Santanu S. Dey¹ Aleksandr M. Kazachkov² Andrea Lodi³ Gonzalo Muñoz⁴

¹Georgia Institute of Technology.

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Thanks to A. M. Kazachkov for all the figures in the slides.

Feb 2021

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1 The challenge – creating lightweight outer approximation of SDPs

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Solving SDPs by using	
sparse PCA	

Creating lightweight outer approximation of SDPs

Sparse priniciple component analysis

Experiements

Semi-definite programming

$$\begin{array}{ll} \min & \langle \boldsymbol{C}, \boldsymbol{X} \rangle \\ \text{s.t.} & \langle \boldsymbol{A}^{i}, \boldsymbol{X} \rangle \leq \boldsymbol{b}_{i} \quad \forall i \in \{1, \dots, m\} \\ & \boldsymbol{X} \in \mathcal{S}_{+}^{n}, \end{array}$$
 (SDP)

where *C* and the A^{i} 's are $n \times n$ matrices, $\langle M, N \rangle := \sum_{i,j} M_{ij} N_{ij}$, and

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 $\mathcal{S}^n_+ = \{ X \in \mathbb{R}^{n \times n} \, | \, X = X^T, \ u^\top X u \ge 0, \ \forall u \in \mathbb{R}^n \}.$

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 Polynomial-time algorithm – but often challenging to solve in practice.

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- Polynomial-time algorithm but often challenging to solve in practice.
- In many applications (Combinatorial optimization, non-convex quadratic problems), the SDP is a relaxation of a more challenging nonconvex problem, which needs to be solved using the (spacial) branch-and-bound algorithm. We do not want to maintain a SDP relaxation – since it would have to solved at each node — but maintain a linear programming relaxation.

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Semi-definite programming: solving via linear cutting-planes

1. Construct a linear programming relaxation:

$$\begin{array}{ll} \min & \langle C, X \rangle \\ \text{s.t.} & \langle A^i, X \rangle \leq b_i \quad \forall i \in \{1, \dots, m\} \\ & \frac{X \in S^n_+}{} \end{array} \quad (\text{LP-Relax-of-SDP})$$

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 (LP-Relax-of-SDP)

2. Let optimal solution be \tilde{X} . If $\tilde{X} \in S^n_+$, then we have solved the SDP.

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2. Let optimal solution be \tilde{X} . If $\tilde{X} \in S^n_+$, then we have solved the SDP.

3. Else,

$$ilde{X} = \sum_{i=1}^n \lambda_i oldsymbol{v}^i (oldsymbol{v}^i)^{\mathsf{T}}$$
 and, say $\lambda_1 < \mathsf{0},$

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4. Let
$$V = v^1 (v^1)^{\top}$$
. Then
 $\langle V, \tilde{X} \rangle = \lambda_1 < 0$, but $\langle V, X \rangle \ge 0$ for all $X \in S^n_+$

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. Then
 $\langle V, \tilde{X} \rangle = \lambda_1 < 0$, but $\langle V, X \rangle \ge 0$ for all $X \in S^n_+$

5. Update, (LP-Relax-of -SDP) as:

$$\begin{array}{ll} \min & \langle \boldsymbol{C}, \boldsymbol{X} \rangle \\ \text{s.t.} & \langle \boldsymbol{A}^i, \boldsymbol{X} \rangle \leq b_i \quad \forall i \in \{1, \ldots, m\} \\ & \langle \boldsymbol{V}, \boldsymbol{X} \rangle \geq 0. \end{array}$$

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Go to Step 2.

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Experiements

Lets see an example of this at work...

Box QP:

$$\begin{array}{ll} \min & x^\top Q x + c^\top x \\ \text{s.t.} & x \in [0,1]^n \end{array}$$

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► SDP (+ McCormick) relaxation: min $\langle Q, xx^T \rangle + c^T x$

s.t. $x \in [0, 1]^n$

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SDP (+ McCormick) relaxation:

min $\langle Q, xx^T \rangle + c^\top x$ s.t. $x \in [0, 1]^n$

min $\langle Q, X \rangle + c^{\top} x$ s.t. $x \in [0, 1]^n, X = xx^T$

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min $\langle Q, X \rangle + c^{\top} x$ s.t. $x \in [0, 1]^n, X = xx^T$

 $\begin{array}{ll} \min & \langle Q, X \rangle + c^{\top} x \\ \text{s.t.} & \max\{0, x_i + x_j - 1\} \leq X_{ij} \leq \min\{x_i, x_j\} \ i, j \in [n] \\ & \begin{bmatrix} 1 & x^{\top} \\ x & X \end{bmatrix} \in \mathcal{S}_+^n. \end{array}$

► spar125-025-1 (https://github.com/sburer/BoxQPinstances): n = 125 and Q has 25% non-zeros.



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Sparse priniciple component analysis

Experiements

Gap closed vs. time



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Why are the LPs becoming so difficult to solve?

• n = 125. So LP has 7875 variables.

