

# A consistent algorithmic framework for structured machine learning

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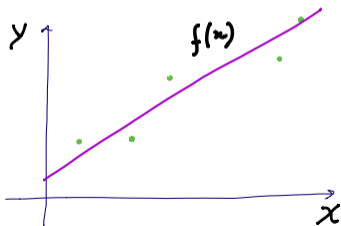
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joint work with C. Ciliberto (Imperial College), A. Rudi (INRIA-Paris)

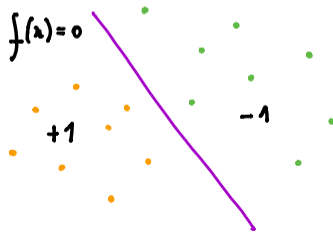
# Classic supervised learning

given  $\{(x_1, y_1), \dots, (x_n, y_n)\}$  find  $f(x_{\text{new}}) \sim y_{\text{new}}$

## Regression



## Binary classification



## Structured learning

“A domain of machine learning, in which the prediction must satisfy the additional constraints found in **structured data**, poses one of machine learning’s greatest challenges: learning functional dependencies between arbitrary input and output domains.”

Bakir et al., Predicting structured data. MIT press, 2007. [1]

## Structured learning applications

- ▶ Image segmentation [2],
- ▶ captioning [3],
- ▶ speech recognition [4, 5],
- ▶ protein folding [6],
- ▶ ordinal regression [7],
- ▶ ranking [8].

## Examples of “structured” outputs

- ▶ Finite discrete alphabets (binary/multi-category classification, multilabel),
- ▶ strings,
- ▶ ordered lists,
- ▶ sequences.

Classically only discrete possibly output spaces.

# Classical approaches

## Likelihood estimation models

- ▶ General approaches (Struct-SVM [9], Conditional Random Fields [10]),
- ▶ but limited guarantees (generalization bounds).

## Surrogate approaches

- ▶ Strong theoretical guarantees,
- ▶ but ad hoc, e.g. classification [11], multiclass [12], ranking [8]. . .

We will try to take the best of both!

# Outline

Framework

Algorithms

Theory

Experiments

## Statistical learning

- ▶  $(\mathcal{X} \times \mathcal{Y}, \rho)$  probability space, such that  $\rho(x, y) = \rho_{\mathcal{X}}(x)\rho(y|x)$ .
- ▶  $\Delta : \mathcal{Y} \times \mathcal{Y} \rightarrow [0, \infty)$



## Statistical learning

- ▶  $(\mathcal{X} \times \mathcal{Y}, \rho)$  probability space, such that  $\rho(x, y) = \rho_{\mathcal{X}}(x)\rho(y|x)$ .
- ▶  $\Delta : \mathcal{Y} \times \mathcal{Y} \rightarrow [0, \infty)$

Problem Solve

$$\min_{f \in \mathcal{Y}^{\mathcal{X}}} \int d\rho(x, y) \Delta(f(x), y)$$

given  $(x_i, y_i)_{i=1}^n$  i.i.d. samples of  $\rho$ .

## Empirical risk minimization (ERM)

$$\min_{f \in \mathcal{H}} \frac{1}{n} \sum_{i=1}^n \Delta(f(x_i), y_i)$$

- ▶ Statistically sound

$$\sup_{f \in \mathcal{F}} \left| \frac{1}{n} \sum_{i=1}^n \Delta(f(x_i), y_i) - \int d\rho(x, y) \Delta(f(x), y) \right|$$

- ▶ Impractical: how to pick  $\mathcal{F} \subset \mathcal{Y}^{\mathcal{X}}$  if  $\mathcal{Y}$  is not linear?

