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Deep learning in medical imaging: Techniques for image reconstruction, super-resolution and segmentation

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Machine learning in medical imaging: There is a lot of hype



Al In Medicine: Rise Of The Machines (Forbes, 2017)



ΜΙΤ

Al Is Continuing Its Assault on Radiologists

A new model can detect abnormalities in x-rays better than radiologists—in some parts of the body, anyway.

NEW YORKER

APRIL 3, 2017 ISSUE

A.I. VERSUS M.D.

What happens when diagnosis is automated?

By Siddhartha Mukherjee



Machine learning in medical imaging: There is a lot of hype

"They should stop training radiologists now." Geoffrey Hinton (godfather of deep learning) in 2017

"To the question, will AI replace radiologists, I say the answer is no..."

"... but radiologists who do AI will replace radiologists who don't." Curtis Langlotz in 2017









Machine learning for medical imaging: Opportunities

• Big data is slowly arriving in medical imaging

UK Biobank will provide large-scale imaging data from 100,000 subjects



Machine learning for medical imaging: Opportunities



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Machine learning for medical imaging: Opportunities







Practical challenges for ML in medical imaging





Practical challenges for ML in medical imaging





Overview









MR image acquisition: Challenges

- Magnetic Resonance Imaging (MRI)
 - MRI acquisition is inherently a slow process
 - Slow acquisition is
 - ok for static objects (e.g. brain, bones, etc)
 - problematic for moving objects (e.g. heart, liver, fetus)
 - Options for MRI acquisition:
 - real-time MRI: fast, but 2D and relatively poor image quality
 - gated MRI: fine for period motion, e.g. respiration or cardiac motion but requires gating (ECG or navigators) leading to long acquisition times (30-90 min).

Example: Cardiac imaging









 MRI acquisition is performed in k-space by sequent traversing sampling trajectories. K-space Image acquisition is slow t = 0



• MRI acquisition is performed in k-space by sequentially traversing sampling trajectories.



K-space

Signal space





• MRI acquisition is performed in k-space by sequentially traversing sampling trajectories.



Signal space







K-space undersampling

 Acquiring a fraction of k-space <u>accelerates</u> the process but introduces <u>aliasing</u> in signal space.

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Image reconstruction from undersampled k-space



- One can recover full k-space through compressed sensing techniques:
 - Lustig et al., MRM 2007
 - Jung et al., MRM 2009
 - Otazo et al., MRM 2010

Based on generic priors, e.g. sparsity or low-rank

- More recently other techniques have shown to be powerful for this task as well:
 - Caballero et al., IEEE TMI 2014: Dictionary learning
 - Bhatia et al., MICCAI 2016: Manifold learning
 - Schlemper et al., IEEE TMI 2017: Deep learning for cardiac MRI
 - K. Hammernik et al., MRM 2017: Deep learning for knee MRI

Based on learnt priors



• Reconstruct image $\mathbf{x} \in \mathbb{C}^N$ given undersampled k-space measurements $\mathbf{y} \in \mathbb{C}^M$ $(M \ll N)$:

 $\mathbf{y} = \mathbf{F}_u$

Undersampled Fourier encoding matrix

Acquisition noise



• Reconstruct image $\mathbf{x} \in \mathbb{C}^N$ given undersampled k-space measurements $\mathbf{y} \in \mathbb{C}^M$ $(M \ll N)$:

Undersampled Fourier encoding matrix

Acquisition noise

• In the case of Cartesian sampling we have $\mathbf{F}_u = \mathbf{M}\mathbf{F}$ where $\mathbf{F} \in \mathbb{C}^{N \times N}$ applies the 2D Fourier transform and $\mathbf{M} \in \mathbb{C}^{M \times N}$ is the undersampling mask in k-space



• We are trying to solve the following unconstrained optimisation problem:





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For CNN based reconstruction we formulate the problem as

$$\min_{\mathbf{x}} \|\mathbf{x} - f_{\mathrm{cnn}}(\mathbf{x}_u | \boldsymbol{\theta}) \|_2^2 + \lambda \|\mathbf{F}_u \mathbf{x} - \mathbf{y}\|_2^2$$

