



# COARSE GRAINING IN PHYSICAL SPACE

Lorenzo Boninsegna & Cecilia Clementi Long Program EL2017





## OUTLINE



- MOTIVATION
- COARSE GRAINING (CG) INGREDIENTS
- COARSE GRAINING STRATEGIES
- CHALLENGES:
  - IDENTIFICATION OF CG BEADS
  - REPRODUCING THE CORRECT DYNAMICS
- INCORPORATING EXP DATA
- OUTLOOK

#### HIERARCHY IN PHYSICAL SYSTEMS

study case 1





assembling of microscopic constituents impacts mesoscopic features



### **BIOMOLECULES AND COARSE-GRAINING**



![](_page_4_Figure_2.jpeg)

(courtesy of Cecilia Clementi)

#### COARSE GRAINING IN A NUTSHELL

Coarse-Graining (CG)

decimating degrees of freedom into effective ones

![](_page_5_Picture_3.jpeg)

- Physical intuition or principles usually guide the choices
- Model needs to retain 'important' features
- Increasing interest in data-driven, automatic procedures

#### **RESOLUTION IS KEY**

![](_page_6_Figure_1.jpeg)

high resolution, properties are preserved by different CG sites

![](_page_6_Picture_3.jpeg)

low resolution, ultra CG many atoms/residues are grouped into a single CG bead

#### THE CG INGREDIENTS

#### ...effective ...effective degrees ╋ of freedom $\xi_i$ Hamiltonian $\mathcal{H}$ identify groups of atoms moving project the all atom Hamiltonian together in the dynamics onto reduced space $(\mathbf{x}_1,\cdots,\mathbf{x}_N) \xrightarrow{\Phi} (\xi_1,\cdots,\xi_M)$ $H(\mathbf{x}_1,\cdots,\mathbf{x}_N) \xrightarrow{\Gamma} \mathcal{H}(\xi_1,\cdots,\xi_M)$ (M < N)**CG MODEL CG dynamics** CG thermodynamics are these the actual low resolution description of the FG

properties?

## COARSE GRAINING PHILOSOPHIES

Problem is formidable and can be tackled from alternative points of view

![](_page_8_Figure_2.jpeg)

#### STRUCTURE - BASED MODELS: PREQUEL

![](_page_9_Figure_1.jpeg)

Natural protein energy landscape resembles a rugged funnel

![](_page_9_Figure_3.jpeg)

## STRUCTURE - BASED MODELS: ZEROTH ORDER

Theoretical justification in **principle of minimal frustration**:

proteins have evolved their ability to fold by minimizing frustration

![](_page_10_Figure_3.jpeg)

one CG bead per residue

$$\mathcal{H}_{Go} = -\sum_{native} \epsilon$$

smooth, funneled landscape (ideal gas)

Despite simplicity, many successful studies:

- Das et al., PNAS (2005), 102, 14569
- Hyeon et al., PNAS (2007), 104, 2175
- Koga et al., PNAS (2006), 103, 5367

Clementi, Curr. Opin. Struct. Biol. (2008),18,10 Clementi, Nymeyer & Onuchic (JMB 2000)

## **STRUCTURE - BASED MODELS: CORRECTIONS**

Beyond zeroth order:
$$\mathcal{H}_{SBM} = \mathcal{H}_{Go} + \sum_{native} \delta \epsilon_{ij} + \sum_{non-native} \delta_{ij} + \cdots$$
heterogeneityfrustration

This is necessary to account for compact non native states or misfolded structures

![](_page_11_Figure_3.jpeg)

Kluber, Burt, Clementi (2017, submitted)

## MARTINI FORCE FIELD

![](_page_12_Figure_1.jpeg)

FG representation of the amino acids. Different colors represent different particle types

![](_page_12_Picture_3.jpeg)