## Inner risk

Lemma (Ciliberto, Rudi, R. '17)

*Let*

$$f_* = \operatorname{argmin}_{f \in \mathcal{Y}^{\mathcal{X}}} \int d\rho(x, y) \Delta(f(x), y)$$

*then*

$$f_*(x) = \operatorname{argmin}_{y \in \mathcal{Y}} \int d\rho(y|x) \Delta(y, y').$$

## Structured Encoding Loss Function (SELF)

### Definition (SELF)

The loss function  $\Delta : \mathcal{Y} \times \mathcal{Y} \rightarrow [0, \infty)$  is such that there exists

- ▶ a real separable Hilbert space  $(\mathcal{H}, \langle \cdot, \cdot \rangle)$  and
- ▶ maps  $\Psi, \Phi : \mathcal{Y} \rightarrow \mathcal{H}$

such that  $\forall y, y' \in \mathcal{Y}$

$$\Delta(y, y') = \langle \Psi(y), \Phi(y') \rangle$$

## Examples of SELF

- ▶ In any finite output spaces  $|\mathcal{Y}| = T$

$$\Delta(y, y') = e_y^\top V e_{y'}, \quad V \in \mathbb{R}^{T \times T}.$$

- ▶ Symmetric positive definite loss functions, Kernel Dependency Estimator [16].
- ▶ Smooth loss functions with  $\mathcal{Y} = [0, 1]^d$ .
- ▶ Restriction of SELF are SELF, and SELF can be composed.

## Structured statistical learning

$$(\mathcal{Y}, \Delta)$$

- ▶ The output space might not be a linear space and can be continuous.
- ▶ Structure encoded by the loss function.

Beyond finite, discrete spaces to include continuous output spaces, e.g.

- ▶ Manifold regression [14],
- ▶ prediction of probability distributions [15].

## Inner SELF (risk)

$$\int d\rho(y|x)\Delta(f(x), y) = \int d\rho(y|x) \langle \Psi(y), \Phi(y') \rangle = \left\langle \underbrace{\int d\rho(y|x)\Psi(y)}_{g_*(x)}, \Phi(y') \right\rangle$$

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Lemma (Ciliberto, Rudi, R. '17)

$$f_*(x) = \operatorname{argmin}_{y \in \mathcal{Y}} \langle g_*(x), \Phi(y) \rangle$$

$$g_* = \int d\rho(y|\cdot)\Psi(y) = \operatorname{argmin}_{g \in \mathcal{H}^x} \int d\rho(x, y) \|g(x) - \Psi(y)\|^2$$



## Inner risk minimization (IRM)

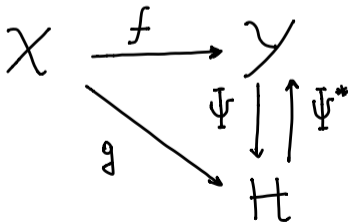
$$\hat{f}(x) = \operatorname{argmin}_{y \in \mathcal{Y}} \langle \hat{g}(x), \Phi(y) \rangle$$

$$\hat{g} = \operatorname{argmin}_{g \in \mathcal{G} \subset \mathcal{H}^{\mathcal{X}}} \frac{1}{n} \sum_{i=1}^n \|g(x_i) - \Psi(y_i)\|^2$$

## IRM: a general surrogate approach

- ▶ encode  $\Psi : \mathcal{Y} \rightarrow \mathcal{H}$
- ▶ learn  $(x_i, \Psi(y_i))_{i=1}^n \mapsto \hat{g}$
- ▶ decode  $\Psi^* : \mathcal{H} \rightarrow \mathcal{Y}$

$$\Psi^*(h) = \operatorname{argmin}_{y \in \mathcal{Y}} \langle h, \Phi(y) \rangle, \quad h \in \mathcal{H}.$$



## Some questions

- ▶ A minimization over  $\mathcal{Y}$  instead of  $\mathcal{Y}^x$ : what we gained?
  
- ▶ Does a SELF exist?

