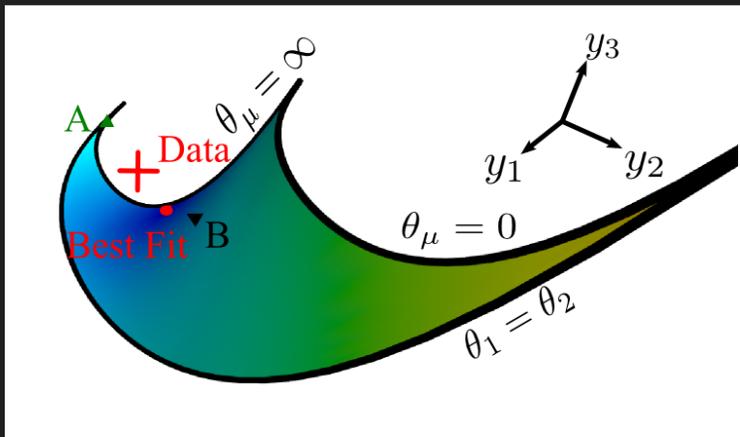
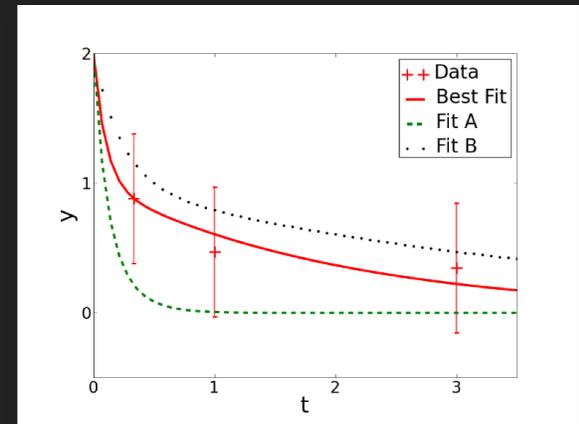
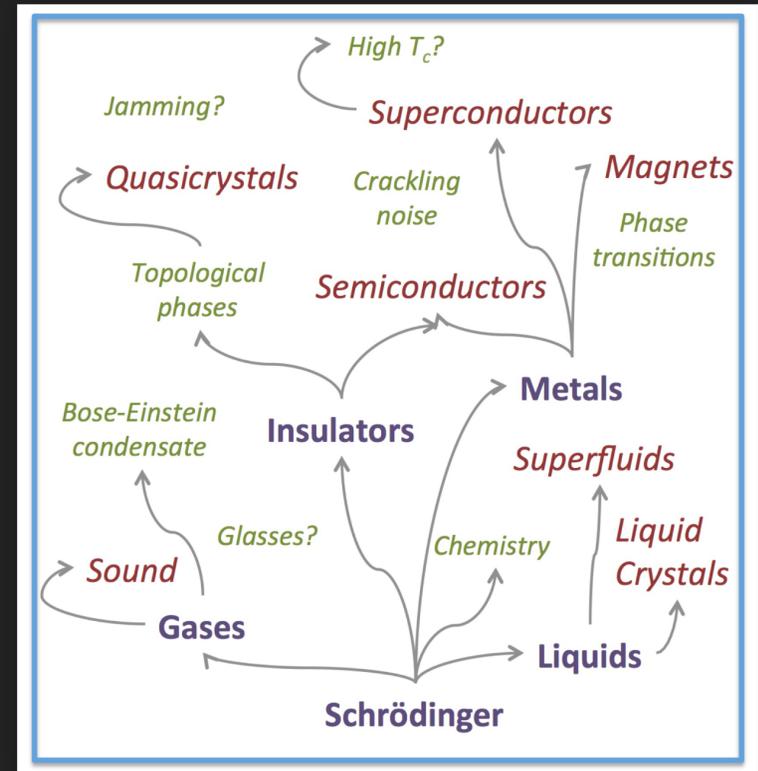


SLOPPY MODELS AND EFFECTIVE THEORIES IN PHYSICS, BIOLOGY, AND BEYOND



MARK K. TRANSTRUM
 IPAM WORKSHOP: UNCERTAINTY
 QUANTIFICATION FOR STOCHASTIC
 SYSTEMS AND APPLICATIONS

NOVEMBER 17, 2017



OUTLINE

1. UQ and Effective Theories in Physics
2. Sloppy Models
3. Information Geometry
4. Manifold Boundary Approximation Method (MBAM)
5. Information Topology

UNCERTAINTY QUANTIFICATION

TYPES OF UNCERTAINTY

- Parametric Uncertainty
- Structural Uncertainty
- Experimental Uncertainty
- Algorithmic Uncertainty

MODELING QUESTIONS

- Model Selection/Model Reduction
- Model Complexity
 - Accuracy
 - Computability

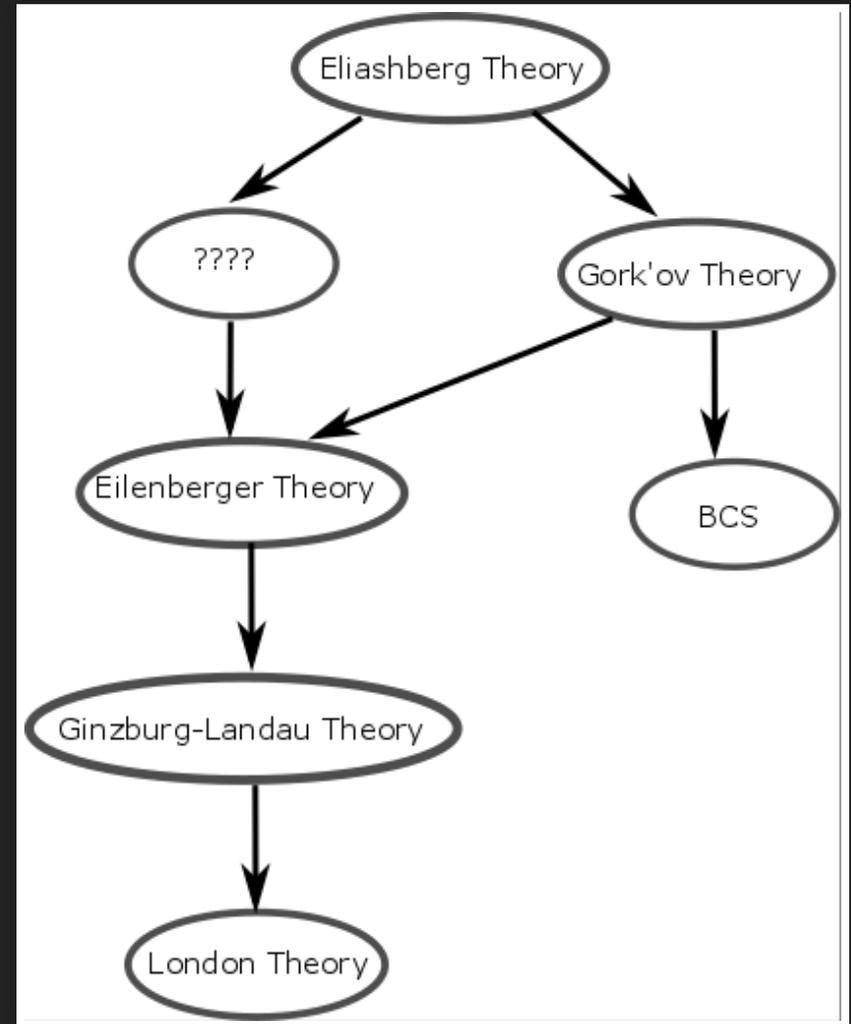
EXAMPLE: SUPERCONDUCTIVITY

CENTER FOR BRIGHT BEAMS

cbb.cornell.edu

Goal: Make material-specific predictions to guide development of the next generation of particle accelerators.

- Hierarchy of potential models
- Simple models are special cases of more complicated theories
- Partially ordered set (Hasse Diagram)



HIERARCHY OF SCIENTIFIC THEORIES

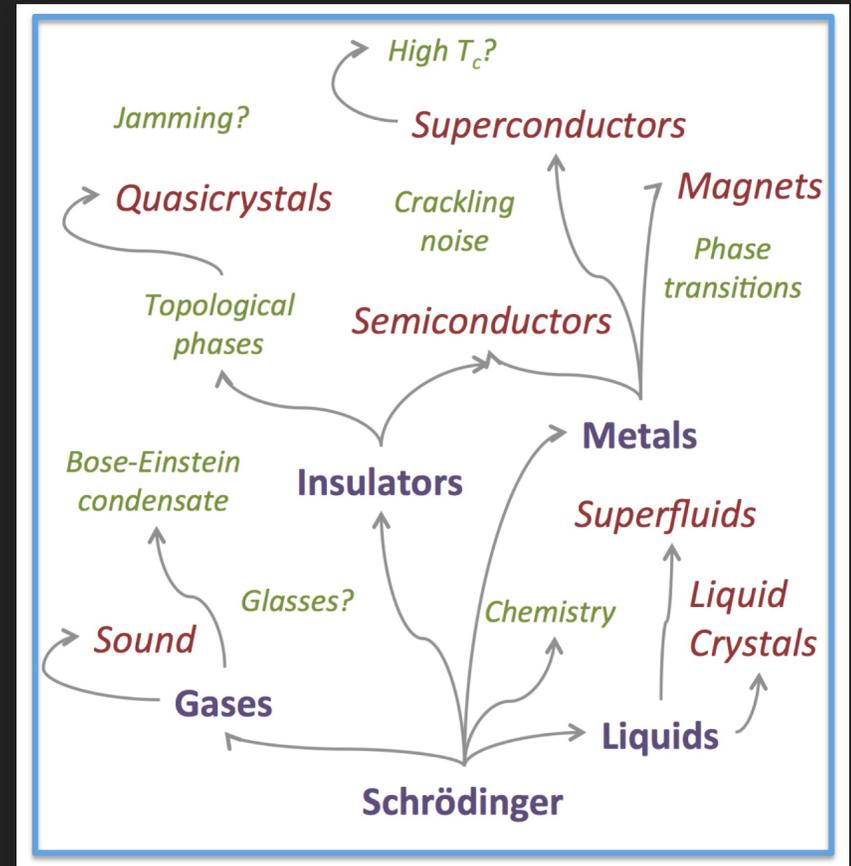
MANY PRACTICAL QUESTIONS:

- Parameter estimation
- Numerical methods
- Experimental design
- Large scale models demand new computational and theoretical tools (UQ).

More broadly, how do we organize our knowledge about the world?

And why?

- Reductionism
- Emergence



PHILOSOPHY OF SCIENCE

- Wigner: Mathematics [modeling] has been unreasonably successful at explaining physical phenomena
- Anderson: More is Different
 - Reductionism vs. Constructionism
 - Simple theories are organized hierarchically
 - Very different systems can be described by the same theory
 - Equivalence classes of physical systems described by the same model (Universality)
- Goldenfeld & Kadanoff: Don't model bulldozers with quarks.
 - Use the right level of description to catch the phenomena of interest.
- David Pines: Protectorates
 - A collective behavior whose "properties are determined by higher organizing principles and nothing else"

AN INFORMATION THEORY PERSPECTIVE: (EMERGENT) PHYSICAL LAWS ARE EFFICIENT DATA COMPRESSIONS SCHEMES.

Shannon Information: $H(X) = -\langle \log(P(X)) \rangle$

- Absolute bound on lossless compression

Fisher Information: $I(\theta) = -\langle \nabla_{\theta}^2 \log P \rangle = \langle \nabla_{\theta} \log P \nabla_{\theta} \log P \rangle$

- Information carried by random variable about parameters θ

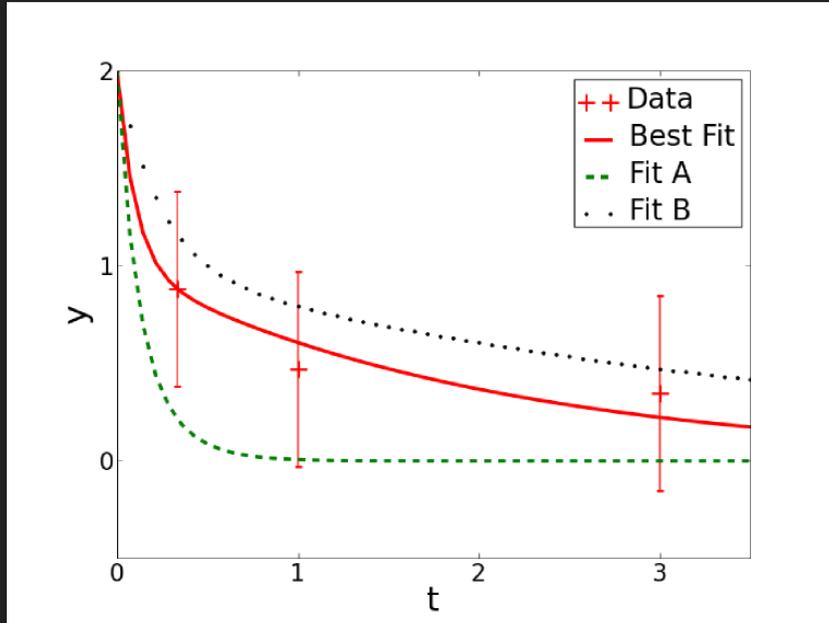
Algorithmic Complexity

- Kolmogorov: shortest string (program) that will reproduce some data
- Human-Interpretable
- Floating Point Operations
- Memory
- Internal Precision

OUR FRAMEWORK

- Model: Mapping from parameters ($\theta \in \mathbb{R}^N$) to predictions (probability distribution for a quantity of interest).
- The model mapping implies a computational algorithm for reproducing an observed distribution
- Goal: Find a computationally simpler, approximate distribution.
- Kullback-Leibler Divergence: Cost of using the wrong distribution:
 - $D_{KL}(p||q) = -\langle \log(q/p) \rangle_p$
 - How many extra bits required for encoding data using distribuion q that was drawn from p .
 - Not a proper metric.
 - Infinitesimal separation: $q = p(\theta + d\theta) \rightarrow D_{KL}(p||q) \propto d\theta^T I d\theta$
- Fisher Information (I):
 - Riemannian Metric on the space of probability distributions $I \rightarrow g$.
 - Information Geometry
- Strategy: Use computational differential geometry to explore the space equivalent models.

