GAFD Tutorial I

Keith Julien

Department of Applied Mathematics, University of Colorado Boulder

Mathematics of Turbulence Long Program

IPAM, UCLA Sept 8th-12th



Geophysical Fluid Dynamics (GFD)

- GFD: Turbulent dynamics of (stably and unstably) stratified fluids on a giant rotating sphere
 - ~ planetary atmospheres, oceans, interiors
 - \sim stellar interiors
 - other geometries also occur, .e.g. cylindrical geometries observed in astrophysical accretion disks.
- Motivation
 - ~ understand complex phenomena occurring in GFD object
 - ~ gain predictive understanding with perhaps the ability to forecast (e.g. climate, solar weather)
- Methodology (challenge: spatio-temporal complexity)
 - finding good mathematical, experimental representations that provide good physical interpretations of GFD systems => mix of (applied) mathematics and theoretical physics
 - Paucity of data from observation/laboratory ==> GFD heavily computational

Some examples (an incomplete sample)

A mix of observations and simulations





General circulation, rotation and stratification gives rise to jets: e.g. polar & subtropical. Instability - Rossby waves





General circulation, rotation and stratification gives rise to jets: e.g. polar & subtropical. Instability - Rossby waves





Equatorial region is a wave-guide rich in trapped waves.

Coupling with moisture in the form of deep convection leads to persistent oscillatory features on seasonal and intraseasonal timescale.

Madden-Julian-Oscillation (eastward propagation of anomalous rainfall)

Ocean dynamics

mesoscale ~ O(100) km



$\frac{\text{submesoscale} \le O(1) \text{ km}}{\text{Langmuir Turbulence}}$



planetary - gyre scale ~ O(1000) km





Liquid iron outer core is the seat of the geodynamo. - convectively unstable and strongly influence by rotation

Earth's Interior

Complex wave phenomena





Electrically conducting fluid heavily influenced by Earth's rotation s.t. motions are highly anisotropic. B-field free decay time: 20,000 yrs Existence: 4 billion years

Earth's Interior

Complex wave phenomena





Electrically conducting fluid heavily influenced by Earth's rotation s.t. motions are highly anisotropic. B-field free decay time: 20,000 yrs Existence: 4 billion years

Earth's Interior

Complex wave phenomena



Geomagnetic reversal in dipole field occur on O(100K yrs) with transient on O(10Kyrs) Non-axisymmetric component temporal changes on O(1Kyr) including westward drift

Giant Planets

Scott & Polvani JAS 2007



Characterized by alternating bands of zonal jets w vortical eddy generation in region of strong shear

Jet formation is an open question - observed dynamics are likely a combination of strongly-stably stratified weather layer and rotationally constrained convective turbulence in the deep interior.



Characterized by alternating bands of zonal jets w vortical eddy generation in region of strong shear

Open question - observed dynamics are likely a combination of strongly-strably stratified weather layer and rotationally constrained convective turbulence in the deep interior.



Characterized by alternating bands of zonal jets w vortical eddy generation in region of strong shear

Open question - observed dynamics are likely a combination of strongly-stably stratified weather layer and rotationally constrained convective turbulence in the deep interior.

Solar Dynamics





Rotating convective turbulence is the prime driver of the interior structure.

Open question - model demonstrations of differential rotation pattern, solar tachocline, self consistent dynamo mechanism



Brown et al ApJ 2010



DAILY SUNSPOT AREA AVERAGED OVER INDIVIDUAL SOLAR ROTATIONS

Rotating convective turbulence is the prime driver of interior structure.

Open question - self consistent model demonstrations of differential rotation pattern, solar tachocline, self consistent dynamo mechanism



1. Protostars in Nebula

A disk of mostly gas and some dust swirls around a new star.

3. Young star with protoplanetary disk



Holes begin to open in the disk as dust and gas collide, stick together, and begin to form planets.



2. Protoplanetary Disk begins to form

4. Planet formation

Courtesy H. Khlar



Open problem - generation of turbulence, efficiency of turbulence in disk generation and longevity of vortical eddies (? self-sustaining baroclinic instability)

Navier-Stokes Equation



Nonlinear Cascade

$$\partial_t \boldsymbol{u} + (\boldsymbol{u} \cdot \nabla \boldsymbol{u}) = -E \boldsymbol{u} \nabla \boldsymbol{p} + \frac{1}{Re} \nabla^2 \boldsymbol{u} + \boldsymbol{F}$$

Sall'03-02402

 $\nabla \cdot \boldsymbol{u} = 0$

Big whorls have little whorls That feed on their velocity, And little whorls have lesser whorls And so on to viscosity. Lewis F. Richardson, 1922 Nonlinear Cascade

$$\partial_t \boldsymbol{u} + (\boldsymbol{u} \cdot \nabla \boldsymbol{u}) = -E \boldsymbol{u} \nabla \boldsymbol{p} + \frac{1}{Re} \nabla^2 \boldsymbol{u} + \boldsymbol{F}$$

Sale Stor

$$\nabla \cdot \boldsymbol{u} = 0$$



Kolmogorov Hypothesis

Kolmogorov Scales



Homogeneous Turbulence



Isotropic turbulence



Anisotropy at dissipation scales

She et al., Nature, Vol. 334, 226-228, 1990

Geophysical Fluids

Inclusion of Rotation and Stratification

Rotation/Coriolis Force $F_c = 2\boldsymbol{\Omega} \times \boldsymbol{u}$



Coriolis Force: pseudo-force that appears in a rotating frame of reference w/ fixed rotation acts to deflect fluid parcels perpendicular to their direction of motion

$$\begin{bmatrix} D \\ Dt \end{bmatrix}_i = \begin{bmatrix} D \\ Dt \end{bmatrix}_r + \mathbf{\Omega} \times \mathbf{r}$$
$$\mathbf{u}_i = \mathbf{u}_r + \mathbf{\Omega} \times \mathbf{r}$$
$$\mathbf{u}_r : \begin{bmatrix} D_t \mathbf{u}_r \end{bmatrix}_i = \begin{bmatrix} D_t \mathbf{u}_r \end{bmatrix}_r + \mathbf{\Omega} \times \mathbf{u}_r$$

Rotation/Coriolis Force $F_c = 2\boldsymbol{\Omega} \times \boldsymbol{u}$



Coriolis Force: pseudo-force that appears in a rotating frame of reference w/ fixed rotation acts to deflect fluid parcels perpendicular to their direction of motion

$$\left[\frac{D}{Dt}\right]_{i} = \left[\frac{D}{Dt}\right]_{r} + \mathbf{\Omega} \times \mathbf{u}_{i}: \ \left[D_{t}\boldsymbol{u}_{i}\right]_{i} = \left[D_{t}\boldsymbol{u}_{r}\right]_{r} + 2\mathbf{\Omega} \times \boldsymbol{u}_{r} + \mathbf{\Omega} \times \mathbf{\Omega} \times \boldsymbol{r}$$

Rotation/Coriolis Force $F_c = 2\boldsymbol{\Omega} \times \boldsymbol{u}$





Coriolis Force: pseudo-force that appears in a rotating frame of reference w/ fixed rotation acts to deflect fluid parcels perpendicular to their direction of motion

$$\left[\frac{D}{Dt}\right]_{i} = \left[\frac{D}{Dt}\right]_{r} + \boldsymbol{\Omega} \times \boldsymbol{u}_{i}: \ \left[D_{t}\boldsymbol{u}_{i}\right]_{i} = \left[D_{t}\boldsymbol{u}_{r}\right]_{r} + 2\boldsymbol{\Omega} \times \boldsymbol{u}_{r} + \boldsymbol{\Omega} \times \boldsymbol{\Omega} \times \boldsymbol{r}$$

