

MGA Tutorial, September 08, 2004 Construction of Wavelets

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### Outline of talk

- Introduction .
- Building blocks:Standard sampling, Fourier and Wavelets
- Some more Fourier Analysis. Time Frequency plane
- More about building blocks: Orthonormal bases.
- The Continuous Wavelet Transform
- Discrete wavelet transform.
  - Desired properties of the wavelets.
  - Different approaches in their construction.
  - Multi-scale-analysis and bi-orthogonal bases, scaling equation
  - Lowpass, Highpass filter, Wavelet filter-tree.
- Wavelets basis in dimension 2.

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- Wavelet packets filter-tree and wavelet packets library.
- Cost functions, Best basis and adaptiveness.
- Interpolets and sparse sampling in high dimension.



Introduction

Wavelets= small packet of waves Theory of wavelet offspring from:

- Mathematics: Fourier analysis / Harmonic analysis
- Signal processing: Quadratic mirror filter

Wavelet theory 1985-



Example data on a Music CD: Use blackboard



Expansion of functions in trigonometric series by



Jean Baptiste Joseph Fourier (1768 - 1830) around 1807

.....but



use of approximation by trigonometric functions was used earlier by



Leonard Euler(1707-1783)

.....but



Daniel Bernuolli(1700 - 1783). "He showed that the movements of strings of musical instruments are composed of and infinite number of harmonic vibrations all superimposed on the string." (late 1720th)



# Building blocks of a signal

- Sampling of a signal: representation in standard basis
- Frequency description of the signal Fourier basis
- Wavelets an compromise between those two extremes.



Time - frequency plane

# $|f(t)|^2 / ||f|^2$

is the density distribution of function in time.

 $|\hat{f}(\omega)|^2/\|\hat{f}|^2$ 

is the density distribution of function in frequency. We will look at the product as a density distribution in the Time-Frequency plane.



Standard sampling and Fourier representation in TF- plane


#### Standard sampling

Fourier representation



Heisenberg uncertainty principle:

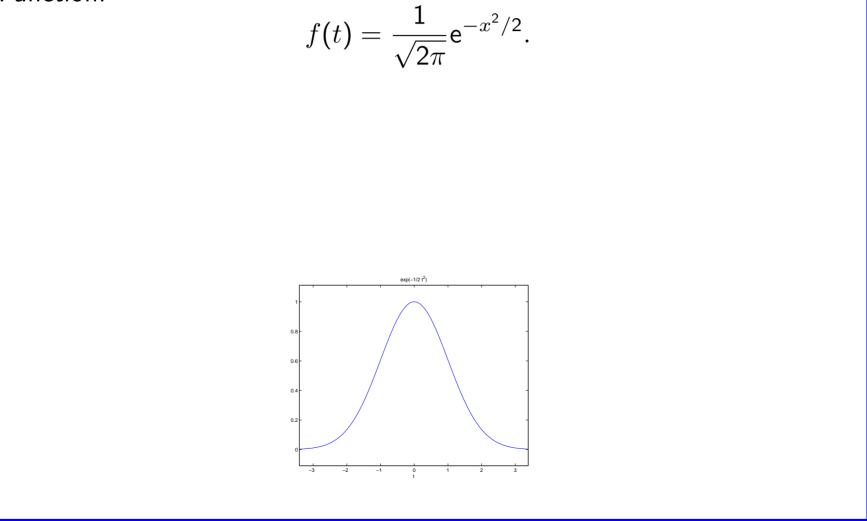
(Assume f is normalized: ||f|| = 1.)

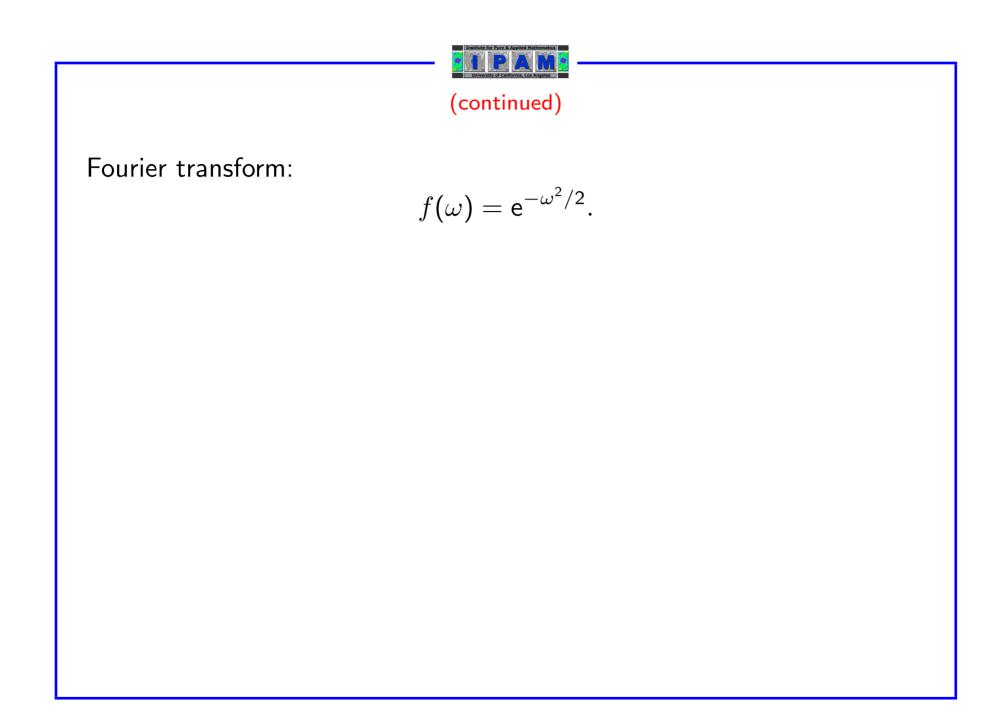
 $Var(function time)*Var(function frequency) \ge Constant$ 



Minimum for Gaussian function (Normal distribution)

Function:



