

# Automating Science using Robot Scientists

Ross D. King,

Alan Turing Institute, Chalmers University, [rdking@turing.ac.uk](mailto:rdking@turing.ac.uk)



# Scientific Discovery

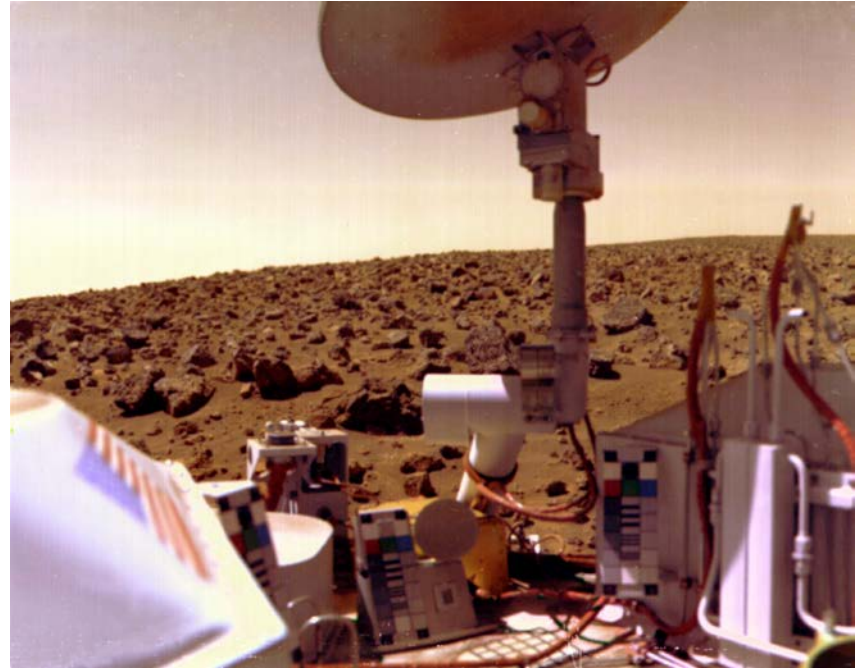
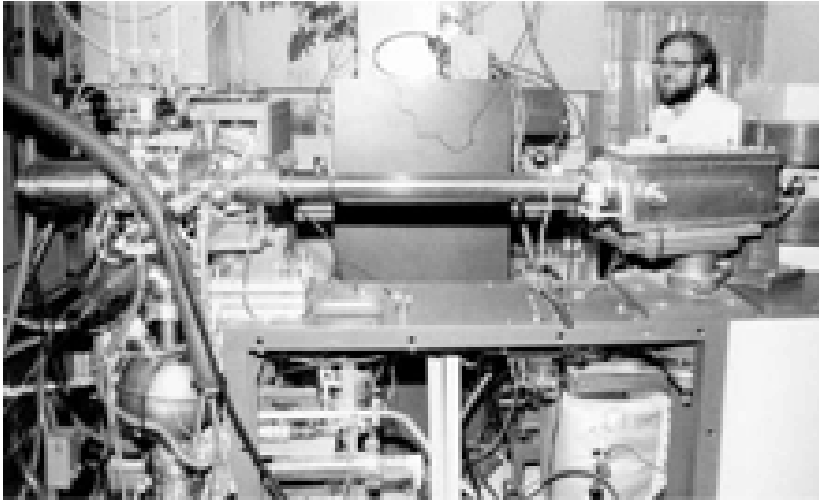
# AI Systems have Superhuman Scientific Powers

- n Flawlessly remember vast numbers of facts
- n Flawless logical reasoning
- n Near optimal probabilistic reasoning
- n Learn from vast amounts of data
- n Extract information from millions of scientific papers.
- n Etc.

# Science as an AI Task

- n Scientific problems are abstract, but involve the real-world.
- n Scientific problems are restricted in scope – no need to know about “Cabbages and Kings”.
- n Nature is honest.
- n Nature is a worthy object of our study.
- n The generation of scientific knowledge is a public good.

# Meta-Dendral



Analysis of mass-spectrometry data.

Joshua Lederburg, Ed. Feigenbaum, Bruce Buchanan,  
Karl Djerassi, *et al.* 1960-70s.

# Bacon



## **Kepler's 3 Laws of Planetary Motion**

- 1 ) Each planet orbits the sun in an elliptical path with the sun at one focus**
- 2 ) The radius vector ( from sun to planet ) sweeps out equal areas in equal time intervals**
- 3 ) The square of the period is proportional to the cube of the semi-major axis of the orbit**

$$\text{i.e. } T^2 = k a^3 \quad \text{for some constant } k$$

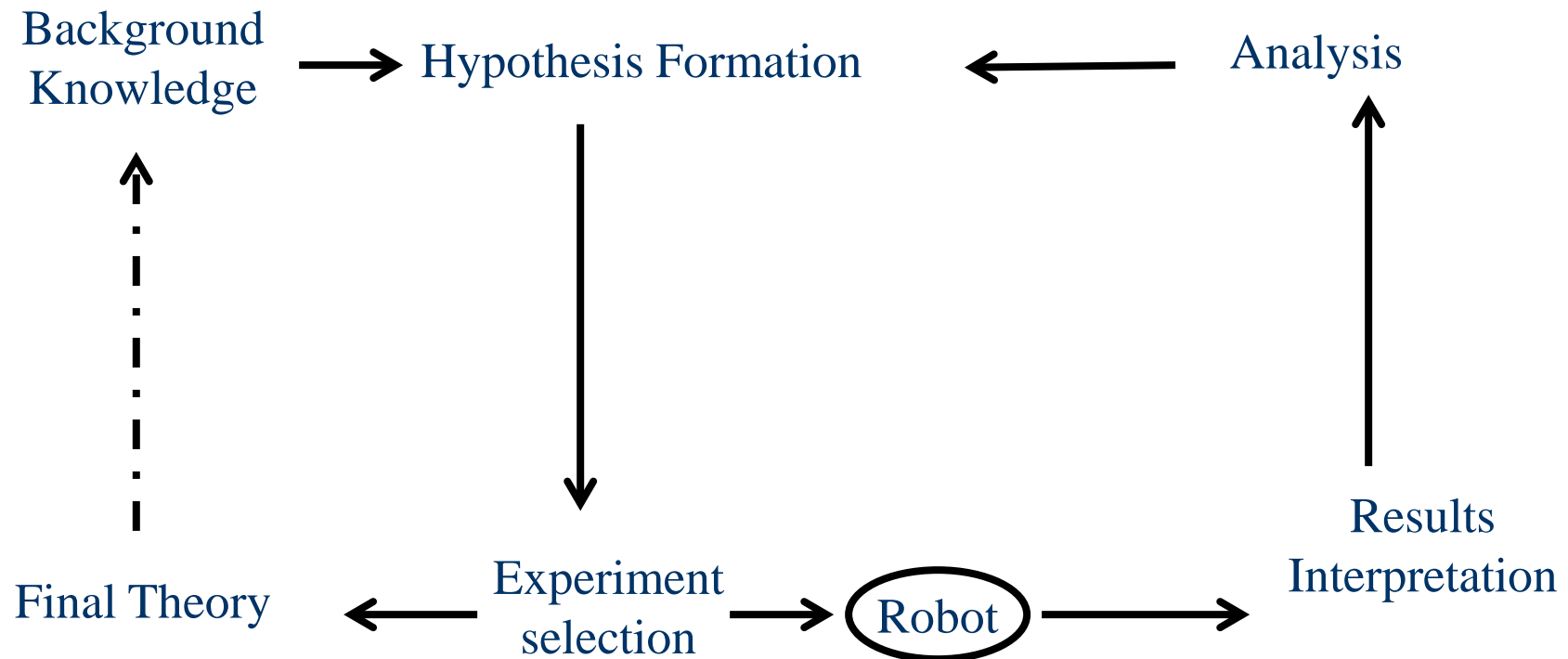
**Figure 11.1**

Rediscovering physics and chemistry. Langley, Bradshaw, Simon (1979).

# Robot Scientists

# The Concept of a Robot Scientist

Computer system capable of originating its own experiments, physically executing them, interpreting the results, and then repeating the cycle.

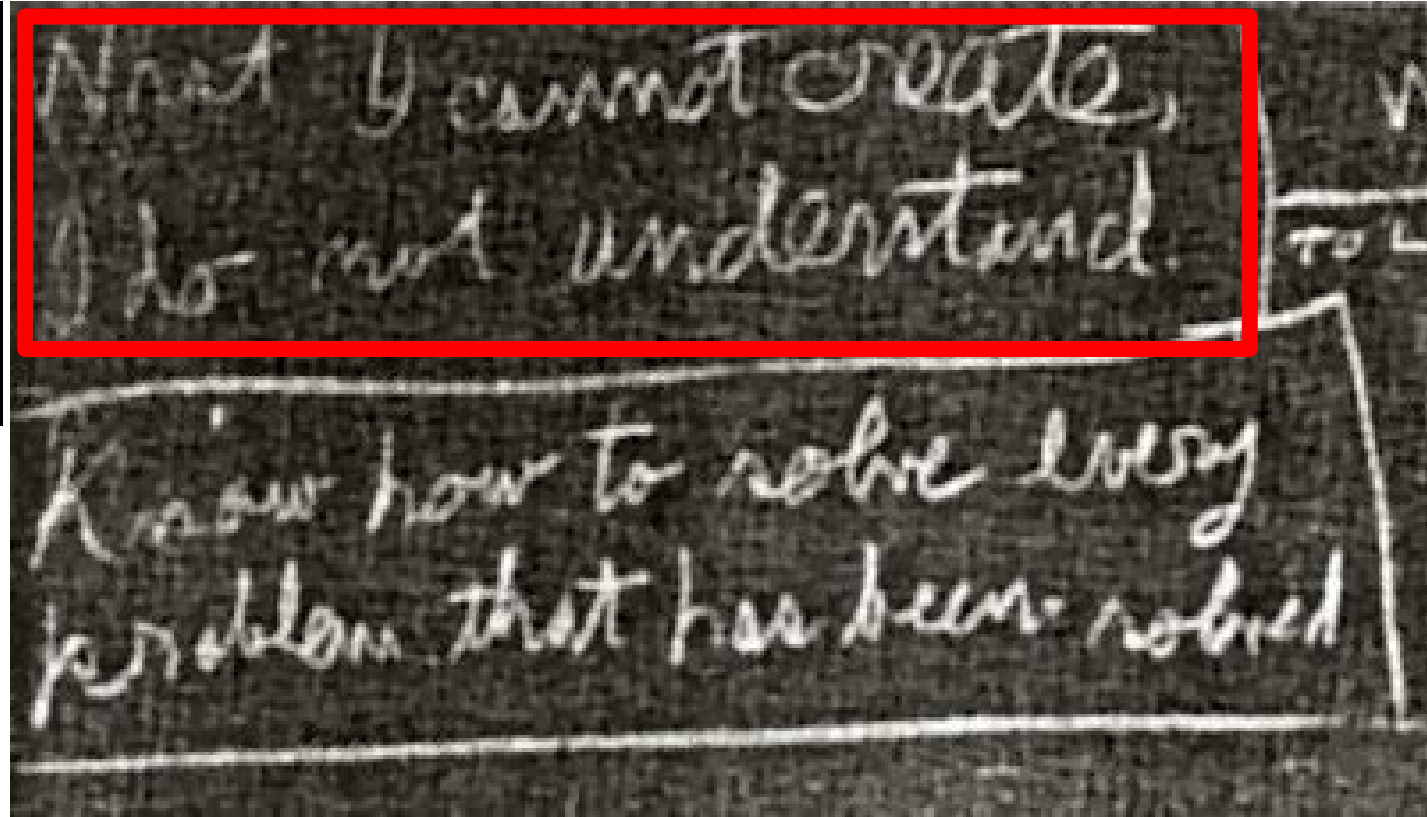
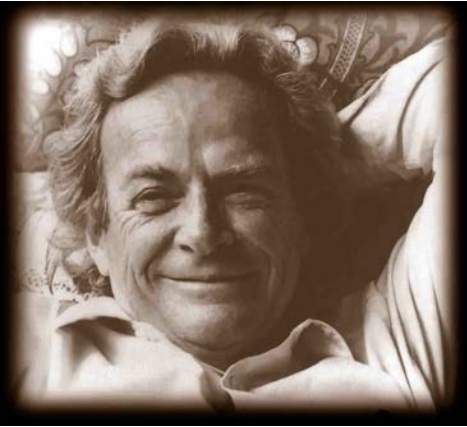




# Motivation: Philosophical

- n What is Science?
- n The question whether it is possible to automate scientific discovery seems to me central to understanding science.
- n There is a strong philosophical position which holds that we do not fully understand a phenomenon unless we can make a machine which reproduces it.