CG representation of a WALP23 peptide in a double lipid layer

- four-to-one mapping
- four main types of interaction sites, different levels
- integrated in GROMACS

non bonded potential

$$\mathbf{V}_{\text{Lennard-Jones}}(r_{ij}) = 4\varepsilon_{ij} \left[ \left( \frac{\sigma_{ij}}{r_{ij}} \right)^{12} - \left( \frac{\sigma_{ij}}{r_{ij}} \right)^6 \right]$$

bonded potential  

$$V_{b} = \frac{1}{2}K_{b}(d_{ij} - d_{b})^{2}$$

$$V_{a} = \frac{1}{2}K_{a}[\cos(\varphi_{ijk}) - \cos(\varphi_{a})]^{2}$$

$$V_{d} = K_{d}[1 + \cos(n\psi_{ijkl} - \psi_{d})]$$

$$V_{id} = K_{id}(\psi_{ijkl} - \psi_{id})^{2}$$

Marrink *et al., J. Phys. Chem. B* (**2004**) 108, 750 Monticelli *et al., JCTC* (**2008**) 4, 819

## AWSEM FORCE FIELD

**AWSEM** (Associative memory Water Mediated Structure and Energy Model)

both knowledge and physics based approaches, with a bioinformatically justified term which correspond to memories of proteins structures with similar sequences

![](_page_13_Figure_3.jpeg)

## COARSE GRAINING PHILOSOPHIES

Problem is formidable and can be tackled from alternative points of view

![](_page_14_Figure_2.jpeg)

Noid, *J. Chem. Phys* (**2013**), 139, 090901 Saunders and Voth, *Ann. Rev. Biophys.* (**2013**), 42, 73

#### CG THERMODYNAMICS

![](_page_15_Figure_1.jpeg)

Let  $M : x_i \to X_i$  be the **CG mapping**. Then CG thermodynamics given (in principle)

$$e^{-\beta W(\mathbf{X})} \propto \int d\mathbf{x} \delta \left( \mathbf{X} - \mathbf{M}(\mathbf{x}) \right) e^{-\beta U(\mathbf{x})}$$

reproducing PMF is one of major CG goals

- → integrating on the mapping hyperplane
- 'renormalization' of interactions
- → CG potential of mean force (PMF)

#### **INVERSION METHODS**

![](_page_16_Figure_1.jpeg)

#### **Different formulations**

(iterative) Boltzmann inversion  $V_{n+1}(r) = V_n(r) + kT \ln \frac{\text{RDF}_n(r)}{\text{RDF}_{\text{target}}(r)}$ 

Monte Carlo

RDF = (any) radial distribution function

$$V_{n+1}(r_i) = V_n(r_i) + \Delta V_n(r_i)$$
  
$$\Delta \text{RDF}_n(r_i) = \sum_{j=1}^{N} \frac{\partial \langle \text{RDF}_n(r_j) \rangle}{\partial V_n(r_j)} \Delta V_n(r_j) + O(\Delta V_n^2)$$

Lyubartsev *et al, Phys. Rev. E* (**1995**) 52, 3730 Müller-Plathe , *Chemphyschem* (**2002**) 3, 734 Soper, *Chem. Phys.* (**1996**) 202, 295

#### MULTISCALE COARSE GRAINING (MS-CG)

![](_page_17_Figure_1.jpeg)

 $\exp\left(-\beta U(\mathbf{X}^N)\right) \propto \int d\mathbf{x} \exp\left(-\beta u(\mathbf{x})\right) \delta(\mathbf{M}(\mathbf{x}) - \mathbf{X}^N) \quad \begin{array}{l} \text{free energy} \\ \text{mapping} \end{array}$ 

Assume CG mapping is known (crucial) and cast as follows

$$\mathbf{X}_k = \hat{\mathbf{M}}_k(\mathbf{x}) = \sum_i c_{ik} \mathbf{x}_i, \qquad \forall k = 1, \cdots, N$$

then

$$\mathbf{F}_k(\mathbf{X}^N) = -\frac{\partial U(\mathbf{X}^N)}{\partial \mathbf{X}_k} = \dots = \langle \sum_{j \in \mathcal{S}_k} \eta_{kj} \mathbf{f}_j(\mathbf{x}) \rangle_{\delta(\mathbf{X}^N - \mathbf{M}(\mathbf{x}))}$$

