian upper-bound.

Reference: Lelievre, R., Reygner - Journal of Evolution Equations (2022).

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Krein-Rutman theorem

The compactness provides key spectral properties leading to the existence of a QSD, using in particular Krein-Rutman theorem.

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The compactness provides key spectral properties leading to the existence of a QSD, using in particular Krein-Rutman theorem.

Theorem (QSD existence/uniqueness and convergence properties)

There exists a unique QSD μ on $D = \mathcal{O} \times \mathbb{R}^d$ for the Langevin process $(X_t)_{t>0}$. Besides, μ satisfies:

- $(\mathbf{d}x) = \psi(x)\mathbf{d}x \text{ on } D,$
- **2** ψ is the unique, normalized, non-negative classical solution in $C^2(D) \cap C^b(D \cup \Gamma^-)$ of the following eigenvalue problem

$$\begin{array}{ll} \mathcal{L}^*\psi(x) = -\lambda\psi(x), & x \in D \\ \psi(x) = 0, & x \in \Gamma^- \end{array}$$

③ There exists $\alpha > 0$ such that for all θ probability on *D*, there exists $C_{\theta} > 0$ and for all $t \ge 0$,

$$\left\|\mathbb{P}_{\theta}(X_t \in \cdot | \tau_{\partial} > t) - \mu(\cdot)\right\|_{TV} \leq C_{\theta} e^{-\alpha t}.$$

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Overdamped Langevin exit point

If $\overline{q}_0 \sim \overline{\mu}(\mathrm{d} q) = \overline{\psi}(q) \mathrm{d} q$ (QSD), then

$$ar{q}_{\overline{ au}_{\partial}} \sim rac{eta^{-1}}{\overline{\lambda}} |\partial_{ extsf{n}} \overline{\psi}(extsf{q})| \sigma_{\partial \mathcal{O}}(\mathrm{d} extsf{q}),$$

where $\sigma_{\partial \mathcal{O}}$ is the surface measure on $\partial \mathcal{O}$.

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where $\sigma_{\partial \mathcal{O}}$ is the surface measure on $\partial \mathcal{O}$.

Proof: Integration by parts on

$$\int_{\mathcal{O}} \mathbb{E}_{q} \left[f(\overline{q}_{\overline{\tau}_{\partial}}) \right] \overline{\psi}(q) \mathrm{d}q,$$

using that $\mathcal{L}^*\overline{\psi} = -\overline{\lambda}\,\overline{\psi}$ (see Le Bris, Lelievre, Luskin, Perez (2010)).

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Langevin exit point

If $(q_0, p_0) \sim \mu(\mathrm{d}q, \mathrm{d}p) = \psi(q, p) \mathrm{d}q \mathrm{d}p$ (QSD), then

$$(q_{\tau_{\partial}}, p_{\tau_{\partial}}) \sim \frac{1}{\lambda} |p \cdot n(q)| \psi(q, p) \sigma_{\partial \mathcal{O}}(\mathrm{d}q) \mathrm{d}p,$$

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Consider here $\gamma > 0$ and $\sigma = \sqrt{2\gamma\beta^{-1}}$. Let $\left(X_t^{(\gamma)} = (q_t^{(\gamma)}, p_t^{(\gamma)})\right)_{t \ge 0}$ be the Langevin process

$$\begin{cases} \mathrm{d} \boldsymbol{q}_t^{(\gamma)} = \boldsymbol{p}_t^{(\gamma)} \mathrm{d} t, \\ \mathrm{d} \boldsymbol{p}_t^{(\gamma)} = \boldsymbol{F}(\boldsymbol{q}_t^{(\gamma)}) \mathrm{d} t - \gamma \boldsymbol{p}_t^{(\gamma)} \mathrm{d} t + \sqrt{2\gamma\beta^{-1}} \mathrm{d} \boldsymbol{B}_t. \end{cases}$$

Let $(\overline{q}_t)_{t>0}$ be the overdamped Langevin process

$$\mathrm{d}\overline{q}_t = F(\overline{q}_t)\mathrm{d}t + \sqrt{2\beta^{-1}}\mathrm{d}B_t$$

Assume that F is globally Lipschitz, then for T > 0,

$$Law((q_{\gamma t}^{(\gamma)})_{t\in[0,T]}) \xrightarrow[\gamma \to \infty]{} Law((\overline{q}_t)_{t\in[0,T]}).$$

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Question: Overdamped limit of the Langevin QSD ?