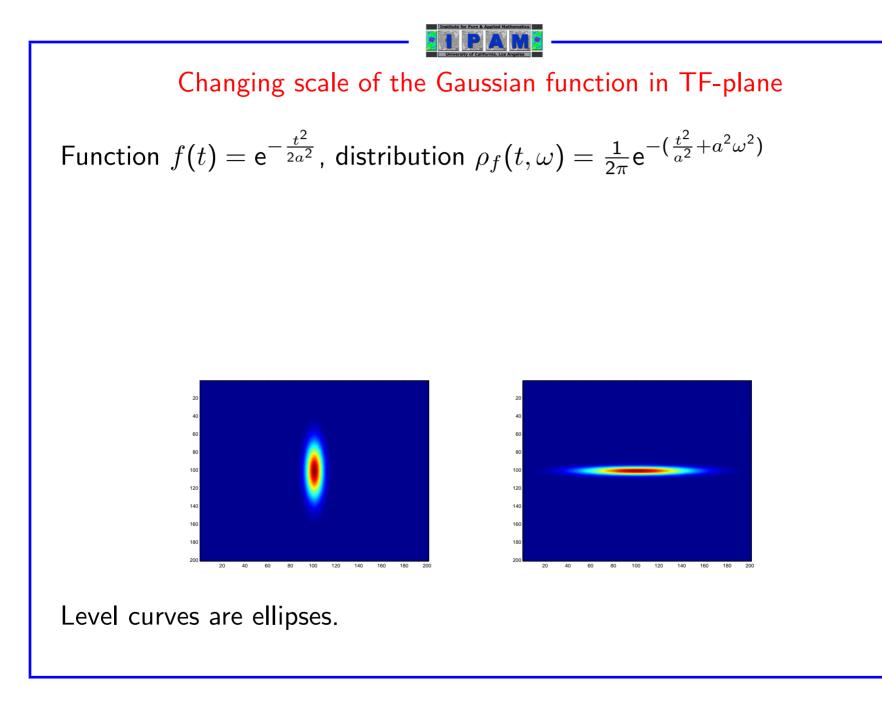


# Institute for Pure & Applied Mathematics Image: Constraint of the second seco

The Gaussian function in time-frequency plane

Function  $f(t) = e^{-t^2/2}$ Distribution function on time-frequency plane:  $\rho_f(t,\omega) = \frac{1}{2\pi} \mathrm{e}^{-(t^2 + \omega^2)}$ 1. 0.8 0.6 0.4 -0.2 180 200 10 -10

Level curves are circles





Next few slides:

Some basic definitions and notations:



### Orthonormal basis

### Orthonormal family of functions

• Functions are uncorrelated: for any two different functions  $\varphi_n$  and  $\varphi_m$  in the family  $(n \neq m)$ :

$$(\varphi_n, \varphi_m) = \int \varphi_n(t) \overline{\varphi_m(t)} dt = 0.$$

 Function are normalized: any function φ<sub>n</sub> in the family has norm equal to 1:

$$\|\varphi_n\|^2 = (\varphi_n, \varphi_n) = \int \varphi_n(t) \overline{\varphi_n(t)} dt = 1.$$



#### Orthonormal basis

 An orthonormal basis for a space of functions is an orthonormal family of functions {φ<sub>n</sub>}<sub>n</sub> such that any function f in the space can be written as sum

$$f = \sum_{n} c_n \varphi_n.$$

• The constants  $c_n$  is obtained by the inner product between the the functions f and  $\varphi_n$ 

$$c_n = \int f(t) \overline{\varphi_n(t)} dt.$$



#### Bi-orthogonal basis

A family o functions {φ<sub>n</sub>}<sub>n</sub> in a space V and a family of functions {φ<sub>n</sub>}<sub>n</sub> in the dual space V are *bi-orthogonal bases* if if they are bases for V resp. V and

$$(\tilde{\varphi}_n, \varphi_m) = \int \tilde{\varphi}_n(t) \overline{\varphi_m(t)} dt \begin{cases} \neq 0 \text{ when } n = m, \\ = 0 \text{ when } n \neq m. \end{cases}$$

Then any function f in the space V can be written as sum

$$f = \sum_{n} c_n \varphi_n.$$

• The constants  $c_n$  is obtained by the inner product between the the functions f and  $\varphi_n$ 

$$c_n = (f, \tilde{\varphi}_n)/(\tilde{\varphi}_n, \varphi_n).$$



- the dual space  $\tilde{V}$  may, or may not be the same as V

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Continuous versus discreet wavelet transform

• Continuous parameter family of wavelets

$$\psi_{a,b}(t) = \frac{1}{\sqrt{b}}\psi(\frac{t-a}{b}).$$

where a and b are real parameters,  $b\neq \mathbf{0}$ 

• Orthonormal wavelet basis  $\{\psi_{kj}\}_{k,j\in\mathbf{Z}}$  where

$$\psi_{kj}(t) = 2^{\frac{j}{2}}\psi(2^j - k).$$

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#### Continuous wavelet transform

Let  $\psi$  be a function on the real line and

$$\psi_{a,b}(t) = \frac{1}{\sqrt{|b|}}\psi(\frac{t-a}{b}).$$

The wavelet let transform is defined by

$$f \rightarrow W_f(a,b) = \int f(t) \overline{\psi_{a,b}(t)} dt.$$



Inversion of the continuous wavelet transform

$$f(t)] = \frac{1}{C_{\psi}} \int \int_{\mathbf{R}x\mathbf{R}} W_f(a,b) \psi_{a,b}(t) \frac{da \, db}{a^2}.$$

In contrast to the discrete wavelet transform we don't need very special function  $\psi$ . In general we need to have  $\hat{\psi}(0) = 0$  and that

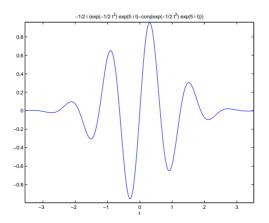
$$C_{\psi} = \int \hat{|}\psi(\omega)|^2 \frac{d\omega}{\omega} < \infty.$$

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Example: Morlet wavelets

• Real Morlet-5 wavelet:

$$\psi(t) = \sin(5t) \mathrm{e}^{-\frac{t^2}{2}}.$$





Fourier transform

$$\hat{\psi}(\omega) = \frac{1}{2i\sqrt{2\pi}} \left( \mathrm{e}^{-\frac{(\omega-5)^2}{2}} - \mathrm{e}^{-\frac{(\omega+5)^2}{2}} \right).$$

• Complex Morlet-5

$$\psi(t) = \frac{\partial}{\partial t} \mathrm{e}^{i5t} \mathrm{e}^{-\frac{t^2}{2}}.$$

