

# Three-way decomposition of the Boltzmann distribution function

Sergej Rjasanow  
University of Saarland, Germany

April 16, 2009



# Plan of the talk

- Boltzmann equation
- Motivation
- Three Way Decomposition
- Adaptive Cross Approximation
- Numerical examples



# Plan of the talk

- Boltzmann equation
- Motivation
- Three Way Decomposition
- Adaptive Cross Approximation
- Numerical examples



# Plan of the talk

- Boltzmann equation
- Motivation
- Three Way Decomposition
- Adaptive Cross Approximation
- Numerical examples



# Plan of the talk

- Boltzmann equation
- Motivation
- Three Way Decomposition
- Adaptive Cross Approximation
- Numerical examples



# Plan of the talk

- Boltzmann equation
- Motivation
- Three Way Decomposition
- Adaptive Cross Approximation
- Numerical examples



# Plan of the talk

- Boltzmann equation
- Motivation
- Three Way Decomposition
- Adaptive Cross Approximation
- Numerical examples



# Boltzmann equation

L. Boltzmann, 1844-1906



Boltzmann equation

$$f_t + (\nu, \operatorname{grad}_x f) = \frac{1}{Kn} Q(f, f)$$

Distribution function

$$f = f(t, x, \nu), \quad t \geq 0, \quad x \in \Omega \subset \mathbb{R}^3, \quad \nu \in \mathbb{R}^3$$

Collision integral

$$Q(f, f) = \int_{\mathbb{R}^3} \int_{S^2} B(\nu, w, e) \left( f(\nu') f(w') - f(\nu) f(w) \right) dw de$$

$$\nu' = \frac{1}{2} \left( \nu + w + |\nu - w| e \right), \quad w' = \frac{1}{2} \left( \nu + w - |\nu - w| e \right)$$

# Boltzmann equation

## Collision kernels

### Inverse power potentials

$$B(v, w, e) = B(|u|, \mu) = |u|^{1-4/m} g_m(\mu), \quad m > 1, \quad u = v - w$$

### Maxwell pseudo-molecules

$$B(|u|, \mu) = g_4(\mu)$$

### Variable Hard Spheres model

$$B(|u|, \mu) = C_\lambda |u|^\lambda, \quad -3 < \lambda \leq 1$$

### Hard spheres model

$$B(|u|, \mu) = \frac{d^2}{4} |u|$$

# Boltzmann equation

## Macroscopic quantities

density

$$\rho(t, x) = \int_{\mathbb{R}^3} f(t, x, v) dv$$

momentum

$$m(t, x) = \int_{\mathbb{R}^3} v f(t, x, v) dv$$

flow of momentum

$$M(t, x) = \int_{\mathbb{R}^3} v v^\top f(t, x, v) dv$$

flow of energy

$$r(t, x) = \frac{1}{2} \int_{\mathbb{R}^3} v |v|^2 f(t, x, v) dv$$

# Motivation

Gain term of the collision integral

$$Q_+(f, f)(v) = \int_{\mathbb{R}^3} \int_{S^2} B(v, w, e) f(v') f(w') de dw$$

Discretisation of the  $v$ -space

$$Q_n = \{v_k = V + h_v k, h_v > 0, -n/2 + 1 \leq k_j \leq n/2, j = 1, 2, 3\}$$

Numerical work for

$$Q_+(f, f)(v_k) \approx \sum_{l \in Q_n} \sum_{m \in ??} B(v_k, w_l, e_m) f(v') f(w')$$

is of the order  $O(n^8)$



## Choise of $e_m$

$$k' = \frac{1}{2} (k + l + |k - l|e_m), \quad l' = \frac{1}{2} (k + l - |k - l|e_m)$$

or

$$k' + l' = k + l, \quad k' - l' = m \text{ with } m : |m|^2 = |k - l|^2, \quad e_m = m/|m|$$

Find all solutions  $m_1, m_2, m_3 \in \mathbb{Z}$  of the equation

$$m_1^2 + m_2^2 + m_3^2 = K \in \mathbb{N}$$

## Additive number theory

- $K = 4^j(8j + 7)$  - no solutions
- $K = 4^j j$  - finite number of solutions
- else - the number of solutions is  $O(K^{1/2-\varepsilon})$

# Motivation

Choise of  $e_m$

$$k' = \frac{1}{2} (k + l + |k - l|e_m), \quad l' = \frac{1}{2} (k + l - |k - l|e_m)$$

or

$$k' + l' = k + l, \quad k' - l' = m \text{ with } m : |m|^2 = |k - l|^2, \quad e_m = m/|m|$$

Find all solutions  $m_1, m_2, m_3 \in \mathbb{Z}$  of the equation

$$m_1^2 + m_2^2 + m_3^2 = K \in \mathbb{N}$$

Additive number theory

- $K = 4^j(8j + 7)$  - no solutions
- $K = 4^j j$  - finite number of solutions
- else - the number of solutions is  $O(K^{1/2-\varepsilon})$

