# Branching patterns in the optimal design of heat transport



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A. Souza, I. Tobasco & C. R. Doering, JFM 889 (2020)
I. Tobasco & C. R. Doering, CPAM 72 (2019)
C. R. Doering & I. Tobasco, PRL 118 (2017)

+ more *in prep* 



P. Hassanzadeh, G. P. Chini, C. R. Doering, JFM 751 (2014)



#### **<u>Goal</u>: Transport/cool optimally...**

## ...amongst a given class of velocities



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## **Enstrophy-constrained optimization**

natural from the point of view of a power budget

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$$\begin{cases} \partial_t \mathbf{u} + \mathbf{u} \cdot \nabla \mathbf{u} = \nabla p + \nu \Delta \mathbf{u} + \mathbf{f} & \text{in } \Omega \\ \nabla \cdot \mathbf{u} = 0 & \text{in } \Omega \\ \mathbf{u} = 0 & \text{at } \partial \Omega \end{cases}$$



$$\nu \left\langle |\nabla \mathbf{u}|^2 \right\rangle = \left\langle \mathbf{f} \cdot \mathbf{u} \right\rangle$$

Energy dissipation balances power input to sustain flow









Both scaling laws hold up to log corrections for  $Pe \gg 1$ .

"warmup" — energy-constrained transport



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$$\min_{\substack{\mathbf{u}(x,t)\\ |\mathbf{u}|^2 \rangle^{1/2} = Pe}} \left\langle |\nabla T|^2 \right\rangle \leq C' \frac{1}{Pe}$$
$$|\mathbf{u}|^2 \rangle^{1/2} = Pe$$
$$\mathbf{u} \cdot \hat{\mathbf{r}} = 0 \text{ at } \partial \Omega$$

"warmup" — energy-constrained transport



$$? \leq \min_{\substack{\mathbf{u}(x,t)\\ \mathbf{u}|^2 \rangle^{1/2} = Pe}} \left\langle |\nabla T|^2 \right\rangle \leq C' \frac{1}{Pe}$$
$$\left\langle |\mathbf{u}|^2 \right\rangle^{1/2} = Pe\\ \mathbf{u} \cdot \hat{\mathbf{r}} = 0 \text{ at } \partial \Omega$$

back to enstrophy-constrained transport

$$\begin{array}{c} \partial_t T + \mathbf{u} \cdot \nabla T = \Delta T + 1 \\ \mathbf{cool} \\ \mathbf{a} \text{ heated disc} \end{array} \right) \quad C \frac{1}{Pe^{2/3}} \leq \min_{\substack{\mathbf{u}(x,t) \\ \langle |\nabla \mathbf{u}|^2 \rangle^{1/2} = Pe \\ \mathbf{u} = 0 \text{ at } \partial \Omega}} \langle |\nabla T|^2 \rangle \quad \leq C' \frac{\log^{4/3} Pe}{Pe^{2/3}} \\ \mathbf{u} = 0 \text{ at } \partial \Omega \end{array}$$

back to enstrophy-constrained transport

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How do optimal flows behave?



(sharp in case of steady flows)

proof by "symmetrization"



$$\begin{cases} \partial_t T_+ + \mathbf{u} \cdot \nabla T_+ = \Delta T_+ + 1\\ -\partial_t T_- - \mathbf{u} \cdot \nabla T_- = \Delta T_- + 1 \end{cases}$$

proof by "symmetrization"



$$\begin{cases} \partial_t T_+ + \mathbf{u} \cdot \nabla T_+ = \Delta T_+ + 1\\ -\partial_t T_- - \mathbf{u} \cdot \nabla T_- = \Delta T_- + 1 \end{cases}$$
$$\eta = \frac{1}{2} (T_+ - T_-) \qquad \xi = \frac{1}{2} (T_+ + T_-) \end{cases}$$
$$\begin{cases} (\partial_t + \mathbf{u} \cdot \nabla) \eta = \Delta \xi + 1\\ (\partial_t + \mathbf{u} \cdot \nabla) \xi = \Delta \eta \end{cases}$$