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Why are the LPs becoming so difficult to solve?

• n = 125. So LP has 7875 variables.

$$ilde{X} = \sum_{i=1}^n \lambda_i oldsymbol{v}^i oldsymbol{(v}^i)^T$$
 and, say $\lambda_1 < 0,$

Typically, the eigenvector (v^1) corresponding to the negative eigenvalue is dense.

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Therefore, the inequality

$$\langle V, X \rangle \geq 0,$$

is a completely dense inequality in an LP which is already "largish".

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 As these dense inequalities keep getting added, the LP solve times increase.

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is a completely dense inequality in an LP which is already "largish".

- As these dense inequalities keep getting added, the LP solve times increase.
- On the other hand, LP solvers love sparsity (Many linear algebra routine can exploit sparsity)!

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Conclusion

 It is no enough to just explore linear programming relaxations of SDPs.

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Conclusion

- It is no enough to just explore linear programming relaxations of SDPs.
- What we really want is sparse linear programming relaxations to SDPs.

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Conclusion

- It is no enough to just explore linear programming relaxations of SDPs.
- What we really want is sparse linear programming relaxations to SDPs.
- Lets decide a sparsity level k << n: If X̃ ∉ Sⁿ₊, then find a vector v such that

$$\boldsymbol{v}^{\top} \tilde{\boldsymbol{X}} \boldsymbol{v} < \boldsymbol{0}, \|\boldsymbol{v}\|_{\boldsymbol{0}} \leq \boldsymbol{k},$$

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then $V = vv^{\top}$ will be sparse.

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Questions:

1. How to find such "sparse eigenvectors"?

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- Questions:
 - 1. How to find such "sparse eigenvectors"?
 - 2. Will such sparse linear approximation of SDPs work?

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then $V = vv^{\top}$ will be sparse.

- Questions:
 - 1. How to find such "sparse eigenvectors"?
 - 2. Will such sparse linear approximation of SDPs work?
- Some previous papers dealing with the same topic: [A. Qualizza, P. Belotti, and F. Margot (2012)], [R. Baltean-Lugojan, P. Bonami, R. Misener, and A. Tramontani (2018)]

2 Our key technique - Sparse PCA : a well studied problem in statistics/ML literature

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Experiements

Principal component analysis (PCA) and sparse PCA

• Let $\bar{X} \in S^n_+$ (covariance matrix), the PCA problem:

$$\left. \begin{array}{ccc} w^* \in & \operatorname{argmax}_w & w^\top \bar{X} w \\ & \text{s.t.} & \|w\|_2 \leq 1 \end{array} \right\} \ \mathsf{PCA}$$

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- The optimal objective function of the above problem is the largest eigen value of \overline{X} .
- Given X is covariance matrix the optimal solution of the above problem can be interpreted as the the direction that captures the maximum variance.

► If *w*^{*} is dense, this this is no ideal from interpretability.

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- ► If *w*^{*} is dense, this this is no ideal from interpretability.

$$\tilde{w} := \operatorname{argmax}_{w} \quad w^{\top} \bar{X} w \\ \text{s.t.} \quad \|w\|_{2} \le 1 \\ \|w\|_{0} \le k$$
 Sparse PCA

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Experiements

How does SPCA help?

Goal (given \tilde{X}):

Find
$$v$$
: such that $v^{\top} \tilde{X} v < 0$, $\|v\|_2 \le 1$, $\|v\|_0 \le k$

SPCA (assuming $ar{X} \in \mathcal{S}^n_+$) :

Solve : max
$$v^{\top} \bar{X} v : \|v\|_2 \le 1, \|v\|_0 \le k$$

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 $ilde{X}
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SPCA (assuming $ar{X} \in S^n_+$) :

Solve : max $v^{\top} \bar{X} v : \|v\|_2 \le 1, \|v\|_0 \le k$

$$ilde{X}
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 (Not necessarily PSD) $ightarrow \underbrace{- ilde{X} + \lambda^{max}(ilde{X})}_{ar{X}}$

Proposition (Sparse separation via SPCA)

If max {v[⊤] (-X̃ + λ^{max}(X̃)I) v : ||v||₂ ≤ 1, ||v||₀ ≤ k} ≤ λ^{max}(X̃), then there is no sparse inequality.
If max {v[⊤] (-X̃ + λ^{max}(X̃)I) v : ||v||₂ ≤ 1, ||v||₀ ≤ k} > λ^{max}(X̃), then if v^{*} is the optimal solution then ⟨v^{*}(v^{*})[⊤], X⟩ ≥ 0 is a sparse separating hyperplane.

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Sparse PCA is "mathematically hopeless" to solve — what about "in practice"?

Approximation algorithm with multiplicative guarantee: [S. On Chan, D. Papailliopoulos, A. Rubinstein, 2016], [M. Magdon-Ismail, (2017)] NP-hardness of approximation to within (1 - ε), for some small constant ε > 0.

