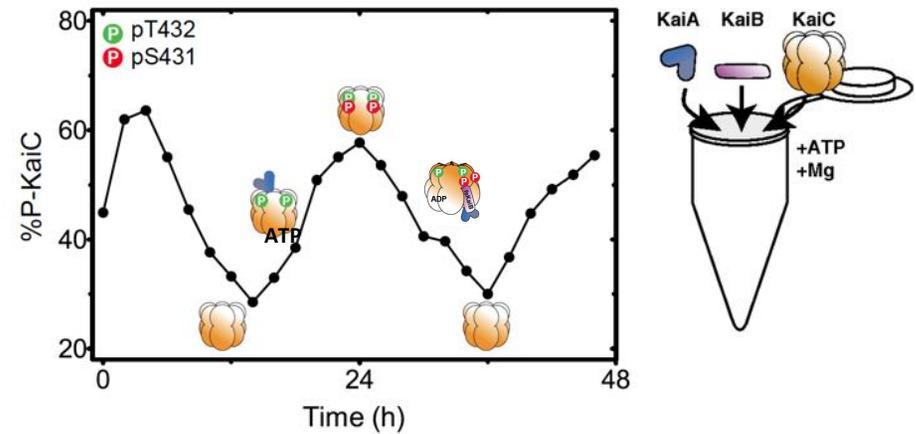
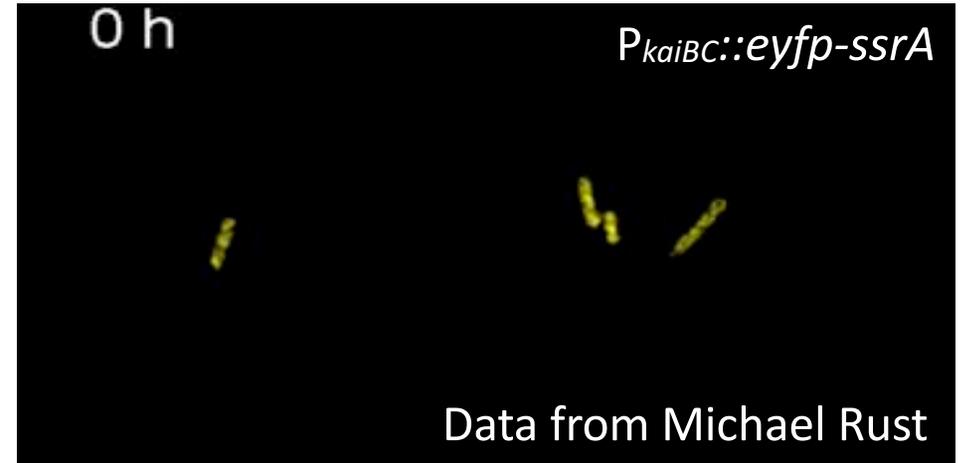
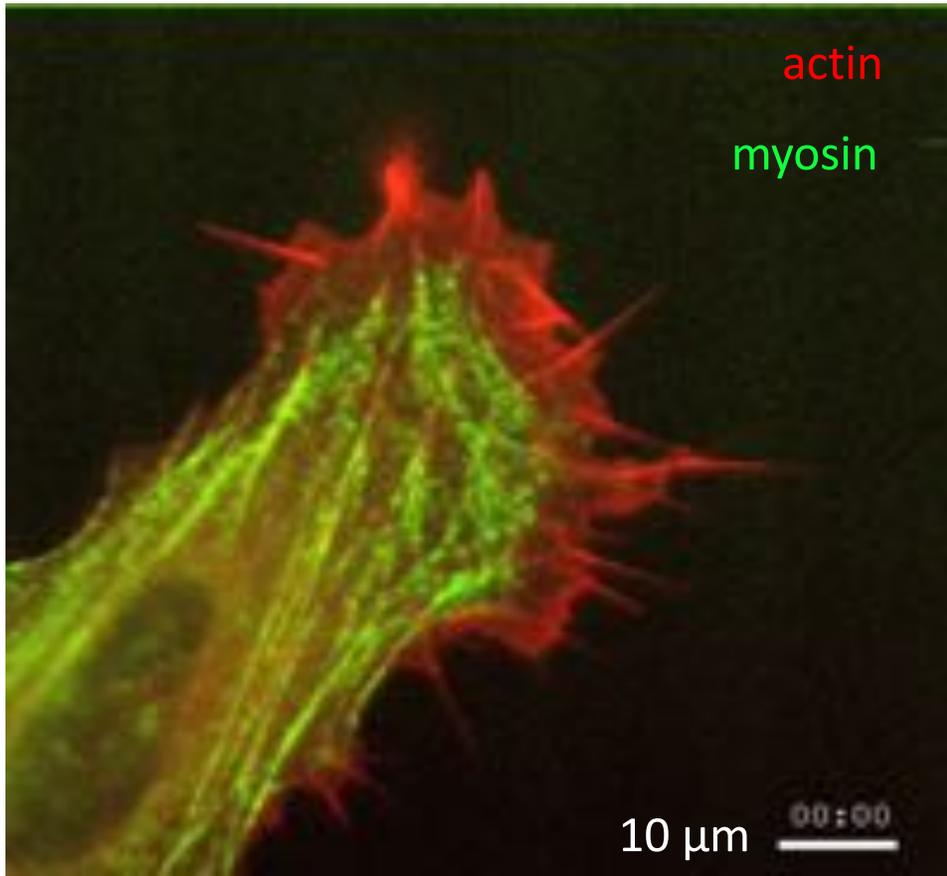
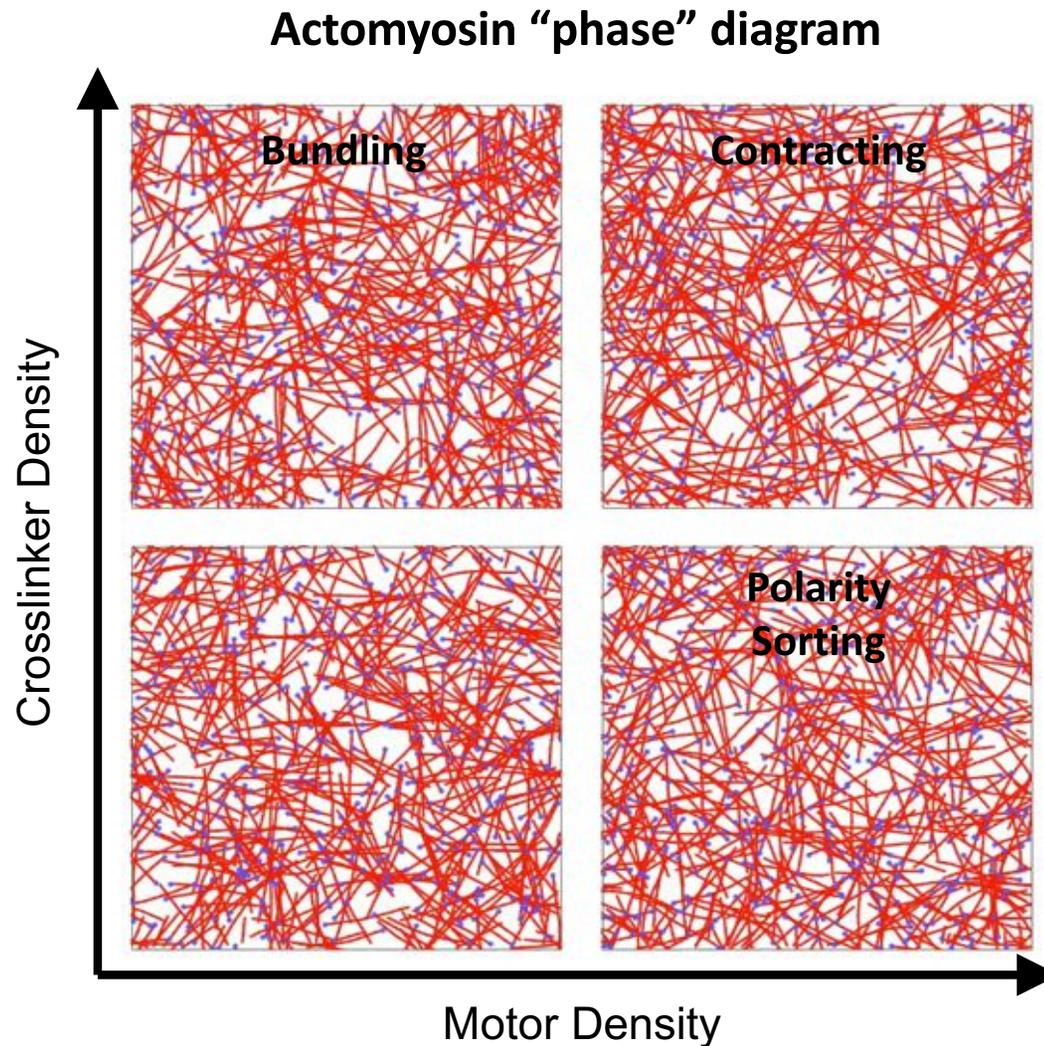


Living systems are far from equilibrium.



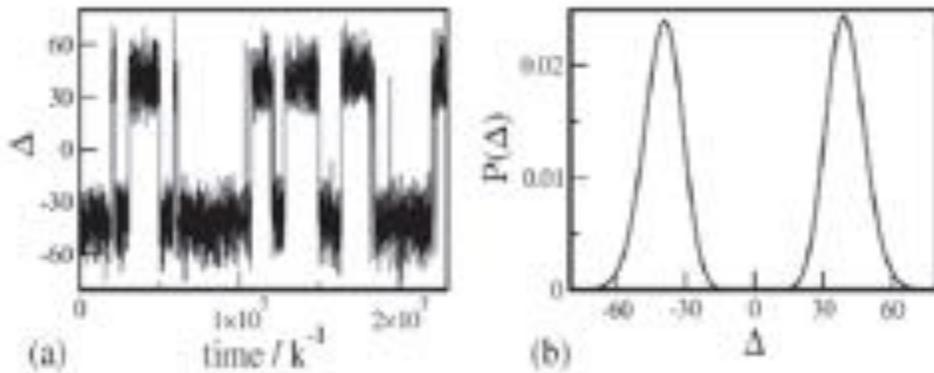
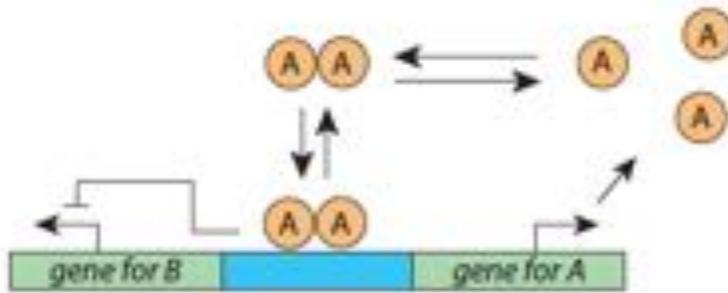
[http://cellix.imba.oeaw.ac.at/fileadmin/conferences/Videotour\\_CellMotility/NEW\\_2010/Figure\\_7\\_400.MOV](http://cellix.imba.oeaw.ac.at/fileadmin/conferences/Videotour_CellMotility/NEW_2010/Figure_7_400.MOV)

Models of living systems have traditionally been sufficiently simple that they can be simulated directly.



# Examples of models of living systems that are challenging to simulate directly.

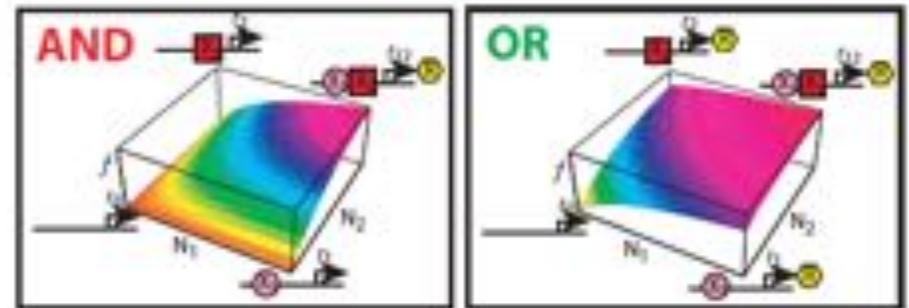
## Multimodality



Allen, Warren, and ten Wolde (2005)

## Tail statistics

$$\frac{\partial^2}{\partial N_i \partial N_j} \text{CRIF} = K \frac{\langle \delta N_i, \delta N_j, \delta N_R \rangle}{\langle \delta N_i^2 \rangle \langle \delta N_j^2 \rangle}$$



Warmflash and Dinner (2008)

Nonequilibrium systems present a number of challenges for enhanced sampling methods:

- no *a priori* knowledge of the distribution function;

$$\langle A \rangle = \frac{\int A(q) e^{-\beta E} dq}{\int e^{-\beta E} dq}$$

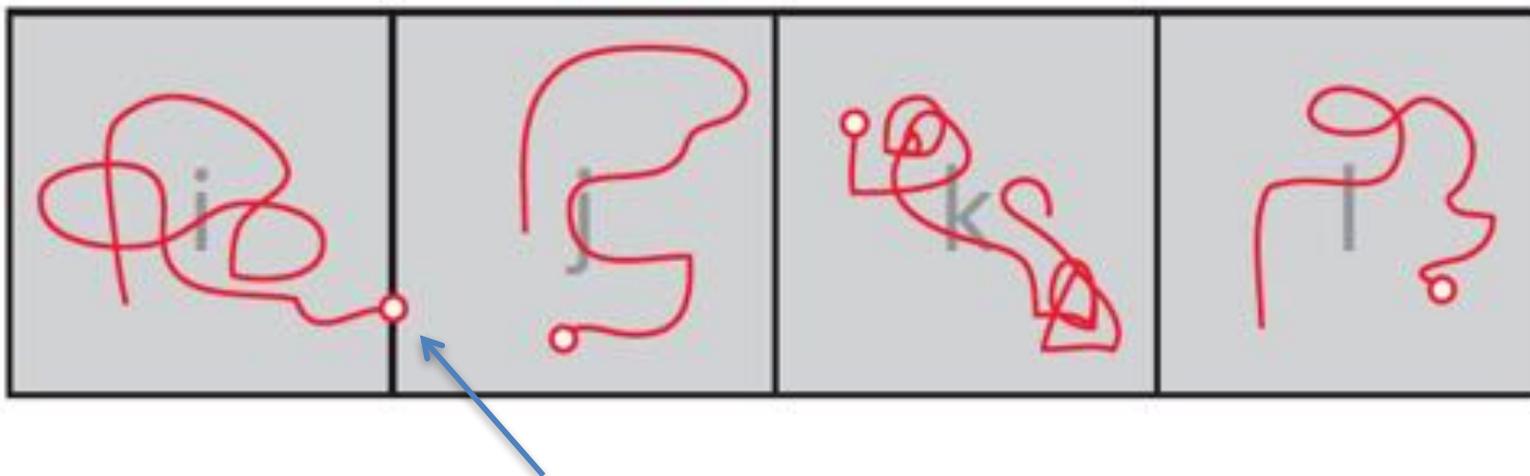
- microscopically irreversible dynamics;

$$P(q)W(q \rightarrow q') \neq P(q')W(q' \rightarrow q)$$

- global flows in phase space.