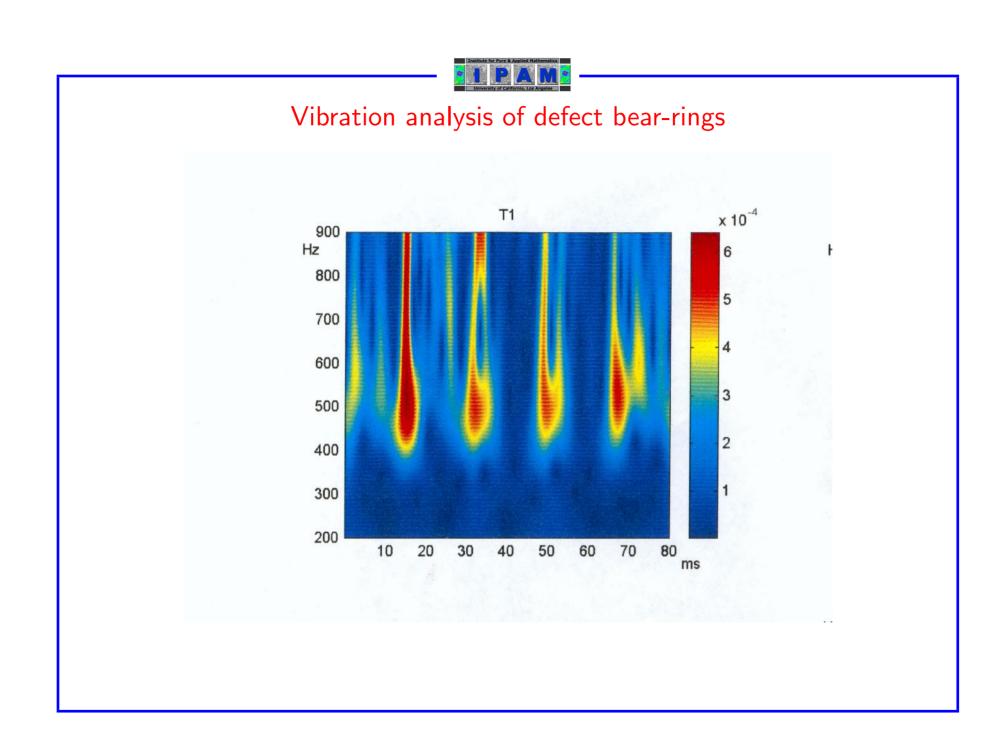
Fourier transform

$$\hat{\psi}(\omega) = i\omega \mathrm{e}^{-rac{(\omega-5)^2}{2}}$$



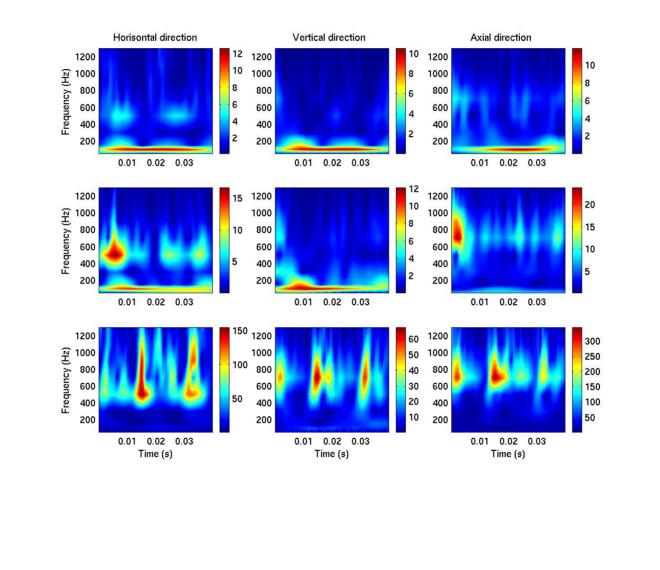
### Application of Continuous Wavelet Transform

- In general not so useful when it involves reconstruction of functions, since it is too complex.
- Good for frequence analyze of functions since it gives information booth of time and frequency of events.
- As we saw with the scaling of the Gaussian one may easily gradually change the focusing in the analysis between frequency and time.





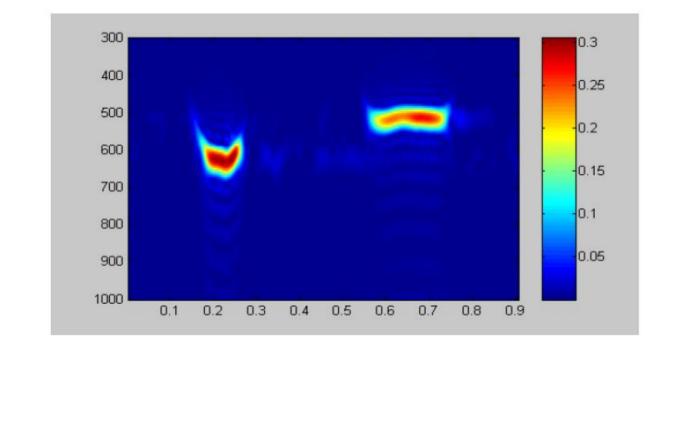
# Classification of bear-ring signals





# TF analysis of singing birds

Time-frequency analysis of "gjöken" Anne-Grete Roer, Ås Lanbruktshøyskole

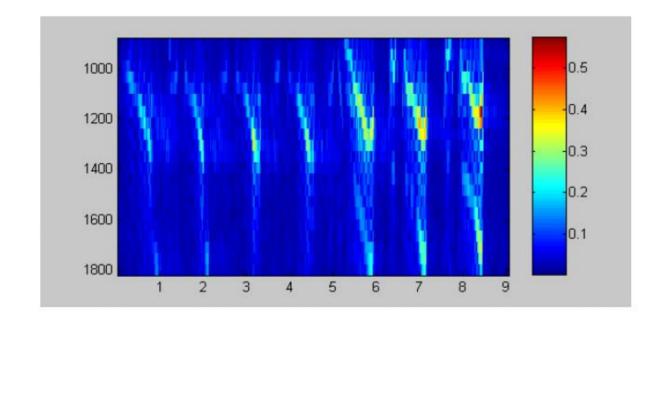




## TF analysis of singing birds (continued)

Time-frequency analysis of "storlom"

Anne-Grete Roer, Ås Lanbruktshøyskole



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#### Discrete wavelet transform

We have two parallel descriptions of the discrete wavelet transform

• By an orthonormal basis of wavelets and

$$f(t) = \sum_{kj} c_{kj} \psi_{kj}(t),$$

and the wavelet transform of  $\boldsymbol{f}$  is

$$f \rightarrow c_{kj} = \int f(t) \overline{\psi_{kj}(t)} dt.$$

 By a low-pass filter h and a high-pass filter g which are arranged in an algorithmic tree. The filter h g are such that they can make a Quadratic Mirror Filter