![](_page_17_Figure_7.jpeg)

conditional average of local atomistic forces, given than the system is in an allowed configuration

Noid et al., J. Chem. Phys. (2008) 128, 244114

Introduce a set of vectors  $\mathbf{G}(\mathbf{X}^N) = (\mathbf{G}_1, \cdots, \mathbf{G}_{N_D}) (\mathbf{X}^N)$ 

Define functional

$$\chi^{2}[\mathbf{G}] = \frac{1}{3N} \langle \sum_{k=1}^{N} | \sum_{q \in \mathcal{S}_{k}} \eta_{kj} \mathbf{f}_{j}(\mathbf{x}) + \mathbf{G}_{k}(\mathbf{M}(\mathbf{x})) \rangle^{2} \rangle_{\beta}$$

effective atomistic force value taken by vectors

It can be proved that

$$\chi^2[\mathbf{G}] \ge \chi^2[\mathbf{F}] = \chi^2[-\frac{\partial U(\mathbf{X}^N)}{\partial \mathbf{X}}]$$

CG force from PMF

amenable to a systematic variational optimization (see QM also)

basis functions

$$\mathcal{G}_{1}(\mathbf{X}^{N}) = -\nabla U_{1}(\mathbf{X}^{N})$$

$$\dots$$

$$\mathcal{G}_{p}(\mathbf{X}^{N}) = -\nabla U_{p}(\mathbf{X}^{N})$$

$$+ \begin{array}{c} \text{optimization of linear combinations} \\ \mathbf{G}_{q} = \sum_{i=1}^{N_{D}} \phi_{D} \mathcal{G}_{D}(\mathbf{X}^{N}) \\ \mathbf{G}_{q} = \sum_{i=1}^{N_{D}} \phi_{D} \mathcal{G}_{D}(\mathbf{X}^{N}) \end{array}$$

$$= \begin{array}{c} \text{variational PMF} \\ \mathbf{U}^{*}(\mathbf{X}^{N}) = \sum_{i} \phi_{i}^{*} U_{i}(\mathbf{X}^{N}) \\ \mathbf{U}^{*}(\mathbf{X}^{N}) = \sum_{i} \phi_{i}^{*} U_{i}(\mathbf{X}^{N}) \end{array}$$

#### CHALLENGES

#### MAPPING AND REPRESENTATIONS

![](_page_20_Figure_1.jpeg)

![](_page_20_Figure_2.jpeg)

#### structural modularity

(e.g., amino acids, nucleotides)

#### **dynamical proximity** (e.g., quasi-rigid domains)

#### DYNAMICAL PROXIMITY

![](_page_21_Figure_1.jpeg)

Banisch & Koltai (2017) Chaos 27, 035804

## COHERENT DOMAINS IN FIP35 KINETICS

**S3D** (Structural and State Space Decomposition) algorithm:

- 1. Kinetic model using Markov State Model analysis
- 2. Find state-specific coherent domains using SPTDMap

![](_page_22_Figure_4.jpeg)

- state dependent resolutions/decompositions
- interstate transitions as clusters' *splitting and merging*
- clusters' hierarchy

#### MINIMAL ASSEMBLY UNITS

![](_page_23_Figure_1.jpeg)

minimal assembly units as *Lego* logs

multi scale characterization

Boninsegna, Banisch, Clementi (2017) submitted

#### TOWARDS A RIGOROUS CG MAPPING

<image>

We know the 'beads', but actual mapping:  $\mathbf{M}: \mathbf{x}_i o \mathbf{X}_i$  still missing

Could use the same suggested in MS-CG?