# Original Nonequilibrium Umbrella Sampling Algorithm

- 1) Divide order parameter space
- 2) Sample each region and estimate fluxes
- 3) Estimate weights
- 4) Repeat until weights and fluxes converge



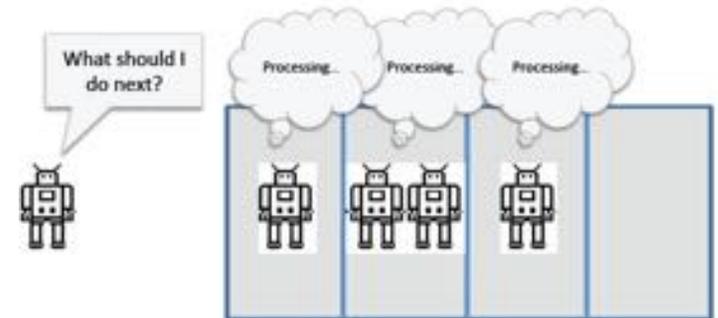
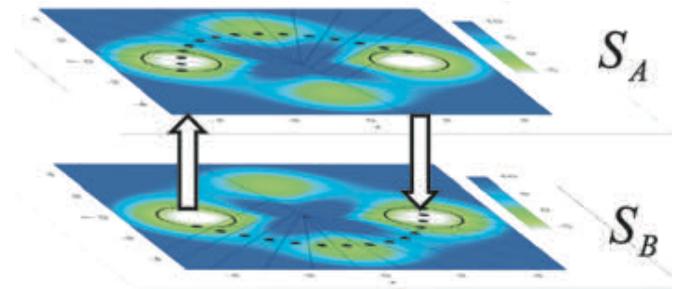
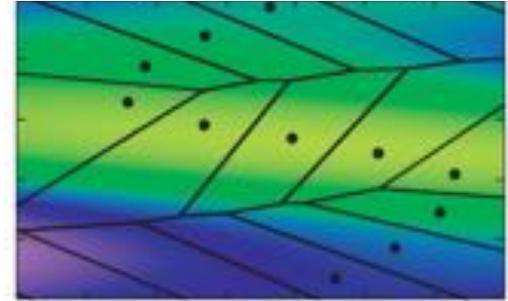
Upon attempted boundary crossing:

- add point to flux list,
- note flux to adjust region weights,
- restart walker, partitioning weight between saved and active copies

Warmflash, Bhimalapuram, Dinner (2007) J. Chem. Phys. 127, 154112.  
Dickson, Dinner (2010) Annu. Rev. Phys. Chem. 61, 441-59.

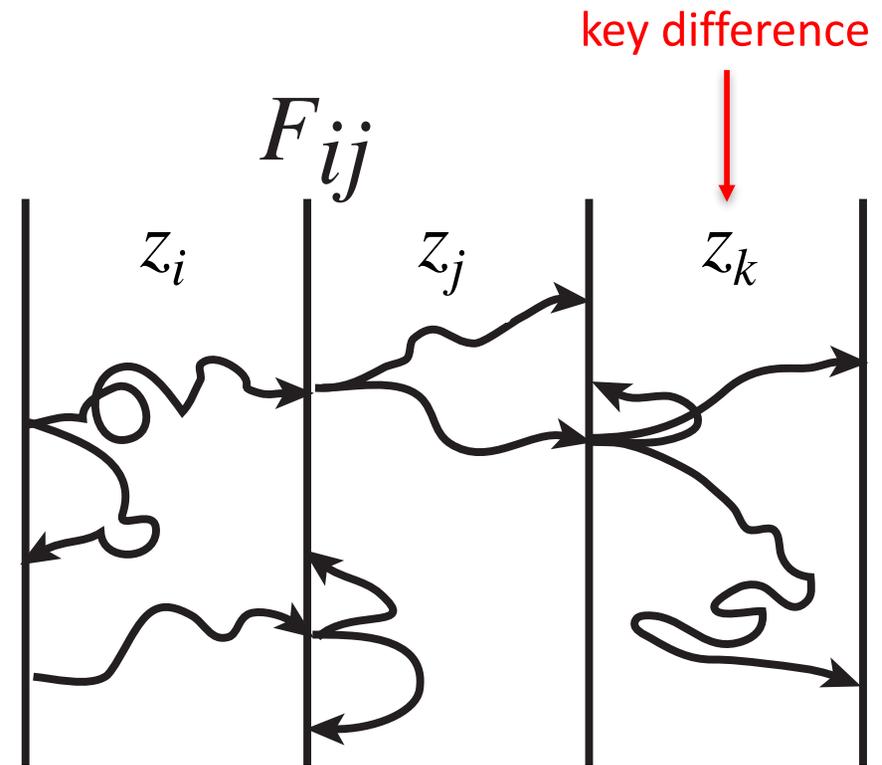
## Further developments of original NEUS

- Reaction path discovery (string method)
  - Dickson et al. JCP 130, 074104 (2009)
- Rates
  - Dickson et al. JCP 131, 154104 (2009)
  - Vanden-Eijnden JCP 131, 044120 (2009)
- Parallelism
  - Dickson et al. JCTC 7, 2710-2720 (2011).



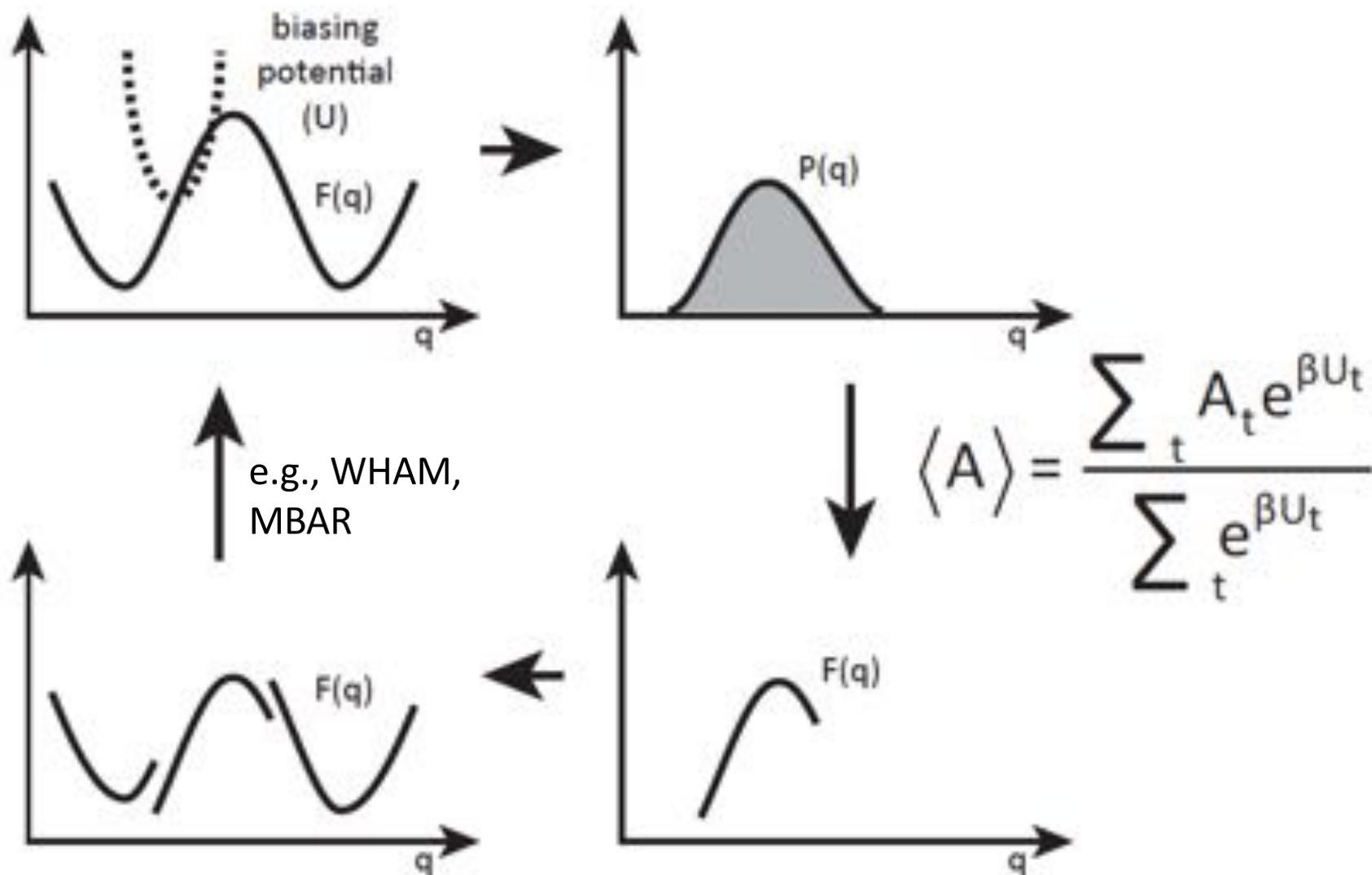
Splitting methods preserve the underlying dynamics but branch and prune the trajectories to focus sampling in specific areas

- Weighted Ensemble (WE)
- Forward Flux Sampling (FFS)
- Steered Transition Path Sampling (STePS)
- Nonequilibrium Umbrella Sampling (NEUS)



NEUS is distinct in that it is also a stratification method.

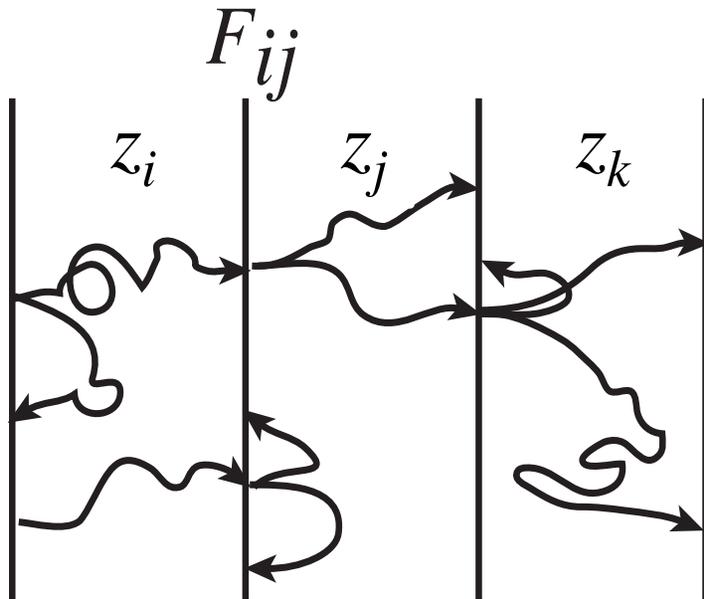
Equilibrium umbrella sampling is a well-known stratification method in molecular simulation.



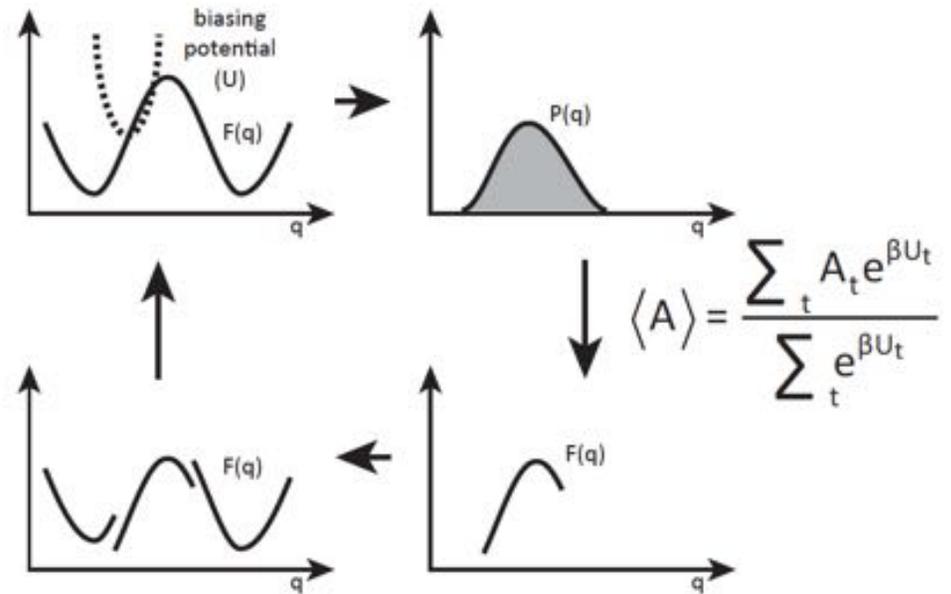
Torrie, Valleau, J Comput Phys 23, 187 (1977)  
 Pangali, Rao, Berne, J Chem Phys 71, 2975 (1979)

Can we make a framework that encompasses both these methods?

Nonequilibrium US



Equilibrium US



Work with Jeremy Tempkin, Erik Thiede,  
Brian Van Koten, and Jonathan Weare

Funding from NIH

# Outline

- Motivation
- Eigenvector Method for Umbrella Sampling (EMUS)
  - Formulation
  - Error analysis
  - Examples

Thiede, Van Koten, Weare, Dinner, J Chem Phys 145, 084115 (2016)

Dinner, Thiede, Van Koten, Weare, arxiv:1705.08445 (2017)

- Nonequilibrium Umbrella Sampling (NEUS)
  - Formulation
  - Examples

Dinner, Tempkin, Van Koten, Mattingly, Weare, SIREV; arXiv:1610.09426

# Umbrella sampling as an eigenproblem

We want to obtain the free energy, or equivalently the probability:

$$\pi(x) \propto \exp(-\beta H_0(x))$$

To this end, we apply a bias, e.g.,

$$\psi_i(x) = \exp\left(-\beta(q - q_0^i)^2\right)$$

Simulation  $i$  samples from the probability

$$\pi_i(x) = \frac{\psi_i(x)\pi(x)}{\int \psi_i(x)\pi(x)dx}$$

To align the probabilities from different simulations, we need to determine the normalization, equivalent to the zero of free energy:

$$z_i = \int \psi_i(x)\pi(x)dx$$

# Umbrella sampling as an eigenproblem

Once we have the normalization, we can calculate any average from

$$\langle f \rangle = \sum_i z_i \int \frac{f(x)}{\sum_k \psi_k(x)} \pi_i(x) dx$$

