

# Conservation laws with ML for energy landscapes

Tristan Bereau Max Planck Institute for Polymer Research Mainz, Germany

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## $\mathbf{F} = m\mathbf{a}$



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# $\mathbf{F} = m\mathbf{a}$ Specify interparticle forces: "force field"



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Numerically integrate particle positions



# $\mathbf{F} = ma$

Specify interparticle forces: "force field"



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Numerically integrate particle positions



# $\mathbf{F} = ma$











Numerically integrate particle positions



# $\mathbf{F} = ma$







Numerically integrate particle positions



# $\mathbf{F} = ma$







Numerically integrate particle positions



# $F = ma^{\prime}$







Numerically integrate particle positions



# $F = ma^{\prime}$









# $\mathbf{H} = m\mathbf{a}$





# Links to machine learning

### Potential energy surface





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### Can we build a more accurate PES?

### Can we **easily** build an accurate PES?

### Can we make the numerical integration faster and/or more efficient?



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# Disclaimer: only kernel methods covered

Kernel

needs a representation linear algebra can be efficient with small data

### Deep learning

learns the representation complex mathematical structure data hungry











# Kernel machine learning 101









# Kernel machine learning 101

















### Kernel machine learning 101 Define kernel $K(r,r') = \exp\left(-\frac{(r-r')^2}{2\sigma^2}\right)$ $U_{\rm LJ}(r)$ Training points Prediction Make a prediction: $U(r) = \sum \alpha_i K(r_i^*, r)$ $U_{\rm LJ}(r) = 4\epsilon \left[ \left(\frac{\sigma}{r}\right)^{12} - \left(\frac{\sigma}{r}\right)^6 \right]$ Training points Predicted energy Query sample Train your model:





2.01.61.8 1.4

 $\alpha = (K + \lambda \mathbb{I})^{-1} U$ 























THEORY GROUP Rasmussen, Advanced lectures on machine learning. Springer, 63-71 (2004)



# Gaussian processes



THEORY GROUP Rasmussen, Advanced lectures on machine learning. Springer, 63-71 (2004)

 $f \sim \mathcal{GP}(m,k)$ 





 $f \sim \mathcal{GP}(m,k)$  $\mu_i = m(x_i) \qquad \Sigma_{ij} = k(x_i, x_j)$ 

f(x)

### random variable: value of the stochastic function at x

THEORY GROUP Rasmussen, Advanced lectures on machine learning. Springer, 63-71 (2004)

Gaussian processes

mean

covariance





Gaussian processes  $f \sim \mathcal{GP}(m,k)$  $\mu_i = m(x_i) \qquad \Sigma_{ij} = k(x_i, x_j)$ covariance mean kernel 

f(x)

### random variable: value of the stochastic function at x



THEORY GROUP Rasmussen, Advanced lectures on machine learning. Springer, 63-71 (2004)





THEORY GROUP

Gaussian processes  $f \sim \mathcal{GP}(m,k)$  $\mu_i = m(x_i) \qquad \Sigma_{ij} = k(x_i, x_j)$ covariance mean kernel Nonuniform: replace by repulsive potential (Csanyi and coworkers, Clementi and 

f(x)

### random variable: value of the stochastic function at x

|Noé, . . .)

target property

Rasmussen, Advanced lectures on machine learning. Springer, 63-71 (2004)





### **Conformational space** missing from training





## Linking conformational and interpolation spaces











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## Symmetries and conservation laws



# Mechanics 101: Principle of least action









### Mechanics 101: Principle of least action $\mathcal{S}[x(t)] = \int_{t_1}^{t_2} \mathrm{d}t \, L[x(t), \dot{x}(t), t]$ kinetic energy action potential energy Lagrangian L = T





Hamilton's principle: system minimizes action (variational principle)



# $\mathcal{S}[x^*(t)] = 0$





## Mechanics 101: Principle of least action $\mathcal{S}[x(t)] = \int_{t_1}^{t_2} dt \, L[x(t), \dot{x}(t), t] \qquad \qquad \text{kinetic end}$ action $\mathcal{L} = T - Lagrangian \ L = T$ kinetic energy potential energy