Rotation/Coriolis Force



 $\begin{array}{ll} \text{Earth:} & 2\Omega\sim 1.4\times 10^{-4} \text{rad/s}, & \beta\sim 2.2\times 10^{-11} \text{rad/m s} \\ \text{Jupiter:} & 2\Omega\sim 3.5\times 10^{-4} \text{rad/s}, & \beta\sim 4.9\times 10^{-12} \text{rad/m s} \\ \text{sun:} & 2\Omega\sim 5\times 10^{-6} \text{rad/s} \end{array}$

Local approximations of 2Ω

f-plane: $f \approx 2\Omega \sin \vartheta$

 β -plane: $f \approx 2\Omega \sin \vartheta + \beta y$

eq-plane:
$$f \approx \beta y$$
 $\beta = \frac{2\Omega}{R_p} \cos \vartheta$

Coriolis Force: pseudo-force that appears in a rotating frame of reference w/ fixed rotation acts to deflect fluid parcels perpendicular to their direction of motion

$$\left[\frac{D}{Dt}\right]_{i} = \left[\frac{D}{Dt}\right]_{r} + \boldsymbol{\Omega} \times \boldsymbol{u}_{i} : \left[D_{t}\boldsymbol{u}_{i}\right]_{i} = \left[D_{t}\boldsymbol{u}_{r}\right]_{r} + 2\boldsymbol{\Omega} \times \boldsymbol{u}_{r} + \boldsymbol{\Omega} \times \boldsymbol{\Omega} \times \boldsymbol{r}$$

Governing Equations

$$\partial_t \boldsymbol{u} + \boldsymbol{u} \cdot \nabla \boldsymbol{u} + \frac{1}{Ro} \hat{\boldsymbol{z}} \times \boldsymbol{u} = -E \boldsymbol{u} \nabla \boldsymbol{\pi} + \frac{1}{Re} \nabla^2 \boldsymbol{u} + \boldsymbol{F}$$
$$\nabla \cdot \boldsymbol{u} = 0$$
$$Ro = \frac{U^2/L}{2\Omega U} = \frac{\text{inertia}}{\text{Coriolis}} = \frac{U}{2\Omega L}$$

Types of motion affected by the Coriolis force: Inherent spin is less than planetary angular velocity $Ro \leq 1$ or $U/L \leq 2\Omega$ Vary on timescales greater than a planetary day $StrRo \leq 1$ or $T \geq 1/2\Omega$

Governing Equations

$$\partial_t \boldsymbol{u} + \boldsymbol{u} \cdot \nabla \boldsymbol{u} + \frac{1}{Ro} \hat{\boldsymbol{z}} \times \boldsymbol{u} = -E \boldsymbol{u} \nabla \boldsymbol{\pi} + \frac{1}{Re} \nabla^2 \boldsymbol{u} + \boldsymbol{F}$$

$$\nabla \cdot \boldsymbol{u} = 0$$
Zeman length-scale
$$Ro - \frac{U}{Rol_0} \sim 1, \qquad l_\Omega = \frac{\varepsilon^{1/2}}{\varepsilon^{1/2}} \approx LRo^{3/2}$$

$$Ro = \frac{U}{2\Omega L}$$

$$Ro_{l_{\Omega}} \sim 1, \qquad l_{\Omega} = \frac{\varepsilon^{1/2}}{(2\Omega)^{3/2}} \approx LRo^{3/2}$$

Types of motion affected by the Coriolis force:

 $Ro \leq 1$ or $U/L \leq 2\Omega$ Inherent spin is less than planetary angular velocity $StrRo \leq 1$ or $T \geq 1/2\Omega$ Vary on timescales greater than a planetary day

 $l \ge l_{\Omega} \qquad U \sim (\varepsilon l)^{1/3}$ What fluid scales are influence by rotation?

Inertial Oscillations

Consider case Eu << I/Ro, inviscid motions Re >>I

$$\frac{Du}{Dt} - \frac{1}{Ro}v = 0$$
$$\frac{D^2u}{Dt^2} + \frac{1}{Ro^2}u = 0$$
$$\frac{Dv}{Dt} + \frac{1}{Ro}u = 0$$

Inertial oscillation: velocities oscillate with period $T_i = \pi/2\Omega$

$$u = U\cos(Ro^{-1}t), \ v = U\sin(Ro^{-1}t) \longrightarrow u_d = U_d\cos(2\Omega t), \ v_d = U_d\sin(2\Omega t)$$

Inertial circles: fluid parcels trace a circle of radius R_i in one inertial period





Inertial Oscillations: Oceanic example

Velocity profiles in N. Pacific Subtropical Front 30 N 100 300 500 DEPTH (m") 700 100 300 500 700 900 20 cm/s 380 Kunze & Sanford J. Phys. Ocean 1984



Horizontal velocity profiles taken a half inertial period apart are near mirror-images of each other suggesting flows are dominated by inertial motions

Half the variance in the IW band is explained by inertial motions in the upper ocean (Ferrari & Wunsch.Ann. Rev. Fluid Mech 2008).

Dispersion Relation: Waves vs Eddies

Consider case Eu ~ I/Ro, inviscid motions Re >>I

Separation of dynamics into fast and slow motions (waves and eddies).

$$\partial_t \boldsymbol{u} + \frac{1}{Ro} \widehat{\boldsymbol{z}} \times \boldsymbol{u} \approx -Eu \nabla p$$

$$\nabla \cdot \boldsymbol{u} = 0$$

$$\boldsymbol{v} \propto e^{i(\boldsymbol{k}\cdot\boldsymbol{x}-\omega t)}, \ \boldsymbol{k}\cdot\boldsymbol{u}=0, \ \boldsymbol{k}=(\boldsymbol{k}_{\perp},k_{z})=|\boldsymbol{k}|(\cos\phi,\sin\phi)$$

Inertial waves

$$\partial_{tt} \nabla^2 w + \frac{1}{Ro^2} \partial_{zz} w = 0$$
$$\omega^2 = \frac{1}{Ro^2} \frac{k_z^2}{|\mathbf{k}|^2} = \frac{1}{Ro^2} \sin^2 \phi$$

Freq. only a function propagation dir'n

Vortical modes/eddies are in geostrophic balance

$$oldsymbol{u}_{\perp} = EuRo~(-\partial_y p, \partial_x p), \quad w = 0$$

 $\omega = 0, \quad \partial_z(oldsymbol{u}_{\perp}, p) = 0$

Taylor-Proudman constraint

Dispersion Relation: Waves vs Eddies

Consider case Eu ~ I/Ro, inviscid motions Re >>I

Separation of dynamics into fast and slow motions (waves and eddies).

$$\partial_t \boldsymbol{u} + \frac{1}{Ro} \widehat{\boldsymbol{z}} \times \boldsymbol{u} \approx -Eu \nabla p$$

$$\nabla \cdot \boldsymbol{u} = 0$$

$$\boldsymbol{v} \propto e^{i(\boldsymbol{k}\cdot\boldsymbol{x}-\omega t)}, \ \boldsymbol{k}\cdot\boldsymbol{u}=0, \ \boldsymbol{k}=(\boldsymbol{k}_{\perp},k_{z})=|\boldsymbol{k}|(\cos\phi,\sin\phi)$$

Inertial waves:

$$\partial_{tt} \nabla^2 w + \frac{1}{Ro^2} \partial_{zz} w = 0$$
$$\omega^2 = \frac{1}{Ro^2} \frac{k_z^2}{|\mathbf{k}|^2} = \frac{1}{Ro^2} \sin^2 \phi$$

Freq. only a function propagation dir'n

Vortical modes/eddies are in geostrophic balance

$$oldsymbol{u}_{\perp} = EuRo~(-\partial_y p, \partial_x p), \quad w = 0$$

 $\omega = 0, \quad \partial_z(oldsymbol{u}_{\perp}, p) = 0$

Taylor-Proudman constraint

Dispersion Relation: Waves vs Eddies

Consider case Eu ~ I/Ro >>I, inviscid motions Re >>I

Separation of dynamics into fast and slow motions (waves and eddies).

$$\partial_{t} \boldsymbol{u} + \frac{1}{Ro} \widehat{\boldsymbol{z}} \times \boldsymbol{u} \approx -Eu \nabla p$$

