

Notions of differential structure on metric measure spaces and applications

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Aim of the talk

On mms there is a well established notion of Sobolev space.

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$$Df(\nabla g)$$

2) this is useful for understanding both analysis and geometry of mms

Neither doubling nor Poincaré are assumed.

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- ▶ Preliminaries
 - ▶ Sobolev space over a metric measure space
 - ▶ Differential calculus on normed spaces

- ▶ Analysis
 - ▶ Differentials and gradients
 - ▶ Horizontal and vertical derivatives
 - ▶ Averaging out the unsmoothness
 - ▶ Distributional Laplacian
 - ▶ Laplacian comparison estimates

- ▶ Geometry
 - ▶ The splitting theorem

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Test plans

Let (X, d) be complete and separable and \mathbf{m} a non-negative Radon measure on it.

Let $\pi \in \mathcal{P}(C([0, 1], X))$. We say that π is a test plan provided:

- ▶ for some $C > 0$ it holds

$$e_{t\#}\pi \leq C\mathbf{m}, \quad \forall t \in [0, 1].$$

- ▶ it holds

$$\iint_0^1 |\dot{\gamma}_t|^2 dt d\pi < \infty$$

The Sobolev class $S^2(X, d, \mathbf{m})$

We say that $f : X \rightarrow \mathbb{R}$ belongs to $S^2(X, d, \mathbf{m})$ provided there exists $G \in L^2(X, \mathbf{m})$ such that

$$\int |f(\gamma_1) - f(\gamma_0)| d\pi(\gamma) \leq \iint_0^1 G(\gamma_t) |\dot{\gamma}_t| dt d\pi(\gamma)$$

for any test plan π .

Any such G is called 'weak upper gradient' of f .

The minimal G in the \mathbf{m} -a.e. sense will be denoted by $|Df|$

Basic properties

Locality

$$|Df| = |Dg| \quad \mathbf{m\text{-a.e. on } \{f = g\}}$$

Chain rule

$$|D(\varphi \circ f)| = |\varphi'| \circ f |Df|$$

for φ Lipschitz

'Leibniz rule'

$$|D(fg)| \leq |f| |Dg| + |g| |Df|$$

for $f, g \in S^2 \cap L^\infty$

The Sobolev space $W^{1,2}(X, d, \mathbf{m})$

The Sobolev space is defined as

$$W^{1,2}(X, d, \mathbf{m}) := L^2(X, \mathbf{m}) \cap \mathcal{S}^2(X, d, \mathbf{m})$$

endowed with the norm

$$\|f\|_{W^{1,2}} := \sqrt{\|f\|_{L^2}^2 + \|Df\|_{L^2}^2}$$

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Differentials

Given $f : \mathbb{R}^d \rightarrow \mathbb{R}$ smooth, its differential $Df : \mathbb{R}^d \rightarrow T^*\mathbb{R}^d$ is intrinsically defined by

$$Df(x)(v) := \lim_{t \rightarrow 0} \frac{f(x + tv) - f(x)}{t}, \quad \forall x \in \mathbb{R}^d, v \in T_x\mathbb{R}^d$$

Gradients

To define the gradient of a smooth f we need more structure: a norm.

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A way to get it is starting from the observation that for any tangent vector w it holds

$$Df(x)(w) \leq \|Df(x)\|_* \|w\| \leq \frac{1}{2} \|Df(x)\|_*^2 + \frac{1}{2} \|w\|^2.$$

Then we can say that $v = \nabla f(x)$ provided $=$ holds, or equivalently

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Rmk.

Uniqueness holds iff the norm is strictly convex

Linearity holds iff the norm comes from a scalar product.

