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## Construction of Wavelets

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- Introduction .
- Building blocks:Standard sampling, Fourier and Wavelets
- Some more Fourier Analysis. Time - Frequency plane
- More about building blocks: Orthonormal bases.
- The Continuous Wavelet Transform
- Discrete wavelet transform.
- Desired properties of the wavelets.
- Different approaches in their construction.
- Multi-scale-analysis and bi-orthogonal bases, scaling equation
- Lowpass, Highpass filter, Wavelet filter-tree.
- Wavelets basis in dimension 2 .
- Wavelet packets filter-tree and wavelet packets library.
- Cost functions, Best basis and adaptiveness.
- Interpolets and sparse sampling in high dimension.

Wavelets= small packet of waves
Theory of wavelet offspring from:

- Mathematics: Fourier analysis / Harmonic analysis
- Signal processing: Quadratic mirror filter

Wavelet theory 1985-

## Example data on a Music CD: Use blackboard



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use of approximation by trigonometric functions was used earlier by
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Leonard Euler(1707-1783)
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...... . but



Daniel Bernuolli(1700-1783). "He showed that the movements of strings of musical instruments are composed of and infinite number of harmonic vibrations all superimposed on the string." (late 1720th)

## Building blocks of a signal

- Sampling of a signal: representation in standard basis
- Frequency description of the signal

Fourier basis

- Wavelets an compromise between those two extremes.


## Time - frequency plane

$$
|f(t)|^{2} / \|\left. f\right|^{2}
$$

is the density distribution of function in time.

$$
|\hat{f}(\omega)|^{2} / \|\left.\hat{f}\right|^{2}
$$

is the density distribution of function in frequency.
We will look at the product as a density distribution in the Time-Frequency plane.

Standard sampling and Fourier representation in TF- plane


Standard sampling


Fourier representation

## Heisenberg uncertainty principle:

(Assume $f$ is normalized: $\|f\|=1$.)
$\operatorname{Var}($ function time $) * \operatorname{Var}$ (function frequency) $\geq$ Constant

## Minimum for Gaussian function (Normal distribution)

Function:

$$
f(t)=\frac{1}{\sqrt{2 \pi}} \mathrm{e}^{-x^{2} / 2}
$$



Fourier transform:

$$
f(\omega)=\mathrm{e}^{-\omega^{2} / 2} .
$$

## The Gaussian function in time-frequency plane

Function $f(t)=\mathrm{e}^{-t^{2} / 2}$
Distribution function on time-frequency plane:

$$
\rho_{f}(t, \omega)=\frac{1}{2 \pi} \mathrm{e}^{-\left(t^{2}+\omega^{2}\right)}
$$



Level curves are circles

## Changing scale of the Gaussian function in TF-plane

Function $f(t)=\mathrm{e}^{-\frac{t^{2}}{2 a^{2}}}$, distribution $\rho_{f}(t, \omega)=\frac{1}{2 \pi} \mathrm{e}^{-\left(\frac{t^{2}}{a^{2}}+a^{2} \omega^{2}\right)}$



Level curves are ellipses.

Next few slides:
Some basic definitions and notations:


## Orthonormal basis

## Orthonormal family of functions

- Functions are uncorrelated: for any two different functions $\varphi_{n}$ and $\varphi_{m}$ in the family $(n \neq m)$ :

$$
\left(\varphi_{n}, \varphi_{m}\right)=\int \varphi_{n}(t) \overline{\varphi_{m}(t)} d t=0
$$

- Function are normalized: any function $\varphi_{n}$ in the family has norm equal to 1 :

$$
\left\|\varphi_{n}\right\|^{2}=\left(\varphi_{n}, \varphi_{n}\right)=\int \varphi_{n}(t) \overline{\varphi_{n}(t)} d t=1
$$



