How many measurements do we need to reconstruct a digital object to within fixed accuracy?

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Recovery Problem

- Object $f \in \mathbf{R}^N$ we wish to reconstruct: digital signal, image; dataset.
- Can take linear measurements

$$y_k = \langle f, \psi_k
angle, \qquad k = 1, 2, \dots, K.$$

• How many measurements do we need to do recover f to within accuracy ϵ

$$\|f - f^{\sharp}\|_{\ell_2} \leq \epsilon$$

for typical objects f taken from some class $f \in \mathcal{F} \subset \mathbb{R}^N$.

• Interested in practical reconstruction methods.

Agenda

- Background: exact reconstruction of sparse signals
- Near-optimal reconstruction of compressible signals
- Duality
- Uniform uncertainty principles
- Relationship with coding theory
- Numerical experiments

Sparse Signals

- Vector $f \in \mathbb{R}^N$; digital signal, coefficients of a digital signal/image, etc.)
- |T| nonzero coordinates (|T| spikes)

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T:=\{t,\ f(t)\neq 0\}
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- Do not know the locations of the spikes
- Do not know the amplitude of the spikes



Recovery of Sparse Signals

- Sparse signal f: |T| spikes
- Available information

$$y = F f$$
,

F is K by N with K << N

• Can we recover f from K measurements?

Fourier Ensemble

- Random set $\Omega \subset \{0,\ldots,N-1\}$, $|\Omega| = K$.
- Random frequency measurements: observe $(Ff)_k = \hat{f}(k)$

$$\hat{f}(k) = \sum_{t=0}^{N-1} f(t) e^{-i2\pi kt/N}, \quad k \in \Omega$$

Exact Recovery from Random Frequency Samples

- Available information: $y_k = \hat{f}(k)$, Ω random and $|\Omega| = K$.
- To recover f, simply solve

$$(P_1)$$
 $f^{\sharp} = \operatorname{argmin}_{g \in \mathbf{R}^N} \|g\|_{\ell_1},$ subject to $Fg = Ff.$

where

$$\|g\|_{\ell_1}:=\sum_{t=0}^{N-1}|g(t)|.$$

Theorem 1 (C., Romberg, Tao) Suppose

$$|K| \ge lpha \cdot |T| \cdot \log N.$$

Then the reconstruction is exact with prob. greater than $1 - O(N^{-\alpha\rho})$ for some fixed $\rho > 0$: $f^{\sharp} = f$. (N.b. $\rho \approx 1/29$ works).

Exact Recovery from Gaussian Measurements

• Gaussian random matrix

$$F(k,t) = X_{k,t}, \qquad X_{k,t} \ i.i.d. \ N(0,1)$$

• This will be called the Gaussian ensemble

Solve

$$(P_1)$$
 $f^{\sharp} = \operatorname{argmin}_{g \in \mathbf{R}^N} \|g\|_{\ell_1}$ subject to $Fg = Ff.$

Theorem 2 (C., Tao) Suppose

$$|K| \ge lpha \cdot |T| \cdot \log N.$$

Then the reconstruction is exact with prob. greater than $1 - O(N^{-\alpha \rho})$ for some fixed $\rho > 0$: $f^{\sharp} = f$.

Gaussian Random Measurements

 $y_k = \langle f, X
angle, \quad X_t \, \, i.i.d. \, \, N(0,1)$



Equivalence

• Combinatorial optimization problem

$$(P_0) \qquad \min_g \|g\|_{\ell_0} := \#\{t, g(t) \neq 0\}, \qquad Fg = Ff$$

• Convex optimization problem (LP)

$$(P_1) \qquad \min_g \|g\|_{\ell_1}, \qquad Fg = Ff$$

• Equivalence:

For $K \simeq |T| \log N$, the solutions to (P_0) and (P_1) are unique and are the same!

About the ℓ_1 -norm

- Minimum ℓ_1 -norm reconstruction in widespread use
- Santosa and Symes (1986) proposed this rule to reconstruct spike trains from incomplete data
- Connected with Total-Variation approaches, e.g. Rudin, Osher, Fatemi (1992)
- More recently, l₁-minimization, *Basis Pursuit*, has been proposed as a convex alternative to the combinatorial norm l₀. Chen, Donoho Saunders (1996)
- Relationships with uncertainty principles: Donoho & Huo (01), Gribonval & Nielsen (03), Tropp (03) and (04), Donoho & Elad (03)

min ℓ_1 as LP

 $\min \|x\|_{\ell_1}$ subject to Ax = b

• Reformulated as an LP (at least since the 50's).

