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The Structure of Radiative Shocks

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Motivation

- Non-trivial, analytic solutions do not exist for radiation hydrodynamics.
 - ▶ Compromise: Generate *semi-analytic* solutions; solutions from numerically integrating nonlinear ODEs.
 - ▶ Seek traveling wave solutions \Rightarrow *radiative shocks*.
- In this talk, use solutions to
 - ▶ verify code correctness
 - ▶ test AMR (rad-shocks are multiscale problems)
- Gives physics insight that would be *very* difficult to obtain by a series of runs from a computational physics code.

- 1 Overview of radiative shocks
- 2 Equations of radiation hydrodynamics
 - Grey nonequilibrium diffusion
 - Euler coupled with grey nonequilibrium diffusion
 - Equilibrium diffusion limit
- 3 Overview of Semi-analytic Approach
- 4 Sample Solutions
- 5 Code Comparison

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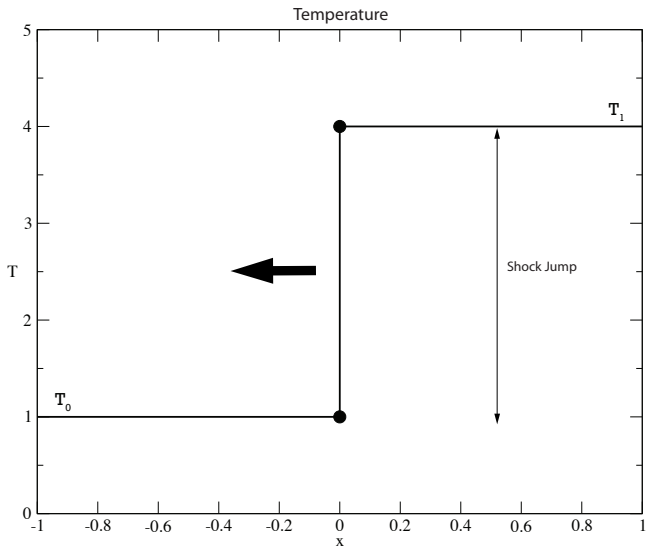
As one example, regimes in astrophysics governed by

- Inviscid hydrodynamics (Euler equations; non-relativistic)
- Thermal radiation (X-ray) transport
- High-energy density:
 - ▶ Material temperatures $O(1 \text{ keV} = 11.6 \times 10^6 \text{ Kelvin})$
 - ▶ Radiation *pressure* affects hydrodynamics

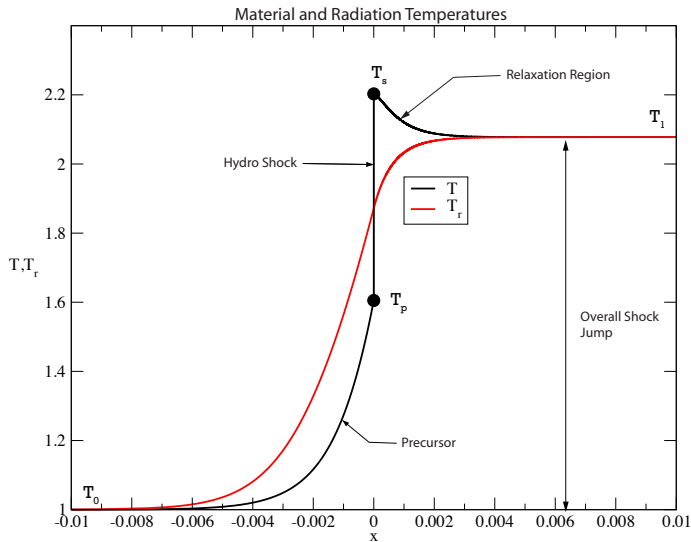
Past Work on Radiative Shocks

- Most theory on “thick – thick” shocks: equilibrates on either side of shock.
- **Overview of Theory:**
 - ▶ Y. B. ZEL'DOVICH and Y. P. RAIZER, *Physics of Shock Waves and High-Temperature Hydrodynamic Phenomena*, 1966 (Dover 2002).
 - ▶ D. MIHALAS and B. W. MIHALAS, *Foundations of Radiation Hydrodynamics*, 1984 (Dover 1999).
 - ▶ R.P. DRAKE, *High-Energy-Density Physics*, Springer, 2006.
- Grey VEF/AMR, ion/electron, calculations:
 - ▶ M. W. SINCELL, M. GEHMEYR, and D. MIHALAS, two articles in *Shock Waves*, 1999.
- **Theory and Solutions:**
 - ▶ **Equilibrium:** S. BOUQUET, R. TEYSSIER, and J. P. CHIEZE, *Astrophysical Journal Supplement Series*, 2000.
 - ▶ **Equilibrium:** R. B. LOWRIE and R. M. RAUENZAHN, *Shock Waves*, 2007.
 - ▶ **Nonequilibrium:** R. B. LOWRIE and J. D. EDWARDS, *Shock Waves*, 2008.
- **Extended thermodynamics:**
 - ▶ W. Weiss, “Structure of Shock Waves,” in *Rational Extended Thermodynamics*, Müller & Ruggeri (eds.), Springer, 1998.