 $\nabla \cdot \boldsymbol{u} = 0$
Geostrophy

$$\boldsymbol{v} \propto e^{i(\boldsymbol{k}\cdot\boldsymbol{x}-\omega t)}, \ \boldsymbol{k}\cdot\boldsymbol{u}=0, \ \boldsymbol{k}=(\boldsymbol{k}_{\perp},k_{z})=|\boldsymbol{k}|(\cos\phi,\sin\phi)$$

Inertial waves

$$\partial_{tt} \nabla^2 w + \frac{1}{Ro^2} \partial_{zz} w = 0$$
$$\omega^2 = \frac{1}{Ro^2} \frac{k_z^2}{|\mathbf{k}|^2} = \frac{1}{Ro^2} \sin^2 \phi$$

Freq. only a function propagation dir'n

Vortical modes/eddies are in geostrophic balance

$$oldsymbol{u}_{\perp} = EuRo~(-\partial_y p, \partial_x p), \quad w = 0$$

 $\omega = 0, \quad \partial_z(oldsymbol{u}_{\perp}, p) = 0$

Taylor-Proudman constraint
Proudman-Taylor Constraint (Experiment)

Proudman 1916 Proc. Roy. Soc. Lond. A

Taylor 1923 Proc. Roy. Soc. Lond. A



Geostrophy: diagnostic balance

$$\frac{1}{Ro}\widehat{\boldsymbol{z}} \times \boldsymbol{u} \approx -Eu\nabla p$$

$$\nabla \cdot \boldsymbol{u} = 0$$

$$oldsymbol{u}_{\perp} = EuRo~(-\partial_y p, \partial_x p), \quad w = 0$$

 $\omega = 0, \quad \partial_z(oldsymbol{u}_{\perp}, p) = 0$

Proudman-Taylor Constraint (Experiment)

Proudman 1916 Proc. Roy. Soc. Lond. A

Taylor 1923 Proc. Roy. Soc. Lond. A





Geostrophy: diagnostic balance

$$\frac{1}{Ro}\widehat{\boldsymbol{z}} \times \boldsymbol{u} \approx -Eu\nabla p$$

$$\nabla \cdot \boldsymbol{u} = 0$$

$$oldsymbol{u}_{\perp} = EuRo~(-\partial_y p, \partial_x p), \quad w = 0$$

 $\omega = 0, \quad \partial_z(oldsymbol{u}_{\perp}, p) = 0$

 $\mathsf{Evolution} \Rightarrow$

 $f\approx 2\Omega\sin\vartheta$

Quasigeostrophy - (Prognostic) departure from geostrophy $u_{\perp} = u_{\perp}^G + u_{\perp}^{AG}$

$$\partial_t \boldsymbol{u}_{\perp} + \boldsymbol{u}_{\perp} \cdot \nabla_{\perp} \boldsymbol{u}_{\perp} + \frac{1}{Ro} \widehat{\boldsymbol{z}} \times \boldsymbol{u}_{\perp}^{AG} = -Eu \nabla_{\perp} p^{AG} + F + D$$

 $abla_{\perp} \cdot \left(oldsymbol{u}_{\perp}^{AG}
ight) = 0$



Bofetta & Ecke Ann. Rev. Fluid. Mech. 2012

 $f\approx 2\Omega\sin\vartheta$

Quasigeostrophy - (Prognostic) departure from geostrophy $u_{\perp}=u_{\perp}^G+u_{\perp}^{AG}$

$$egin{aligned} \partial_t \zeta + oldsymbol{u}_\perp \cdot
abla_\perp \zeta &= \mathcal{F} + \mathcal{D}, & \zeta_a = \widehat{oldsymbol{z}} \cdot
abla imes oldsymbol{u} + Ro^{-1} \ oldsymbol{u}_\perp &= -
abla imes \psi \widehat{oldsymbol{z}}, & \zeta =
abla_\perp^2 \psi \end{aligned}$$



Bofetta & Ecke Ann. Rev. Fluid. Mech. 2012

 $f\approx 2\Omega\sin\vartheta$

Quasigeostrophy - (Prognostic) departure from geostrophy $u_{\perp} = u_{\perp}^G + u_{\perp}^{AG}$

$$\partial_t \nabla_{\perp}^2 \psi + J[\psi, \nabla_{\perp}^2 \psi] = \mathcal{F} + \mathcal{D}, \quad \zeta_a = \widehat{\boldsymbol{z}} \cdot \nabla \times \boldsymbol{u} + Ro^{-1}$$
$$\boldsymbol{u}_{\perp} = -\nabla \times \psi \widehat{\boldsymbol{z}}, \quad \zeta = \nabla_{\perp}^2 \psi$$



Bofetta & Ecke Ann. Rev. Fluid. Mech. 2012

$$\partial_t \zeta + \boldsymbol{u}_\perp \cdot \nabla_\perp \zeta = \mathcal{F} + \mathcal{D},$$

Two conserved quantities: Energy $~~\langle |
abla_{ot}\psi|^2
angle$

$$\zeta_a = \widehat{\boldsymbol{z}} \cdot \nabla \times \boldsymbol{u} + Ro^{-1}$$
$$\boldsymbol{u}_{\perp} = -\nabla \times \psi \widehat{\boldsymbol{z}}, \quad \zeta = \nabla_{\perp}^2 \psi$$

Enstrophy $\langle |\zeta_a|^2 \rangle$

 $\frac{\varepsilon}{\varepsilon^{2/3}k^{-5/3}}$

Transfer between three interacting modes $\begin{aligned} k
<math display="block">\delta \mathcal{E}(p) < 0 \Rightarrow$

 $\delta \mathcal{E}(p) < 0 \Rightarrow$ $\delta \mathcal{E}(k) > \delta \mathcal{E}(q) > 0$ $\delta \mathcal{Z}(q) > \delta \mathcal{Z}(k) > 0$

Dual cascade: Energy
$$\mathcal{E}(k) = \int_0^\infty E(k) dk$$
 Enstrophy $\mathcal{Z}(k) = \int_0^\infty k^2 E(k) dk$

Tuesday, October 14, 14

 $\log(\mathcal{E}(k))$

Barotropic Vorticity Equation - Beta Plane

$$egin{aligned} \partial_t \zeta + oldsymbol{u}_\perp \cdot
abla_\perp \zeta + eta v &= \mathcal{F} + \mathcal{D}, & \zeta_a = \widehat{oldsymbol{z}} \cdot
abla imes oldsymbol{u} + Ro^{-1} + eta y \ oldsymbol{u}_\perp &= -
abla imes \psi \widehat{oldsymbol{z}}, & \zeta =
abla_\perp^2 \psi \end{aligned}$$

Two conserved quantities: Energy $~~\langle |
abla_{ot}\psi|^2
angle$

Enstrophy
$$\langle |\zeta_a|^2
angle$$

Dispersion Rel'n

$$\omega = \frac{\beta k_x}{k_x^2 + k_y^2}$$

westward propagation

Mechanism North



Rossby wave

Dual cascade: Energy
$$\mathcal{E}(k) = \int_0^\infty E(k) dk$$
 Enstrophy $\mathcal{Z}(k) = \int_0^\infty k^2 E(k) dk$

Barotropic Rossby Waves

Inverse energy cascade is suppressed by low wavenumber Rossby waves (Rhines JFM 1975)

$$\omega_{turb} \approx \omega_{\beta} \quad \Rightarrow \quad \varepsilon^{1/3} k_{\perp}^{2/3} \approx \frac{\beta k_x}{k_{\perp}^2}$$

Inverse cascade barrier

$$k_x \approx \left(\frac{\beta^3}{\varepsilon}\right)^{1/5} \cos^{8/5} \vartheta$$

$$k_y \approx \left(\frac{\beta^3}{\varepsilon}\right)^{1/5} \sin\vartheta \cos^{3/5}\vartheta$$