Hamilton's principle: system minimizes action (variational principle)

stationarity under small perturbations leads to Euler-Lagrange equations

$$\delta \mathcal{S} = \int_{t_1}^{t_2} \mathrm{d}t \, L(x^* + \varepsilon, \dot{x}^* + \dot{\varepsilon}, t) - L(x^*, \dot{x}^*, t)$$
$$= \int_{t_1}^{t_2} \mathrm{d}t \, \left(\varepsilon \frac{\partial L}{\partial x} + \dot{\varepsilon} \frac{\partial L}{\partial x}\right) = \int_{t_1}^{t_2} \mathrm{d}t \, \left(\varepsilon \frac{\partial L}{\partial x} - \varepsilon \frac{\mathrm{d}}{\mathrm{d}t} \frac{\partial L}{\partial \dot{x}}\right) = 0$$



# $\mathcal{S}[x^*(t)] = 0$





## Mechanics 101: Principle of least action $\mathcal{S}[x(t)] = \int_{t_1}^{t_2} dt \, L[x(t), \dot{x}(t), t] \qquad \qquad \text{kinetic error} \\ \text{Lagrangian } L = T$ kinetic energy potential energy





Hamilton's principle: system minimizes action (variational principle)

stationarity under small perturbations leads to Euler-Lagrange equations

 $\varepsilon(t_1) = \varepsilon(t_2) = 0$ 

$$\delta S = \int_{t_1}^{t_2} dt L(x^* + \varepsilon, \dot{x}^* + \dot{\varepsilon}, t) - L(x^*, \dot{x}^*, t)$$
$$= \int_{t_1}^{t_2} dt \left( \varepsilon \frac{\partial L}{\partial x} + \dot{\varepsilon} \frac{\partial L}{\partial x} \right) = \int_{t_1}^{t_2} dt \left( \varepsilon \frac{\partial L}{\partial x} - \varepsilon \frac{d}{dt} \frac{\partial L}{\partial \dot{x}} \right) = 0$$
  
integration by parts &



# $\mathcal{S}[x^*(t)] = 0$









From symmetries, to invariants, to conserved quantities

 $\mathcal{S}[x(t), y(t), z(t)] = \left[ dt \, \frac{m}{2} \left( \dot{x}^2 + \dot{y}^2 + \dot{z}^2 \right) - mgz \right]$ 





- $\mathcal{S}[x(t), y(t), z(t)] =$
- Introduce constant translations along x and y:
  - $S[x(t) + x_0, y(t) + y_0, z(t)]$



$$\mathrm{d}t\,\frac{m}{2}\left(\dot{x}^2+\dot{y}^2+\dot{z}^2\right)-mgz$$

$$= \int dt \frac{m}{2} \left( \dot{x}^2 + \dot{y}^2 + \dot{z}^2 \right) - mgz$$
$$= \mathcal{S}[x(t), y(t), z(t)]$$





- $\mathcal{S}[x(t), y(t), z(t)] =$
- Introduce constant translations along *x* and *y*:
  - $S[x(t) + x_0, y(t) + y_0, z(t)]$

(Translational) symmetry leaves the action invariant. It leaves the Euler-Lagrange equation unchanged:



$$\mathrm{d}t\,\frac{m}{2}\left(\dot{x}^2+\dot{y}^2+\dot{z}^2\right)-mgz$$

$$= \int dt \frac{m}{2} \left( \dot{x}^2 + \dot{y}^2 + \dot{z}^2 \right) - mgz$$
$$= \mathcal{S}[x(t), y(t), z(t)]$$

 $\frac{\partial L}{\partial x} - \frac{\mathrm{d}}{\mathrm{d}t} \frac{\partial L}{\partial \dot{x}} = 0$ 





$$\mathcal{S}[x(t), y(t), z(t)] = \int dt \, \frac{m}{2} \left( \dot{x}^2 + \dot{y}^2 + \dot{z}^2 \right) - mgz$$

Introduce constant translations along x and y:

$$\mathcal{S}[x(t) + x_0, y(t) + y_0, z(t)] = \int dt \, \frac{m}{2} \left( \dot{x}^2 + \dot{y}^2 + \dot{z}^2 \right) - mgz$$
$$= \mathcal{S}[x(t), y(t), z(t)]$$

(Translational) symmetry leaves the action invariant. It leaves the Euler-Lagrange equation unchanged:

$$\frac{\partial L}{\partial x} = 0 \qquad \qquad \frac{\partial L}{\partial \dot{x}} = m\dot{x} = \text{const.}$$



From symmetries, to invariants, to conserved quantities

 $\frac{\partial L}{\partial L} - \frac{\mathrm{d}}{\partial L} = 0$  $dt \partial \dot{x}$  $\partial x$ 

> Translational invariance implies linear momentum conversation









 $\mathcal{S}[\mathbf{r}(t)] =$ 

### **Rotational symmetry**

Apply transformation  $\mathbf{r} \rightarrow \mathbf{r}'$ where  $\mathbf{r}'(t) = R\mathbf{r}(t) = \mathbf{r}(t) + \alpha \times \mathbf{r}(t)$ 