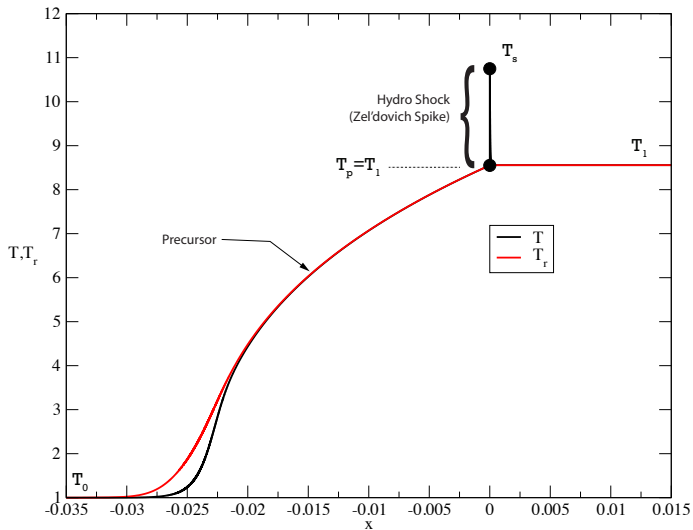
Inviscid Hydrodynamic Shocks



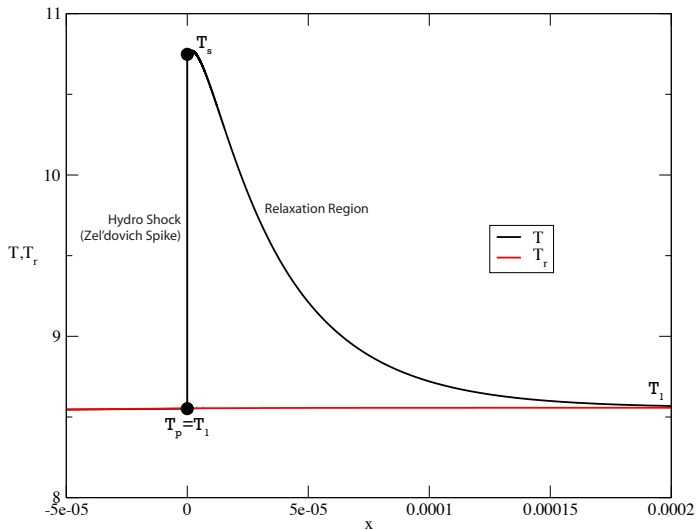
Subcritical Radiative Shocks ($T_p < T_1$)



Supercritical Radiative Shocks ($T_p = T_1$)



Zel'dovich Spike



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Grey nonequilibrium diffusion in 1 slide

1-D planar (slab) geometry

First two moments of radiative transfer equation:

$$\begin{aligned}\partial_t E + \partial_x F &= c\sigma_a[B(T) - E] - \frac{\sigma_t}{c} \left(F - \frac{4}{3}vE \right) v \\ \frac{1}{c^2} \partial_t F + \partial_x P &= -\frac{\sigma_t}{c} \left(F - \frac{4}{3}vE \right)\end{aligned}$$

Nonequilibrium diffusion sets $P = E/3$ and drops $\partial_t F$ to yield

$$\partial_t E + \underline{\frac{4}{3} \partial_x (vE)} - \partial_x \left(\frac{c}{3\sigma_t} \partial_x E \right) = c\sigma_a[B(T) - E] + \underline{\frac{1}{3} v \partial_x E}$$

Underlined terms often dropped in “low-energy density” approximation.

Euler Coupled with Grey Nonequilibrium Diffusion

Nondimensional form, 1-D planar (slab) geometry

Most of this talk will be about solutions of

$$\partial_t \rho + \partial_x(\rho v) = 0,$$

$$\partial_t(\rho v) + \partial_x \left(\rho v^2 + p + \frac{1}{3} \mathcal{P}_0 T_r^4 \right) = 0,$$

$$\partial_t(\rho \mathcal{E}) + \partial_x [v(\rho \mathcal{E} + p)] = \mathcal{P}_0 \sigma_a (T_r^4 - T^4) - \frac{1}{3} \mathcal{P}_0 v \partial_x T_r^4,$$

$$\partial_t(\rho \mathcal{E} + \mathcal{P}_0 T_r^4) + \partial_x \left[v \left(\rho \mathcal{E} + p + \frac{4}{3} \mathcal{P}_0 T_r^4 \right) \right] = \mathcal{P}_0 \partial_x (\kappa \partial_x T_r^4),$$

where $\mathcal{E} = e + \frac{1}{2} v^2$ and for a γ -law EOS

$$p = \frac{\rho T}{\gamma}, \quad e = \frac{T}{\gamma(\gamma - 1)}, \quad \mathcal{P}_0 = \frac{\tilde{a}_R \tilde{T}_0^4}{\gamma \tilde{p}_0} \approx \frac{\text{rad. pressure}}{\text{mat. pressure}}.$$

Embedded discontinuities are hydrodynamic shocks.

Equilibrium Diffusion Limit

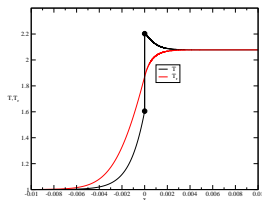
We'll also discuss "1T" solutions. Optically thick limit, $T_r \rightarrow T$, and our system reduces to

$$\begin{aligned}\partial_t \rho + \partial_x(\rho v) &= 0, \\ \partial_t(\rho v) + \partial_x \left(\rho v^2 + p + \frac{1}{3} \mathcal{P}_0 T^4 \right) &= 0, \\ \partial_t(\rho E + \mathcal{P}_0 T^4) + \partial_x \left[v \left(\rho E + p + \frac{4}{3} \mathcal{P}_0 T^4 \right) \right] &= \mathcal{P}_0 \partial_x(\kappa \partial_x T^4).\end{aligned}$$

- Euler equations with nonlinear heat conduction and a modified equation-of-state.
- For small- \mathcal{P}_0 , heat conduction may dominate.
- Embedded discontinuities are isothermal shocks.

Problem statement

- Assume that far from shock, $T_r = T$ (“thick–thick”).
- Galilean invariant, so use steady frame.



- *Given:* The value γ and
 - ▶ Pre-shock state ($x \rightarrow -\infty$): $\rho_0, T_0, T_{r0} = T_0$.
 - ▶ Non-dimensional constants: \mathcal{P}_0 and $\mathcal{M}_0 \equiv \tilde{v}_0/\tilde{a}_0$, Mach number).
 - ▶ Functions $\sigma_a(\rho, T)$ and $\kappa(\rho, T)$ ($\tilde{\kappa} = \tilde{c}/3\tilde{\sigma}_t$).
- *Calculate:* $\rho(x), v(x), T(x)$, and $T_r(x)$.
- *Optional:* Transform back to a frame where shock is moving.

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Euler Coupled with Grey Nonequilibrium Diffusion

Nondimensional form, 1-D planar (slab) geometry

Seek traveling-wave solutions of

$$\partial_t \rho + \partial_x(\rho v) = 0,$$

$$\partial_t(\rho v) + \partial_x \left(\rho v^2 + p + \frac{1}{3} \mathcal{P}_0 T_r^4 \right) = 0,$$

$$\partial_t(\rho E) + \partial_x [v(\rho E + p)] = \mathcal{P}_0 \sigma_a (T_r^4 - T^4) - \frac{1}{3} \mathcal{P}_0 v \partial_x T_r^4,$$

$$\partial_t(\rho E + \mathcal{P}_0 T_r^4) + \partial_x \left[v \left(\rho E + p + \frac{4}{3} \mathcal{P}_0 T_r^4 \right) \right] = \mathcal{P}_0 \partial_x (\kappa \partial_x T_r^4),$$

Overall Jump Relation

Integrate conservation equations from $-\infty < x < \infty$ to give:

$$\begin{pmatrix} \rho v \\ \rho v^2 + p^* \\ (\rho E^* + p^*)v \end{pmatrix}_0 = \begin{pmatrix} \rho v \\ \rho v^2 + p^* \\ (\rho E^* + p^*)v \end{pmatrix}_1,$$

where

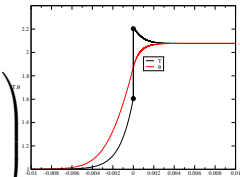
$$p^* = p + \frac{1}{3}P_0 T^4, \quad e^* = e + \frac{1}{\rho}P_0 T^4, \quad E^* = e^* + \frac{1}{2}v^2.$$

- Get ninth-order polynomial in T_1 ; see Bouquet *et al* (2000).
- Same procedure used for any radiation model.