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Overdamped limit of the Langevin QSD

Let $\mu^{(\gamma)}$ be the Langevin QSD on D and $\overline{\mu}$ be the overdamped Langevin QSD on \mathcal{O} , then

$$\mu^{(\gamma)}(\mathrm{d}q\mathrm{d}p) \underset{\gamma \to \infty}{\longrightarrow} \overline{\mu}(\mathrm{d}q) \frac{\mathrm{e}^{-\beta \frac{|p|^2}{2}}}{(2\pi\beta^{-1})^{d/2}} \mathrm{d}p.$$

Besides,

$$\lambda^{(\gamma)} \underset{\gamma \to \infty}{\sim} \frac{\lambda}{\gamma}$$

Reference: R. - Electronic Journal of Probability (2022).

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Besides,

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Reference: R. - Electronic Journal of Probability (2022).

Stationary overdamped limit

Let $\mu_{\infty}^{(\gamma)}$ be the Langevin stationary distribution and $\overline{\mu_{\infty}}$ be the overdamped Langevin stationary distribution, then there exists C > 0 such that for all $\gamma \geq 2$,

$$\mathcal{W}\left(\mu_{\infty}^{(\gamma)},\overline{\mu}_{\infty}\otimes\mathcal{L}(\mathcal{Z})
ight)\leq Crac{\sqrt{\log(\gamma)}}{\gamma}.$$

Reference: Monmarché, R. - Electronic Communications in Probability (2022)

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Research letter



R., Lelièvre and Reygner - Mathematical foundations for the Parallel Replica algorithm applied to the underdamped Langevin dynamics - *MRS Communications*, 2022.

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Introduction

- Metastability in molecular dynamics and the Parallel Replica algorithm
- Quasi-stationary distribution and Parallel Replica justification

2 Langevin process and kinetic Fokker-Planck equation

- Transition density of the absorbed semigroup
- Compactness of the absorbed semigroup

3 Quasi-stationary distributions and overdamped limit of the Langevin process

- Existence and long-time convergence
- Overdamped limit of the QSD

Metadynamics

- Description of the algorithm
- Adaptative Metadynamics

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Metadynamics for the Mueller potential

Consider the two-dimensional overdamped Langevin dynamics

$$\mathrm{d}X_t = -\nabla V(X_t)\mathrm{d}t + \sqrt{2k_BT}\mathrm{d}B_t,$$

where V is the Mueller potential defined by:

$$V(x_1, x_2) = \sum_{i=1}^{4} K_i e^{a_i (x_1 - \beta_i)^2 + b_i (x_1 - \beta_i) (x_2 - \gamma_i) + c_i (x_2 - \gamma_i)^2}.$$

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Figure: Sampling in the Mueller potential. 100 000 iterations

We want to sample a transition path between A and B using Metadynamics.

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Metadynamics

Definition: A collective variable $s : \mathbb{R}^2 \mapsto \mathbb{R}$ captures the low-dimensional information of the system. A good collective variable takes different values in relevant *metastable states* and *transition states*.