One can show that  $\mathcal{S}[\mathbf{r}(t) + \alpha \times \mathbf{r}(t)] = \mathcal{S}[\mathbf{r}(t)]$ 

Conservation of angular momentum



### From symmetries to conserved quantities (cont'd)

$$\int \mathrm{d}t \, \frac{m}{2} \dot{\mathbf{r}}^2 - V(r)$$

### **Time translation**

Apply transformation  $\mathbf{r} \rightarrow \mathbf{r}'$ where  $\mathbf{r}'(t+\epsilon) = \mathbf{r}(t)$ 

One can show that  $\mathcal{S}[\mathbf{r}'(t+\epsilon)] = \mathcal{S}[\mathbf{r}(t)]$ (up to a boundary term) Conservation of energy








## Noether's theorem

# To every differentiable symmetry generated by local actions there corresponds a conserved quantity

## 3 examples:

- Translational symmetry: Linear momentum conservation
- Rotational symmetry: Angular momentum conservation
- Time translation: Energy conservation



## mentum conservation mentum conservation ation







# 2 ways of encoding symmetries:- Representation- ML model

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# Encoding symmetries in the representation

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## Translational and rotational symmetries Behler-Parrinello Coulomb matrix



$$G_{i}^{1} = \sum_{j \neq i}^{\text{all}} e^{-\eta(R_{ij} - R_{s})^{2}} f_{c}(R_{ij})$$
  

$$G_{i}^{2} = 2^{1-\zeta} \sum_{j,k \neq i}^{\text{all}} (1 + \lambda \cos \theta_{ijk})^{\zeta}$$
  

$$\times e^{-\eta(R_{ij}^{2} + R_{ik}^{2} + R_{jk}^{2})} f_{c}(R_{ij}) f_{c}(R_{ik}) f_{c}(R_{jk})$$
  
Distances  
Angles

Behler & Parrinello, Phys Rev Lett 98 (2007)





Rupp, Tkatchenko, Müller, von Lilienfeld, Phys Rev Lett, 108 (2012)



**6** (2012) 17



# Encoding symmetries in the ML model

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## Action of group G on input sample $x \mapsto T_{g}(x)$

**THEORY GROUP** Risi Kondor, *Group theoretical methods in machine learning, PhD thesis* (2008)

## Encoding symmetries in ML models using group theory





## Action of group G on input sample $x \mapsto T_{\rho}(x)$

Can we find a kernel that is invariant to this group action?  $f(T_g(x)) = f(x) \forall g \in G$ 



## Encoding symmetries in ML models using group theory

 $k(x, x') = k(T_g(x), T_{g'}(x'))$ 









Action of group G on input sample  $x \mapsto T_{\rho}(x)$ 

Can we find a kernel that is invariant to this group action?

To ensure invariance, symmetrize the kernel

 $k^{G}(x, x') = \frac{1}{|G|} \sum_{k \in V} k(x, T_{g}(x'))$  $g \in G$ 

Risi Kondor, Group theoretical methods in machine learning, PhD thesis (2008)

## Encoding symmetries in ML models using group theory

 $f(T_g(x)) = f(x) \forall g \in G$  $k(x, x') = k(T_g(x), T_{g'}(x'))$ 









## Example of symmetrized kernel

SOAP kernel/representation\*



 $S(\hat{R}) \equiv S(\rho, \hat{R}\rho') = \int d\mathbf{r} \,\rho(\mathbf{r})\rho'(\hat{R}\mathbf{r}) = \sum \sum D_{m'm''}^{l'}(\hat{R}) \int dr \, c_{lm}^{i*}(r) c_{l'm'}^{i'}(r) \int d\hat{\mathbf{r}} \, Y_{lm}^{*}(\hat{\mathbf{r}}) Y_{l'm''}(\hat{\mathbf{r}})$ 

$$k(\rho, \rho') = \int \left| S(\rho, \hat{R}\rho') \right|^n d\hat{R} =$$
$$= \int d\hat{R} \left| \int \rho(\mathbf{r}) \rho'(\hat{R}\mathbf{r}) d\mathbf{r} \right|$$

metric between two samples











Tensorial property (e.g., dipole moment, force) **rotates** with the sample









Tensorial property (e.g., dipole moment, force) rotates with the sample











Tensorial property (e.g., dipole moment, force) **rotates** with the sample











Tensorial property (e.g., dipole moment, force) **rotates** with the sample



"Build kernel so as to encode the rotational properties of the target property"