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- Fixed parameter tractable: [D. Papailiopoulos, A. G. Dimakis, S. Korokythakis (2014)] [A. Del Pia (2019)] Poly-time algorithm under fixed rank of matrix.

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Dey, Kazachkov, Lodi, Muñoz

Creating lightweight outer approximation of SDPs

Sparse priniciple component analysis

Experiements

Sparse PCA is "mathematically hopeless" to solve — what about "in practice"?

- Approximation algorithm with multiplicative guarantee: [S. On Chan, D. Papailliopoulos, A. Rubinstein, 2016], [M. Magdon-Ismail, (2017)] NP-hardness of approximation to within (1ε) , for some small constant $\varepsilon > 0$. The best approximation guarantee of $n^{\frac{1}{3}}$.
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ML community has come up with some fantastic heuristics:

- ► [X.-T. Yuan and T. Zhang (2013)] "Truncated power method"
- ▶ [M. Journee, Y. Nesterov, P. Richtarik, and R. Sepulchre, (2010)]

3 Experiments

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Experiements

Back to experimental results with k = 0.25n, One cut per iteration

Percent gap closed with respect to QP optimum (spar125-025-1) - dense — sparse Gap closed (%) B B 30 600 1800 2400 3000 Time (s)

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Experiements

Need to add multiple cuts in each iteration

After trying out various ideas, we settled on the following scheme:

We add multiple cuts in each iteration generated as follows:

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After trying out various ideas, we settled on the following scheme:

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 - \tilde{X} , we find v^0 such that $(v^0)^{\top} \tilde{X} v^0 = \lambda^0 < 0$.

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 $\tilde{X}^1 := \tilde{X} - \lambda^0 (v^0)^\top v^0,$

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Repeat...

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- Repeat...
- v^0, v^1, \dots are used to generate cuts.

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Experiements

More experiments (multiple cuts per iteration):



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Experiements

More experiments (multiple cuts per iteration):







Lets add some dense cuts in the first iteration.

Solving SDPs by using sparse PCA Dey, Kazachkov, Lodi,

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Experiements

More experiments (multiple cuts per iteration, dense cuts in first iteration):



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Results

Solving SDPs by using sparse PCA

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Experiements

Results on 111 BoxQP instances for SPARSE, DENSE, and HYBRID. Results are averages over instances grouped by size, under a time limit of 1 hour.

		Gap closed (%)			Last LP time (s)			
Instance group	#	SPARSE	DENSE	HYBRID	SPARSE	DENSE	HYBRID	
$n \in [20, 30]$	18	98.50	100.00	100.00	0.10	2.93	2.93	
$n \in [40, 50]$	33	98.83	99.90	99.89	0.64	10.73	7.34	
$n \in [60, 80]$	21	98.45	96.24	98.17	6.49	28.27	11.69	
$n \in [90, 125]$	27	94.62	90.68	95.48	48.09	106.54	49.08	
$n \in [200, 250]$	12	75.16	84.70	83.92	520.24	764.30	506.98	

Commercial SDP solver (Mosek) for $n \in [200, 250]$ needs approximately 35 GB memory, needs > 1 hour to solve.

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Experiements

Results

Results on 135 BIQ instances for SPARSE, DENSE, and HYE	BRID. Results are
averages over instances grouped by size, under a time lin	nit of 1 hour.

		Gap closed $(\%)$			Last LP time (s)		
Instance group	#	SPARSE	DENSE	HYBRID	SPARSE	DENSE	HYBRID
$n \in [20, 90]$	18	98.70	99.47	99.81	1.33	15.14	7.26
n = 100	31	94.92	82.53	95.00	31.33	91.35	34.82
$n \in [120, 150]$	41	90.18	89.35	92.61	125.87	262.56	132.43
$n \in [200, 250]$	45	54.72	65.72	64.06	479.61	830.75	519.96

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Results

Solving SDPs by using sparse PCA

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Experiements

Results on 151 MAXCUT instances for SPARSE, DENSE, and HYBRID. Results are averages over instances grouped by size, under a time limit of 1 hour.

		Gap closed (%)			Last LP time (s)			
Instance group	#	SPARSE	DENSE	HYBRID	SPARSE	DENSE	HYBRID	
n = 60	10	97.45	98.73	98.86	3.20	13.69	10.98	
n = 80	30	93.61	93.43	96.65	18.59	47.48	24.07	
n = 100	99	79.36	77.44	82.66	60.09	107.76	86.74	
$n \in [150, 225]$	12	6.00	5.13	5.85	717.56	775.20	704.32	

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Thank You.

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- Grigoriy Blekherman, Santanu S. Dey, Marco Molinaro, Shengding Sun, "Sparse PSD approximation of the PSD cone," *Mathematical Programming*, 2020.

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 Grigoriy Blekherman, Santanu S. Dey, Kevin Shu, Shengding Sun, "Hyperbolic relaxation of k-Locally positive semidefinite matrices" arXiv:2012.04031.