Dual cascade: Energy
$$\mathcal{E}(k) = \int_0^\infty E(k) dk$$
 Enstrophy $\mathcal{Z}(k) = \int_0^\infty k^2 E(k) dk$

Barotropic Rossby Waves

Inverse energy cascade is suppressed by low wavenumber Rossby waves

$$\omega_{turb} \approx \omega_{\beta} \quad \Rightarrow \quad \varepsilon^{1/3} k_{\perp}^{2/3} \approx \frac{\beta k_x}{k_{\perp}^2}$$

Inverse cascade barrier

$$k_x \approx \left(\frac{\beta^3}{\varepsilon}\right)^{1/5} \cos^{8/5} \vartheta$$

$$k_y \approx \left(\frac{\beta^3}{\varepsilon}\right)^{1/5} \sin\vartheta \cos^{3/5}\vartheta$$

Beta-plane spectrum



Dual cascade: Energy
$$\mathcal{E}(k) = \int_0^\infty E(k) dk$$
 Enstrophy $\mathcal{Z}(k) = \int_0^\infty k^2 E(k) dk$

Barotropic Rossby Waves



Maltrud & Vallis JFM1992



Dual cascade: Energy
$$\mathcal{E}(k) = \int_0^\infty E(k)dk$$
 Enstrophy $\mathcal{Z}(k) = \int_0^\infty k^2 E(k)dk$

Stratification/buoyancy Force $F_b = b\widehat{z} \equiv -g\frac{\delta\rho}{\rho_0}\widehat{z}, \qquad \rho = \rho_0 + \rho(z) + \delta\rho$



$$\begin{split} \frac{Dw}{Dt} &\approx -b \\ \frac{Db}{Db} &\approx -N^2(z)w \\ \hline \\ \frac{Db}{Dt} &\approx -N^2(z)w \end{split}$$

$$N^{2}(z) = -\frac{g}{\rho_{0}} \frac{\partial \rho(z)}{\partial z}$$

 $N^2(z) > 0, \quad \partial_z \rho(z) < 0$ above $\partial_z \rho(z) < 0$

Fluid parcel oscillates about equilibrium posn

Neutral stratification:

Stable stratification:

$$N^2(z) = 0, \quad \partial_z \rho(z) = 0$$

Unstable stratification:

 $N^2(z)<0,\quad \partial_z\rho(z)>0$

Fluid parcel accelerates away from equilibrium posn (Convection)

 $N^2 < 0$



The ocean is layered, with less dense water overriding denser water yielding a stratification:

$$N^{2} = -\frac{g}{\rho_{o}}\frac{\partial\rho}{\partial z} \sim 10^{-4} - 10^{-6} \text{ s}^{-2}$$





Fluid Equations: Stratified Flows

$$\partial_t \boldsymbol{u} + \boldsymbol{u} \cdot \nabla \boldsymbol{u} = -E u \nabla \pi + \frac{1}{Fr} b \widehat{\boldsymbol{z}} + \frac{1}{Re} \nabla^2 \boldsymbol{u} + \boldsymbol{F}$$

$$abla \cdot \boldsymbol{u} = 0$$

$$\partial_t b + \boldsymbol{u} \cdot \nabla b + \frac{1}{Fr} w = \frac{1}{Pe} \nabla^2 b$$

Froude number

$$Fr = \frac{U^2/H}{NU} = \frac{\text{inertia}}{\text{buoyancy}} = \sqrt{\frac{KE}{PE}} = \frac{U}{NH}$$

Ozmidov length scale

$$Fr_{l_b} \sim 1, \qquad l_b = rac{arepsilon^{1/2}}{N^{3/2}} pprox HFr^{3/2}$$

Types of motions affected by stratification:

KE less than PE release

Vary on timescales greater than a buoyancy period

$$Fr \leq 1$$
, or $U/H \leq N$
 $StrFr \leq 1$ or $T \leq 1/N$

What fluid scales are influence by rotation? $l \geq l_b \ U \sim (arepsilon l)^{1/3}$

Dispersion Relation: Waves & Eddies

Consider case Eu ~ I/Fr >>1, inviscid motions Re >>1

Separation of dynamics into fast and slow motions (waves and eddies).

$$egin{aligned} \partial_t oldsymbol{u} &pprox -Eu
abla p + rac{1}{Fr} b \widehat{oldsymbol{z}} \ &
abla \cdot oldsymbol{u} &= 0 \ &
abla_t b &pprox -rac{1}{Fr} w \end{aligned}$$

Normal mode analysis:

$$\boldsymbol{v} \propto e^{i(\boldsymbol{k}\cdot\boldsymbol{x}-\omega t)}, \ \boldsymbol{k}\cdot\boldsymbol{u}=0, \ \boldsymbol{k}=(\boldsymbol{k}_{\perp},k_{z})=|\boldsymbol{k}|(\cos\phi,\sin\phi)$$

Inertial waves (fast dynamics)

$$\partial_{tt} \nabla^2 w + \frac{1}{Fr^2} \nabla_{\perp}^2 w = 0$$
$$\omega^2 = \frac{1}{Fr^2} \frac{|\mathbf{k}_{\perp}|^2}{|\mathbf{k}|^2} = \frac{1}{Fr^2} \cos^2 \phi$$

Slow dynamics (eddies) are in hydrostatic balance

$$EuFr\partial_z p = b, \quad w = 0$$

 $\omega = 0, \quad \nabla_\perp(p,b) = 0$

Freq. only a function propagation dir'n

Internal Gravity Waves (Experiments)

$$T_{forcing} = 7 \sec \qquad T_{forcing} = 6 \sec \qquad T_{forcing} = 5 \sec$$

$$\frac{2\pi}{N} = 3.6 \text{ sec}$$

Experiments: Sakai's GFD lab

http://dennou.gaia.h.kyoto-u.ac.jp/library/gfd_exp/exp_e/index.htm

Dispersion Relation: Waves & Eddies

Consider case Eu ~ I/Fr >>1, inviscid motions Re >>1

Separation of dynamics into fast and slow motions (waves and eddies).

$$\begin{split} 0 &\approx -Eu\nabla p + \frac{1}{Fr}b\widehat{\boldsymbol{z}} \\ \nabla \cdot \boldsymbol{u} &= 0 \\ 0 &\approx -\frac{1}{Fr}w \end{split}$$

Normal mode analysis:

$$\boldsymbol{v} \propto e^{i(\boldsymbol{k}\cdot\boldsymbol{x}-\omega t)}, \ \boldsymbol{k}\cdot\boldsymbol{u}=0, \ \boldsymbol{k}=(\boldsymbol{k}_{\perp},k_{z})=|\boldsymbol{k}|(\cos\phi,\sin\phi)$$

Inertial waves (fast dynamics)

$$\begin{aligned} \partial_{tt} \nabla^2 w &+ \frac{1}{Fr^2} \nabla_{\perp}^2 w = 0 \\ \omega^2 &= \frac{1}{Fr^2} \frac{|\boldsymbol{k}_{\perp}|^2}{|\boldsymbol{k}|^2} = \frac{1}{Fr^2} \cos^2 \phi \end{aligned}$$

Slow dynamics (eddies) are in hydrostatic balance

$$EuFr\partial_z p = b, \quad w = 0$$

 $\omega = 0, \quad \nabla_\perp(p,b) = 0$

Freq. only a function propagation dir'n



1024^3 temperature Marino et al EPL 2013

FIGURE 5. Spectra $E_{\perp \Phi_1}(k_{\perp})$ for $N^2 = 1, 10, 50, 100$. The large-scale parts collapse to a single spectrum of $\sim k_{\perp}^{-3}$. On the other hand, the small scales form a different spectrum corresponding to the value of N, but each spectrum has the same slope of -5/3.