J.-O. Strömberg



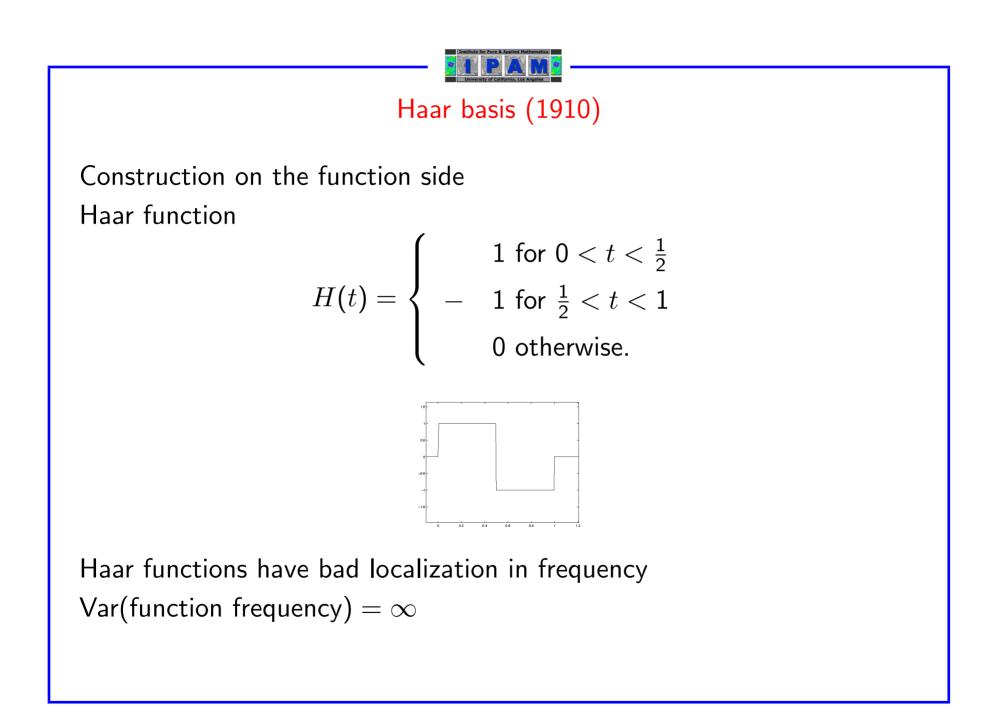
What properties do we want  $\psi$  to have

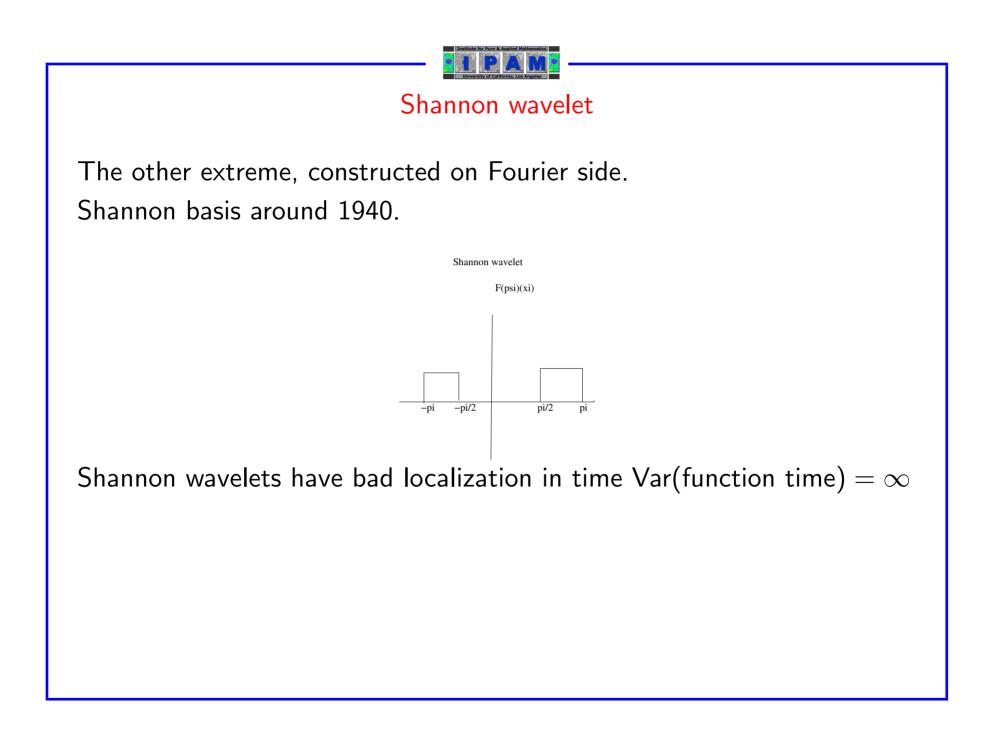
- good localization in time.
- good localization in frequency.
- vanishing moments, the more the better.
- smoothness properties
- easy to compute with as filter finite.



Three main approaches for construction

- Construction on the function side.
- Construction on the Fourier transform side.
- Construction based on construction of Quadratic Mirror filter







### Franklin system - asymptotically a wavelet

- Philip Franklin (1926):Construction of orthonormal spline system of piecewise polynomial of order *m* on a bounded interval. Away from the endpoints the function is approximatively a wavelet to any precision.
- Strömberg 1981. Transferring Franklin's construction to spline systems on the whole real line getting Franklin's asymptotic limit function as a wavelet generating an orthonormal basis. This wavelet function is exponentially decreasing.



### Wavelet theory appear

• Yves Meyer (1985): Construction a wavelet on the Fourier side

$$\hat{\psi}(\xi) = b(\xi) \mathrm{e}^{i\frac{\xi}{2}},$$

where  $b(\xi)$  an even function (the function  $\chi_{[-\pi,\pi]}$  smoothed out in a special way) This wavelet is  $C^{\infty}$  smooth, of course compactly supported Fourier transform and it decreasing polynomially of any order.

- Stephan Mallat (1986) Multi-scale analysis and construction of wavelet from Quadratic Mirror-filter.
- Ingrid Daubechies (1987): Construction of wavelets with compact support by construction wavelet filter with finite length.

