On the Non-isothermal Electrodiffusion and Nernst-Planck-Boussinesq System

Quyuan Lin

School of Mathematical and Statistical Sciences Clemson University

IPAM: Embracing Stochasticity in Electrochemical Modeling

September 16, 2025

Outline

- Review of Nernst-Planck-Navier-Stokes system
- Introduction of Nernst-Planck-Boussinesq system
- Global existence of weak solutions in 3D
- Long-time dynamics and convergence to the steady state

Introduction Electrodiffusion

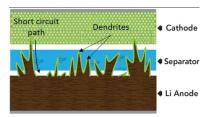
- Electrodiffusion is a phenomenon describing the diffusion of ions under the influence of an electric field induced by ion charges themselves.
- It has various real-world applications in neuroscience, semiconductor theory, water purification, desalination, ion separation, etc.
- Suppressing dendrite growth will significantly improve the performance of batteries. Electrodiffusion near the dendrite nucleation site can change the local mass transport and ultimately affect dendrite growth (Tan-Ryan, 2016).

Introduction Electrodiffusion

- Electrodiffusion is a phenomenon describing the diffusion of ions under the influence of an electric field induced by ion charges themselves.
- It has various real-world applications in neuroscience, semiconductor theory, water purification, desalination, ion separation, etc.
- Suppressing dendrite growth will significantly improve the performance of batteries. Electrodiffusion near the dendrite nucleation site can change the local mass transport and ultimately affect dendrite growth (Tan-Ryan, 2016).

Introduction Electrodiffusion

- Electrodiffusion is a phenomenon describing the diffusion of ions under the influence of an electric field induced by ion charges themselves.
- It has various real-world applications in neuroscience, semiconductor theory, water purification, desalination, ion separation, etc.
- Suppressing dendrite growth will significantly improve the performance of batteries.
 Electrodiffusion near the dendrite nucleation site can change the local mass transport and ultimately affect dendrite growth (Tan-Ryan, 2016).



$$egin{aligned} \partial_t c_i +
abla \cdot j_i &= 0, \quad j_i = u c_i - D_i
abla c_i - D_i rac{e z_i}{k_B T} c_i
abla \Psi, \quad i = 1, \dots, N, \\ - \varepsilon \Delta \Psi &= e N_A \sum_{i=1}^N z_i c_i &= F \sum_{i=1}^N z_i c_i =:
ho. \end{aligned}$$

- c_i : non-negative functions, i-th ionic species concentrations.
- j_i : the flux, three components: advection, diffusion, and electromigration.
- Ψ : electric potential, ρ : charge density, u: the velocity field, T: absolute temperature.
- $D_i > 0$ (constant): diffusivities, $z_i \in \mathbb{R}$ (constant): valences, k_B : Boltzmann constant, e: elementary charge, e: the dielectric permittivity of the solvent, N_A : Avogadro constant, $F = eN_A$: Faraday constant.
- The electromigration term $-D_i \frac{ez_i}{k_B T} c_i \nabla \Psi = -D_i \frac{Fz_i}{RT} c_i \nabla \Psi$ where $R = k_B N_A$ is the molar gas constant.
- In the mathematical literature, the temperature T is usually assumed to be a constant in space and time.

$$egin{aligned} \partial_t c_i +
abla \cdot j_i &= 0, \quad j_i = u c_i - D_i
abla c_i - D_i rac{e z_i}{k_B T} c_i
abla \Psi, \quad i = 1, \dots, N, \\ - \varepsilon \Delta \Psi &= e N_A \sum_{i=1}^N z_i c_i &= F \sum_{i=1}^N z_i c_i =:
ho. \end{aligned}$$

- c_i : non-negative functions, i-th ionic species concentrations.
- j_i : the flux, three components: advection, diffusion, and electromigration.
- Ψ : electric potential, ρ : charge density, u: the velocity field, T: absolute temperature.
- $D_i > 0$ (constant): diffusivities, $z_i \in \mathbb{R}$ (constant): valences, k_B : Boltzmann constant, e: elementary charge, e: the dielectric permittivity of the solvent, N_A : Avogadro constant, $F = eN_A$: Faraday constant.
- The electromigration term $-D_i \frac{ez_i}{k_B T} c_i \nabla \Psi = -D_i \frac{Fz_i}{RT} c_i \nabla \Psi$ where $R = k_B N_A$ is the molar gas constant.
- In the mathematical literature, the temperature T is usually assumed to be a constant in space and time.

$$\begin{split} \partial_t c_i + \nabla \cdot j_i &= 0, \quad j_i = u c_i - D_i \nabla c_i - D_i \frac{e z_i}{k_B T} c_i \nabla \Psi, \quad i = 1, \dots, N, \\ - \varepsilon \Delta \Psi &= e N_A \sum_{i=1}^N z_i c_i = F \sum_{i=1}^N z_i c_i =: \rho. \end{split}$$

- c_i : non-negative functions, i-th ionic species concentrations.
- j_i : the flux, three components: advection, diffusion, and electromigration.
- Ψ : electric potential, ρ : charge density, u: the velocity field, T: absolute temperature.
- $D_i > 0$ (constant): diffusivities, $z_i \in \mathbb{R}$ (constant): valences, k_B : Boltzmann constant, e: elementary charge, ε : the dielectric permittivity of the solvent, N_A : Avogadro constant, $F = eN_A$: Faraday constant.
- The electromigration term $-D_i \frac{ez_i}{k_B T} c_i \nabla \Psi = -D_i \frac{Fz_i}{RT} c_i \nabla \Psi$ where $R = k_B N_A$ is the molar gas constant.
- In the mathematical literature, the temperature T is usually assumed to be a constant in space and time.

$$\begin{split} \partial_t c_i + \nabla \cdot j_i &= 0, \quad j_i = u c_i - D_i \nabla c_i - D_i \frac{e z_i}{k_B T} c_i \nabla \Psi, \quad i = 1, \dots, N, \\ - \varepsilon \Delta \Psi &= e N_A \sum_{i=1}^N z_i c_i = F \sum_{i=1}^N z_i c_i =: \rho. \end{split}$$

- c_i : non-negative functions, i-th ionic species concentrations.
- j_i : the flux, three components: advection, diffusion, and electromigration.
- Ψ : electric potential, ρ : charge density, u: the velocity field, T: absolute temperature.
- $D_i > 0$ (constant): diffusivities, $z_i \in \mathbb{R}$ (constant): valences, k_B : Boltzmann constant, e: elementary charge, ε : the dielectric permittivity of the solvent, N_A : Avogadro constant, $F = eN_A$: Faraday constant.
- The electromigration term $-D_i \frac{ez_i}{k_B T} c_i \nabla \Psi = -D_i \frac{Fz_i}{RT} c_i \nabla \Psi$ where $R = k_B N_A$ is the molar gas constant.
- In the mathematical literature, the temperature T is usually assumed to be a constant in space and time.

$$egin{aligned} \partial_t c_i +
abla \cdot j_i &= 0, \quad j_i = u c_i - D_i
abla c_i - D_i rac{e z_i}{k_B T} c_i
abla \Psi, \quad i = 1, \dots, N, \\ - \varepsilon \Delta \Psi &= e N_A \sum_{i=1}^N z_i c_i &= F \sum_{i=1}^N z_i c_i =:
ho. \end{aligned}$$

- c_i : non-negative functions, i-th ionic species concentrations.
- j_i : the flux, three components: advection, diffusion, and electromigration.
- Ψ : electric potential, ρ : charge density, u: the velocity field, T: absolute temperature.
- $D_i > 0$ (constant): diffusivities, $z_i \in \mathbb{R}$ (constant): valences, k_B : Boltzmann constant, e: elementary charge, ε : the dielectric permittivity of the solvent, N_A : Avogadro constant, $F = eN_A$: Faraday constant.
- The electromigration term $-D_i \frac{ez_i}{k_B T} c_i \nabla \Psi = -D_i \frac{Fz_i}{RT} c_i \nabla \Psi$ where $R = k_B N_A$ is the molar gas constant.
- In the mathematical literature, the temperature T is usually assumed to be a constant in space and time.

When coupled to the incompressible homogeneous Navier-Stokes equations:

$$\partial_t u + u \cdot \nabla u - \nu \Delta u + \nabla p = -\rho \nabla \Psi,$$

 $\nabla \cdot u = 0.$

the system is called the Nernst-Planck-Navier-Stokes (NPNS) system.

- The NPNS system is typically studied in an open smooth bounded domain $\mathcal{D} \subseteq \mathbb{R}^d$ or in torus \mathbb{T}^d with d=2,3.
- For bounded domain case, the boundary conditions: $u|_{\partial \mathcal{D}}=0$ and $\Psi|_{\partial \mathcal{D}}=V(x)$, imposed voltage.
- For c_i , there are primarily three types of boundary conditions:
 - **3** Blocking boundary condition: $(j_i \cdot \hat{n})|_{\partial \mathcal{D}} = 0$ for i = 1, ..., N. Boundaries function as impermeable barriers, preventing ions from crossing them.
 - ② Dirichlet: $c_i|_{\partial \mathcal{D}} = \gamma_i(x)$ for i = 1, ..., N with $\gamma_i(x)$ being nonnegative functions. Ion-selective (or perm-selective) membranes that uphold a fixed ion concentration.
 - Selective boundary condition: a mixed type of the previous two

When coupled to the incompressible homogeneous Navier-Stokes equations:

$$\partial_t u + u \cdot \nabla u - \nu \Delta u + \nabla p = -\rho \nabla \Psi,$$

 $\nabla \cdot u = 0.$

the system is called the Nernst-Planck-Navier-Stokes (NPNS) system.

- The NPNS system is typically studied in an open smooth bounded domain $\mathcal{D} \subseteq \mathbb{R}^d$ or in torus \mathbb{T}^d with d=2,3.
- For bounded domain case, the boundary conditions: $u|_{\partial \mathcal{D}} = 0$ and $\Psi|_{\partial \mathcal{D}} = V(x)$, imposed voltage.
- For c_i , there are primarily three types of boundary conditions:
 - **3** Blocking boundary condition: $(j_i \cdot \hat{n})|_{\partial \mathcal{D}} = 0$ for i = 1, ..., N. Boundaries function as impermeable barriers, preventing ions from crossing them.
 - ② Dirichlet: $c_i|_{\partial \mathcal{D}} = \gamma_i(x)$ for $i=1,\ldots,N$ with $\gamma_i(x)$ being nonnegative functions. Ion-selective (or perm-selective) membranes that uphold a fixed ion concentration
 - Selective boundary condition: a mixed type of the previous two

When coupled to the incompressible homogeneous Navier-Stokes equations:

$$\partial_t u + u \cdot \nabla u - \nu \Delta u + \nabla p = -\rho \nabla \Psi,$$

$$\nabla \cdot u = 0.$$

the system is called the Nernst-Planck-Navier-Stokes (NPNS) system.

- The NPNS system is typically studied in an open smooth bounded domain $\mathcal{D} \subseteq \mathbb{R}^d$ or in torus \mathbb{T}^d with d=2,3.
- For bounded domain case, the boundary conditions: $u|_{\partial \mathcal{D}} = 0$ and $\Psi|_{\partial \mathcal{D}} = V(x)$, imposed voltage.
- For c_i , there are primarily three types of boundary conditions:
 - **3** Blocking boundary condition: $(j_i \cdot \hat{n})|_{\partial \mathcal{D}} = 0$ for $i = 1, \dots, N$. Boundaries function as impermeable barriers, preventing ions from crossing them.
 - ② Dirichlet: $c_i|_{\partial \mathcal{D}} = \gamma_i(x)$ for $i = 1, \dots, N$ with $\gamma_i(x)$ being nonnegative functions. Ion-selective (or perm-selective) membranes that uphold a fixed ion concentration.
 - Selective boundary condition: a mixed type of the previous two.