Hydro Shock Relations

At a discontinuity separating state- p and state- s :

$$\begin{pmatrix} \rho v \\ \rho v^2 + p \\ (\rho E + p)v \\ -\kappa \partial_x T_r^4 + \frac{4}{3} v T_r^4 \end{pmatrix}_p = \begin{pmatrix} \rho v \\ \rho v^2 + p \\ (\rho E + p)v \\ -\kappa \partial_x T_r^4 + \frac{4}{3} v T_r^4 \end{pmatrix}_s$$



- First 3 equations: Standard hydro jump conditions. Holds for any radiation model.
- Last equation: Continuity of *Eulerian frame* radiation flux.

Reduced Equations

4 PDEs reduce to 2 ODEs. We use Mach number (\mathcal{M}) as the independent variable:

$$\frac{dx}{d\mathcal{M}} = \frac{3\mathcal{M}_0(\mathcal{M}^2 - 1)\rho\beta}{\mathcal{P}_0},$$
$$\frac{dT}{d\mathcal{M}} = (\gamma - 1)\beta \left[4\mathcal{M}_0 T_r^3 T_r' + (\gamma\mathcal{M}^2 - 1)r \right],$$

where $\beta(T, \mathcal{M})$ and $r(T, \mathcal{M})$ are known functions, and

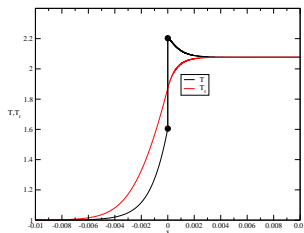
$$\rho(T, \mathcal{M}) = \frac{\mathcal{M}_0}{\mathcal{M}\sqrt{T}}, \quad T_r(T, \mathcal{M}) = \frac{1}{\gamma\mathcal{P}_0} \left[K_m - 3\gamma \frac{\mathcal{M}_0^2}{\rho(T, \mathcal{M})} - 3T\rho(T, \mathcal{M}) \right]$$

- If $T_r \approx \text{const.}$, then $\mathcal{M} = 1/\sqrt{\gamma}$ corresponds to maximum T (isothermal sonic point – ISP).

Overview of Solution Procedure

- 1 Compute post-shock state ($x \rightarrow \infty$): Find root of a ninth-order polynomial in T_1 .
- 2 End states are typically *saddle* points. Solve two IVPs:
 - ▶ Find precursor region: Integrate ODEs from $\mathcal{M} = \mathcal{M}_0$ to $\mathcal{M} = 1$.
 - ▶ Find relaxation region: Integrate ODEs from $\mathcal{M} = \mathcal{M}_1$ to $\mathcal{M} = 1$.
- 3 If the two ODE solutions do not match at $\mathcal{M} = 1$, then shift the solutions such that they are connected with a hydro shock.

See Lowrie & Edwards (*Shock Waves*, 2008) for the details.



Outline

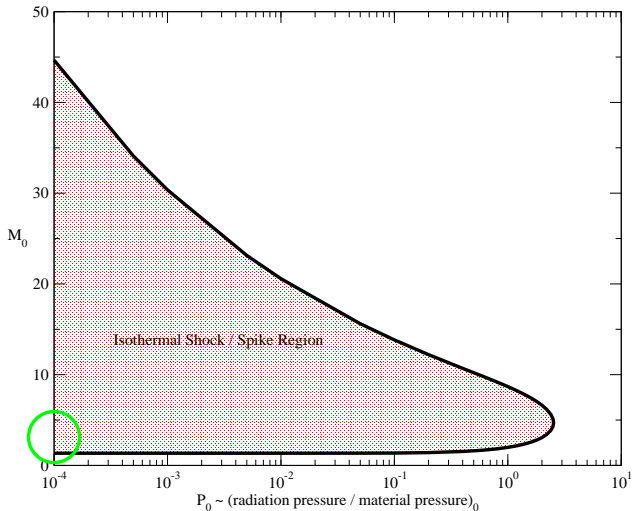
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Radiative shock solutions may be characterized by the following:

- Is there an embedded hydro shock?
 - ▶ If no, all variables continuous.
 - ▶ If yes,
 - ★ Subcritical ($T_p < T_1$).
 - ★ Supercritical ($T_p \approx T_1$).
- Is there an isothermal sonic point (ISP; $\mathcal{M} = 1/\sqrt{\gamma}$)?
 - ▶ If yes, then there is a temperature (Zel'dovich) spike $\implies T_{\max} > T_1$.
 - ▶ Lowrie & Edwards (2008) derive an algebraic expression for T_{\max} that is very accurate.
- May have a hydro shock without a spike.
- May have a spike without a hydro shock.

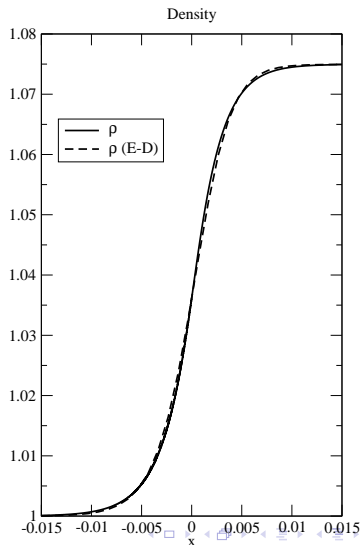
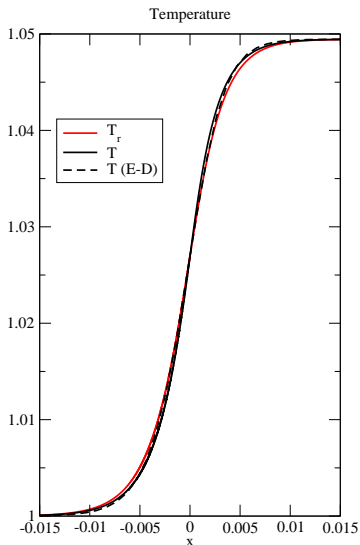
Isothermal Shock (Equilib.) \Leftrightarrow Spike (Non-equilib.)