• Split
$$x$$
 into $x = x_+ - x_-$

$$\min \mathbf{1}^T x_+ + \mathbf{1}^T x_-$$
 subject to $egin{cases} \left(A & -A
ight) \begin{pmatrix} x_+ \\ x_- \end{pmatrix} = b \ x_+ \ge 0, x_- \ge 0 \end{cases}$

Reconstruction of Spike Trains from Fourier Samples

- Gilbert et al. (04)
- Santosa & Symes (86)
- Dobson & Santosa (96)
- Bresler & Feng (96)
- Vetterli et. al. (03)

Why Does This Work? Geometric Viewpoint Suppose $f \in \mathbb{R}^2$, f = (0, 1).





Exact

Miss

Higher Dimensions



Duality in Linear/Convex Programming

- *f* unique solution 'if and only' if dual is feasible
- Dual is feasible if there is $P \in \mathbf{R}^N$
 - P is in the rowspace of F
 - P is a subgradient of $\|f\|_{\ell_1}$

$$P\in \partial \|f\|_{\ell_1} \quad \Leftrightarrow \quad egin{cases} P(t)= ext{sgn}(f(t)), & t\in T\ |P(t)|<1, & t\in T^c \end{cases}$$

Interpretation: Dual Feasibility with Freq. Samples



Numerical Results

- Signal length N = 256
- Randomly place |T| spikes, observe K| Gaussian coefficients
- Measure % recovered perfectly
- White = always recovered, black = never recovered



Empirical probablities of exact reconstruction: spikes and random basis

Numerical Results

- Signal length N = 1024
- Randomly place |T| spikes, observe K random frequencies
- Measure % recovered perfectly
- white = always recovered, black = never recovered



Reconstruction of Piecewise Polynomials, I

- Randomly select a few jump discontinuities
- Randomly select cubic polynomial in between jumps
- Observe about 500 random coefficients
- Minimize ℓ_1 norm of wavelet coefficients



Reconstruction of Piecewise Polynomials,II

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- Randomly select 8 jump discontinuities
- Randomly select cubic polynomial in between jumps
- Observe about 200 Fourier coefficients at random



Reconstruction of Piecewise Polynomials, III



About 200 Fourier coefficients only!

Minimum TV Reconstruction

Many extensions:

 $\min_{g} \|g\|_{TV}$ s.t. $\hat{g}(\omega) = \hat{f}(\omega), \ \omega \in \Omega$



Reconstruction: min BV + nonnegativity constraint

min ℓ_2

min TV – Exact!

Other Phantoms

Classical Reconstruction



Total Variation Reconstruction

Compressible Signals

- In real life, signals are not sparse but most of them are compressible
- Compressible signals: rearrange the entries in decreasing order $|f|_{(1)}^2 \ge |f|_{(2)}^2 \ge \ldots \ge |f|_{(N)}^2$

$$\mathcal{F}_p(C) = \{f: |f|_{(n)} \leq Cn^{-1/p}, orall n\}$$

• This is what makes transform coders work (sparse coding)



Compressible Signals I: Wavelets in 1D



Compressible Signals II: Wavelets in 2D



Compressible Signals II: Curvelets



Examples of Compressible Signals

• Smooth signals. Continuous-time object has s bounded derivatives, then nth largest entry of the wavelet or Fourier coefficient sequence

• Signals with bounded variations. In 2 dimensions, the BV norm of a continuous time object is approximately

$$\|f\|_{BV} \approx \|\nabla f\|_{L_1}$$

In the wavelet domain

$$|\theta(f)|_{(n)} \leq C \cdot n^{-1}.$$

• Many other examples: e.g. Gabor atoms and certain classes of oscillatory signals, curvelets and images with edges, etc.

Nonlinear Approximation of Compressible Signals

•
$$f\in \mathcal{F}_p(C), |f|_{(n)}\leq C\cdot n^{-1/p}$$

• Keep K-largest entries in $f \to f_K$

$$\|f - f_K\| \le C \cdot K^{-r}, \quad r = 1/p - 1/2.$$

• E.g.
$$p = 1$$
, $\|f - f_K\| \le C \cdot K^{-1/2}$.

Recovery of Compressible Signals

- How many measurements to recover f to within precision $\epsilon = K^{-r}$.
- Intuition: at least *K*, probably many more.

Where Are the Largest Coefficients?