Introduction

Mathematical problems

Under different boundary conditions and different ionic settings: number of species; relation of z_i ; relation of D_i ,

- Local/Global in time existence of weak/strong solutions;
- Uniqueness, continuous dependence on the initial data (well-posedness);
- Long time dynamics;
- Stability of steady states (Boltzmann states);
- Justification of interior electroneutrality.
-

Introduction

- Existence of global weak solutions in 3D: Jerome–Sacco (2009), Ryham (2009), Schmuck (2009), Fischer–Saal (2017).
- Global existence and uniqueness of 2D solution in smooth bounded domain as well as the convergence to steady state: Constantin-Ignatova (2018).
- The nonlinear stability of Boltzmann states in 3D: Constantin-Ignatova-Lee (2022).
- Interior electroneutrality: Constantin-Ignatova-Lee (2021).
- With periodic boundary conditions, the long-time dynamics: Abdo-Ignatova (2021, 2024) and the analyticity of solutions: Abdo-Ignatova (2022).
- Some other electrodiffusion models, including Nernst-Planck-Euler: Zhang-Yin (2015, 2020), Ignatova-Shu (2021), Shen-Wang (2022), Abdo-Lee-Wang (2022) and Nernst-Planck-Darcy: Ignatova-Shu (2022), Abdo-Lee-Wang (2022).

- Main challenge: the electromigration term $\nabla \cdot (D_i \frac{ez_i}{k_B T} c_i \nabla \Psi)$.
- A direct L^2 estimate leads to $D_i \frac{ez_i}{k_B T} \int_{\mathcal{D}} c_i \nabla \Psi \nabla c_i$, which results in $\|c_i\|_{L^2}^k$ where the exponent k > 2 depends on the dimension. This only allows a local solution.
- Special case: N=2, $D_1=D_2=D$, $z_1=-z_2=z>0$. Introduce $\sigma=Fz(c_1+c_2)$ and noticing that $\rho=Fz(c_1-c_2)$, then (T is assumed to be constant):

$$\begin{split} \partial_t \sigma + u \cdot \nabla \sigma - D \Delta \sigma - \frac{Dez}{k_B T} \nabla \cdot (\rho \nabla \Psi) &= 0, \\ \partial_t \rho + u \cdot \nabla \rho - D \Delta \rho - \frac{Dez}{k_B T} \nabla \cdot (\sigma \nabla \Psi) &= 0. \end{split}$$

The L^2 estimates lead to

$$\int_{\mathcal{D}} \frac{1}{T} \Big(\nabla \cdot (\sigma \nabla \Psi) \rho + \nabla \cdot (\rho \nabla \Psi) \sigma \Big) dx = -\int_{\mathcal{D}} \frac{1}{\varepsilon T} \rho^2 \sigma dx \leq 0,$$

which becomes a dissipation term

- Main challenge: the electromigration term $\nabla \cdot (D_i \frac{ez_i}{k_B T} c_i \nabla \Psi)$.
- A direct L^2 estimate leads to $D_i \frac{ez_i}{k_B T} \int_{\mathcal{D}} c_i \nabla \Psi \nabla c_i$, which results in $\|c_i\|_{L^2}^k$ where the exponent k > 2 depends on the dimension. This only allows a local solution.
- Special case: N=2, $D_1=D_2=D$, $z_1=-z_2=z>0$. Introduce $\sigma=Fz(c_1+c_2)$ and noticing that $\rho=Fz(c_1-c_2)$, then (T is assumed to be constant):

$$\begin{split} &\partial_t \sigma + u \cdot \nabla \sigma - D \Delta \sigma - \frac{Dez}{k_B T} \nabla \cdot \left(\rho \nabla \Psi \right) = 0, \\ &\partial_t \rho + u \cdot \nabla \rho - D \Delta \rho - \frac{Dez}{k_B T} \nabla \cdot \left(\sigma \nabla \Psi \right) = 0. \end{split}$$

The L^2 estimates lead to

$$\int_{\mathcal{D}} \frac{1}{T} \Big(\nabla \cdot (\sigma \nabla \Psi) \rho + \nabla \cdot (\rho \nabla \Psi) \sigma \Big) dx = -\int_{\mathcal{D}} \frac{1}{\varepsilon T} \rho^2 \sigma dx \leq 0,$$

which becomes a dissipation term.

 In the general setting for ionic concentrations, study the relative entropy (Kullback-Leibler divergence)

$$\int \sum_{i=1}^{N} c_i \log \left(\frac{c_i}{c_i^*}\right) dx,$$

which can provide some good dissipations.

Boltzmann steady states:

$$c_i^*(x) = Z_i^{-1} \exp\left(-\frac{z_i e}{k_B T} \Psi^*(x)\right),$$

$$-\varepsilon \Delta \Psi^* = \rho^* = e N_A \sum_{i=1}^N z_i c_i^*, \ \Psi^*|_{\partial \mathcal{D}} = V(x),$$

where $Z_i > 0$ are constants that can depend on Ψ^* .

 In the general setting for ionic concentrations, study the relative entropy (Kullback-Leibler divergence)

$$\int \sum_{i=1}^{N} c_i \log \left(\frac{c_i}{c_i^*}\right) dx,$$

which can provide some good dissipations.

Boltzmann steady states:

$$\begin{split} c_i^*(x) &= Z_i^{-1} \exp(-\frac{z_i e}{k_B T} \Psi^*(x)), \\ &- \varepsilon \Delta \Psi^* = \rho^* = e N_A \sum_{i=1}^N z_i c_i^*, \ \Psi^*|_{\partial \mathcal{D}} = V(x), \end{split}$$

where $Z_i > 0$ are constants that can depend on Ψ^* .

Introduction

- Limitation of existing electrodiffusion models:
 - ① The exclusion of temperature variations, which simplifies the nonlinear structure of the model (in particular, the electromigration term $\nabla \cdot (\frac{z_i}{t} c_i \nabla \Psi)$).
 - The salinity resulting from the variation of the ionic concentrations creates a buoyancy force, which has been disregarded.
- The magnitude of temperature variations and salinity might be small, but their regularity can play an important role.
- Consider Boussinesq approximation (ignores density differences except where they appear in buoyancy) for u and T:

$$\partial_t u + u \cdot \nabla u - \nu \Delta u + \nabla p = -g \beta \vec{k} - \rho \nabla \Psi, \tag{1a}$$

$$\nabla \cdot u = 0, \tag{1b}$$

$$\beta = 1 - \alpha_T (T - T_r) + \alpha_S (S - S_r), \tag{1c}$$

$$\partial_t T + u \cdot \nabla T - \kappa \Delta T = 0, \tag{1c}$$

$$S = \sum_{i=1}^{N} c_i M_i. \tag{1e}$$

• S the salinity, β the density, T_r , S_r are the reference values of T, S. M_i is the Molar mass of the i-th ionic species.

Introduction

- Limitation of existing electrodiffusion models:
 - ① The exclusion of temperature variations, which simplifies the nonlinear structure of the model (in particular, the electromigration term $\nabla \cdot (\frac{z_i}{t} c_i \nabla \Psi)$).
 - The salinity resulting from the variation of the ionic concentrations creates a buoyancy force, which has been disregarded.
- The magnitude of temperature variations and salinity might be small, but their regularity can play an important role.
- Consider Boussinesq approximation (ignores density differences except where they appear in buoyancy) for u and T:

$$\partial_t u + u \cdot \nabla u - \nu \Delta u + \nabla p = -g \beta \vec{k} - \rho \nabla \Psi, \tag{1a}$$

$$\nabla \cdot u = 0, \tag{1b}$$

$$\beta = 1 - \alpha_T (T - T_r) + \alpha_S (S - S_r), \tag{1c}$$

$$\partial_t T + u \cdot \nabla T - \kappa \Delta T = 0, \tag{1d}$$

$$S = \sum_{i=1}^{N} c_i M_i. \tag{1e}$$

• S the salinity, β the density, T_r , S_r are the reference values of T, S. M_i is the Molar mass of the i-th ionic species.

Introduction

- Limitation of existing electrodiffusion models:
 - ① The exclusion of temperature variations, which simplifies the nonlinear structure of the model (in particular, the electromigration term $\nabla \cdot (\frac{z_i}{t} c_i \nabla \Psi)$).
 - The salinity resulting from the variation of the ionic concentrations creates a buoyancy force, which has been disregarded.
- The magnitude of temperature variations and salinity might be small, but their regularity can play an important role.
- Consider Boussinesq approximation (ignores density differences except where they appear in buoyancy) for u and T:

$$\partial_t u + u \cdot \nabla u - \nu \Delta u + \nabla p = -g \beta \vec{k} - \rho \nabla \Psi, \tag{1a}$$

$$\nabla \cdot u = 0, \tag{1b}$$

$$\beta = 1 - \alpha_T (T - T_r) + \alpha_S (S - S_r), \tag{1c}$$

$$\partial_t T + u \cdot \nabla T - \kappa \Delta T = 0, \tag{1d}$$

$$S = \sum_{i=1}^{N} c_i M_i. \tag{1e}$$

• S the salinity, β the density, T_r , S_r are the reference values of T, S. M_i is the Molar mass of the i-th ionic species.

$$\partial_t c_i + u \cdot \nabla c_i - D_i \Delta c_i - D_i \frac{e z_i}{k_R} \nabla \cdot (\frac{1}{T} c_i \nabla \Psi) = 0, \tag{2a}$$

$$-\varepsilon\Delta\Psi = \rho = \sum_{i=1}^{N} eN_{A}z_{i}c_{i}, \tag{2b}$$

$$\partial_t u + u \cdot \nabla u - \nu \Delta u + \nabla p = g \left(\alpha_T (T - T_r) - \alpha_S \left(\sum_{i=1}^N c_i M_i - S_r \right) \right) \vec{k} - \rho \nabla \Psi, \quad (2c)$$

$$\nabla \cdot u = 0, \tag{2d}$$

$$\partial_t T + u \cdot \nabla T - \kappa \Delta T = 0. \tag{2e}$$

- When $T \equiv T_r$ and $\alpha_S = 0$ in the NPB system, one can recover the NPNS system. NPNS system is a special case of NPB system.
- On a torus \mathbb{T}^3 , T_r and S_r are the spatial average, and they are invariant in time.
- An important property of c_i : when $c_i(0) \ge 0$ and the solution is regular enough, then $c_i(t) \ge 0$ remain non-negative.

$$\partial_t c_i + u \cdot \nabla c_i - D_i \Delta c_i - D_i \frac{e z_i}{k_B} \nabla \cdot (\frac{1}{T} c_i \nabla \Psi) = 0, \tag{2a}$$

$$-\varepsilon\Delta\Psi = \rho = \sum_{i=1}^{N} eN_{A}z_{i}c_{i}, \tag{2b}$$

$$\partial_t u + u \cdot \nabla u - \nu \Delta u + \nabla p = g \left(\alpha_T (T - T_r) - \alpha_S \left(\sum_{i=1}^N c_i M_i - S_r \right) \right) \vec{k} - \rho \nabla \Psi, \quad (2c)$$

$$\nabla \cdot u = 0, \tag{2d}$$

$$\partial_t T + u \cdot \nabla T - \kappa \Delta T = 0. \tag{2e}$$

- When $T \equiv T_r$ and $\alpha_S = 0$ in the NPB system, one can recover the NPNS system. NPNS system is a special case of NPB system.
- On a torus \mathbb{T}^3 , T_r and S_r are the spatial average, and they are invariant in time.
- An important property of c_i : when $c_i(0) \ge 0$ and the solution is regular enough, then $c_i(t) \ge 0$ remain non-negative.