$\gamma = 5/3$. See Lowrie & Rauenzahn (2007).



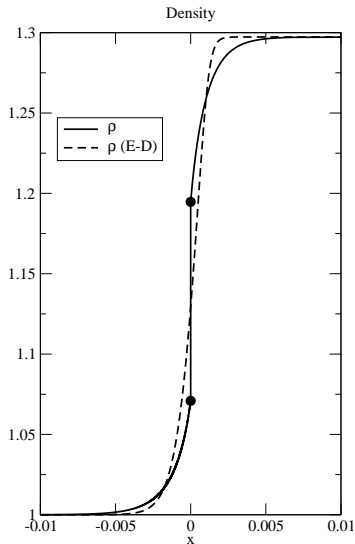
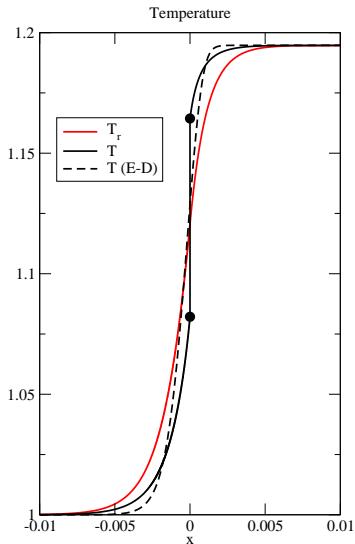
$\mathcal{M}_0 = 1.05$ solution

$\mathcal{P}_0 = 10^{-4}$, $\sigma_a = 10^6$, $\kappa = 1$, $\gamma = 5/3$; subcritical; no embedded shock or isothermal sonic point (ISP).



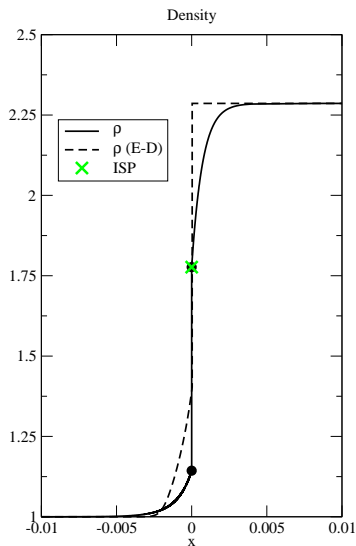
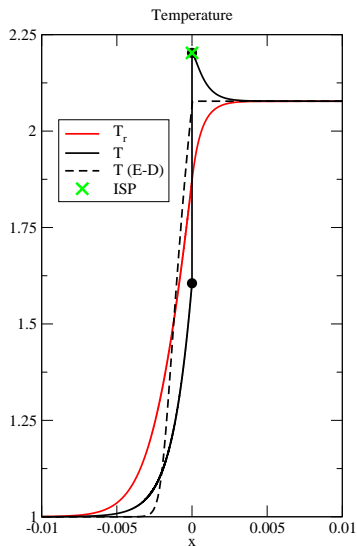
$\mathcal{M}_0 = 1.2$ solution

Subcritical; shock, but no ISP.



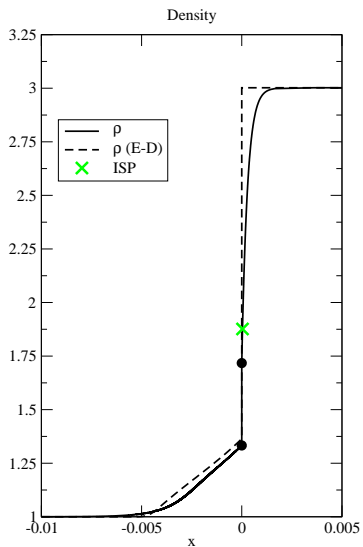
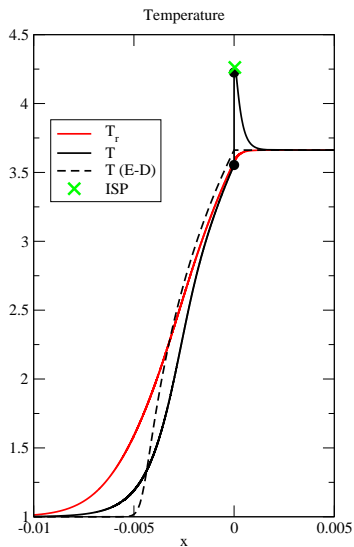
$\mathcal{M}_0 = 2$ solution

Subcritical; ISP coincident with shock.



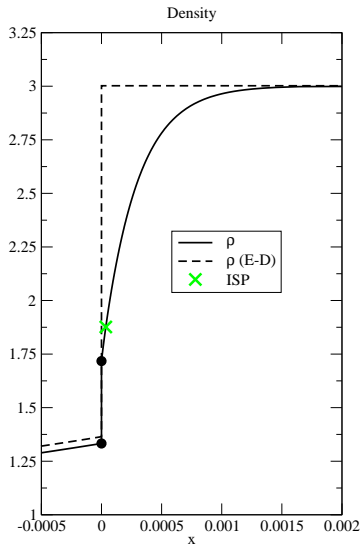
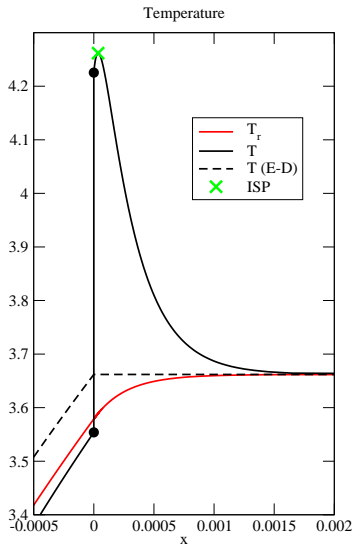
$M_0 = 3$ solution

Subcritical; ISP downstream of shock.