# Motivation

Choise of  $e_m$

$$k' = \frac{1}{2} (k + l + |k - l|e_m), \quad l' = \frac{1}{2} (k + l - |k - l|e_m)$$

or

$$k' + l' = k + l, \quad k' - l' = m \text{ with } m : |m|^2 = |k - l|^2, \quad e_m = m/|m|$$

Find all solutions  $m_1, m_2, m_3 \in \mathbb{Z}$  of the equation

$$m_1^2 + m_2^2 + m_3^2 = K \in \mathbb{N}$$

Additive number theory

- $K = 4^j(8j + 7)$  - no solutions
- $K = 4^j j$  - finite number of solutions
- else - the number of solutions is  $O(K^{1/2-\varepsilon})$

Choise of  $e_m$

$$k' = \frac{1}{2} (k + l + |k - l|e_m), \quad l' = \frac{1}{2} (k + l - |k - l|e_m)$$

or

$$k' + l' = k + l, \quad k' - l' = m \text{ with } m : |m|^2 = |k - l|^2, \quad e_m = m/|m|$$

Find all solutions  $m_1, m_2, m_3 \in \mathbb{Z}$  of the equation

$$m_1^2 + m_2^2 + m_3^2 = K \in \mathbb{N}$$

Additive number theory

- $K = 4^j(8j + 7)$  - no solutions
- $K = 4^j j$  - finite number of solutions
- else - the number of solutions is  $O(K^{1/2-\varepsilon})$

## Example

$$f_0(v) = \frac{1}{2(2\pi)^{3/2}} \left( e^{-\frac{|v - (2, 2, 0)^\top|^2}{2}} + e^{-\frac{|v + (-2, 0, 0)^\top|^2}{2}} \right)$$

Exact evolution of the moments

$$M(t) = \begin{pmatrix} 5 & -2 & 0 \\ -2 & 3 & 0 \\ 0 & 0 & 1 \end{pmatrix} e^{-t/2} + \frac{1}{3} \begin{pmatrix} 8 & 0 & 0 \\ 0 & 11 & 0 \\ 0 & 0 & 8 \end{pmatrix} (1 - e^{-t/2})$$

$$r(t) = \begin{pmatrix} -4 \\ 13 \\ 0 \end{pmatrix} e^{-t/3} + \frac{1}{3} \begin{pmatrix} 0 \\ 43 \\ 0 \end{pmatrix} (1 - e^{-t/3}) - \frac{1}{3} \begin{pmatrix} 12 \\ 4 \\ 0 \end{pmatrix} (e^{-t/2} - e^{-t/3})$$

# Motivation

Memory, numerical work and the (formal) accuracy

$$Mem = O(n^3), \quad Op = O(n^7), \quad Acc = O(n^{-1/2})$$

$n$	$M_{11}$	$M_{22}$
4	0.19921	0.19847
8	0.04685	0.09627
16	0.03640	0.08599
32	0.02478	0.06289
64	0.01853	0.04698

A. Bobylev, Rja. 1997

# Motivation

## Boltzmann collision operator

$$Q_+(f, f)(v) = \mathcal{F}_{y \rightarrow v} \left[ \int_{\mathbb{R}^3} T(u, y) \mathcal{F}_{z \rightarrow y}^{-1} [f(z-u)f(z+u)](u, y) du \right](v)$$

$$T(u, y) = 8 \int_{S^2} B(2|u|, \mu) e^{-\imath |u|(y, e)} de$$

Memory, numerical work and the formal accuracy

$$\text{Mem} = O(n^4), \quad \text{Op} = 15n^6 \ln(n) + O(n^6), \quad \text{Acc} = O(n^{-2})$$

VHS-model with  $B(|u|, \mu) = C_\lambda |u|^\lambda$

$$T(u, y) = 2^{5+\lambda} \pi C_\lambda |u|^\lambda \operatorname{sinc}(|u| |y|)$$

numerical work  $\text{Op} = n^6/8 + 315/32n^5 \ln(n)$



## Numerical accuracy

for  $M_{11}$

$n$	$m$	error	factor
8	16	0.06785	-
16	32	0.00466	14.5
32	64	0.00135	3.5
64	128	0.00032	4.2

$n$	$m$	error	factor
12	24	0.06590	-
24	48	0.00248	26.5
48	96	0.00059	4.2
96	192	0.00014	4.2



## Numerical accuracy

for  $r_2$

$n$	$m$	error	factor
8	16	0.14164	-
16	32	0.00232	61.1
32	64	0.00077	3.0
64	128	0.00018	4.3