# Richard Feynman's Blackboard



“What I cannot create, I do not understand”

# Motivation: Technological

- n Robot Scientists have the potential to increase the productivity of science. They can work cheaper, faster, more accurately, and longer than humans. They can also be easily multiplied.
  - *Enabling the high-throughput testing of hypotheses.*
- n Robot Scientists have the potential to improve the quality of science.
  - *by enabling the description of experiments in greater detail and semantic clarity.*

# Robot Scientist Timeline

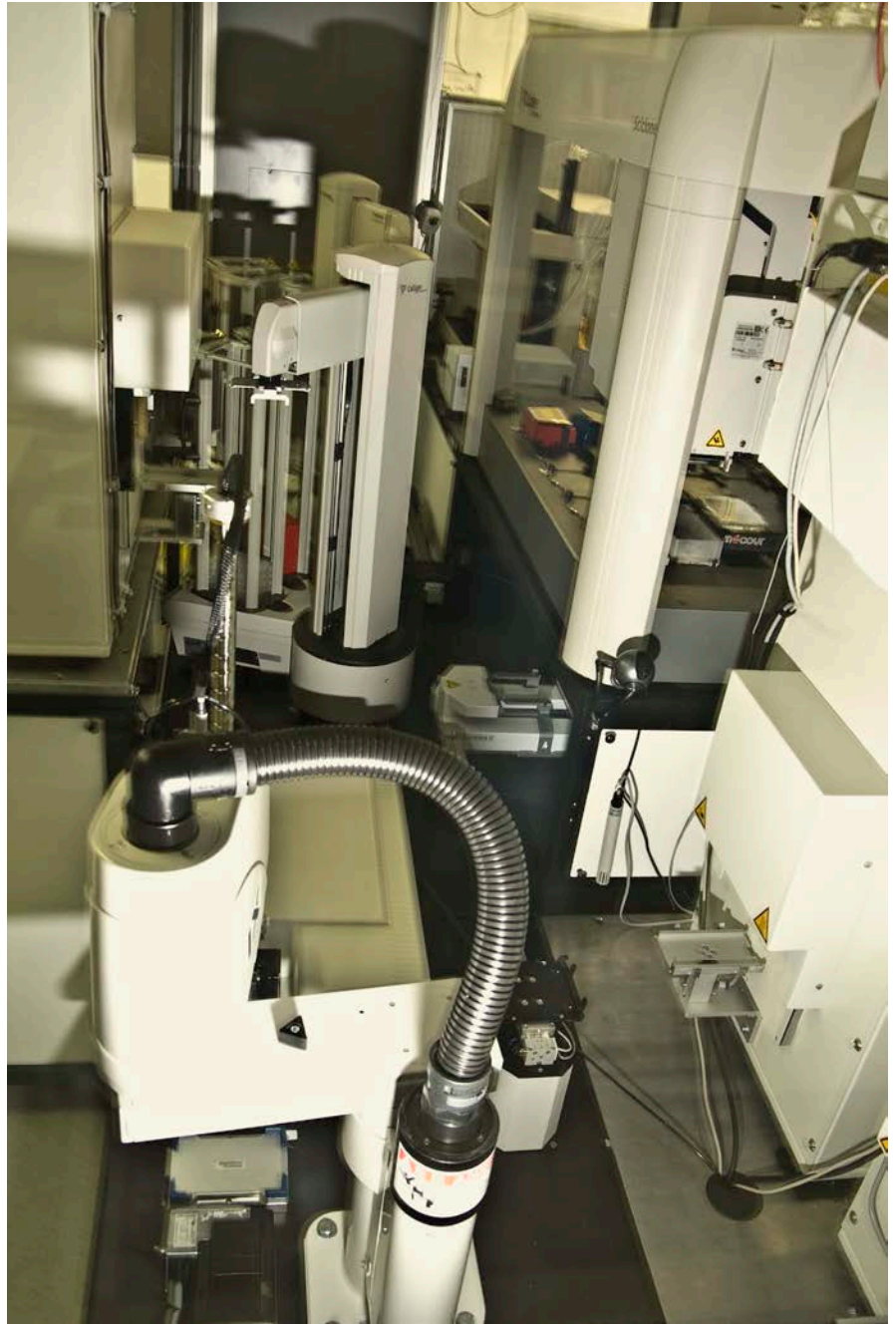
- n 1999-2004 Initial Robot Scientist Project
  - Limited Hardware: Collaboration with Douglas Kell (Aber Biology), Steve Oliver (Manchester), Stephen Muggleton (Imperial)

**King et al. (2004) *Nature*, 427, 247-252**
  
- n 2004-2011 Adam – Yeast Functional Genomics
  - Sophisticated Laboratory Automation: Collaboration with Steve Oliver (Cambridge).

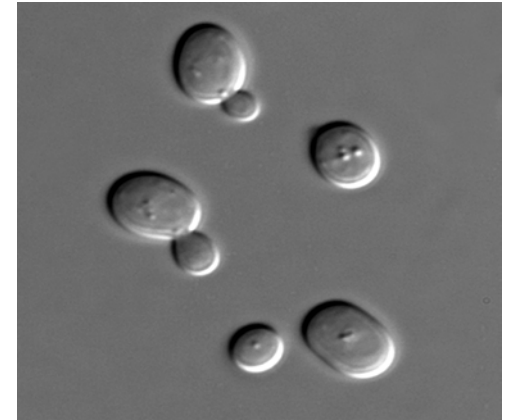
**King et al. (2009) *Science*, 324, 85-89**
  
- n 2008-2015 Eve – Drug Design for Tropical Diseases
  - Sophisticated Laboratory Automation: Collaboration with Steve Oliver (Cambridge)

**Williams et al. (2015) *Royal Society Interface*, DOI 10.1098/rsif.2014.1289**
  
- n 2015-2019 Eve – Systems Biology
  - Coutant et al. (2019) *Proc. Nat. Acad. Sci. U.S.A.* 201900548**

Adam



# The Application Domain

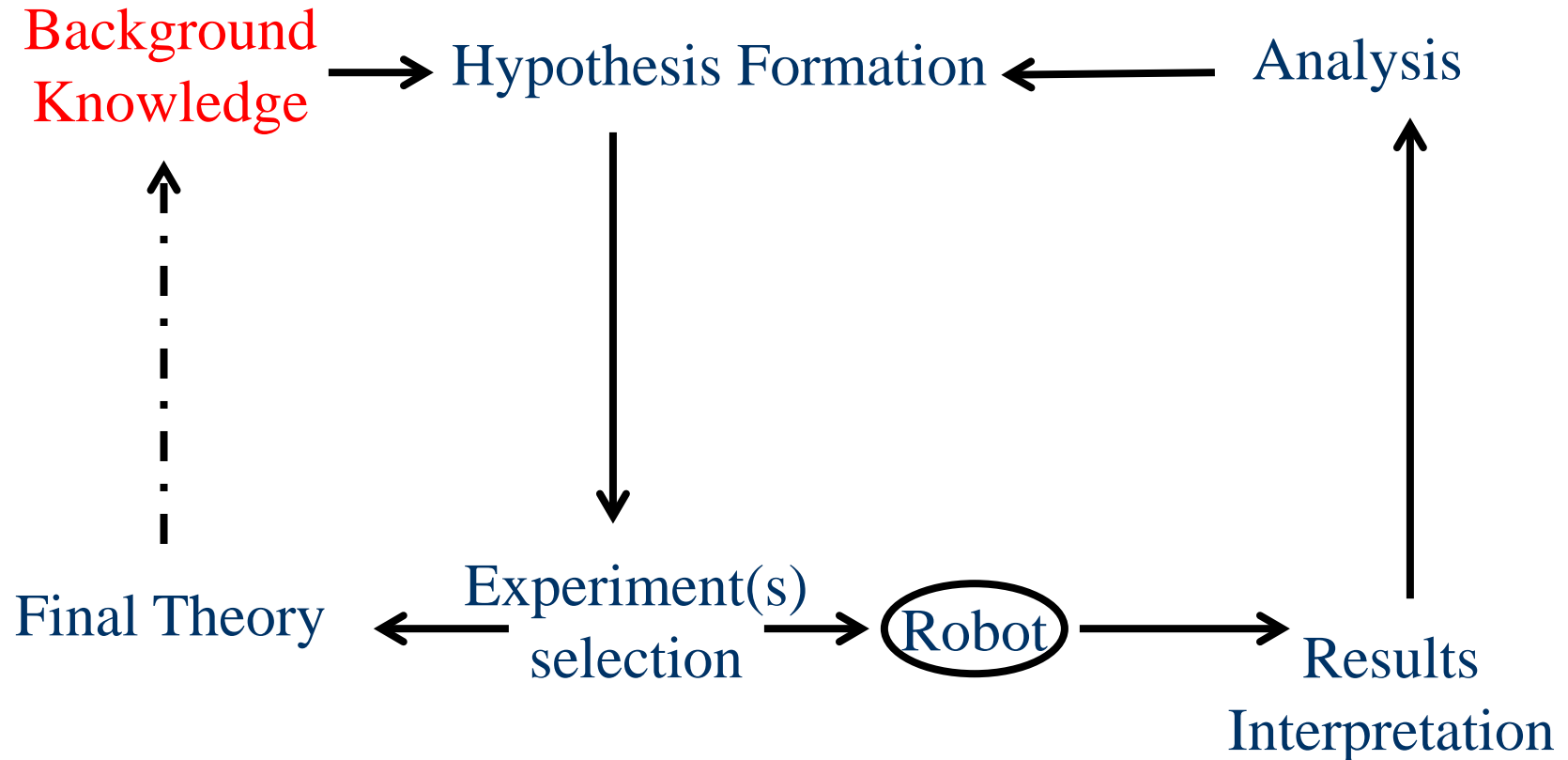


- n Functional genomics
- n In yeast (*S. cerevisiae*) ~20% of the 6,000 genes still have no known function.
- n EUROFAN 2 made all viable single deletant strains.
- n Task to determine the “function” of a gene by growth experiments.