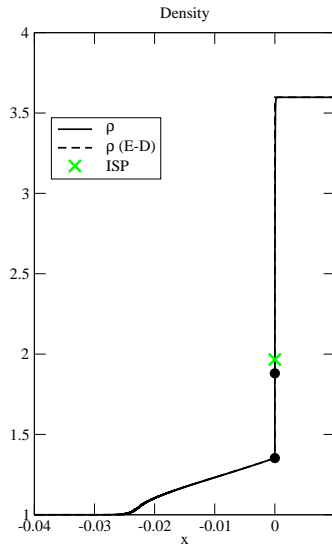
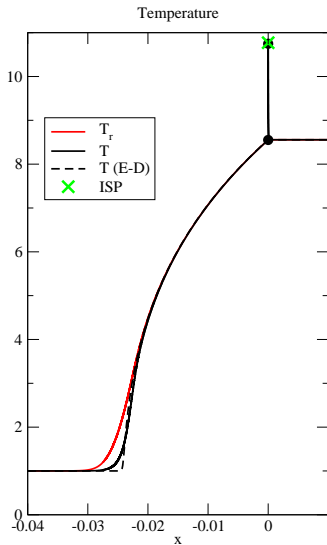
$M_0 = 3$ solution

Spike region.



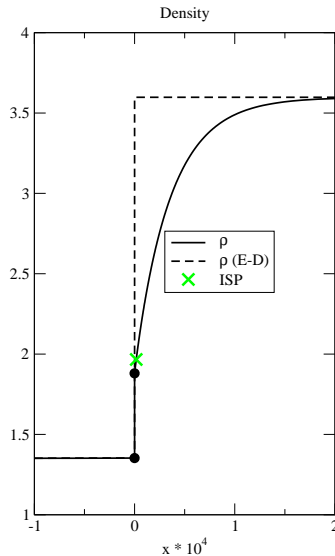
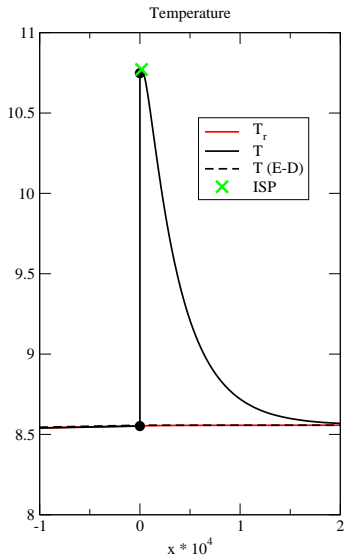
$M_0 = 5$ solution

Supercritical; ISP downstream of shock.



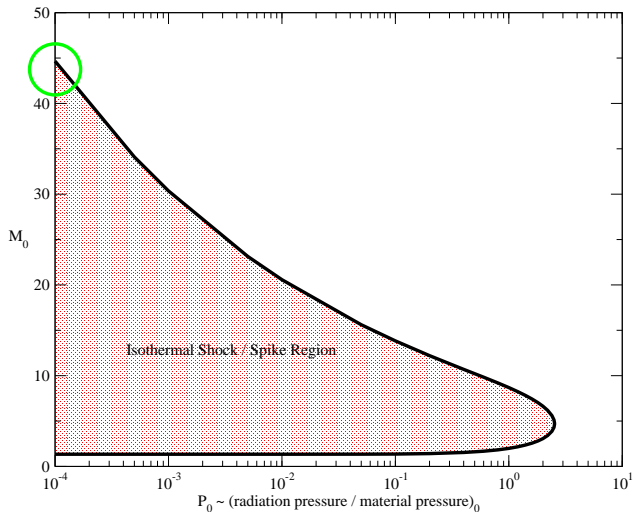
$\mathcal{M}_0 = 5$ solution (continued)

Zel'dovich spike region



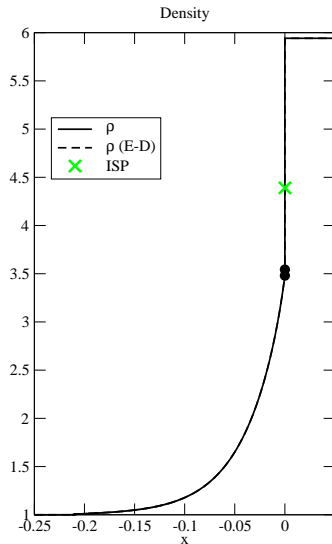
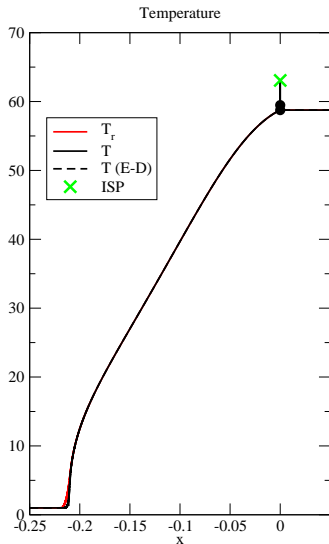
Isothermal Shock (Equilib.) \Leftrightarrow Spike (Non-equilib.)

$\gamma = 5/3$. See Lowrie & Rauenzahn (2007).



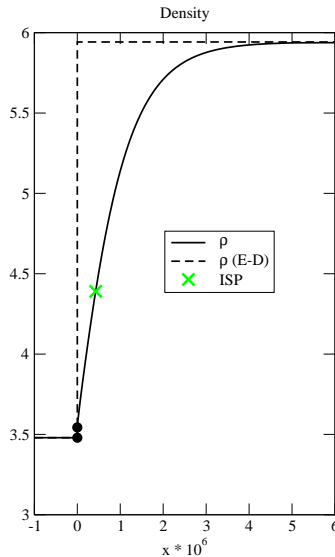
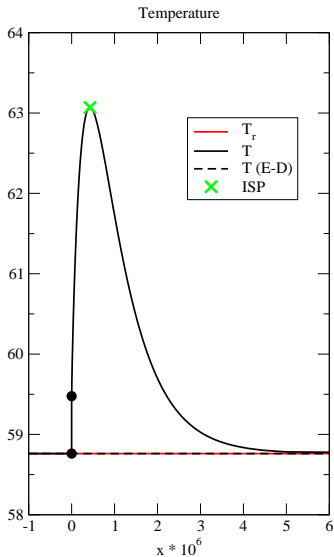
$M_0 = 27$ solution

Supercritical; ISP downstream of shock. NOTE OVER COMPRESSION.