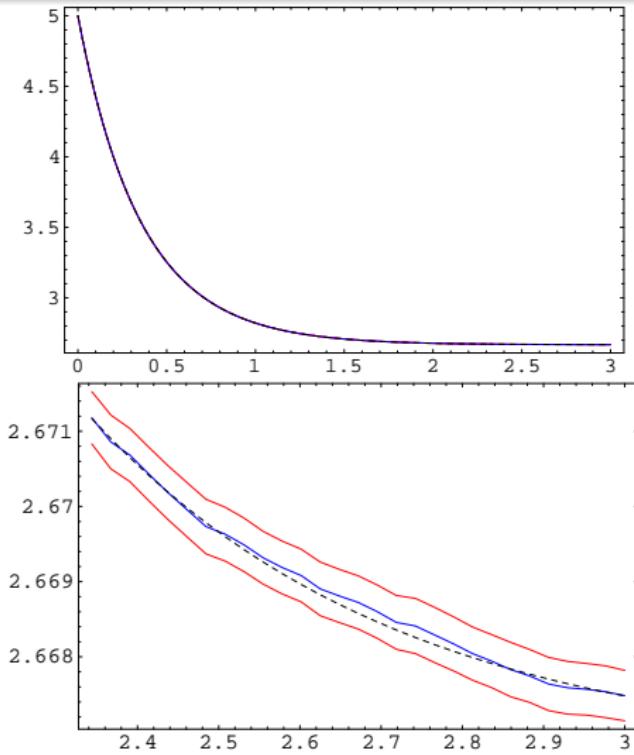
$n$	$m$	error	factor
12	24	0.15667	-
24	48	0.00137	114
48	96	0.00033	4.1
96	192	0.00008	4.1

I. Ibragimov, Rja. 2002



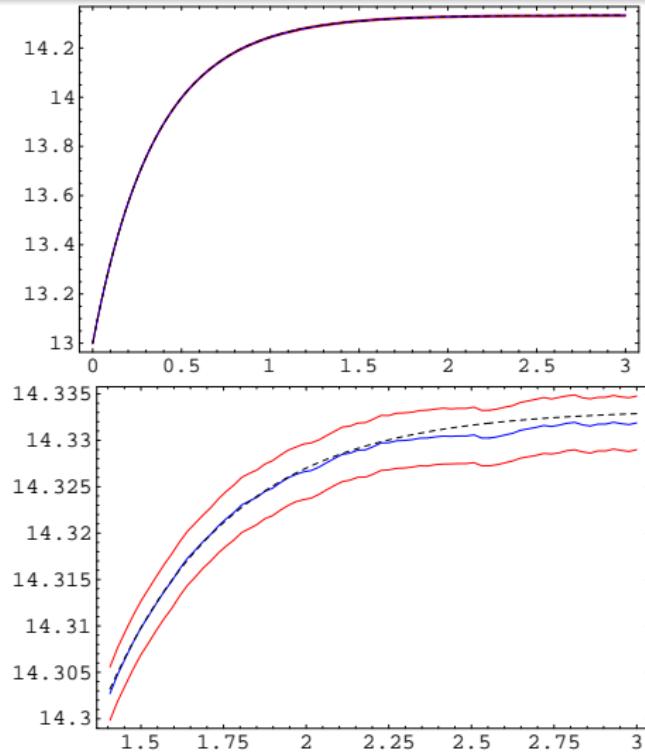
# Hard spheres model

## relaxation of $M_{11}$



# Hard spheres model

## relaxation of $r_2$



# Motivation

## Degenerated Function

$$f(t, v) = \sum_{k=1}^{r(t)} \beta_k(t) \prod_{\ell=1}^3 f_k^{(\ell)}(t, v^{(\ell)}) , \quad v = (v^{(1)}, v^{(2)}, v^{(3)})^\top$$

## Discretisation

$$F(t) = \left( f_j(t) \right)_{j \in C_n}, \quad f_j(t) = \sum_{k=1}^{r(t)} \beta_k(t) \prod_{\ell=1}^3 f_k^{(\ell)}(t, v_j^{(\ell)}) , \quad j \in C_n$$

## Memory requirements, FFT

$$\text{Mem} = \mathcal{O}(n), \quad \text{Op}(FFT) : 125n^3 \ln n \longrightarrow 15 r n \ln n$$

$$\text{Low Rank Tensor } \|F - F_\varepsilon\|_F \leq \varepsilon \|F\|_F, \quad \|F\|_F = \sqrt{\sum_{j \in C_n} (f_j)^2}$$

# Motivation

## Maxwell Distribution, $r = 1$

$$f_M(v) = \rho_0 \prod_{\ell=1}^3 \frac{1}{(2\pi T_0)^{1/2}} e^{-\frac{(v^{(\ell)} - V_0^{(\ell)})^2}{2T_0}}$$

## BKW Solution, $r = 3$

$$f(t, v) = \frac{\rho_0}{(2\pi T_0)^{3/2}} (\beta(t) + 1)^{3/2} \left( 1 + \beta(t) \left( \frac{\beta(t) + 1}{2T_0} |v|^2 - \frac{3}{2} \right) \right) e^{-\frac{\beta(t) + 1}{2T_0} |v|^2}$$

with

$$\beta(t) = \frac{\beta_0 e^{-\rho_0 t/6}}{1 + \beta_0 (1 - e^{-\rho_0 t/6})}$$

# Motivation

## Maxwell Distribution, $r = 1$

$$f_M(v) = \rho_0 \prod_{\ell=1}^3 \frac{1}{(2\pi T_0)^{1/2}} e^{-\frac{(v^{(\ell)} - V_0^{(\ell)})^2}{2T_0}}$$