# Formalising the Problem

- n Use logic programming to represent background knowledge: metabolism modelled as a directed labeled hyper-graph.
- n Use abduction to infer new hypotheses:
  - Abductive logic programming.
  - Techniques from Bioinformatics.
- n Use active learning to decide efficient experiments: cost of compounds and time.
- n Use machine learning to decide meaning of experimental results.

# The Experimental Cycle

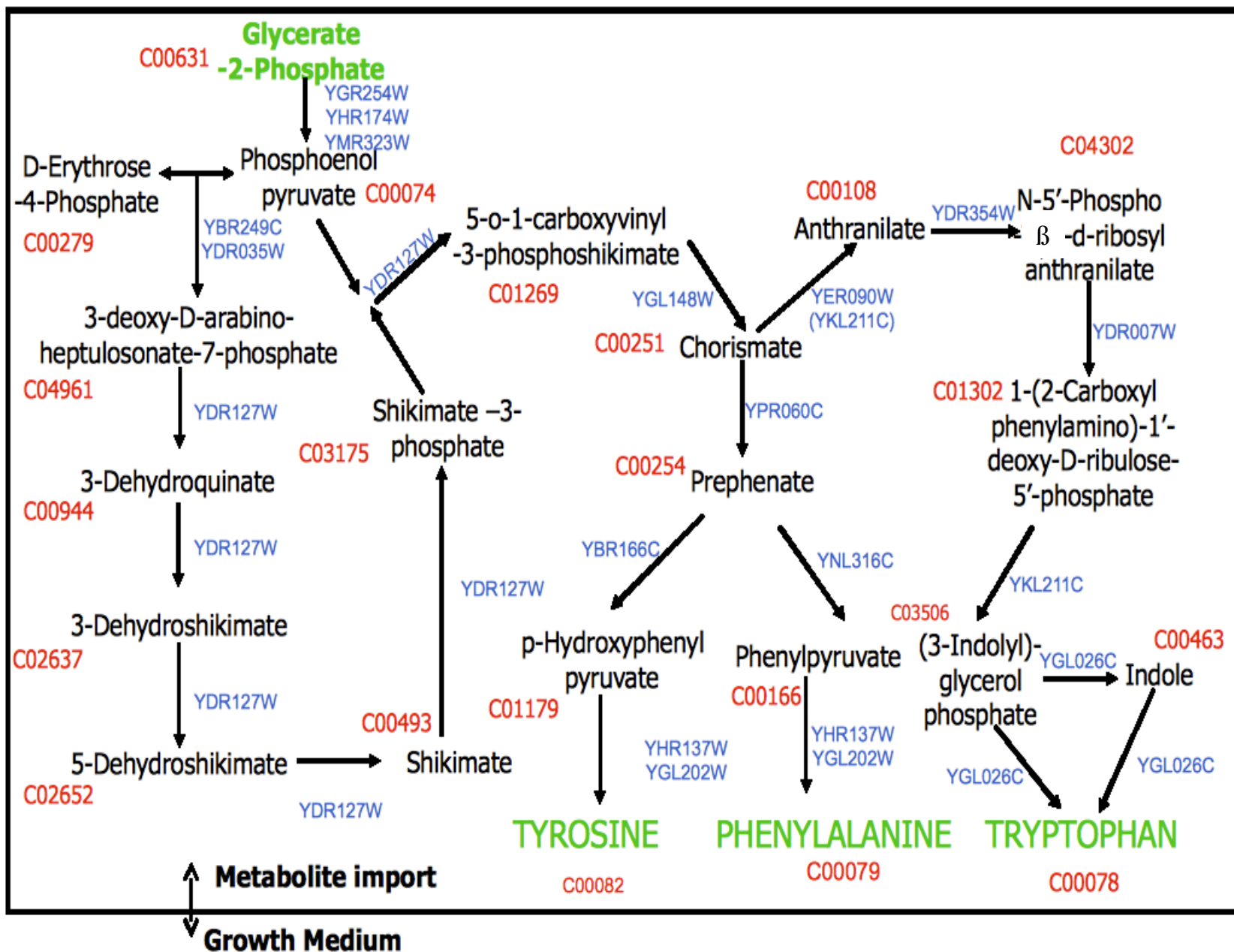




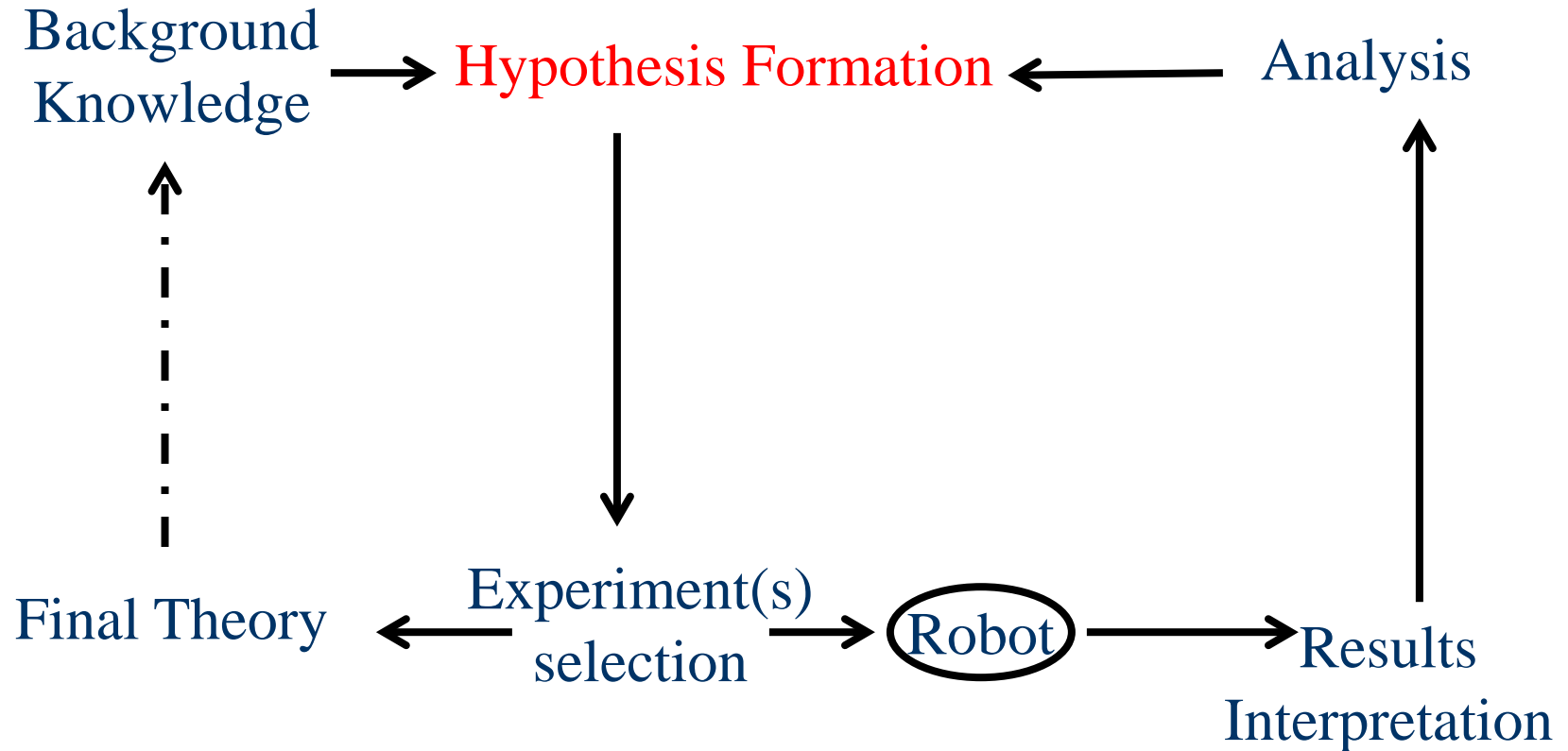
# Logical Cell Model

- n We developed a logical formalism for modelling metabolic pathways (encoded in logic programs). This is essentially a directed labeled hyper-graph: with metabolites as nodes and enzymes as arcs.
- n If a path can be found from cell inputs (metabolites in the growth medium) to all the cell outputs (essential compounds) then the cell can grow.

# Phenylalanine, Tyrosine, and Tryptophan Pathways for *S. cerevisiae*



# The Experimental Cycle



# Inferring Hypotheses

- n Science is based on the hypothetico-deductive method.
- n In the philosophy of science. It has often been argued that only humans can make the “leaps of imagination” necessary to form hypotheses.
- n In biology most hypothesis generation is abductive, not inductive.
- n Adam used abductive inference to infer missing arcs/labels in its metabolic graph - hypotheses. With these missing nodes Adam could then deductively infer (explain) the observed experimental results.

# Types of Logical Inference

## Deduction

Rule: All swans are white.

Fact: Daffy is a swan.

∴ Daffy is white.

## Abduction

Rule: All swans are white.

Fact: Daffy is white.

∴ Daffy is a swan.

## Induction

Fact: Daffy is a swan and white.

Fact: Tweety is a swan and white

∴ All swans are white.

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∴ Daffy is white.

## Abduction

Rule: All swans are white.

Fact: Daffy is white.

∴ Daffy is a swan.      **Daffy is a duck.**

## Induction

Fact: Daffy is a swan and white.

Fact: Tweety is a swan and white

∴ All swans are white.

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Fact: Daffy is a swan and white.