Data consistency layer



• To ensure data fidelity, we add a data consistency layer. For fixed network parameters we can write:

$$\mathbf{s}_{\text{rec}}(j) = \begin{cases} \mathbf{s}_{\text{cnn}}(j) & \text{if } j \notin \Omega & \text{Missing part of k-space} \\ \mathbf{s}_{\text{cnn}}(j) + \lambda \mathbf{s}_{0}(j) & \text{if } j \in \Omega & \text{Acquired part of k-space} \\ \mathbf{1} + \lambda & \mathbf{1} + \lambda & \mathbf{1} & \mathbf{1} \\ \mathbf{1} + \lambda & \mathbf{1} & \mathbf{1} & \mathbf{1} & \mathbf{1} \\ \mathbf{1} + \lambda & \mathbf{1} & \mathbf{1} & \mathbf{1} & \mathbf{1} \\ \mathbf{1} + \lambda & \mathbf{1} & \mathbf{1} & \mathbf{1} & \mathbf{1} \\ \mathbf{1} + \lambda & \mathbf{1} & \mathbf{1} & \mathbf{1} & \mathbf{1} \\ \mathbf{1} + \lambda & \mathbf{1} & \mathbf{1} & \mathbf{1} & \mathbf{1} \\ \mathbf{1} + \lambda & \mathbf{1} & \mathbf{1} & \mathbf{1} & \mathbf{1} \\ \mathbf{1} + \lambda & \mathbf{1} & \mathbf{1} & \mathbf{1} & \mathbf{1} \\ \mathbf{1} + \lambda & \mathbf{1} & \mathbf{1} & \mathbf{1} & \mathbf{1} \\ \mathbf{1} + \lambda & \mathbf{1} & \mathbf{1} & \mathbf{1} & \mathbf{1} \\ \mathbf{1} + \lambda & \mathbf{1} & \mathbf{1} & \mathbf{1} & \mathbf{1} \\ \mathbf{1} + \lambda & \mathbf{1} & \mathbf{1} & \mathbf{1} & \mathbf{1} \\ \mathbf{1} + \lambda & \mathbf{1} & \mathbf{1} & \mathbf{1} & \mathbf{1} \\ \mathbf{1} + \lambda & \mathbf{1} & \mathbf{1} & \mathbf{1} & \mathbf{1} \\ \mathbf{1} + \lambda & \mathbf{1} & \mathbf{1} & \mathbf{1} & \mathbf{1} \\ \mathbf{1} + \lambda & \mathbf{1} & \mathbf{1} & \mathbf{1} & \mathbf{1} \\ \mathbf{1} + \lambda & \mathbf{1} & \mathbf{1} & \mathbf{1} & \mathbf{1} \\ \mathbf{1} + \lambda & \mathbf{1} & \mathbf{1} & \mathbf{1} & \mathbf{1} \\ \mathbf{1} + \lambda & \mathbf{1} & \mathbf{1} & \mathbf{1} & \mathbf{1} \\ \mathbf{1} + \lambda & \mathbf{1} & \mathbf{1} & \mathbf{1} & \mathbf{1} \\ \mathbf{1} + \lambda & \mathbf{1} & \mathbf{1} & \mathbf{1} & \mathbf{1} \\ \mathbf{1} + \lambda & \mathbf{1} & \mathbf{1} & \mathbf{1} & \mathbf{1} \\ \mathbf{1} + \lambda & \mathbf{1} & \mathbf{1} & \mathbf{1} \\ \mathbf{1} + \lambda & \mathbf{1} & \mathbf{1} & \mathbf{1} \\ \mathbf{1} + \lambda & \mathbf{1} & \mathbf{1} & \mathbf{1} \\ \mathbf{1} + \lambda & \mathbf{1} & \mathbf{1} & \mathbf{1} \\ \mathbf{1} + \lambda & \mathbf{1} & \mathbf{1} & \mathbf{1} \\ \mathbf{1} + \lambda & \mathbf{1} \\ \mathbf{1} + \lambda & \mathbf{1} & \mathbf{1}$$

Data consistency layer



- End-to-end training requires specification of forward and backward passes
- Forward pass:

$$f_L(\mathbf{x}, \mathbf{y}; \lambda) = \mathbf{F}^H \Lambda \mathbf{F} \mathbf{x} + \frac{\lambda}{1+\lambda} \mathbf{F}_u^H \mathbf{y}$$