## BKW Solution, $r = 3$

$$f(t, v) = \frac{\rho_0}{(2\pi T_0)^{3/2}} (\beta(t) + 1)^{3/2} \left( 1 + \beta(t) \left( \frac{\beta(t) + 1}{2 T_0} |v|^2 - \frac{3}{2} \right) \right) e^{-\frac{\beta(t) + 1}{2 T_0} |v|^2}$$

with

$$\beta(t) = \frac{\beta_0 e^{-\rho_0 t/6}}{1 + \beta_0 (1 - e^{-\rho_0 t/6})}$$

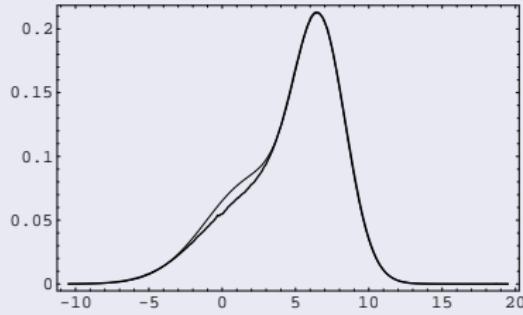
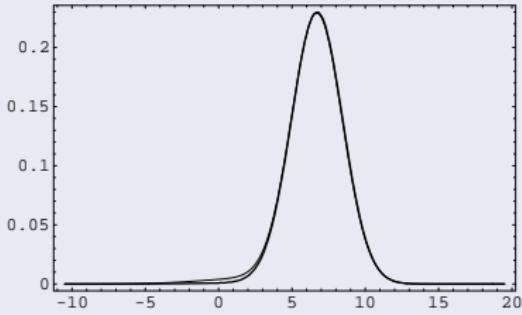
# Motivation

Mott-Smith model,  $r = 2$

$$f_{MS}(x, v) = a(x) f_{M_-}(v) + (1 - a(x)) f_{M_+}(v), \quad 0 \leq a(x) \leq 1, \quad x \in \mathbb{R}$$

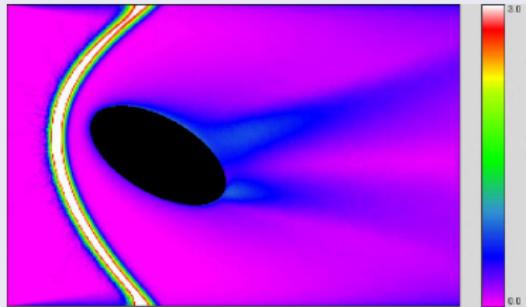
with

$$a(x) = \frac{e^{\beta(x-x_0)}}{1 + e^{\beta(x-x_0)}}, \quad x \in \mathbb{R}$$

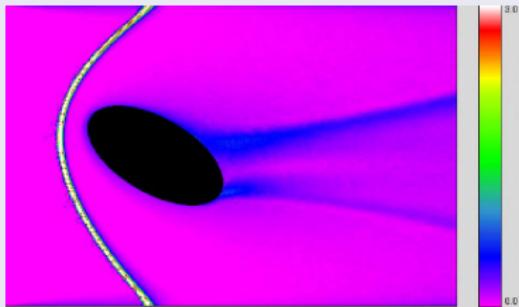


# Motivation

## Criterion of local equilibrium



$$Kn = 0.08$$



$$Kn = 0.02$$

with

$$Crit = \frac{1}{\varrho T} \left( \frac{1}{2} \|P - p I\|_F^2 + \frac{2}{5 T} |q|^2 + \frac{1}{120 T^2} \gamma^2 \right)^{1/2}$$

$$f(v) \approx f_M(v) \left( 1 + a + (b, v) + (Cv, v) + (d, v)|v|^2 + e|v|^4 \right)$$

# Adaptive Cross Approximation

Approximation of the function  $K(x, y)$

$$X = \{x_1, \dots, x_n\}, \quad Y = \{y_1, \dots, y_m\}$$

with

$$K(x, y) = \sum_{k=1}^r u_k(x)v_k(y) + R_r(x, y), \quad r = r(\varepsilon)$$

Approximation of the matrix  $A \in \mathbb{R}^{n \times m}$

$$a_{ij} = K(x_i, y_j)$$

with

$$\tilde{A} = \sum_{k=1}^r u_k v_k^\top, \quad u_k \in \mathbb{R}^n, \quad v_k \in \mathbb{R}^m$$

Accuracy, Memory

$$A \approx \tilde{A}, \quad \|A - \tilde{A}\|_F \leq \varepsilon \|A\|_F, \quad \text{Mem}(\tilde{A}) : O(nm) \rightarrow O(n+m)$$