## Covariant kernels

Encode rotational properties of the target property in the **kernel** 







## $\hat{\mathbf{f}}(\mathcal{S}\rho \mid \mathcal{D}) = \hat{\mathbf{S}}\hat{\mathbf{f}}(\rho \mid \mathcal{D})$ Force prediction Transformation (rotation/inversion) Descriptor Training data

THEORY GROUP Glielmo, Sollich, De Vita, *Phys Rev B* **95** (2017)

## Covariant kernels

Encode rotational properties of the target property in the **kernel** 







## $\mathbf{f}(\mathcal{S}\rho \mid \mathcal{D}) = \mathbf{S}\hat{\mathbf{f}}(\rho \mid \mathcal{D})$ Force prediction Transformation (rotation/inversion) Descripto Training data

THEORY Glielmo, Sollich, De Vita, *Phys Rev B* **95** (2017)

## Covariant kernels

Encode rotational properties of the target property in the **kernel** 

"Transform the configuration, and the prediction transforms with it"











## Transformations (rotation/inversion)

THEORY Glielmo, Sollich, De Vita, Phys Rev B 95 (2017)

# Covariant kernels $\mathbf{K}(\mathcal{S}\rho,\mathcal{S}'\rho') = \mathbf{S}\mathbf{K}(\rho,\rho')\mathbf{S}'^{\mathrm{T}}$ Configurations

 $\mathbf{K}(\boldsymbol{\rho},\boldsymbol{\rho}') = \int d\mathcal{R}\mathbf{R}k_b(\boldsymbol{\rho},\mathcal{R}\boldsymbol{\rho}')$ 

 $\mathbf{K}^{\mu}(\rho, \rho') = \frac{1}{L} \sum_{ij} \phi(r_i, r_j) \mathbf{r}_i \otimes \mathbf{r}_j'^{\mathrm{T}}$ 











# Extension to higher-order tensors $\mathbf{K}^{\mathsf{Q}}(\mathcal{S}\rho, \mathcal{S}'\rho') = \mathbf{S}'\mathbf{S}^{\mathsf{T}}\mathbf{K}^{\mathsf{Q}}(\rho, \rho')\mathbf{S}\mathbf{S}'^{\mathsf{T}}$

 $\mathbf{K}^{\mathbf{Q}}(\rho, \rho') = \frac{1}{L} \sum_{ij} \left( \mathbf{R}_{j}^{\mathrm{T}} \otimes \mathbf{R}_{i} \right) \Phi(r_{i}, r_{j}) \left( \mathbf{R}_{i}^{\mathrm{T}} \otimes \mathbf{R}_{j} \right)$ aligns  $\mathbf{r}_i$  onto  $\hat{z}$  $\hat{z}_{\dagger}$ **fr**<sub>i</sub>

Bereau, DiStasio Jr., Tkatchenko, von Lilienfeld, J Chem Phys 148 (2018) THEORY Grisafi, Wilkins, Csanyi, Ceriotti, Phys Rev Lett **120** (2018) GROUP

 $\Phi(r_i, r_j) = e^{\frac{-\alpha_{ij}^2}{4\sigma^2}} \int d\alpha \int d\beta \int d\gamma \frac{\sin \beta}{8\pi^2} \times \mathbf{R}^{\mathrm{T}}(\alpha, \beta, \gamma) \otimes \mathbf{R}(\alpha, \beta, \gamma) e^{\frac{r_i r_j \cos \beta}{2\sigma^2}}$  $=\begin{pmatrix} \varphi_1 & 0 & 0 & 0 & \varphi_2 & 0 & 0 & 0 \\ 0 & \varphi_1 & 0 & -\varphi_2 & 0 & 0 & 0 & 0 \\ 0 & 0 & \varphi_3 & 0 & 0 & 0 & 0 & 0 \\ 0 & -\varphi_2 & 0 & \varphi_1 & 0 & 0 & 0 & 0 \\ \varphi_2 & 0 & 0 & 0 & \varphi_1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & \varphi_3 & 0 & 0 & 0 \\ \end{pmatrix}$ 









# Application to intermolecular interactions

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## Transferable model for intermolecular interactions

### Physics-based models

Encode laws, symmetries
Little chemical information

## Compositional (e.g., benzene vs. chlorobenzene)



### Data-driven models

- Need to *learn* laws, symmetries
- Interpolate across chemistry







)