NONLINEAR REGRESSION (NLLS)



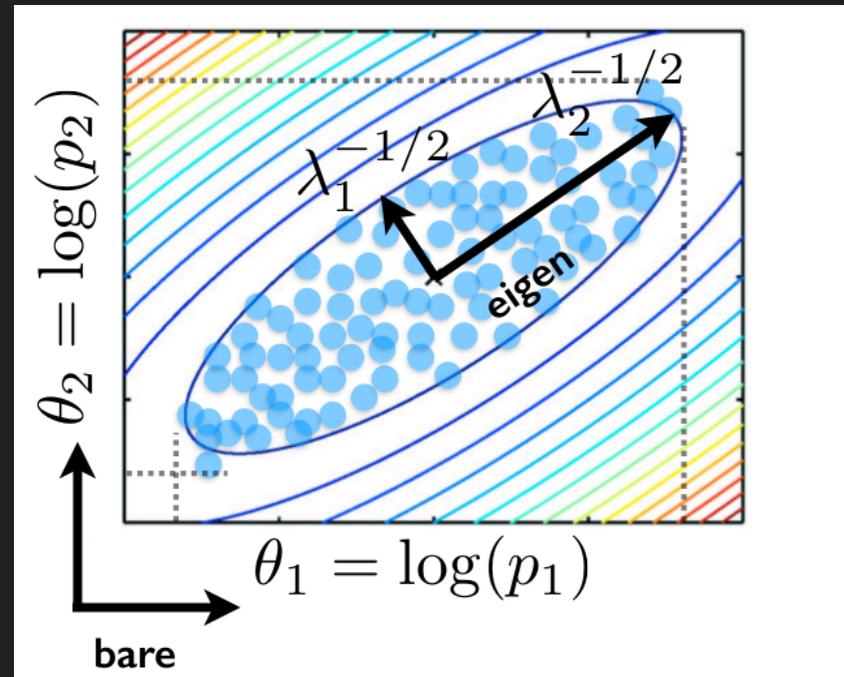
$$y(t, \theta) = e^{-\theta_1 t} + e^{-\theta_2 t}$$

$$C(\theta) = \frac{1}{2} \sum_m \left(\frac{d_m - y(t_m, \theta)}{\sigma_m} \right)^2$$
$$= \frac{1}{2} \sum_m r_m^2$$

COST SURFACE

Which parameter values are consistent with the data?

- Asymptotic Inference
- Quadratic Approximation at the best fit
- Hessian Matrix (Fisher Information Matrix)



$$H_{\mu\nu} = \partial_\mu \partial_\nu C = \frac{1}{2} \partial_\mu \partial_\nu \sum_m r_m^2$$

$$H_{\mu\nu} = \sum_m \partial_\mu r_m \partial_\nu r_m + \sum_m r_m \partial_\mu \partial_\nu r_m$$

$$H_{\mu\nu} \approx I_{\mu\nu} = (J^T J)_{\mu\nu}$$

$I_{\mu\nu}$ is intrinsic to the model, independent of the data.

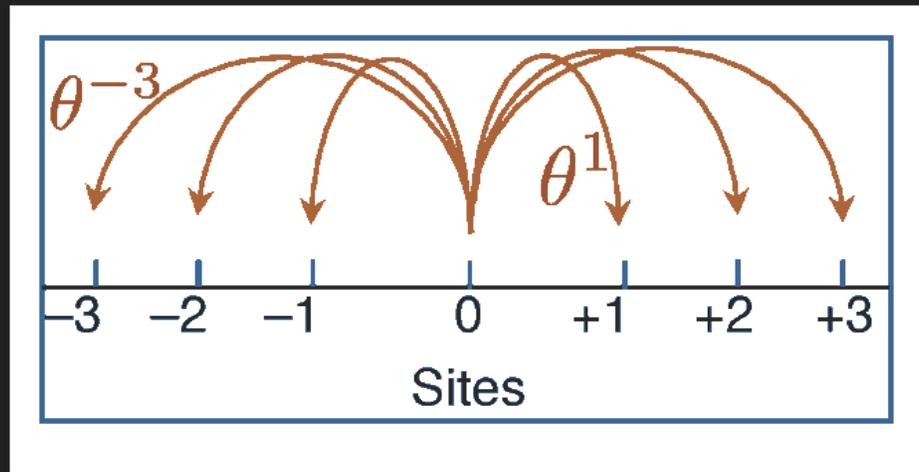
Use it to study a model class rather than a specific fitting problem.

$$\partial_\mu \equiv \frac{\partial}{\partial \theta_\mu}$$

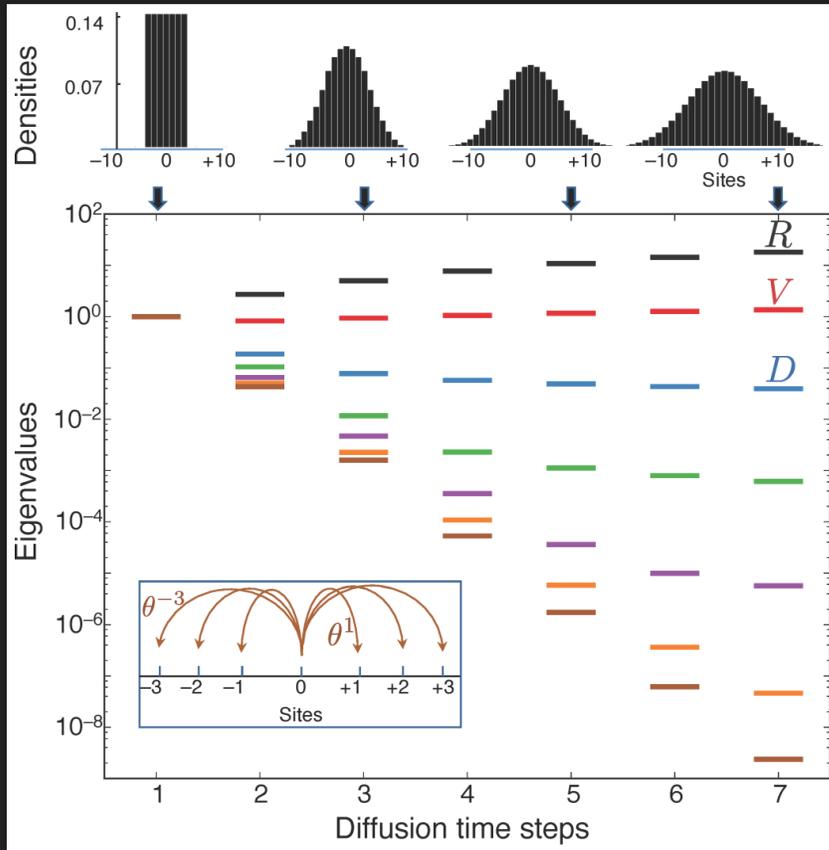
$$J_{m\mu} = \partial_\mu r_m$$

EXAMPLE: MICROSCOPIC DIFFUSION

- Particles "hopping" on a lattice
- Parameters: probability of hopping a given number of sites away
- Initial density: All particles at the origin
- Data: Observed density after several steps
- Goal: Infer the parameters from observations of density at later times



EXAMPLE: MICROSCOPIC DIFFUSION



- Short time scales, parameter inference is easy
- More difficult after observations are coarsened
- Only a few parameter combinations need to be carefully tuned to explain data
- Most parameter combinations are irrelevant: can take on *ANY* values.
- Small parameter: Ratio of scales

Machta, Benjamin B., et al. "Parameter space compression underlies emergent theories and predictive models." *Science* 342.6158 (2013): 604-607.

DIFFUSION: MICROSCOPIC TO MACROSCOPIC

- Continuum limit: Gradient expansion
 - Formally justified by the small parameter (ratio of scales)

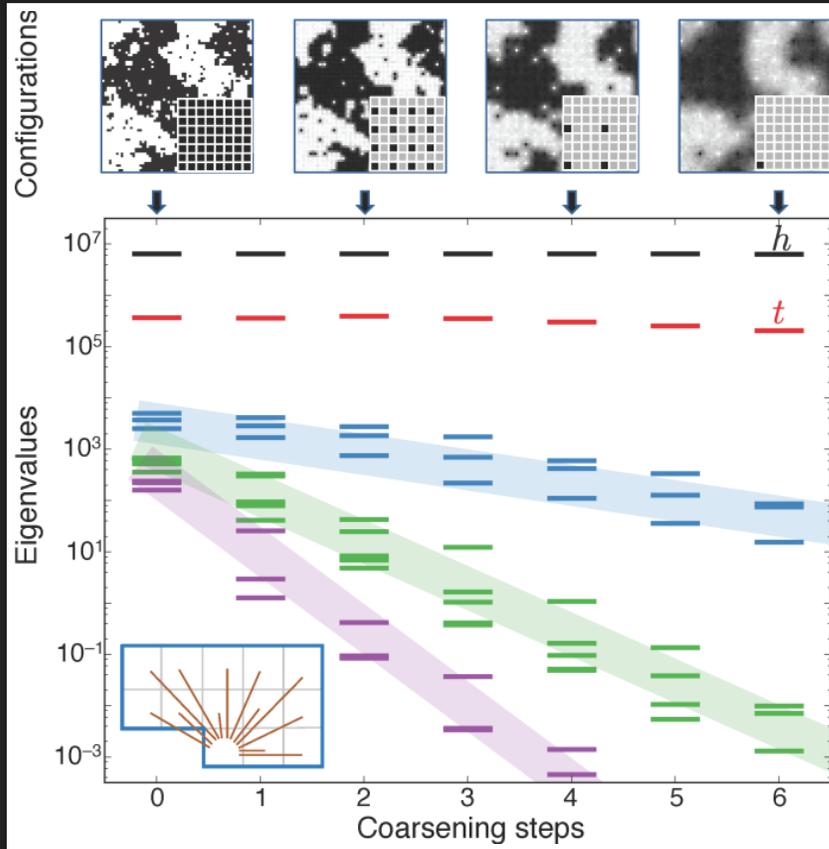
$$\frac{\partial \rho}{\partial t} = R \rho + \mathbf{v} \cdot \nabla \rho + D \nabla^2 \rho + \dots$$

- In most cases, first two terms are zero because of symmetry:

$$\frac{\partial \rho}{\partial t} = D \nabla^2 \rho$$

- Fisher Information justifies the use of a simple theory
- Intuitively, are these models equivalent?
 - One model has many parameters
 - The other model has only one parameter
 - How can a low-dimensional object approximate a higher-dimensional object?

EXAMPLE: CRITICAL PHENOMENON



Ising Model:

$$\mathcal{H} = - \sum_{\mu} \sum_{d(i,j)=\mu} \theta_{\mu} s_i s_j$$

Small parameter: (inverse system size)

Ising universality class:

- Magnets
- Liquid-Gas
- Biological Membranes

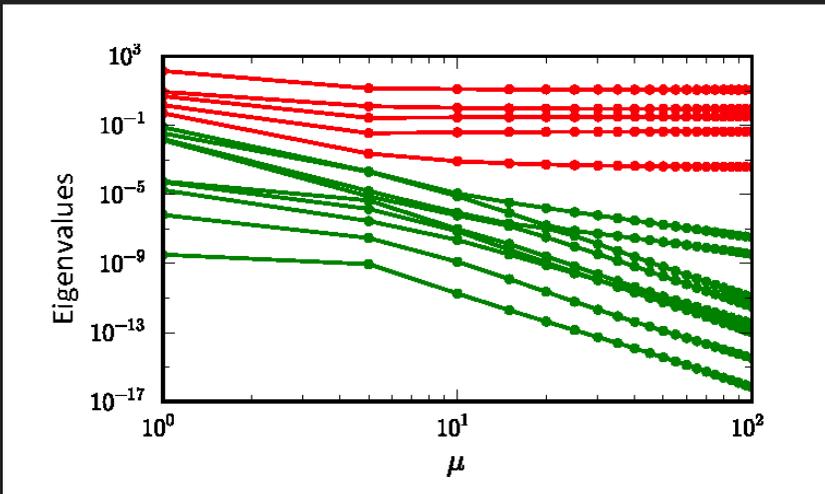
Machta, Benjamin B., et al. "Parameter space compression underlies emergent theories and predictive models." *Science* 342.6158 (2013): 604-607.