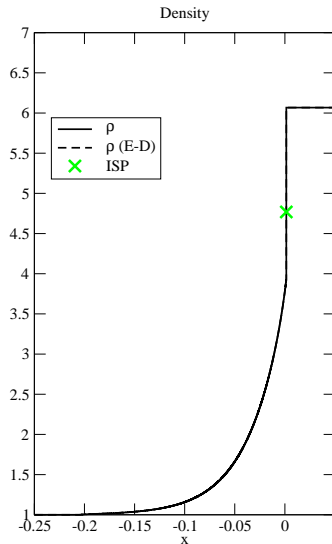
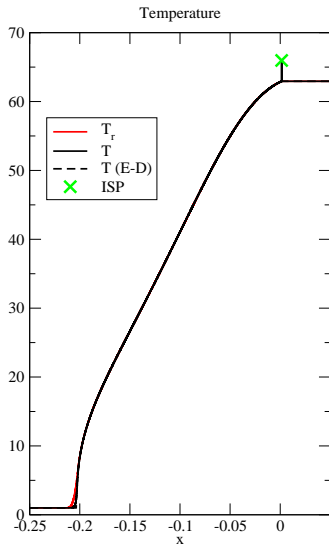
$\mathcal{M}_0 = 27$ solution (continued)

Zel'dovich spike region



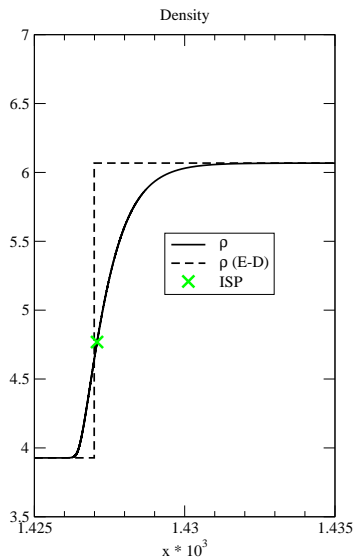
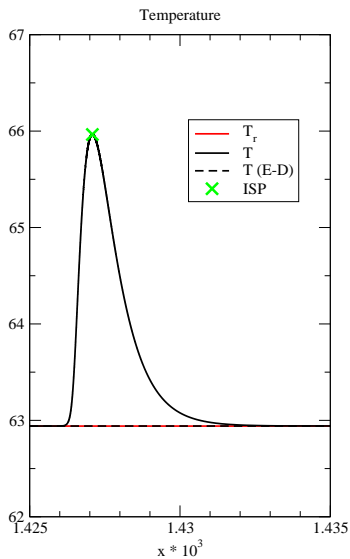
$\mathcal{M}_0 = 30$ solution

No shock, but still an ISP!



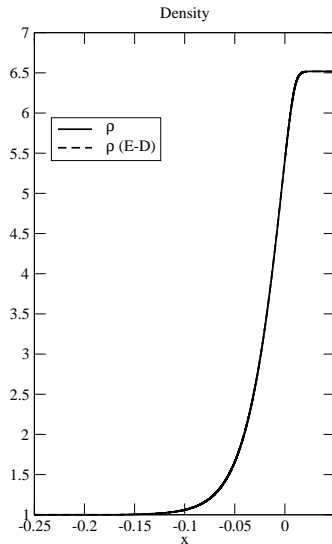
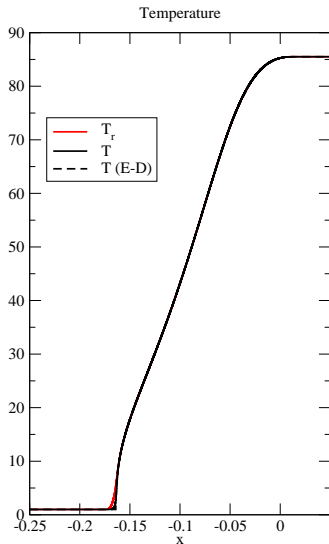
$\mathcal{M}_0 = 30$ solution (continued)

Spike region



$\mathcal{M}_0 = 50$ solution

No shock or ISP



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Code Comparison Test Cases

- Hydrogen gas, $\gamma = 5/3$
- Bremsstrahlung absorption model (Zel'dovich & Razier; assume fully ionized):

$$\sigma_a(\rho, T) = \sigma_{a,0} \rho^2 T^{-7/2}$$

- Thomson scattering:

$$\sigma_s(\rho) = \sigma_{s,0} \rho$$

- $\rho_0 = 1$ g/cc
- Cases:
 - 1 $T_0 = 10$ eV, $\mathcal{M}_0 = 10$, subcritical
 - 2 $T_0 = 100$ eV, $\mathcal{M}_0 = 5$, supercritical
 - 3 $T_0 = 100$ eV, $\mathcal{M}_0 = 45$, no embedded hydro shock
- Comparison of relaxation rates shows that 3T effects should be small.
- Compare with a finite-volume, Godunov-based AMR code (RAGE).

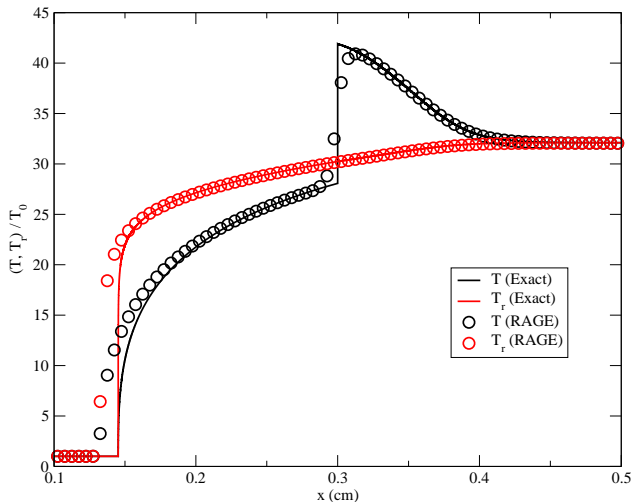
Two Initialization Methods

- 1 Initialize with exact shock profile.
 - ▶ How well can the code propagate the shock and maintain the profile?
 - ▶ Pros: Boundary conditions not an issue.
 - ▶ Cons: Requires code initialize from exact solution.
 - ▶ This method was used for all error-norm calculations.
- 2 Piston problem.
 - ▶ Black-body piston moving at v_1 , radiating at $T_r = T_1$.
 - ▶ Given enough time, the resulting shock should match the semi-analytic solution.
 - ▶ Pros: Easy setup; better test.
 - ▶ Cons: Requires “large” solution domain; boundary conditions become an issue.