## Orthonormal basis

- An orthonormal basis for a space of functions is an orthonormal family of functions $\left\{\varphi_{n}\right\}_{n}$ such that any function $f$ in the space can be written as sum

$$
f=\sum_{n} c_{n} \varphi_{n} .
$$

- The constants $c_{n}$ is obtained by the inner product between the the functions $f$ and $\varphi_{n}$

$$
c_{n}=\int f(t) \overline{\varphi_{n}(t)} d t
$$

## Bi-orthogonal basis

- A family o functions $\left\{\varphi_{n}\right\}_{n}$ in a space $V$ and a family of functions $\left\{\tilde{\varphi}_{n}\right\}_{n}$ in the dual space $\tilde{V}$ are bi-orthogonal bases if if they are bases for $V$ resp. $\tilde{V}$ and

$$
\left(\tilde{\varphi}_{n}, \varphi_{m}\right)=\int \tilde{\varphi}_{n}(t) \overline{\varphi_{m}(t)} d t\left\{\begin{array}{l}
\neq 0 \text { when } n=m \\
=0 \text { when } n \neq m
\end{array}\right.
$$

Then any function $f$ in the space $V$ can be written as sum

$$
f=\sum_{n} c_{n} \varphi_{n} .
$$

- The constants $c_{n}$ is obtained by the inner product between the the functions $f$ and $\varphi_{n}$

$$
c_{n}=\left(f, \tilde{\varphi}_{n}\right) /\left(\tilde{\varphi}_{n}, \varphi_{n}\right) .
$$

- the dual space $\tilde{V}$ may, or may not be the same as $V$


## Continuous versus discreet wavelet transform

- Continuous parameter family of wavelets

$$
\psi_{a, b}(t)=\frac{1}{\sqrt{b}} \psi\left(\frac{t-a}{b}\right)
$$

where $a$ and $b$ are real parameters, $b \neq 0$

- Orthonormal wavelet basis $\left\{\psi_{k j}\right\}_{k, j \in \mathbf{Z}}$ where

$$
\psi_{k j}(t)=2^{\frac{j}{2}} \psi\left(2^{j}-k\right) .
$$

## Continuous wavelet transform

Let $\psi$ be a function on the real line and

$$
\psi_{a, b}(t)=\frac{1}{\sqrt{|b|}} \psi\left(\frac{t-a}{b}\right)
$$

The wavelet let transform is defined by

$$
f \quad \rightarrow \quad W_{f}(a, b)=\int f(t) \overline{\psi_{a, b}(t)} d t
$$

Inversion of the continuous wavelet transform

$$
f(t)]=\frac{1}{C_{\psi}} \iint_{\mathbf{R} x \mathbf{R}} W_{f}(a, b) \psi_{a, b}(t) \frac{d a d b}{a^{2}} .
$$

In contrast to the discrete wavelet transform we don't need very special function $\psi$. In general we need to have $\hat{\psi}(0)=0$ and that

$$
C_{\psi}=\left.\int \hat{\mid} \psi(\omega)\right|^{2} \frac{d \omega}{\omega}<\infty .
$$

## Example: Morlet wavelets

- Real Morlet-5 wavelet:

$$
\psi(t)=\sin (5 t) \mathrm{e}^{-\frac{t^{2}}{2}} .
$$



Fourier transform

$$
\hat{\psi}(\omega)=\frac{1}{2 i \sqrt{2 \pi}}\left(\mathrm{e}^{-\frac{(\omega-5)^{2}}{2}}-\mathrm{e}^{-\frac{(\omega+5)^{2}}{2}}\right) .
$$

- Complex Morlet-5

$$
\psi(t)=\frac{\partial}{\partial t} e^{i 5 t} \mathrm{e}^{-\frac{t^{2}}{2}} .
$$

Fourier transform

$$
\hat{\psi}(\omega)=i \omega \mathrm{e}^{-\frac{(\omega-5)^{2}}{2}}
$$

## Application of Continuous Wavelet Transform

- In general not so useful when it involves reconstruction of functions, since it is too complex.
- Good for frequence analyze of functions since it gives information booth of time and frequency of events.
- As we saw with the scaling of the Gaussian one may easily gradually change the focusing in the analysis between frequency and time.