EXAMPLE: SLOW MANIFOLDS

Van der pol oscillator:

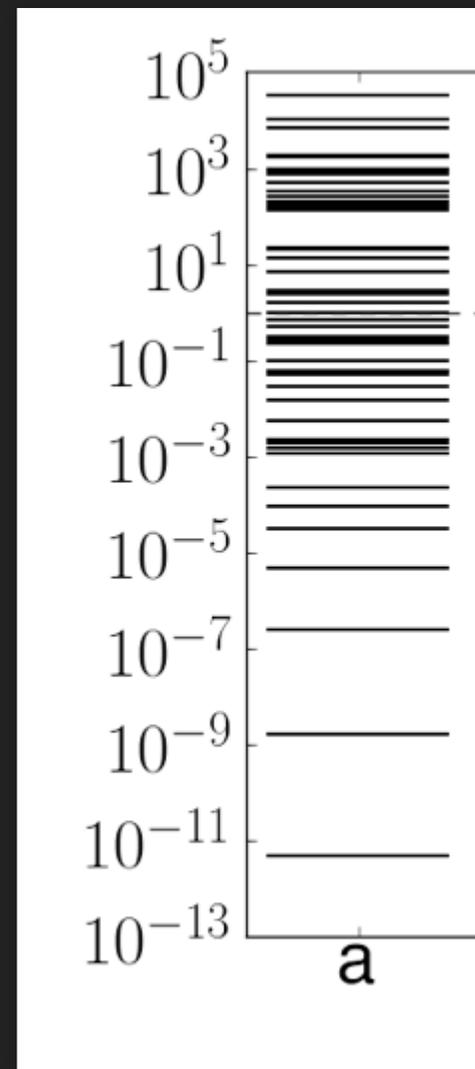
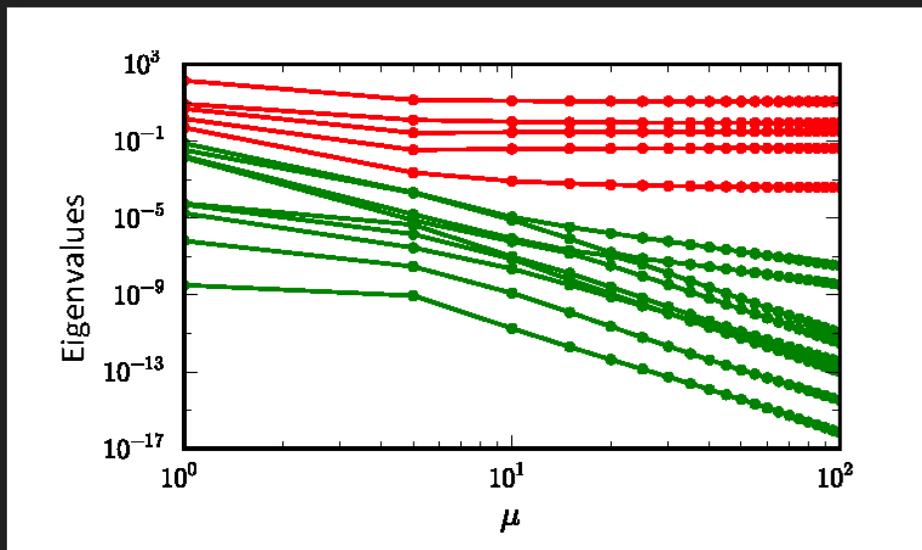
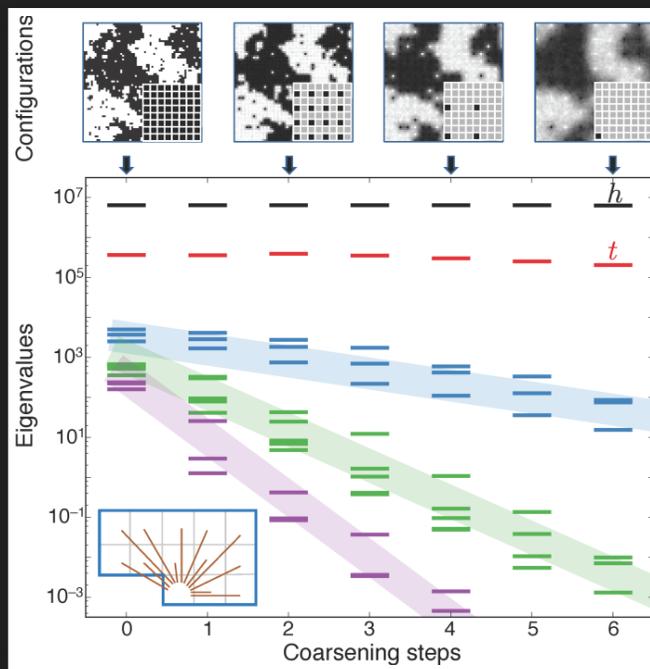
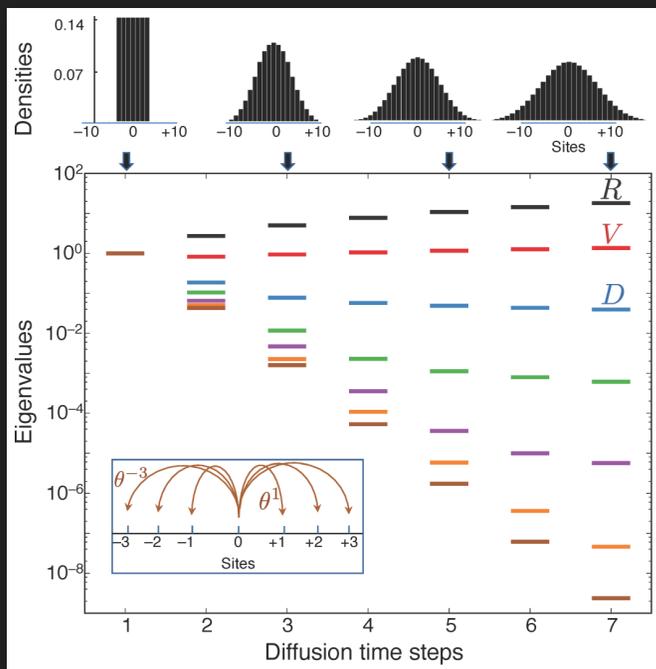
$$\mu^{-2}\dot{x} = x - \frac{x^3}{3} - y + \sum_{m,n} a_{m,n} \left(x - \frac{x^3}{3} - y \right)^m x^n$$

$$\dot{y} = x$$

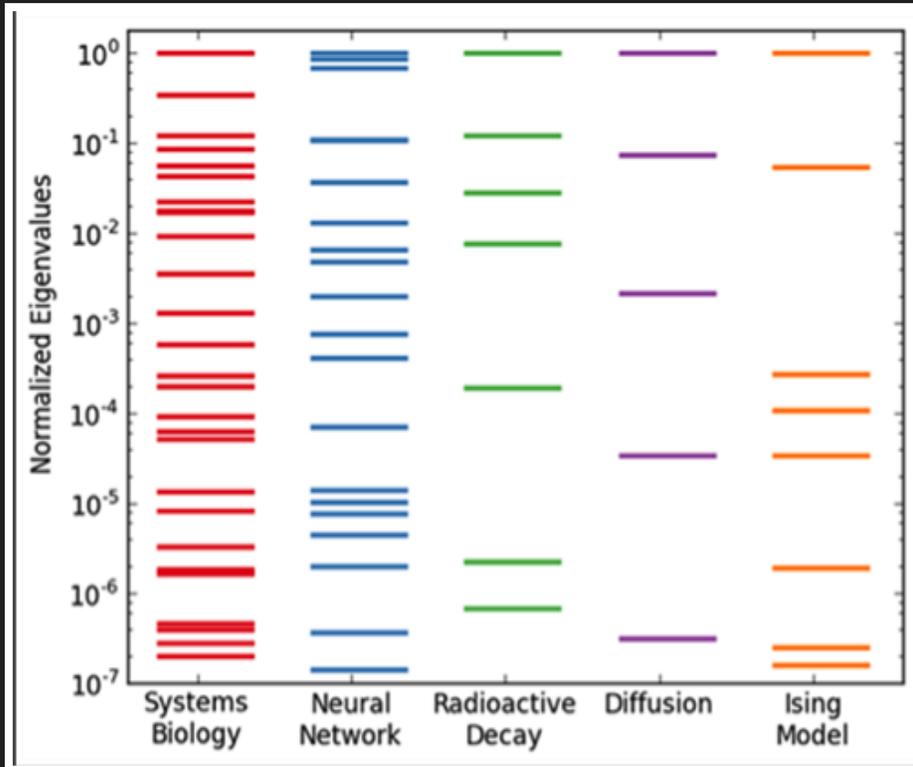


Small parameter: Ratio of time scales

Chachra, Ricky, Mark K. Transtrum, and James P. Sethna. "Structural susceptibility and separation of time scales in the van der Pol oscillator." *Physical Review E* 86.2 (2012): 026712.



SLOPPY MODELS



- Exponential Distribution of FIM eigenvalues
- Parameter inference is hard
- Lots of equivalent microscopic models
- Irrelevant (sloppy) parameter combinations can take on *ANY* values.
- Emergent "theory" hidden inside the complexity
- Low effective dimensionality

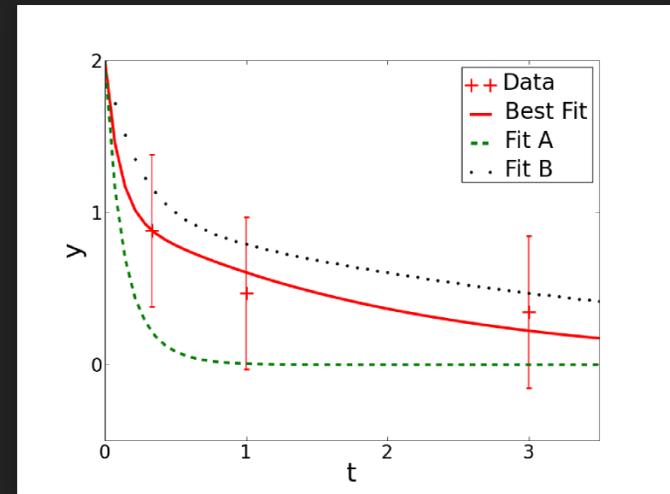
Machta, Benjamin B., et al. "Parameter space compression underlies emergent theories and predictive models." *Science* 342.6158 (2013): 604-607.

SLOPPINESS AND FISHER INFORMATION

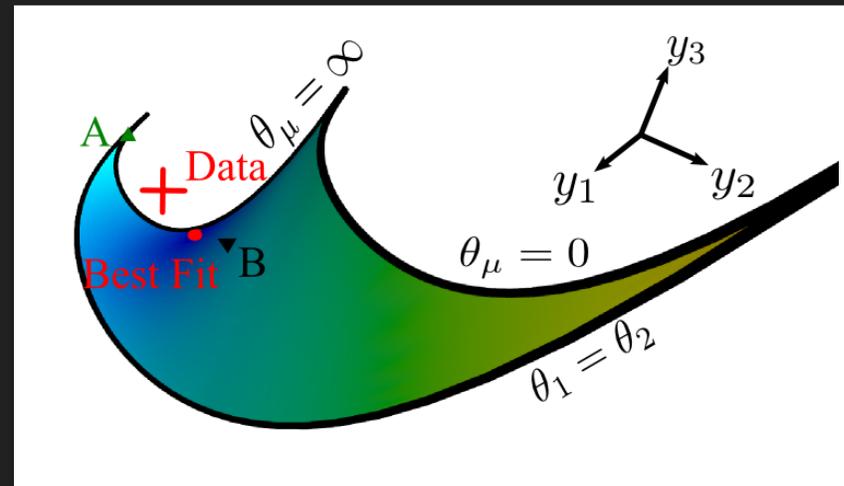
- FIM eigenvalues suggest a low effective dimensionality
 - Can we make this idea rigorous?
- What happens if we reparameterize the model?
 - Change units?
 - Rates vs. time constants?
 - Other combinations of parameters
- FIM eigenvalues can be transformed into any positive values by reparameterizing the model.
- Is there a more intrinsic measure of sloppiness?
- Answer: Information Geometry

THE MODEL MANIFOLD

- *Model Manifold*: Mapping from parameters to data
- All possible model predictions embed a manifold in the space of data with *parameters as coordinates*.
- Riemannian Metric (induced from data space) = Fisher Information Matrix
- Sloppy models are *bounded manifolds*



$$y(t, \theta) = e^{-\theta_1 t} + e^{-\theta_2 t}$$



Transtrum, Mark K., Benjamin B. Machta, and James P. Sethna. "Why are nonlinear fits to data so challenging?." *Physical review letters* **104.6** (2010): 060201.