Boninsegna, Banisch, Clementi (2017) submitted

#### **COARSE GRAINED DYNAMICS**

#### **COARSE GRAINED DYNAMICS**

![](_page_26_Figure_1.jpeg)

$$dx_t = -\nabla V(x)dt + \sqrt{2\beta^{-1}\sigma}dB_t \qquad \longrightarrow \qquad dz_t = -A'(z)dt + \sqrt{2\beta^{-1}\sigma_z}dB_t$$

Intuitively:

Degrees of freedom to be integrated out upon CG exert friction on those to be retained in the CG model

Of course compromise is needed, otherwise computational speedup due to degrees of f freedom decimation is lost

#### AN EXAMPLE: DYNAMICAL FORCE MATCHING

![](_page_27_Figure_1.jpeg)

Zwanzig, J. Stat. Phys. (1973) Davtyan et al., J. Chem. Pays. (2015)

#### SINDy algorithm

- · Collect all positions and 'velocities'
- Define a function database, i.e. space of polynomials

$$\Theta(\mathbf{X}) = \begin{bmatrix} \begin{vmatrix} & & & & \\ 1 & \mathbf{X} & \mathbf{X}_{2}^{P_{2}} & \mathbf{X}_{3}^{P_{3}} & \cdots & \sin(\mathbf{X}) & \cos(\mathbf{X}) & \cdots \end{bmatrix}.$$

- Linear combinations of these functions with appropriate coefficients are going to approximate the components of the dynamic constraints  $\int \frac{d}{dt} \mathbf{x}(t) = \mathbf{f}(\mathbf{x}(t))$
- Coefficients  $\Xi = [\xi_1 \ \xi_2 \ \cdots \ \xi_n]$  are found by solving the linear regression  $\dot{\mathbf{X}} = \Theta(\mathbf{X})\Xi$ .
- Coefficient sparsity is imposed on-the-fly, i.e. each entry is a sparse vector
- The machine-learned dynamics is then obtained by

$$\dot{\mathbf{x}}_k = \mathbf{f}_k(\mathbf{x}) = \Theta(\mathbf{x}^T)\boldsymbol{\xi}_k$$

<u>Q</u>: How do original and machine learned dynamics compare?

![](_page_29_Figure_1.jpeg)

Adapt this to high dimensional stochastic complex dynamics to coarse grain on-the-fly?

#### INCORPORATE EXPERIMENTAL DATA IN DESIGNING COARSE GRAINED MODELS

#### STRATEGY

![](_page_31_Figure_1.jpeg)

Pitera & Chodera, JCTC (**2012**) Boomsma, Plos. Comput. Biol. (**2014**)

#### GC Hamiltonian:

$$\mathcal{H}_{CG} = \mathcal{H}_{bond} + \sum_{contacts} K_c V_q(r_{ij}, r_0, \epsilon_q)$$

heterogeneous & non-native interactions

![](_page_32_Figure_3.jpeg)

#### ODEM MODELS

![](_page_33_Figure_1.jpeg)

Chen et al., (2017) submitted

![](_page_34_Picture_0.jpeg)

#### **OUTLOOK & PERSPECTIVES**

![](_page_34_Picture_2.jpeg)

CG is inevitable and a formidable problem

e.g. CG degree of freedom, Hamiltonian, FG consistency

- 'Ultimate CG' would combine exp and theory
- Optimality, approximation control
- Thought provoking:
  - State dependent CG beads
  - 'Parallel tempering' CG simulations with on-the fly adapted resolution

Noid *et al., J. Chem. Phys.* (**2008**) 128, 244114 Clementi, *Curr. Opin. Struct. Biol.* (**2008**),18,10

![](_page_35_Picture_0.jpeg)

# ipm

#### ACKNOWLEDGMENTS

#### Prof. Cecilia Clementi

Dr. Feliks Nüske Dr. Giovanni Pinamonti Alexander Kluber Justin Chen Eugen Hruska

Our collaborators:

Prof. Frank Noé Prof. Peter Koltai Dr. Ralf Banisch (Freie Universität Berlin) (Freie Universität Berlin) (Freie Universität Berlin)

![](_page_35_Picture_8.jpeg)

#### MULTISCALE CHALLENGE: PARADIGMATIC EXAMPLE

![](_page_39_Figure_1.jpeg)

acting subunit

actin filament

cytoskeleton network

complex interactions many degrees of freedom

![](_page_39_Picture_6.jpeg)