## Transferable model for intermolecular interactions

Physics-based models

- Encode laws, symmetries
- Little chemical information

## Any small molecule made of H, C, O, N neutral compounds

Compositional (e.g., benzene vs. chlorobenzene)



### Data-driven models

- Need to *learn* laws, symmetries
- Interpolate across chemistry













## Long-ranged

- Static electrostatics
- Many-body dispersion
- Polarization

Van Vleet, Misquitta, Stone, and Schmidt, *J. Chem. Theory Comput.* **12** (2016); Vandenbrande, et al., *J. Chem. Theory Comput.* **13** (2017); Grimme, *J. Chem. Theory Comput.* **10** (2014); Verstraelen, et al., *J. Chem. Theory Comput.* **12** (2016); Metz et al, *J. Chem. Theory Comput* **12** (2016)

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## Short-ranged

- Charge penetration
- Repulsion
- (Charge transfer)





## Long-ranged

## **Perturbation theory**

- Static electrostatics
- Many-body dispersion
- Polarization



Van Vleet, Misquitta, Stone, and Schmidt, J. Chem. Theory Comput. 12 (2016); Vandenbrande, et al., J. Chem. Theory Comput. 13 (2017); Grimme, J. Chem. Theory Comput. 10 (2014); Verstraelen, et al., J. Chem. Theory THEORY *Comput.* **12** (2016); Metz et al, *J. Chem. Theory Comput* **12** (2016)

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# Short-ranged

## **Overlap models**

- Charge penetration
- Repulsion
- (Charge transfer)

 $S_{ij} = \int \mathrm{d}^3 \mathbf{r} \rho_i(\mathbf{r}) \rho_j(\mathbf{r})$ 





## Long-ranged

- Static electrostatics
- Many-body dispersion
- Polarization

## **Use ML to predict atoms-in-molecules** properties

- Multipole moments
- Hirshfeld ratios

Van Vleet, Misquitta, Stone, and Schmidt, J. Chem. Theory Comput. 12 (2016); Vandenbrande, et al., J. Chem. Theory Comput. 13 (2017); Grimme, J. Chem. Theory Comput. 10 (2014); Verstraelen, et al., J. Chem. Theory THEORY *Comput.* **12** (2016); Metz et al, *J. Chem. Theory Comput* **12** (2016) GROUP

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## Short-ranged

- Charge penetration
- Repulsion
- (Charge transfer)

Atomic density widths/populations





Long-ranged

- Static electrostatics
- Many-body dispersion Hirshfeld ratios
- Polarization

- Multipole moments
- Hirshfeld ratios

Van Vleet, Misquitta, Stone, and Schmidt, J. Chem. Theory Comput. 12 (2016); Vandenbrande, et al., J. Chem. Theory Comput. 13 (2017); Grimme, J. Chem. Theory Comput. 10 (2014); Verstraelen, et al., J. Chem. Theory THEORY *Comput.* **12** (2016); Metz et al, *J. Chem. Theory Comput* **12** (2016) GROUP







Stone, The Theory of Intermolecular Forces **THEORY** Bereau and Meuwly, Many-Body Effects and Electrostatics in Biomolecules

## Static multipole electrostatics





Stone, The Theory of Intermolecular Forces Bereau and Meuwly, Many-Body Effects and Electrostatics in Biomolecules

R



 $-\frac{\mu_{\alpha}R_{\alpha}}{R^{3}}+\frac{1}{3}\Theta_{\alpha\beta}\frac{3R_{\alpha}R_{\beta}-R^{2}\delta_{\alpha\beta}}{D^{5}}$ 





THEORY GROUP

Stone, The Theory of Intermolecular Forces Bereau and Meuwly, Many-Body Effects and Electrostatics in Biomolecules





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Bereau and Meuwly, Many-Body Effects and Electrostatics in Biomolecules





# Multipoles: Learning curves



**THEORY GROUP** Bereau, DiStasio Jr., Tkatchenko, von Lilienfeld, *JCP* **148**, 241706 (2018); JCP Editor's Choice 2018

## **Easier to learn** H,O than C,N





## Multipoles: Correlation curves









monopole







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## Intermolecular energy across conformations and composition









Jurecka, Sponer, Cerny, Hobza, PCCP (2006) Paton and Goodman, J Chem Inf Model (2009)





**THEORY GROUP** Bereau, DiStasio Jr., Tkatchenko, von Lilienfeld, *JCP* **148**, 241706 (2018); JCP Editor's Choice 2018 1518 104 VIEWS SHARES TO CO CO CO