## Classification of bear-ring signals



## IPAME

## TF analysis of singing birds

Time-frequency andysis of "giöken"
Ahne-Grete Roer,
As Lanbruktshoyskole



## Discrete wavelet transform

We have two parallel descriptions of the discrete wavelet transform

- By an orthonormal basis of wavelets and

$$
f(t)=\sum_{k j} c_{k j} \psi_{k j}(t)
$$

and the wavelet transform of $f$ is

$$
f \quad \rightarrow \quad c_{k j}=\int f(t) \overline{\psi_{k j}(t)} d t
$$

- By a low-pass filter $\mathbf{h}$ and a high-pass filter $\mathbf{g}$ which are arranged in an algorithmic tree. The filter $h g$ are such that they can make a Quadratic Mirror Filter


## What properties do we want $\psi$ to have

- good localization in time.
- good localization in frequency.
- vanishing moments, the more the better.
- smoothness properties
- easy to compute with - as filter finite.


## Three main approaches for construction

- Construction on the function side.
- Construction on the Fourier transform side.
- Construction based on construction of Quadratic Mirror filter


## Haar basis (1910)

Construction on the function side Haar function

$$
H(t)=\left\{\begin{array}{l}
1 \text { for } 0<t<\frac{1}{2} \\
-\quad 1 \text { for } \frac{1}{2}<t<1 \\
0 \text { otherwise } .
\end{array}\right.
$$



Haar functions have bad localization in frequency $\operatorname{Var}($ function frequency $)=\infty$

## Shannon wavelet

The other extreme, constructed on Fourier side.
Shannon basis around 1940.


Shannon wavelets have bad localization in time $\operatorname{Var}($ function time $)=\infty$

## Franklin system - asymptotically a wavelet

- Philip Franklin (1926):Construction of orthonormal spline system of piecewise polynomial of order $m$ on a bounded interval. Away from the endpoints the function is approximatively a wavelet to any precision.
- Strömberg 1981. Transferring Franklin's construction to spline systems on the whole real line getting Franklin's asymptotic limit function as a wavelet generating an orthonormal basis. This wavelet function is exponentially decreasing.



## Wavelet theory appear

- Yves Meyer (1985): Construction a wavelet on the Fourier side

$$
\hat{\psi}(\xi)=b(\xi) \mathrm{e}^{i \frac{\xi}{2}}
$$

where $b(\xi)$ an even function (the function $\chi_{[-\pi, \pi]}$ smoothed out in a special way) This wavelet is $C^{\infty}$ smooth, of course compactly supported Fourier transform and it decreasing polynomially of any order.

- Stephan Mallat (1986) Multi-scale analysis and construction of wavelet from Quadratic Mirror-filter.
- Ingrid Daubechies (1987): Construction of wavelets with compact support by construction wavelet filter with finite length.

I want to go through the construction of Daubechies finite wavelet filter.
I will relate the construction more to the spaces of spline function whereas Daubechies makes the construction of the filter on their Fourier transform side.

We need some more notation.

## Translation operators

For integer $k$ an $f \in L^{2}$ :

$$
T_{k} f(x)=f(x-k) .
$$

For integer $k$ and $f=\{f[j]\} \in l^{2}$ :

$$
\left(T_{k} f\right)[k]=f[j-k] .
$$

Adjoint notation

$$
a^{*}[k]=\overline{a[-k]} .
$$

Inner product
$<a, T^{k} b>=\sum_{j} a[j] \overline{b[j-k]}=a * b^{*}[k]$.

## Orthogonal complement

Definition: For $h$ in $l^{2}$ define $\operatorname{Orthcomp}(h)$ by

$$
\operatorname{Orthcomp}(h)[j]=(-1)^{j} \bar{h}[1-j] .
$$

Lemma: If $h$ in $l^{2}$ and $g=\operatorname{Orthcom}(h)$. Then $\left\{T_{2 k} h\right\}_{k}$ is orthogonal to $\left\{T_{2 k} g\right\}_{k}$.