Forward cascade observed (Lindborg JFM 2004, Billant & Chomaz JFM 2000), break in exponent occurs at Ozmidov scale



$$\partial_t \boldsymbol{u} + \boldsymbol{u} \cdot \nabla \boldsymbol{u} + \frac{1}{Ro} \widehat{\boldsymbol{z}} \times \boldsymbol{u} = -E u \nabla \pi + \frac{1}{Fr_L} b \widehat{\boldsymbol{z}} + \frac{1}{Re} \nabla^2 \boldsymbol{u} + \boldsymbol{F}$$

 $\nabla \cdot \boldsymbol{u} = 0$

$$\partial_t b + \boldsymbol{u} \cdot \nabla b + \frac{1}{Fr_L} w = \frac{1}{Pe} \nabla^2 b$$

Rossby, Froude numbers;

$$Ro = \frac{U}{2\Omega L}, \quad Fr_L = \frac{U}{NL}, \quad Fr_v = \frac{U}{NH}$$

$$\partial_t \boldsymbol{u} + \boldsymbol{u} \cdot \nabla \boldsymbol{u} + \frac{1}{Ro} \widehat{\boldsymbol{z}} \times \boldsymbol{u} = -E u \nabla \pi + \frac{1}{Fr_L} b \widehat{\boldsymbol{z}} + \frac{1}{Re} \nabla^2 \boldsymbol{u} + \boldsymbol{F}$$

 $\nabla \cdot \boldsymbol{u} = 0$

$$\partial_t b + \boldsymbol{u} \cdot \nabla b + \frac{1}{Fr_L} w = \frac{1}{Pe} \nabla^2 b$$

Rossby, Froude numbers;

$$Ro = \frac{U}{2\Omega L}, \quad Fr_L = \frac{U}{NL}, \quad Fr_v = \frac{U}{NH}$$

$$\begin{cases} \mathsf{GFD \ setting} \\ \left(\frac{N}{2\Omega}\right)_{Earth} \sim 100, \ 2\Omega \sim 10^{-4} \mathrm{rad/s} \\ N > 2\Omega \ \Rightarrow \ Fr_L < Ro \ \Rightarrow \ l_b < l_\Omega \\ \mathsf{RST} \ \Rightarrow \ \mathsf{ST} \ \Rightarrow \ \mathsf{HT} \end{cases}$$

$$\partial_t \boldsymbol{u} + \boldsymbol{u} \cdot \nabla \boldsymbol{u} + \frac{1}{Ro} \widehat{\boldsymbol{z}} \times \boldsymbol{u} = -E u \nabla \pi + \frac{1}{Fr_L} b \widehat{\boldsymbol{z}} + \frac{1}{Re} \nabla^2 \boldsymbol{u} + \boldsymbol{F}$$

$$\nabla \cdot \boldsymbol{u} = 0$$

$$\partial_t b + \boldsymbol{u} \cdot \nabla b + \frac{1}{Fr_L} w = \frac{1}{Pe} \nabla^2 b$$

Rossby, Froude numbers;

$$Ro = \frac{U}{2\Omega L}, \quad Fr_L = \frac{U}{NL}, \quad Fr_v = \frac{U}{NH}$$

$$\begin{array}{l} & \operatorname{\mathsf{GFD}} \ \operatorname{setting} \\ & \left(\frac{N}{2\Omega}\right)_{Earth} \sim 100, \ 2\Omega \sim 10^{-4} \mathrm{rad/s} \\ & N > 2\Omega \ \Rightarrow \ Fr_L < Ro \ \Rightarrow \ l_b < l_\Omega \\ & \operatorname{\mathsf{RST}} \ \Rightarrow \ \operatorname{\mathsf{ST}} \ \Rightarrow \ \operatorname{\mathsf{HT}} \end{array}$$

(*i*) Hydrostatic balance: $Fr_L \ll 1 \Rightarrow Eu\partial_z \sim \frac{1}{Fr_L}, \ w \sim Fr_L$

(*ii*) PGF:
$$Eu \sim 1 \Rightarrow \partial_z \sim \frac{1}{Fr_L}$$

(*iii*) Rotation: $Ro \sim 1 \Rightarrow L_d = \frac{N}{2\Omega}H$

$$\underbrace{\partial_t \boldsymbol{u}_{\perp} + \boldsymbol{u} \cdot \nabla \boldsymbol{u}_{\perp}}_{H_{\perp}} + \frac{1}{Ro} \widehat{\boldsymbol{z}} \times \boldsymbol{u}_{\perp} = -Eu\nabla p + \frac{1}{Fr_L}b\widehat{\boldsymbol{z}} + \frac{1}{Re}\nabla^2 \boldsymbol{u}_{\perp} + F_{\perp}$$

$$\nabla \cdot \boldsymbol{u} = 0$$

Primitive Equations typical for GCM's

$$\partial_t b + \boldsymbol{u} \cdot \nabla b + \frac{1}{Fr_L} N^2(z) w = \frac{1}{Pe} \nabla^2 b$$

Rossby, Froude numbers;

$$Ro = \frac{U}{2\Omega L}, \quad Fr_L = \frac{U}{NL}, \quad Fr_v = \frac{U}{NH}$$

$$\begin{array}{l} \mbox{GFD setting} \\ \left(\frac{N}{2\Omega}\right)_{Earth} \sim 100, \ 2\Omega \sim 10^{-4} {\rm rad/s} \\ N > 2\Omega \ \Rightarrow \ Fr_L < Ro \ \Rightarrow \ l_b < l_\Omega \\ \mbox{RST} \ \Rightarrow \ \mbox{ST} \ \Rightarrow \ \mbox{HT} \end{array}$$

(i) Hydrostatic balance: $Fr_L \ll 1 \Rightarrow Eu\partial_z \sim \frac{1}{Fr_L}, \ w \sim Fr_L$

(*ii*) PGF:
$$Eu \sim 1 \Rightarrow \partial_z \sim \frac{1}{Fr_L}$$

(*iii*) Rotation: $Ro \sim 1 \Rightarrow L_d = \frac{N}{2\Omega}H$

Eddy - Wave dynamics for RST

$$\partial_t \boldsymbol{u} + \boldsymbol{u} \cdot \nabla \boldsymbol{u} + \frac{1}{Ro} \widehat{\boldsymbol{z}} \times \boldsymbol{u} = -Eu \nabla \pi + \frac{1}{Fr_L} b \widehat{\boldsymbol{z}} + \frac{1}{Re} \nabla^2 \boldsymbol{u} + \boldsymbol{F}$$

 $\nabla \cdot \boldsymbol{u} = 0$

$$\partial_t b + \boldsymbol{u} \cdot \nabla b + \frac{1}{Fr_L} w = \frac{1}{Pe} \nabla^2 b$$

Rossby, Froude numbers;

$$Ro = \frac{U}{2\Omega L}, \quad Fr_L = \frac{U}{NL}, \quad Fr_v = \frac{U}{NH}$$

Eddy - Wave dynamics for RST

Inertial-gravity waves have bounded spectrum

$$\begin{aligned} \partial_{tt} \nabla^2 w &+ \frac{1}{Ro^2} \partial_{zz} w + \frac{1}{Fr_L^2} \nabla_{\perp}^2 w \approx 0 \\ \omega_f^2 &= \frac{1}{Ro^2} \sin^2 \phi + \frac{1}{Fr_2^2} \cos^2 \phi \end{aligned}$$

Primitive Equations Filter isotropic IGW

$$\omega_f \in [1/Ro_L, 1/Fr_L] \to [2\Omega, N]$$

Slow dynamics in geostrophic and hydrostatic balance (Thermal wind balance) reduction: all field can be related to the pressure

$$egin{aligned} &rac{1}{Ro}\widehat{m{z}} imes m{u}&\approx -Eu
abla_{ot}p\ &0&pprox -Eu\partial_{m{z}}p+rac{1}{Fr_L}b\ &
abla_{ot}\cdotm{u}_{ot}&=0 \end{aligned}$$

Rotating Stratified Turbulence (Marino et al EPL 2013)



Inverse cascade for nonzero rotation rates



Inverse cascade for nonzero rotation rates

Mininni & AP, Phys. Fluids 22 (2010)

> Zoom on a Beltrami core vortex

amidst a tangle of smaller-scale vortex filaments

Together with particle trajectories

1536³ grid, k_F=7, Re=5100, Ro=0.06, 1536³ grid



Geostrophic - Nonhydrostatic Dynamics?

$$\partial_t \boldsymbol{u} + \boldsymbol{u} \cdot \nabla \boldsymbol{u} + \frac{1}{Ro} \widehat{\boldsymbol{z}} \times \boldsymbol{u} = -E u \nabla \pi + \frac{1}{Fr_L} b \widehat{\boldsymbol{z}} + \frac{1}{Re} \nabla^2 \boldsymbol{u} + \boldsymbol{F}$$

$$abla \cdot \boldsymbol{u} = 0$$

$$\partial_t b + oldsymbol{u} \cdot
abla b + rac{1}{Fr_L} w = rac{1}{Pe}
abla^2 b$$

For rotating, stably stratified flows, primary modeling tools are - Primitive equations and QuasiGesotrophic equation

What about unstably stratified flows?