$$\partial_t c_i + u \cdot \nabla c_i - D_i \Delta c_i - D_i \frac{e z_i}{k_B} \nabla \cdot (\frac{1}{T} c_i \nabla \Psi) = 0, \tag{2a}$$

$$-\varepsilon\Delta\Psi = \rho = \sum_{i=1}^{N} eN_{A}z_{i}c_{i}, \tag{2b}$$

$$\partial_t u + u \cdot \nabla u - \nu \Delta u + \nabla p = g \left(\alpha_T (T - T_r) - \alpha_S \left(\sum_{i=1}^N c_i M_i - S_r \right) \right) \vec{k} - \rho \nabla \Psi, \quad (2c)$$

$$\nabla \cdot u = 0, \tag{2d}$$

$$\partial_t T + u \cdot \nabla T - \kappa \Delta T = 0. \tag{2e}$$

- When $T \equiv T_r$ and $\alpha_S = 0$ in the NPB system, one can recover the NPNS system. NPNS system is a special case of NPB system.
- On a torus \mathbb{T}^3 , T_r and S_r are the spatial average, and they are invariant in time.
- An important property of c_i : when $c_i(0) \ge 0$ and the solution is regular enough, then $c_i(t) \ge 0$ remain non-negative.

$$\partial_t c_i + u \cdot \nabla c_i - D_i \Delta c_i - D_i \frac{e z_i}{k_B} \nabla \cdot (\frac{1}{T} c_i \nabla \Psi) = 0, \tag{2a}$$

$$-\varepsilon\Delta\Psi = \rho = \sum_{i=1}^{N} eN_{A}z_{i}c_{i}, \tag{2b}$$

$$\partial_t u + u \cdot \nabla u - \nu \Delta u + \nabla p = g \left(\alpha_T (T - T_r) - \alpha_S \left(\sum_{i=1}^N c_i M_i - S_r \right) \right) \vec{k} - \rho \nabla \Psi, \quad (2c)$$

$$\nabla \cdot u = 0, \tag{2d}$$

$$\partial_t T + u \cdot \nabla T - \kappa \Delta T = 0. \tag{2e}$$

- When $T \equiv T_r$ and $\alpha_S = 0$ in the NPB system, one can recover the NPNS system. NPNS system is a special case of NPB system.
- On a torus \mathbb{T}^3 , T_r and S_r are the spatial average, and they are invariant in time.
- An important property of c_i : when $c_i(0) \ge 0$ and the solution is regular enough, then $c_i(t) \ge 0$ remain non-negative.

- Goal: Global existence of (weak) solutions: need global in time estimates.
- The appearance of T in the denominator: assume $T_0(x) \geq T^* > 0$ for all $x \in \mathcal{D}$ according to the Third Law of Thermodynamics. By maximum principle, $T(x,t) \geq T^* > 0$.
- All challenges in the NPNS system remain in the NPB system, but things can be worse! For example, in the case of N = 2, $D_1 = D_2 = D$, $z_1 = -z_2 = z$ case,

$$\int_{\mathcal{D}} \frac{1}{T} \Big(\nabla \cdot (\sigma \nabla \Psi) \rho + \nabla \cdot (\rho \nabla \Psi) \sigma \Big) dx = -\int_{\mathcal{D}} \frac{1}{\varepsilon T} \rho^2 \sigma dx + \int_{\mathcal{D}} \frac{\rho \sigma}{T^2} \nabla T \cdot \nabla \Psi dx.$$

- The dissipation structure in many NPNS works is no longer valid because the temperature is no longer a constant. Integration by parts will introduce some bad terms involving with T as well as its derivatives.
- The presence of salinity $S = \sum c_i M_i$ (through buoyancy force) in the momentum equation requires some control of c_i .

- Goal: Global existence of (weak) solutions: need global in time estimates.
- The appearance of T in the denominator: assume $T_0(x) \ge T^* > 0$ for all $x \in \mathcal{D}$ according to the Third Law of Thermodynamics. By maximum principle, $T(x,t) \ge T^* > 0$.
- All challenges in the NPNS system remain in the NPB system, but things can be worse! For example, in the case of N = 2, $D_1 = D_2 = D$, $z_1 = -z_2 = z$ case,

$$\int_{\mathcal{D}} \frac{1}{T} \Big(\nabla \cdot (\sigma \nabla \Psi) \rho + \nabla \cdot (\rho \nabla \Psi) \sigma \Big) dx = -\int_{\mathcal{D}} \frac{1}{\varepsilon T} \rho^2 \sigma dx + \int_{\mathcal{D}} \frac{\rho \sigma}{T^2} \nabla T \cdot \nabla \Psi dx.$$

- The dissipation structure in many NPNS works is no longer valid because the temperature is no longer a constant. Integration by parts will introduce some bad terms involving with T as well as its derivatives.
- The presence of salinity $S = \sum c_i M_i$ (through buoyancy force) in the momentum equation requires some control of c_i .

- Goal: Global existence of (weak) solutions: need global in time estimates.
- The appearance of T in the denominator: assume $T_0(x) \ge T^* > 0$ for all $x \in \mathcal{D}$ according to the Third Law of Thermodynamics. By maximum principle, $T(x,t) \ge T^* > 0$.
- All challenges in the NPNS system remain in the NPB system, but things can be worse! For example, in the case of N = 2, $D_1 = D_2 = D$, $z_1 = -z_2 = z$ case,

$$\int_{\mathcal{D}} \frac{1}{T} \Big(\nabla \cdot (\sigma \nabla \Psi) \rho + \nabla \cdot (\rho \nabla \Psi) \sigma \Big) dx = -\int_{\mathcal{D}} \frac{1}{\varepsilon T} \rho^2 \sigma dx + \int_{\mathcal{D}} \frac{\rho \sigma}{T^2} \nabla T \cdot \nabla \Psi dx.$$

- The dissipation structure in many NPNS works is no longer valid because the temperature is no longer a constant. Integration by parts will introduce some bac terms involving with T as well as its derivatives.
- The presence of salinity $S = \sum c_i M_i$ (through buoyancy force) in the momentum equation requires some control of c_i .

- Goal: Global existence of (weak) solutions: need global in time estimates.
- The appearance of T in the denominator: assume $T_0(x) \ge T^* > 0$ for all $x \in \mathcal{D}$ according to the Third Law of Thermodynamics. By maximum principle, $T(x,t) \ge T^* > 0$.
- All challenges in the NPNS system remain in the NPB system, but things can be worse! For example, in the case of N = 2, $D_1 = D_2 = D$, $z_1 = -z_2 = z$ case,

$$\int_{\mathcal{D}} \frac{1}{T} \Big(\nabla \cdot (\sigma \nabla \Psi) \rho + \nabla \cdot (\rho \nabla \Psi) \sigma \Big) dx = -\int_{\mathcal{D}} \frac{1}{\varepsilon T} \rho^2 \sigma dx + \int_{\mathcal{D}} \frac{\rho \sigma}{T^2} \nabla T \cdot \nabla \Psi dx.$$

- The dissipation structure in many NPNS works is no longer valid because the temperature is no longer a constant. Integration by parts will introduce some bad terms involving with T as well as its derivatives.
- The presence of salinity $S = \sum c_i M_i$ (through buoyancy force) in the momentum equation requires some control of c_i .

• The estimate of relative entropy $E(t):=\sum_{i=1}^N\int_{\mathbb{T}^3}c_i(t)\log\frac{c_i(t)}{\bar{c}_i}dx$:

$$\frac{d}{dt}E + \underbrace{\sum_{i=1}^{N} D_{i} \left\| \frac{1}{\sqrt{c_{i}}} \left(\nabla c_{i} + \frac{ez_{i}c_{i}\nabla\Psi}{k_{B}T} \right) \right\|_{L^{2}}^{2}}_{:=D_{A}} = \underbrace{\sum_{i=1}^{N} D_{i} \int_{\mathbb{T}^{3}} \left(\nabla c_{i} + \frac{ez_{i}}{k_{B}T} c_{i}\nabla\Psi \right) \cdot \left(\frac{ez_{i}}{k_{B}T} \nabla\Psi \right) dx}_{:=\mathcal{N}}, (3)$$

• Consider $D_1 = \cdots = D_N = D$. In this case the evolution of ρ is:

$$\partial_t \rho + u \cdot \nabla \rho - D \Delta \rho = D N_A \frac{e^2}{k_B} \sum_{i=1}^N \nabla \cdot \left(z_i^2 c_i \frac{1}{T} \nabla \Psi \right)$$

$$\frac{\varepsilon}{2} \frac{d}{dt} \|\nabla \Psi\|_{L^2}^2 + \frac{D}{\varepsilon} \|\rho\|_{L^2}^2 + \underbrace{\sum_{i=1}^N DN_A \frac{e^2}{k_B} \int_{\mathbb{T}^3} z_i^2 c_i \frac{1}{T} |\nabla \Psi|^2 dx}_{:=D_B} = \int_{\mathbb{T}^3} u \cdot \nabla \Psi \rho dx$$

- Dissipations D_A and D_B together can control $\mathcal N$
- Here the diffusion terms $-\sum_{i=1}^{N} DeN_{A}z_{i}\Delta c_{i}$ boil down to $-D\Delta\rho$, which is not true when D_{i} are different. And when D_{i} are different, the corresponding D_{B} term is not good enough to control N.

• The estimate of relative entropy $E(t) := \sum_{i=1}^N \int_{\mathbb{T}^3} c_i(t) \log \frac{c_i(t)}{\bar{c}_i} dx$:

$$\frac{d}{dt}E + \underbrace{\sum_{i=1}^{N} D_{i} \left\| \frac{1}{\sqrt{c_{i}}} \left(\nabla c_{i} + \frac{ez_{i}c_{i}\nabla\Psi}{k_{B}T} \right) \right\|_{L^{2}}^{2}}_{:=D_{A}} = \underbrace{\sum_{i=1}^{N} D_{i} \int_{\mathbb{T}^{3}} \left(\nabla c_{i} + \frac{ez_{i}}{k_{B}T} c_{i}\nabla\Psi \right) \cdot \left(\frac{ez_{i}}{k_{B}T} \nabla\Psi \right) dx}_{:=\mathcal{N}}, (3)$$

• Consider $D_1 = \cdots = D_N = D$. In this case the evolution of ρ is:

$$\partial_t \rho + u \cdot \nabla \rho - D \Delta \rho = D N_A \frac{e^2}{k_B} \sum_{i=1}^N \nabla \cdot \left(z_i^2 c_i \frac{1}{T} \nabla \Psi \right).$$

$$\frac{\varepsilon}{2} \frac{d}{dt} \|\nabla \Psi\|_{L^2}^2 + \frac{D}{\varepsilon} \|\rho\|_{L^2}^2 + \sum_{i=1}^N DN_A \frac{e^2}{k_B} \int_{\mathbb{T}^3} z_i^2 c_i \frac{1}{T} |\nabla \Psi|^2 dx = \int_{\mathbb{T}^3} u \cdot \nabla \Psi \rho dx.$$

- Dissipations D_A and D_B together can control $\mathcal N$
- Here the diffusion terms $-\sum_{i=1}^{N} DeN_{A}z_{i}\Delta c_{i}$ boil down to $-D\Delta\rho$, which is not true when D_{i} are different. And when D_{i} are different, the corresponding D_{B} term is not good enough to control N.