In particular,

$$z_j = \langle \psi_j \rangle = \sum_i z_i \int \frac{\psi_j(x)}{\sum_k \psi_k(x)} \pi_i(x) dx$$

or

$$z_j = \sum_i z_i F_{ij}$$

with the stochastic matrix  $F$  defined as

$$F_{ij} = \int \frac{\psi_j(x)}{\sum_k \psi_k(x)} \pi_i(x) dx$$

## EMUS procedure

1. Estimate  $F$  and  $\langle f \rangle_j$  by sampling from  $\pi_j$ .
2. Solve the eigenvector equation

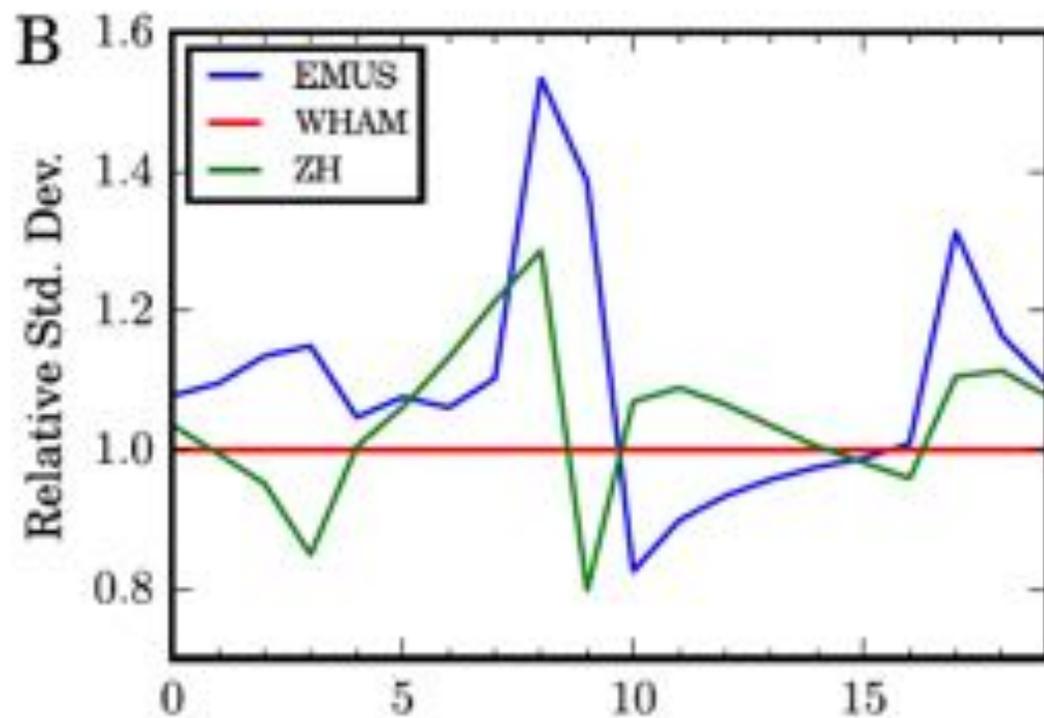
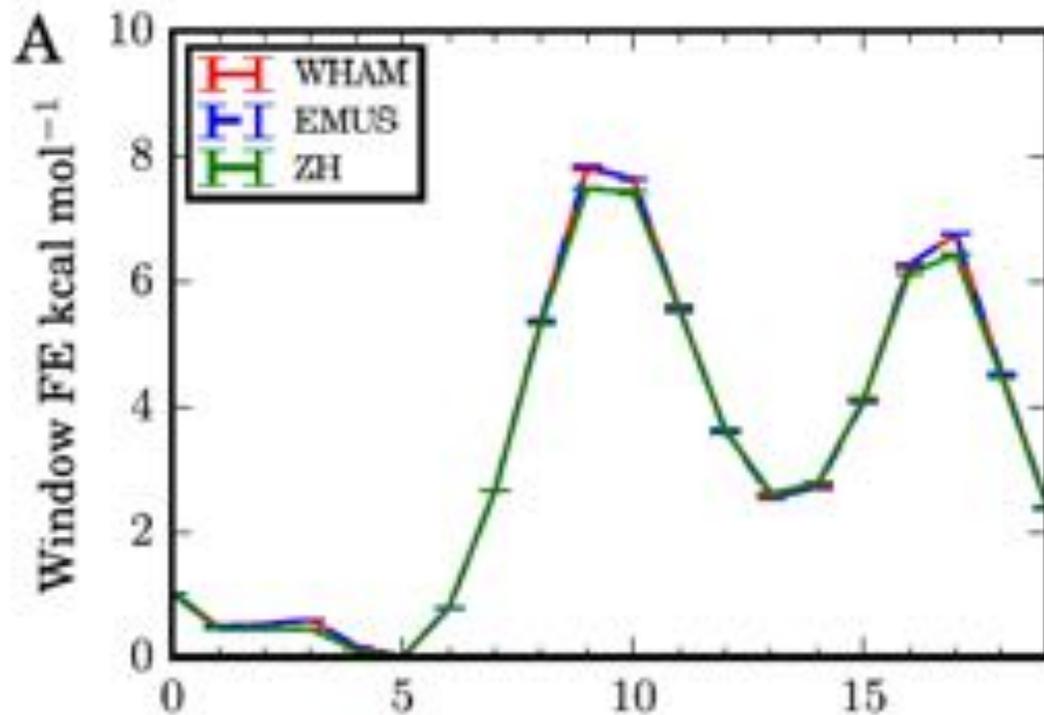
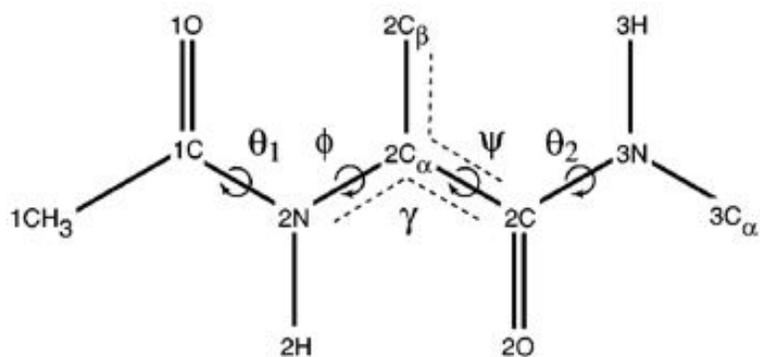
$$z^T F = z^T$$

3. Compute the desired expectation as a weighted average

$$\int_{x \in \mathbb{R}^d} f(x) \pi(dx) = \sum_{j=1}^n z_j \langle f \rangle_j$$

$$\langle f \rangle_j = \int_{x \in \mathbb{R}^d} f(x) \pi_j(dx).$$

This Eigenvector Method for Umbrella Sampling (EMUS) for obtaining the window normalizations performs comparably to existing methods while facilitating mathematical analysis of the error.



## Relation to Multistate Bennett Acceptance Ratio (MBAR)

EMUS satisfies the extended bridge sampling equation

$$z_j \sum_{i=1}^L \langle \alpha_{ij}(x) \psi_i(x) \pi(x) \rangle_j = \sum_{i=1}^L z_i \langle \alpha_{ij}(x) \psi_j(x) \pi(x) \rangle_i$$

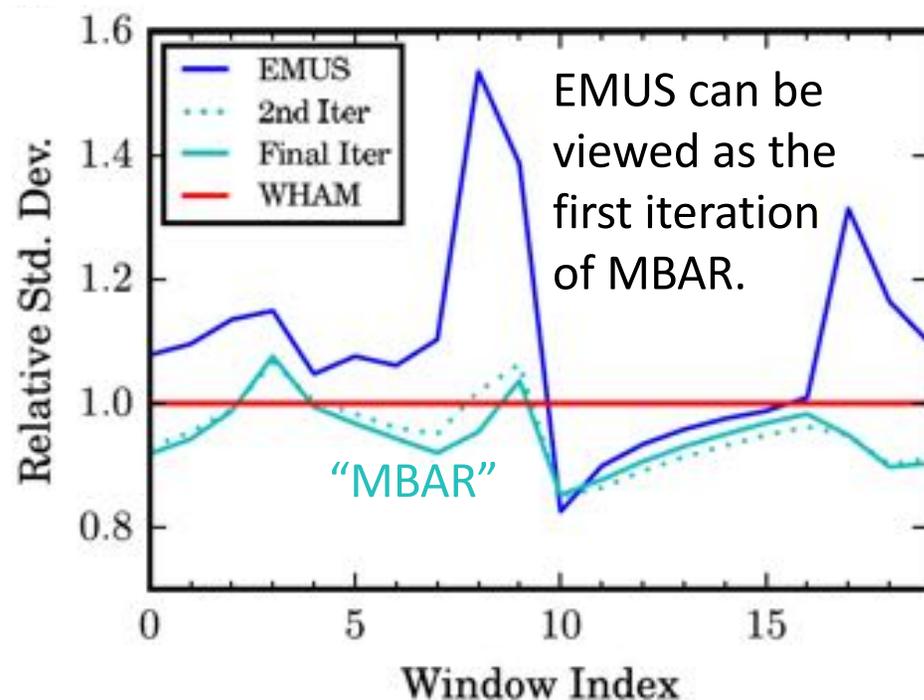
with arbitrary  $\alpha_{ij}$ . For MBAR, Shirts and Chodera (2008) chose

$$\alpha_{ij}^{\text{MBAR}}(x) = \frac{n_i / z_i}{\sum_k \psi_k(x) \pi(x) n_k / z_k}$$

while EMUS corresponds to

$$\alpha_{ij}^{\text{EMUS}}(x) = \frac{1}{\sum_k \pi(x) \psi_k(x)}$$

The dependence of  $\alpha_{ij}$  on  $z$  in MBAR necessitates self-consistent solution and complicates error analysis.



# EMUS Error analysis

We can prove a central limit theorem for EMUS. A key result is

$$\text{var}(G_{lm}) \approx \sum_i n_i \text{var}_i \left( \sum_j \frac{\partial G_{lm}}{\partial F_{ij}} \frac{\psi_j(x)}{\sum_k \psi_k(x)} \right)$$

number of independent samples

Delta method

$$\text{var}(f(\bar{g})) \approx \text{var}(\nabla f(\bar{g}) \cdot g)$$

For practical computation, write

$$\frac{\partial G_{lm}}{\partial F_{ij}} = -\frac{\partial}{\partial F_{ij}} \log \left( \frac{z_l}{z_m} \right) = \frac{1}{z_m} \frac{\partial z_m}{\partial F_{ij}} - \frac{1}{z_l} \frac{\partial z_l}{\partial F_{ij}}$$

# EMUS Error analysis

We can go further by exploiting the eigenvector framework for umbrella sampling,

In particular,

$$\frac{\partial z_k}{\partial F_{ij}} = z_i (I - F)_{jk}^{\#}$$

where # denotes the group inverse:  $AA^{\#}A = A$ ,  $A^{\#}AA^{\#} = A^{\#}$ ,  $AA^{\#} = A^{\#}A$ .

Golub, G; Meyer, C. "Using the QR Factorization and Group Inversion to Compute, Differentiate, and Estimate the Sensitivity of Stationary Probabilities for Markov Chains." *SIAM J. Alg. Disc. Meth.* 7, 12 (1986)

# Algorithm for assigning computational effort to minimize the overall error in an average

1. Sample to obtain the entries in  $F$ .
2. Calculate the group inverse of  $I-F$ , and in turn the matrix of derivatives  $\partial G_{lm}/\partial F_{ij}$ .
3. For each window, construct the trajectory

$$v_{ni} = \sum_j \frac{\partial G_{lm}}{\partial F_{ij}} \frac{\psi_j(x_{ni})}{\sum_k \psi_k(x_{ni})}$$

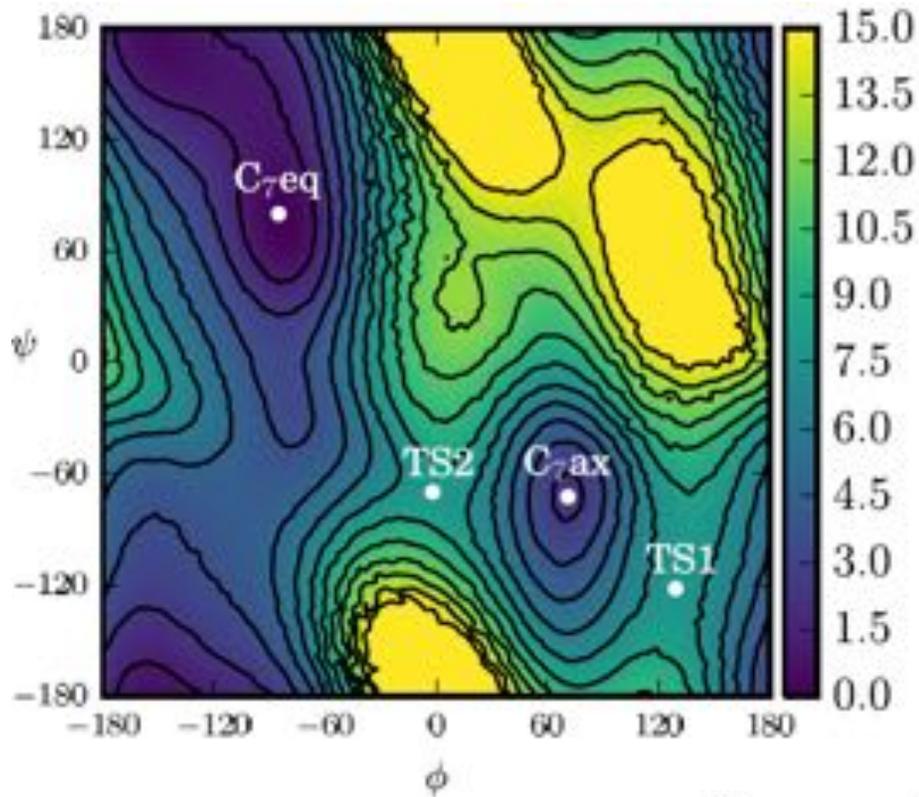
4. Calculate the variance and autocorrelation time of this trajectory to obtain

$$\text{err}_i^2 = \text{var}_i(v_{ni})/n_i$$

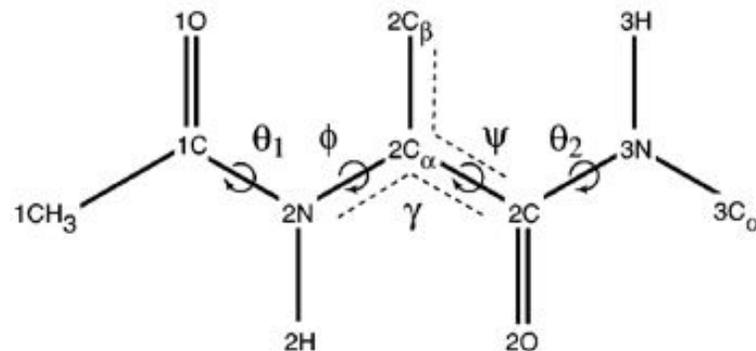
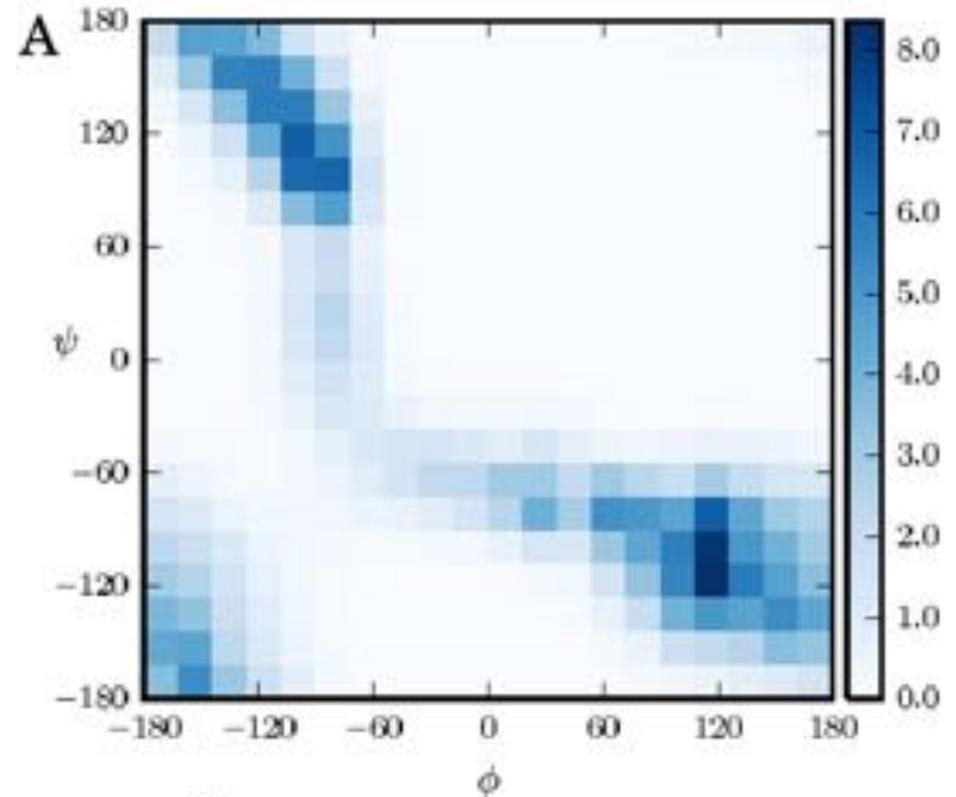
1. Assign computational resources proportional to  $\text{err}_i$ , which we term the “relative importances”.