Reduced PDE Models Balanced Dynamics

Unified QuasiGeostrophic (QG) Theory

Anisotropic rescaling of BE: A = H/L

$$\begin{split} D_t^{\perp} \boldsymbol{u}_{\perp} + \frac{1}{A} \boldsymbol{w} \partial_z \boldsymbol{u}_{\perp} + \frac{1}{Ro} \widehat{\boldsymbol{z}} \times \boldsymbol{u}_{\perp} &= -Eu \nabla_{\perp} p + \frac{1}{Re} \left(\nabla_{\perp}^2 + \frac{1}{A^2} \partial_{zz} \right) \boldsymbol{u}_{\perp} \\ D_t^{\perp} \boldsymbol{w} + \frac{1}{A} \boldsymbol{w} \partial_z \boldsymbol{w} &= -\frac{Eu}{A} \partial_z p + \frac{1}{Fr_L} b + \frac{1}{Re} \left(\nabla_{\perp}^2 + \frac{1}{A^2} \partial_{zz} \right) \boldsymbol{w} \\ D_t^{\perp} b + \frac{1}{A} \boldsymbol{w} \partial_z b + \frac{1}{Fr_L} \boldsymbol{w} N^2(z) &= \frac{1}{Pe} \left(\nabla_{\perp}^2 + \frac{1}{A^2} \partial_{zz} \right) b \\ \nabla_{\perp} \cdot \boldsymbol{u}_{\perp} + \frac{1}{A} \partial_z \boldsymbol{w} &= 0 \end{split}$$

Separate NSE into horizontal and vertical components

Geostrophy (diagnostic balance):

$$Eu \sim \frac{1}{Ro}$$

$$oldsymbol{u}_{\perp} = oldsymbol{u}_{\perp}^G + oldsymbol{u}_{\perp}^{AG}$$

$$D_t^{\perp} \boldsymbol{u}_{\perp} + \frac{1}{A} w \partial_z \boldsymbol{u}_{\perp} + \left(\frac{1}{Ro} \widehat{\boldsymbol{z}} \times \boldsymbol{u}_{\perp} = -E u \nabla_{\perp} p \right) + \frac{1}{Re} \left(\nabla_{\perp}^2 + \frac{1}{A^2} \partial_{zz} \right) \boldsymbol{u}_{\perp}$$

$$D_t^{\perp}w + \frac{1}{A}w\partial_z w = -\frac{Eu}{A}\partial_z p + \frac{1}{Fr_L}b + \frac{1}{Re}\left(\nabla_{\perp}^2 + \frac{1}{A^2}\partial_{zz}\right)w$$

$$D_t^{\perp}b + \frac{1}{A}w\partial_z b + \frac{1}{Fr_L}wN^2(z) = \frac{1}{Pe}\left(\nabla_{\perp}^2 + \frac{1}{A^2}\partial_{zz}\right)b$$

$$\left(
abla _{ot} \cdot oldsymbol{u}_{ot}
ight) + rac{1}{A} \partial_{oldsymbol{z}} w = 0$$

dynamics require ageostrophic motions

Geostrophy (diagnostic balance):

$$oldsymbol{u}_{ot}^G =
abla^{ot} p^G$$

$$D_t^{\perp} \boldsymbol{u}_{\perp}^G + \frac{1}{A} \boldsymbol{w} \partial_z \boldsymbol{u}_{\perp}^G + \frac{1}{Ro} \widehat{\boldsymbol{z}} \times \boldsymbol{u}_{\perp}^{AG} = -\frac{1}{Ro} \nabla_{\perp} p^{AG} + \frac{1}{Re} \left(\nabla_{\perp}^2 + \frac{1}{A^2} \partial_{zz} \right) \boldsymbol{u}_{\perp}^G$$
$$D_t^{\perp} \boldsymbol{w} + \frac{1}{A} \boldsymbol{w} \partial_z \boldsymbol{w} = -\frac{1}{ARo} \partial_z p^G + \frac{1}{Fr_L} b + \frac{1}{Re} \left(\nabla_{\perp}^2 + \frac{1}{A^2} \partial_{zz} \right) \boldsymbol{w}$$

$$D_t^{\perp}b + \frac{1}{A}w\partial_z b + \frac{1}{Fr_L}wN^2(z) = \frac{1}{Pe}\left(\nabla_{\perp}^2 + \frac{1}{A^2}\partial_{zz}\right)b$$

$$abla_{\perp} \cdot oldsymbol{u}_{\perp}^{AG} + rac{1}{A} \partial_{oldsymbol{z}} w = 0$$

dynamics require ageostrophic motions

$$oldsymbol{u}_{\perp}^{AG}, p^{AG} \sim Ro \quad \Rightarrow \quad w \sim ARo$$

A = H/L

Geostrophy (diagnostic balance):

$$oldsymbol{u}_{\perp}^G =
abla^{\perp} p^G$$

$$\begin{split} D_t^{\perp} \boldsymbol{u}_{\perp}^G + \frac{1}{A} \boldsymbol{w} \partial_z \boldsymbol{u}_{\perp}^G + \frac{1}{Ro} \widehat{\boldsymbol{z}} \times \boldsymbol{u}_{\perp}^{AG} &= -\frac{1}{Ro} \nabla_{\perp} p^{AG} + \frac{1}{Re} \left(\nabla_{\perp}^2 + \frac{1}{A^2} \partial_{zz} \right) \boldsymbol{u}_{\perp}^G \\ D_t^{\perp} \boldsymbol{w} + \frac{1}{A} \boldsymbol{w} \partial_z \boldsymbol{w} &= -\frac{1}{ARo} \partial_z p^G + \frac{1}{Fr_L} \boldsymbol{b} + \frac{1}{Re} \left(\nabla_{\perp}^2 + \frac{1}{A^2} \partial_{zz} \right) \boldsymbol{w} \\ D_t^{\perp} \boldsymbol{b} + \frac{1}{A} \boldsymbol{w} \partial_z \boldsymbol{b} + \frac{1}{Fr_L} \boldsymbol{w} N^2(z) &= \frac{1}{Pe} \left(\nabla_{\perp}^2 + \frac{1}{A^2} \partial_{zz} \right) \boldsymbol{b} \end{split}$$

$$abla_{\perp} \cdot oldsymbol{u}_{\perp}^{AG} + rac{1}{A} \partial_{oldsymbol{z}} w = 0$$

dynamics require ageostrophic motions

$$oldsymbol{u}_{ot}^{AG}, p^{AG} \sim Ro \Rightarrow w \sim ARo$$

universal scaling in QG theory $A = H/L$

Geostrophy (diagnostic balance):

$$oldsymbol{u}_{ot}^G =
abla^{ot} p^G$$

$$D_t^{\perp} \boldsymbol{u}_{\perp}^G + Row \partial_z \boldsymbol{u}_{\perp}^G + \widehat{\boldsymbol{z}} imes \boldsymbol{u}_{\perp}^{AG} = -
abla_{\perp} p^{AG} + rac{1}{Re} \left(
abla_{\perp}^2 + rac{1}{A^2} \partial_{zz}
ight) \boldsymbol{u}_{\perp}^G$$