• The estimate of relative entropy $E(t) := \sum_{i=1}^N \int_{\mathbb{T}^3} c_i(t) \log \frac{c_i(t)}{\bar{c}_i} dx$:

$$\frac{d}{dt}E + \underbrace{\sum_{i=1}^{N} D_{i} \left\| \frac{1}{\sqrt{c_{i}}} \left(\nabla c_{i} + \frac{ez_{i}c_{i}\nabla\Psi}{k_{B}T} \right) \right\|_{L^{2}}^{2}}_{:=D_{A}} = \underbrace{\sum_{i=1}^{N} D_{i} \int_{\mathbb{T}^{3}} \left(\nabla c_{i} + \frac{ez_{i}}{k_{B}T} c_{i}\nabla\Psi \right) \cdot \left(\frac{ez_{i}}{k_{B}T} \nabla\Psi \right) dx}_{:=\mathcal{N}}, (3)$$

• Consider $D_1 = \cdots = D_N = D$. In this case the evolution of ρ is:

$$\partial_t \rho + u \cdot \nabla \rho - D \Delta \rho = D N_A \frac{e^2}{k_B} \sum_{i=1}^N \nabla \cdot \left(z_i^2 c_i \frac{1}{T} \nabla \Psi \right).$$

$$\frac{\varepsilon}{2} \frac{d}{dt} \|\nabla \Psi\|_{L^{2}}^{2} + \frac{D}{\varepsilon} \|\rho\|_{L^{2}}^{2} + \underbrace{\sum_{i=1}^{N} DN_{A} \frac{e^{2}}{k_{B}} \int_{\mathbb{T}^{3}} z_{i}^{2} c_{i} \frac{1}{T} |\nabla \Psi|^{2} dx}_{:=D_{B}} = \int_{\mathbb{T}^{3}} \mathbf{u} \cdot \nabla \Psi \rho dx.$$

- Dissipations D_A and D_B together can control \mathcal{N} .
- Here the diffusion terms $-\sum_{i=1}^{N} DeN_{A}z_{i}\Delta c_{i}$ boil down to $-D\Delta\rho$, which is not true when D_{i} are different. And when D_{i} are different, the corresponding D_{B} term is not good enough to control N.

• The estimate of relative entropy $E(t) := \sum_{i=1}^N \int_{\mathbb{T}^3} c_i(t) \log \frac{c_i(t)}{\bar{c}_i} dx$:

$$\frac{d}{dt}E + \underbrace{\sum_{i=1}^{N} D_{i} \left\| \frac{1}{\sqrt{c_{i}}} \left(\nabla c_{i} + \frac{ez_{i}c_{i}\nabla\Psi}{k_{B}T} \right) \right\|_{L^{2}}^{2}}_{:=D_{A}} = \underbrace{\sum_{i=1}^{N} D_{i} \int_{\mathbb{T}^{3}} \left(\nabla c_{i} + \frac{ez_{i}}{k_{B}T} c_{i}\nabla\Psi \right) \cdot \left(\frac{ez_{i}}{k_{B}T} \nabla\Psi \right) dx}_{:=\mathcal{N}}, (3)$$

• Consider $D_1 = \cdots = D_N = D$. In this case the evolution of ρ is:

$$\partial_t \rho + u \cdot \nabla \rho - D \Delta \rho = D N_A \frac{e^2}{k_B} \sum_{i=1}^N \nabla \cdot \left(z_i^2 c_i \frac{1}{T} \nabla \Psi \right).$$

$$\frac{\varepsilon}{2} \frac{d}{dt} \|\nabla \Psi\|_{L^2}^2 + \frac{D}{\varepsilon} \|\rho\|_{L^2}^2 + \sum_{i=1}^N DN_A \frac{e^2}{k_B} \int_{\mathbb{T}^3} z_i^2 c_i \frac{1}{T} |\nabla \Psi|^2 dx = \int_{\mathbb{T}^3} u \cdot \nabla \Psi \rho dx.$$

- Dissipations D_A and D_B together can control \mathcal{N} .
- Here the diffusion terms $-\sum_{i=1}^{N} DeN_{A}z_{i}\Delta c_{i}$ boil down to $-D\Delta\rho$, which is not true when D_{i} are different. And when D_{i} are different, the corresponding D_{B} term is not good enough to control N.

Challenges and Strategies

- (continue) The nonlinear term $\int_{\mathbb{T}^3} u \cdot \nabla \Psi \rho dx$ is cancelled by the electric force $\rho \nabla \Psi$ in momentum equation when estimating $||u||_{L^2}^2$.
- In the estimate of $\|u\|_{L^2}^2$, we need to control the term $\int_{\mathbb{T}^3} uc_i dx$. Keep in mind we don't have L^2 control of c_i .
- By triangle inequality, D_A and D_B lead to the dissipation $\|\nabla \sqrt{c_i}\|_{L^2}^2$
- As $c_i \ge 0$, write $uc_i = u\sqrt{c_i}\sqrt{c_i}$, and do L^3 for each term using Hölder inequality, and then interpolation. $\|\nabla\sqrt{c_i}\|_{L^2}$ can be controlled by the dissipation, and

$$\|\sqrt{c_i}\|_{L^2}^2 = \|c_i\|_{L^1} = \overline{c_i} = \overline{c_i(0)}$$

Challenges and Strategies

- (continue) The nonlinear term $\int_{\mathbb{T}^3} u \cdot \nabla \Psi \rho dx$ is cancelled by the electric force $\rho \nabla \Psi$ in momentum equation when estimating $||u||_{L^2}^2$.
- In the estimate of $\|u\|_{L^2}^2$, we need to control the term $\int_{\mathbb{T}^3} uc_i dx$. Keep in mind we don't have L^2 control of c_i .
- By triangle inequality, D_A and D_B lead to the dissipation $\|\nabla \sqrt{c_i}\|_{L^2}^2$
- As $c_i \ge 0$, write $uc_i = u\sqrt{c_i}\sqrt{c_i}$, and do L^3 for each term using Hölder inequality, and then interpolation. $\|\nabla\sqrt{c_i}\|_{L^2}$ can be controlled by the dissipation, and

$$\|\sqrt{c_i}\|_{L^2}^2 = \|c_i\|_{L^1} = \overline{c_i} = \overline{c_i(0)}$$

Challenges and Strategies

- (continue) The nonlinear term $\int_{\mathbb{T}^3} u \cdot \nabla \Psi \rho dx$ is cancelled by the electric force $\rho \nabla \Psi$ in momentum equation when estimating $\|u\|_{L^2}^2$.
- In the estimate of $\|u\|_{L^2}^2$, we need to control the term $\int_{\mathbb{T}^3} uc_i dx$. Keep in mind we don't have L^2 control of c_i .
- By triangle inequality, D_A and D_B lead to the dissipation $\|\nabla \sqrt{c_i}\|_{L^2}^2$.
- As $c_i \ge 0$, write $uc_i = u\sqrt{c_i}\sqrt{c_i}$, and do L^3 for each term using Hölder inequality, and then interpolation. $\|\nabla\sqrt{c_i}\|_{L^2}$ can be controlled by the dissipation, and

$$\|\sqrt{c_i}\|_{L^2}^2 = \|c_i\|_{L^1} = \overline{c_i} = \overline{c_i(0)}.$$



A regularization scheme

- Let $\{\phi_{\eta}\}_{\eta\in(0,1)}$ be a family of standard periodic mollifiers with $\int_{\mathbb{T}^3}\phi_{\eta}(x)dx=1$. Denote by \mathcal{J}_{η} the operator $\mathcal{J}_{\eta}f = \phi_{\eta} * f = \int_{\mathbb{T}^3} \phi_{\eta}(x-y)f(y)dy$.

$$\partial_t c_i^{\eta} + \mathcal{J}_{\eta} u^{\eta} \cdot \nabla c_i^{\eta} - D \Delta c_i^{\eta} - D \frac{e}{k_B} \nabla \cdot \left(z_i \frac{1}{T^{\eta}} c_i^{\eta} \nabla \mathcal{J}_{\eta} \mathcal{J}_{\eta} \Psi^{\eta} \right) = 0, \tag{4a}$$

$$-\varepsilon\Delta\Psi^{\eta} = \rho^{\eta} = \sum_{i=1}^{N} eN_{A}z_{i}c_{i}^{\eta}, \tag{4b}$$

$$\partial_t u^{\eta} + \mathcal{J}_{\eta} u^{\eta} \cdot \nabla u^{\eta} - \nu \Delta u^{\eta} + \nabla p^{\eta}$$

$$= g\left(\alpha_{T}(T^{\eta} - T_{r}^{\eta}) - \alpha_{S}\left(\sum_{i=1}^{N} c_{i}^{\eta} M_{i} - S_{r}^{\eta}\right)\right) \vec{k} - \mathcal{J}_{\eta}\left(\rho^{\eta} \nabla \mathcal{J}_{\eta} \mathcal{J}_{\eta} \Psi^{\eta}\right), \quad (4c)$$

$$\nabla \cdot u^{\eta} = 0, \tag{4d}$$

$$\partial_t T^{\eta} + \mathcal{J}_{\eta} \mathbf{u}^{\eta} \cdot \nabla T^{\eta} - \kappa \Delta T^{\eta} = 0.$$

• Initial conditions
$$(c_i^{\eta}(0), u_0^{\eta}, T_0^{\eta}) = (\mathcal{J}_{\eta}c_i(0), \mathcal{J}_{\eta}u_0, \mathcal{J}_{\eta}T_0).$$

• The conditions $c_i(0) \geq 0$, $T_0 \geq T^* > 0$, and $\overline{u_0} = 0$ imply that $c_i^{\eta}(0) \geq 0$,

$$T_0^{\eta} \geq T^* > 0$$
, and $\overline{u_0^{\eta}} = 0$. Also $T_r^{\eta} = \overline{T^{\eta}} = T_r$ and $S_r^{\eta} = \sum_{i=1}^N \overline{c_i^{\eta}} M_i = S_r$

A regularization scheme

- Let $\{\phi_{\eta}\}_{\eta\in(0,1)}$ be a family of standard periodic mollifiers with $\int_{\mathbb{T}^3}\phi_{\eta}(x)dx=1$. Denote by \mathcal{J}_{η} the operator $\mathcal{J}_{\eta}f=\phi_{\eta}*f=\int_{\mathbb{T}^3}\phi_{\eta}(x-y)f(y)dy$.
- A regularization scheme of the NPB system:

$$\partial_{t}c_{i}^{\eta} + \mathcal{J}_{\eta}u^{\eta} \cdot \nabla c_{i}^{\eta} - D\Delta c_{i}^{\eta} - D\frac{e}{k_{B}}\nabla \cdot (z_{i}\frac{1}{T^{\eta}}c_{i}^{\eta}\nabla\mathcal{J}_{\eta}\mathcal{J}_{\eta}\Psi^{\eta}) = 0, \tag{4a}$$

$$-\varepsilon\Delta\Psi^{\eta} = \rho^{\eta} = \sum_{i=1}^{N} eN_{A}z_{i}c_{i}^{\eta}, \tag{4b}$$

$$\partial_t u^{\eta} + \mathcal{J}_{\eta} u^{\eta} \cdot \nabla u^{\eta} - \nu \Delta u^{\eta} + \nabla p^{\eta}$$

$$= g \left(\alpha_T (T^{\eta} - T_r^{\eta}) - \alpha_S \left(\sum_{i=1}^N c_i^{\eta} M_i - S_r^{\eta} \right) \right) \vec{k} - \mathcal{J}_{\eta} \left(\rho^{\eta} \nabla \mathcal{J}_{\eta} \mathcal{J}_{\eta} \Psi^{\eta} \right), \quad \text{(4c)}$$

$$\nabla \cdot u^{\eta} = 0, \tag{4d}$$

$$\partial_t T^{\eta} + \mathcal{J}_{\eta} u^{\eta} \cdot \nabla T^{\eta} - \kappa \Delta T^{\eta} = 0. \tag{4e}$$