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 $\langle \nabla \eta \cdot \nabla \xi \rangle = 0 \implies \langle |\nabla T|^2 \rangle = \langle |\nabla T_+|^2 \rangle = \langle |\nabla \eta|^2 + |\nabla \xi|^2 \rangle$ 

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 $\langle \nabla \eta \cdot \nabla \xi \rangle = 0 \implies \langle |\nabla T|^2 \rangle = \langle |\nabla T_+|^2 \rangle = \langle |\nabla \eta|^2 + |\nabla \xi|^2 \rangle$ 

$$\left\langle |\nabla T|^2 \right\rangle \le \left\langle |\nabla \eta|^2 + |\nabla \Delta^{-1} \left( (\partial_t + \mathbf{u} \cdot \nabla) \eta - 1 \right) |^2 \right\rangle$$
$$\left\langle |\nabla T|^2 \right\rangle \ge \left\langle 2\xi - |\nabla \xi|^2 - |\nabla \Delta^{-1} (\partial_t + \mathbf{u} \cdot \nabla) \xi|^2 \right\rangle$$

#### Lower bound on cooling



 $\langle |\nabla T|^2 \rangle \ge \langle 2\xi - |\nabla \xi|^2 - |\nabla \Delta^{-1}(\partial_t + \mathbf{u} \cdot \nabla)\xi|^2 \rangle$ 

A test function with a boundary layer yields  $\langle |\nabla T|^2 \rangle \gtrsim \langle |\nabla \mathbf{u}|^2 \rangle^{-1/3}$ 

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Very reminiscent of the background method...

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Very reminiscent of the background method...

...regardless of how you prove it, is it optimal?

#### Search for steady optimal flows

$$\min_{\substack{\mathbf{u}(x)\\\mathbf{u}=0 \text{ at } \partial\Omega}} \oint_{\Omega} |\nabla T|^2 = \min_{\substack{\mathbf{u}(x),\eta(x)\\\eta=0 \text{ at } \partial\Omega}} \oint_{\Omega} |\nabla \Delta^{-1} \left(\mathbf{u} \cdot \nabla \eta - 1\right)|^2 + \frac{1}{Pe^2} \oint_{\Omega} |\nabla \mathbf{u}|^2 \oint_{\Omega} |\nabla \eta|^2$$

$$(f_{\Omega} |\nabla \mathbf{u}|^2)^{1/2} = Pe \qquad u=0 \text{ at } \partial\Omega$$
non-convex regularizing lower order term, prefers patterns sets a lengthscale

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#### Together, the terms compete to determine optimal flows.

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Together, the terms compete to determine optimal flows.

#### Reminds of problems in elasticity, micromagnetics, ...



Ortiz & Gioia JMPS 1994



Huang et al PRL 2010



Hubert & Schafer 1998

#### **Building a branching ansatz**



# A transition layer



# A transition layer



$$\begin{aligned} \oint_{\Omega} |\nabla \Delta^{-1} \left( \mathbf{u} \cdot \nabla \eta - 1 \right)|^2 \\ = \oint_{r=0}^{r=R} \left| \overline{\mathbf{u} \cdot \hat{\mathbf{r}} \eta} - \frac{r}{2} \right|^2 r \, dr + \mathcal{Q} \{ \mathbf{u} \eta \} \end{aligned}$$

# A transition layer



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$$\overline{\mathbf{u}\cdot\hat{\mathbf{r}}\eta}\approx\frac{r}{2}$$

# **Optimal branching**

r

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r

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r

## **Takeaways/Questions**



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enstrophy-constrained optimal cooling *in prep* 

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Possible log corrections?

Does timedependence play a role?

Missing bound in energyconstrained cooling?

enstrophy-constrained optimal cooling in prep

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