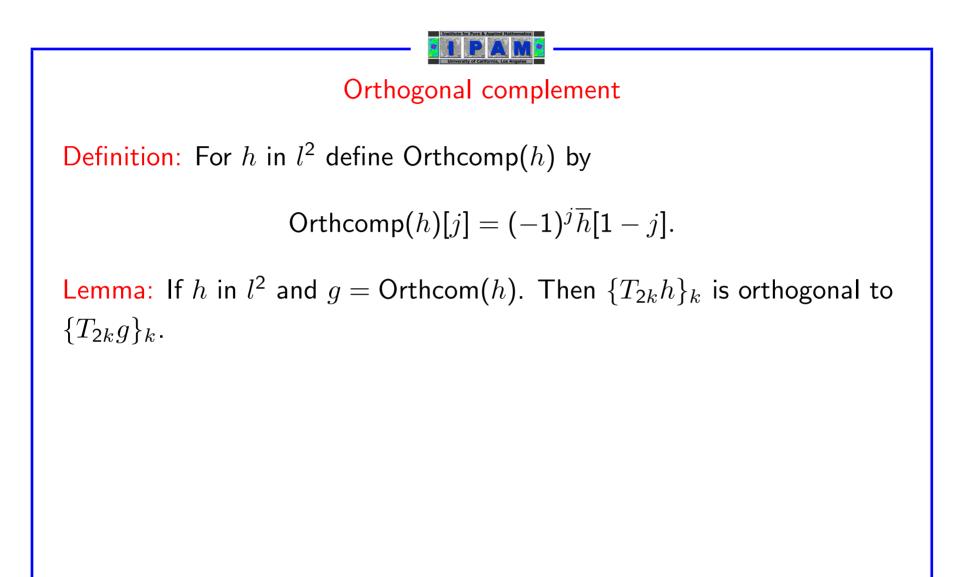


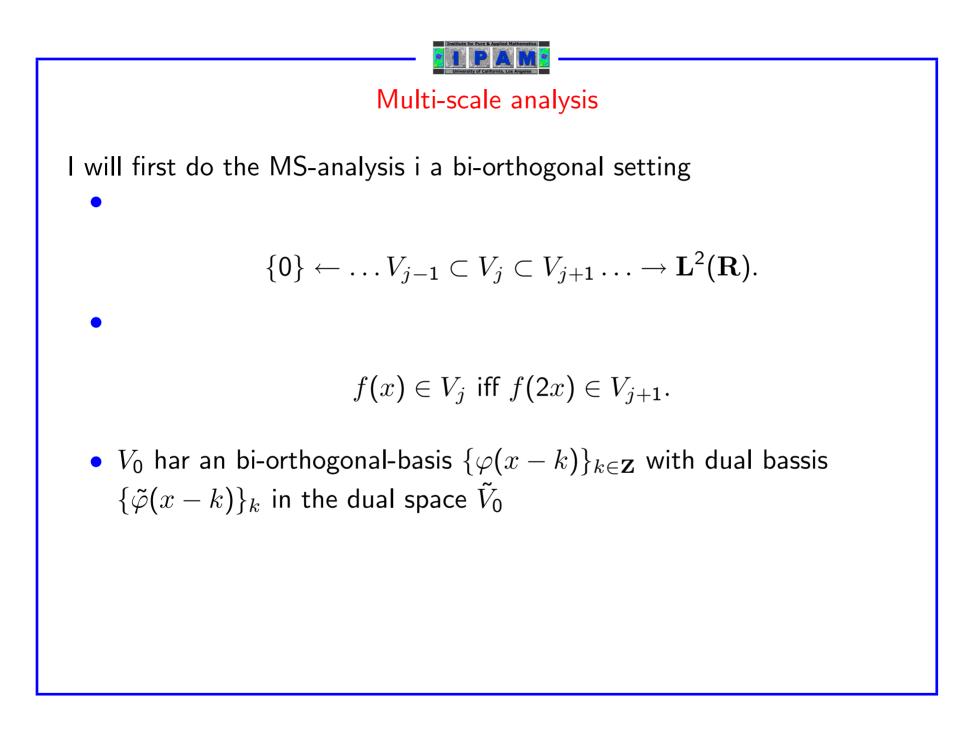
I want to go through the construction of Daubechies finite wavelet filter. I will relate the construction more to the spaces of spline function whereas Daubechies makes the construction of the filter on their Fourier transform side.

We need some more notation.

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Translation operators					

For integer k an  $f \in L^2$ :  $T_k f(x) = f(x - k).$ For integer k and  $f = \{f[j]\} \in l^2$ :  $(T_k f)[k] = f[j-k].$ Adjoint notation  $a^*[k] = \overline{a[-k]}.$ Inner product  $\langle a, T^k b \rangle = \sum_j a[j]\overline{b[j-k]} = a * b^*[k].$ 







#### Let

 $B^{(0)} = \text{Dirac delta function},$ 

$$B^{(m)}(x) = B^{(m-1)} * \chi_{[0,1]}(x),$$

For fixed m > 0 let  $\varphi_k(x) = B^{(m)}(x-k)$ .

We define  $V^{(m)_0}$  to be the closure of span $(\varphi_k)$ .  $V^{(m)_0}$  is the space of functions in  $C^{m-2}$  which are piecewise polynomial of degree less or equal to m-1 on intervals (n-1, n)



The scaling equations

$$\varphi(x) = c \sum_{k} h[k] \varphi(2x - k),$$

$$\psi(x) = c \sum_{k} g[k]\varphi(2x-k).$$

### The cascade algorithm

Take the limit  $\varphi$  (if it exist) of the sequence  $\varphi^{(m)}$  given by iteration formula

$$\varphi^{(m)}(x) = c \sum_{k} h[k] \varphi^{(m-1)}(2x-k),$$

where c is a suitable normalization constant, the starting function  $\varphi^{(0)}$  could be almost any function with  $\int \varphi dt \neq 0$ 

**Observe:** It is commutes with with convolutions:

if sequence h generates  $\varphi$  and g generates  $\psi$  with the sequence h \* g starting with  $\varphi^{(0)} * \psi^{(0)}$  the outcome of the cascade algorithm is  $\varphi * \psi$ 

$$h = [1, 1] \Rightarrow \varphi = \chi_{[0,1](x)}$$
  

$$h = [1, 1]^2 = [1, 2, 1] \Rightarrow \text{ linear box-spline } B^{(2)}(x)$$
  

$$h = [1, 1]^4 = [1, 4, 6, 4, 1, ] \Rightarrow \text{ cubic box-spline } B^4(x),$$
  
and so on  

$$h = [1, 1]^m = \Rightarrow m \text{ order box-spline } B^{(m)}(x)$$



### Decomposition of $V_0$

Suppose that the space  $V_0$  has a bi-orthogonal basis  $\{\varphi^1(x-k)\}$  with dual functions  $\{\tilde{\varphi}^1(x-k)\}$  in the dual space  $\tilde{V}_0$ 

We will find a complement  $W_{-1}$  of  $V_{-1}$  in the space  $V_0$ 

- with a bi-orthogonal basis  $\{\varphi(x-2k)\}$  of  $V_{-1}$  with dual functions  $\{\tilde{\varphi}(x-2k)\}$  in a dual space  $\tilde{V}_{-1}$
- with a bi-orthogonal basis  $\{\psi(x-2k)\}$  of  $W_{-1}$  with dual functions  $\{\tilde{\psi}(x-2k)\}$  in a dual space  $\tilde{W}_{-1}$
- and where the functions  $\{\varphi(x-2k)\} \cup \{\psi(x-2k)\}$  is an



bi-orthogonal basis of  $V_0$  with dual basis  $\{ ilde{arphi}(x-2k)\} \cup \{ ilde{\psi}(x-2k)\}$  in  $ilde{V}_0$ 

Transferring the problem to  $l^2$ .