- Initial conditions $(c_i^{\eta}(0), u_0^{\eta}, T_0^{\eta}) = (\mathcal{J}_{\eta} c_i(0), \mathcal{J}_{\eta} u_0, \mathcal{J}_{\eta} T_0).$
- The conditions $c_i(0) \geq 0$, $T_0 \geq T^* > 0$, and $\overline{u_0} = 0$ imply that $c_i^{\eta}(0) \geq 0$,

$$T_0^{\eta} \ge T^* > 0$$
, and $\overline{u_0^{\eta}} = 0$. Also $T_r^{\eta} = \overline{T^{\eta}} = T_r$ and $S_r^{\eta} = \sum_{i=1}^N \overline{c_i^{\eta}} M_i = S_r$

A regularization scheme

- Let $\{\phi_{\eta}\}_{\eta \in (0,1)}$ be a family of standard periodic mollifiers with $\int_{\mathbb{T}^3} \phi_{\eta}(x) dx = 1$. Denote by \mathcal{J}_{η} the operator $\mathcal{J}_{\eta} f = \phi_{\eta} * f = \int_{\mathbb{T}^3} \phi_{\eta}(x-y) f(y) dy$.
- A regularization scheme of the NPB system:

$$\partial_{t}c_{i}^{\eta} + \mathcal{J}_{\eta}u^{\eta} \cdot \nabla c_{i}^{\eta} - D\Delta c_{i}^{\eta} - D\frac{e}{k_{B}}\nabla \cdot (z_{i}\frac{1}{T^{\eta}}c_{i}^{\eta}\nabla\mathcal{J}_{\eta}\mathcal{J}_{\eta}\Psi^{\eta}) = 0, \tag{4a}$$

$$-\varepsilon\Delta\Psi^{\eta} = \rho^{\eta} = \sum_{i=1}^{N} eN_{A}z_{i}c_{i}^{\eta}, \tag{4b}$$

$$\partial_t u^{\eta} + \mathcal{J}_n u^{\eta} \cdot \nabla u^{\eta} - \nu \Delta u^{\eta} + \nabla p^{\eta}$$

$$= g \left(\alpha_{T} (\boldsymbol{T}^{\eta} - \boldsymbol{T}_{r}^{\eta}) - \alpha_{S} \left(\sum_{i=1}^{N} c_{i}^{\eta} M_{i} - \boldsymbol{S}_{r}^{\eta} \right) \right) \vec{k} - \mathcal{J}_{\eta} \left(\rho^{\eta} \nabla \mathcal{J}_{\eta} \mathcal{J}_{\eta} \boldsymbol{\Psi}^{\eta} \right), \quad (4c)$$

$$\nabla \cdot u^{\eta} = 0, \tag{4d}$$

$$\partial_t T^{\eta} + \mathcal{J}_{\eta} \mathbf{u}^{\eta} \cdot \nabla T^{\eta} - \kappa \Delta T^{\eta} = 0. \tag{4e}$$

- Initial conditions $(c_i^{\eta}(0), u_0^{\eta}, T_0^{\eta}) = (\mathcal{J}_{\eta} c_i(0), \mathcal{J}_{\eta} u_0, \mathcal{J}_{\eta} T_0).$
- The conditions $c_i(0) \ge 0$, $T_0 \ge T^* > 0$, and $\overline{u_0} = 0$ imply that $c_i^{\eta}(0) \ge 0$,

$$T_0^{\eta} \geq T^* > 0$$
, and $\overline{u_0^{\eta}} = 0$. Also $T_r^{\eta} = \overline{T^{\eta}} = T_r$ and $S_r^{\eta} = \sum_{i=1}^N \overline{c_i^{\eta}} M_i = S_r$.

A regularization scheme

- Assume the initial conditions of the original NPB system satisfy:
 - **1** $c_i(0)$ is non-negative and satisfying the compatibility condition $\sum_{i=1}^N eN_Az_i\overline{c_i(0)} = 0$;
 - ② T_0 is bounded below by $T_0 \ge T^* > 0$;
 - $\nabla \Psi_0 \in L^2, \ c_i(0) \in L^1, \ c_i(0) \log c_i(0) \in L^1, \ T_0 \in L^2, \ \text{and}$ $u_0 \in H = \overline{\left\{ u \in C^{\infty}(\mathbb{T}^3) : \nabla \cdot u = 0, \ \int_{\mathbb{T}^3} u = 0 \right\}} \| \cdot \|_{L^2}.$

Proposition 1

For each $\eta>0$, consider system (4) with initial conditions $(c_i^{\eta}(0), u_0^{\eta}, T_0^{\eta}) = (\mathcal{J}_{\eta}c_i(0), \mathcal{J}_{\eta}u_0, \mathcal{J}_{\eta}T_0)$. Then for any $\mathcal{T}>0$, there exists a unique strong solution $(c_i^{\eta}, u^{\eta}, T^{\eta})$ to system (4) on $[0, \mathcal{T}]$ such that

$$c_i^{\eta}, T^{\eta} \in C([0, T]; C^{\infty}(\mathbb{T}^3)), \quad and \quad u^{\eta} \in C([0, T]; C^{\infty}(\mathbb{T}^3) \cap H).$$
 (5)

Moreover, $c_i^{\eta}(t) \geq 0$ and $T^{\eta}(t) \geq T^*$ for any $t \in [0, T]$.

 The proof is based on iteration of the linearization of the regularization scheme, and prove uniform bound in terms of the iteration steps.

A regularization scheme

- Assume the initial conditions of the original NPB system satisfy:
 - **1** $c_i(0)$ is non-negative and satisfying the compatibility condition $\sum_{i=1}^N eN_Az_i\overline{c_i(0)} = 0$;
 - ② T_0 is bounded below by $T_0 \ge T^* > 0$;
 - $\nabla \Psi_0 \in L^2, \ c_i(0) \in L^1, \ c_i(0) \log c_i(0) \in L^1, \ T_0 \in L^2, \ \text{and}$ $u_0 \in H = \overline{\left\{ u \in C^{\infty}(\mathbb{T}^3) : \nabla \cdot u = 0, \ \int_{\mathbb{T}^3} u = 0 \right\}} \|\cdot\|_{L^2}.$

Proposition 1

For each $\eta>0$, consider system (4) with initial conditions $(c_i^{\eta}(0), u_0^{\eta}, T_0^{\eta}) = (\mathcal{J}_{\eta}c_i(0), \mathcal{J}_{\eta}u_0, \mathcal{J}_{\eta}T_0)$. Then for any $\mathcal{T}>0$, there exists a unique strong solution $(c_i^{\eta}, u^{\eta}, T^{\eta})$ to system (4) on $[0, \mathcal{T}]$ such that

$$c_i^{\eta}, T^{\eta} \in C([0, T]; C^{\infty}(\mathbb{T}^3)), \quad \text{and} \quad u^{\eta} \in C([0, T]; C^{\infty}(\mathbb{T}^3) \cap H).$$
 (5)

Moreover, $c_i^{\eta}(t) \geq 0$ and $T^{\eta}(t) \geq T^*$ for any $t \in [0, T]$.

• The proof is based on iteration of the linearization of the regularization scheme, and prove uniform bound in terms of the iteration steps.

Uniform bounds in η

Proposition 2

Assume the same initial conditions as before, but now suppose $T_0 \in L^p$ for some $p \ge 2$. Then the sequence of solutions $(u^\eta, c_i^\eta, T^\eta)$ and the corresponding Ψ^η and ρ^η satisfy the following uniform-in- η bounds:

$$\begin{split} &\sqrt{c_i^\eta} \text{ are uniformly bounded in } L^\infty(0,\mathcal{T};L^2) \cap L^2(0,\mathcal{T};H^1), \\ &\mathcal{T}^\eta \text{ are uniformly bounded in } L^\infty(0,\mathcal{T};L^\rho) \cap L^2(0,\mathcal{T};H^1), \\ &u^\eta \text{ are uniformly bounded in } L^\infty(0,\mathcal{T};H) \cap L^2(0,\mathcal{T};V), \\ &c_i^\eta \text{ and } \rho^\eta \text{ are uniformly bounded in } L^2(0,\mathcal{T};L^\frac32) \cap L^\frac43(0,\mathcal{T};W^{1,\frac65}). \end{split}$$

Proposition 3

Suppose the same assumption on the initial conditions in Proposition 2 holds. Then the sequence of time derivatives $(\partial_t T^\eta, \partial_t u^\eta, \partial_t \sqrt{c_i^\eta + 1})$ satisfy

$$\partial_t T^{\eta}$$
 are uniformly bounded in $L^{\frac{4}{3}}(0,\mathcal{T};H^{-1})$, $\partial_t u^{\eta}$ are uniformly bounded in $L^{\frac{4}{3}}(0,\mathcal{T};\mathcal{D}(A)')$, $\partial_t \sqrt{c_i^{\eta}+1}$ are uniformly bounded in $L^1(0,\mathcal{T};H^{-2})$.

• The estimate of T^{η} is straightforward:

$$\begin{split} &\|T^{\eta}(t)\|_{L^{2}}^{2}+2\kappa\int_{0}^{t}\|\nabla T^{\eta}(s)\|_{L^{2}}^{2}ds=\|T_{0}^{\eta}\|_{L^{2}}^{2},\quad \|T^{\eta}(t)\|_{L^{p}}\leq\|T_{0}^{\eta}\|_{L^{p}},\\ &\|T^{\eta}(t)-T_{r}^{\eta}\|_{L^{2}}^{2}\leq\|T_{0}^{\eta}-T_{r}^{\eta}\|_{L^{2}}^{2}e^{-\frac{2\kappa}{C_{p}}t}. \end{split}$$

• Perform estimate of u, $\nabla \Psi$, and E simultaneously:

$$\frac{d}{dt}(\varepsilon \left\| \nabla \mathcal{J}_{\eta} \Psi^{\eta} \right\|_{L^{2}}^{2} + \left\| u^{\eta} \right\|_{L^{2}}^{2} + 2N_{A}k_{B}T^{*}E^{\eta}) + \text{dissipation} \leq C \|T^{\eta} - T_{r}^{\eta}\|_{L^{2}}^{2} + \overline{c_{i}^{\eta}(0)}^{2} \|u^{\eta}\|_{L^{2}}^{2}$$

• In order to control $E^{\eta}(0)$ by E(0), we need:

Lemma :

Let $f \in L^1(\mathbb{T}^3)$ be a nonnegative function with $\int_{\mathbb{T}^3} f \log f dx < \infty$. For any $\eta \in (0,1)$, it holds that

$$\int_{\mathbb{T}^3} \mathcal{J}_{\eta} f \log \mathcal{J}_{\eta} f dx \le \int_{\mathbb{T}^3} f \log f dx$$

• The estimate of T^{η} is straightforward:

$$\begin{split} &\|T^{\eta}(t)\|_{L^{2}}^{2}+2\kappa\int_{0}^{t}\|\nabla T^{\eta}(s)\|_{L^{2}}^{2}ds=\|T_{0}^{\eta}\|_{L^{2}}^{2},\quad \|T^{\eta}(t)\|_{L^{p}}\leq\|T_{0}^{\eta}\|_{L^{p}},\\ &\|T^{\eta}(t)-T_{r}^{\eta}\|_{L^{2}}^{2}\leq\|T_{0}^{\eta}-T_{r}^{\eta}\|_{L^{2}}^{2}e^{-\frac{2\kappa}{C_{p}}t}. \end{split}$$

• Perform estimate of u, $\nabla \Psi$, and E simultaneously:

$$\frac{d}{dt}(\varepsilon \left\| \nabla \mathcal{J}_{\eta} \Psi^{\eta} \right\|_{L^{2}}^{2} + \left\| u^{\eta} \right\|_{L^{2}}^{2} + 2N_{A}k_{B}T^{*}E^{\eta}) + \text{dissipation} \leq C \|T^{\eta} - T_{r}^{\eta}\|_{L^{2}}^{2} + \overline{c_{i}^{\eta}(0)}^{2} \|u^{\eta}\|_{L^{2}}^{2}.$$