## Multi-scale analysis

I will first do the MS-analysis i a bi-orthogonal setting

$$
\{0\} \leftarrow \ldots V_{j-1} \subset V_{j} \subset V_{j+1} \ldots \rightarrow \mathbf{L}^{2}(\mathbf{R}) .
$$

$$
f(x) \in V_{j} \text { iff } f(2 x) \in V_{j+1} .
$$

- $V_{0}$ har an bi-orthogonal-basis $\{\varphi(x-k)\}_{k \in \mathbf{Z}}$ with dual bassis $\{\tilde{\varphi}(x-k)\}_{k}$ in the dual space $\tilde{V}_{0}$


## Box spline function

Let

$$
\begin{gathered}
B^{(0)}=\text { Dirac delta function } \\
B^{(m)}(x)=B^{(m-1)} * \chi_{[0,1]}(x)
\end{gathered}
$$

For fixed $m>0$ let $\varphi_{k}(x)=B^{(m)}(x-k)$.

We define $V^{(m)_{0}}$ to be the closure of $\operatorname{span}\left(\varphi_{k}\right)$. $V^{(m)_{0}}$ is the space of functions in $C^{m-2}$ which are piecewise polynomial of degree less or equal to $m-1$ on intervals $(n-1, n)$

## The scaling equations

$$
\begin{aligned}
& \varphi(x)=c \sum_{k} h[k] \varphi(2 x-k), \\
& \psi(x)=c \sum_{k} g[k] \varphi(2 x-k)
\end{aligned}
$$

## The cascade algorithm

Take the limit $\varphi$ (if it exist) of the sequence $\varphi^{(m)}$ given by iteration formula

$$
\varphi^{(m)}(x)=c \sum_{k} h[k] \varphi^{(m-1)}(2 x-k)
$$

where $c$ is a suitable normalization constant, the starting function $\varphi^{(0)}$ could be almost any function with $\int \varphi d t \neq 0$

Observe: It is commutes with with convolutions:
if sequence $h$ generates $\varphi$ and $g$ generates $\psi$ with the sequence $h * g$ starting with $\varphi^{(0)} * \psi^{(0)}$ the outcome of the cascade algorithm is $\varphi * \psi$
$h=[1,1] \Rightarrow \varphi=\chi_{[0,1](x)}$
$h=[1,1]^{2}=[1,2,1] \Rightarrow$ linear box-spline $B^{(2)}(x)$
$h=[1,1]^{4}=[1,4,6,4,1,] \Rightarrow$ cubic box-spline $B^{4}(x)$,
and so on
$h=[1,1]^{m}=\Rightarrow m$ order box-spline $B^{(m)}(x)$

## Decomposition of $V_{0}$

Suppose that the space $V_{0}$ has a bi-orthogonal basis $\left\{\varphi^{1}(x-k)\right\}$ with dual functions $\left\{\tilde{\varphi}^{1}(x-k)\right\}$ in the dual space $\tilde{V}_{0}$

We will find a complement $W_{-1}$ of $V_{-1}$ in the space $V_{0}$

- with a bi-orthogonal basis $\{\varphi(x-2 k)\}$ of $V_{-1}$ with dual functions $\{\tilde{\varphi}(x-2 k)\}$ in a dual space $\tilde{V}_{-1}$
- with a bi-orthogonal basis $\{\psi(x-2 k)\}$ of $W_{-1}$ with dual functions $\{\tilde{\psi}(x-2 k)\}$ in a dual space $\tilde{W}_{-1}$
- and where the functions $\{\varphi(x-2 k)\} \cup\{\psi(x-2 k)\}$ is an
bi-orthogonal basis of $V_{0}$ with dual basis $\{\tilde{\varphi}(x-2 k)\} \cup\{\tilde{\psi}(x-2 k)\}$ in $\tilde{V}_{0}$