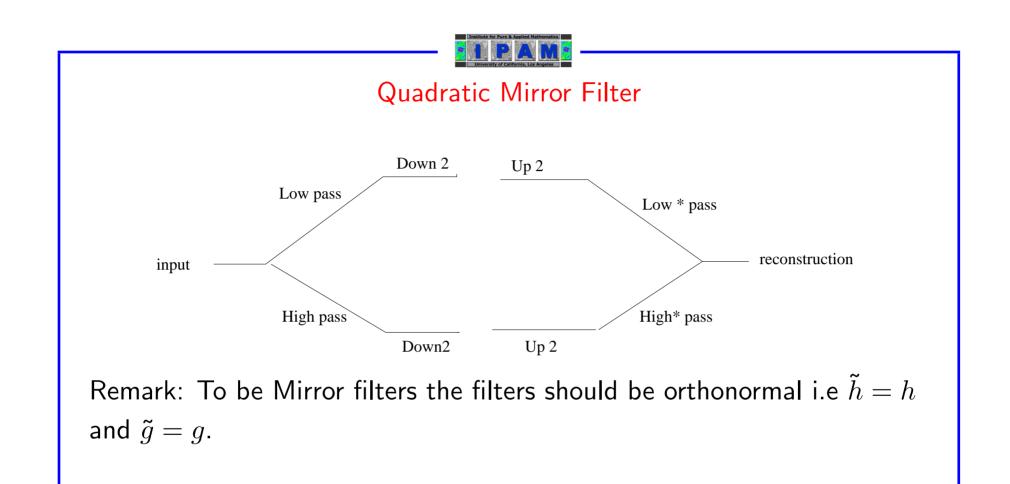
Using the bases of  $V_1$  and  $\tilde{V}_1$  we can transfer to the similar problem where  $V_0$  is a subset of  $V_1 = l^2$  and  $\tilde{V}_1 = l^2$ . Observe: It might happen that the dual space  $V_0$  and  $\tilde{V}_0$  may be

different spaces and also that  $W_0$  and  $\tilde{W}_0$  are different spaces

### Basis representation and filters

(Assuming we have normalized so that  $< \varphi, \tilde{\varphi} > = < \psi, \tilde{\psi} > = 1$ ) we have the representation of function  $f \in V_0$ 

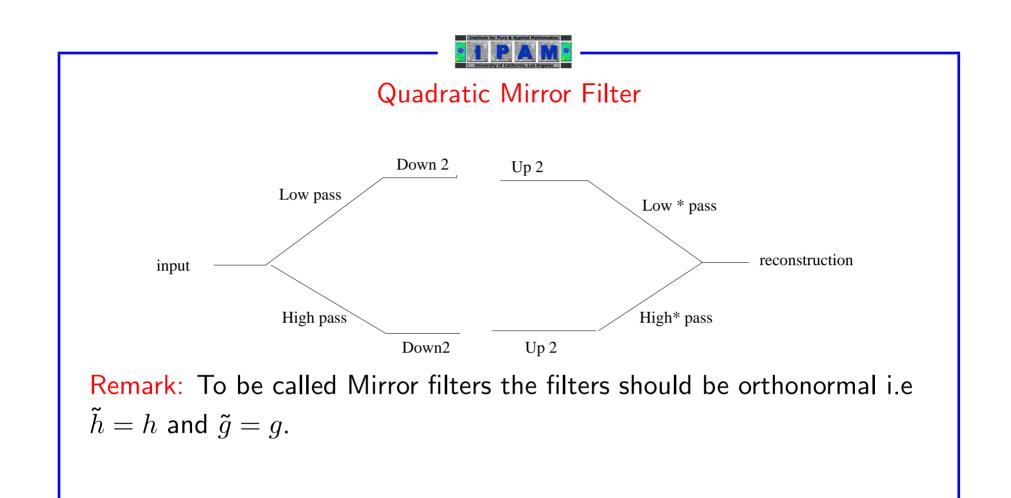
$$f(x) = \sum_{k} \langle f, T^{2k} \tilde{\varphi} \rangle T^{2k} \varphi(x) + \sum_{k} \langle f, T^{2k} \tilde{\psi} \rangle T^{2k} \psi(x).$$



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- When m is even will find the bi-orthogonal filters: h with dual h for V<sub>-1</sub> bi-orthogonal. V<sub>0</sub>
   g with dual g for W<sub>-1</sub> respectively. W<sub>0</sub>
- (Assuming we have normalized the filter such that  $< h, \tilde{h}> = < g, \tilde{g}> = 1$  we have for data set  $f \in l^2$

$$f[j] = \sum_{k} \langle f, T^{2k}\tilde{h} \rangle T^{2k}h[j] + \sum_{k} \langle f, T^{2k}g \rangle T^{2k}g[j].$$



- Filter  $h = [1, 1]^m$  is given from the scaling equations.
- Filter  $\tilde{g} = \text{Orthcomp}(h)$ .
- Once filter  $\tilde{h}$  is known we set  $g = \text{Orthcomp}(\tilde{h})$ .
- h has length m+1 we will find  $\tilde{h}$  of length m-1 by straightforward orthogonalization in  $\mathbb{R}^{m-1}$  against restriction of  $T^{2k}h$  to  $\mathbb{R}^{m-1}$ .
- Example:

When m = 2  $h = [1, 1]^2 = [1, 2, 1] \Rightarrow \tilde{h} = [1].$ When m = 4 $h = [1, 1]^2 = [1, 4, 6, 4, 1] \Rightarrow \tilde{h} = [-1, 4, -1].$ 

When m = 6

$$h = [1, 1]^6 = [1, 6, 15, 20, 15, 6, 1] \Rightarrow \tilde{h} = [3, -18, 38, -18, 3].$$

