Lambertian model of reflectance II: harmonic analysis

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Illumination cone

- What is the set of images of an object under different lighting, with any number of sources?
- Images are additive and non-negative
- This set, therefore, forms a *convex cone* in R^p, p number of pixels (Belhumeur & Kriegman)



Illumination cone

- Cone characterization is generic, holds also with specularities, shadows and interreflections
- Unfortunately, representing the cone is complicated (infinite degrees of freedom)
- Cone is "thin" for Lambertian objects; indeed the illumination cone of many objects can be represented with few PCA vectors (Yuille et al.)

Illumination cone is often thin

	Ball	Face	Phone	Parrot
#1	48.2	53.7	67.9	42.8
#3	94.4	90.2	88.2	76.3
#5	97.9	93.5	94.1	84.7
#7	99.1	95.3	96.3	88.5
#9	99.5	96.3	97.2	90.7

(Yuille et al.)

Lambertian reflectance is smooth

(Basri & Jacobs; Ramamoorthi & Hanrahan)



Reflectance obtained with convolution



Reflectance obtained with convolution



Spherical harmonics

$$Y_{nm}(\theta, \phi) = \sqrt{\frac{(2n+1)}{4\pi} \frac{(n-|m|)!}{(n+|m|)!}} P_{nm}(\cos\theta) e^{im\phi}$$
$$p_{nm}(z) = \frac{(1-z^2)^{m/2}}{2^n n!} \frac{d^{n+m}}{dz^{n+m}} (z^2-1)^n$$

- Orthonormal basis for functions on the sphere
- *n*'th order harmonics have 2*n*+1 components
- Rotation = phase shift (same n, different m)
- In space coordinates: polynomials of degree *n*
- Funk-Hecke convolution theorem

Spherical harmonics



Harmonic approximation

• Lighting, in terms of harmonics

$$\ell(\theta,\phi) = \sum_{n=0}^{\infty} \sum_{m=-n}^{n} l_{nm} Y_{nm}(\theta,\phi)$$

• Reflectance

$$r(\theta,\phi) = k * \ell \approx \sum_{n=0}^{2} \sum_{m=-n}^{n} k_n l_{nm} Y_{nm}(\theta,\phi)$$

• Approximation accuracy, 99.2% (Basri & Jacobs; Ramamoorthi & Hanrahan)

Harmonic transform of kernel





Subspace approximation

- Up to 2nd order:
 - 9 basis images
 - Accuracy: 99.2%
- Up to 1st order:
 - 4 basis images: ambient + point source
 - Accuracy: 87.5%
- In practice, due to self occlusions ~98% can be achieved with just 6 basis images (Ramamoorthi)

Scope

- Harmonic representations handle convex, lambertian objects with multiple light sources (including attached shadows)
- Harmonic representations do not model cast shadows and inter-reflections
- Accuracy is maintained for fairly close light sources
- Representing specular objects may require a very large basis



Applications

- We can use this theory to predict novel appearances under new lighting
- Harmonic lighting theory has led to applications in
 - Face recognition
 - Photometric stereo
 - 3D reconstruction with prior
 - Motion analysis

"Harmonic faces"



Non-negative light

- We can enforce in addition that light is nonnegative, by projecting the illumination cone onto the harmonic space
- Closed-form constraints for 1st order approximation
- Sampling method, or Toeplitz matrix (Shirdhonkar & Jacobs) for higher orders

Photometric stereo

(Basri, Jacobs & Kemelmacher)



SVD recovers *L* and *S* up to an $(r \times r)$ ambiguity

Photometric stereo



Reconstruction with a prior

(Kemelmacher & Basri)

- Given just one image SFS is impractical
- Reconstruction is possible when a prior is available
- Energy

$$\min_{l,\rho,Z} \iint_{\Omega} D + S$$

• Data term

$$D = (I - \rho l^T Y(\hat{n}))^2$$

- Regularization $S = \lambda_1 \left(\Delta (Z - Z_{prior}) \right)^2 + \lambda_2 \left(\Delta (\rho - \rho_{prior}) \right)^2$
- Solve as a linear PDE

Reconstruction with a prior





























More...

























Mooney faces



(Kemelmacher, Nadler & B, CVPR 2008)

Motion + lighting



Motion + lighting

(Basri & Frolova)

- Given 2 images $I(p) = \rho l^T \hat{n} \qquad J(p') = \rho l^T R \hat{n}$
- Take ratio to eliminate albedo $\frac{J(p')}{I(p)} = \frac{l^T R n}{l^T n}$
- If motion is small we can represent J(p') using a Taylor expansion around p

Small motion

• We obtain a PDE that is quasi linear in z

$$az_x + bz_y = c$$

• Where

$$a(x, y, z) = l_1(I_{\theta} - zJ_x) - l_3I$$

$$b(x, y, z) = l_2(I_{\theta} - zJ_x)$$

$$c(x, y, z) = -l_3(I_{\theta} - zJ_x) - l_1I$$

with

$$I_{\theta} = \frac{J - I}{\theta}$$

• Can be solved with continuation (characteristics)

Reconstruction









More reconstructions



Conclusion

- Understanding the effect of lighting on images is challenging, but can lead to better interpretation of images
- Harmonic analysis allows to model complex lighting in a linear model
- Various applications in recognition and reconstruction
- We only looked at Lambertian objects...