## Transferring the problem to $l^{2}$.

Using the bases of $V_{1}$ and $\tilde{V}_{1}$ we can transfer to the similar problem where $V_{0}$ is a subset of $V_{1}=l^{2}$ and $\tilde{V}_{1}=l^{2}$.
Observe: It might happen that the dual space $V_{0}$ and $\tilde{V}_{0}$ may be different spaces and also that $W_{0}$ and $\tilde{W}_{0}$ are different spaces

## Basis representation and filters

(Assuming we have normalized so that $\langle\varphi, \tilde{\varphi}\rangle=\langle\psi, \tilde{\psi}\rangle=1$ ) we have the representation of function $f \in V_{0}$

$$
f(x)=\sum_{k}<f, T^{2 k} \tilde{\varphi}>T^{2 k} \varphi(x) \quad+\quad \sum_{k}<f, T^{2 k} \tilde{\psi}>T^{2 k} \psi(x) .
$$



Remark: To be Mirror filters the filters should be orthonormal i.e $\tilde{h}=h$ and $\tilde{g}=g$.

- When $m$ is even will find the bi-orthogonal filters: $h$ with dual $\tilde{h}$ for $V_{-1}$ bi-orthogonal. $\tilde{V}_{0}$ $g$ with dual $\tilde{g}$ for $W_{-1}$ respectively. $\tilde{W}_{0}$
- (Assuming we have normalized the filter such that $<h, \tilde{h}\rangle=<g, \tilde{g}>=1$ we have for data set $f \in l^{2}$

$$
f[j]=\sum_{k}<f, T^{2 k} \tilde{h}>T^{2 k} h[j]+\sum_{k}<f, T^{2 k} g>T^{2 k} g[j] .
$$



Remark: To be called Mirror filters the filters should be orthonormal i.e $\tilde{h}=h$ and $\tilde{g}=g$.

- Filter $h=[1,1]^{m}$ is given from the scaling equations.
- Filter $\tilde{g}=\operatorname{Orthcomp}(h)$.
- Once filter $\tilde{h}$ is known we set $g=\operatorname{Orthcomp}(\tilde{h})$.
- $h$ has length $m+1$ we will find $\tilde{h}$ of length $m-1$ by straightforward orthogonalization in $\mathbf{R}^{m-1}$ against restriction of $T^{2 k} h$ to $\mathbf{R}^{m-1}$.
- Example:

When $m=2$

$$
h=[1,1]^{2}=[1,2,1] \Rightarrow \tilde{h}=[1] .
$$

When $m=4$

$$
h=[1,1]^{2}=[1,4,6,4,1] \Rightarrow \tilde{h}=[-1,4,-1] .
$$

When $m=6$

$$
h=[1,1]^{6}=[1,6,15,20,15,6,1] \Rightarrow \tilde{h}=[3,-18,38,-18,3] .
$$



The product $p=h *(\tilde{h})^{*}$ will be an interpolation filter which will generate what may be called interpolets.
Delaurier \& Dubuc 1989.
$q=g *(\tilde{g})^{*}$ will be a "difference filter" and $q=\operatorname{Orthcomp}(p)$.
The interpolating filter will be:

When $m=2 p=[1,2,1]$, the generated intepolets i fig.:


When $m=4 p=[-1,0,9,16,9,0,1]$ :


When $m=6 p=[3,0,-25,0,150,256,150,0,-25,0,3]$ :


## Factorization of the interpolation filter

- The filter $p$ can be split up into factors that can be combined in many ways.
- For instance it may be written an autocorrelation filter

$$
p=a * a^{*}
$$

which means that $\tilde{a}=a$, i.e $a$ is is an orthonormal filter.

- If we starting the cascade algorithm with something orthonormal as the Box-splines of order $m=1$, then outcome will be a scaling function $\varphi$ and a wavelet function $\psi$ that generates an orthonormal wavelet.