# Adaptive Cross Approximation

Approximation of the function  $K(x, y)$

$$X = \{x_1, \dots, x_n\}, \quad Y = \{y_1, \dots, y_m\}$$

with

$$K(x, y) = \sum_{k=1}^r u_k(x)v_k(y) + R_r(x, y), \quad r = r(\varepsilon)$$

Approximation of the matrix  $A \in \mathbb{R}^{n \times m}$

$$a_{ij} = K(x_i, y_j)$$

with

$$\tilde{A} = \sum_{k=1}^r u_k v_k^\top, \quad u_k \in \mathbb{R}^n, \quad v_k \in \mathbb{R}^m$$

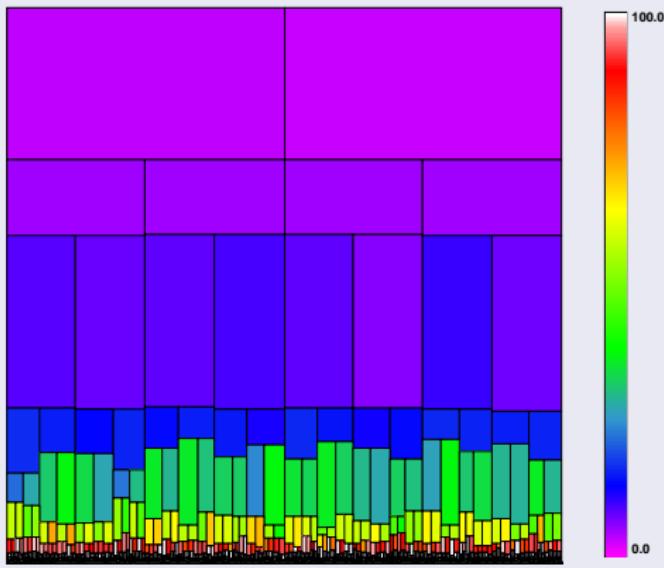
Accuracy, Memory

$$A \approx \tilde{A}, \quad \|A - \tilde{A}\|_F \leq \varepsilon \|A\|_F, \quad \text{Mem}(\tilde{A}) : O(nm) \rightarrow O(n+m)$$



# Adaptive Cross Approximation

## Approximation of blocks



# Adaptive Cross Approximation

## Full pivoted ACA

$$R_0 = A, \quad S_0 = 0$$

for  $k = 0, 1, 2, \dots$

$$i_{k+1}, j_{k+1} = \arg \max_{i,j} |(R_k)_{i,j}|$$

$$R_{k+1} = R_k - \gamma_{k+1} (R_k e_{j_{k+1}})(e_{i_{k+1}}^T R_k)$$

$$S_{k+1} = S_k + \gamma_{k+1} (R_k e_{j_{k+1}})(e_{i_{k+1}}^T R_k)$$

with

$$\gamma_{k+1} = \frac{1}{(R_k)_{i_{k+1}, j_{k+1}}}$$

$A = R_k + S_k$  and  $(R_k)_{i_m, j} = (R_k)_{i, j_m} = 0$  for  $m = 1, \dots, k$



# Adaptive Cross Approximation

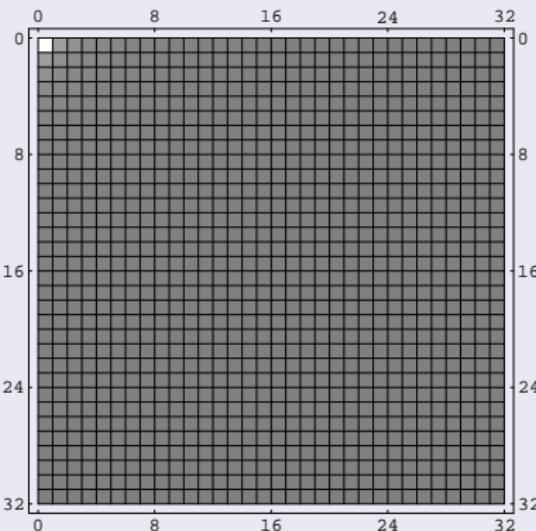
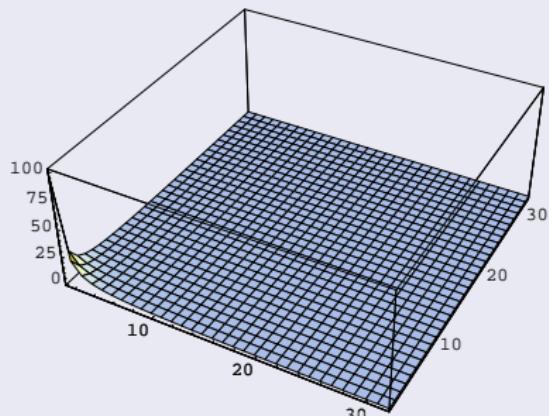
## Corner singularity