• In order to control $E^{\eta}(0)$ by E(0), we need:

Lemma :

Let $f \in L^1(\mathbb{T}^3)$ be a nonnegative function with $\int_{\mathbb{T}^3} f \log f dx < \infty$. For any $\eta \in (0,1)$, it holds that

$$\int_{\mathbb{T}^3} \mathcal{J}_{\eta} f \log \mathcal{J}_{\eta} f dx \leq \int_{\mathbb{T}^3} f \log f dx$$

• The estimate of T^{η} is straightforward:

$$\begin{split} &\|T^{\eta}(t)\|_{L^{2}}^{2}+2\kappa\int_{0}^{t}\|\nabla T^{\eta}(s)\|_{L^{2}}^{2}ds=\|T_{0}^{\eta}\|_{L^{2}}^{2},\quad \|T^{\eta}(t)\|_{L^{p}}\leq\|T_{0}^{\eta}\|_{L^{p}},\\ &\|T^{\eta}(t)-T_{r}^{\eta}\|_{L^{2}}^{2}\leq\|T_{0}^{\eta}-T_{r}^{\eta}\|_{L^{2}}^{2}e^{-\frac{2\kappa}{C_{p}}t}. \end{split}$$

• Perform estimate of u, $\nabla \Psi$, and E simultaneously:

$$\frac{d}{dt} (\varepsilon \left\| \nabla \mathcal{J}_{\eta} \Psi^{\eta} \right\|_{L^{2}}^{2} + \left\| u^{\eta} \right\|_{L^{2}}^{2} + 2N_{A}k_{B}T^{*}E^{\eta}) + \text{dissipation} \leq C \|T^{\eta} - T_{r}^{\eta}\|_{L^{2}}^{2} + \overline{c_{i}^{\eta}(0)}^{2} \|u^{\eta}\|_{L^{2}}^{2}.$$

• In order to control $E^{\eta}(0)$ by E(0), we need:

Lemma 1

Let $f \in L^1(\mathbb{T}^3)$ be a nonnegative function with $\int_{\mathbb{T}^3} f \log f dx < \infty$. For any $\eta \in (0,1)$, it holds that

$$\int_{\mathbb{T}^3} \mathcal{J}_{\eta} f \log \mathcal{J}_{\eta} f dx \leq \int_{\mathbb{T}^3} f \log f dx.$$

Uniform bounds in η

- Note that $\partial_t \sqrt{c_i^\eta} = \frac{\partial_t c_i^\eta}{2\sqrt{c_i^\eta}}$ and $\partial_t \sqrt{c_i^\eta + 1} = \frac{\partial_t c_i^\eta}{2\sqrt{c_i^\eta + 1}}$. The "+1" is to prevent denominator from vanishing.
- Based on Proposition 2 and 3, we have

Corollary 1

Suppose the same assumption on the initial conditions in Proposition 2 holds. Then there exists a decreasing sequence of numbers $\{\eta_k\}_{k\in\mathbb{N}}$ with $\lim_{k\to\infty}\eta_k=0$ such that the sequence of solutions $(u^{\eta_k},c_i^{\eta_k},T^{\eta_k})$ satisfy

$$\begin{split} u^{\eta_k} &\rightharpoonup u \text{ in } L^2(0,\mathcal{T};V), \quad u^{\eta_k} \stackrel{*}{=} u \text{ in } L^\infty(0,\mathcal{T};H), \quad u^{\eta_k} \to u \text{ in } L^2(0,\mathcal{T};H), \\ \mathcal{T}^{\eta_k} &\rightharpoonup \mathcal{T} \text{ in } L^2(0,\mathcal{T};H^1), \quad \mathcal{T}^{\eta_k} \stackrel{*}{=} \mathcal{T} \text{ in } L^\infty(0,\mathcal{T};L^p), \quad \mathcal{T}^{\eta_k} \to \mathcal{T} \text{ in } L^2(0,\mathcal{T};L^p), \\ \sqrt{c_i^{\eta_k}} &\rightharpoonup \sqrt{c_i} \text{ in } L^2(0,\mathcal{T};H^1), \quad \sqrt{c_i^{\eta_k}} \stackrel{*}{=} \sqrt{c_i} \text{ in } L^\infty(0,\mathcal{T};L^2), \\ \sqrt{c_i^{\eta_k}} + 1 \to \sqrt{c_i+1} \text{ and } \sqrt{c_i^{\eta_k}} \to \sqrt{c_i} \text{ in } L^2(0,\mathcal{T};L^2), \\ c_i^{\eta_k} &\rightharpoonup c_i \text{ in } L^2(0,\mathcal{T};L^\frac32) \cap L^\frac43(0,\mathcal{T};W^{1,\frac55}). \end{split}$$

• The proof follows directly from Proposition 2, Proposition 3, the Banach-Alaoglu theorem, and the Aubin-Lions compactness theorem.

Uniform bounds in η

- Note that $\partial_t \sqrt{c_i^\eta} = \frac{\partial_t c_i^\eta}{2\sqrt{c_i^\eta}}$ and $\partial_t \sqrt{c_i^\eta + 1} = \frac{\partial_t c_i^\eta}{2\sqrt{c_i^\eta + 1}}$. The "+1" is to prevent denominator from vanishing.
- Based on Proposition 2 and 3, we have

Corollary 1

Suppose the same assumption on the initial conditions in Proposition 2 holds. Then there exists a decreasing sequence of numbers $\{\eta_k\}_{k\in\mathbb{N}}$ with $\lim_{k\to\infty}\eta_k=0$ such that the sequence of solutions $(u^{\eta_k},c_i^{\eta_k},T^{\eta_k})$ satisfy

$$\begin{split} u^{\eta_k} &\rightharpoonup u \text{ in } L^2(0,\mathcal{T};V), \quad u^{\eta_k} \stackrel{*}{=} u \text{ in } L^\infty(0,\mathcal{T};H), \quad u^{\eta_k} \to u \text{ in } L^2(0,\mathcal{T};H), \\ \mathcal{T}^{\eta_k} &\rightharpoonup \mathcal{T} \text{ in } L^2(0,\mathcal{T};H^1), \quad \mathcal{T}^{\eta_k} \stackrel{*}{=} \mathcal{T} \text{ in } L^\infty(0,\mathcal{T};L^p), \quad \mathcal{T}^{\eta_k} \to \mathcal{T} \text{ in } L^2(0,\mathcal{T};L^p), \\ \sqrt{c_i^{\eta_k}} &\rightharpoonup \sqrt{c_i} \text{ in } L^2(0,\mathcal{T};H^1), \quad \sqrt{c_i^{\eta_k}} \stackrel{*}{=} \sqrt{c_i} \text{ in } L^\infty(0,\mathcal{T};L^2), \\ \sqrt{c_i^{\eta_k}+1} \to \sqrt{c_i+1} \text{ and } \sqrt{c_i^{\eta_k}} \to \sqrt{c_i} \text{ in } L^2(0,\mathcal{T};L^2), \\ c_i^{\eta_k} &\rightharpoonup c_i \text{ in } L^2(0,\mathcal{T};L^\frac32) \cap L^\frac43(0,\mathcal{T};W^{1,\frac65}). \end{split}$$

 The proof follows directly from Proposition 2, Proposition 3, the Banach-Alaoglu theorem, and the Aubin-Lions compactness theorem.

Uniform bounds in η

- Note that $\partial_t \sqrt{c_i^\eta} = \frac{\partial_t c_i^\eta}{2\sqrt{c_i^\eta}}$ and $\partial_t \sqrt{c_i^\eta + 1} = \frac{\partial_t c_i^\eta}{2\sqrt{c_i^\eta + 1}}$. The "+1" is to prevent denominator from vanishing.
- Based on Proposition 2 and 3, we have

Corollary 1

Suppose the same assumption on the initial conditions in Proposition 2 holds. Then there exists a decreasing sequence of numbers $\{\eta_k\}_{k\in\mathbb{N}}$ with $\lim_{k\to\infty}\eta_k=0$ such that the sequence of solutions $(u^{\eta_k},c_i^{\eta_k},T^{\eta_k})$ satisfy

$$\begin{split} u^{\eta_k} &\rightharpoonup u \text{ in } L^2(0,\mathcal{T};V), \quad u^{\eta_k} \stackrel{*}{\twoheadrightarrow} u \text{ in } L^\infty(0,\mathcal{T};H), \quad u^{\eta_k} \to u \text{ in } L^2(0,\mathcal{T};H), \\ \mathcal{T}^{\eta_k} &\rightharpoonup \mathcal{T} \text{ in } L^2(0,\mathcal{T};H^1), \quad \mathcal{T}^{\eta_k} \stackrel{*}{\twoheadrightarrow} \mathcal{T} \text{ in } L^\infty(0,\mathcal{T};L^p), \quad \mathcal{T}^{\eta_k} \to \mathcal{T} \text{ in } L^2(0,\mathcal{T};L^p), \\ \sqrt{c_i^{\eta_k}} &\rightharpoonup \sqrt{c_i} \text{ in } L^2(0,\mathcal{T};H^1), \quad \sqrt{c_i^{\eta_k}} \stackrel{*}{\twoheadrightarrow} \sqrt{c_i} \text{ in } L^\infty(0,\mathcal{T};L^2), \\ \sqrt{c_i^{\eta_k}+1} \to \sqrt{c_i+1} \text{ and } \sqrt{c_i^{\eta_k}} \to \sqrt{c_i} \text{ in } L^2(0,\mathcal{T};L^2), \\ c_i^{\eta_k} &\rightharpoonup c_i \text{ in } L^2(0,\mathcal{T};L^\frac32) \cap L^\frac43(0,\mathcal{T};W^{1,\frac65}). \end{split}$$

 The proof follows directly from Proposition 2, Proposition 3, the Banach-Alaoglu theorem, and the Aubin-Lions compactness theorem.

Theorem 1 (Abdo-Hu-L., preprint 2024)

Suppose the same assumption on the initial conditions in Proposition 2 holds, but $T_0 \in L^{3+\delta}$ for a fixed and arbitrarily small $\delta > 0$. Then for any time $\mathcal{T} > 0$ there exists a weak solution (c_i, u, T) to system (2) on $[0, \mathcal{T}]$ satisfying

$$\begin{split} u \in L^{\infty}(0, \mathcal{T}; H) \cap L^{2}(0, \mathcal{T}; V), & \mathcal{T} \in L^{\infty}(0, \mathcal{T}; L^{3+\delta}) \cap L^{2}(0, \mathcal{T}; H^{1}), \\ c_{i} \in L^{\infty}(0, \mathcal{T}; L^{1}) \cap L^{2}(0, \mathcal{T}; L^{\frac{3}{2}}) \cap L^{\frac{4}{3}}(0, \mathcal{T}; W^{1, \frac{6}{5}}), \end{split}$$

with the property that $c_i(x,t) \ge 0$ and $T(x,t) \ge T^*$ for a.e. $(x,t) \in \mathbb{T}^3 \times [0,T]$.

- $c_i(x,t) \ge 0$ and $T(x,t) \ge T^*$ a.e. follows from the results that $c_i^{\eta_k}(x,t) \ge 0$ and $T^{\eta_k}(x,t) \ge T^*$ for all $k \in \mathbb{N}$.
- The $L^{3+\delta}$ requirement for T_0 is due to the cubic nonlinearity in the electromigration term.