Equilibrium distribution:

$$X_{\infty} \sim \mu(x) = rac{\mathrm{e}^{-V(x)/k_BT}}{lpha}.$$

Latent equilibrium distribution:

$$s(X_{\infty}) \sim p(s) = \int_{\mathbb{R}^2} \mu(x) \delta_{s(x)=s}(\mathrm{d}x).$$

Free energy:

$$F(s) = -k_B T \log(p(s)).$$

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Metadynamics

Assuming one has an estimate $B \approx -F$. If we perturb the potential into $\tilde{V}(x) = V(x) + B(s(x))$.

$$\begin{split} s(\tilde{X}_{\infty}) &\sim \tilde{p}(s) \propto \int_{\mathbb{R}^2} \delta_{s(x)=s} (\mathrm{d}x) \mathrm{e}^{-(V(x)+B(s(x))/k_B T} \\ &= \mathrm{e}^{-B(s)/k_B T} \int_{\mathbb{R}^2} \delta_{s(x)=s} (\mathrm{d}x) \mathrm{e}^{-V(x)/k_B T} \\ &= \mathrm{e}^{-B(s)/k_B T} \mathrm{e}^{-F(s)/k_B T} \approx 1. \end{split}$$

As a result,

 $s(ilde{X}_{\infty}) \sim$ Uniform

Problem: We need a free energy estimate first ...

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Metadynamics

Build an approximation of F iteratively:

$$B_{t+1}(s) = B_t(s) + w e^{-\frac{(s_t-s)^2}{2\sigma^2}}$$



Figure: Metadynamics

Generates uniform samples on the path $A \leftrightarrow B$.

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Autoencoder

Train the sampled data on an autoencoder to obtain the collective variable.



$$Loss = \|x - y\|^2.$$

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Metadynamics trajectories



Figure: 50 000 Metadynamics iterations with autoencoder trained on the database of A and B

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Metadynamics trajectories



Figure: 50 000 Metadynamics iterations with autoencoder trained on the database of A and B



Figure: 25 000 Metadynamics iterations with CV as the orthogonal projection on [AB]

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Train the autoencoder adaptatively on the previous trajectory after every 1000 Metadynamics iterations.

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Train the autoencoder adaptatively on the previous trajectory after every 1000 Metadynamics iterations.



Figure: 40 000 Metadynamics iterations with autoencoder trained iteratively on the trajectory

Impose conditions on the path such that it visits A and B.

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Impose conditions on the path such that it visits A and B.

$$Loss = \|x - AE(x)\|^{2} + (\|AE(x_{A}) - x_{A}\|^{2} + \|AE(x_{B}) - x_{B}\|^{2})/2.$$

The path is defined by:

- (Latent projection) $s_A = s(x_A), s_B = s(x_B)$
- (Discretization) $s_i = s_A + i(s_B s_A)/N$, $(1 \le i \le N)$.
- Path is given by $(D(s_i))_{1 \le i \le N}$,

where D is the decoder of the autoencoder.

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- Path is given by $(D(s_i))_{1 \le i \le N}$,

where D is the decoder of the autoencoder.



Figure: 38 000 Metadynamics iterations with autoencoder trained iteratively on the trajectory. Path is plotted in orange.

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Consider a modified Mueller potential \tilde{V} defined by:

$$\tilde{V}(x) = V(x) + (-100 + ||x - \eta||^2) e^{-2||x - \eta||^2},$$

with $\eta = [-1.7, 0.2]$.

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$$\tilde{V}(x) = V(x) + (-100 + ||x - \eta||^2) e^{-2||x - \eta||^2},$$

with $\eta = [-1.7, 0.2]$.



Figure: 100 000 Metadynamics iterations with autoencoder trained iteratively on the trajectory. Path in orange.

Penalize high energy configurations happening in the path.

$$Loss = \|x - y\|^{2} + (\|AE(x_{A}) - x_{A}\|^{2} + \|AE(x_{B}) - x_{B}\|^{2})/2 + E_{path},$$

where

$$E_{path} = \sum_{i=1}^{N} \|D(s_{i+1}) - D(s_i)\|(V(D(s_i)) + C),$$

with C > 0 such that $V(D(s_i)) + C > 0$.

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Figure: 100 000 Metadynamics iterations with autoencoder trained iteratively on the trajectory. Path in orange.

Reference: R., Boudier, Goryaeva, Marinica and Maillet - *Journal of Chemical Theory and Computation*, (2022).

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Mouad Ramil (Seoul National University)			March 3	27 2023		31 / 32

Thank you for your attention!

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