$$K(x, y) = \frac{1}{\alpha + x + y}, \quad \alpha = 10^{-2}$$

Step	Pivot row	Pivot column	Pivot value	Relative error
1	1	1	$1.00 \cdot 10^{+2}$	$3.43 \cdot 10^{-1}$
2	2	2	$7.91 \cdot 10^{+0}$	$1.62 \cdot 10^{-1}$
3	6	6	$1.10 \cdot 10^{+0}$	$3.66 \cdot 10^{-2}$
4	28	28	$2.25 \cdot 10^{-1}$	$2.26 \cdot 10^{-3}$
5	3	3	$6.10 \cdot 10^{-2}$	$8.40 \cdot 10^{-4}$
6	13	13	$9.87 \cdot 10^{-3}$	$2.28 \cdot 10^{-5}$
7	4	4	$3.91 \cdot 10^{-4}$	$8.85 \cdot 10^{-6}$
8	20	20	$1.02 \cdot 10^{-4}$	$2.69 \cdot 10^{-7}$
9	9	9	$6.32 \cdot 10^{-6}$	$3.30 \cdot 10^{-8}$
10	32	32	$1.97 \cdot 10^{-6}$	$1.13 \cdot 10^{-9}$

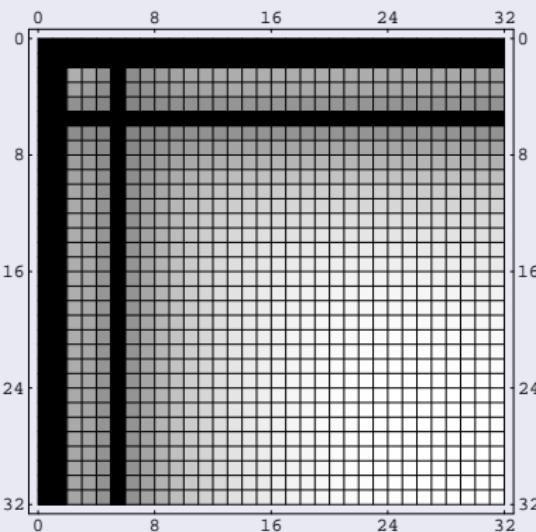
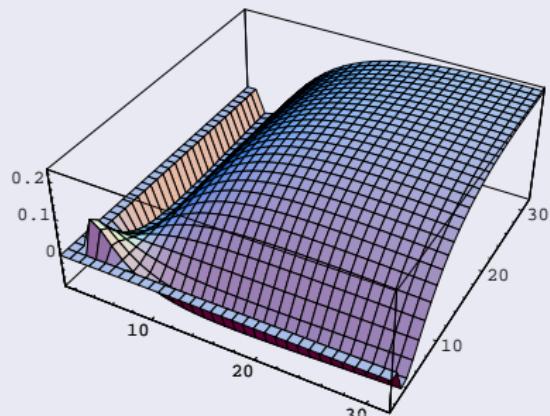
# Adaptive Cross Approximation

## Initial situation



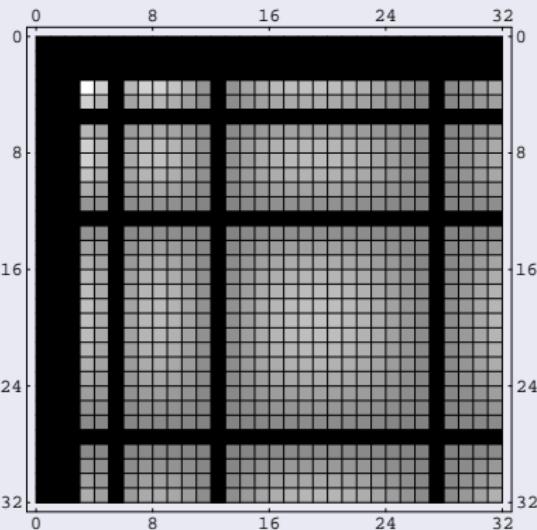
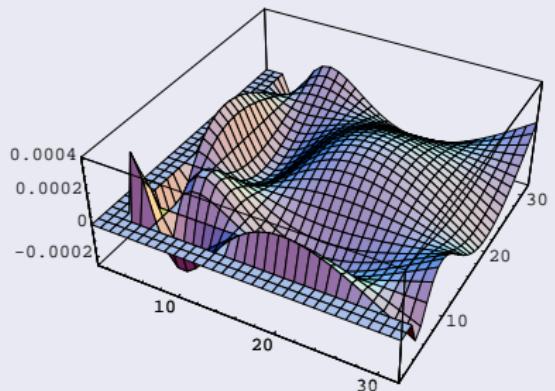
# Adaptive Cross Approximation