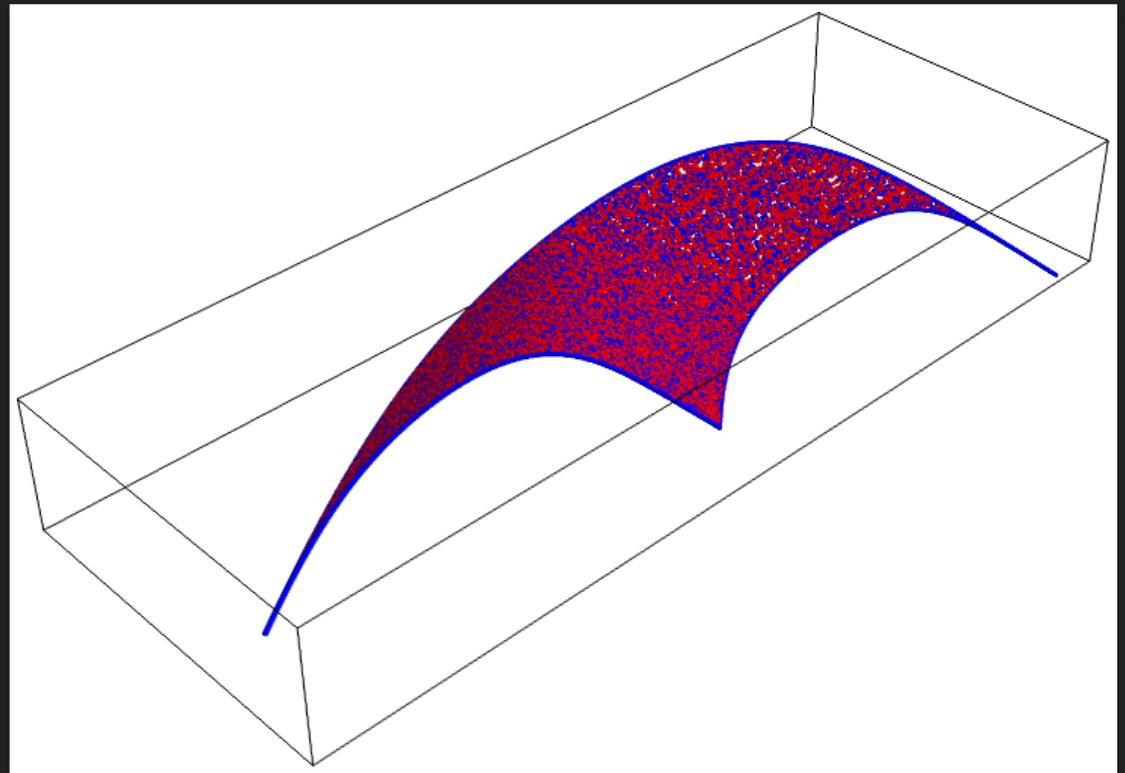
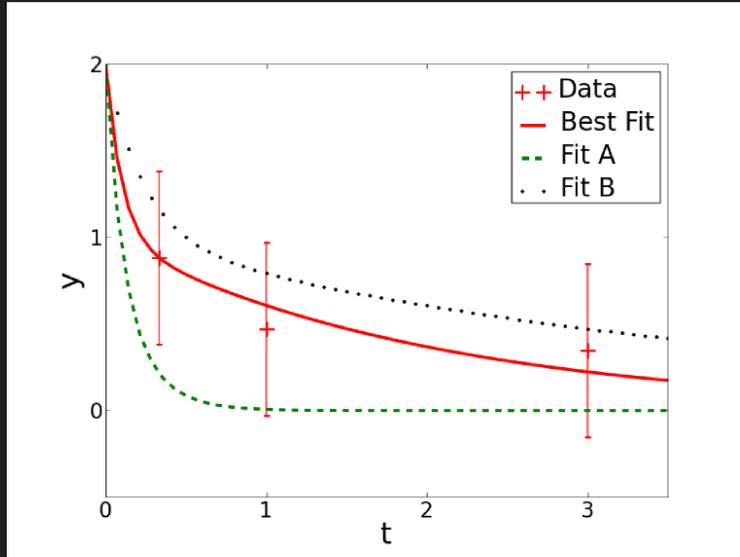
GALLERY OF MODEL MANIFOLDS

TWO EXPONENTIALS

$$y(t, \theta) = e^{-\theta_1 t} + e^{-\theta_2 t}$$

2 Parameters

3 Observations

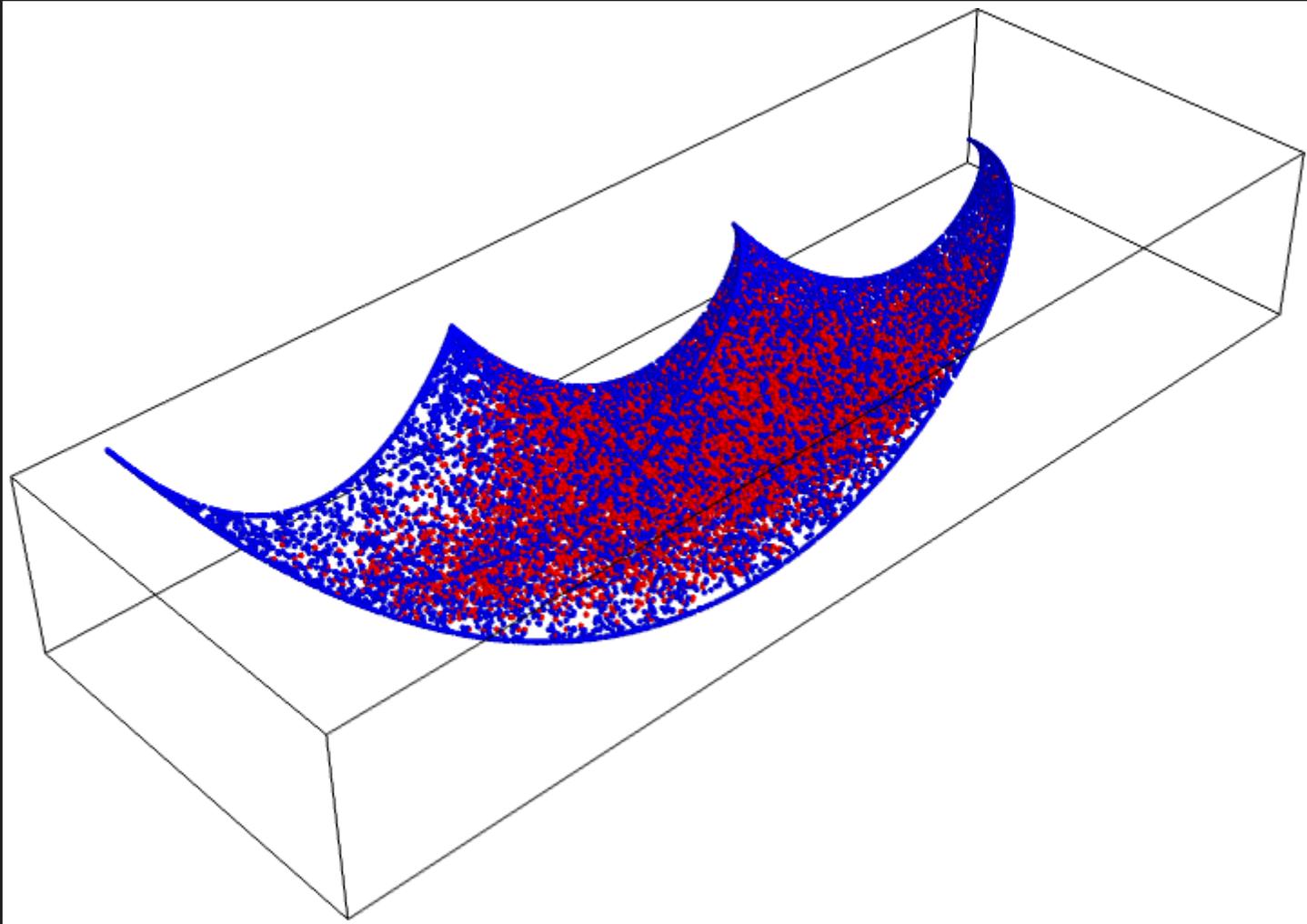


THREE EXPONENTIALS

$$y(t, \theta) = e^{-\theta_1 t} + e^{-\theta_2 t} + e^{-\theta_3 t}$$

3 Parameters

5 Observations

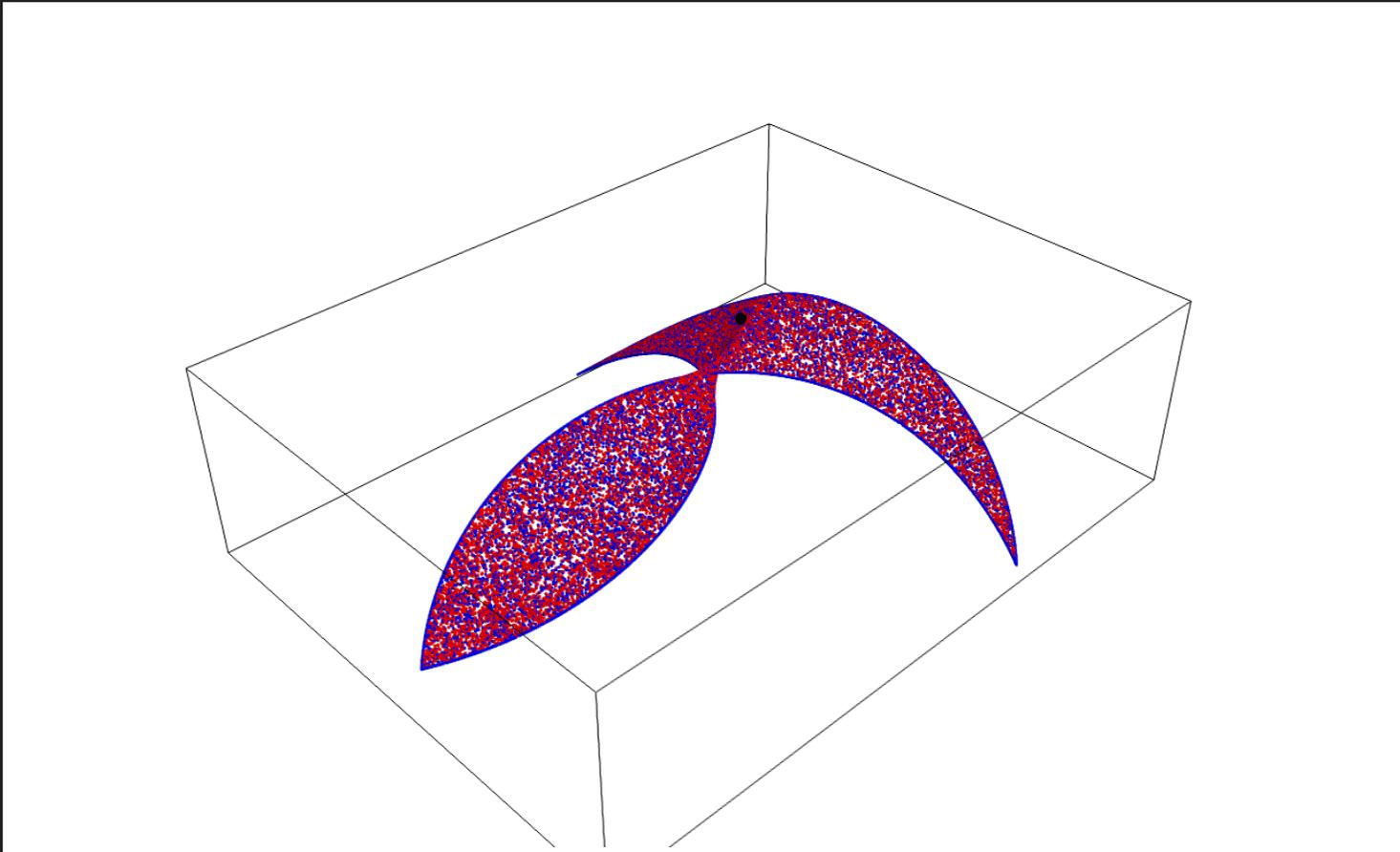


ENZYMES CATALYZED REACTION

$$y(x, \theta) = \frac{\theta_1(x^2 + \theta_2 x)}{(x^2 + \theta_3 x + \theta_4)}$$