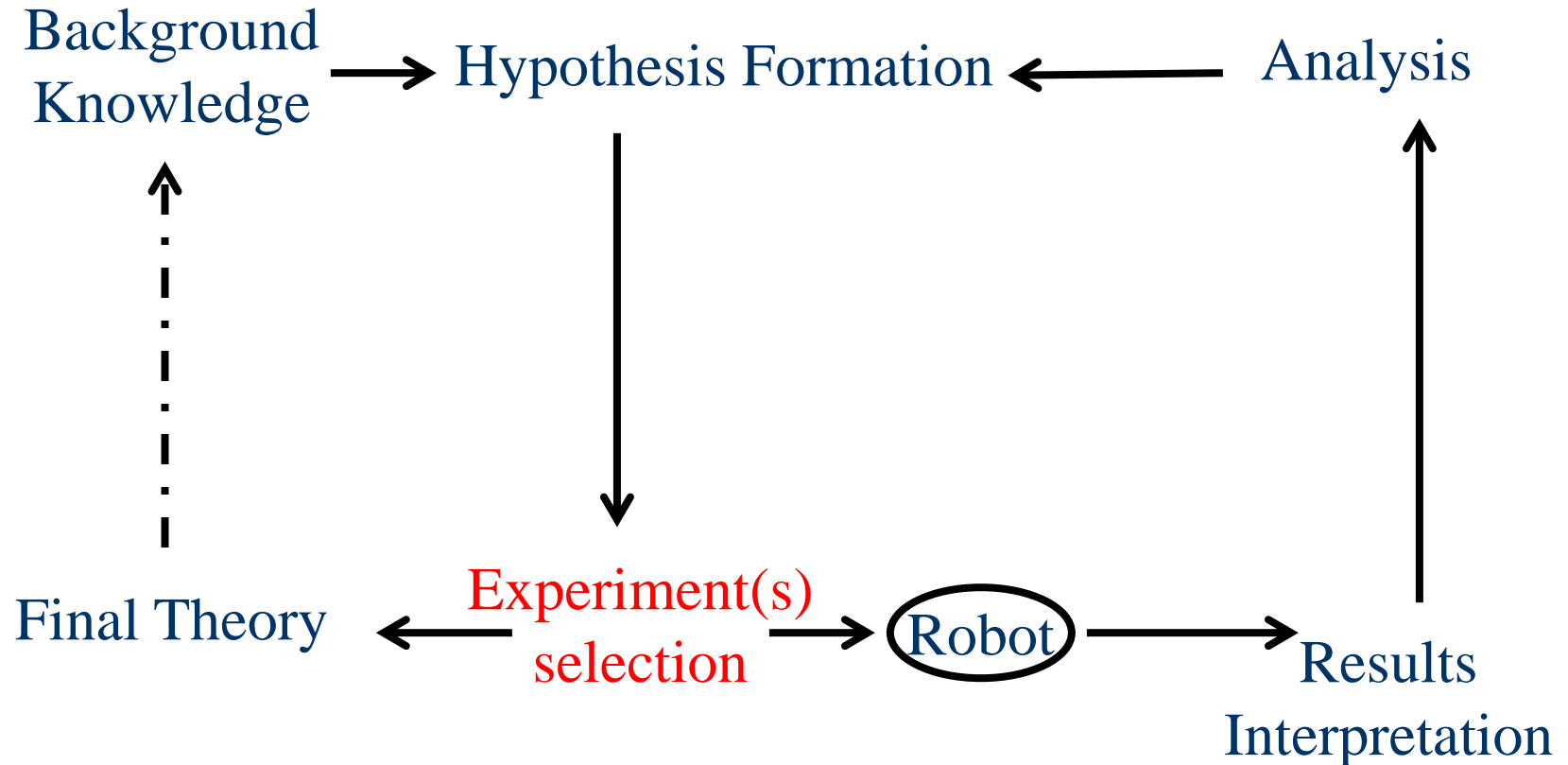
Fact: Tweety is a swan and white

∴ All swans are white.

**Bruce is a black swan.**



# The Experimental Cycle



# Inferring Experiments

Given a set of hypotheses we wish to infer an experiment that will efficiently discriminate between them

Assume:

- n Every experiment has an associated cost.
- n Each hypothesis has a probability of being correct.

The task:

- n To choose a series of experiments which minimise the expected cost of eliminating all but one hypothesis.

# Active Learning

- n In the 1972 Fedorov (Theory of optimal experiments) showed that this problem is in general intractable (NP complete).
- n However, it can be shown that the problem is the same as finding an optimal decision tree; and it is known that this problem can be solved “nearly” optimally in polynomial time.
- n We have shown that this strategy can outperform (get answer *faster* and *cheaper*) than simply choosing the cheapest experiment. Also better than humans on test problem.

# Recurrence Formula

$EC(H, T)$  denote the minimum expected cost of experimentation given the set of candidate hypotheses  $H$  and the set of candidate trials  $T$ :

$$EC(\emptyset, T) = 0$$

$$EC(\{h\}, T) = 0$$

$$EC(H, T) \approx \min_{t \in T} [C_t + p(t)(\text{mean}_{t' \in (T-t)} C_{t'}) J_{H[t]} + (1 - p(t)) \text{mean}_{t' \in (T-t)} C_{t'} J_{H[\bar{t}]}]$$

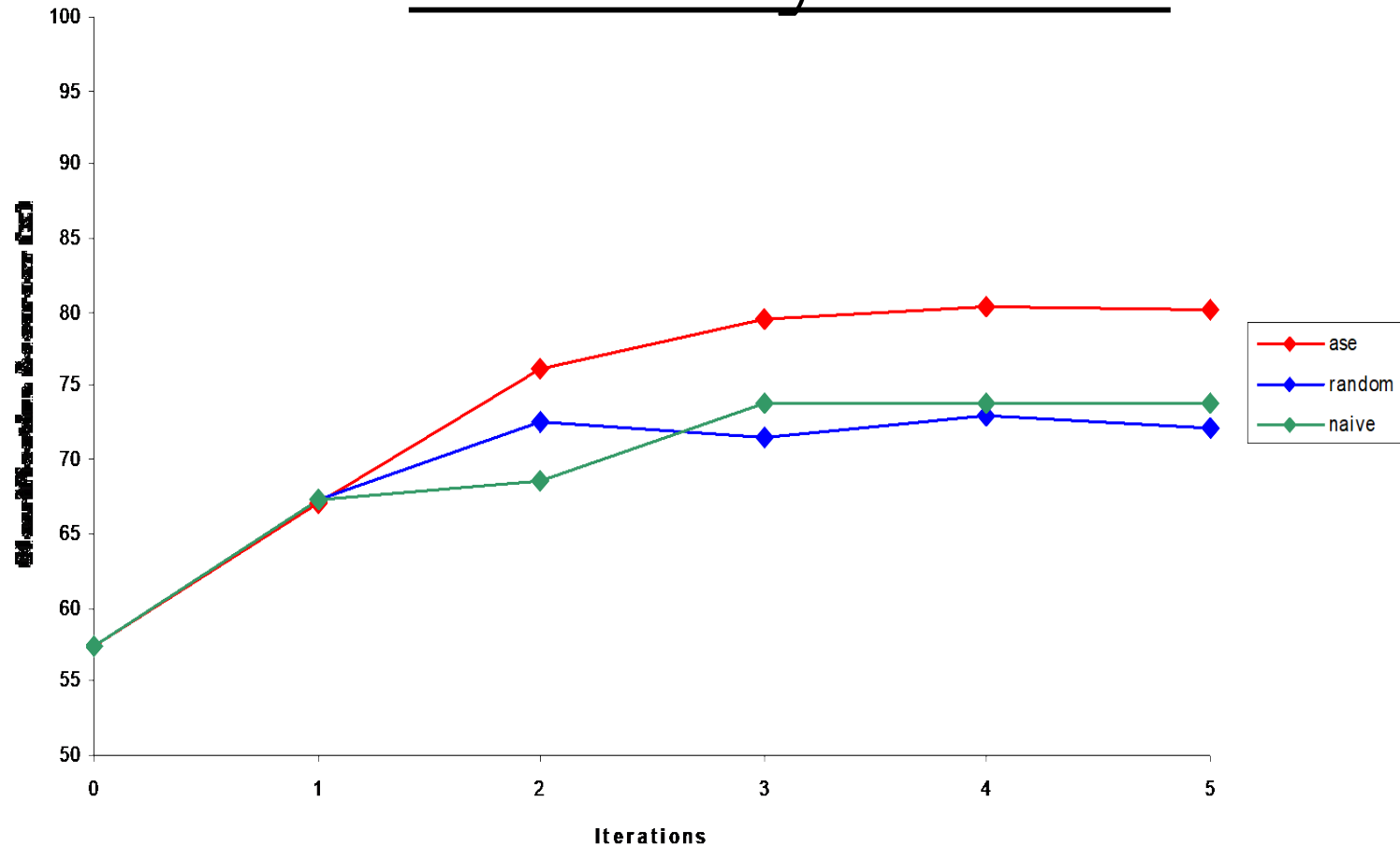
$$J_H = -\sum_{h \in H} p(h) [\log_2(p(h))]$$

$C_t$  is the monetary price of the trial  $t$

$p(t)$  is the probability that the outcome of the trial  $t$  is positive

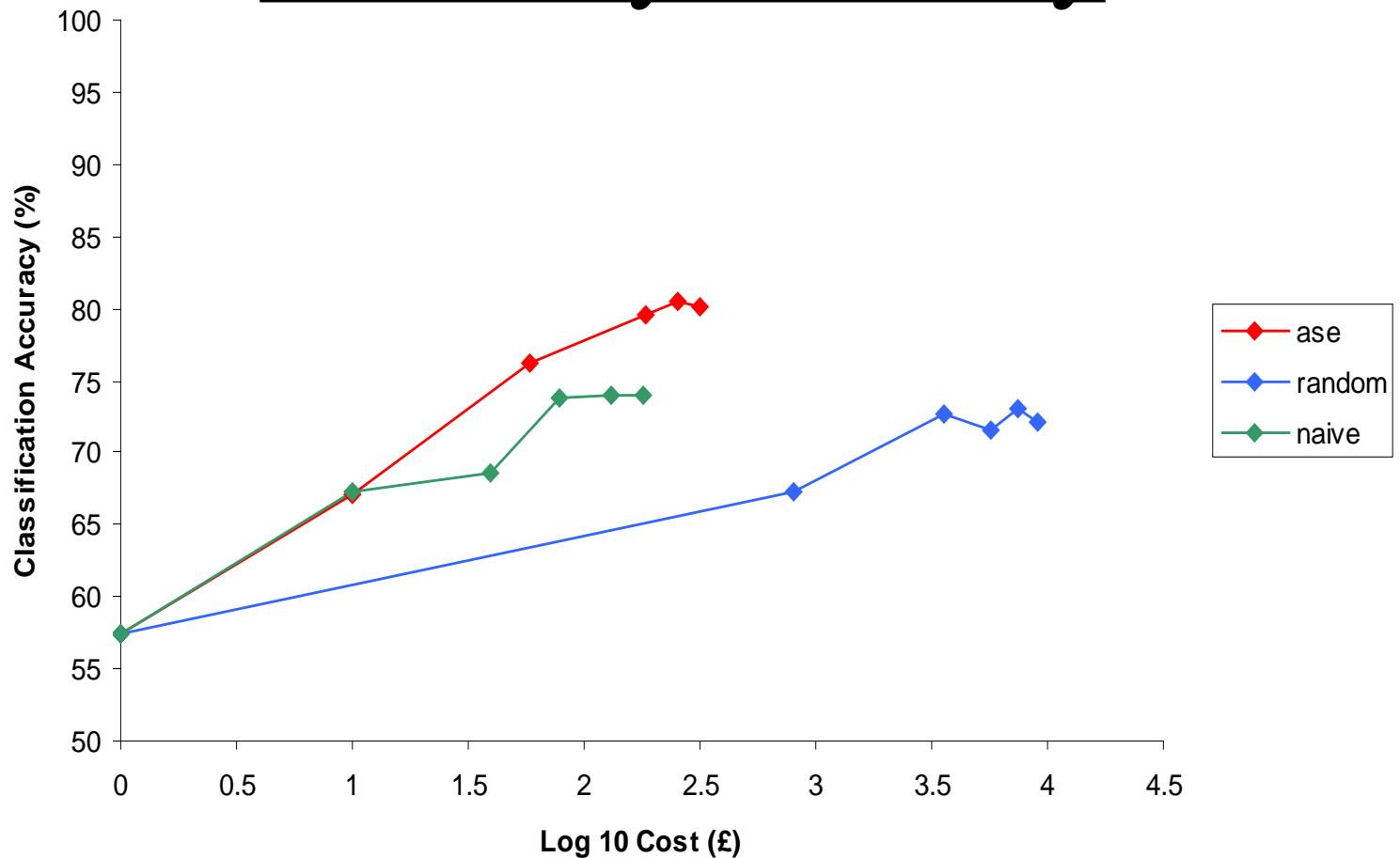
$p(t)$  can be computed as the sum of the probabilities of the hypotheses ( $h$ ) which are consistent with a positive outcome of  $t$