With either method, you should propagate the shock long enough to establish a self-similar profile.

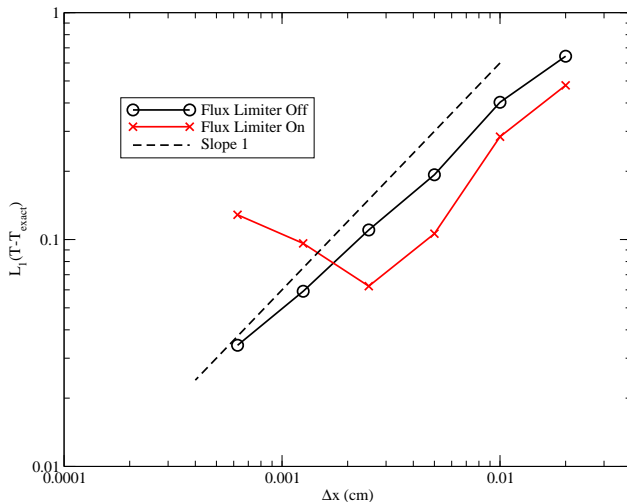
$T_0 = 10 \text{ eV}$, $\mathcal{M}_0 = 10$ Sample Results

$\Delta x = 50 \text{ } \mu\text{m}$, propagated 1 cm, $T_1 \approx 321 \text{ eV}$, $T_{\text{max}} \approx 419 \text{ eV}$



$T_0 = 10 \text{ eV}$, $\mathcal{M}_0 = 10$ Error Convergence

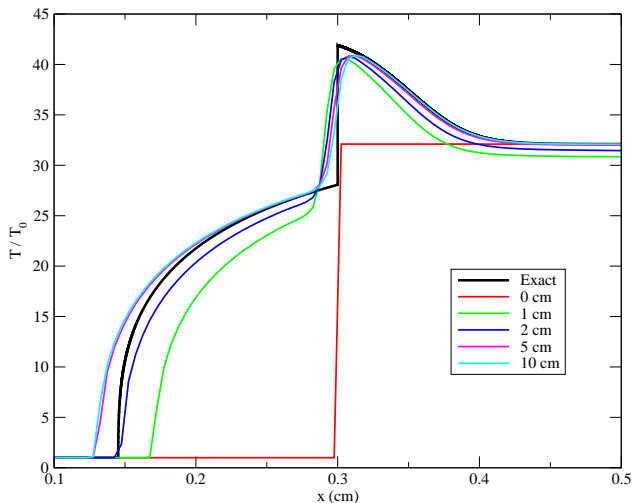
Exact solution computed without flux limiter.



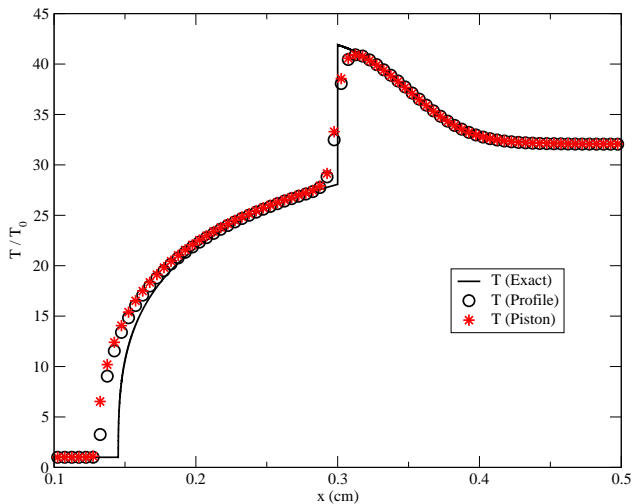
$T_0 = 10 \text{ eV}$, $\mathcal{M}_0 = 10$, Piston Problem Initialization

Legend indicates distance exact profile has moved. Solutions shifted to align.

$\Delta x = 50 \mu\text{m}$.

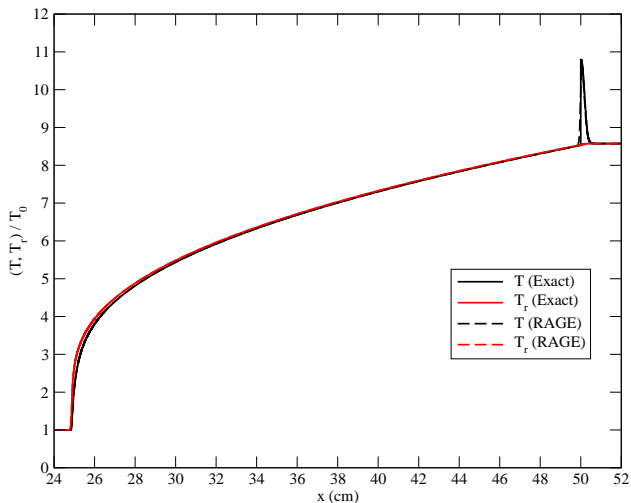


Profile vs. Piston Initialization

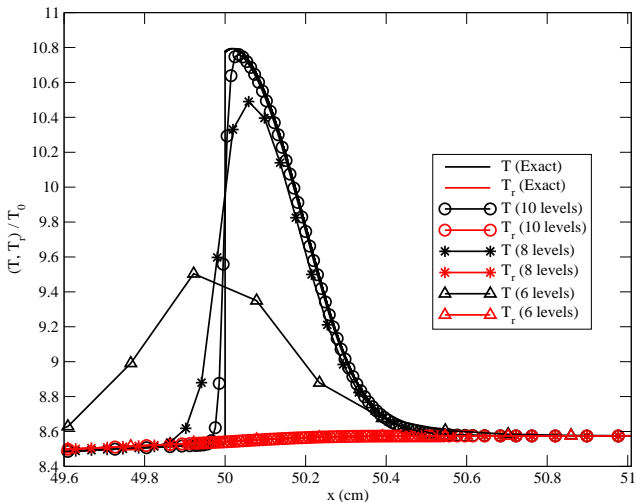


$T_0 = 100$ eV, $\mathcal{M}_0 = 5$ Sample Results

AMR (8 levels): $\Delta x_{\max} = 5$ cm, $\Delta x_{\min} \approx 391$ μm , propagated 230 cm, $T_1 \approx 857$ eV,
 $T_{\max} \approx 1.08$ keV