# EMUS error contributions to $\Delta G(C_{7eq} - C_{7ax})$ of the alanine dipeptide

Potential of mean force (kcal/mol)

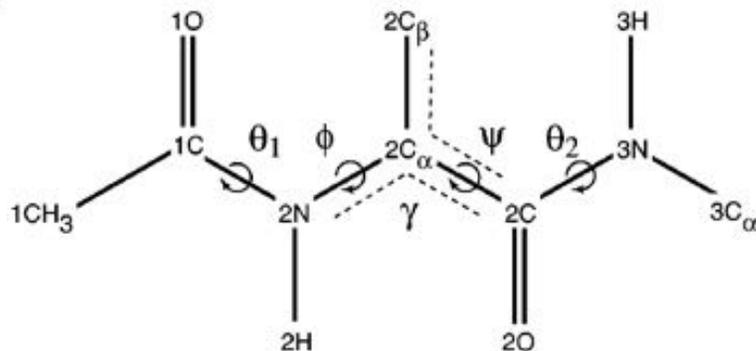
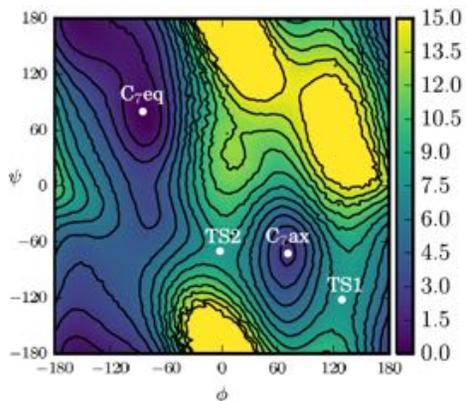
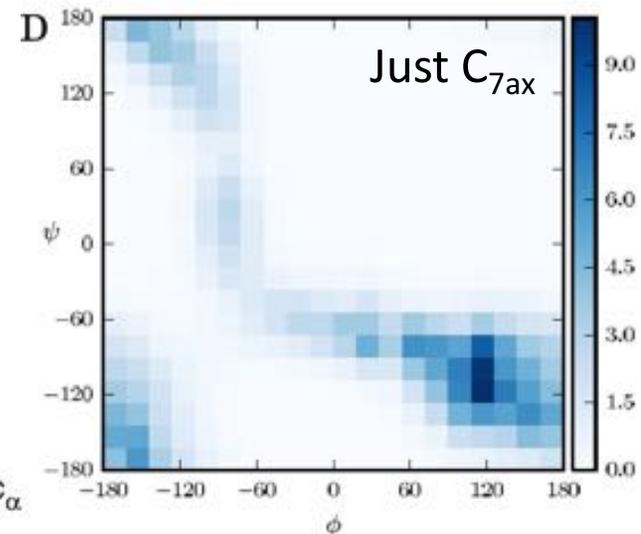
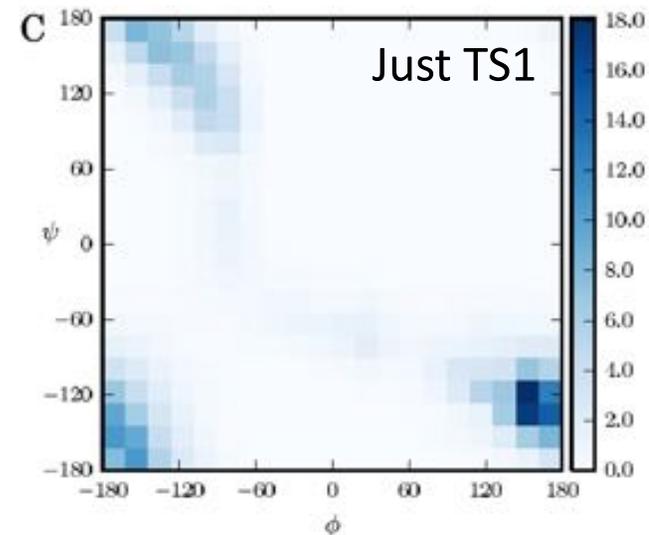
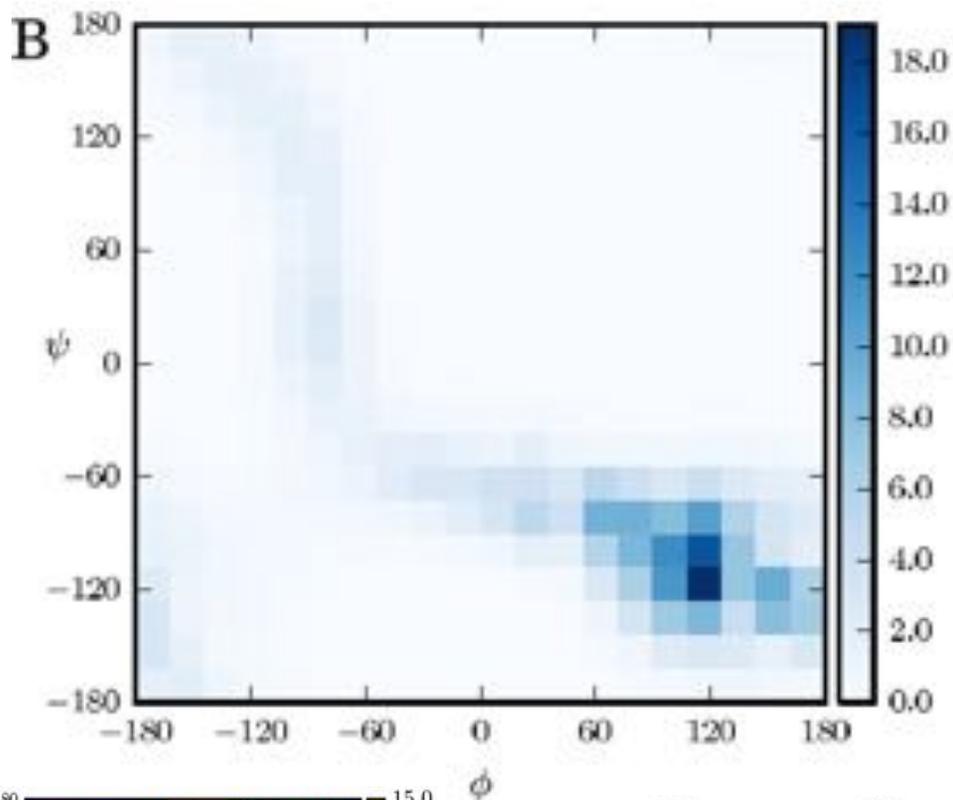


Window importances

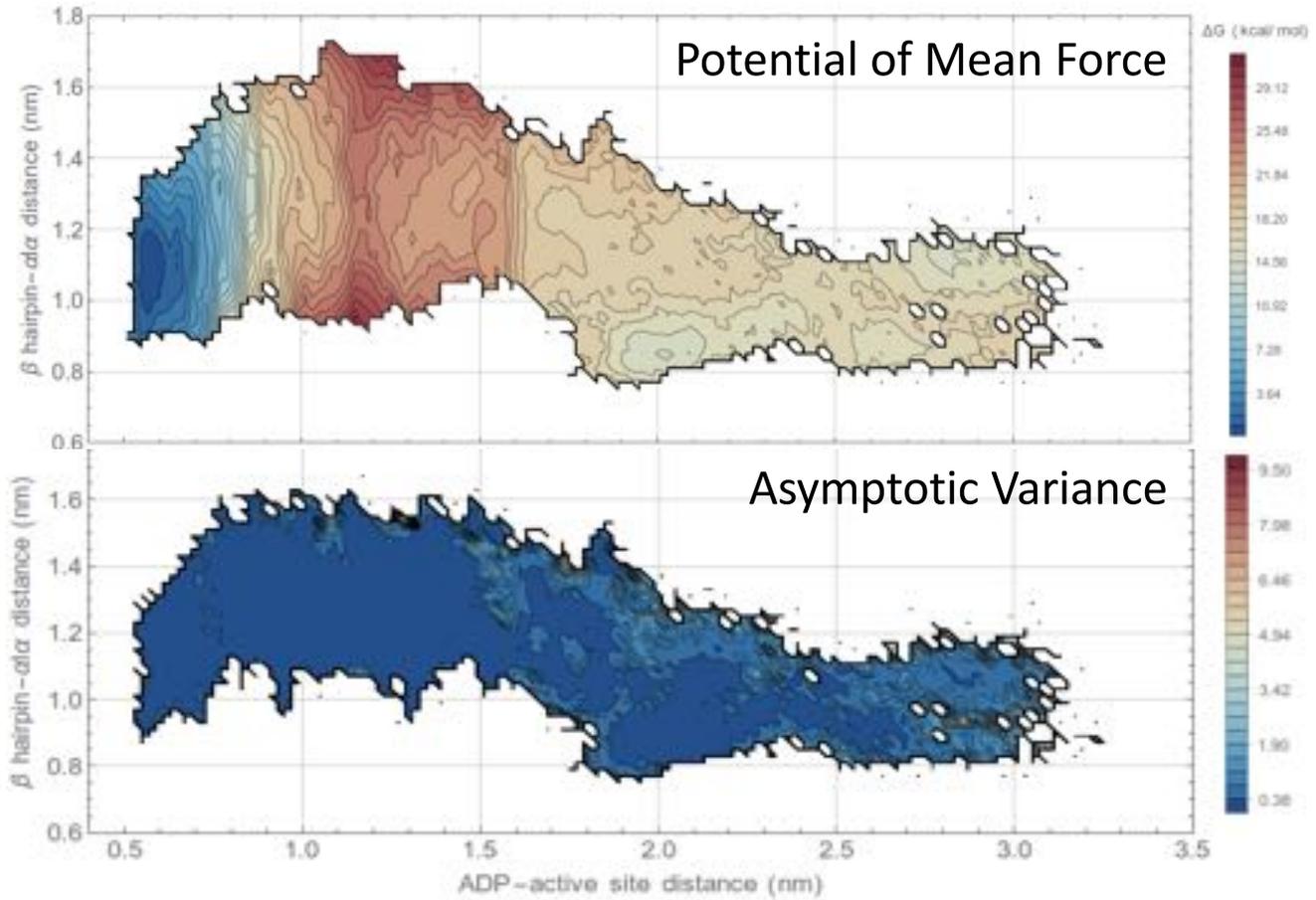
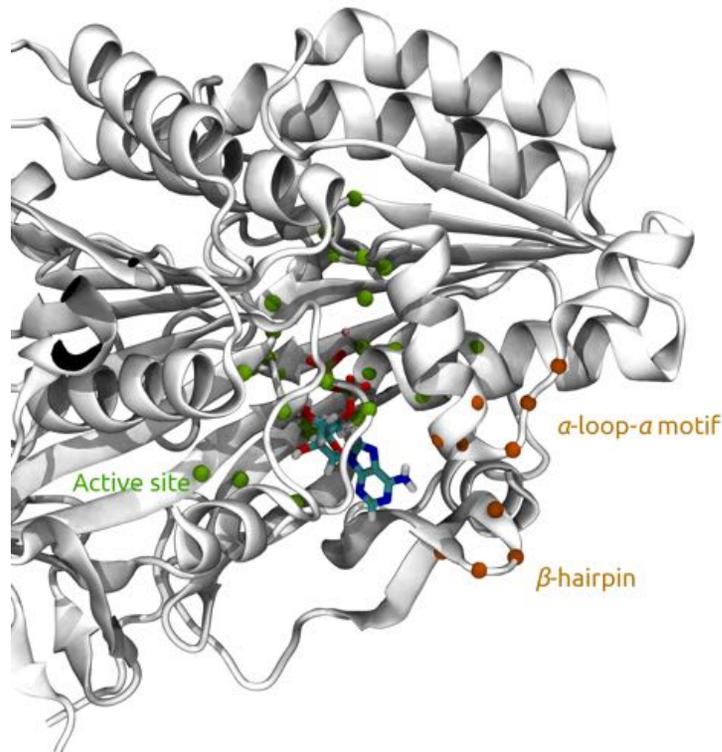
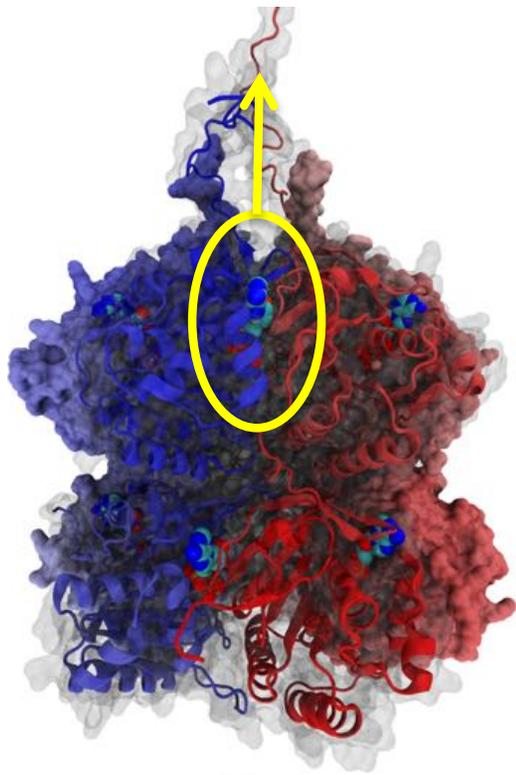


# EMUS error contributions to $\Delta G(\text{TS1} - C_{7\text{ax}})$ of the alanine dipeptide

Window importances



# EMUS applied to ADP release from a circadian clock protein (KaiC, AAA+ ATPase)



Simulations by Lu Hong

# EMUS Summary

- We cast equilibrium US as an eigenproblem.

$$z_j = \sum_i z_i F_{ij}$$

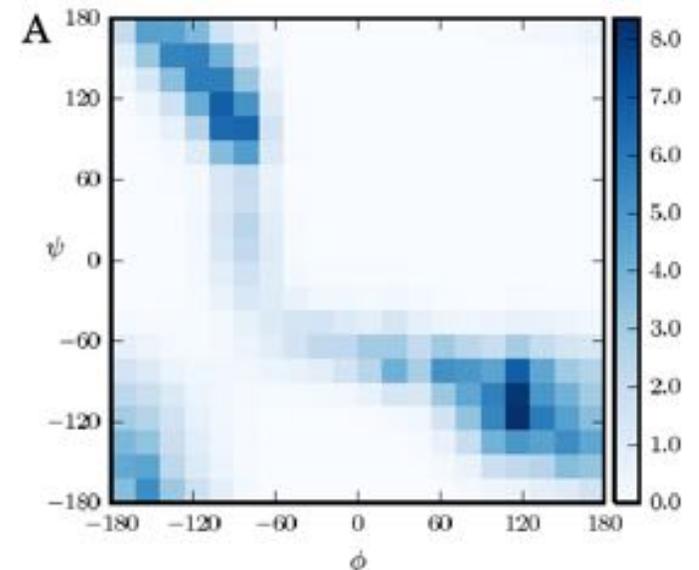
- The non-iterative nature of EMUS facilitates error analysis.

$$F_{ij} = \int \frac{\psi_j(x)}{\sum_k \psi_k(x)} \pi_i(x) dx$$

- Average-specific window contributions can be used to guide sampling.

$$\frac{\partial z_k}{\partial F_{ij}} = z_i (I - F)^{\#}_{jk}$$

- <https://github.com/ehthiede/EMUS>



# Outline

- Motivation
- Eigenvector Method for Umbrella Sampling (EMUS)
  - Formulation
  - Error analysis
  - Examples

Thiede, Van Koten, Weare, Dinner, J Chem Phys 145, 084115 (2016)