#### multi scale coupling

#### BIOMOLECULES: STRUCTURE, FUNCTION AND EQUILIBRIUM

![](_page_40_Figure_1.jpeg)

BUT landscape is metastable, complex, frustrated

![](_page_41_Picture_0.jpeg)

#### SAMPLE ATOMISTIC HAMILTONIAN

![](_page_42_Figure_1.jpeg)

$$\begin{split} H &= \sum_{bonds} K_d (d_i - d_0)^2 + \sum_{angles} K_\theta (\theta_i - \theta_0)^2 \\ &+ \sum_{Dihedrals} K_\phi(n) [1 + \cos(n(\phi_i - \phi_0))] \\ &+ \sum K'_\phi (\phi'_i - \phi'_0)^2 \end{split}$$

I-Dihedrals

![](_page_42_Figure_4.jpeg)

![](_page_42_Figure_5.jpeg)

![](_page_42_Figure_6.jpeg)

non bonded terms

![](_page_42_Figure_8.jpeg)

(courtesy of Cecilia Clementi)

#### MODULARITY

![](_page_43_Figure_1.jpeg)

**NUCLEID ACIDS** 

![](_page_43_Figure_3.jpeg)

## PRINCIPLE OF MAXIMUM ENTROPY

Link between Shannon's information theory and stat. mech.

Q: what is the probability distribution which best represents the state of knowledge after observing a set of quantity?

![](_page_44_Picture_3.jpeg)

entropy

observations (constraints)

$$S(p) = -\sum_{i}^{n} p(x_i) \ln p(x_i) \qquad \qquad \sum_{k} p(x_k) = 1 \qquad \sum_{k} p(x_k) f(x_k) = F_k$$

Solve constrained optimization to get:

$$p(x_k) = \frac{1}{Z} e^{-\sum_j \lambda_j f_j(x_k)} \qquad \qquad Z = \sum_k e^{-\sum_j \lambda_j f_j(x_k)}$$

Enforcing averages on MD distribution is equivalent to introducing a biasing potential

$$p(x) = \frac{1}{Z} e^{-\beta U(x) - \sum_{k} \lambda_{k} f_{k}(x)}$$
 observable

![](_page_44_Picture_11.jpeg)

![](_page_44_Picture_12.jpeg)

#### OBSERVABLE-driven DESIGN OF EFFECTIVE MOLECULAR MODELS (ODEM)

- Experimental measurements :  $(f_1, ..., f_K)$  uncertainties  $(\Delta f_1, ..., \Delta f_K)$
- Start from an initial guess for the parameters,  $\epsilon^{(0)}$  (0<sup>th</sup> order model) Run MD with  $H^{(0)}(\mathbf{x})$
- Estimate maximum likelihood equilibrium distribution  $\pi^{(0)}(\mathbf{x})$  from MSM
- Compute value of observable  $f_k$  from MSM as:

$$e_k[\boldsymbol{\pi}] = \sum_i \frac{\pi_i}{n_i} \sum_{j \in S_i} g_k(\mathbf{x}_{ij})$$

• Measure "goodness" Q of the model:

$$Q = \mathbb{P}\left[\left(e_1[\boldsymbol{\pi}], ..., e_K[\boldsymbol{\pi}]\right) \mid \text{Exp}\right] = \prod_k \mathcal{N}(e_k[\boldsymbol{\pi}]; f_k, \Delta f_k)$$

• Upon infinitesimal parameter change  $\epsilon^{(1)} = \epsilon^{(0)} + \delta \epsilon$  equilibrium distribution change is:

$$\pi_i^{(1)} = \frac{\pi_i^{(0)}}{n_i} \sum_{x \in S_i} \exp\left[-\beta(H^{(0)}(\mathbf{x}) - H^{(1)}(\mathbf{x}))\right]$$

- Compute expression of  $Q^{(1)}$  as a function of  $\epsilon^{(1)}$
- Pick  $\epsilon^{(1)}$  to maximize  $Q^{(1)}$