$$(ARo)^{2} \left(D_{t}^{\perp} w + Row \partial_{z} w \right) = - \partial_{z} p^{G} + \left[\frac{ARo}{Fr_{L}} \right] b + \frac{(ARo)^{2}}{Re} \left(\nabla_{\perp}^{2} + \frac{1}{A^{2}} \partial_{zz} \right) w$$

$$D_t^{\perp}b + Row\partial_z b + \left[\frac{ARo}{Fr_L}\right]wN^2(z) = \frac{1}{Pe}\left(\nabla_{\perp}^2 + \frac{1}{A^2}\partial_{zz}\right)b$$

$$abla_{\perp} \cdot oldsymbol{u}_{\perp}^{AG} + \partial_z w = 0$$

Rescale vertical motions

Geostrophy (diagnostic balance):

$$oldsymbol{u}_{ot}^G =
abla^{ot} p^G$$

$$D_t^{\perp} oldsymbol{u}_{\perp}^G + Row \partial_z oldsymbol{u}_{\perp}^G + \widehat{oldsymbol{z}} imes oldsymbol{u}_{\perp}^{AG} = -
abla_{\perp} p^{AG} + rac{1}{Re} \left(
abla_{\perp}^2 + rac{1}{A^2} \partial_{zz}
ight) oldsymbol{u}_{\perp}^G$$

$$(ARo)^2 \left(D_t^{\perp} w + Row \partial_z w \right) = - \partial_z p^G + \left[\frac{ARo}{Fr_L} \right] b + \frac{(ARo)^2}{Re} \left(\nabla_{\perp}^2 + \frac{1}{A^2} \partial_{zz} \right) w$$

$$D_t^{\perp}b + Row\partial_z b + \left[\frac{ARo}{Fr_L}\right]wN^2(z) = \frac{1}{Pe}\left(\nabla_{\perp}^2 + \frac{1}{A^2}\partial_{zz}\right)b$$

$$abla_{\perp} \cdot oldsymbol{u}_{\perp}^{AG} + \partial_z w = 0$$

Vertical advection is subdominant

Inclusion of buoyancy driving requires $Fr_L = ARo$ -- a measure of the stratification strength

Geostrophy (diagnostic balance):

$$oldsymbol{u}_{\perp}^G =
abla^{\perp} p^G$$

Closed Balanced Model

$$D_t^{\perp} oldsymbol{u}_{\perp}^G + \widehat{oldsymbol{z}} imes oldsymbol{u}_{\perp}^{AG} = -
abla_{\perp} p^{AG} + rac{1}{Re} \left(
abla_{\perp}^2 + rac{1}{A^2} \partial_{zz}
ight) oldsymbol{u}_{\perp}^G$$

$$(ARo)^2 D_t^{\perp} w = -\partial_z p^G + b + \frac{(ARo)^2}{Re} \left(\nabla_{\perp}^2 + \frac{1}{A^2} \partial_{zz}\right) w$$

$$D_t^{\perp}b + wN^2(z) = rac{1}{Pe}\left(
abla_{\perp}^2 + rac{1}{A^2}\partial_{zz}
ight)b$$

$$abla_{\perp} \cdot oldsymbol{u}_{\perp}^{AG} + \partial_z w = 0$$

Measure of stratification $Fr_L = ARo$

Fr governs whether the dynamics are hydrostatic or nonhydrostatic


$$QG \text{ Summary}$$

$$D_t^{\perp}\zeta - \partial_z w = \frac{1}{Re} \left(\nabla_{\perp}^2 + \frac{1}{A^2} \partial_{zz} \right) \zeta$$

$$(ARo)^2 D_t^{\perp} w = -\partial_z \psi + b + \frac{(ARo)^2}{Re} \left(\nabla_{\perp}^2 + \frac{1}{A^2} \partial_{zz} \right) w$$

$$D_t^{\perp} b + wN^2(z) = \frac{1}{Pe} \left(\nabla_{\perp}^2 + \frac{1}{A^2} \partial_{zz} \right) b$$

Julien et al JFM 2006

Stratification
$$Fr = ARo \ll 1$$
 $Fr \sim Ro$ $Fr \sim 1$ $Ro \ll 1$
 $w \sim (ARo)u$

$$A = \begin{array}{c|c} QG & Intermediate \\ \hline & & & \\ H/L <<1 & H/L = O(1) \\ Charney (1948) & Embid & Majda (1998) \end{array}$$

$$OG Summary$$

$$D_t^{\perp}\zeta - \partial_z w = \frac{1}{Re} \left(\nabla_{\perp}^2 + \frac{1}{A^2} \partial_{zz} \right) \zeta$$

$$(ARo)^2 D_t^{\perp} w = -\partial_z \psi + b + \frac{(ARo)^2}{Re} \left(\nabla_{\perp}^2 + \frac{1}{A^2} \partial_{zz} \right) w$$

$$D_t^{\perp} b + wN^2(z) = \frac{1}{Pe} \left(\nabla_{\perp}^2 + \frac{1}{A^2} \partial_{zz} \right) b$$

Julien et al JFM 2006

Stratification
$$Fr = ARo \ll 1$$
 $Fr \sim Ro$ $Fr \sim 1$ $Ro \ll 1$
 $w \sim (ARo)u$

$$A = \begin{bmatrix} H/L <<1 \\ H/L <<1 \\ Charney (1948) \end{bmatrix}$$

$$H/L = O(1)$$

$$Embid \& Majda (1998)$$

$$QG-H$$

$$D_t^{\perp}q = \left(\nabla_{\perp}^2 + \frac{1}{A^2}\partial_{zz}\right) \left[\frac{1}{Re}\zeta + \frac{1}{Pe}\partial_z\left(\frac{\partial_z\psi}{N^2(z)}\right)\right]$$

$$q = \left[\zeta + \partial_z\left(\frac{\partial_z\psi}{N^2(z)}\right)\right]$$

Conservation: Energy, Enstrophy dual cascade



QG-NH

$$\begin{split} D_t^{\perp} \zeta - \partial_z w &= \frac{1}{Re} \left(\nabla_{\perp}^2 + \frac{1}{A^2} \partial_{zz} \right) \zeta \\ (ARo)^2 D_t^{\perp} w &= -\partial_z \psi + b + \frac{(ARo)^2}{Re} \left(\nabla_{\perp}^2 + \frac{1}{A^2} \partial_{zz} \right) w \\ D_t^{\perp} b + w N^2(z) &= \frac{1}{Pe} \left(\nabla_{\perp}^2 + \frac{1}{A^2} \partial_{zz} \right) b \end{split}$$

Julien et al JFM 2006

Conservation: Energy only, dual cascade still present. Tuesday, October 14, 14



QG Summary

$$\begin{split} D_t^{\perp} \zeta - \partial_z w &= \frac{1}{Re} \left(\nabla_{\perp}^2 + \frac{1}{A^2} \partial_{zz} \right) \zeta \\ (ARo)^2 D_t^{\perp} w &= -\partial_z \psi + b + \frac{(ARo)^2}{Re} \left(\nabla_{\perp}^2 + \frac{1}{A^2} \partial_{zz} \right) w \\ D_t^{\perp} b + w N^2(z) &= \frac{1}{Pe} \left(\nabla_{\perp}^2 + \frac{1}{A^2} \partial_{zz} \right) b \end{split}$$