Dinner, Thiede, Van Koten, Weare, arxiv:1705.08445 (2017)

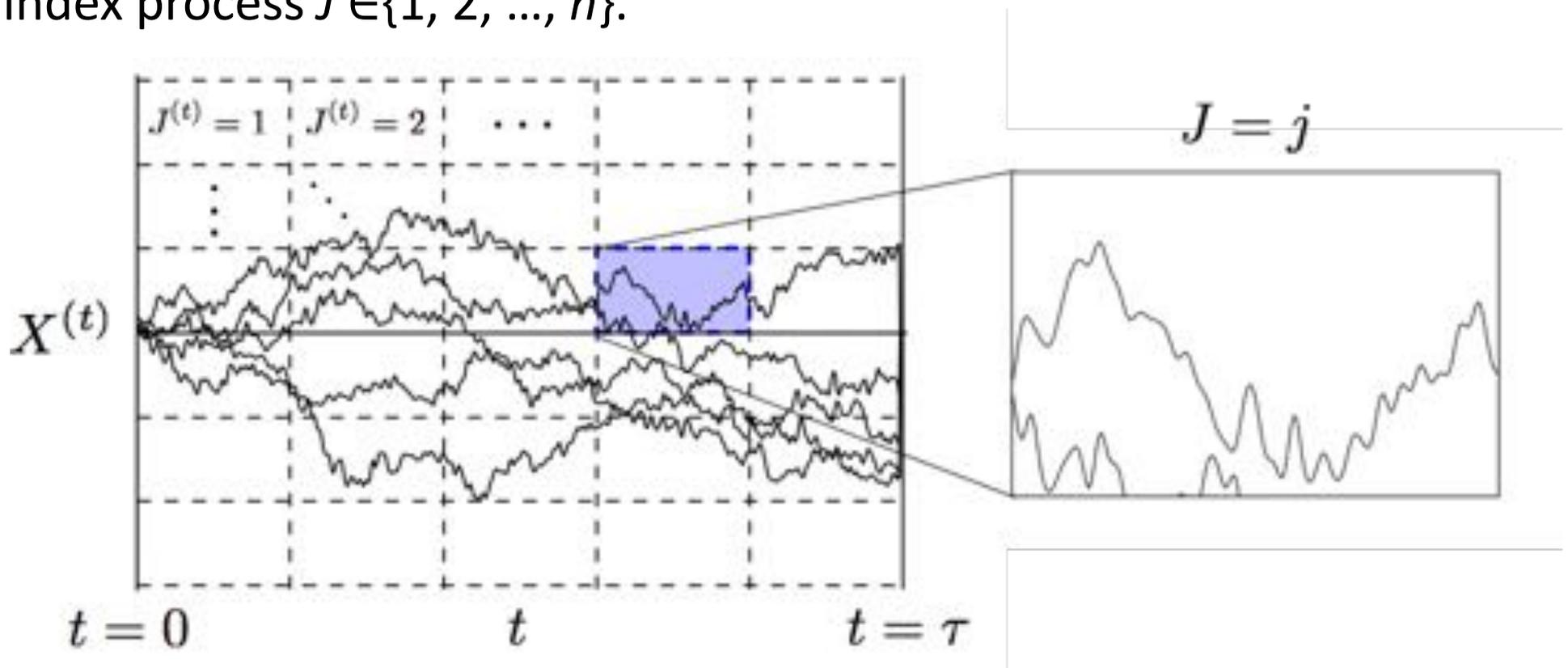
- Nonequilibrium Umbrella Sampling (NEUS)
  - Formulation
  - Examples

Dinner, Tempkin, Van Koten, Mattingly, Weare, SIREV; arXiv:1610.09426

We seek to calculate nonequilibrium expectations as a sum over windows:

$$\mathbf{E} \left[ \sum_{t=0}^{\tau-1} f(t, dx) \right] = \sum_{j=1}^n z_j \langle f \rangle_j$$

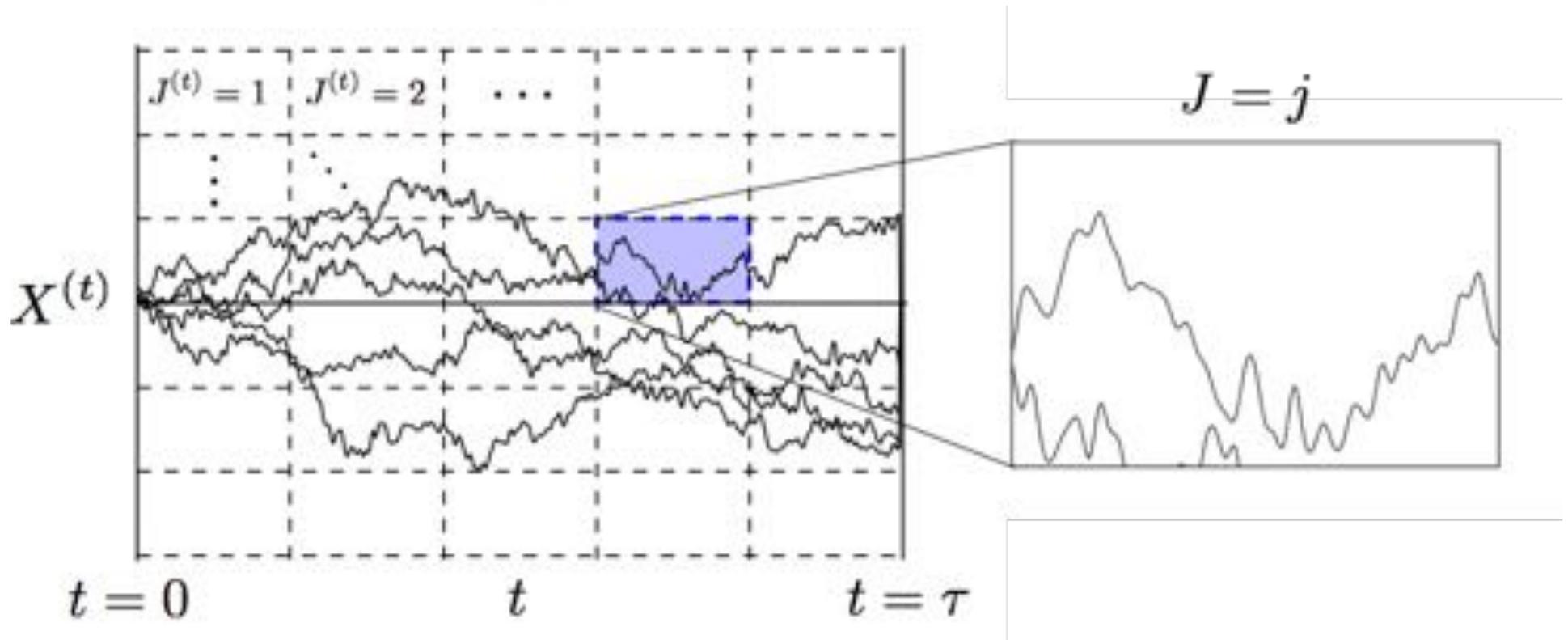
To this end, we define windows in space and time and define an index process  $J \in \{1, 2, \dots, n\}$ .



Now,

$$\pi_i(t, dx) = \frac{\mathbf{P} \left[ t < \tau, X^{(t)} \in dx, J^{(t)} = i \right]}{z_i}$$

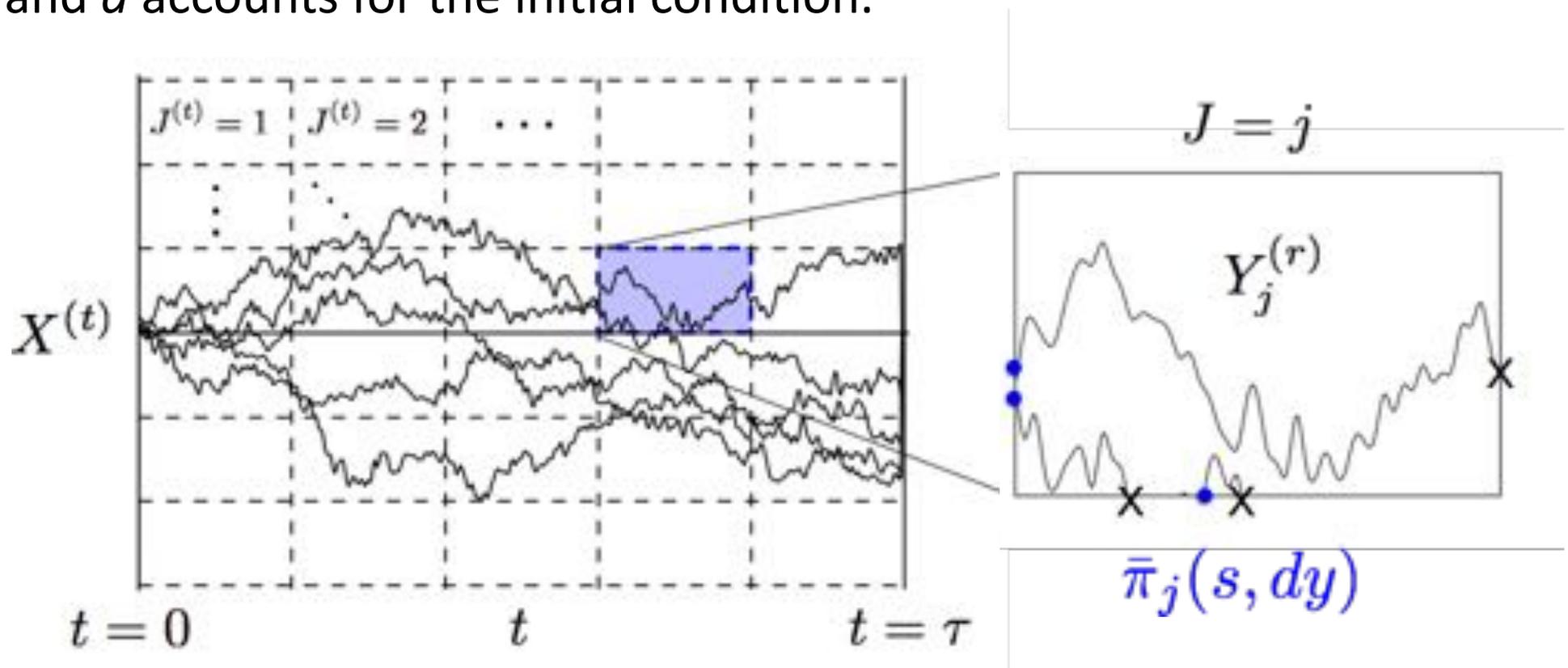
$$z_j = \sum_{t=0}^{\infty} \mathbf{P} \left[ t < \tau, J^{(t)} = j \right]$$



The key difference from EMUS is that now, to obtain  $\pi_j$ , we sample trajectory segments with initial points drawn from the entry point distribution into window  $j$ ,  $\bar{\pi}_j$ . If we can do that, the  $z_i$  can be shown to satisfy

$$z^T G + a^T = z^T$$

where  $G$  is the matrix of window-to-window transition probabilities and  $a$  accounts for the initial condition.



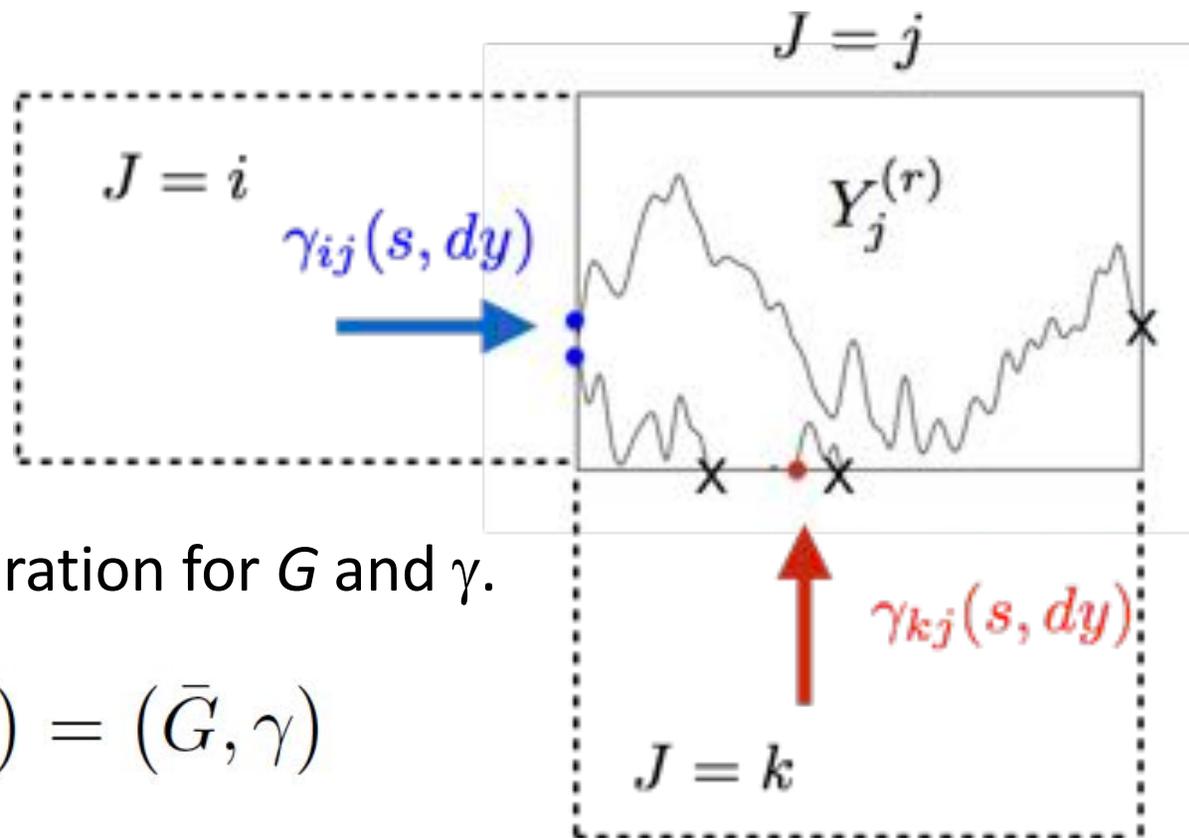
window-to-window transition probabilities  
(analog of  $F_{ij}$  in EMUS)

conditional distribution for a particular neighbor pair

entry-point distribution

$$\bar{\pi}_j(s, dy) = \frac{1}{z_j(1 - G_{jj})} \begin{cases} \sum_{i \neq j} z_i G_{ij} \gamma_{ij}(s, dy), & \text{if } s > 0 \\ a_j \mathbf{P}[X^{(0)} \in dy | J^{(0)} = j] & \text{if } s = 0 \end{cases}$$

We use the statistics of exit points to update estimates of  $\gamma_{ij}$  in neighboring windows.



This defines a fixed-point iteration for  $G$  and  $\gamma$ .

$$(\mathcal{G}(\bar{G}, \gamma), \Gamma(\bar{G}, \gamma)) = (\bar{G}, \gamma)$$

NEUS is a form of stochastic approximation.