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# Energy conservation

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# Up to now: learning a scalar field $f: \mathbb{R}^n \to \mathbb{R}$ $f(\mathbf{x}) = \sum_{i=1}^{N} \alpha_i K(\mathbf{x}, \mathbf{x}_i) \qquad N = N$

Macêdo and Castro, Learning divergence-free and curl-free vector fields with matrix-valued kernels, IMPA (2010) THEORY Micchelli and M. Pontil. Neural Computation, 17(1):177–204, 2005. • GROUP

## Learning a vector field: matrix-valued kernels 🔰



 $\alpha_i \in \mathbb{R}$  $K: \mathbb{R}^n \times \mathbb{R}^n \to \mathbb{R}$ 









Up to now: learning a scalar field  $f: \mathbb{R}^n \to \mathbb{R}$ 

$$f(\mathbf{x}) = \sum_{i=1}^{N} \alpha_i K(\mathbf{x}, \mathbf{x}_i) \qquad N =$$

Learning a vector field  $\mathbf{f}: \mathbb{R}^n \to \mathbb{R}^n$ 

 $\mathbf{f}(\mathbf{x}) = \sum \alpha_i K(\mathbf{x}, \mathbf{x}_i)$ Nn i=1

Macêdo and Castro, Learning divergence-free and curl-free vector fields with matrix-valued kernels, IMPA (2010) THEORY Micchelli and M. Pontil. Neural Computation, 17(1):177–204, 2005.

## Learning a vector field: matrix-valued kernels























## By default: components learned *independently*. No prior on the vector field.












Time invariance leads to an **energy-conserving** force field (curl-free):  $\nabla \mathbf{x} \mathbf{f} = \mathbf{0}$ 

Design matrix-valued kernel that is *also* curl free.





#### By default: components learned *independently*. No prior on the vector field.











### Recall the (translation-invariant) kernel:



THEORY GROUP E. Fuselier. PhD thesis, Texas A&M University (2006)

#### Enforcing structure onto the vector field: Matrix-valued radial basis functions







Recall the (translation-invariant) kernel:  $K(\mathbf{r},\mathbf{r}') = \exp\left(-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-$ 

### Construct matrix-valued RBF $\Phi: \mathbb{R}^n$ Apply linear differential operator: $\Phi(\mathbf{x}) := (\mathscr{L}\phi)(\mathbf{x})$



Enforcing structure onto the vector field: Matrix-valued radial basis functions

$$\frac{\mathbf{r} - \mathbf{r}'\|^2}{2\sigma^2} = \varphi \left( \|\mathbf{r} - \mathbf{r}'\| \right)$$
  
scalar RBF  $\Phi : \mathbb{R}^n \to \mathbb{R}$   
 $\to \mathbb{R}^{n \times n}$  from a scalar RBF  $\phi(\mathbf{x}) = \varphi(\|\mathbf{x}\|)$   
 $\varphi(\mathbf{x}) := (\mathcal{L}\phi)(\mathbf{x})$ 





Recall the (translation-invariant) kernel:  $K(\mathbf{r},\mathbf{r}') = \exp\left(-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-\frac{\|\mathbf{r}\|}{-$ 

Apply linear differential operator:  $\Phi(\mathbf{x}) := (\mathscr{L}\phi)(\mathbf{x})$ 

#### Example: curl-free

THEORY GROUP E. Fuselier. PhD thesis, Texas A&M University (2006)

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Construct matrix-valued RBF  $\Phi: \mathbb{R}^n \to \mathbb{R}^{n \times n}$  from a scalar RBF  $\phi(\mathbf{x}) = \phi(\|\mathbf{x}\|)$ 

$$(H\phi)_{ij} := \frac{\partial^2 \phi}{\partial x_i \partial x_j}$$





## Vector fields: curl-free and divergence-free 🔰

# divergence-free



Figure 1. Learning a vector field decomposition: samples, learned field, divergence- and curl-free parts.

THEORY Macêdo and Castro, Learning divergence-free and curl-free vector fields with matrix-valued kernels, IMPA (2010) GROUP







#### Distribution (Brownian dynamics)



### Kernel learning of a 2D potential

 $\frac{V(x,y)}{k_{\rm B}T} = \frac{1}{50}(x-4)(x-2)(x+2)(x+3) + \frac{1}{20}y^2 + \frac{1}{25}\sin(3(x+5)(y-6))$ 

Potential from: Wang et al., ACS Cent. Sci. 5 755–767 (2019)