Near Optimal Recovery of Compressible Signals

• Select K Gaussian random vectors (X_k) , $k = 1, \ldots, K$

$$X_k \sim N(0, I_N)$$

- Observe $y_k = \langle f, X_k
 angle$
- Reconstruct by solving (P_1) ; minimize the ℓ_1 -norm subject to constraints.

Theorem 3 (C., Tao) Assume 0 or for <math>p = 1 that $\mathcal{F}_1(C)$ is the ℓ_1 -ball. Then with overwhelming probability

$$\sup_{\mathcal{F}_p(C)} \|f^{\#} - f\|_2 = C \cdot (K/\log N)^{-r}.$$

See also recent work by D. Donoho (2004)

Big Surprise

Want to know an object up to an error ϵ ; e.g. an object whose wavelet coefficients are sparse.

• Strategy 1: Oracle tells exactly (or you collect all N wavelet coefficients) which K coefficients are large and measure those

$$\|f - f_K\| \asymp \epsilon$$

• Strategy 2: Collect $K \log N$ random coefficients and reconstruct using ℓ_1 .

Surprising claim

- Same performance but with only $K \log N$ coefficients!
- Performance is achieved by solving an LP.

Optimality

- Can you do with fewer than $K \log N$ for accuracy K^{-r} ?
- Simple answer: NO (at least in the range K << N)

Optimality: Example

 $f\in B_1:=\{f,\,\|f\|_{\ell_1}\leq 1\}$

• Entropy numbers: for a given set $\mathcal{F} \subset \mathbb{R}^N$, we $N(\mathcal{F}, r)$ is the smallest number of Euclidean balls of radius r which cover \mathcal{F}

$$e_k = \inf\{r > 0 : N(\mathcal{F}, r) \le 2^{k-1}\}.$$

Interpretation in coding theory: to encode a signal from \mathcal{F} to within precision e_k , one would need at least k bits.

• Entropy estimates (Schütt (1984), Kühn (2001))

$$e_k symp \left(rac{\log(N/k+1)}{k}
ight)^{1/2}, \quad \log N \leq k \leq N.$$

To encode an object f in the ℓ_1 -ball to within precision $1/\sqrt{K}$ one would need to spend at least $O(K \log(N/K))$ bits. For $K \simeq N^{\beta}$, $\beta < 1$, $O(K \log N)$ bits.

Gelfand *n*-width (Optimality)

- k measurements Ff; this sets the constraint that f live on an affine space $f_0 + S$ where S is a linear subspace of co-dimension less or equal to k.
- The data available for the problem cannot distinguish any object belonging to that plane. For our problem, the data cannot distinguish between any two points in the intersection $B_1 \cap f_0 + S$. Therefore, any reconstruction procedure $f^*(y)$ based upon $y = F_\Omega f$ would obey

$$\sup_{f\in\mathcal{F}}\|f-f^*\|\geq rac{{\sf diam}(B_1\cap S)}{2}.$$

• The *Gelfand* numbers of a set \mathcal{F} are defined as

$$c_k = \inf_S \{ \sup_{f \in \mathcal{F}} \|f_{|S}\| : \operatorname{codim}(S) < k \},$$

Gelfand Width



Gelfand and entropy numbers (Optimality)

• Gelfand numbers dominate the entropy numbers (Carl, 1981)

$$\left(rac{\log N/k}{k}
ight)^{1/2} symp e_k \lessapprox c_k$$

• Therefore, for error 1/k

 $k\log N/k \lessapprox$ #meas.

• Similar argument for \mathcal{F}_p

Something Special about Gaussian Measurements?

- Works with the other measurement ensembles
- Binary ensemble: $F(k,t) = \pm 1$ with prob. 1/2

$$\sup \|f^{\sharp}-f\|_2 = C \cdot (K/\log N)^{-r}.$$

• Fourier ensemble:

$$\sup \|f^{\sharp} - f\|_2 = C \cdot (K/\log^3 N)^{-r}.$$

Restricted Isometries

• Restricted isometry constants δ_S

$$1-\delta_S \leq \|F_T^*F_T\| \leq 1+\delta_S, \quad \forall T, |T| \leq S.$$

with F_T , $K \times |T|$ matrix obtained by sampling the columns with indices in T.