Theorem 1 (Abdo-Hu-L., preprint 2024)

Suppose the same assumption on the initial conditions in Proposition 2 holds, but $T_0 \in L^{3+\delta}$ for a fixed and arbitrarily small $\delta > 0$. Then for any time $\mathcal{T} > 0$ there exists a weak solution (c_i, u, \mathcal{T}) to system (2) on $[0, \mathcal{T}]$ satisfying

$$\begin{split} u \in L^{\infty}(0,\mathcal{T};H) \cap L^{2}(0,\mathcal{T};V), & \mathcal{T} \in L^{\infty}(0,\mathcal{T};L^{3+\delta}) \cap L^{2}(0,\mathcal{T};H^{1}), \\ c_{i} \in L^{\infty}(0,\mathcal{T};L^{1}) \cap L^{2}(0,\mathcal{T};L^{\frac{3}{2}}) \cap L^{\frac{4}{3}}(0,\mathcal{T};W^{1,\frac{6}{5}}), \end{split}$$

with the property that $c_i(x,t) \ge 0$ and $T(x,t) \ge T^*$ for a.e. $(x,t) \in \mathbb{T}^3 \times [0,T]$.

- $c_i(x,t) \ge 0$ and $T(x,t) \ge T^*$ a.e. follows from the results that $c_i^{\eta_k}(x,t) \ge 0$ and $T^{\eta_k}(x,t) \ge T^*$ for all $k \in \mathbb{N}$.
- ullet The $L^{3+\delta}$ requirement for T_0 is due to the cubic nonlinearity in the electromigration term.

Long-time Dynamics

Theorem 2 (Abdo-Hu-L. 2024, preprint)

Suppose that (c_i, u, T) is a weak solution to system (2) obtained in Theorem 1. Then the temperature T(t) decays exponentially in time to the initial average $\overline{T_0} = T_r$ in L^2 . Moreover, if the initial averages of the concentrations $\overline{c_i(0)}$ satisfy the condition

$$\max_{i \in \{1, \dots, N\}} \overline{c_i(0)} \le \frac{DRT^* \nu}{C\alpha_S^2},\tag{6}$$

where C is some constant depending only on the domain, then $(c_i(t), u(t))$ decays exponentially in time to $(\overline{c_i(0)}, 0)$ in L^1 and L^2 , respectively, and the relative entropy $\int_{\mathbb{T}^3} c_i \log \frac{c_i(t)}{\overline{c_i}} dx$ decays exponentially in time to 0. In particular, if the salinity effect in the buoyancy is negligible, i.e., $\alpha_S = 0$, then the decay holds unconditionally without any size assumptions on $\overline{c_i(0)}$.

Long-time dynamics Proof

Recall that

$$\begin{split} \frac{d}{dt} &(\varepsilon \left\| \nabla \mathcal{J}_{\eta} \Psi^{\eta} \right\|_{L^{2}}^{2} + \left\| u^{\eta} \right\|_{L^{2}}^{2} + 2N_{A}k_{B}T^{*}E^{\eta}) \\ &+ \frac{2D}{\varepsilon} \left\| \mathcal{J}_{\eta} \rho^{\eta} \right\|_{L^{2}}^{2} + \nu \left\| \nabla u^{\eta} \right\|_{L^{2}}^{2} + \frac{DN_{A}k_{B}T^{*}}{2} \sum_{i=1}^{N} \left\| \nabla \sqrt{c_{i}^{\eta}} \right\|_{L^{2}}^{2} \\ &+ \dots \\ &\leq C \|T^{\eta} - T_{t}\|_{L^{2}}^{2} + \overline{c_{i}(0)}^{2} \|u^{\eta}\|_{L^{2}}^{2}. \end{split}$$

Denote by the energy and the dissipation

$$\mathcal{E}^{\eta} := \varepsilon \|\nabla \mathcal{J}_{\eta} \Psi^{\eta}\|_{L^{2}}^{\epsilon} + \|u^{\eta}\|_{L^{2}}^{\epsilon} + 2N_{A}k_{B}T^{*}E^{\eta},$$

$$\mathcal{J}^{\eta} := \frac{2D}{\varepsilon} \|\mathcal{J}_{\eta} \rho^{\eta}\|_{L^{2}}^{2} + \nu \|\nabla u^{\eta}\|_{L^{2}}^{2} + \frac{DN_{A}k_{B}T^{*}}{2} \sum_{i=1}^{N} \|\nabla \sqrt{c_{i}^{\eta}}\|_{L^{2}}^{2}$$

- Elliptic estimate: $\frac{2D}{\varepsilon} \|\mathcal{J}_{\eta} \rho^{\eta}\|_{L^{2}}^{2} \geq \frac{2D\varepsilon}{C_{e}} \|\nabla \mathcal{J}_{\eta} \Psi^{\eta}\|_{L^{2}}^{2}$
- Poincaré inequality: $\frac{\nu}{2} \|\nabla u^{\eta}\|_{L^2}^2 \geq \frac{\nu}{2C_0} \|u^{\eta}\|_{L^2}^2$.
- Logarithmic Sobolev inequality:

$$\frac{DN_{A}k_{B}T^{*}}{4}\sum_{i=1}^{N}\|\nabla\sqrt{c_{i}^{\eta}}\|_{L^{2}}^{2} \geq \frac{DN_{A}k_{B}T^{*}}{4C_{s}}\sum_{i=1}^{N}\int_{\mathbb{T}^{3}}c_{i}^{\eta}\log\frac{c_{i}^{\eta}}{\bar{c}_{i}}dx = \frac{DN_{A}k_{B}T^{*}}{4C_{s}}E^{\eta}$$

Long-time dynamics Proof

Recall that

$$\begin{split} \frac{d}{dt} &(\varepsilon \left\| \nabla \mathcal{J}_{\eta} \Psi^{\eta} \right\|_{L^{2}}^{2} + \left\| u^{\eta} \right\|_{L^{2}}^{2} + 2N_{A}k_{B}T^{*}E^{\eta}) \\ &+ \frac{2D}{\varepsilon} \left\| \mathcal{J}_{\eta} \rho^{\eta} \right\|_{L^{2}}^{2} + \nu \left\| \nabla u^{\eta} \right\|_{L^{2}}^{2} + \frac{DN_{A}k_{B}T^{*}}{2} \sum_{i=1}^{N} \left\| \nabla \sqrt{c_{i}^{\eta}} \right\|_{L^{2}}^{2} \\ &+ \dots \\ &\leq C \| T^{\eta} - T_{r} \|_{L^{2}}^{2} + \overline{c_{i}(0)}^{2} \| u^{\eta} \|_{L^{2}}^{2}. \end{split}$$

• Denote by the energy and the dissipation

$$\mathcal{E}^{\eta} := \varepsilon \|\nabla \mathcal{J}_{\eta} \Psi^{\eta}\|_{L^{2}}^{2} + \|u^{\eta}\|_{L^{2}}^{2} + 2N_{A}k_{B}T^{*}E^{\eta},$$

$$\mathcal{D}^{\eta} := \frac{2D}{\varepsilon} \|\mathcal{J}_{\eta} \rho^{\eta}\|_{L^{2}}^{2} + \nu \|\nabla u^{\eta}\|_{L^{2}}^{2} + \frac{DN_{A}k_{B}T^{*}}{2} \sum_{i=1}^{N} \|\nabla \sqrt{c_{i}^{\eta}}\|_{L^{2}}^{2}.$$

- Elliptic estimate: $\frac{2D}{\varepsilon} \|\mathcal{J}_{\eta} \rho^{\eta}\|_{L^{2}}^{2} \geq \frac{2D\varepsilon}{C_{\sigma}} \|\nabla \mathcal{J}_{\eta} \Psi^{\eta}\|_{L^{2}}^{2}$
- Poincaré inequality: $\frac{\nu}{2} \|\nabla u^{\eta}\|_{L^2}^2 \ge \frac{\nu}{2C_p} \|u^{\eta}\|_{L^2}^2$
- Logarithmic Sobolev inequality:

$$\frac{DN_{A}k_{B}T^{*}}{4}\sum_{i=1}^{N}\|\nabla\sqrt{c_{i}^{\eta}}\|_{L^{2}}^{2} \geq \frac{DN_{A}k_{B}T^{*}}{4C_{s}}\sum_{i=1}^{N}\int_{\mathbb{T}^{3}}c_{i}^{\eta}\log\frac{c_{i}^{\eta}}{\bar{c}_{i}}dx = \frac{DN_{A}k_{B}T^{*}}{4C_{s}}E^{\eta}$$

Long-time dynamics Proof

Recall that

$$\begin{split} \frac{d}{dt} &(\varepsilon \left\| \nabla \mathcal{J}_{\eta} \Psi^{\eta} \right\|_{L^{2}}^{2} + \left\| u^{\eta} \right\|_{L^{2}}^{2} + 2N_{A}k_{B}T^{*}E^{\eta}) \\ &+ \frac{2D}{\varepsilon} \left\| \mathcal{J}_{\eta} \rho^{\eta} \right\|_{L^{2}}^{2} + \nu \left\| \nabla u^{\eta} \right\|_{L^{2}}^{2} + \frac{DN_{A}k_{B}T^{*}}{2} \sum_{i=1}^{N} \left\| \nabla \sqrt{c_{i}^{\eta}} \right\|_{L^{2}}^{2} \\ &+ \dots \\ &\leq C \| T^{\eta} - T_{r} \|_{L^{2}}^{2} + \overline{c_{i}(0)}^{2} \| u^{\eta} \|_{L^{2}}^{2}. \end{split}$$

Denote by the energy and the dissipation

$$\mathcal{E}^{\eta} := \varepsilon \|\nabla \mathcal{J}_{\eta} \Psi^{\eta}\|_{L^{2}}^{2} + \|u^{\eta}\|_{L^{2}}^{2} + 2N_{A}k_{B} T^{*} E^{\eta},$$

$$\mathcal{D}^{\eta} := \frac{2D}{\varepsilon} \|\mathcal{J}_{\eta} \rho^{\eta}\|_{L^{2}}^{2} + \nu \|\nabla u^{\eta}\|_{L^{2}}^{2} + \frac{DN_{A}k_{B} T^{*}}{2} \sum_{i=1}^{N} \|\nabla \sqrt{c_{i}^{\eta}}\|_{L^{2}}^{2}.$$

- $\bullet \ \ \mathsf{Elliptic} \ \ \mathsf{estimate:} \ \ \tfrac{2D}{\varepsilon} \|\mathcal{J}_{\eta} \rho^{\eta}\|_{L^{2}}^{2} \geq \tfrac{2D\varepsilon}{C_{e}} \|\nabla \mathcal{J}_{\eta} \Psi^{\eta}\|_{L^{2}}^{2},$
- Poincaré inequality: $\frac{\nu}{2} \|\nabla u^{\eta}\|_{L^2}^2 \ge \frac{\nu}{2C_p} \|u^{\eta}\|_{L^2}^2$.
- Logarithmic Sobolev inequality:

$$\frac{DN_{A}k_{B}T^{*}}{4}\sum_{i=1}^{N}\|\nabla\sqrt{c_{i}^{\eta}}\|_{L^{2}}^{2} \geq \frac{DN_{A}k_{B}T^{*}}{4C_{s}}\sum_{i=1}^{N}\int_{\mathbb{T}^{3}}c_{i}^{\eta}\log\frac{c_{i}^{\eta}}{\bar{c}_{i}}dx = \frac{DN_{A}k_{B}T^{*}}{4C_{s}}E^{\eta}.$$

Proof

• The term $\overline{c_i(0)}^2 \|u\|_{L^2}^2$ on the right-hand side will destroy the decay. It comes from the salinity term in the momentum equation. Revisit the estimate:

$$\left| \int_{\mathbb{T}^3} g \alpha_S (\sum_{i=1}^N c_i^\eta M_i - S_r^\eta) u_3^\eta dx \right| \leq \frac{\nu}{4} \|\nabla u^\eta\|_{L^2}^2 + C \nu^{-1} \alpha_S^2 \sum_{i=1}^N \overline{c_i(0)} \|\nabla \sqrt{c_i^\eta}\|_{L^2}^2.$$