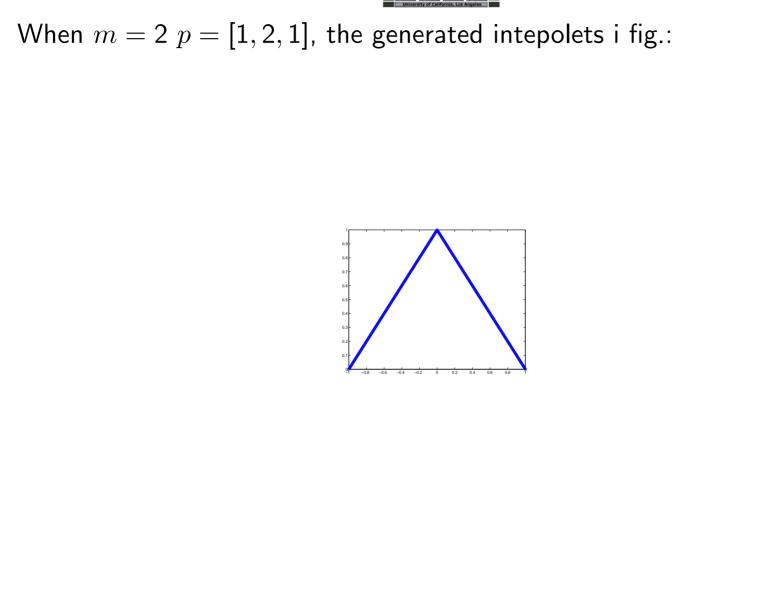


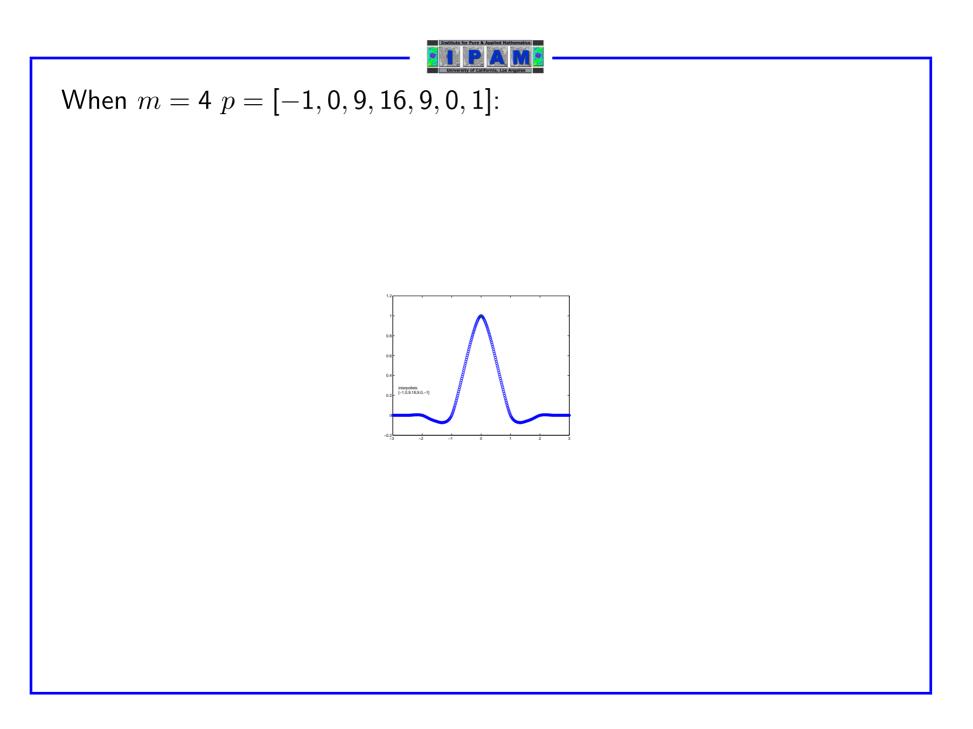
interpolets

The product  $p = h * (\tilde{h})^*$  will be an interpolation filter which will generate what may be called interpolets. Delaurier & Dubuc 1989.

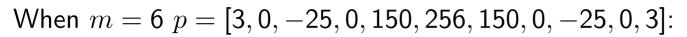
 $q = g * (\tilde{g})^*$  will be a "difference filter" and q = Orthcomp(p). The interpolating filter will be:

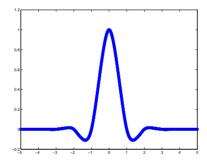














### Factorization of the interpolation filter

- The filter p can be split up into factors that can be combined in many ways.
- For instance it may be written an autocorrelation filter

$$p = a * a^*,$$

which means that  $\tilde{a} = a$  , i.e a is is an orthonormal filter.

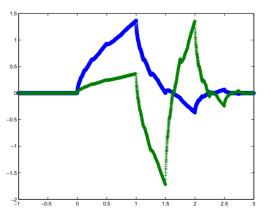
• If we starting the cascade algorithm with something orthonormal as the Box-splines of order m = 1, then outcome will be a scaling function  $\varphi$  and a wavelet function  $\psi$  that generates an orthonormal wavelet.



When m = 2 we get the Haar filters [1, 1] and [1, -1].

When m = 4 we get Daubechies filters of length 4, the corresponding generated functions are in figure:

blue is wavelets and green is wavelets





### When m = 6 we get Daubechies filters of length 6

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short about the desired properties of constructed wavelets

 in general the factor [1, 1] implies in good properties of the wavelets it generates on the Fourier transform a sinc factor (decays like |ξ|<sup>-1</sup>) and the other factor coming from the dual filter, kind of destroys some of these properties, but those factors are needed to obtain orthonormality.

The [1,1] factors win: the longer filter the smoother wavelets

 the factors [1, -1] in the ğ filter creates moments. The other factors (those from g) cannot destroy it, so the number of vanishing moments of the wavelet ψ is directly proportional to the length of the orthogonal wavelet filter.