4 (2) Parameters

11 Observations

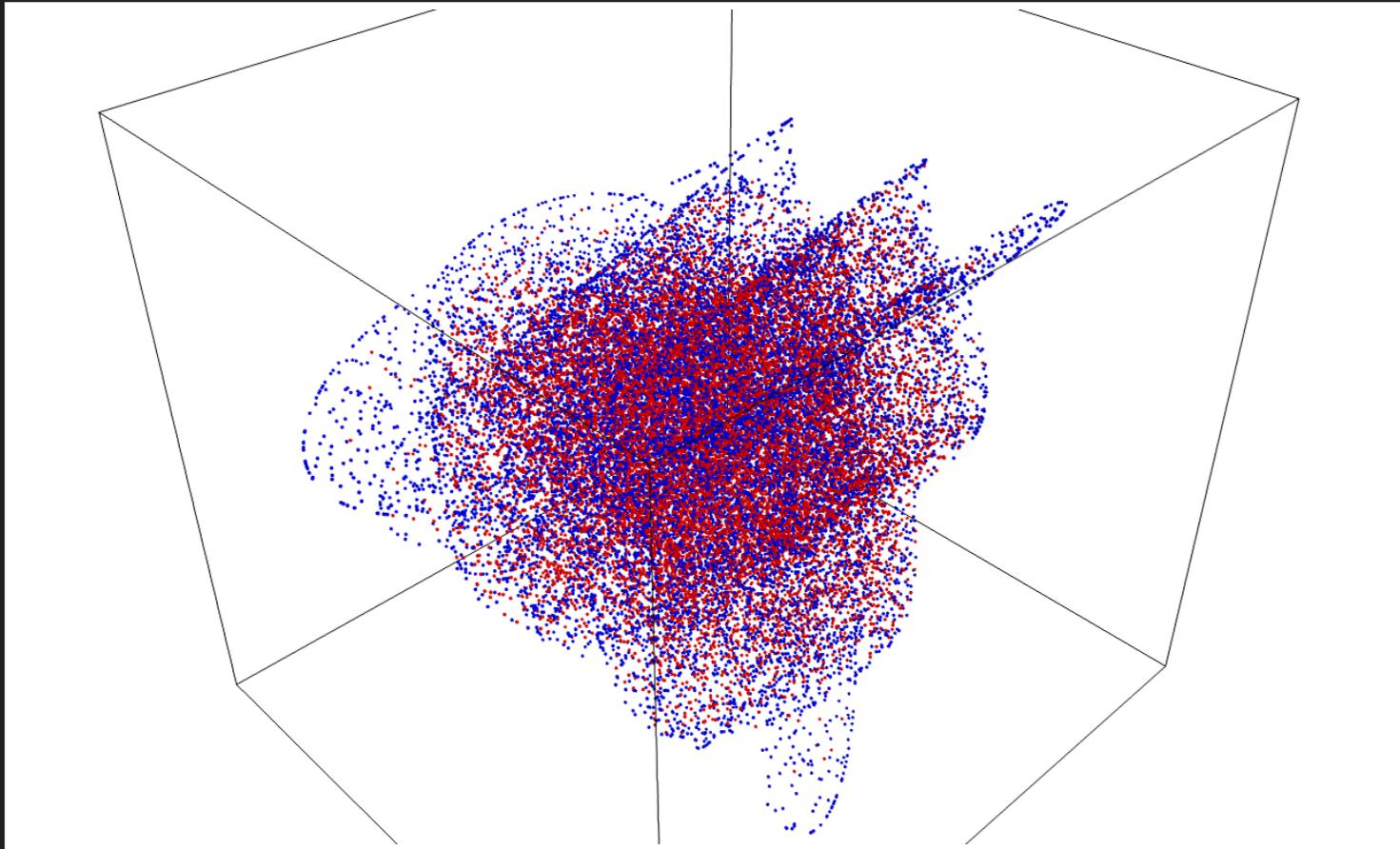


Chebyshev Quadrature

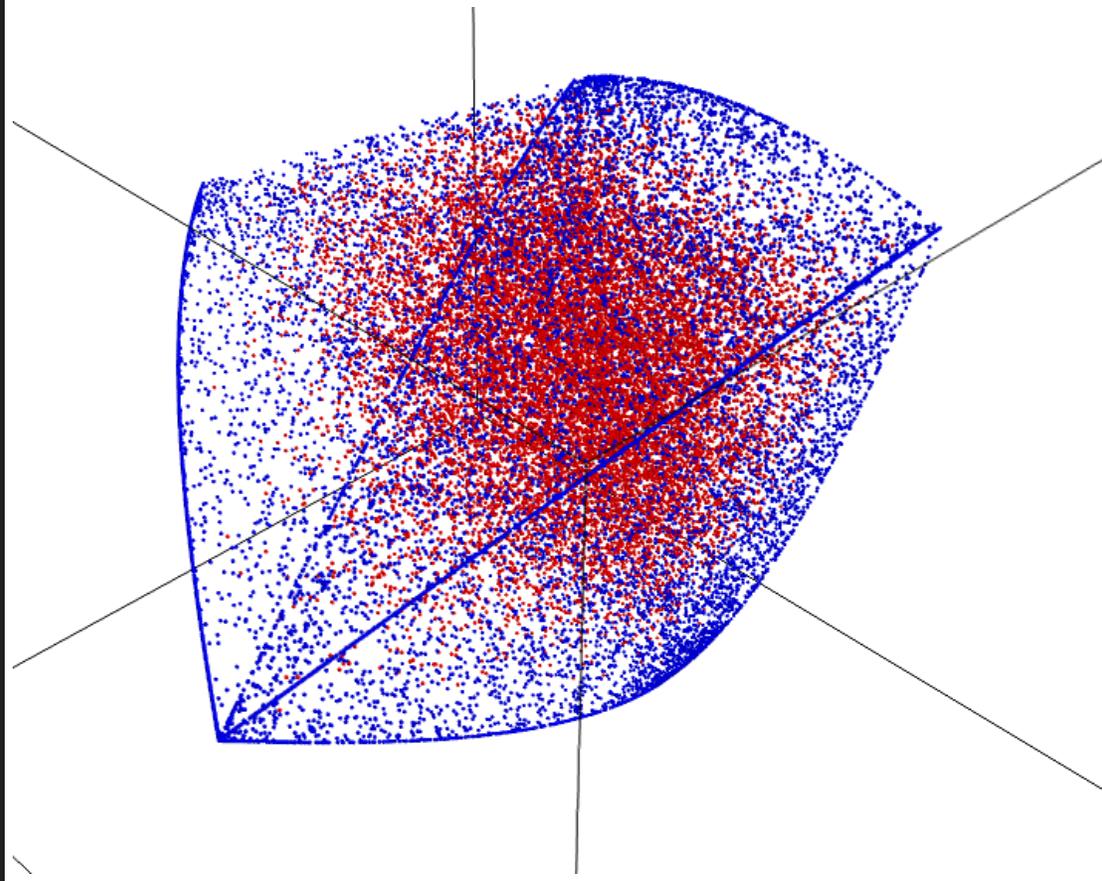
$$y_i = \frac{1}{M} \sum_j T_i(\theta_j)$$

3 Parameters

5 Observations



ISOMERIZATION OF α -PINENE



$$\dot{y}_1 = -(\theta_1 + \theta_2)y_1$$

$$\dot{y}_2 = \theta_1 y_1$$

$$\dot{y}_3 = \theta_2 y_1 - (\theta_3 + \theta_4)y_3 + \theta_5$$

$$\dot{y}_4 = \theta_3 y_3$$

$$\dot{y}_5 = \theta_4 y_3 - \theta_5 y_5$$

5 Parameters

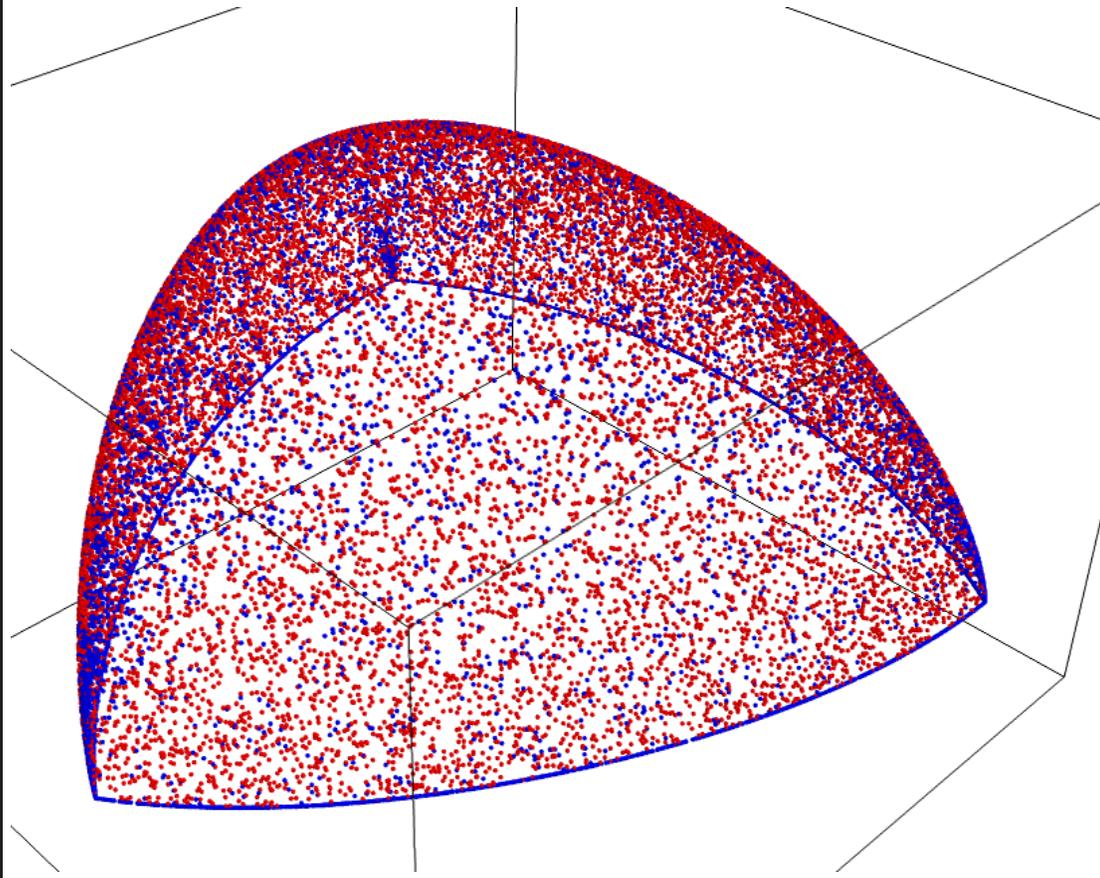
40 Observations

ISING MODEL

$$\mathcal{H} = -J_1 \sum_i s_i s_{i+1} - J_2 \sum_i s_i s_{i+2}$$
$$P(s) \propto e^{-\mathcal{H}}$$

2 Parameters

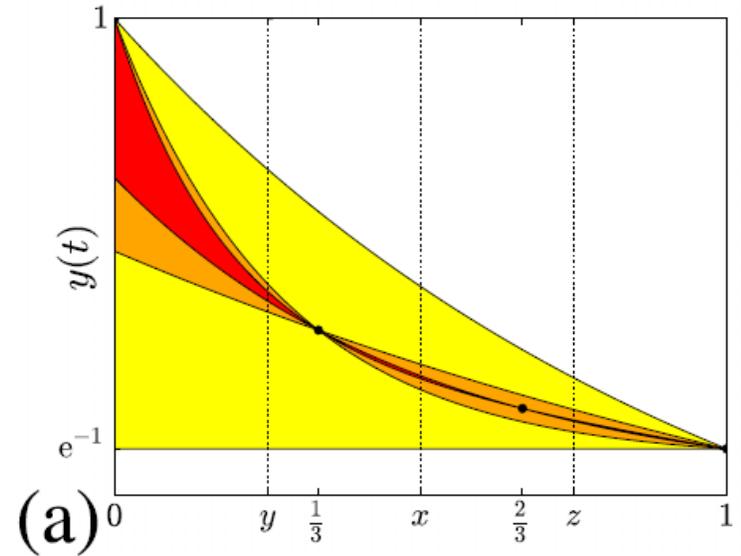
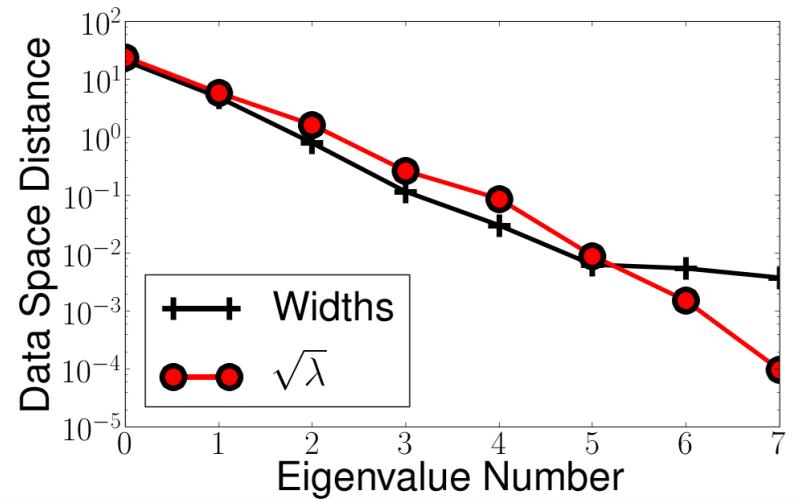
16 Observations (4 spins)