An important identity

$$\max_{v \in \nabla g(x)} Df(v) = \inf_{\varepsilon > 0} \frac{\|D(g + \varepsilon f)\|_*^2(x) - \|Dg\|_*^2(x)}{2\varepsilon}$$

$$\min_{v \in \nabla g(x)} Df(v) = \sup_{\varepsilon < 0} \frac{\|D(g + \varepsilon f)\|_*^2(x) - \|Dg\|_*^2(x)}{2\varepsilon}.$$

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The object $D^\pm f(\nabla g)$

For $f, g \in S^2$, the functions $D^\pm f(\nabla g) : X \rightarrow \mathbb{R}$ are defined by

$$D^+ f(\nabla g) := \inf_{\varepsilon > 0} \frac{|D(g + \varepsilon f)|^2 - |Dg|^2}{2\varepsilon}$$
$$D^- f(\nabla g) := \sup_{\varepsilon < 0} \frac{|D(g + \varepsilon f)|^2 - |Dg|^2}{2\varepsilon}$$

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Notice that

$$D^- f(\nabla g) \leq D^+ f(\nabla g), \quad \mathbf{m} - a.e.$$
$$|D^\pm f(\nabla g)| \leq |Df| |Dg| \in L^1(X, \mathbf{m}),$$
$$D^+(-f)(\nabla g) = -D^- f(\nabla g) = D^+ f(\nabla(-g)), \quad \mathbf{m} - a.e.$$

Calculus rules

Locality

$$D^\pm f(\nabla g) = D^\pm \tilde{f}(\nabla \tilde{g}), \quad \mathbf{m\text{-}a.e. \text{ on } \{f = \tilde{f}\} \cap \{g = \tilde{g}\}}$$

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Chain rule

$$D^\pm(\varphi \circ f)(\nabla g) = \varphi' \circ f D^{\pm \text{sign}(\varphi' \circ f)} f(\nabla g),$$

$$D^\pm f(\nabla(\varphi \circ g)) = \varphi' \circ g D^{\pm \text{sign}(\varphi' \circ g)} f(\nabla g)$$

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Leibniz rule

$$D^+(f_1 f_2)(\nabla g) \leq f_1 D^{\text{sign}(f_1)} f_2(\nabla g) + f_2 D^{\text{sign}(f_2)} f_1(\nabla g),$$

$$D^-(f_1 f_2)(\nabla g) \geq f_1 D^{-\text{sign}(f_1)} f_2(\nabla g) + f_2 D^{-\text{sign}(f_2)} f_1(\nabla g)$$

For $f_1, f_2 \in S^2 \cap L^\infty$, and $g \in S^2$.

Special situations

(X, d, \mathbf{m}) is **infinitesimally strictly convex** provided

$$D^+f(\nabla g) = D^-f(\nabla g), \quad \mathbf{m} - a.e.$$

for any $f, g \in S^2$. In this case the common value will be denoted by $Df(\nabla g)$. For $g \in S^2$ the map

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(X, d, \mathbf{m}) is **infinitesimally Hilbertian** if $f \mapsto \int |Df|^2 d\mathbf{m}$ is a quadratic form. In this case

$$D^+ f(\nabla g) = D^- f(\nabla g) = D^+ g(\nabla f) = D^- g(\nabla f), \quad \mathbf{m} - a.e.$$

and we denote these quantities by $\nabla f \cdot \nabla g$.

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Plan representing gradients: definition

For $g \in S^2$ and $\pi \in \mathcal{P}(C([0, 1], X))$ test plan it holds

$$\overline{\lim}_{t \downarrow 0} \int \frac{g(\gamma_t) - g(\gamma)}{t} d\pi \leq \frac{1}{2} \int |Dg|^2(\gamma_0) d\pi + \overline{\lim}_{t \downarrow 0} \frac{1}{2t} \int \int_0^t |\dot{\gamma}_s|^2 ds d\pi$$

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We say that π represents ∇g , provided it holds

$$\underline{\lim}_{t \downarrow 0} \int \frac{g(\gamma_t) - g(\gamma)}{t} d\pi \geq \frac{1}{2} \int |Dg|^2(\gamma_0) d\pi + \underline{\lim}_{t \downarrow 0} \frac{1}{2t} \int \int_0^t |\dot{\gamma}_s|^2 ds d\pi$$

Plan representing gradients: existence

Theorem (G. '12, Ambrosio-G.-Savaré '11).