# Accuracy v Time



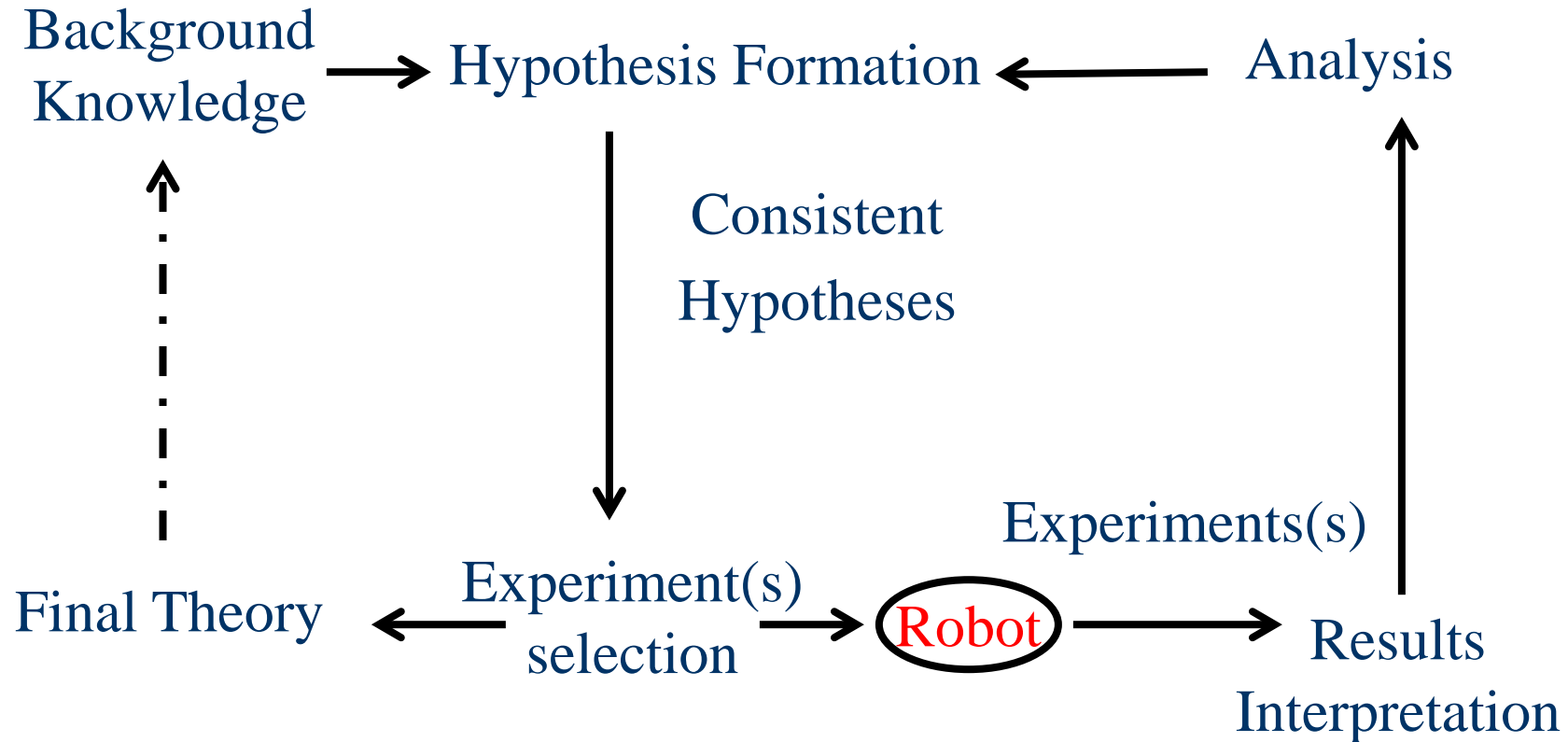
At the end of the 5th iteration: ASE 80.1%, Naïve 74.0%, Random 72.2%. ASE was significantly more accurate than either Naïve ( $p < 0.05$ ) or Random ( $p < 0.07$ ) using a paired t-test.

# Accuracy v Money

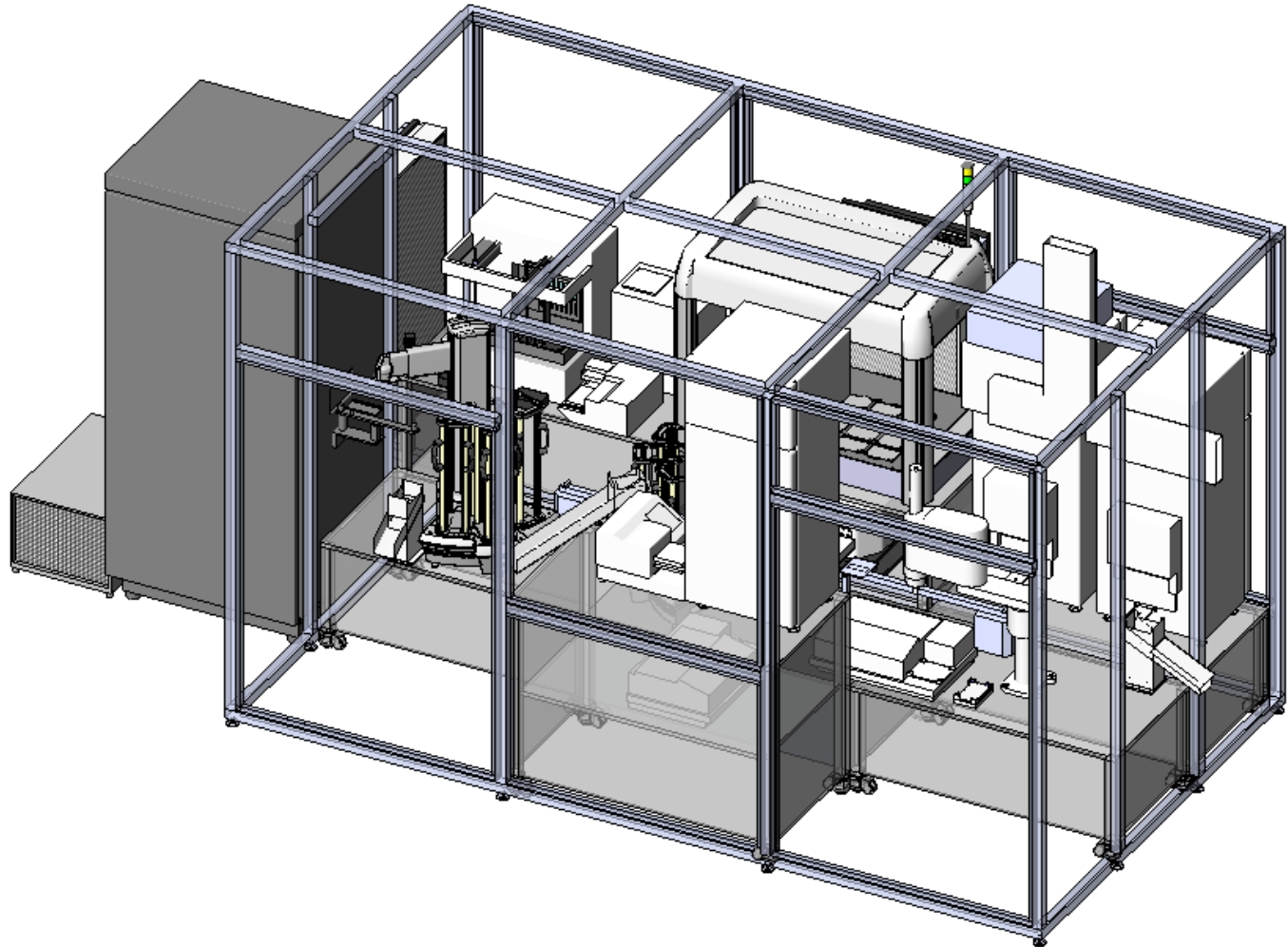


Given a spend of  $\leq \text{£}10^{2.26}$ , ASE 79.5%, Naïve 73.9%, Random 57.4%. ASE was significantly more accurate than either Naïve ( $p < 0.05$ ) or Random ( $p < 0.001$ ).

# The Experimental Cycle



# Diagram of Adam





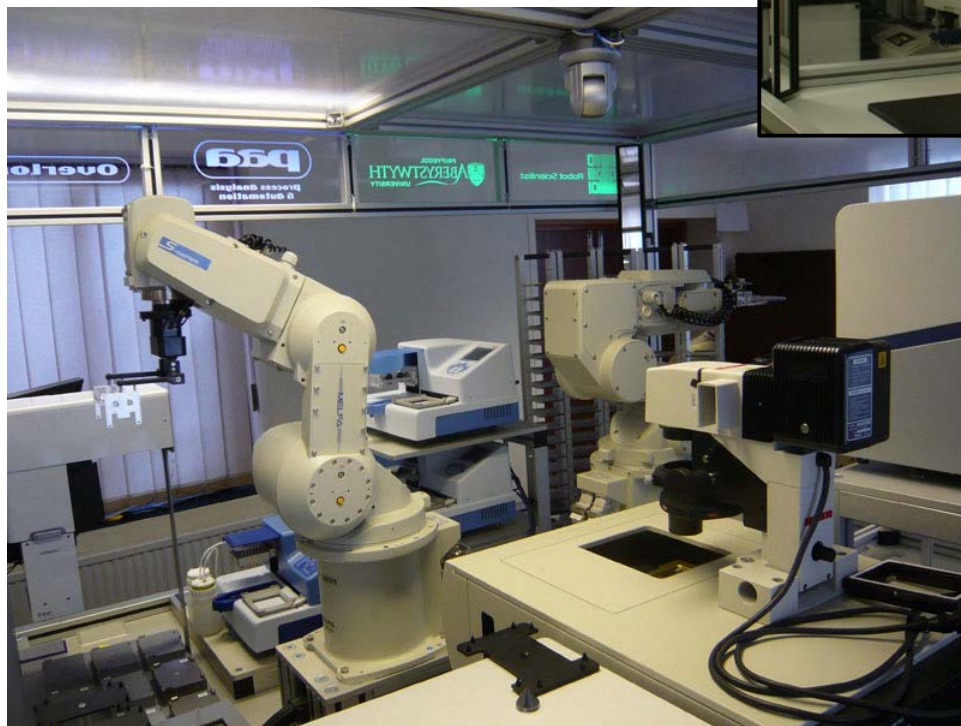
# Novel Science

- n Adam generated and confirmed novel functional-genomics hypotheses concerning the identify of genes encoding enzymes catalysing orphan reactions in the metabolic network of the yeast *S. cerevisiae*.
- n Adam's conclusions have been manually verified using bioinformatic and biochemical evidence.
- n Adam was the first machine to autonomously discover novel scientific knowledge: hypothesise, and experimentally confirm.