# Standard kernel Learn the instantaneous forces $({f^x}, {f^y})$ and assume independence $q_2$ $N \equiv N \qquad N \times N \qquad N \equiv N \qquad N \times N$ $K(\mathbf{q},\mathbf{q}') = \exp\left(-\frac{(\mathbf{q}-\mathbf{q}')^2}{2\sigma^2}\right)$ -2 $\left| f_j^x = \sum \alpha_i^x \left( K(\mathbf{q}_i, \mathbf{q}_j) + \lambda \mathbb{I} \right) \qquad f_j^y = \sum \alpha_i^y \left( K(\mathbf{q}_i, \mathbf{q}_j) + \lambda \mathbb{I} \right) \right|$

 $\mathbf{q} = \begin{pmatrix} 2(x+y) \\ x-y \end{pmatrix}$ 



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$$\operatorname{Cov}\left(\frac{\partial E(\mathbf{q}_i)}{\partial r^k}, \frac{\partial E(\mathbf{q}_j)}{\partial r^l}\right) = \frac{\partial \mathbf{q}}{\partial r_i^k}$$



### Energy-conserving kernel







### Energy-conserving kernel







$$\operatorname{Cov}\left(\frac{\partial E(\mathbf{q}_{i})}{\partial r^{k}}, \frac{\partial E(\mathbf{q}_{j})}{\partial r^{l}}\right) = \frac{\partial \mathbf{q}}{\partial r_{i}^{k}}$$
$$K(\mathbf{q}, \mathbf{q}') = \exp\left(-\frac{(\mathbf{q} - \mathbf{q}')^{2}}{2\sigma^{2}}\right)$$

$$\mathbf{K}_{\text{Hess}}(q_i^k, q_j^l) = \frac{\partial \mathbf{q}}{\partial r_i^k} \cdot \frac{\partial \mathbf{q}}{\partial r_j^l} \frac{\partial}{\partial \mathbf{q}} \frac{\partial}{\partial \mathbf{q}}$$
$$= \frac{\partial \mathbf{q}}{\partial r_i^k} \cdot \frac{\partial \mathbf{q}}{\partial r_j^l} \frac{1}{\sigma^2} \left( \frac{\partial \mathbf{q}}{\partial r_j^k} - \frac{\partial \mathbf{q}}{\partial r_j^l} \frac{1}{\sigma^2} \right)$$

THEORY Mathias, Master Thesis, Bonn (2015); Glielmo et al., arXiv:1905.07626; Csanyi; Tkatchenko; Müller...

### Energy-conserving kernel







$$\operatorname{Cov}\left(\frac{\partial E(\mathbf{q}_{i})}{\partial r^{k}}, \frac{\partial E(\mathbf{q}_{j})}{\partial r^{l}}\right) = \frac{\partial \mathbf{q}}{\partial r_{i}^{k}}$$
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THEORY GROUP Mathias, Master Thesis, Bonn (2015); Glielmo et al., arXiv:1905.07626; Csanyi; Tkatchenko; Müller...

Energy-conserving kernel

 $\frac{\partial^2 K(\mathbf{q}_i, \mathbf{q}_j)}{\partial \mathbf{q} \partial \mathbf{q}} \frac{\partial \mathbf{q}}{\partial r_j^l} + \frac{\partial K(\mathbf{q}_i, \mathbf{q}_j)}{\partial \mathbf{q}} \frac{\partial^2 \mathbf{q}}{\partial r_i^k \partial r_j^l}$  $\mathbf{K}_{\text{Hess}}(q_i^k, q_i^l)$  $\frac{\partial}{\partial \mathbf{q}} \exp\left(-\frac{(\mathbf{q}_i - \mathbf{q}_j)^2}{2\sigma^2}\right)$  $1 - \frac{(\mathbf{q}_i - \mathbf{q}_j)^2}{\sigma^2} \exp\left(-\frac{(\mathbf{q}_i - \mathbf{q}_j)^2}{2\sigma^2}\right)$ 





$$K(\mathbf{q}, \mathbf{q}') = \exp\left(-\frac{(\mathbf{q} - \mathbf{q}')^2}{2\sigma^2}\right)$$

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$$= \frac{\partial \mathbf{q}}{\partial r_i^k} \cdot \frac{\partial \mathbf{q}}{\partial r_j^l} \frac{1}{\sigma^2} \left($$

enables energy conservation

THEORY Mathias, Master Thesis, Bonn (2015); Glielmo et al., arXiv:1905.07626; Csanyi; Tkatchenko; Müller...