- If $C\nu^{-1}\alpha_S^2\max_{i\in\{1,\dots,N\}}\overline{c_i(0)}\leq \frac{DN_Ak_BT^*}{4}\Leftrightarrow \max_{i\in\{1,\dots,N\}}\overline{c_i(0)}\leq \frac{DN_Ak_BT^*\nu}{4C\alpha_S^2}$, the orange part can be absorbed by the dissipation.
- There exists some M > 0 such that

$$\mathcal{E}^{\eta}(t) \lesssim e^{-Mt}$$

• If (c_i, u, T) is a weak solution obtained by passing to the limit $\eta \to 0$ from $(c_i^{\eta}, u^{\eta}, T^{\eta})$, then $\|u^{\eta}(t)\|_{L^2} \to \|u(t)\|_{L^2}$ in $L^2(0, T)$ and $E^{\eta}(t) \to E(t)$ in $L^1(0, T)$ By passing to a subsequence in $\eta \to 0$, it follows that for a.e. $t \in [0, T]$,

$$||u(t)||_{L^2}^2 + E(t) = ||u(t)||_{L^2}^2 + \int_{\mathbb{T}^3} c_i(t) \log \frac{c_i(t)}{\overline{c}_i} \lesssim e^{-\widetilde{M}t}.$$

ullet By Csiszar-Kullback-Pinsker inequality, $\|c_i(t)-\overline{c_i}\|_{L^1}^2\lesssim E(t).$ Therefore,

$$|c_i(t) - \overline{c_i}|_{L^1}^2 \lesssim e^{-\widetilde{M}t}$$

Proof

• The term $\overline{c_i(0)}^2 \|u\|_{L^2}^2$ on the right-hand side will destroy the decay. It comes from the salinity term in the momentum equation. Revisit the estimate:

$$\left| \int_{\mathbb{T}^3} g \alpha_{S} (\sum_{i=1}^N c_i^{\eta} M_i - S_r^{\eta}) u_3^{\eta} dx \right| \leq \frac{\nu}{4} \|\nabla u^{\eta}\|_{L^2}^2 + C \nu^{-1} \alpha_{S}^2 \sum_{i=1}^N \overline{c_i(0)} \|\nabla \sqrt{c_i^{\eta}}\|_{L^2}^2.$$

- If $C\nu^{-1}\alpha_S^2\max_{i\in\{1,\dots,N\}}\overline{c_i(0)}\leq \frac{DN_Ak_BT^*}{4}\Leftrightarrow \max_{i\in\{1,\dots,N\}}\overline{c_i(0)}\leq \frac{DN_Ak_BT^*\nu}{4C\alpha_S^2}$, the orange part can be absorbed by the dissipation.
- There exists some M > 0 such that

$$\mathcal{E}^{\eta}(t) \lesssim e^{-Mt}$$
,

• If (c_i, u, T) is a weak solution obtained by passing to the limit $\eta \to 0$ from $(c_i^{\eta}, u^{\eta}, T^{\eta})$, then $\|u^{\eta}(t)\|_{L^2} \to \|u(t)\|_{L^2}$ in $L^2(0, T)$ and $E^{\eta}(t) \to E(t)$ in $L^1(0, T)$ By passing to a subsequence in $\eta \to 0$, it follows that for a.e. $t \in [0, T]$,

$$||u(t)||_{L^2}^2 + E(t) = ||u(t)||_{L^2}^2 + \int_{\mathbb{T}^3} c_i(t) \log \frac{c_i(t)}{\overline{c}_i} \lesssim e^{-\widetilde{M}t}.$$

• By Csiszar-Kullback-Pinsker inequality, $\|c_i(t) - \overline{c_i}\|_{L^1}^2 \lesssim E(t)$. Therefore,

$$|c_i(t) - \overline{c_i}|_{L^1}^2 \lesssim e^{-\widetilde{M}t}$$

Proof

• The term $\overline{c_i(0)}^2 \|u\|_{L^2}^2$ on the right-hand side will destroy the decay. It comes from the salinity term in the momentum equation. Revisit the estimate:

$$\left| \int_{\mathbb{T}^3} g \alpha_S (\sum_{i=1}^N c_i^\eta M_i - S_r^\eta) u_3^\eta dx \right| \leq \frac{\nu}{4} \|\nabla u^\eta\|_{L^2}^2 + C \nu^{-1} \alpha_S^2 \sum_{i=1}^N \overline{c_i(0)} \|\nabla \sqrt{c_i^\eta}\|_{L^2}^2.$$

- If $C\nu^{-1}\alpha_S^2\max_{i\in\{1,\dots,N\}}\overline{c_i(0)}\leq \frac{DN_Ak_BT^*}{4}\Leftrightarrow \max_{i\in\{1,\dots,N\}}\overline{c_i(0)}\leq \frac{DN_Ak_BT^*\nu}{4C\alpha_S^2}$, the orange part can be absorbed by the dissipation.
- There exists some M > 0 such that

$$\mathcal{E}^{\eta}(t) \lesssim e^{-Mt}$$
,

• If (c_i, u, T) is a weak solution obtained by passing to the limit $\eta \to 0$ from $(c_i^{\eta}, u^{\eta}, T^{\eta})$, then $\|u^{\eta}(t)\|_{L^2} \to \|u(t)\|_{L^2}$ in $L^2(0, T)$ and $E^{\eta}(t) \to E(t)$ in $L^1(0, T)$. By passing to a subsequence in $\eta \to 0$, it follows that for a.e. $t \in [0, T]$,

$$||u(t)||_{L^2}^2 + E(t) = ||u(t)||_{L^2}^2 + \int_{\mathbb{T}^3} c_i(t) \log \frac{c_i(t)}{\overline{c}_i} \lesssim e^{-\widetilde{M}t}.$$

• By Csiszar-Kullback-Pinsker inequality, $\|c_i(t) - \overline{c_i}\|_{L^1}^2 \lesssim E(t)$. Therefore,

$$|c_i(t) - \overline{c_i}|_{L^1}^2 \lesssim e^{-\widetilde{M}t}$$
.

Proof

• The term $\overline{c_i(0)}^2 \|u\|_{L^2}^2$ on the right-hand side will destroy the decay. It comes from the salinity term in the momentum equation. Revisit the estimate:

$$\left| \int_{\mathbb{T}^3} g \alpha_{S} (\sum_{i=1}^N c_i^{\eta} M_i - S_r^{\eta}) u_3^{\eta} dx \right| \leq \frac{\nu}{4} \|\nabla u^{\eta}\|_{L^2}^2 + C \nu^{-1} \alpha_{S}^2 \sum_{i=1}^N \overline{c_i(0)} \|\nabla \sqrt{c_i^{\eta}}\|_{L^2}^2.$$

- If $C\nu^{-1}\alpha_5^2\max_{i\in\{1,\dots,N\}}\overline{c_i(0)}\leq \frac{DN_Ak_BT^*}{4}\Leftrightarrow\max_{i\in\{1,\dots,N\}}\overline{c_i(0)}\leq \frac{DN_Ak_BT^*\nu}{4C\alpha_5^2}$, the orange part can be absorbed by the dissipation.
- There exists some M > 0 such that

$$\mathcal{E}^{\eta}(t) \lesssim e^{-Mt}$$
,

• If (c_i, u, T) is a weak solution obtained by passing to the limit $\eta \to 0$ from $(c_i^{\eta}, u^{\eta}, T^{\eta})$, then $\|u^{\eta}(t)\|_{L^2} \to \|u(t)\|_{L^2}$ in $L^2(0, T)$ and $E^{\eta}(t) \to E(t)$ in $L^1(0, T)$. By passing to a subsequence in $\eta \to 0$, it follows that for a.e. $t \in [0, T]$,

$$||u(t)||_{L^2}^2 + E(t) = ||u(t)||_{L^2}^2 + \int_{\mathbb{T}^3} c_i(t) \log \frac{c_i(t)}{\overline{c}_i} \lesssim e^{-\widetilde{M}t}.$$

• By Csiszar-Kullback-Pinsker inequality, $\|c_i(t) - \overline{c_i}\|_{L^1}^2 \lesssim E(t)$. Therefore,

$$||c_i(t) - \overline{c_i}||_{L^1}^2 \lesssim e^{-\widetilde{M}t}$$
.

- Main differences and challenges between NPB system and other electrodiffusion models are the non-constant temperature and the salinity.
- Global existence of 3D weak solutions for the case when ionic diffusivities are identical.
- With some size constraint on $c_i(0)$, we have the exponential in time decay of $(c_i(t), u(t), T(t))$ to $(\overline{c_i(0)}, 0, \overline{T_0})$, and $E(t) = \int_{\mathbb{T}^3} c_i(t) \log \frac{c_i(t)}{\overline{c_i}} dx$ to 0. The size condition can be dropped if the salinity effect can be ignored, i.e., $\alpha_S = 0$.
- Some interesting future questions:
 - Global existence of 3D weak solutions when ionic diffusivities are different.
 - The study in bounded domain with physical boundary conditions.
 - ① Decay of solutions to steady state without size constraint on $c_i(0)$
 - The corresponding Boltzmann states and their stability

- Main differences and challenges between NPB system and other electrodiffusion models are the non-constant temperature and the salinity.
- Global existence of 3D weak solutions for the case when ionic diffusivities are identical.
- With some size constraint on $c_i(0)$, we have the exponential in time decay of $(c_i(t), u(t), T(t))$ to $(\overline{c_i(0)}, 0, \overline{T_0})$, and $E(t) = \int_{\mathbb{T}^3} c_i(t) \log \frac{c_i(t)}{\overline{c_i}} dx$ to 0. The size condition can be dropped if the salinity effect can be ignored, i.e., $\alpha_S = 0$.
- Some interesting future questions:
 - Global existence of 3D weak solutions when ionic diffusivities are different.
 - The study in bounded domain with physical boundary conditions.
 - 3 Decay of solutions to steady state without size constraint on $\overline{c_i(0)}$
 - The corresponding Boltzmann states and their stability

- Main differences and challenges between NPB system and other electrodiffusion models are the non-constant temperature and the salinity.
- Global existence of 3D weak solutions for the case when ionic diffusivities are identical.
- With some size constraint on $\overline{c_i(0)}$, we have the exponential in time decay of $(c_i(t), u(t), T(t))$ to $(\overline{c_i(0)}, 0, \overline{T_0})$, and $E(t) = \int_{\mathbb{T}^3} c_i(t) \log \frac{c_i(t)}{\overline{c_i}} dx$ to 0. The size condition can be dropped if the salinity effect can be ignored, i.e., $\alpha_S = 0$.
- Some interesting future questions:
 - Global existence of 3D weak solutions when ionic diffusivities are different.
 - The study in bounded domain with physical boundary conditions.
 - 3 Decay of solutions to steady state without size constraint on $\overline{c_i(0)}$
 - The corresponding Boltzmann states and their stability

- Main differences and challenges between NPB system and other electrodiffusion models are the non-constant temperature and the salinity.
- Global existence of 3D weak solutions for the case when ionic diffusivities are identical.
- With some size constraint on $\overline{c_i(0)}$, we have the exponential in time decay of $(c_i(t), u(t), T(t))$ to $(\overline{c_i(0)}, 0, \overline{T_0})$, and $E(t) = \int_{\mathbb{T}^3} c_i(t) \log \frac{c_i(t)}{\overline{c_i}} dx$ to 0. The size condition can be dropped if the salinity effect can be ignored, i.e., $\alpha_S = 0$.
- Some interesting future questions:
 - 4 Global existence of 3D weak solutions when ionic diffusivities are different.
 - The study in bounded domain with physical boundary conditions.
 - 3 Decay of solutions to steady state without size constraint on $\overline{c_i(0)}$.
 - The corresponding Boltzmann states and their stability.

Thank you!