**LOW EFFECTIVE
DIMENSIONALITY**

MANIFOLD WIDTHS

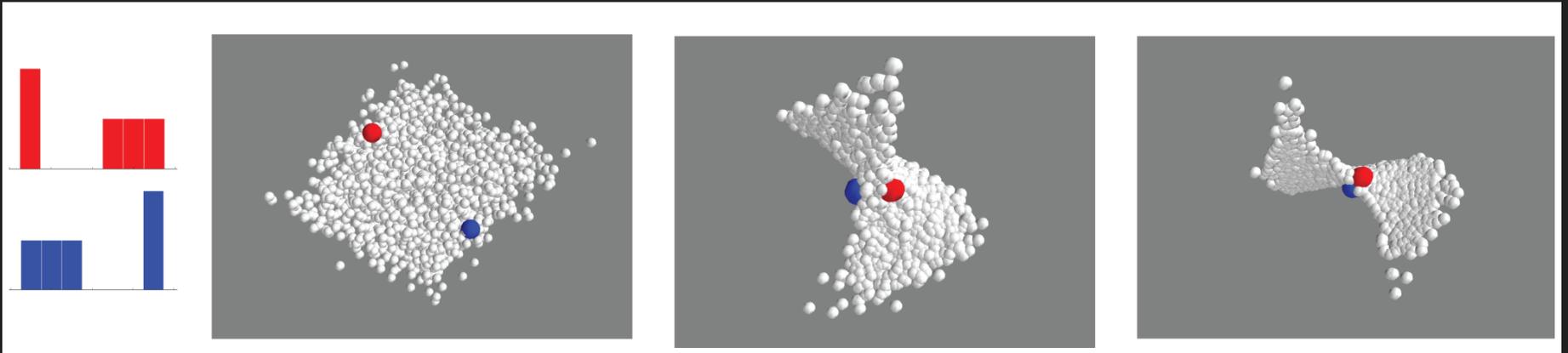
- "Measure" the manifold with geodesics.
- Widths are exponentially narrow: *Hyper-ribbon*
- Interpolation
- Parameterization independent measure of sloppiness
- Widths are approximated by the FIM eigenvalues
- Intrinsic measure of the effective dimensionality of the model



Transtrum, Mark K., et al. "Perspective: Sloppiness and emergent theories in physics, biology, and beyond." *The Journal of chemical physics* 143.1 (2015): 07B201_1.

DIFFUSION REVISITED

As observations are coarsened, the high-dimensional manifold is systematically compressed into something of lower effective dimensionality.

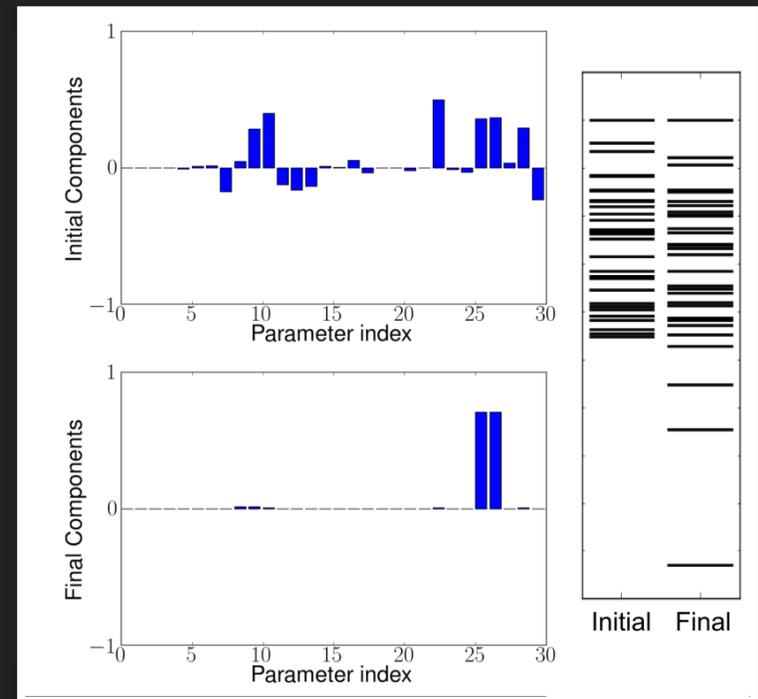
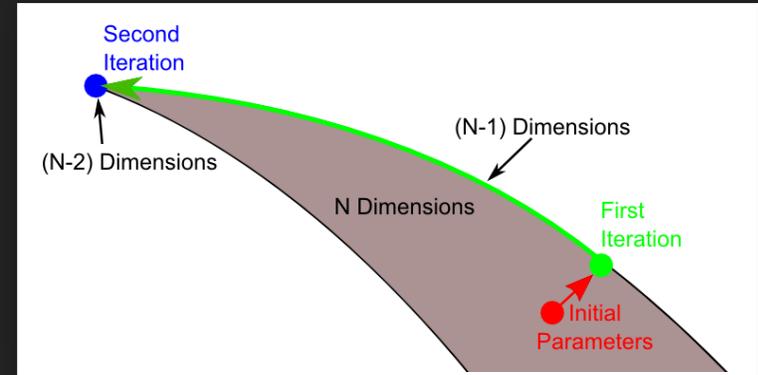


PARAMETER REDUCTION

MANIFOLD BOUNDARY APPROXIMATION

METHOD (MBAM)

- Can we remove sloppy parameters?
- Find the emergent theory hidden in the model?
- Geodesics along sloppines direction to nearby boundary.
- Eigendirections simplify at the boundary to physically reasonable models
- Reparameterize model such that one parameter goes to zero at boundary (identifying the small parameter)



MANIFOLDS (WITH BOUNDARY, CORNER)

MANIFOLD

- A topological space that locally looks like \mathbb{R}^N .
- There exists an invertible map $f : \mathcal{M} \rightarrow \mathbb{R}^N$.

MANIFOLD WITH BOUNDARY

- A topological space that locally looks like $\mathbb{R}^{N-1} \times \mathbb{R}_+$
- Like a manifold, but one coordinate is never negative.
- This coordinate is zero at the boundary

MANIFOLD WITH CORNER

- A topological space that locally looks like $\mathbb{R}^{N-p} \times \mathbb{R}_+^p$
- Like a manifold with boundary, but p coordinates are never negative.
- Each coordinate is individually zero on a boundary "cell".
- These cells meet at a corner, where all p coordinates are zero.

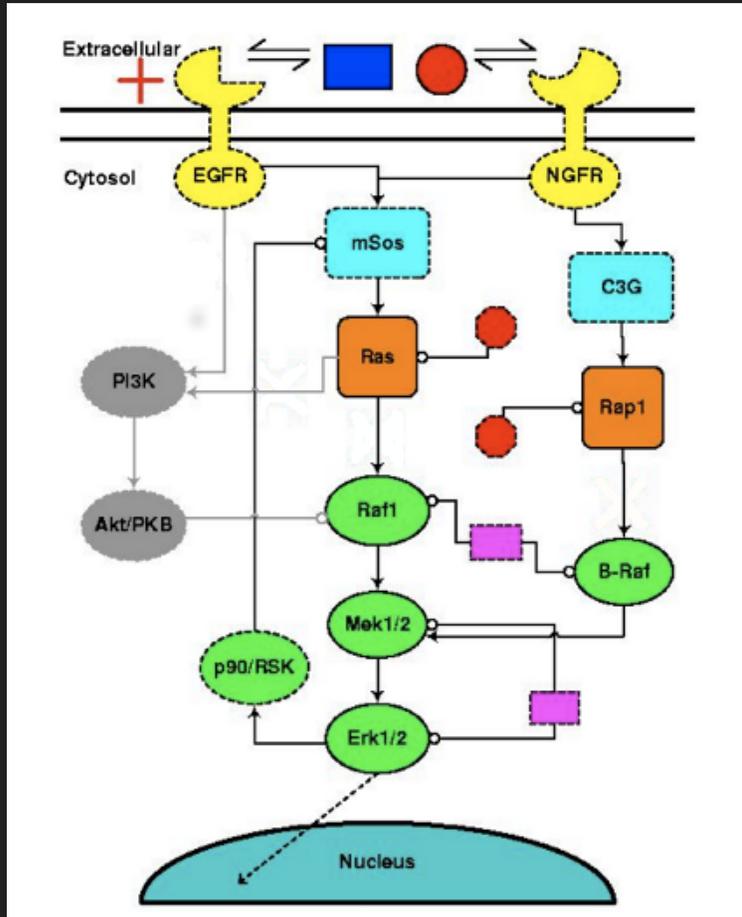
MBAM EXAMPLE

- A Michaelis-Menten reaction $[\dot{P}] = -[\dot{S}] = \frac{k[E][S]}{K+[S]}$ with parameters k and K .
- The geodesic reveals that at the boundary both k and K become infinite but that the ratio k/K remains finite.
- Reparameterize: $\tilde{k} = k/K, \epsilon = 1/K$ (These are boundary coordinates)
So that

$$\begin{aligned} [\dot{P}] &= \frac{k[E][S]}{K + [S]} = \frac{k}{K} \frac{[E][S]}{1 + [S]/K} \\ &= \frac{\tilde{k}[E][S]}{1 + \epsilon[S]} \end{aligned}$$

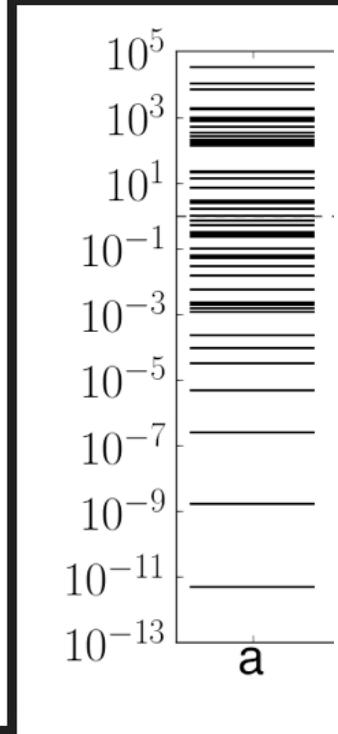
- Taking the limit $\epsilon \rightarrow 0$ gives the boundary model: $[\dot{P}] = \tilde{k}[E][S]$
- But can it be done for nontrivial cases?