Energy-conserving kernel

 $\operatorname{Cov}\left(\frac{\partial E(\mathbf{q}_{i})}{\partial r^{k}}, \frac{\partial E(\mathbf{q}_{j})}{\partial r^{l}}\right) = \frac{\partial \mathbf{q}}{\partial r_{i}^{k}} \cdot \frac{\partial^{2} K(\mathbf{q}_{i}, \mathbf{q}_{j})}{\partial \mathbf{q} \partial \mathbf{q}} \frac{\partial \mathbf{q}}{\partial r_{j}^{l}} + \frac{\partial K(\mathbf{q}_{i}, \mathbf{q}_{j})}{\partial \mathbf{q}} \cdot \frac{\partial^{2} \mathbf{q}}{\partial r_{i}^{k} \partial r_{j}^{l}}$  $\mathbf{K}_{\text{Hess}}(q_i^k, q_i^l)$  $\frac{\partial}{\partial \mathbf{q}} \exp\left(-\frac{(\mathbf{q}_i - \mathbf{q}_j)^2}{2\sigma^2}\right)$  $1 - \frac{(\mathbf{q}_i - \mathbf{q}_j)^2}{\sigma^2} \exp\left(-\frac{(\mathbf{q}_i - \mathbf{q}_j)^2}{2\sigma^2}\right)$ 





## Energy-con





$$K(\mathbf{q},\mathbf{q}') = \exp\left(-\frac{(\mathbf{q}-\mathbf{q}')^2}{2\sigma^2}\right)$$

$$\mathbf{K}_{\text{Hess}}(q_i^k, q_j^l) = \frac{\partial \mathbf{q}}{\partial r_i^k} \cdot \frac{\partial \mathbf{q}}{\partial r_j^l} \frac{\partial}{\partial \mathbf{q}} \frac{\partial}{\partial \mathbf{q}} \exp\left(-\frac{(\mathbf{q}_i - \mathbf{q}_j)^2}{2\sigma^2}\right)$$
$$= \frac{\partial \mathbf{q}}{\partial r_i^k} \cdot \frac{\partial \mathbf{q}}{\partial r_j^l} \frac{1}{\sigma^2} \left(1 - \frac{(\mathbf{q}_i - \mathbf{q}_j)^2}{\sigma^2}\right) \exp\left(-\frac{(\mathbf{q}_i - \mathbf{q}_j)^2}{2\sigma^2}\right)$$

**q** =

enables energy conservation



$$= \begin{pmatrix} 2(x+y) \\ x-y \end{pmatrix} \quad \frac{\partial \mathbf{q}}{\partial x} = \begin{pmatrix} 2 \\ 1 \end{pmatrix} \quad \frac{\partial \mathbf{q}}{\partial y} = \begin{pmatrix} 2 \\ -1 \end{pmatrix}$$
$$\mathbf{q} = \begin{pmatrix} x \\ y \end{pmatrix} \qquad \frac{\partial \mathbf{q}}{\partial x} = \begin{pmatrix} 1 \\ 0 \end{pmatrix} \qquad \frac{\partial \mathbf{q}}{\partial y} = \begin{pmatrix} 0 \\ 1 \end{pmatrix}$$





### Standard kernel







#### - 2.0 - 1.5 - 1.0 - 0.5

- 0.0

-0.5

- -1.0

- -1.5

-2.0





## Energy-conserving ML







### - 2.0 - 1.5 - 1.0 - 0.5 - 0.0

- -0.5 - -1.0

-1.5

-2.0



### Comparison between ML models



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#### **Energy-conserving force field useful in the low-data regime**



#### 1.00- 0.75 - 0.50 - 0.25 - 0.00 -0.25-0.50-0.75-1.00







# Building symmetries in ML force fields





THEORY GROUP Chmiela et al., Nat. Comm. 9:3887 (2018)

$$\alpha_i)_l \frac{\partial}{\partial x_l} \nabla \kappa \left( \mathbf{x}, \mathbf{P}_q \mathbf{x}_i \right)$$
  
energy conservation

 Incorporate symmetries and conservation laws to minimize the training data • Reduces dataset size: can target extremely accurate quantum chemistry





# Building symmetries in ML force fields



Chmiela et al., Nat. Comm. 9:3887 (2018)







### Conclusions



#### **Extrapolation in ML models of energy landscapes** Can lead to catastrophic physics

#### Take advantage of symmetries Noether: symmetry leads to conservation law

### $\mathbf{K}(\mathcal{S}\rho, \mathcal{S}'\rho') = \mathbf{S}\mathbf{K}(\rho, \rho')\mathbf{S}'^{\mathrm{T}}$







#### **Build symmetries in ML model**

Work with subset of kernels that a priori satisfy conservation law