When $m=2$ we get the Haar filters $[1,1]$ and $[1,-1]$.
When $m=4$ we get Daubechies filters of length 4, the corresponding generated functions are in figure: blue is wavelets and green is wavelets


When $m=6$ we get Daubechies filters of length 6

## short about the desired properties of constructed wavelets

- in general the factor $[1,1]$ implies in good properties of the wavelets it generates on the Fourier transform a sinc factor ( decays like $|\xi|^{-1}$ ) and the other factor coming from the dual filter, kind of destroys some of these properties, but those factors are needed to obtain orthonormality.
The $[1,1]$ factors win: the longer filter the smoother wavelets
- the factors $[1,-1]$ in the $\tilde{g}$ filter creates moments. The other factors (those from $g$ ) cannot destroy it, so the number of vanishing moments of the wavelet $\psi$ is directly proportional to the length of the orthogonal wavelet filter.


## Moment conditions on wavelet function

Lemma Given the function $\varphi$ satisfying:

$$
\int \varphi(x) d s \neq 0
$$

and the filter $h$ and define the function $\phi$ by

$$
\phi=\sum h_{k} \varphi_{k} .
$$

Let $m_{0}$, and $m_{1}$ be the order of moment condition of the filter $h$ and of the function $\phi$ in other words:

$$
\begin{gathered}
\sum h_{k} k^{l}\left\{\begin{array}{cc}
=0, & l<m_{0} \\
\neq 0, & l=m_{0}
\end{array}\right. \\
\int \phi(x) x^{l} d x \begin{cases}=0, & l<m_{2} \\
\neq 0, & l=m_{1}\end{cases}
\end{gathered}
$$

## - Instutue for Pure a apolied Mathemotics

Then
$m_{1}=m_{0}$.


## Estimate of wavelet coefficients

Let $f$ be a $m$ times continuous differentiable function on the line and assume that $\phi$ satisfies all moment condition up to order $m$ then

$$
\left|<f, \psi_{k j}>\right| \leq O\left(2^{-j\left(m+\frac{1}{2}\right)}\right) .
$$

## Wavelet basis in dimension 2

Corresponding to the wavelet functions $\left\{\psi_{k, j}\right\}$ are the three sets of tensor functions

$$
\begin{aligned}
& \left\{\varphi_{k j}(x) \psi_{l j}(y)>\right\}_{k, l, j \in Z}, \\
& \left\{\psi_{k j}(x) \varphi_{l j}(y)>\right\}_{k, l, j \in Z}, \\
& \left\{\psi_{k j}(x) \psi_{l j}(y)>\right\}_{k, l, j \in Z},
\end{aligned}
$$

and corresponding to the scaling functions $\left\{\varphi_{k, j}\right\}$ are the functions

$$
\left\{\varphi_{k j}(x) \varphi_{l j}(y)>\right\}_{k, l, j \in Z} .
$$



## Applications of discrete wavelet transform

- Image processing, noise reduction of signals


## Wavelet packets

We extend the wavelet-filter-tree to the full tree. With data of size $N=2^{M}$ there will be $M+1$ levels in the tree including the top.(Top node=input data).


## 1PAM <br> wavelet packets (continued)

- There will be totally $(M+1) N$ different coefficients -including the $N$ input data values.
- Each combination of stopping at nodes in the tree corresponds to an Orthonormal basis. There will be about $1.45^{N}$ different families of orthonormal bases.
- All coefficients may be computed with complexity $M N$

- Assume we have a linear cost function about how good a basis is. Linear means for each basis $B$

$$
\operatorname{Cost}_{B}=\sum_{c_{n} \in B} \operatorname{Cost}\left(c_{n}\right)
$$

- There is an algorithm choosing the best basis $B$ in the libraries of all those bases obtained from different combination of nodes.
- In the best basis we chose a few $(<10)$ most significant coefficients.
- The complexity the algorithm is of order $M N$