## NEUS procedure (parallels EMUS)

1. Estimate  $G$  and  $\langle f \rangle_j$  by sampling from  $\pi_j$  using the latest estimates of the weights  $z$  and the entry point distributions.
2. Solve the affine eigenvector equation

$$z^T G + a^T = z^T$$

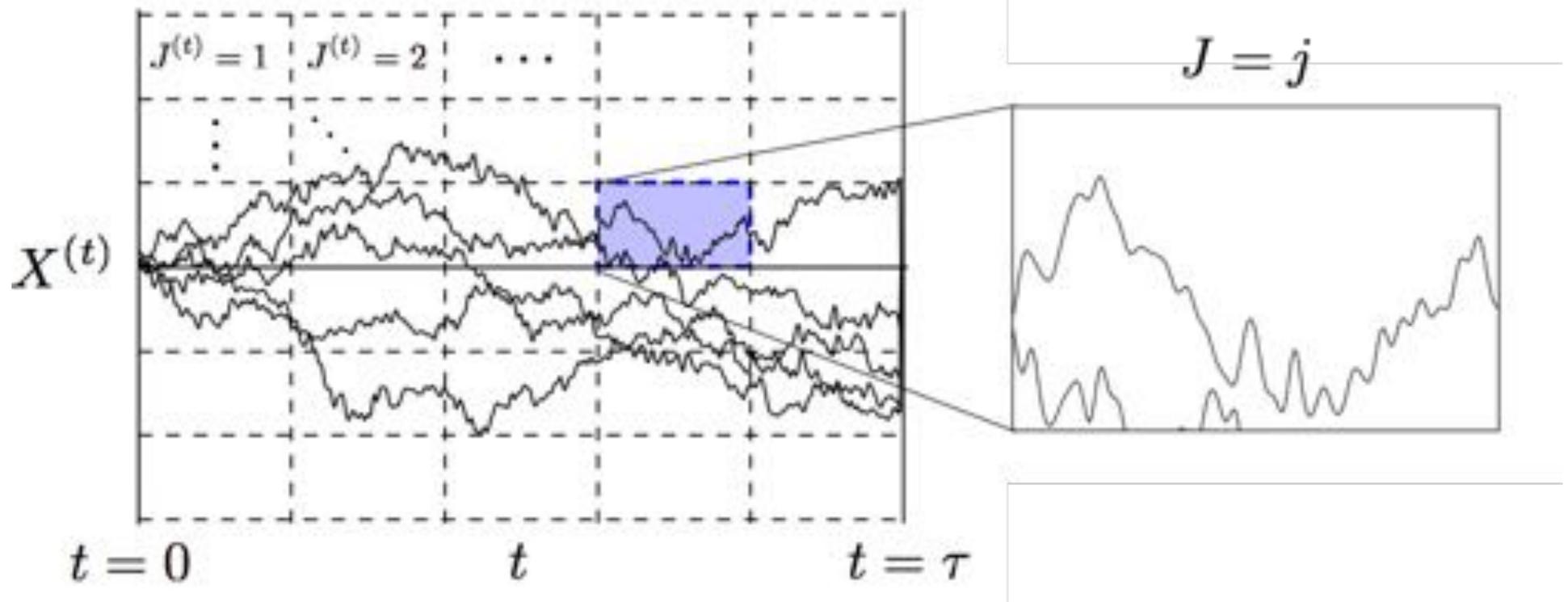
3. Compute the desired expectation as a weighted average

$$\mathbf{E} \left[ \sum_{t=0}^{\tau-1} f(t, dx) \right] = \sum_{j=1}^n z_j \langle f \rangle_j$$

Iterate

### Workshop III: Surrogate Models and Coarsening Techniques

In effect, we have obtained a procedure for generating the dynamics of the index process  $J$  from short trajectory segments.



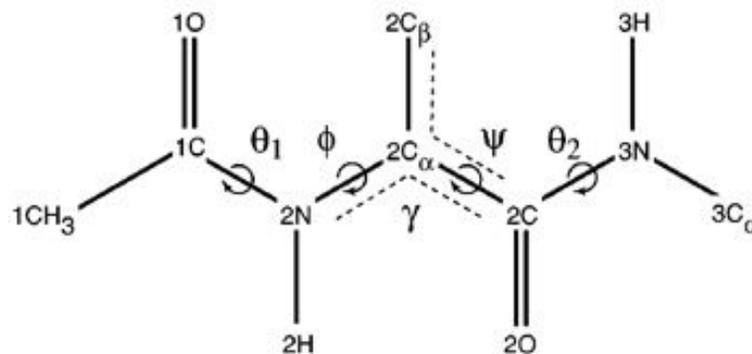
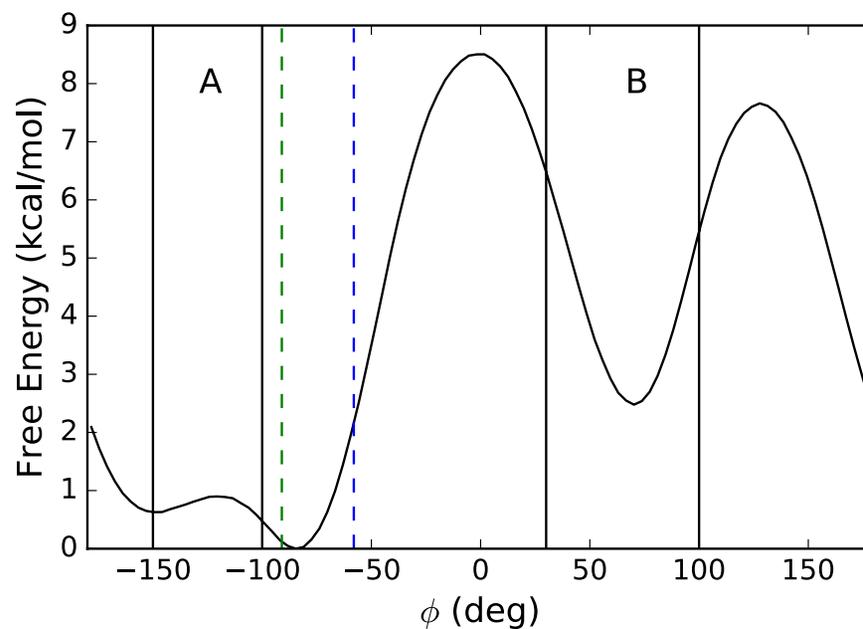
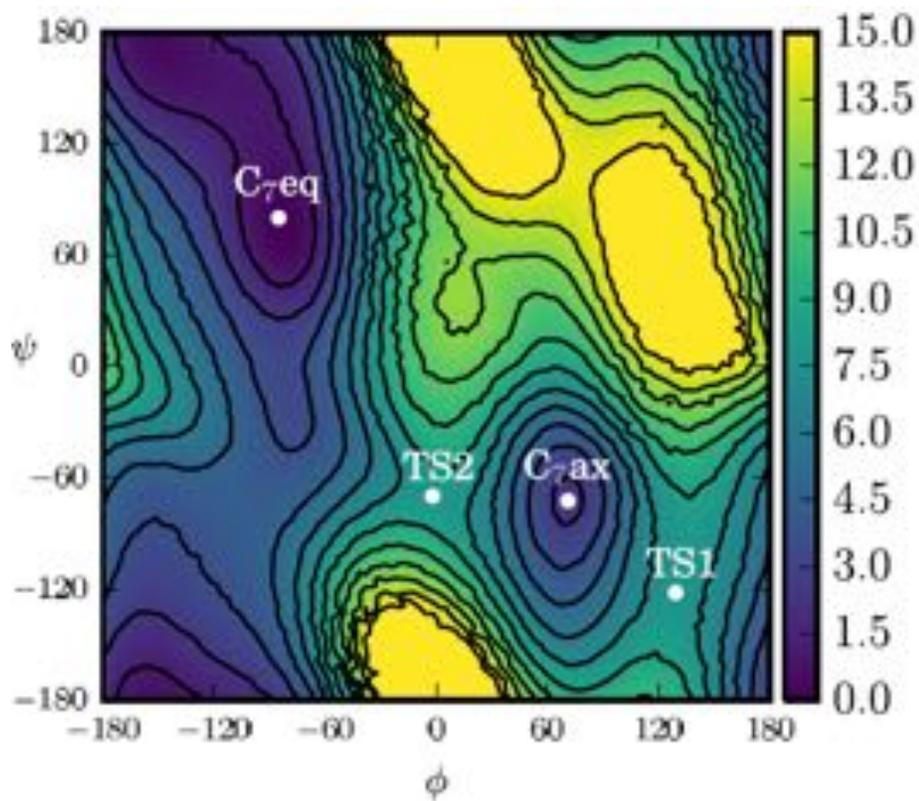
## Advantages of new NEUS procedure

- Unified framework for equilibrium and nonequilibrium US.
- Shows NEUS is a form of stochastic approximation.
- Allows computing expectations over non-stationary processes.
  - Can be used to obtain exact dynamical statistics for microscopically reversible dynamics.
  - Can be used for any process in which the microscopic dynamics defines the distribution function.

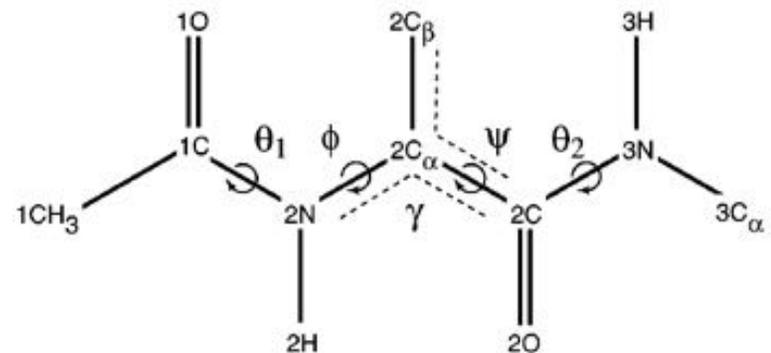
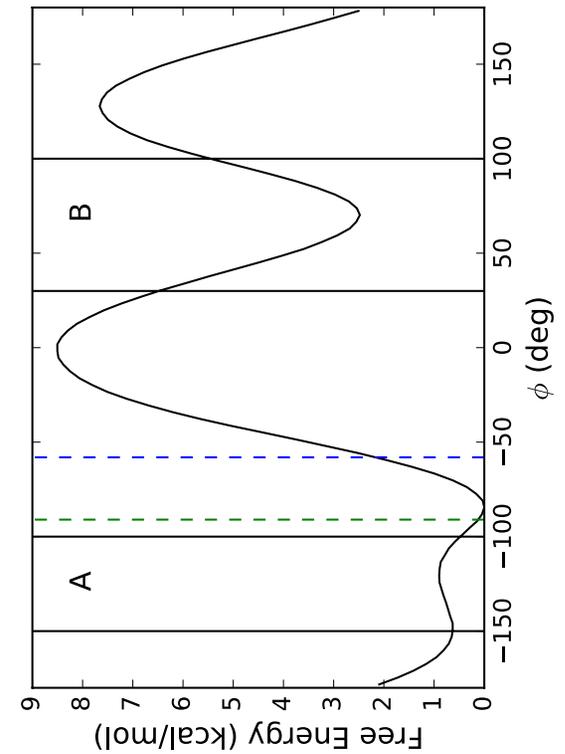
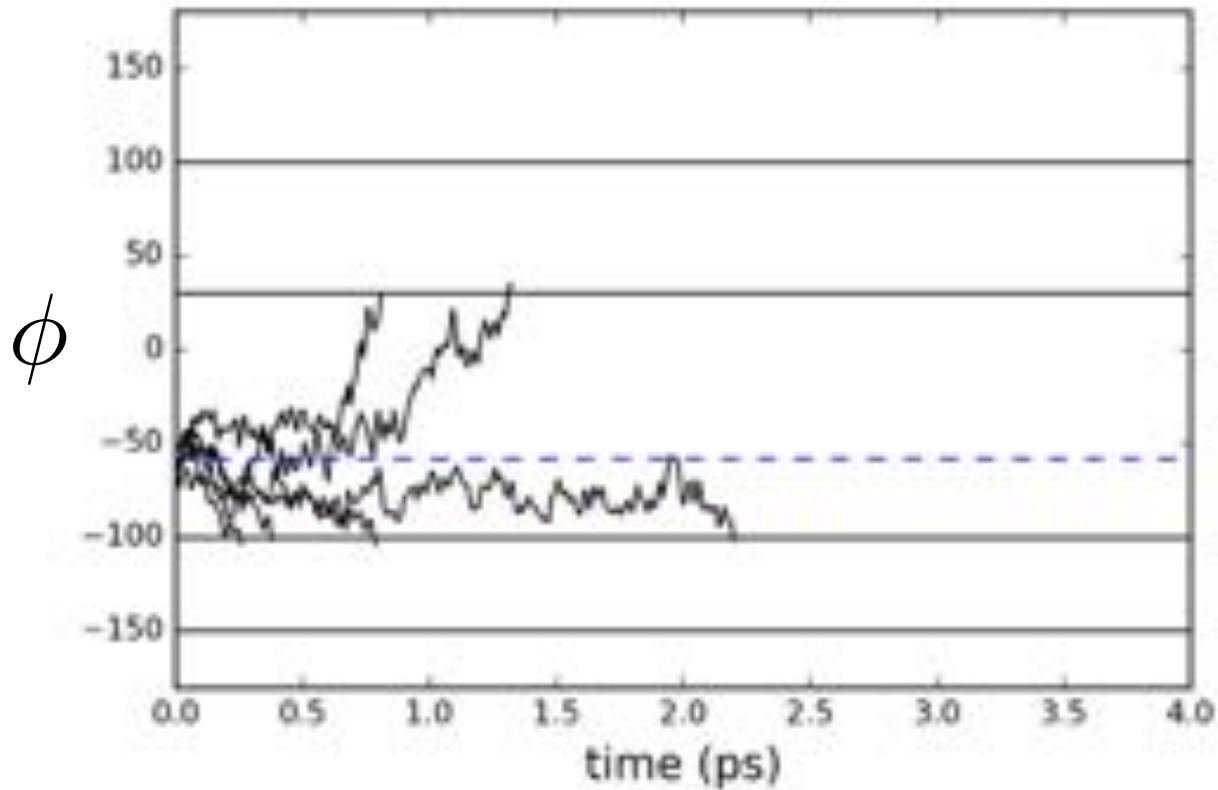
Dinner, Tempkin, Van Koten, Mattingly, Weare, SIREV; arXiv:1610.09426

Example: Compute probability of hitting set B before set A  
for times less than  $\tau_{\max}$ .