Julien et al JFM 2006

Unified QG model capturing balanced dynamics irrespective of spatial anisotropy

QGE modeling capabilities

H: unforced decay

NH: Rotating Convection



RaE^{4/3} = 40, σ = 7 Sprague et al JFM '06 Groom et al PRL '10



QGE modeling capabilities



NH: Rotating Convection

Julien et al GAFD '12 Julien et al PRL '14 RaE^{4/3} = 100, σ = 1





Shallow Water Equations

Simplest setting to explore rotating dynamics



hydrostatic balance - barotropic dynamics

$$-\partial_z p - \rho_0 g = 0$$
$$p = P_{atm} + \rho_0 g(\eta + H - z)$$
$$h = \eta - b + H$$

$$egin{aligned} D_t^ot oldsymbol{u}_ot + f(y) \widehat{oldsymbol{z}} imes oldsymbol{u}_ot = -g
abla_ot \eta \ \partial_t \eta +
abla_ot \cdot (holdsymbol{u}_ot) = 0 \end{aligned}$$

$$f(y) = f_0 + \beta y$$

= $2\Omega \left(\sin \vartheta_0 + \frac{\cos \vartheta_0}{R_e} y \right)$

Vertically integrated continuity equation

Potential vorticity q is conserved

$$D_t q = 0, \qquad q = \left(\frac{\zeta + f}{h}\right), \quad \zeta = \widehat{\boldsymbol{z}} \cdot \nabla \times \boldsymbol{u}_\perp$$

Shallow Water Equations

Simplest setting to explore rotating dynamics



hydrostatic balance - barotropic dynamics

$$-\partial_z p - \rho_0 g = 0$$
$$p = P_{atm} + \rho_0 g(\eta + H - z)$$
$$h = \eta - b + H$$

$$egin{aligned} D_t^ot oldsymbol{u}_ot + rac{1}{Ro} \widehat{f}(y) \widehat{oldsymbol{z}} imes oldsymbol{u}_ot = -rac{1}{Fr^2}
abla_ot \eta \ \partial_t \eta +
abla_ot \cdot (holdsymbol{u}_ot) = 0 \end{aligned}$$

$$\hat{f}(y) = \hat{f}_0 + Roeta y$$
 $Ro = rac{U}{f_0 L} \quad Fr = rac{U}{\sqrt{gH}}$

Vertically integrated continuity equation

Potential vorticity q is conserved

$$D_t q = 0, \qquad q = \left(\frac{\zeta + f}{h}\right), \quad \zeta = \widehat{\boldsymbol{z}} \cdot \nabla \times \boldsymbol{u}_\perp$$

Shallow water dispersion relations



Wavenumber k

Plane wave solutions:
$$\eta \propto e^{i(k_{\perp} \cdot x_{\perp} - \omega t)}$$
 $\eta \propto e^{-\frac{y}{L_d}} e^{i(k_x x - \omega t)}$, $L_d = \sqrt{gH}/f_0$
 $\omega_{IGW}^2 = f_0^2 + (gH)k_{\perp}^2$ $\omega_{KW} = -\beta k_x/k_{\perp}^2$ $\omega_{KW} = (gH)k_x$

boundary wave



Equatorial wave solutions:

$$\eta \propto H_n \left(\frac{y}{L_d}\right) e^{-\frac{y^2}{2L_d}} e^{i(k_x x - \omega t)}, \quad L_d = \left(\frac{gH}{\beta^2}\right)^{1/4}$$





Forced shallow water on sphere (Scott, Polvani JAS 2007)



vorticity

$$L_D \sim \frac{\sqrt{gH}}{f}$$

 $L_{Rh} = \sqrt{U/\beta(1-\alpha)}, \ \alpha = U/\beta L_D^2$

- Rhines mechanism operating on sphere
 - ~ complex int'n waves & jets
 - dependent of deformation radius which increases towards equator
 - ∼ strong mixing btw prograde jets
- High latitude jets increasingly undular
 - \sim no jets for $\alpha > 1$, eddies
 - ✓ Jupiter, Saturn $L_D/a \sim 0.0.25$ SWE ⇒ deeper atmosphere
- Equatorial superrotation depends on $|L_D/a|$ ~ deep convection vs SW theory?

Forced shallow water on sphere (Scott, Polvani JAS 2007)



vorticity

$$L_D \sim rac{\sqrt{gH}}{f}$$

 $L_{Rh} = \sqrt{U/eta(1-lpha)}, \ lpha = U/eta L_D^2$

- Rhines mechanism operating on sphere
 - ~ complex int'n waves & jets
 - dependent of deformation radius which increases towards equator
 - ∼ strong mixing btw prograde jets
- High latitude jets increasingly undular
 - \sim no jets for $\alpha > 1$, eddies
 - ✓ Jupiter, Saturn $L_D/a \sim 0.0.25$ SWE ⇒ deeper atmosphere
- Equatorial superrotation depends on $|L_D/a|$ ~ deep convection vs SW theory?

- Dynamics captured by NSE for GAFD systems
 - \sim Theoretically too rich without idealized investigations
 - ~ Computationally always unresolved physics
- Reductions of NSE
 - reduced/Balanced models isolate appropriate physics and have computational advantages + theoretical insights
 - large scale or small scale phenomena not captured, thus absence of turbulent couplings potentially reduce the models fidelity.
- Open question: strategies of how to proceed!

Resolution of Ocean Component of Coupled IPCC models



Direct Numerical Simulations not possible for several centuries!

Parameterization of unresolved scales: $S_j = \overline{u}_j \overline{\phi}_j - \overline{u_j \phi} \equiv \overline{u'_j \phi'}, \quad \phi = \overline{\phi} + \phi' \dots$

- Phenomenological approach guided by
 - \sim physical intuition
 - ∼ observations
 - \sim idealized models and simulation studies
- Some examples
 - ~ Atmosphere Cloud resolving models (Grabowski, Wu JAS 1998)
 - Ocean mixing GM (Gent-McWilliams) parameterization favoring isopynical mixing (GM JPO 1990, Bachman, Fox-Kemper Ocean Modeling 2013)
- Astrophysical and Planetary Sciences
 - \sim issue of unresolved scales typically not addressed
 - ~ limitations placed on accessing extreme parameter regimes

Multiscale asymptotic approach: $\partial_t = \partial_\tau + \epsilon \partial_T$, $\nabla = \nabla_f + \epsilon \nabla_s$

- Reduction from master equations
 - ~ underlying physics carried along thru asymptotics
 - \sim coupling between scales occurs naturally
 - computational challenge still significant and naturally leads about parameterizations of filtered (fine grid) scales
 - ~ modal vs stochastic approaches (Grooms & Majda, PNAS 2013)
- Some examples
 - \sim Tropics convectively coupled waves (many classes of coupled
 - balanced models) (review Khouider, Majda & Stechmann Nonlinearity 2013)
 - ~ Nonhydrostatic ocean mixing (Malecha, Chini, J JCP 2013)

Multiscale computational approaches - development of efficient massively llel algorithms

- Non-uniform grid, AMR
- Multiscale numerical strategies Ilel in time methods (Haut & Wingate SIAM 2014)

Mathematics of Turbulence

Workshop III: Geophysical and Astrophysical Turbulence

October 27 - 31, 2014

Organizing Committee | Scientific Overview | Speaker List

Application/Registration | Contact Us

Organizing Committee

Jon Aurnou (University of California, Los Angeles (UCLA)) Oliver Bühler (New York University, Courant Institute of Mathematical Science) Baylor Fox-Kemper (Brown University) Pascale Garaud (University of California, Santa Cruz (UC Santa Cruz)) Keith Julien (University of Colorado, Boulder)

Back to Top

Scientific Overview

This workshop will cover a number of selected topics that are common to Oceanography, Planetary Geophysics, Atmospheric Dynamics and Astrophysics including turbulent convection, turbulence induced by baroclinic instabilities, shear turbulence (both stratified and unstratified), double-diffusive convection, and wave-induced turbulence. In all these cases geophysicists and astrophysicists strive to model the effects of the specific type of turbulence considered on heat, compositional and momentum transport. In many instances progress on common problems has been made in parallel without much interaction between the scientific communities.

This workshop will bring together scientists from different backgrounds to share their most recent results, attempting to bridge the subject-gap, and foster fruitful collaborations.

This workshop will include a poster session: a request for posters will be sent to registered participants in Tuesday, October 14, 14