After 3 Iterations



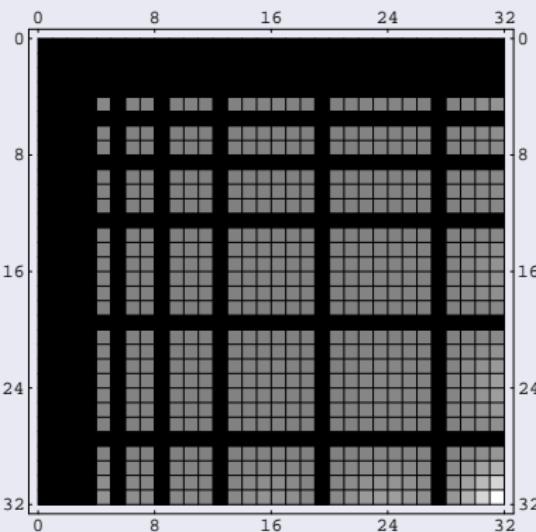
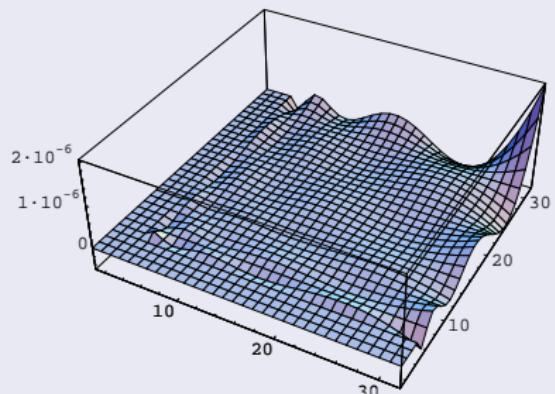
# Adaptive Cross Approximation

After 6 Iterations



# Adaptive Cross Approximation

After 9 Iterations



# Main ideas

## Extension of the ACA

$$S_0(x, y, z) = 0, \quad R_0(x, y, z) = K(x, y, z)$$

$$C_m(x, y, z) = \frac{R_{m-1}(x_{i_m}, y_{j_m}, z_{k_m}) R_{m-1}(x_{i_m}, y, z) R_{m-1}(x, y_{j_m}, z) R_{m-1}(x, y, z_{k_m})}{R_{m-1}(x_{i_m}, y_{j_m}, z) R_{m-1}(x_{i_m}, y, z_{k_m}) R_{m-1}(x, y_{j_m}, z_{k_m})}$$

$$S_m(x, y, z) = S_{m-1}(x, y, z) + C_m(x, y, z),$$

$$R_m(x, y, z) = R_{m-1}(x, y, z) - C_m(x, y, z)$$

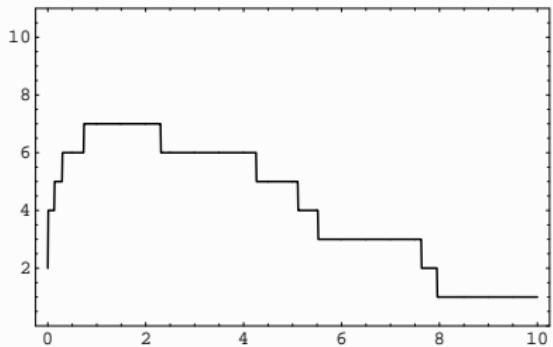


# Numerical experiments

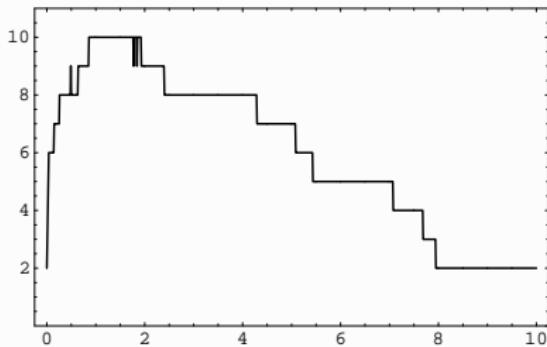
## Initial condition

$$f_0(v) = \frac{1}{2(2\pi)^{3/2}} \left( e^{-\frac{|v - (2, 2, 0)^\top|^2}{2}} + e^{-\frac{|v + (-2, 0, 0)^\top|^2}{2}} \right)$$

## Relaxation of the numerical rank



$$\varepsilon = 10^{-6}$$



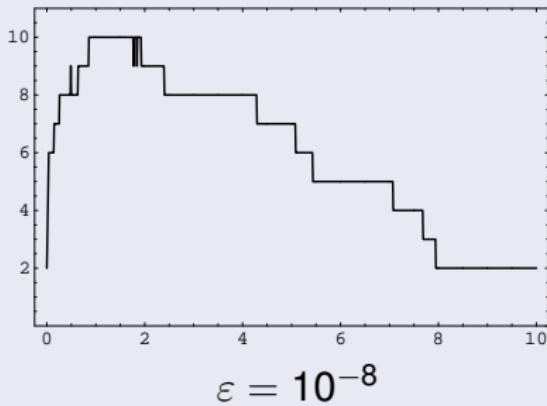
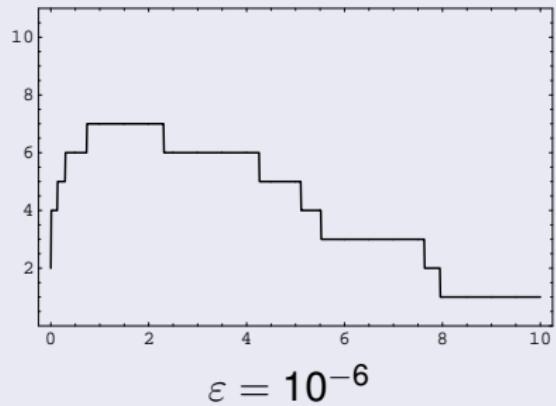
$$\varepsilon = 10^{-8}$$