• Restricted orthogonality constants

 $\langle F_T c, F_{T'}
angle \leq heta_S \cdot \|c\| \, \|c'\|$

• Observation:

$$\theta_S \le \delta_{2S} \le \theta_S + \delta_S$$

Restricted Isometries and Exact Reconstruction

$$(P_1)$$
 $f^{\sharp} = \operatorname{argmin}_{g \in \mathbf{R}^N} \|g\|_{\ell_1},$ subject to $Fg = Ff.$

Theorem 4 (C., Tao) Suppose $\delta_S + 3\theta_S < 1$. Then

$$\|f^{\sharp}-f\|=0.$$

for ALL signals supported on any set T with $|T| \leq S := K/\lambda$.

Restricted Isometries and Optimal Recovery

Theorem 5 (C., Tao) Suppose $\delta_S + 3\theta_S < 1$ and $\delta_S < 1/2$. Then

$$\sup_{f\in {\mathcal F}_p(C)} \|f-f^\sharp\| \leq C\cdot (K/\lambda)^{-r}.$$

This is a purely deterministic statement. Nothing is random here!

Uniform Uncertainty Principle

A measurement matrix F obeys the UUP with oversampling factor λ if for *all* subsets T such that $|T| \leq K/\lambda$

$$1/2 \lessapprox \lambda_{\min}(F_T^*F_T) \leq \lambda_{\max}(F_T^*F_T) \lessapprox rac{3}{2}$$



W. Heisenberg

UUP: Interpretation

- Suppose F is a partial discrete DFT, Ω set of observed frequencies: $F(k,t) = \exp(i2\pi kt/N)/\sqrt{N}$.
- Signal f with support T obeying

 $|T| \leq lpha K/\lambda$

• UUP says that with overwhelming probability

 $\|\hat{f}_{|\Omega}\| \leq \sqrt{3K/2N}\|f\|$

- No concentration is possible unless $K \asymp N$
- "Uniform" because must hold for all such T's

UUP Gives Everything!

- Exact reconstruction of all sparse signals
- Optimal recovery of all compressible signals

Examples

- Gaussian ensemble obeys UUP with oversampling factor $\log N$
- Binary ensemble obeys UUP with oversampling factor $\log N$
- Fourier ensemble obeys UUP with oversampling factor $(\log N)^3$ (essentially, Bourgain)

UUP for the Gaussian Ensemble

- $F(k,t) = X_{k,t}/\sqrt{K}$
- Singular values of random Gaussian matrices: fixed T

$$(1-\sqrt{c}) \lessapprox \sigma_{\min}(F_T) \leq \sigma_{\max}(F_T) \lessapprox (1+\sqrt{c})$$

with overwhelming probability (exceeding $1 - e^{-\beta K}$).

Reference, S. J. Szarek, Condition numbers of random matrices, *J. Complexity* (1991),

See also Ledoux (2001), Johnstone (2002), El-Karoui (2004)

- Marchenko-Pastur law: c = |T|/K.
- Union bound give result for all *T* provided

 $|T| \leq \gamma \cdot K / (\log N / K).$

Universal Codes

Want to compress sparse signals

- *Encoder*. To encode a discrete signal f, the encoder simply calculates the coefficients $y_k = \langle f, X_k \rangle$ and quantizes the vector y.
- Decoder. The decoder then receives the quantized values and reconstructs a signal by solving the linear program (P_1) .

Conjecture Asymptotically nearly achieves the information theoretic limit.

Information Theoretic Limit: Example

- Want to encode the unit- ℓ_1 ball: $f \in \mathbf{R}^N : \sum_t |f(t)| \leq 1$.
- Want to achieve distortion D

$$\|f - f^{\sharp}\|^2 \le D$$

• How many bits? Lower bounded by entropy of the unit- ℓ_1 ball:

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# bits \geq C \cdot D \cdot (\log(N/D) + 1)
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• Same as number of measured coefficients

Robustness

• Say with *K* coefficients

$$\|f-f^{\sharp}\|^2 symp 1/K$$

• Say we loose half of the bits (packet loss). How bad is the reconstruction?

$$\|f-f_{50\%}^{\sharp}\|^2 symp 2/K$$

• Democratic!



Minimize TV subject to random coefficients + ℓ_1 -norm of wavelet coefficients.







Reconstruction from 15K random coefficients



Reconstruction from 15K random coefficients



Original

With 15K



Reconstruction from 25K random coefficients



Original



Summary

- Possible to reconstruct a compressible signal from a few measurements only
- Achieved by random measurements
- Need to solve an LP
- Nearly optimal
- Many applications
 - Finding sparse decompositions
 - Decoding of random linear codes