For $g \in S^2$ and $\mu \in \mathcal{P}(X)$ such that $\mu \leq C\mathbf{m}$, a plan π representing ∇g and such that $e_{0\#}\pi = \mu$ exists.

First order differentiation formula

Let $f, g \in S^2$, and π which represents ∇g .

Then

$$\begin{aligned} & \overline{\lim}_{t \downarrow 0} \int \frac{f(\gamma_t) - f(\gamma_0)}{t} d\pi \\ & \geq \lim_{t \downarrow 0} \int \frac{f(\gamma_t) - f(\gamma_0)}{t} d\pi \end{aligned}$$

First order differentiation formula

Let $f, g \in S^2$, and π which represents ∇g .

Then

$$\begin{aligned} \int D^+ f(\nabla g)(\gamma_0) d\pi &\geq \overline{\lim}_{t \downarrow 0} \int \frac{f(\gamma_t) - f(\gamma_0)}{t} d\pi \\ &\geq \underline{\lim}_{t \downarrow 0} \int \frac{f(\gamma_t) - f(\gamma_0)}{t} d\pi \geq \int D^- f(\nabla g)(\gamma_0) d\pi \end{aligned}$$

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Integrating a function to get improved regularity

Theorem (G. '13) Let:

- ▶ (X, d, \mathbf{m}) be infinitesimally Hilbertian,
- ▶ $t \mapsto \mu_t$ a W_2 -geodesic such that
 - ▶ $\cup_t \text{supp}(\mu_t)$ bounded
 - ▶ $\mu_t \leq C\mathbf{m}$ for every $t \in [0, 1]$
 - ▶ with densities continuous in L^p for some (and thus any) $p < \infty$
- ▶ $f \in S^2(X, d, \mathbf{m}) \cap L^1(X, \mathbf{m})$

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- ▶ $f \in S^2(X, d, \mathbf{m}) \cap L^1(X, \mathbf{m})$

Then the map $t \mapsto \int f d\mu_t$ is C^1

and its derivative is given by

$$\frac{d}{dt} \int f d\mu_t = - \int \nabla f \cdot \nabla \varphi_t d\mu_t$$

where $\frac{\varphi_t}{1-t}$ is any Kantorovich potential from μ_t to μ_1 .

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Distributional Laplacian

Let (X, d, \mathbf{m}) be infinitesimally strictly convex, $\Omega \subset X$ open, $g \in S^2(\Omega)$

We say that $g \in D(\Delta, \Omega)$ if there exists a Radon measure μ on Ω such that

$$-\int_{\Omega} Df(\nabla g) d\mathbf{m} = \int_{\Omega} f d\mu,$$

holds for every f Lipschitz in $L^1(|\mu|)$ with $\mathbf{m}(\text{supp}(f)) < \infty$ with support contained in Ω . In this case we put $\Delta g|_{\Omega} := \mu$

Calculus rules

Chain rule

$$\Delta(\varphi \circ g) = \varphi' \circ g \Delta g + \varphi'' \circ g |Dg|^2 \mathbf{m}$$

On infinitesimally Hilbertian spaces:

Linearity

$$\Delta(g_1 + g_2) = \Delta g_1 + \Delta g_2$$

Leibniz rule

$$\Delta(g_1 g_2) = g_1 \Delta g_2 + g_2 \Delta g_1 + 2 \nabla g_1 \cdot \nabla g_2 \mathbf{m}$$

Nonlinear potential theory ($p = 2$)

It is the study of 2-minimizers, defined as those $g \in S^2$ such that

$$\int_{\Omega} |Dg|^2 d\mathbf{m} \leq \int_{\Omega} |D(g + f)|^2 d\mathbf{m},$$

for every $f \in S^2$ with compact support contained in Ω .

Typically under the assumptions that the measure is doubling and the space supports a 2-Poincaré inequality.