### Moment conditions on wavelet function

**Lemma** Given the function  $\varphi$  satisfying:

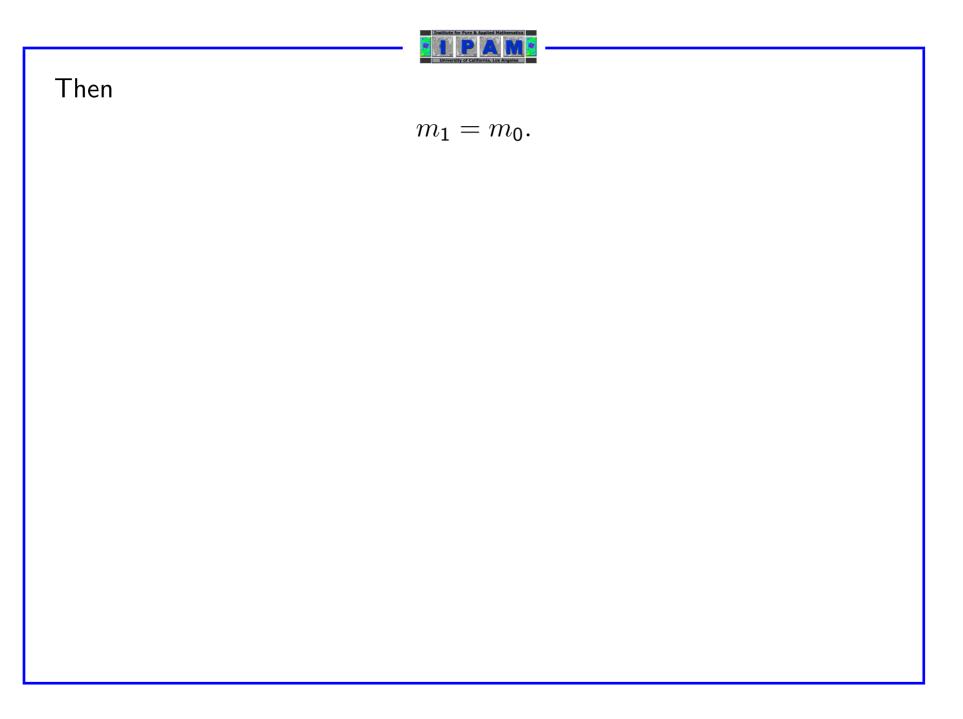
$$\int \varphi(x) ds \neq \mathbf{0},$$

and the filter h and define the function  $\phi$  by

$$\phi = \sum h_k \varphi_k.$$

Let  $m_0$ , and  $m_1$  be the order of moment condition of the filter h and of the function  $\phi$  in other words:

$$\sum h_k k^l \left\{ egin{array}{ll} = 0, & l < m_0, \ 
eq 0, & l = m_0 \end{array} 
ight.$$
 $\int \phi(x) x^l dx \left\{ egin{array}{ll} = 0, & l < m_2, \ 
eq 0, & l = m_1 \end{array} 
ight.$ 





### Estimate of wavelet coefficients

Let f be a m times continuous differentiable function on the line and assume that  $\phi$  satisfies all moment condition up to order m then

$$| < f, \psi_{kj} > | \le O(2^{-j(m+\frac{1}{2})}).$$



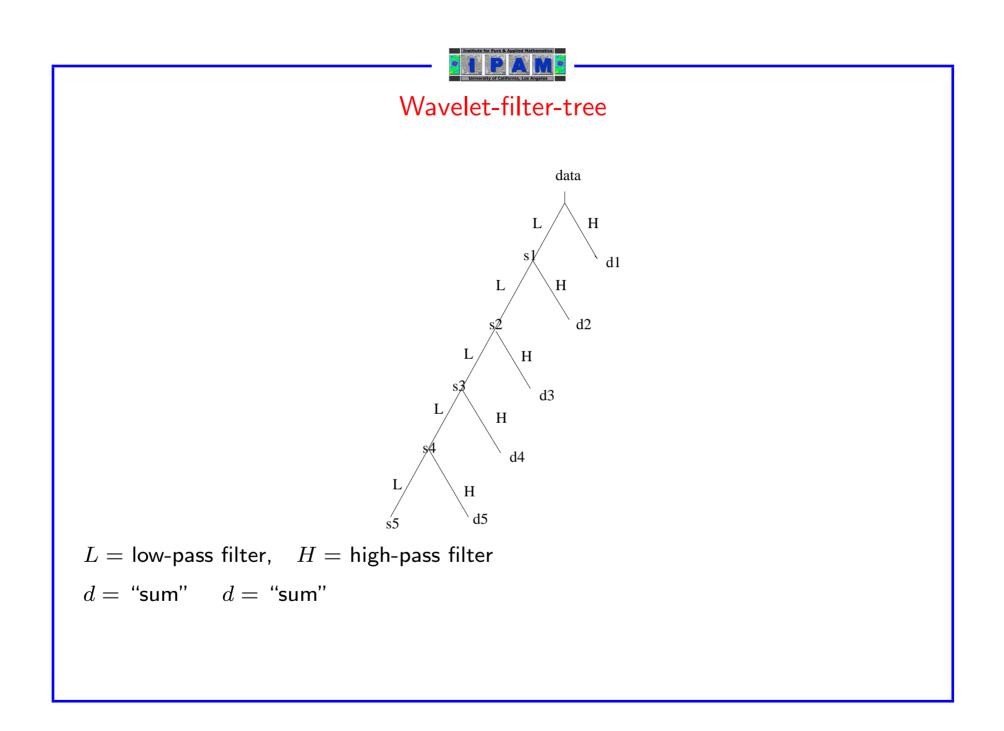
### Wavelet basis in dimension 2

Corresponding to the wavelet functions  $\{\psi_{k,j}\}$  are the three sets of tensor functions

 $\{\varphi_{kj}(x)\psi_{lj}(y) >\}_{k,l,j\in Z},$  $\{\psi_{kj}(x)\varphi_{lj}(y) >\}_{k,l,j\in Z},$  $\{\psi_{kj}(x)\psi_{lj}(y) >\}_{k,l,j\in Z},$ 

and corresponding to the scaling functions  $\{\varphi_{k,j}\}$  are the functions

 $\{\varphi_{kj}(x)\varphi_{lj}(y)\}_{k,l,j\in\mathbb{Z}}.$ 





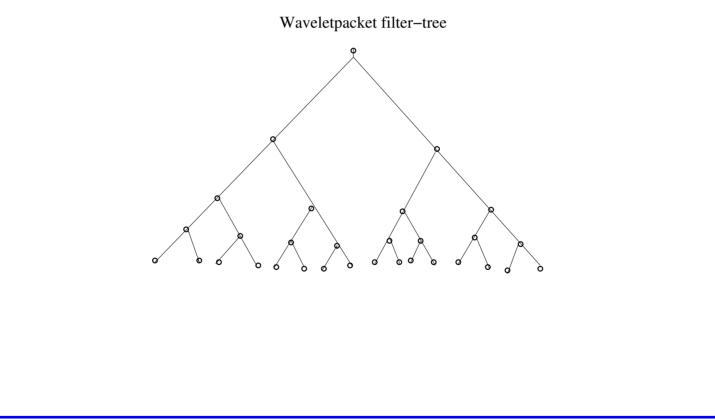
Applications of discrete wavelet transform

• Image processing, noise reduction of signals



#### Wavelet packets

We extend the wavelet-filter-tree to the full tree. With data of size  $N = 2^M$  there will be M + 1 levels in the tree including the top.(Top node=input data).





wavelet packets (continued)

- There will be totally (M + 1)N different coefficients -including the N input data values.
- Each combination of stopping at nodes in the tree corresponds to an Orthonormal basis. There will be about 1.45<sup>N</sup> different families of orthonormal bases.
- All coefficients may be computed with complexity MN



• Assume we have a linear cost function about how good a basis is. Linear means for each basis B

$$Cost_B = \sum_{c_n \in B} Cost(c_n).$$

- There is an algorithm choosing the **best basis** *B* in the libraries of all those bases obtained from different combination of nodes.
- In the best basis we chose a few (< 10) most significant coefficients.
- The complexity the algorithm is of order MN