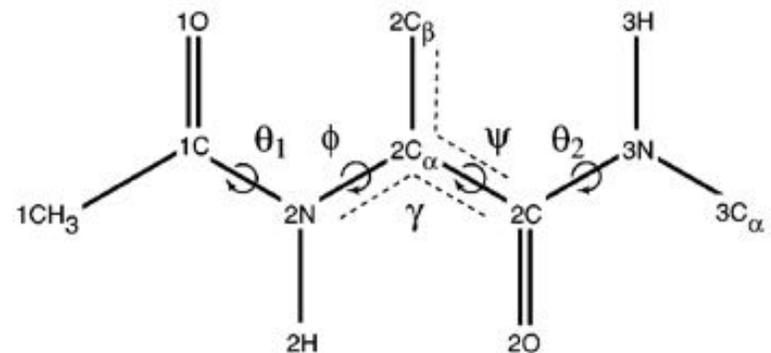
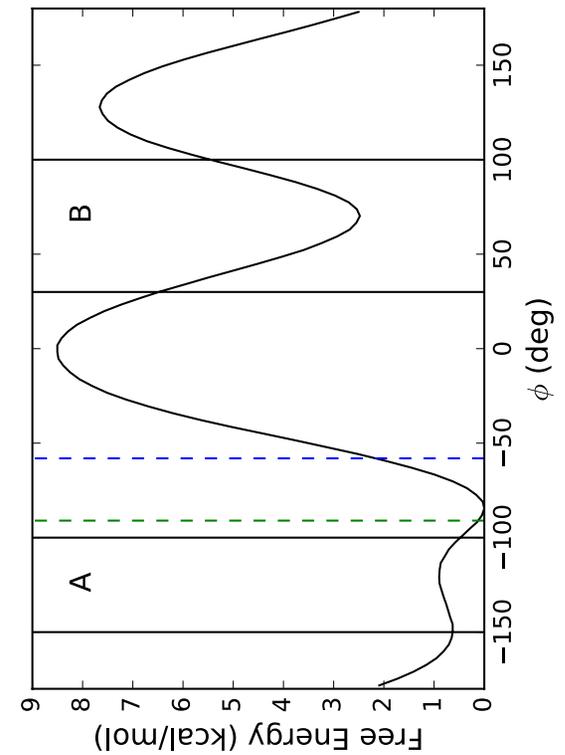
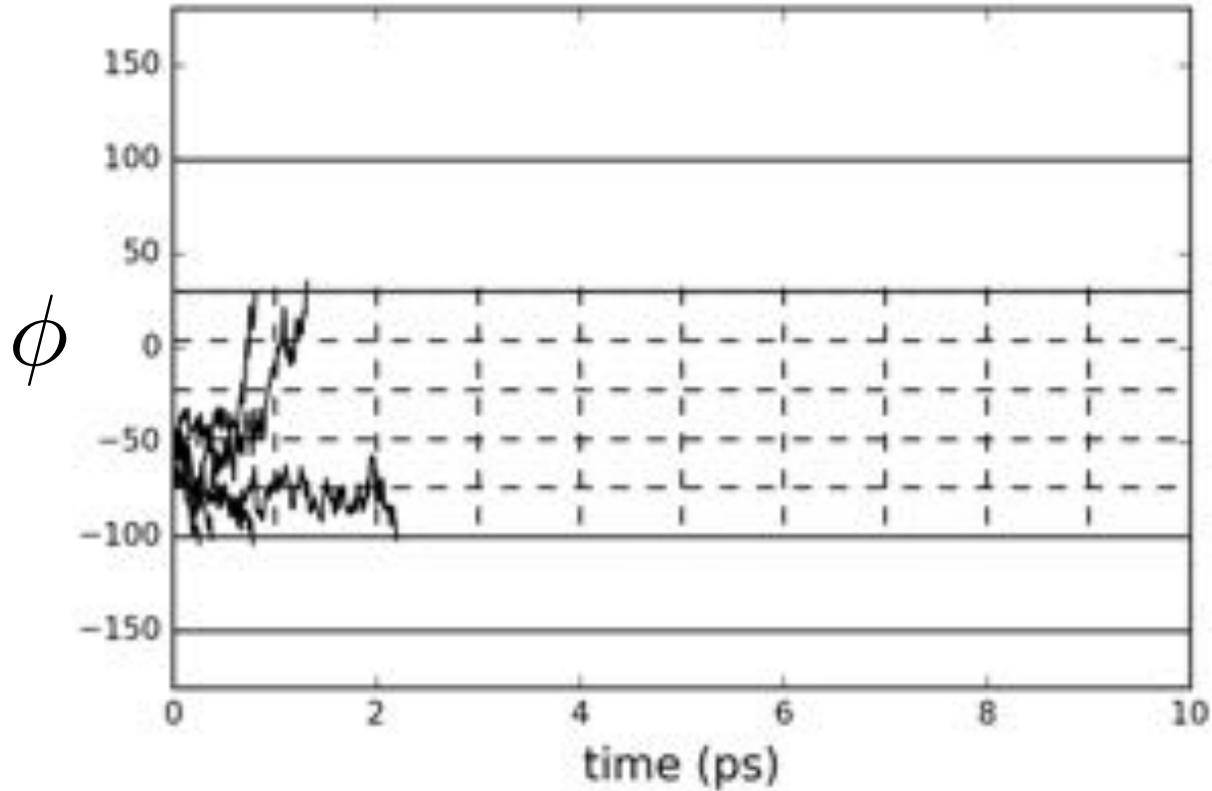
Potential of mean force (kcal/mol)



Example: Compute probability of hitting set B before set A for times less than  $\tau_{\max}$  (direct shooting).

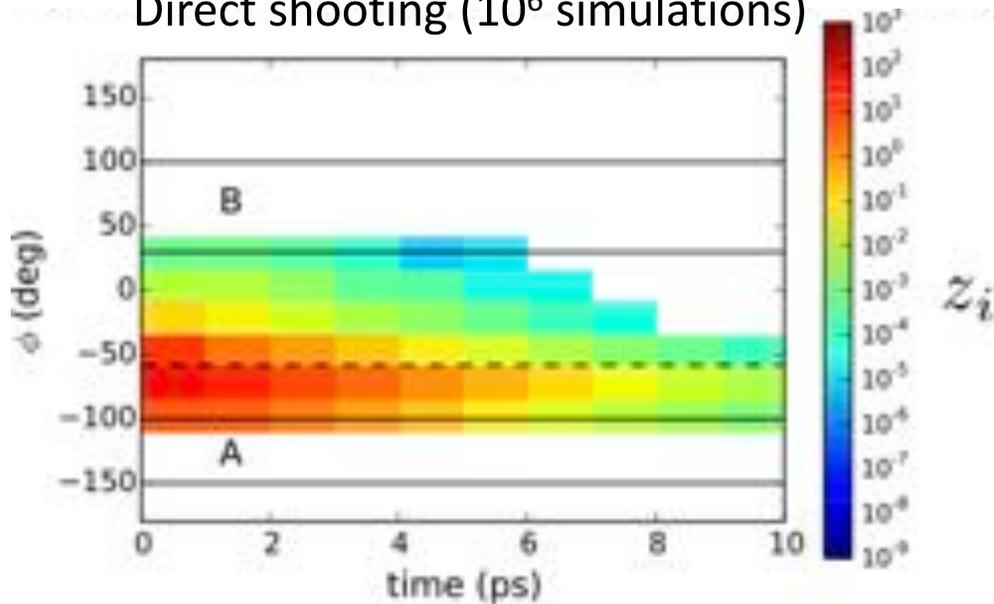


Example: Compute probability of hitting set B before set A for times less than  $\tau_{\max}$  (stratification).



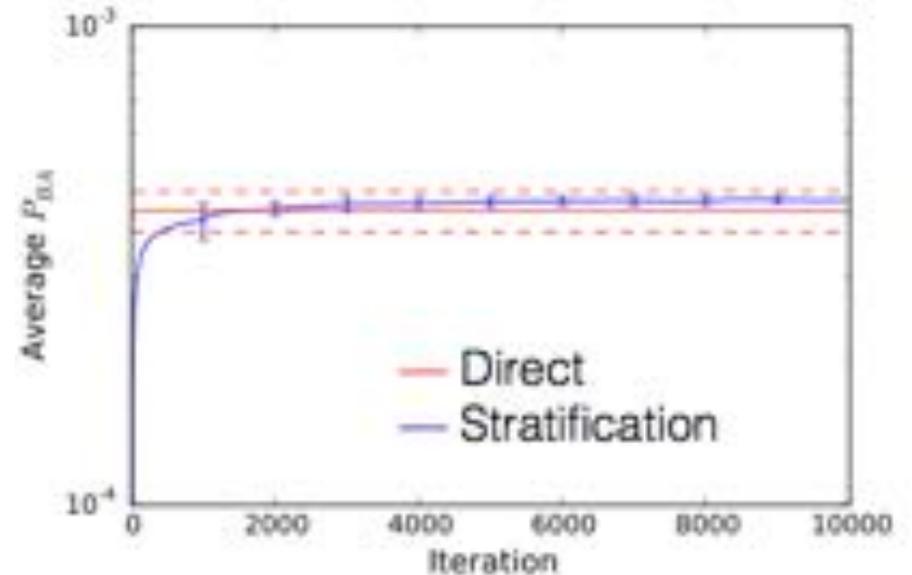
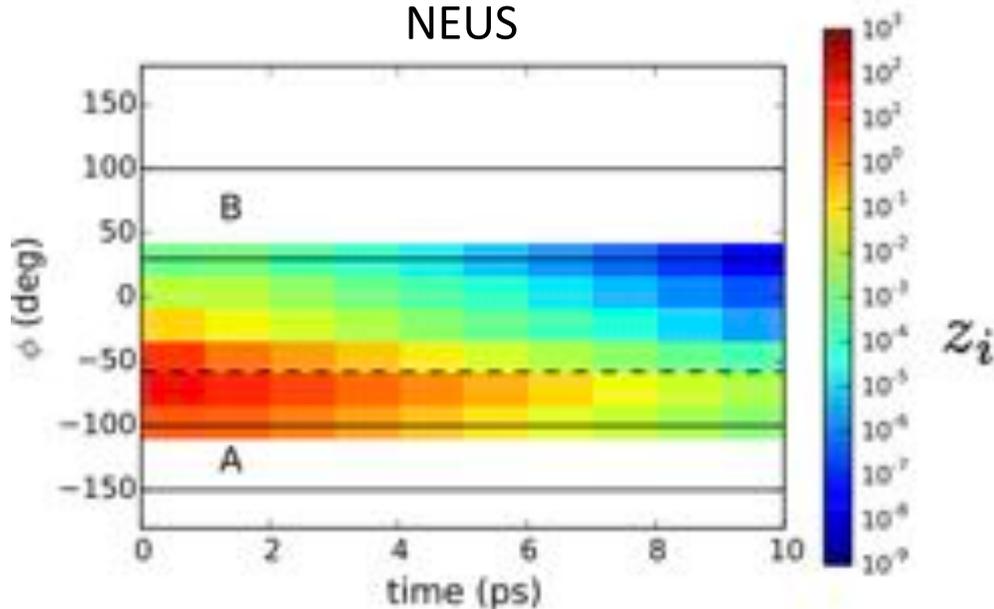
Example: Compute probability of hitting set B before set A for times less than  $\tau_{\max}$ .

Direct shooting ( $10^6$  simulations)



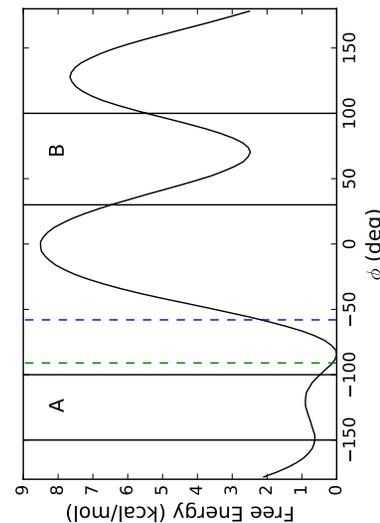
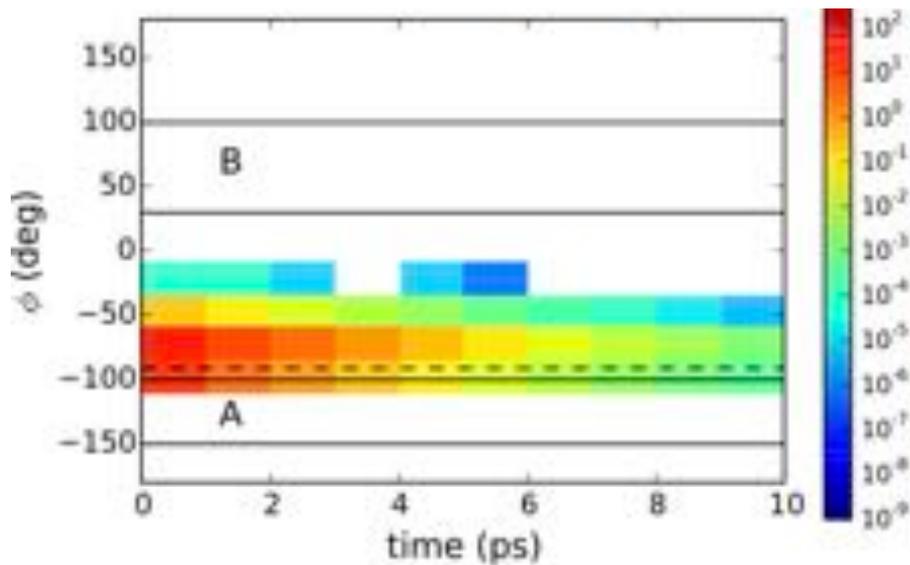
For a sufficiently easy problem, we can verify that we obtain the same result as direct simulation.

NEUS



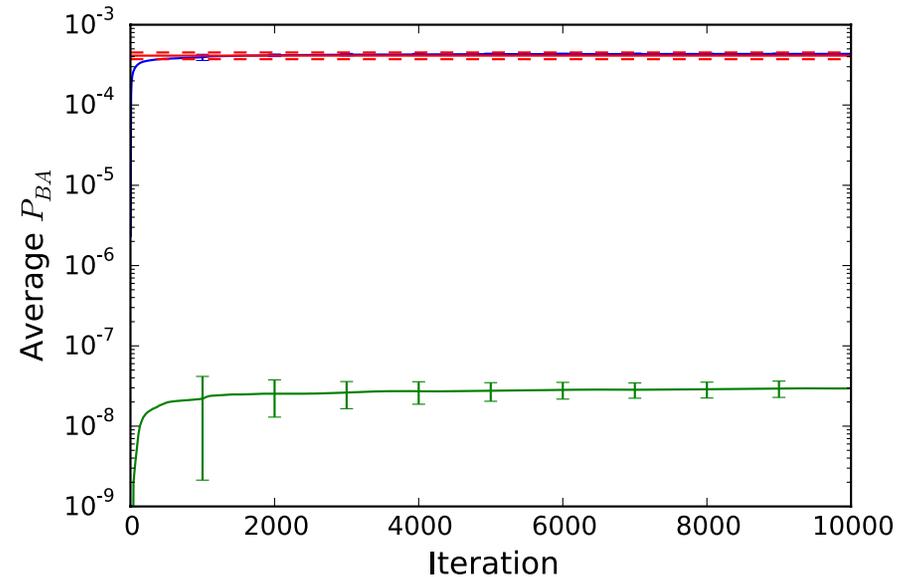
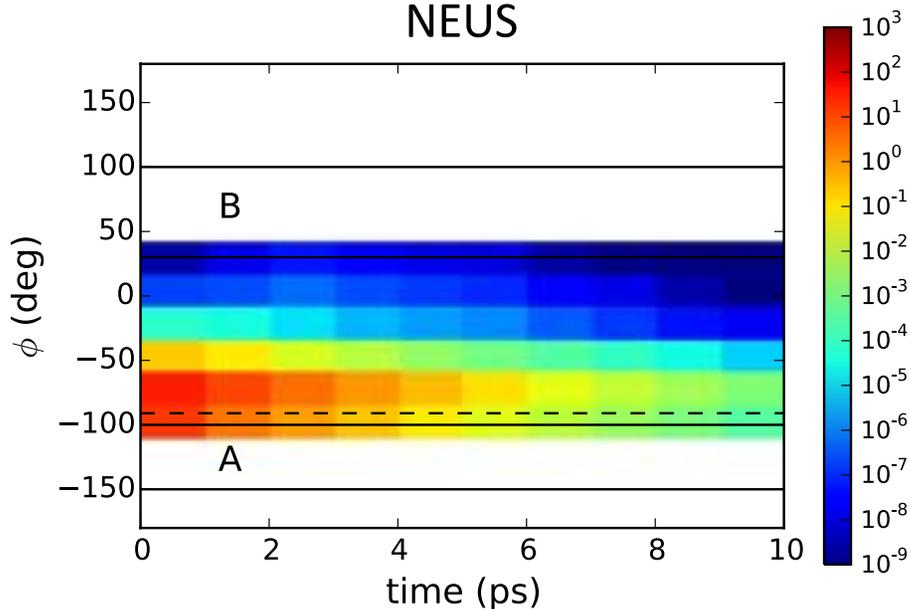
Example: Compute probability of hitting set B before set A  
for times less than  $\tau_{\max}$ .