# Numerical experiments

## Initial condition

$$f_0(v) = \frac{1}{2(2\pi)^{3/2}} \left( e^{-\frac{|v - (2, 2, 0)^\top|^2}{2}} + e^{-\frac{|v + (-2, 0, 0)^\top|^2}{2}} \right)$$

## Relaxation of the numerical rank



# Numerical experiments

## Computational times

$n$	$\varepsilon = 0$	$\varepsilon = 10^{-6}$	$\varepsilon = 10^{-8}$
16	0.2s	8.0s	0.4s
32	11.0s	12.0m	0.8s
64	7.0m	15.0h	3.3s
128	6.0h	--	49.0s
			3.6h



# References

-  I. Ibragimov and S. Rjasanow.  
Numerical solution of the Boltzmann equation on the uniform grid.  
*Computing*, 69(2): 163–186, 2003.
-  I. Ibragimov and S. Rjasanow.  
Three way decomposition for the Boltzmann equation.  
*J. Comp. Math.*, 27: 184-195, 2009.
-  M. Bebendorf and S. Rjasanow.  
Adaptive Low-Rank Approximation of Collocation Matrices.  
*Computing*, 70: 1–24, 2003.
-  S. Rjasanow and O. Steinbach.  
*The Fast Solution of Boundary Integral Equations.*  
Mathematical and Analytical Techniques with Applications to Engineering. Springer-Verlag Berlin-Heidelberg-New York, 2007.

# References

-  I. Ibragimov and S. Rjasanow.  
Numerical solution of the Boltzmann equation on the uniform grid.  
*Computing*, 69(2): 163–186, 2003.
-  I. Ibragimov and S. Rjasanow.  
Three way decomposition for the Boltzmann equation.  
*J. Comp. Math.*, 27: 184-195, 2009.
-  M. Bebendorf and S. Rjasanow.  
Adaptive Low-Rank Approximation of Collocation Matrices.  
*Computing*, 70: 1–24, 2003.
-  S. Rjasanow and O. Steinbach.  
*The Fast Solution of Boundary Integral Equations.*  
Mathematical and Analytical Techniques with Applications to Engineering. Springer-Verlag Berlin-Heidelberg-New York, 2007.

# References

-  I. Ibragimov and S. Rjasanow.  
Numerical solution of the Boltzmann equation on the uniform grid.  
*Computing*, 69(2): 163–186, 2003.
-  I. Ibragimov and S. Rjasanow.  
Three way decomposition for the Boltzmann equation.  
*J. Comp. Math.*, 27: 184-195, 2009.
-  M. Bebendorf and S. Rjasanow.  
Adaptive Low-Rank Approximation of Collocation Matrices.  
*Computing*, 70: 1–24, 2003.
-  S. Rjasanow and O. Steinbach.  
*The Fast Solution of Boundary Integral Equations.*  
Mathematical and Analytical Techniques with Applications to Engineering. Springer-Verlag Berlin-Heidelberg-New York, 2007.

# References

-  I. Ibragimov and S. Rjasanow.  
Numerical solution of the Boltzmann equation on the uniform grid.  
*Computing*, 69(2): 163–186, 2003.
-  I. Ibragimov and S. Rjasanow.  
Three way decomposition for the Boltzmann equation.  
*J. Comp. Math.*, 27: 184-195, 2009.
-  M. Bebendorf and S. Rjasanow.  
Adaptive Low-Rank Approximation of Collocation Matrices.  
*Computing*, 70: 1–24, 2003.
-  S. Rjasanow and O. Steinbach.  
*The Fast Solution of Boundary Integral Equations.*  
Mathematical and Analytical Techniques with Applications to Engineering. Springer-Verlag Berlin-Heidelberg-New York, 2007.

# References

-  I. Ibragimov and S. Rjasanow.  
Numerical solution of the Boltzmann equation on the uniform grid.  
*Computing*, 69(2): 163–186, 2003.
-  I. Ibragimov and S. Rjasanow.  
Three way decomposition for the Boltzmann equation.  
*J. Comp. Math.*, 27: 184-195, 2009.
-  M. Bebendorf and S. Rjasanow.  
Adaptive Low-Rank Approximation of Collocation Matrices.  
*Computing*, 70: 1–24, 2003.
-  S. Rjasanow and O. Steinbach.  
*The Fast Solution of Boundary Integral Equations.*  
Mathematical and Analytical Techniques with Applications to Engineering. Springer-Verlag Berlin-Heidelberg-New York, 2007.



# Adaptive Cross Approximation

Springer monograph