# Outline

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## Solving IRM with linear estimators

$$\hat{f}(x) = \operatorname{argmin}_{y \in \mathcal{Y}} \langle \hat{g}(x), \Phi(y) \rangle, \quad \hat{g} = \operatorname{argmin}_{g \in \mathcal{G}} \frac{1}{n} \sum_{i=1}^n \|g(x_i) - \Psi(y_i)\|^2.$$

## Solving IRM with linear estimators

$$\hat{f}(x) = \operatorname{argmin}_{y \in \mathcal{Y}} \langle \hat{g}(x), \Phi(y) \rangle, \quad \hat{g} = \operatorname{argmin}_{g \in \mathcal{G}} \frac{1}{n} \sum_{i=1}^n \|g(x_i) - \Psi(y_i)\|^2.$$

Lemma (Ciliberto, Rudi, R. '17)

If  $g(x) = Wx$ , then

$$W = (\hat{X}^\top \hat{X})^{-1} \hat{X}^\top \hat{Y}, \quad \hat{X} \in \mathbb{R}^{nd}, \quad \hat{Y} \in \mathcal{H}^n$$

and

$$\hat{g}(x) = \sum_{i=1}^n \alpha_i(x) \Psi(y_i), \quad \alpha(x) = (\hat{X} \hat{X}^\top)^{-1} \hat{X} x \in \mathbb{R}^n$$

## Implicit IRM for linear estimators

$$\hat{f}(x) = \operatorname{argmin}_{y \in \mathcal{Y}} \langle \hat{g}(x), \Phi(y) \rangle, \quad \hat{g} = \operatorname{argmin}_{g \in \mathcal{G}} \frac{1}{n} \sum_{i=1}^n \|g(x_i) - \Psi(y_i)\|^2.$$

Lemma (Ciliberto, Rudi, R. '17)

*If*

$$\hat{g}(x) = \sum_{i=1}^n \alpha_i(x) \Psi(y_i),$$

*then*

$$\hat{f}(x) = \operatorname{argmin}_{y \in \mathcal{Y}} \sum_{i=1}^n \alpha_i(x) \Delta(y_i, y)$$

## Other linear estimators

$$\hat{g}(x) = \sum_{i=1}^n \alpha_i(x) \Psi(y_i),$$

- ▶ Kernel methods  $g(x) = W\gamma(x)$ , where  $\gamma : \mathcal{X} \rightarrow (\mathcal{H}_\Gamma, \langle \cdot, \cdot \rangle_\Gamma)$ .
- ▶ Local kernel estimators.
- ▶ Spectral filters.
- ▶ Sketching/random features/Nystrom.



## Computations: no free lunch

### Training

$$\hat{g} = \operatorname{argmin}_{g \in \mathcal{G}} \frac{1}{n} \sum_{i=1}^n \|g(x_i) - \Psi(y_i)\|^2.$$

Computing  $(\alpha_i(x))_i$  depends only on the inputs and is efficient.

### Prediction

$$\hat{f}(x) = \operatorname{argmin}_{y \in \mathcal{Y}} \sum_{i=1}^n \alpha_i(x) \Delta(y_i, y).$$

Requires problem specific decoding and can be hard.

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## Consistency and excess risk bounds

Problem Solve

$$\min_{f \in \mathcal{Y}^{\mathcal{X}}} R(f), \quad R(f) = \int d\rho(x, y) \Delta(f(x), y)$$

given  $(x_i, y_i)_{i=1}^n$  i.i.d. samples of  $\rho$ .

Excess risk Convergence and rates on

$$R(\hat{f}) - R(f_*)$$

## A relaxation error analysis

Let

$$L(g) = \int d\rho(x, y) \|g(x) - \Psi(y)\|^2$$

Theorem (Ciliberto, Rudi, R. '17)

The following hold:

- ▶ Fisher consistency

$$f_*(x) = \Psi^* g_*(x). \quad a.s.$$

- ▶ Comparison inequality, for all  $g$  and  $f(x) = \Psi^* g(x)$  a.s.

$$R(f) - R(f_*) \leq c_\Delta \sqrt{L(g) - L(g_*)}$$

where

$$c_\Delta = \sup_{y \in \mathcal{Y}} \|\Psi(y)\|$$

## Consistency and rates for IRM-KRR

Let  $\hat{g}_\lambda(x) = \hat{W}_\lambda \gamma(x)$  with

$$\hat{W}_\lambda = \operatorname{argmin}_{W \in \mathcal{L}_2(\mathcal{H}_\Gamma, \mathcal{H})} \frac{1}{n} \sum_{i=1}^n \|W x_i - \Psi(y_i)\|^2 + \lambda \|W\|_2^2.$$