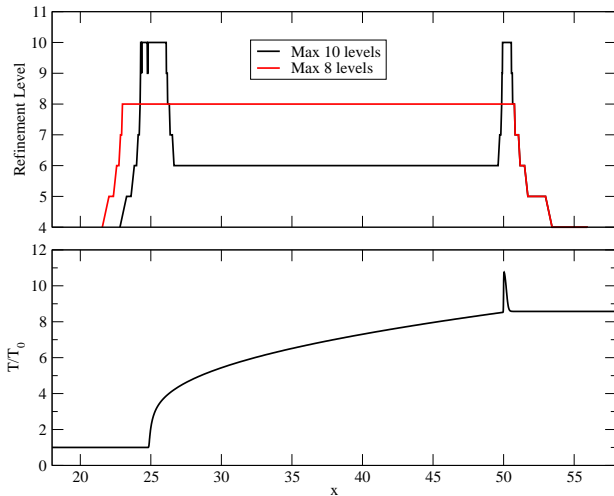


$T_0 = 100$ eV, $\mathcal{M}_0 = 5$ Spike Region



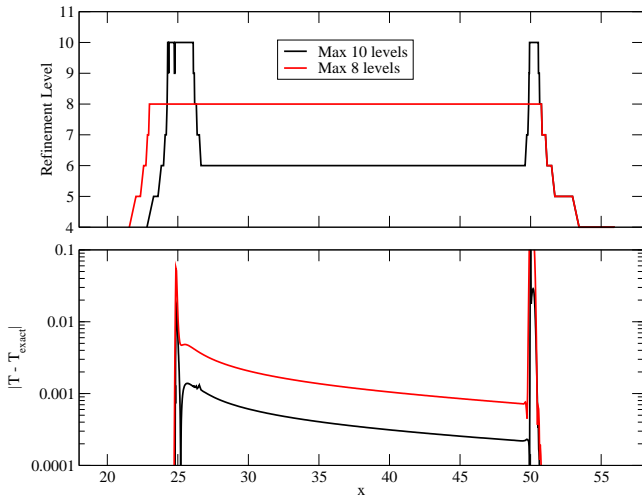
$T_0 = 100$ eV, $\mathcal{M}_0 = 5$ Refinement Distribution

8 levels \implies 814 cells; 10 levels \implies 528 cells (10-level mesh derefined in precursor).



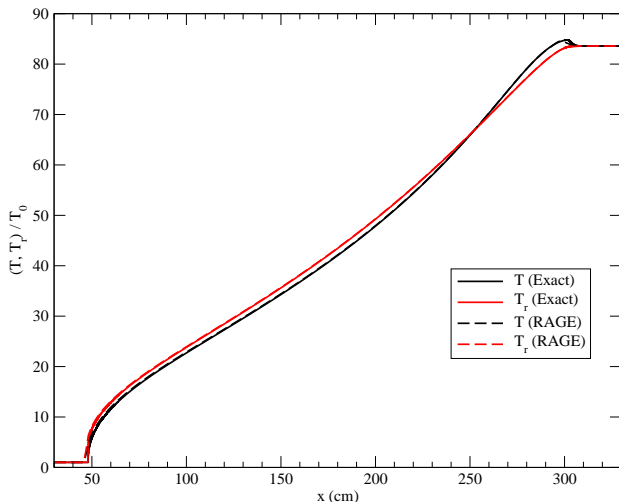
Refinement and Error Distribution

Even though 10-level mesh derefined in $27 \lesssim x \lesssim 49$, it is more accurate.



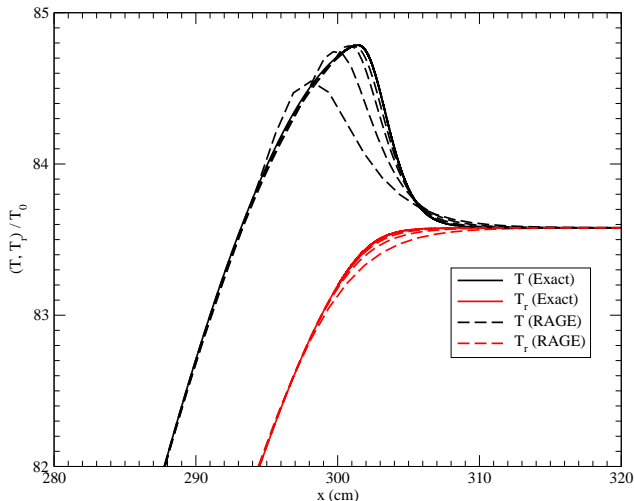
$T_0 = 100$ eV, $\mathcal{M}_0 = 45$ Sample Results

$\Delta x = 1.25$ cm, propagated 20 m, $T_1 \approx 8.36$ keV, $T_{\max} \approx 8.48$ keV



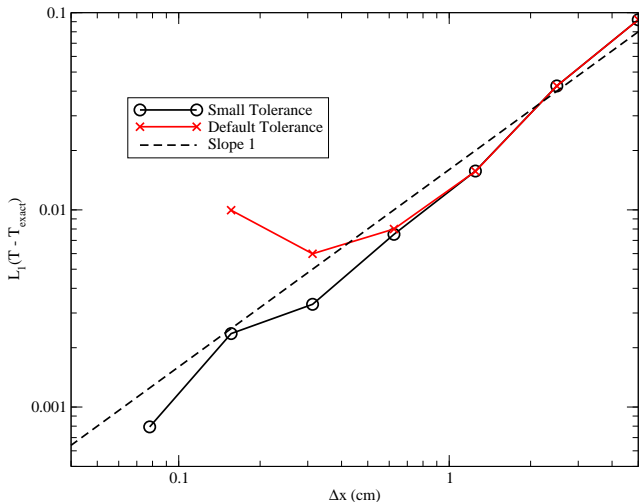
$T_0 = 100$ eV, $\mathcal{M}_0 = 45$ Spike Region

RAGE results with $\Delta x = 1.25$ cm/ 2^N , with $N = 0, 1, 2, 3$



$T_0 = 100 \text{ eV}$, $\mathcal{M}_0 = 45$ Convergence

A hard-coded tolerance was limiting the convergence rate.



- The radiative shock solutions test several issues:
 - ▶ Fully-coupled radiation hydrodynamics
 - ▶ Embedded shock problems \implies ability to capture hydro shocks
 - ▶ Smooth problems \implies ability to attain theoretical convergence rate
 - ▶ Refinement criteria for AMR (solutions are multiscale)
 - ▶ Other radiation models
- Future work
 - ▶ Separate ion/electron temperatures
 - ▶ More advanced radiation models