• Backward pass:

$$\frac{\partial f_L}{\partial \mathbf{x}^T} = \mathbf{F}^H \Lambda \mathbf{F} \qquad \qquad \begin{bmatrix} \frac{\partial f_{dc}(\mathbf{s}, \mathbf{s}_0; \lambda)}{\partial \lambda} \end{bmatrix}_j = \begin{cases} 0 & \text{if } j \notin \Omega \\ \frac{\mathbf{s}_0(j) - \mathbf{s}_{cnn}(j)}{(1+\lambda)^2} & \text{if } j \in \Omega \end{cases}$$

Jacobian of the DC layer with respect to the layer input x

If made trainable

Deep Cascade of CNNs for MRI Reconstruction





Schlemper et al. IEEE TMI 2017

Deep Cascade of CNNs for MRI Reconstruction





Deep Cascade of CNNs for MRI Reconstruction





Schlemper et al. IEEE TMI 2017

Magnitude reconstruction (6-fold)



(a) 6x Undersampled

(b) DLTG

(c) CNN

⁽d) Ground Truth

Magnitude reconstruction (11-fold)



(a) 11x Undersampled

(b) DLTG

(c) CNN

(d) Ground Truth

Schlemper et al. IEEE TMI 2017

Deep Cascade of CNNs for MRI Reconstruction: Results



• Test error across 10 subjects:

PSNR	Model	R=4 (dB)	R=8 (dB)		
	DLTG	27.5 (1.31)	22.6 (0.95)		
	CNN	31.0 (1.08)	25.2 (1.00)		

Speed

Model	Time
DLMRI/DLTG	~6 hr (CPU)
CNN (2D)	0.69 s (GPU)
CNN (2D+t)	10 s (GPU)



2D+t (vs. DLTG)

Schlemper et al. IEEE TMI 2017



Overview







Convolutional Neural Networks for Medical Image Segmentation



W. Bai et. submitted to JCMR, 2018 arXiv:1710.09289v3

Image segmentation as a machine learning problem



- Manual annotations of <u>4,872 subjects</u> (QMUL/Oxford) with <u>93,128</u> pixelwise annotated 2D images slices
- Divided into training/validation/test: 3,972/300/600



W. Bai et. submitted to JCMR, 2018 arXiv:1710.09289v3



SA, basal



LA, 2 chamber



SA, mid-ventricular



LA, 4 chamber



SA, apical

W. Bai et. submitted to JCMR, 2018 arXiv:1710.09289v3





Evaluation of segmentation accuracy Comparison to expert observers



But: Cardiac imaging is still challenging

- Acquisition of cardiac MRI typically consists of 2D multi-slice data due to
 - constraints on SNR
 - breath-hold time
 - total acquisition time
- This leads to thick slice data (thickness 8-10 mm per slice)





But: Cardiac imaging is still challenging

- Acquisition of cardiac MRI typically consists of 2D multi-slice data due to
 - constraints on SNR
 - breath-hold time
 - total acquisition time
- This leads to thick slice data (thickness 8-10 mm per slice)
- Motion between slices can lead to artefacts







Conventional CNNs: Problem







Conventional CNNs: What we want



Conventional CNNs: No explicit use of prior knowledge



• Standard Loss for **segmentation**: Cross-Entropy loss

$$L_x = -\sum_{i \in \mathcal{S}} \sum_{c=1}^C \log\left(\frac{e^{f_{(c,i)}}}{\sum_j e^{f_{(j,i)}}}\right)$$

• Standard loss for **super-resolution**: L2 or L1 loss

$$\sum_{i \in \mathcal{S}} \left\| \Phi(oldsymbol{x}_i, heta_r) - oldsymbol{y}_i
ight\|^2$$

Anatomically constrained CNNs

Low-resolution input

High-resolution output





Anatomically constrained CNN: T-L networks for representing priors



Anatomically constrained CNN: Segmentation framework



O. Oktay et al. IEEE TMI 2017

Anatomically constrained CNN: Segmentation results







Anatomically constrained CNN: Super-resolution framework



Anatomically constrained CNN: Super-resolution results





Original LR image

Baseline SR approach

Anatomically constrained SR model

Ground-truth HR image

Anatomically constrained CNN: Super-resolution results





Challenges for medical image segmentation: Deployment in the clinic



- Thi trai neural networks can be used to train a CNN-based var segmentation
 - which is more invariant to differences in the input data
 - which does not require any annotations on the test domain
- Ma

test domain is not a feasible solution





Deploying machine learning into clinical practice: What is the problem?