### Theorem (Ciliberto, Rudi, R. '17)

Let  $\kappa_\gamma = \sup_{x \in \mathcal{X}} \|\gamma(x)\|$ . Assume  $\exists W_* \in \mathcal{L}_2(\mathcal{H}_\Gamma, \mathcal{H})$  such that  $g_*(x) = W_* x$ . If  $\lambda_n = O(1/\sqrt{n})$ , then with probability at least  $1 - 8e^{-\tau}$

$$\sqrt{L(\hat{g}) - L(g_*)} \leq 24 \kappa_\gamma (1 + \|W\|_2) \tau^2 n^{-1/4}.$$

and for  $\hat{f}(x) = \Psi^* \hat{g}_\lambda(x)$  a.s.

$$R(\hat{f}) - R(f_*) \leq 24 \kappa_\gamma c_\Delta (1 + \|W\|_2) \tau^2 n^{-1/4}.$$

## Remarks

- ▶ This is the first result establishing consistency and rates for structured prediction, see [13] for similar efforts.
- ▶ The bound on  $L(\hat{g}) - L(g_*)$  extend results in [17] under weaker assumptions.
- ▶ The constant  $c_\Delta$  is problem dependent. Finding a general estimate is an open problem [18].

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## Ranking

	Rank Loss
<b>Linear</b> [8]	0.430 ± 0.004
<b>Hinge</b> [19]	0.432 ± 0.008
<b>Logistic</b> [20]	0.432 ± 0.012
<b>SVM Struct</b> [9]	0.451 ± 0.008
<b>IRM-KRR</b>	<b>0.396 ± 0.003</b>

Ranking movies in the MovieLens dataset [21] (ratings (from 1 to 5) of 1682 movies by 943 users). The goal is predict preferences of a given user, i.e. an ordering of the 1682 movies, according to the user's partial ratings. We the loss [8]

$$\Delta_{rank}(y, y') = \frac{1}{2} \sum_{i,j=1}^M \gamma(y')_{ij} (1 - \text{sign}(y_i - y_j)),$$



## Fingerprints reconstruction

	$\Delta$ Deg.
KRLS	$26.9 \pm 5.4$
MR[14]	$22 \pm 6$
SP (ours)	$18.8 \pm 3.9$

Structured estimator



Original image



Ridge regression



Average absolute error (in degrees) for the manifold structured estimator (SP), the manifold regression (MR) approach in [14] and the KRLS baseline. (Right) Fingerprint reconstruction of a single image where the structured predictor achieves 15.7 of average error while KRLS 25.3. The loss is the geodesic on  $\mathcal{S}$

$$\Delta_{\mathcal{S}}(z, y) = \arccos(\langle z, y \rangle)^2$$

## Summing up

- ▶ First consistent algorithmic framework for StructML.
- ▶ A general surrogate approach.
- ▶ TBD: decoding computations+ beyond linear estimators.

## Openings



**Multiple openings for post-docs/PhD positions!**

→ **Launching: Machine Learning Genova Center!**



## Related papers

- ▶ Ciliberto, Rudi and Rosasco A consistent regularization approach for structured prediction. NIPS 2016.
- ▶ Ciliberto, Rudi and Rosasco, and Pontil. Consistent multitask learning with nonlinear output relations, NIPS 2017.
- ▶ Rudi, Ciliberto, Marconi, and Rosasco. Manifold structured prediction. NIPS 2018.
- ▶ Mroueh, Poggio, Rosasco, and Slotine. Multiclass learning with simplex coding. NIPS 2012.

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 Andrej Karpathy and Li Fei-Fei.

Deep visual-semantic alignments for generating image descriptions.

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On structured prediction theory with calibrated convex surrogate losses.  
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-  Florian Steinke, Matthias Hein, and Bernhard Schölkopf.  
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-  Charlie Frogner, Chiyuan Zhang, Hossein Mobahi, Mauricio Araya, and Tomaso A Poggio.  
Learning with a wasserstein loss.  
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