# Novel Scientific Knowledge

Orphan Enzyme	Hypothesised Gene	Prob.	Acc.	No.	Existing Annotation	Dry	Wet	
1	glucosamine-6-phosphate deaminase (3.5.99.6)	YHR163W (SOL3)	<10 <sup>-4</sup>	97	8	'6-phosphogluconolactonase' ida	-	-
2	glutaminase (3.5.1.2)	YIL033C (BCY1)	<10 <sup>-4</sup>	92	11	'cAMP-dependent protein kinase inhibitor' ida	x ?	-
3	L-threonine 3-dehydrogenase (1.1.1.103)	YDL168W (SFA1)	<10 <sup>-4</sup>	83	6	'alcohol dehydrogenase' ida	-	-
4	purine-nucleoside phosphorylase (2.4.2.1)	YLR209C (PNP1)	<10 <sup>-4</sup>	82	11	'purine-nucleoside phosphorylase' ida	✓	-
5	2-aminoadipate transaminase (2.6.1.39)	YGL202W (ARO8)	<10 <sup>-4</sup>	80	3	'aromatic-amino-acid transaminase' ida	✓	✓
6	5,10-methenyltetrahydrofolate synthetase (6.3.3.2)	YER183C (FAU1)	<10 <sup>-4</sup>	80	4	'5,10 formyltetrahydrofolate cyclo-ligase' ida	✓	-
7	glucosamine-6-phosphate deaminase (3.5.99.6)	YNR034W (SOL1)	<10 <sup>-4</sup>	79	2	'possible role in tRNA export'	-	-
8	pyridoxal kinase (2.7.1.35)	YPR121W (THI22)	<10 <sup>-4</sup>	78	1	'phosphomethylpyrimidine kinase' iss	-	-
9	mannitol-1-phosphate 5-dehydrogenase (1.1.1.17)	YNR073C	<10 <sup>-4</sup>	78	6	'putative mannitol dehydrogenase' iss	-	-
10	1-acylglycerol-3-phosphate O-acyltransferase (2.3.1.51)	YDL052C (SLC1)	0.0001	80	6	'1-acylglycerol-3-phosphate O-acyltransferase' ida	✓	-
11	glucosamine-6-phosphate deaminase (3.5.99.6)	YGR248W (SOL4)	0.0002	78	2	'6-phosphogluconolactonase' ida	-	-
12	maleylacetoacetate isomerase (5.2.1.2)	YLL060C (GTT2)	0.0003	76	3	'glutathione S-transferase' ida	-	-
13	serine O-acetyltransferase (2.3.1.30)	YJL218W	0.0005	78	2	'unknown function'	-	-
14	L-threonine 3-dehydrogenase (1.1.1.103)	YLR070C (XYL2)	0.0052	75	6	'xylitol dehydrogenase' ida	-	-
15	2-aminoadipate transaminase (2.6.1.39)	YJL060W (BNA3)	0.0084	73	3	'kynurenine aminotransferase' ida	-	✓
16	pyridoxal kinase (2.7.1.35)	YNR027W	0.0259	76	2	'involved in bud-site selection' iss	-	-
17	polyamine oxidase (1.5.3.11)	YMR020W (FMS1)	0.0289	78	4	'polyamine oxidase' ida	✓	-
18	2-aminoadipate transaminase (2.6.1.39)	YER152C	0.0332	74	3	'uncharacterized'	-	✓
19	L-aspartate oxidase (1.4.3.16)	YJL045W	0.1300	72	1	'succinate dehydrogenase isozyme' iss	-	-
20	purine-nucleoside phosphorylase (2.4.2.1)	YLR017W (MEU1)	0.1421	72	6	'methylthioadenosine phosphorylase' ida	✓	-

Eve

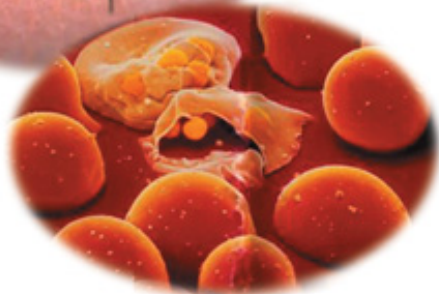


Drug Design

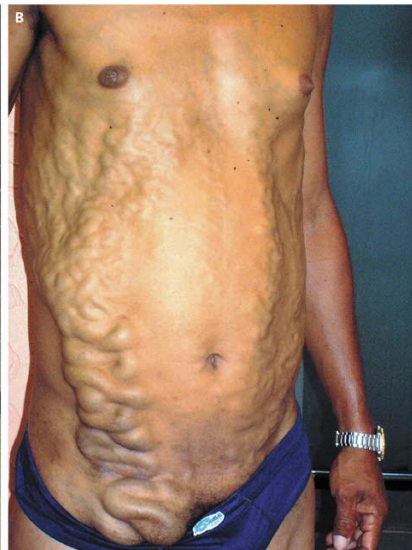
# The Application Domain



Malaria



Shistosomiasis



Leishmania

Chagas



# Why Tropical Diseases?

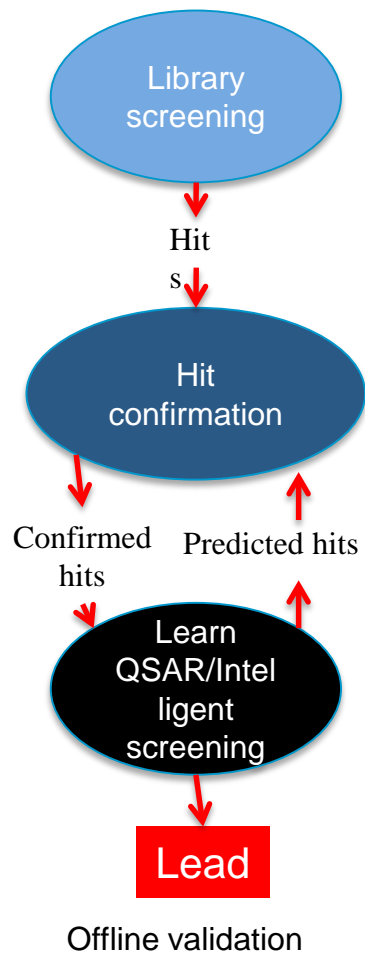
- n Millions of people die of these diseases, and hundreds of millions of people suffer infection.
- n It is clear how to cure these diseases – kill the parasites.
- n They are “neglected”, so avoid competition from the Pharmaceutical industry.



# Formalising the Problem

- n Use standard chemoinformatic methods (Boolean fingerprints) to represent background knowledge.
- n Uses induction (quantitative structure activity relationship – QSAR learning) to infer new hypotheses.
- n Use a combination of active learning and active learning to decide efficient experiments.

# Eve's Automation of Pipeline

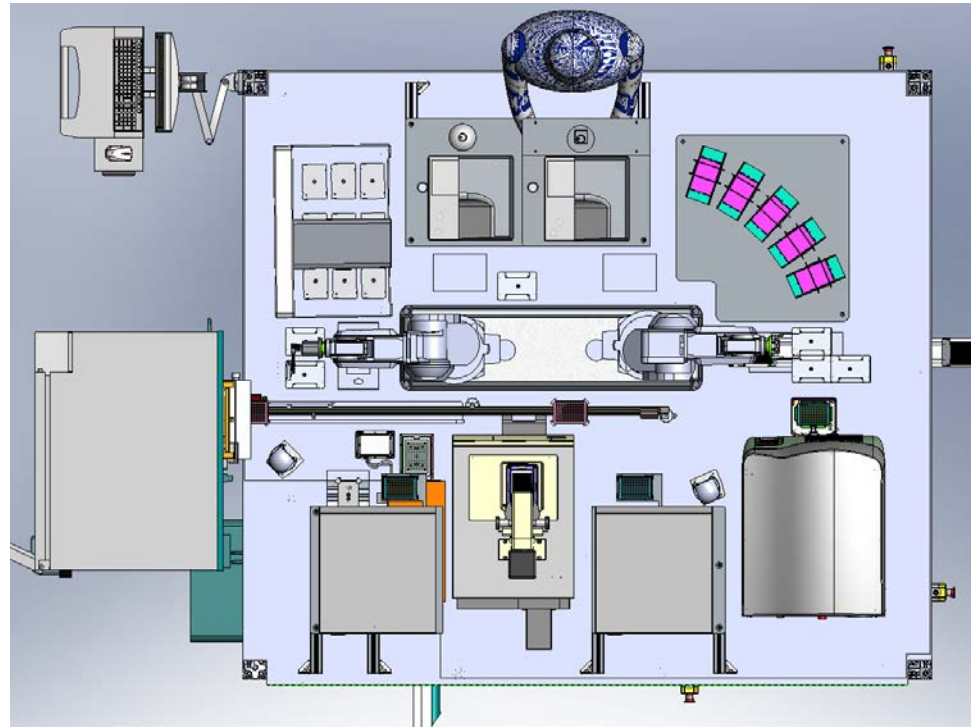


- Standard library screening is brute force:
- Eve uses intelligent screening
  
- In the standard “pipeline” the 3 processes are not integrated.
- In Eve automated and integrated.

# Eve's Hardware

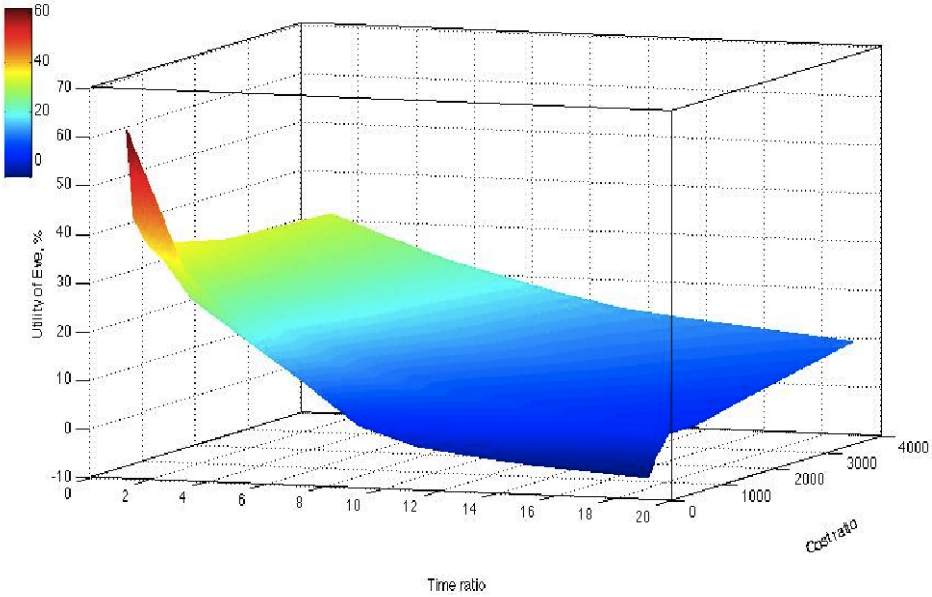
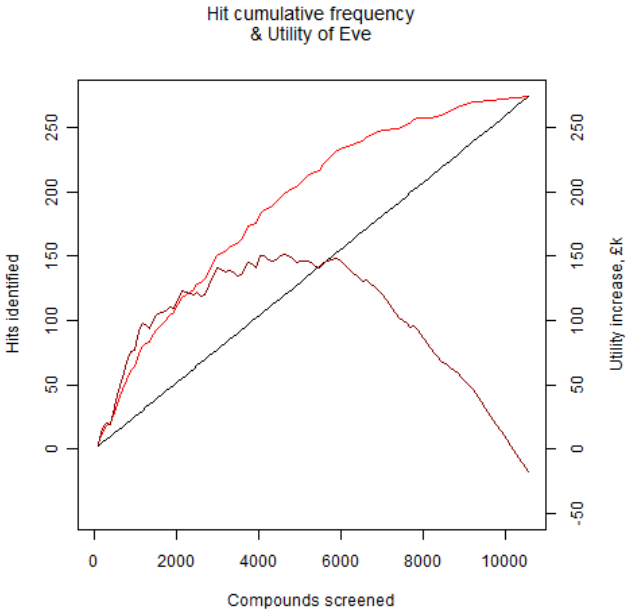
Highlights of Eve's hardware:

- Acoustic liquid handling
- High throughput 384 well plates
- Two industrial robot arms
- Automated 60x microscope
- Liquid handlers, fluorescence readers, barcode scanners, dry store, incubator, tube decapper ...