Relation with nonlinear potential theory

Theorem (G. Mondino '12) Let (X, d, \mathbf{m}) be a doubling space supporting a 2-Poincaré inequality and infinitesimally strictly convex.

Then g is a 2-minimizer on Ω if and only if $g \in D(\Delta, \Omega)$ and $\Delta g|_{\Omega} = 0$.
Similar results hold for sub/super-minimizers.

Relation with nonlinear potential theory

Theorem (G. Mondino '12) Let (X, d, \mathbf{m}) be a doubling space supporting a 2-Poincaré inequality and infinitesimally strictly convex.

Then g is a 2-minimizer on Ω if and only if $g \in D(\Delta, \Omega)$ and $\Delta g|_{\Omega} = 0$.
Similar results hold for sub/super-minimizers.

In particular, sub/super-minimizer have the sheaf property.

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Laplacian comparison

On a Riemannian manifold M with $Ric \geq 0$, $\dim \leq N$ it holds

$$\Delta \frac{1}{2} d^2(\cdot, \bar{x}) \leq N$$

in the sense of distributions.

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Does the same hold on abstract spaces?

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Does the same hold on abstract spaces?

Theorem (G. '12) Let (X, d, m) be an infinitesimally strictly convex $CD(0, N)$ space and $\bar{x} \in X$. Then

$$\Delta \frac{d^2(\cdot, \bar{x})}{2} \leq Nm$$

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Versions of the splitting theorem

Splitting (Cheeger-Gromoll '71)

Let M be a Riemannian manifold with $\text{Ric} \geq 0$ which contains a line.
Then $M = N \times \mathbb{R}$ for some Riemannian manifold N .

Versions of the splitting theorem

Splitting (Cheeger-Gromoll '71)

Let M be a Riemannian manifold with $\text{Ric} \geq 0$ which contains a line.
Then $M = N \times \mathbb{R}$ for some Riemannian manifold N .

Almost splitting (Cheeger-Colding '96)

Let M be a Riemannian manifold with $\text{Ric} \geq -\varepsilon$ which contains a geodesic with length L . $\varepsilon, L^{-1} \ll 1$

Then 'a big portion of M is GH-close to a product'

An equivalent version of the almost splitting

Let (M_n) be a sequence of Riemannian manifolds with uniformly bounded dimension, $\text{Ric}(M_n) \geq -\varepsilon_n$ containing lines γ_n of length L_n , with $\varepsilon_n, L_n^{-1} \rightarrow 0$.

Assume that (M_n) converges in the pGH-sense to a limit space (X, d) .

Then (X, d) splits.

Non-smooth splitting

Question: Let (X, d, \mathbf{m}) be a $CD(0, N)$ space containing a line.

Non-smooth splitting

Question: Let (X, d, \mathbf{m}) be a $CD(0, N)$ space containing a line.

Can we say that there exists a $CD(0, N - 1)$ space (X', d', \mathbf{m}') such that (X, d, \mathbf{m}) is isomorphic to

$$(X' \times \mathbb{R}, d' \otimes d_{\text{Eucl}}, \mathbf{m}' \times \mathcal{L}^1),$$

where

$$(d' \otimes d_{\text{Eucl}})((x', t), (y', s)) := \sqrt{d'(x', y')^2 + |t - s|^2}$$

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Answer: No. (Cordero Erasquin-Villani-Sturm '06)

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Theorem (G. '13)

The answer become yes if we add the assumption that the space is infinitesimally Hilbertian.

Don't forget the stability

The non-smooth splitting would be of little use if we don't know that

$CD(0, N) + \text{infinitesimal Hilbertianity}$

is stable.

Don't forget the stability

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$$CD(0, N) + \text{infinitesimal Hilbertianity}$$

is stable.

This is true and follows from the study of the heat flow

G. '09

G.-Kuwada-Ohta '10

Ambrosio-G.-Savaré '11 I-II

Ambrosio-G.-Mondino-Rajala '12

G.-Mondino-Savaré '13

Thank you