EGFR SIGNALING MODEL

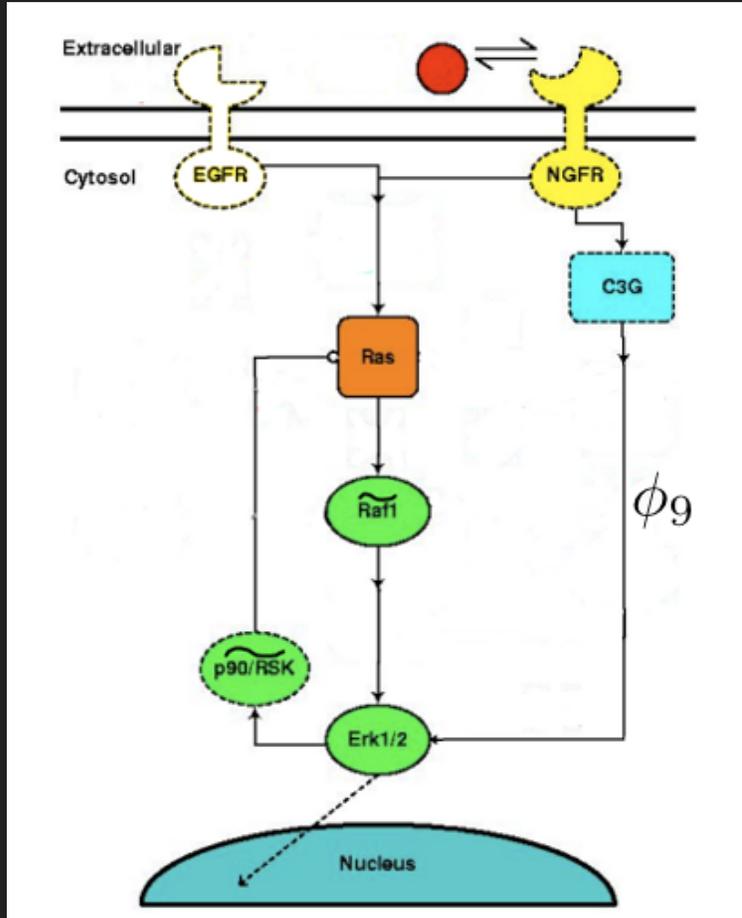


$$\begin{aligned}
 \frac{d[\text{EGP}]}{dt} &= -k_{1\text{EGF}}[\text{EGP}][\text{freeEGFR}] + k_{2\text{EGF}}[\text{boundEGFR}] \\
 \frac{d[\text{NGP}]}{dt} &= -k_{1\text{NGF}}[\text{NGP}][\text{freeNGFR}] + k_{2\text{NGF}}[\text{boundNGFR}] \\
 \frac{d[\text{freeEGFR}]}{dt} &= -k_{1\text{EGF}}[\text{EGP}][\text{freeEGFR}] + k_{2\text{EGF}}[\text{boundEGFR}] - k_{3\text{EGF}}[\text{EGF}][\text{freeEGFR}] + k_{4\text{EGF}}[\text{boundEGFR}] \\
 \frac{d[\text{boundEGFR}]}{dt} &= +k_{1\text{EGF}}[\text{EGP}][\text{freeEGFR}] - k_{2\text{EGF}}[\text{boundEGFR}] - k_{3\text{EGF}}[\text{EGF}][\text{freeEGFR}] + k_{4\text{EGF}}[\text{boundEGFR}] \\
 \frac{d[\text{freeNGFR}]}{dt} &= -k_{1\text{NGF}}[\text{NGP}][\text{freeNGFR}] + k_{2\text{NGF}}[\text{boundNGFR}] - k_{3\text{NGF}}[\text{NGP}][\text{freeNGFR}] + k_{4\text{NGF}}[\text{boundNGFR}] \\
 \frac{d[\text{boundNGFR}]}{dt} &= +k_{1\text{NGF}}[\text{NGP}][\text{freeNGFR}] - k_{2\text{NGF}}[\text{boundNGFR}] - k_{3\text{NGF}}[\text{NGP}][\text{freeNGFR}] + k_{4\text{NGF}}[\text{boundNGFR}] \\
 \frac{d[\text{SosInactive}]}{dt} &= -k_{\text{EGF}}[\text{boundEGFR}] \frac{[\text{SosInactive}]}{[\text{SosInactive}] + K_{\text{mEGF}}} + k_{\text{Sos}}[\text{PP90RakActive}] \frac{[\text{SosActive}]}{[\text{SosInactive}] + K_{\text{mSos}}} - k_{\text{NGF}}[\text{boundNGFR}] \frac{[\text{SosInactive}]}{[\text{SosInactive}] + K_{\text{mNGF}}} + k_{\text{NGF}}[\text{boundNGFR}] \frac{[\text{SosActive}]}{[\text{SosInactive}] + K_{\text{mNGF}}} \\
 \frac{d[\text{SosActive}]}{dt} &= +k_{\text{EGF}}[\text{boundEGFR}] \frac{[\text{SosInactive}]}{[\text{SosInactive}] + K_{\text{mEGF}}} + k_{\text{NGF}}[\text{boundNGFR}] \frac{[\text{SosInactive}]}{[\text{SosInactive}] + K_{\text{mNGF}}} - k_{\text{Sos}}[\text{PP90RakActive}] \frac{[\text{SosActive}]}{[\text{SosInactive}] + K_{\text{mSos}}} - k_{\text{NGF}}[\text{boundNGFR}] \frac{[\text{SosActive}]}{[\text{SosInactive}] + K_{\text{mNGF}}} \\
 \frac{d[\text{PP90RakInactive}]}{dt} &= -k_{\text{PP90Rak}}[\text{B-RafActive}] \frac{[\text{PP90RakInactive}]}{[\text{PP90RakInactive}] + K_{\text{mPP90Rak}}} + k_{\text{PP90Rak}}[\text{B-RafActive}] \frac{[\text{PP90RakActive}]}{[\text{PP90RakInactive}] + K_{\text{mPP90Rak}}} \\
 \frac{d[\text{PP90RakActive}]}{dt} &= +k_{\text{PP90Rak}}[\text{B-RafActive}] \frac{[\text{PP90RakInactive}]}{[\text{PP90RakInactive}] + K_{\text{mPP90Rak}}} - k_{\text{PP90Rak}}[\text{B-RafActive}] \frac{[\text{PP90RakActive}]}{[\text{PP90RakInactive}] + K_{\text{mPP90Rak}}} \\
 \frac{d[\text{RasInactive}]}{dt} &= -k_{\text{Sos}}[\text{SosActive}] \frac{[\text{RasInactive}]}{[\text{RasInactive}] + K_{\text{mSos}}} + k_{\text{RasGap}}[\text{RasGapActive}] \frac{[\text{RasActive}]}{[\text{RasInactive}] + K_{\text{mRasGap}}} \\
 \frac{d[\text{RasActive}]}{dt} &= +k_{\text{Sos}}[\text{SosActive}] \frac{[\text{RasInactive}]}{[\text{RasInactive}] + K_{\text{mSos}}} - k_{\text{RasGap}}[\text{RasGapActive}] \frac{[\text{RasActive}]}{[\text{RasInactive}] + K_{\text{mRasGap}}} \\
 \frac{d[\text{RasGapActive}]}{dt} &= 0 \\
 \frac{d[\text{RafInactive}]}{dt} &= -k_{\text{RasToRaf}}[\text{RasActive}] \frac{[\text{RafInactive}]}{[\text{RafInactive}] + K_{\text{mRasToRaf}}} + k_{\text{Raf}}[\text{RafPPase}] \frac{[\text{RafActive}]}{[\text{RafInactive}] + K_{\text{mRaf}}} + k_{\text{Raf}}[\text{ByAkt}] \frac{[\text{AktActive}]}{[\text{RafInactive}] + K_{\text{mRafByAkt}}} \\
 \frac{d[\text{RafActive}]}{dt} &= +k_{\text{RasToRaf}}[\text{RasActive}] \frac{[\text{RafInactive}]}{[\text{RafInactive}] + K_{\text{mRasToRaf}}} - k_{\text{Raf}}[\text{RafPPase}] \frac{[\text{RafActive}]}{[\text{RafInactive}] + K_{\text{mRaf}}} - k_{\text{Raf}}[\text{ByAkt}] \frac{[\text{AktActive}]}{[\text{RafActive}] + K_{\text{mRafByAkt}}} \\
 \frac{d[\text{Rap1Inactive}]}{dt} &= -k_{\text{Rap1ToBRaf}}[\text{Rap1Active}] \frac{[\text{Rap1Inactive}]}{[\text{Rap1Inactive}] + K_{\text{mRap1ToBRaf}}} + k_{\text{BRaf}}[\text{RafPPase}] \frac{[\text{Rap1Active}]}{[\text{Rap1Inactive}] + K_{\text{mBRaf}}} \\
 \frac{d[\text{Rap1Active}]}{dt} &= +k_{\text{Rap1ToBRaf}}[\text{Rap1Active}] \frac{[\text{Rap1Inactive}]}{[\text{Rap1Inactive}] + K_{\text{mRap1ToBRaf}}} - k_{\text{BRaf}}[\text{RafPPase}] \frac{[\text{Rap1Active}]}{[\text{Rap1Inactive}] + K_{\text{mBRaf}}} \\
 \frac{d[\text{MekInactive}]}{dt} &= -k_{\text{BRaf}}[\text{RafActive}] \frac{[\text{MekInactive}]}{[\text{MekInactive}] + K_{\text{mBRaf}}} + k_{\text{Mek}}[\text{PP2AActive}] \frac{[\text{MekActive}]}{[\text{MekInactive}] + K_{\text{mMek}}} \\
 \frac{d[\text{MekActive}]}{dt} &= +k_{\text{BRaf}}[\text{RafActive}] \frac{[\text{MekInactive}]}{[\text{MekInactive}] + K_{\text{mBRaf}}} - k_{\text{Mek}}[\text{PP2AActive}] \frac{[\text{MekActive}]}{[\text{MekInactive}] + K_{\text{mMek}}} \\
 \frac{d[\text{ErkInactive}]}{dt} &= +k_{\text{Mek}}[\text{MekActive}] \frac{[\text{ErkInactive}]}{[\text{ErkInactive}] + K_{\text{mMek}}} - k_{\text{ERK}}[\text{PP2AActive}] \frac{[\text{ErkActive}]}{[\text{ErkInactive}] + K_{\text{mERK}}} \\
 \frac{d[\text{ErkActive}]}{dt} &= -k_{\text{Mek}}[\text{MekActive}] \frac{[\text{ErkInactive}]}{[\text{ErkInactive}] + K_{\text{mMek}}} + k_{\text{ERK}}[\text{PP2AActive}] \frac{[\text{ErkActive}]}{[\text{ErkInactive}] + K_{\text{mERK}}} \\
 \frac{d[\text{PI3KInactive}]}{dt} &= -k_{\text{PI3K}}[\text{boundEGFR}] \frac{[\text{PI3KInactive}]}{[\text{PI3KInactive}] + K_{\text{mPI3K}}} - k_{\text{PI3K}}[\text{RasActive}] \frac{[\text{PI3KInactive}]}{[\text{PI3KInactive}] + K_{\text{mPI3KRas}}} \\
 \frac{d[\text{PI3KActive}]}{dt} &= +k_{\text{PI3K}}[\text{boundEGFR}] \frac{[\text{PI3KInactive}]}{[\text{PI3KInactive}] + K_{\text{mPI3K}}} + k_{\text{PI3K}}[\text{RasActive}] \frac{[\text{PI3KInactive}]}{[\text{PI3KInactive}] + K_{\text{mPI3KRas}}} \\
 \frac{d[\text{AktInactive}]}{dt} &= -k_{\text{Akt}}[\text{PI3KActive}] \frac{[\text{AktInactive}]}{[\text{AktInactive}] + K_{\text{mAkt}}} \\
 \frac{d[\text{AktActive}]}{dt} &= +k_{\text{Akt}}[\text{PI3KActive}] \frac{[\text{AktInactive}]}{[\text{AktInactive}] + K_{\text{mAkt}}} \\
 \frac{d[\text{C3GInactive}]}{dt} &= -k_{\text{C3GNGF}}[\text{boundNGFR}] \frac{[\text{C3GInactive}]}{[\text{C3GInactive}] + K_{\text{mC3GNGF}}} \\
 \frac{d[\text{C3GActive}]}{dt} &= +k_{\text{C3GNGF}}[\text{boundNGFR}] \frac{[\text{C3GInactive}]}{[\text{C3GInactive}] + K_{\text{mC3GNGF}}} \\
 \frac{d[\text{Rap1Inactive}]}{dt} &= -k_{\text{C3G}}[\text{C3GActive}] \frac{[\text{Rap1Inactive}]}{[\text{Rap1Inactive}] + K_{\text{mC3G}}} + k_{\text{RapCap}}[\text{RapCapActive}] \frac{[\text{Rap1Active}]}{[\text{Rap1Inactive}] + K_{\text{mRapCap}}} \\
 \frac{d[\text{Rap1Active}]}{dt} &= +k_{\text{C3G}}[\text{C3GActive}] \frac{[\text{Rap1Inactive}]}{[\text{Rap1Inactive}] + K_{\text{mC3G}}} - k_{\text{RapCap}}[\text{RapCapActive}] \frac{[\text{Rap1Active}]}{[\text{Rap1Inactive}] + K_{\text{mRapCap}}}
 \end{aligned}$$

29 Coupled ODEs
48 Parameters



REDUCED EGFR SIGNALING MODEL



$$[bEGFR] = \begin{cases} 1 & \text{EGF Present} \\ 0 & \text{Otherwise} \end{cases}$$

$$\frac{d}{dt}[bNGFR] = \theta_1[NGF][fNGFR]$$

$$\frac{d}{dt}[NGF] = -\theta_1[NGF][fNGFR]$$

$$\frac{d}{dt}[RasA] = -[RasA][P90RskA] + \theta_2[bEGFR] + \theta_3[bNGFR]$$

$$\frac{d}{dt}[\widetilde{Raf1A}] = \theta_4[RasA] - \theta_5[\widetilde{Raf1A}]/([\widetilde{Raf1A}] + \theta_6)$$

$$\frac{d}{dt}[C3GA] = \theta_7[bNGFR][C3GI]$$

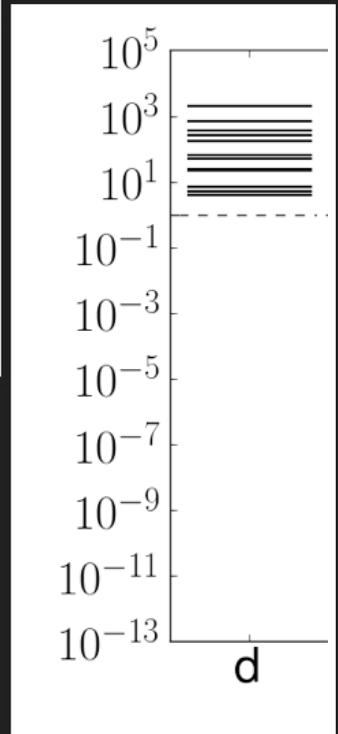
$$[Rap1A] = \theta_8[C3GA]$$

$$[MekA] = [\widetilde{Raf1A}][MekI] + \theta_9[Rap1A]$$

$$\frac{d}{dt}[Erk] = -\theta_{10}[ErkA] + \theta_{11}[MekA][ErkI]$$

$$\frac{d}{dt}[\widetilde{P90RskA}] = \theta_{12}[ErkA]$$

6 Coupled ODEs
12 Parameters



Transtrum, Mark K., and Peng Qiu. "Model reduction by manifold boundaries." *Physical review letters* **113**.9 (2014): 098701.