Direct shooting ( $10^6$  simulations)



If we shift the initial condition to make the problem harder, direct integration becomes impossible but NEUS costs the same.

NEUS

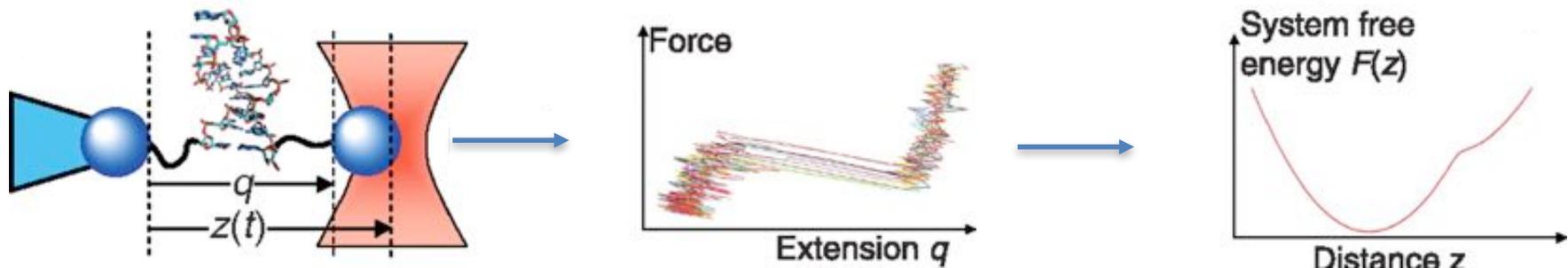


Example: Compute a free energy difference by stratifying the irreversible work, a path-dependent variable

Jarzynski's equality provides an exact relationship between the exponential of the accumulated work,  $W^{(t)}$ , in a driven process and the free energy difference.

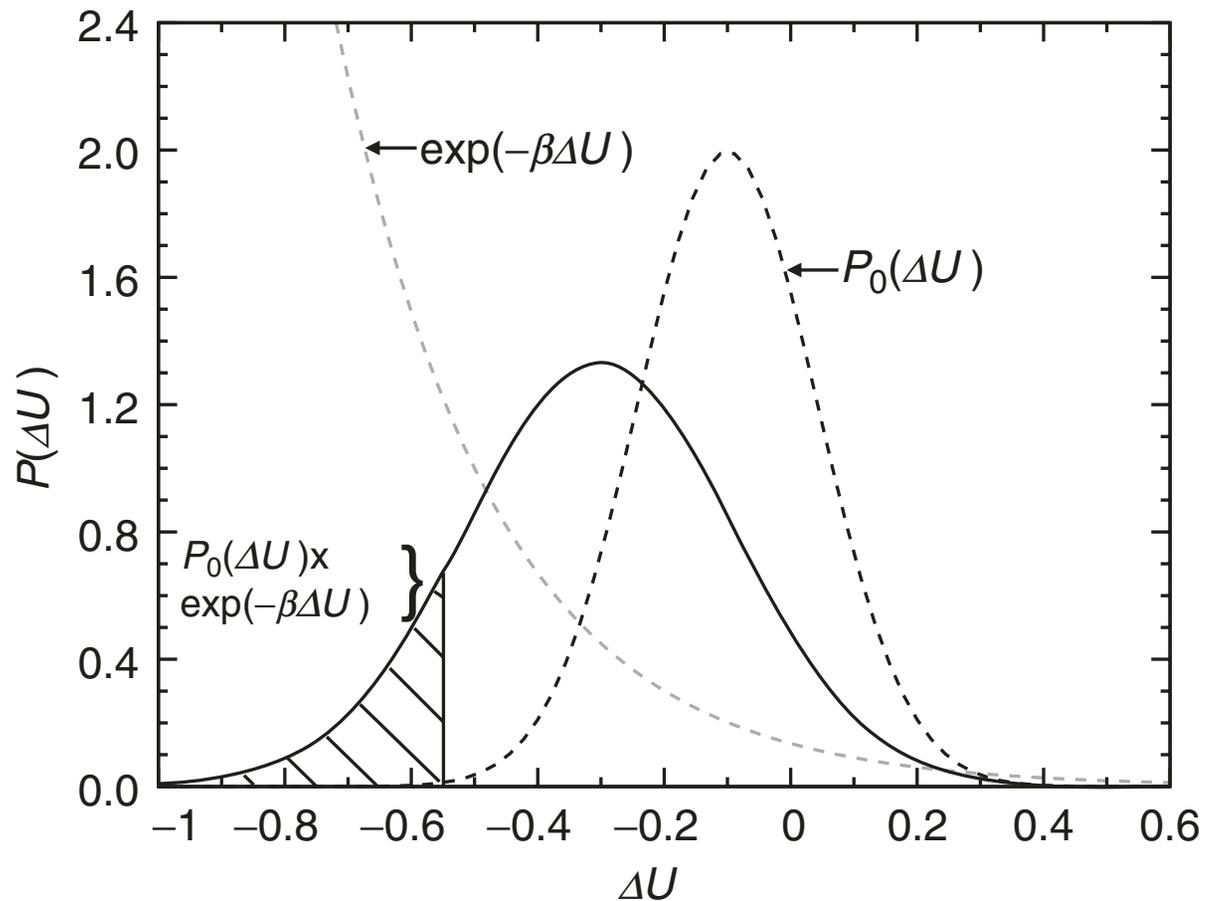
$$e^{-\beta\Delta F} = \langle e^{-\beta W^{(t)}} \rangle$$

This equality has been useful in measuring free energies in single-molecule force spectroscopy experiments as well as providing a computational strategy for computing free energies from steered molecular dynamics simulations.



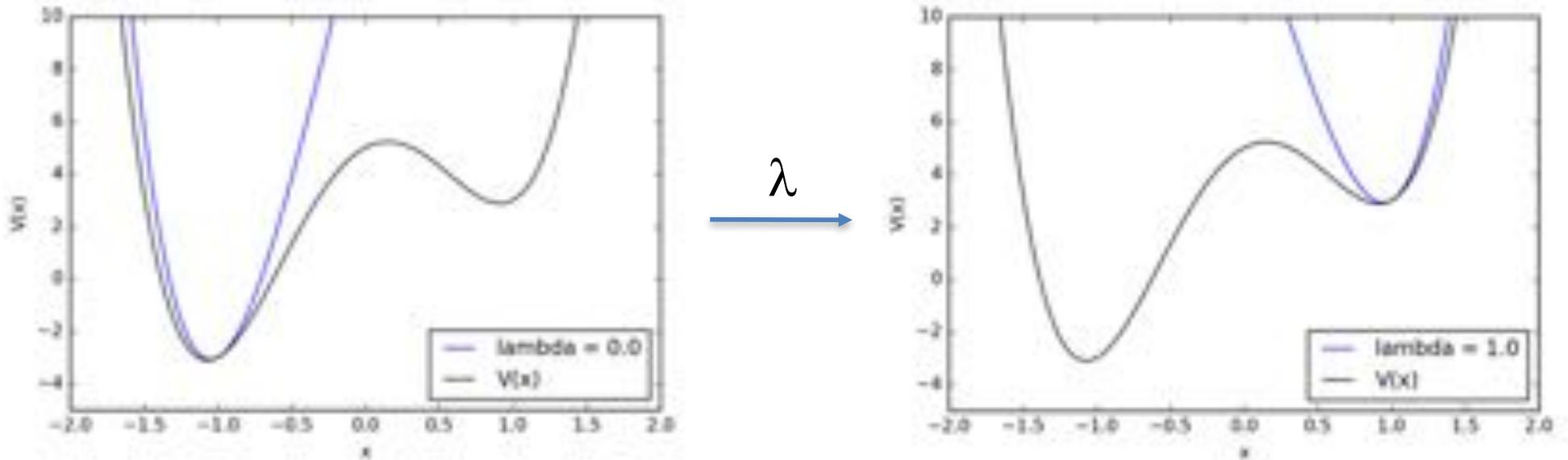
Example: Compute a free energy difference by stratifying the irreversible work, a path-dependent variable

In practice, such simulations suffer from severe statistical errors in the fast-switching regime because the low-work tail dominates the average.



Chipot and Pohorille, Free Energy Simulations, Springer, 2007.

Example: Compute a free energy difference by stratifying the irreversible work, a path-dependent variable

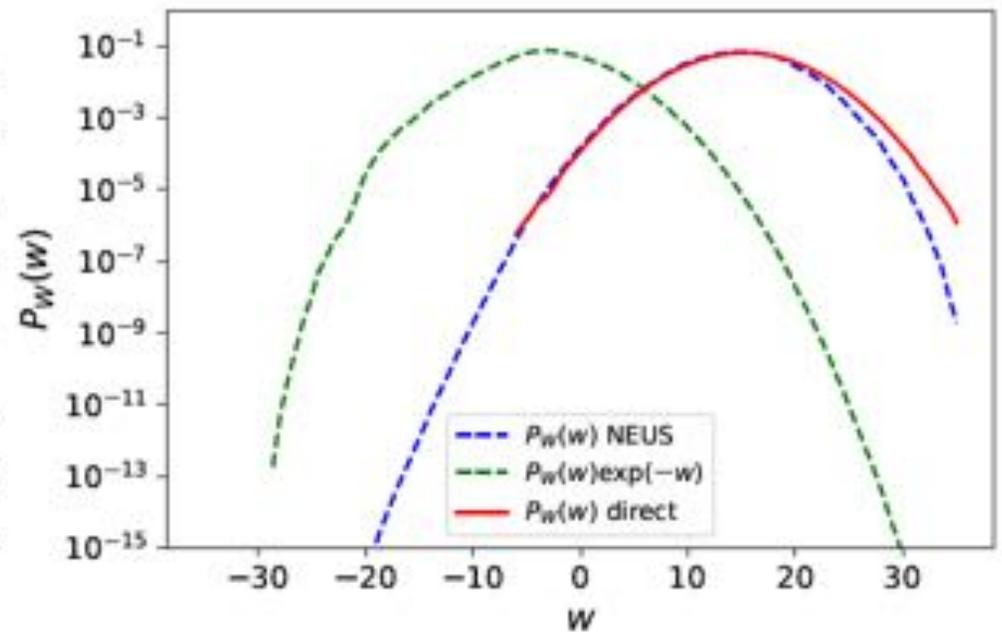
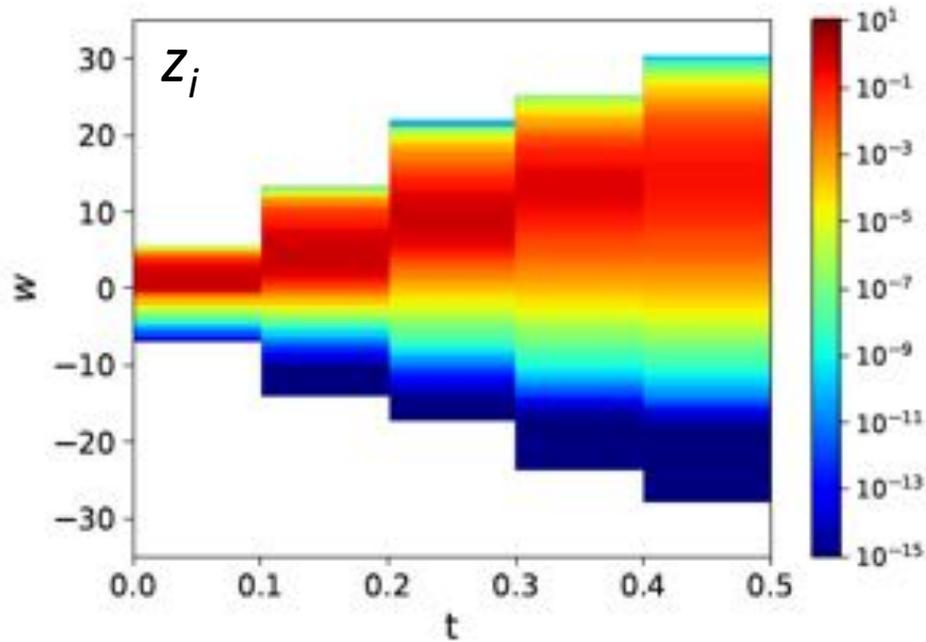


$$V(x, \lambda) = 5(x^2 - 1)^2 + 3x + 10(x - (2\lambda - 1))^2$$

$$W^{(t)} = \sum_{\ell=0}^{t-1} V(\ell + 1, X^{(\ell)}) - V(\ell, X^{(\ell)}), \quad W^{(0)} = 0$$

$$\Delta F \approx -kT \ln \left[ \frac{1}{N} \sum_{i=1}^N \exp(-\beta W_i^{(t)}) \right]$$

Example: Compute a free energy difference by stratifying the irreversible work, a path-dependent variable

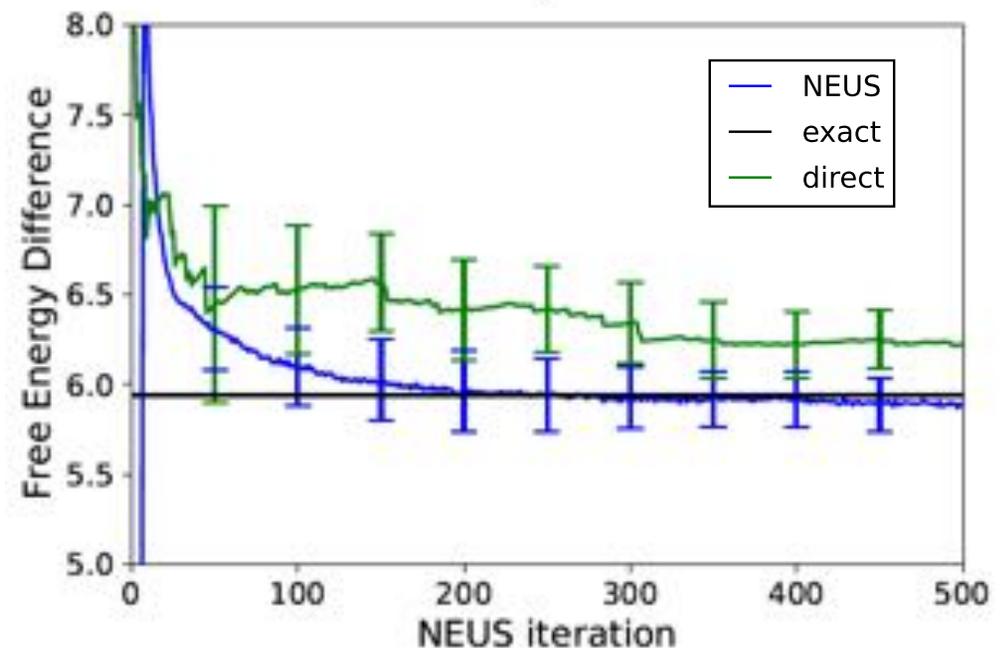


Direct

$$\Delta F \approx -kT \ln \left[ \frac{1}{N} \sum_{i=1}^N \exp(-\beta W_i^{(t)}) \right]$$

NEUS

$$\langle \exp(-\beta W^{(t)}) \rangle = \sum_{i=1}^n z_i \langle \exp(-\beta W^{(t)}) \rangle_i$$



# NEUS Summary

- We cast NEUS as an affine eigenproblem with a structure that parallels equilibrium US.

$$z^T G + a^T = z^T$$

- Solving it involves fixed point iteration of window-to-window transition probabilities and entry-point distributions (reflecting that NEUS is both a splitting and a stratification method).

$$(\mathcal{G}(\bar{G}, \gamma), \Gamma(\bar{G}, \gamma)) = (\bar{G}, \gamma)$$

- Present algorithm allows sampling new classes of dynamical averages.