Solution: Unsupervised domain adaptation with adversarial networks





DeepMedic: Overview



K. Kamnitsas et al. Medical Image Analysis, 2016

DeepMedic in Action





K. Kamnitsas et al. Medical Image Analysis, 2016

DeepMedic: Unsupervised domain adaptation with adversarial networks





DeepMedic: Unsupervised domain adaptation with adversarial networks



Segmenter:
$$(\mathcal{L}_{seg}) = -\frac{1}{m} \sum_{i=1}^{m} [f(x_i) = y_i] log(f(x_i)) \quad , (x_i, y_i) \sim (X_S, Y_S)$$

Domain Discr.:
$$(\mathcal{L}_{adv}) = -\frac{1}{m} \sum_{i=1}^{m} log(f_D(h(x_i))) - \frac{1}{m} \sum_{j=1}^{m} log(1 - f_D(h(x_j))) \quad , x_i \sim X_S \\ x_j \sim X_T$$

K. Kamnitsas et al. IPMI 2017, arXiv:1612.08894



DeepMedic: Unsupervised domain adaptation with adversarial networks



K. Kamnitsas et al. IPMI 2017, arXiv:1612.08894

Challenges for medical image segmentation: DeepMedic, FCN & U-Net

• The good:

- There are some good/promising CNN-based segmentation approaches

Ensemble of Multiple Models & Architectures (EMMA)

Performance *insensitive* to suboptimal configuration

Behaviour **unbiased** by architecture & configuration

- Chosen model & config may be suboptimal for other data/task
- Results and conclusions of analysis are strongly biased



Challenges for medical image segmentation: Behaviour and performance is variable



Model trained with cross-entropy loss

Model trained with IoU (Dice) loss

Ensemble of Multiple Models and Architectures (EMMA)



Need to learn: P(Y|X)

Approximate it by model: $P\left(Y|X; \theta_m, m\right)$

with learnt parameters $\theta_m = \min_{\theta_m} d\left(P\left(Y|X; \theta_m, m\right), P(Y|X) \right)$, d the loss.

Model is defined by chosen meta-parameters *m*.

Commonly *m* is neglected, but it biases the results!

We define stochastic random variable *M*, over configurations of interest.

Need to marginalise out influence of *M*:

$$P(Y|X) = \sum_{\forall m \in M} P(Y, M = m|X) = \sum_{\forall m \in M} P(Y|X, M = m) P(M = m)$$

EMMA approximate the joint by ensembling individual models:

$$\sim P_{EMMA}(Y|X) = \sum_{\forall m \in M} P(Y|X;\theta_m,m) \frac{1}{|M|}$$

M: Network architectures



M: Network configurations

- Architecture configuration:
 - depth, width, scales, residuals, etc.
- Training Loss:
 - Cross-Entropy, IoU, DSC, etc.
- Sampling strategy:
 - equally per class, foreground/background, etc.
- Optimisation:
 - optimizer, learning rate, momentum, regulariser...
- Data normalisation:
 - z-score, bias field correction, histogram matching







Led by CBICA

1st Place

2017 MICCAI BraTS Challenge (Segmentation Task) K. Kamnitsas, et al. "Ensembles of Multiple Models and Architectures for Robust Brain Tumour Segmentation"

and the state of the

BRATS'17 Challenge: Quantitative validation



• EMMA: 2 x DeepMedic, 3 x FCNs, 1 x U-Net

- Different training losses, sampling strategies, widths, depths, configurations

- No config was heavily optimised for the task (3/6 nets were quite suboptimal)

		DSC		Sensitivity		Specificity		$Hausdorff_{95}$				
	Enh.	Whole	Core	Enh.	Whole	Core	Enh	Whole	Core	Enh.	Whole	Core
EMMA	75.7	90.2	82.0	79.0	90.9	78.3	99.8	99.5	99.9	4.22	4.56	6.11
MIC_DKFZ	73.2	89.7 89.6	82.5 79.7	79.0	91.2 89.6	78.1	99.8 99.8	99.4 99.6	99.7 99.9	4.78 4.55	6 .97	9.48

Robustness:

- EMMA of all 6 was better than individuals.
- Ensemble of 3 best nets was only marginally better than EMMA of all 6 nets.

Summary and Conclusions





Current state-of-the-art





Future: End-to-end optimisation of entire imaging pipeline via deep learning





Future: End-to-end optimisation of entire imaging pipeline via deep learning



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