INTERPRETING THE REDUCED MODEL

- Effective "Renormalized" Parameters:

$$\phi_9 = \frac{[\text{BRafI}](k_{\text{Rap1ToBRaf}})(K_{\text{mdBRaf}})(k_{\text{pBRaf}})(K_{\text{mdMek}})}{[\text{PP2AA}][\text{Raf1PPtase}](k_{\text{dBRaf}})(K_{\text{mRap1ToBRaf}})(k_{\text{dMek}})}$$

- Interpretation: Rate of Information Flow through channel
- Emergent Control Knob
- No Black Box
- Bridges the mechanistic and phenomenological descriptions
- Dynamical Variables
 - Biologically Functional Modules
- Proteins → Signaling
- Chemistry → Biology
- Not specific to systems biology

WHERE WE HAVE APPLIED IT:

- Chemical/Biochemical kinetics (Conservation of mass)
- Compartment models (Conservation of mass)
- Power Systems Transients (Singular Perturbation)
- Stable Linear Time Invariant Systems (Balanced Truncation/Singular Perturbation)
- Composition of elementary functions (exponential, rational polynomials etc.)
- Bayesian Networks/Makov Chains/Markov Random Fields (Conservation of Probability)
- Molecular Dynamics (Conservation of Energy)
- Multilayer Perceptrons, i.e., Neural Networks
- General Exponential Families (e.g., Ising Models)
- Models with discrete symmetries (Orbifolds)
- Hodgkin-Huxley Neurons

RELATION TO OTHER REDUCTION METHODS

For an appropriately parameterized model, MBAM is equivalent to several other model reduction methods:

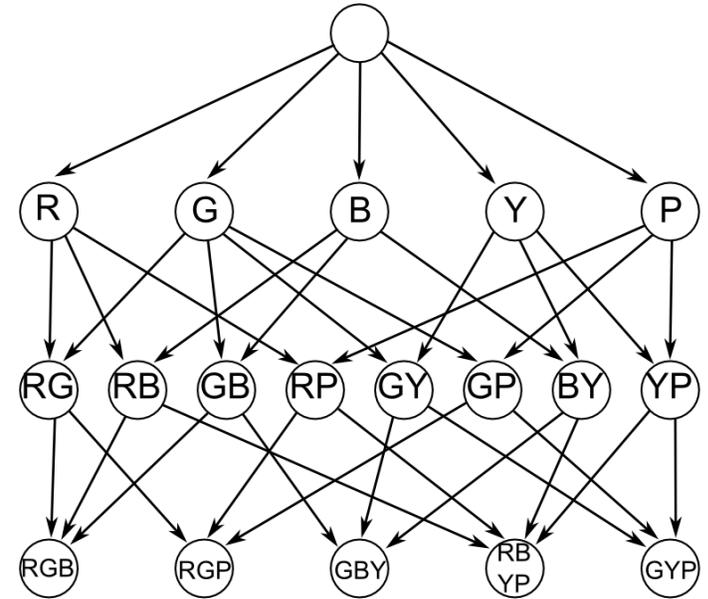
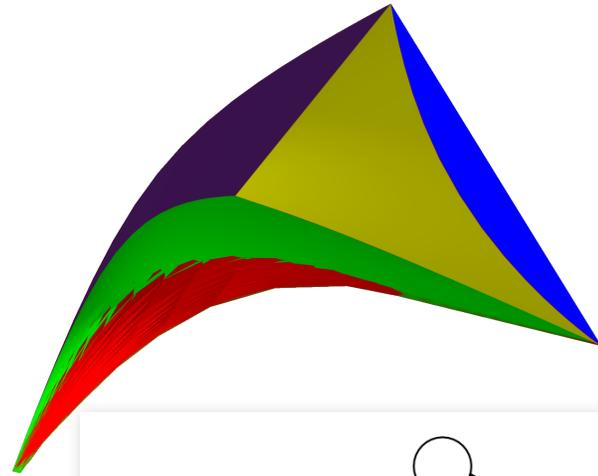
- Real-space/Momentum-space Renormalization Group
- Mean-field Approximations
- Singular Perturbations
- Balanced Truncation
- Steady-state/Equilibrium Approximations
- Thermodynamic/Continuum/Classical limits

A META-THEORY OF MODELING

BEYOND GEOMETRY: INFORMATION

TOPOLOGY

- Manifold boundaries forms a hierarchical cell-complex
- Each boundary cell is a simplified model
- The boundary complex is a topological property, not a geometric property
- Model manifolds are realizations of abstract polytopes
- Adjacency relationships induce a partial order



Transtrum, Mark K., Gus Hart, and Peng Qiu. "Information topology identifies emergent model classes." arXiv preprint arXiv:1409.6203 (2014).

EXAMPLE: ENZYME REACTION



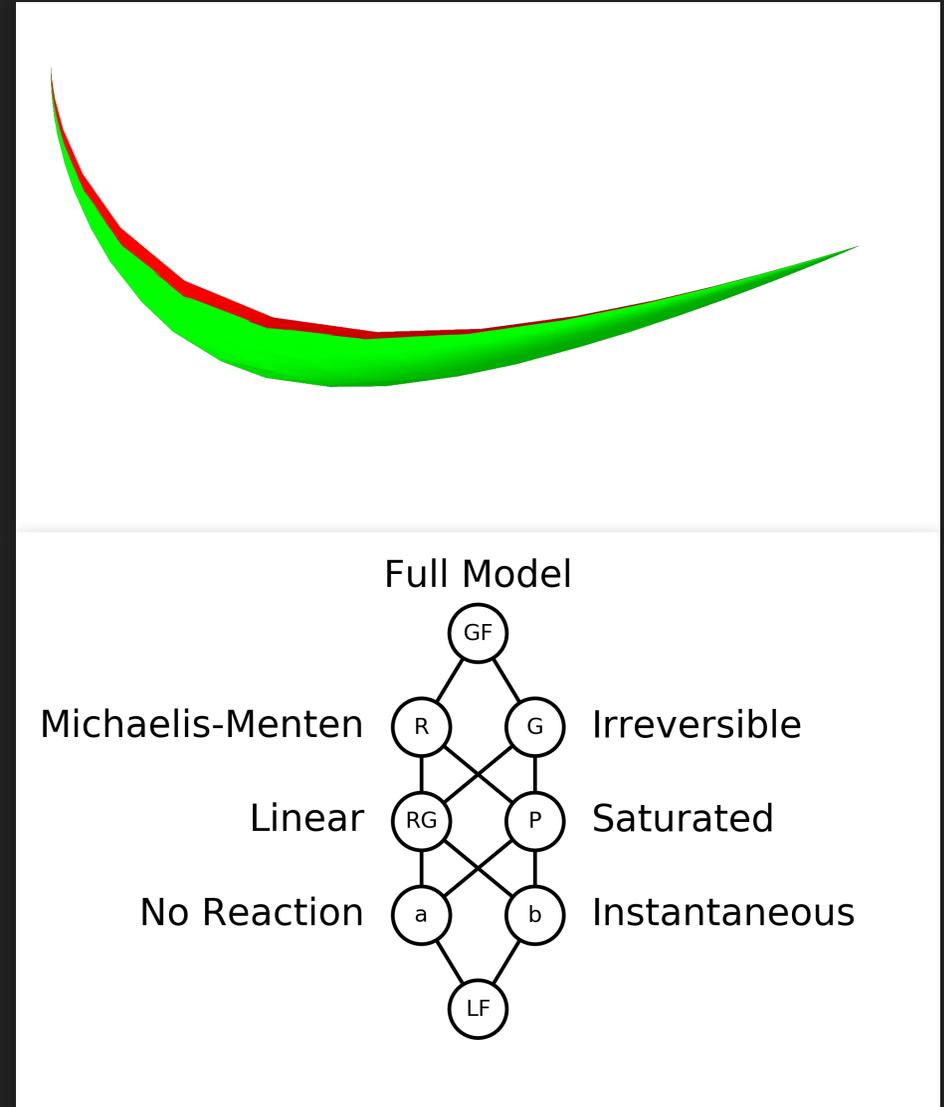
3 Parameters k_f, k_r, k_c

$$\frac{d}{dt}[E] = -k_f[E][S] + k_r[C] + k_c[C]$$

$$\frac{d}{dt}[S] = -k_f[E][S] + k_r[C]$$

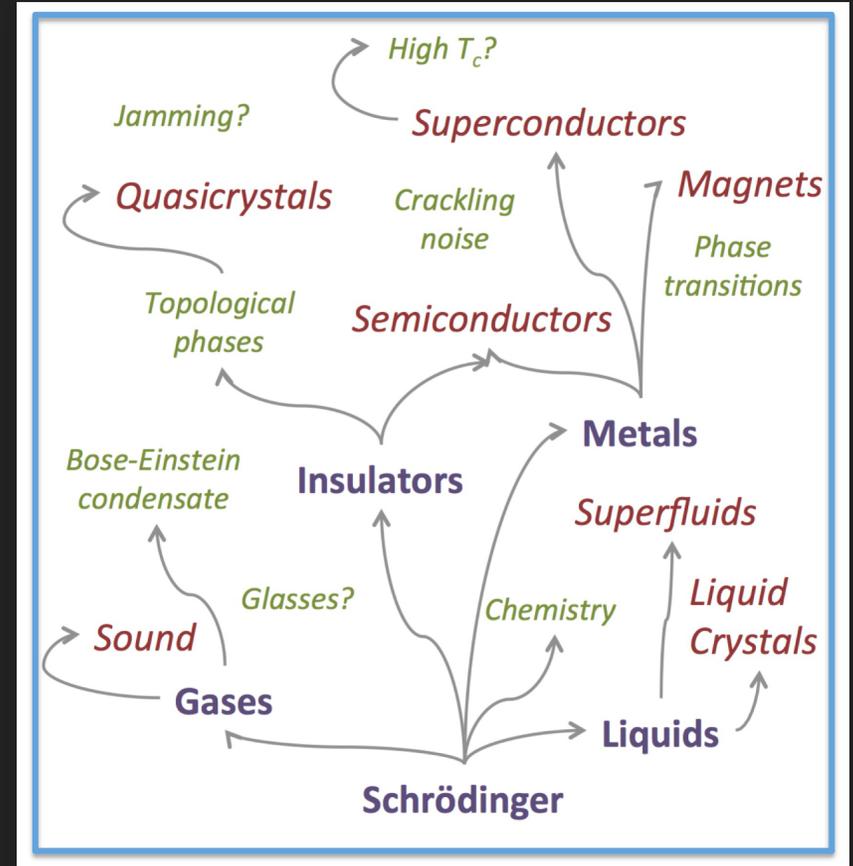
$$\frac{d}{dt}[C] = k_f[E][S] - k_r[C] - k_c[C]$$

$$\frac{d}{dt}[P] = k_c[C]$$



HASSE DIAGRAMS AND APPROXIMATE MODELS

- Each boundary cell captures a different idealized behavior of the system.
- Depending on the context, these idealized behaviors could represent:
 - "Healthy" vs. "Sick"
 - Phases of matter
 - Fast/Slow Dynamics
 - Developmental Stages?



The Hasse diagram is a road map from the intricate, fully-parameterized description through various types of approximations to distinct behavioral regimes.

THOUGHTS ABOUT UQ

- Parametric Uncertainty
 - Models with lots of unknown parameters don't always lead to large prediction uncertainty or overfitting
 - The goal is to identify the relevant degrees of freedom (e.g., Cooper pairs)
 - There is not always a sharp distinction between relevant/irrelevant.
- Structural Uncertainty:
 - Consider an effective model to be a submanifold of a more "complete" model.
 - Structural uncertainty is bound by the widths of the complete model manifold.
 - Sloppy models have an exponential distribution of widths.
- Model selection problem:
 - Accuracy vs. Complexity
 - Model Reduction

SUMMARY AND CONCLUSIONS

- Parameter Reduction & Effective Theories
 - Two Cultures of Mathematical Modeling
 - Fisher Information reflects low-effective dimensionality
 - Physically insightful models often emerge because of a "small parameter"
- Information Geometry
 - Models are equivalent to manifolds
 - Hierarchy of widths
 - Complex Models have low effective dimensionality
 - Parameter Reduction = Manifold Hyper-corners (MBAM)
- Systematically derive new, effective theories from first principles
 - Information Topology: A meta theory for organizing our information about the world

By characterizing the geometric and topological structures underlying scientific models, we can connect bottom-up descriptions of complex processes with top-down inferences drawn from data, paving the way for emergent theories in physics, biology, and beyond.

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