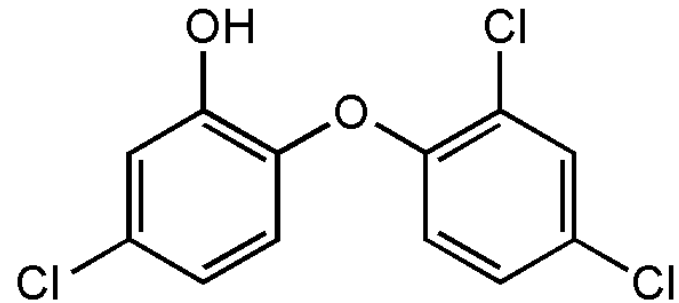
# The Economics of Intelligent Screening



$$\Delta \text{Utility of Eve} = \sum_1^{Nm} (Tm + Cm) + \sum_1^{Nx} (Tc + Cc - Uh) + \sum_1^{Ne} (Tm - Tc + Cm - Cc)$$

- Nm - Number of compounds not assayed by Eve
- Tm - Cost of the time to screen a compound using the mass screening assay
- Cm - Cost of the loss of a compound in the mass screening assay
- Nx - Number of hits missed by Eve
- Tc - Cost of the time to screen a compound using a cherry-picking (confirmation or intelligent) assay
- Cc - Cost of the loss of a compound in a cherry-picking assay
- Uh - Utility of a hit
- Ne - Number of compounds assayed by Eve

# Triclosan Repositioned for Malaria



- n Simple compound
- n Known to be safe – used in toothpaste.
- n Targets both DHFR and FAS-II – well established targets.
- n Demonstrated activity using multiple wet experimental techniques.
- n Works against wild-type and drug-resistant *Plasmodium falciparum*, and *Plasmodium vivax*.

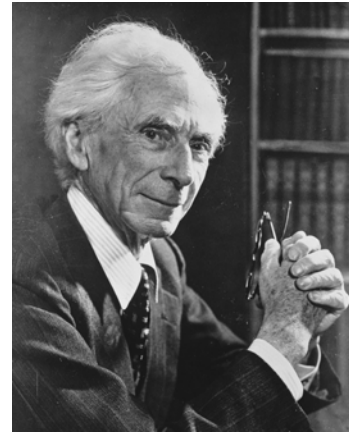
# Relational Learning

# Relational Learning

- n The use in machine learning of representations based of tuples of attributes is in essence the use of propositional logic.
- n Use of the richer, more expressive, language of 1<sup>st</sup>-order predicate logic is termed Relational Learning.
- n Not fashionable now, but in my view, sooner or later relational learning will become essential.
- n Used to be considered too inefficient to be practical, but Deep Neural Networks have moved the bar here!



# 1<sup>st</sup>-Order Predicate Logic



- n Developed a 100 years ago to describe mathematical structure.
- n Propositional logic assumes the world contains facts.
- n 1<sup>st</sup>-order Predicate logic assumes the world contains:
  - Objects: numbers, molecules, atoms, stars...
  - Relations: greater-than, bonds, distances ...
  - Functions: plus1, charge...

# Machine Learning: Attributes

- n Propositional Logics: Statistical, and neural network, methods use tuples (vectors) of attributes (descriptors) to represent examples.
- n An attribute is something true about a whole example.
- n Examples can be put into a single row in a table, the columns are the attributes.

# Attributes and Chemical Structure

- n Difficult to represent arbitrary chemical structure using propositions, i.e. a single table. Either the table grows exponentially, or a compromise must be made in fidelity.
- n What should the attributes be?
  - Boolean fingerprints
  - topological indices
  - Voxols
  - Quantum mechanic descriptors

# Relational Learning

- n Uses richer representation language
  - Enables relations: abstract structure
  - Explicit background knowledge (constraints): expressed as computer programs. Arbitrary complex pieces of prior knowledge.
  - No need for examples to be a single row in a table

King, R.D., et al. (1996) *Proc. Nat. Acad. Sci. U.S.A.* **93**, 438-442.



# Relational Approach: Atoms

- n The predicate atom is used, e.g. in compound 127 (3,4,3' -trinitrobiphenyl).
- n `atom(127, 127_1, c, 22, 0.191).`
- n States that in compound 127, atom no. 1 is a carbon of type 22 (aromatic carbon in a six membered ring) with a partial charge of 0.191.

# Relational Approach: Bonds

- n The predicate bond is used, e.g.  
bond(127, 127\_1, 127\_6, 7).
- n States that in compound 127, atom no. 1 and atom no. 6 are connected by a bond of type 7 (aromatic bond).

# High Level Background

## Knowledge 1

A definition of a Methyl group is:

methyl(Drug,[Atm0,Atm1,Atm2,Atm3,Atm4]) :

atom(Drug, Atm0, Type,.....),	% Link atom
Type not h,	
atom(Drug, Atm1, c. 10, ...),	% Aryl carbon
atom(Drug, Atm2, h, 3, ...),	% Hydrogen
atom(Drug, Atm3, h, 3, ...),	% Hydrogen
atm(Drug, Atm4, h, 3, ...),	% Hydrogen
bond(Drug, Atm0, Atm1,1),	% Single bond
bond(Drug, Atm1, Atm2, 1),	% Single bond
bond(Drug, Atm1, Atm3, 1),	% Single bond
bond(Drug, Atm1, Atm4, 1),	% Single bond
Atm2 @> Atm3,	
Atm3@> Atm4.	% Atm2,3,4 different

# High Level Background

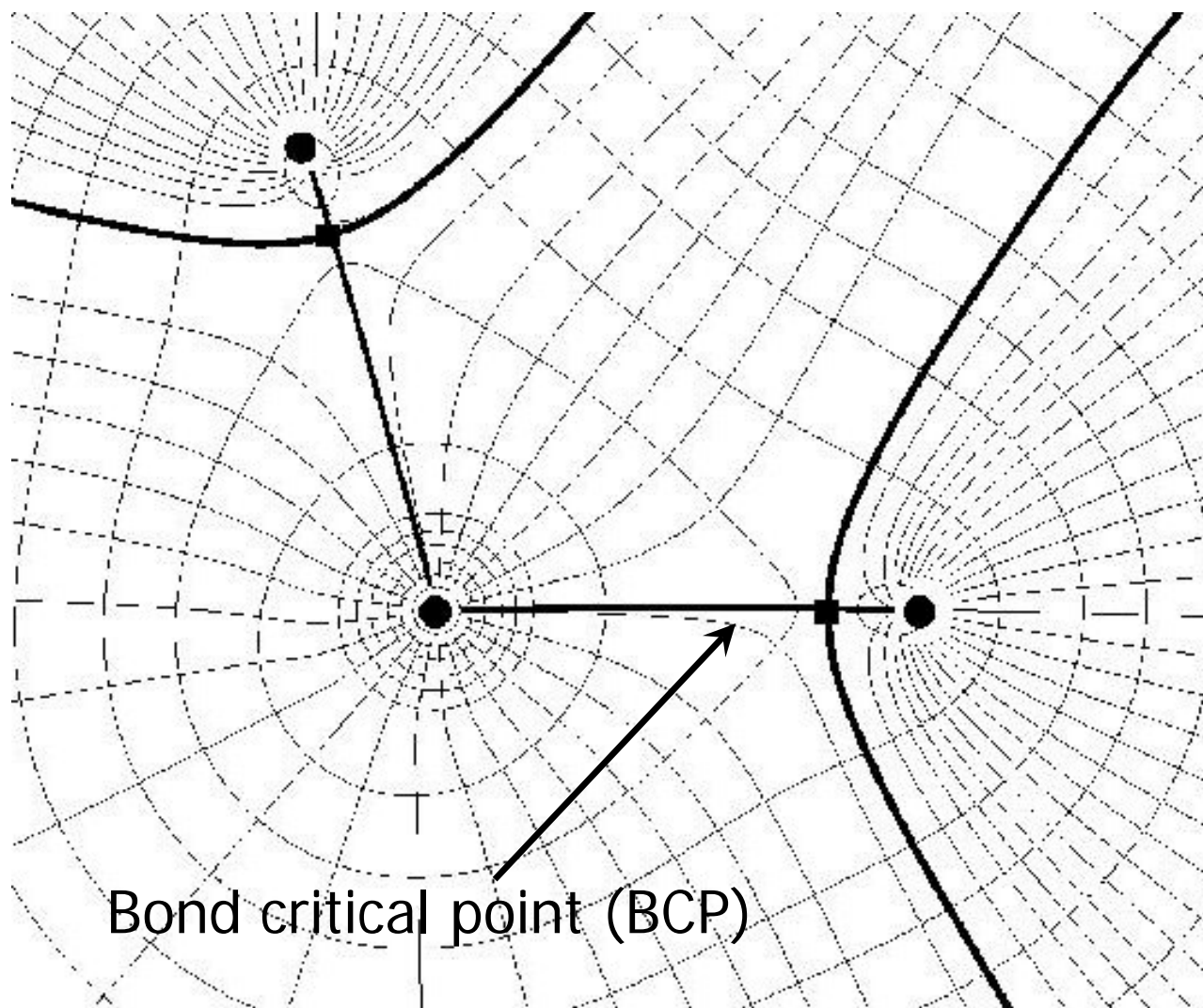
## Knowledge 2

- n Extend to 3D: simply add Pythagoras' theorem.
- n Extend to multiple confirmations: simply add and label confirmations.
- n Extend to quantum mechanics.

# 3D Electron Density



Richard F.W. Bader



Bond critical point (BCP)

# Example StruQT predicates

n	cp(Id,Field,[x,y,z],Hessian)	% critical point
n	signature(Id,Signature).	% signature of Hessian
n	rank(Id,Rank).	% rank of Hessian
n	con_path(Id_1,Id_2)	% connectivity of points
n	hessian(Id,L_1,L_2,L_3)	% eigenvalues of Hessian
n	nuc_attr(Id).	% nuclear attractor
n	bcp(Id)	% bond critical point
n	rcp(Id).	% ring critical point
n	ccp(Id).	% cage critical point

# Transformational Learning

# The New Idea

- n The new idea is to represent examples using predictions made by ML models learnt on other tasks: extrinsic features.
- n This transformation has the dual advantages of significantly improving predictive performance, and providing scientific insight.



# Standard Machine Learning



+

Size	Ears	Cute	Donkey
Big	Big	No	1.0
Small	Big	No	0.3



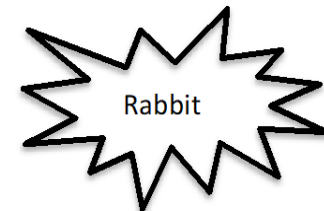
+

Size	Ears	Cute	Kitten
Small	Small	Yes	1.0
Small	Small	No	0.1

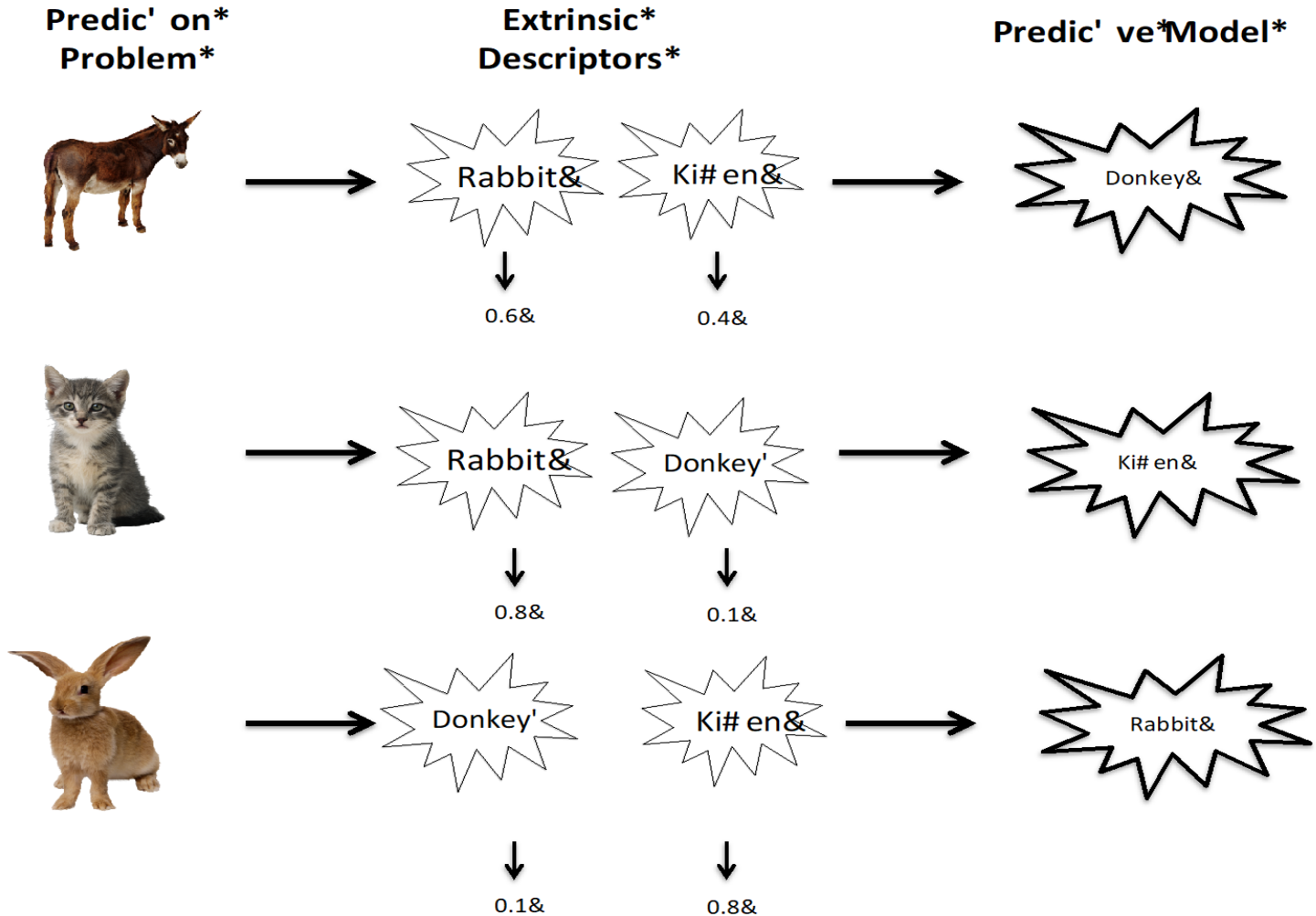


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Size	Ears	Cute	Rabbit
Small	Big	Yes	1.0
Big	Small	Yes	0.2



# Transformative Machine Learning

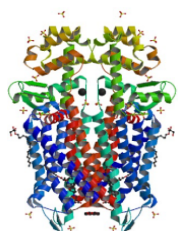


# Standard Machine Learning

Prediction Problem

Intrinsic Descriptors

Prediction Model



+

	G1#	G2#	...#	G1024#	Activity#
<chem>Oc1ccc(O)c2c1O[C@H]3[C@@H](OC)N[C@H]32</chem>	#	#	#	#	#
	1#	0#	1#	1#	0.9#
...	...#	...#	...#	...#	...#
<chem>CC(C)S[C@@H]1[C@H](OC(=O)R)N[C@@H]1C(=O)O</chem>	#	#	#	#	#
	0#	0#	1#	1#	0.3#

→

$F_1(X)$

||

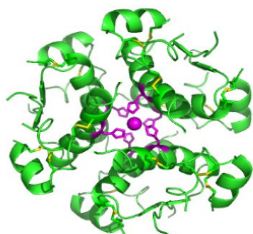
...

||

...

||

...



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	G1#	G2#	...#	G1024#	Activity#
<chem>Oc1ccc(O)c2c1O[C@H]3[C@@H](OC)N[C@H]32</chem>	#	#	#	#	#
	0#	0#	1#	0#	0.5#
...	...#	...#	...#	...#	...#
<chem>CC(C)S[C@@H]1[C@H](OC(=O)R)N[C@@H]1C(=O)O</chem>	#	#	#	#	#
	1#	0#	1#	1#	0.4#

→

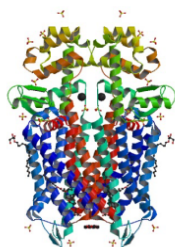
$F_n(X)$

# Transformative Machine Learning

Prediction Problem

Extrinsic Descriptors

Transformative Learning  
Prediction Model



+

	$F_1$	$F_2$	...	$F_n$	Activity
	0.3	0.4	0.7	0.9	0.9
...	...	...	...	...	...
	0.1	0.8	0.7	0.5	0.3

||

...

||

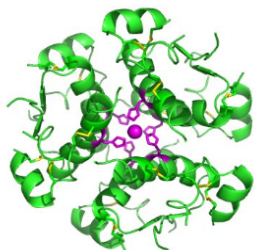
...

→

$T_1(X)$

||

...



+

	$F_1$	$F_2$	...	$F_n$	Activity
	0.2	0.5	0.9	0.1	0.5
...	...	...	...	...	...
	0.5	0.8	0.9	0.1	0.4

→

$T_n(X)$

# Intuition

- n Transformational learning combines ideas from multi-task learning and transfer learning.
- n Instead of using a predefined similarity measure to pre-select a set of similar tasks, we project the different tasks into one joint numeric representation.
- n Then use a meta-learning algorithm to learn from this new representation how to make accurate predictions for the task at hand.

# Experimental Setup – Machine Learning Methods

- n To investigate the utility of Transformative Learning we selected four machine learning methods:
  - Random forests (RF).
  - Support-vector machines (SVMs).
  - k-nearest neighbour (KNN).
  - Neural-networks (NN).
- n These represent the main families of non-linear Machine Learning methods.

# Experimental Setup – Problems

- n We applied the four machine learning methods to three typical real-world scientific problems:
  - Drug-design (quantitative structure activity relationship learning - QSAR). 2,219 target proteins and associated chemical compounds and activities from the ChEMBL database
  - Predicting 1,000 human gene expression (across different tissue types and drug treatments) – LINCS.
  - Meta-machine learning (predicting how well machine learning method will work on problems).

# Results

Problem Area	ML Method	Standard NRMSE (RMSE)	Transformed NRMSE (RMSE)	Stacked NRMSE (RMSE)	Difference % NRMSE (RMSE)
<i>QSAR</i>					
	<i>RF</i>	0.164 (0.651)	0.148 (0.632)	0.148 (0.632)	+10.05 (3.07)
	<i>SVM</i>	0.169 (0.672)	0.152 (0.649)	0.152 (0.649)	+10.10 (3.42)
	<i>KNN</i>	0.167 (0.711)	0.171 (0.734)	0.167 (0.711)	0 (0)
	<i>NN</i>	?	?		?
<i>LINCS</i>					
	<i>RF</i>	0.245 (0.069)	0.236 (0.066)	0.236 (0.066)	+3.68 (4.32)
	<i>SVM</i>	0.255 (0.069)	0.227 (0.068)	0.227 (0.068)	+10.9 (2.18)
	<i>KNN</i>	0.257 (0.072)	0.249 (0.072)	0.249 (0.072)	+2.92 (-0.28)
	<i>NN</i>	0.260 (0.074)	0.263 (0.071)	0.260 (0.074)	0 (0)
<i>Meta-ML</i>					
	<i>RF</i>	0.257 (0.118)	0.124 (0.053)	0.124 (0.053)	51.8 (55.57)
	<i>SVM</i>	0.296 (0.134)	0.214 (0.097)	0.214 (0.097)	27.8 (27.2)
	<i>KNN</i>	0.290 (0.133)	0.274 (0.126)	0.274 (0.126)	5.39 (5.40)
	<i>NN</i>	0.323 (0.148)	0.248 (0.113)	0.248 (0.113)	23.5 (23.7)



# Future Prospects

# The Future?

- n In Chess/Go there is a continuum of ability from novices up to Grandmasters.
- n I argue that this is also true in science, from the simple research of Eve, through what most human scientists can achieve, up to the ability of a Newton or Einstein.
- n If you accept this, then just as in Chess/Go, it is likely that advances in computer hardware and software will drive the development of ever smarter Robot Scientists.
- n The Physics Nobel Frank Wilczek is on record as saying that in 100 years' time the best physicist will be a machine.

# Vision

- n The collaboration between Human and Robot Scientists will produce better science than either can alone – human/computer teams still play better chess than either alone.
- n Scientific knowledge will be primarily expressed in logic with associated probabilities and published using the Semantic Web.
- n The improved productivity of science leads to societal benefits: better food security, better medicines, etc.

# Conclusions

- n Science is a wonderful application area for AI.
- n Automation is becoming increasingly important in scientific research e.g. DNA sequencing, drug design.
- n The Robot Scientist concept is the logical next step in scientific automation.
- n The Robot Scientist Adam was the first machine to have discovered novel scientific knowledge.
- n The Robot Scientist Eve has found new lead compounds for neglected tropical diseases.
- n Robot Scientists are needed for 21<sup>st</sup> century science.

# Acknowledgments

- n The Robot Scientist team: Manchester, Aberystwyth, Cambridge, Brunel, Leuven, Thailand. (BBSRC)