

MACHINE LEARNING FOR FLUID DYNAMICS



STEVE BRUNTON
UNIVERSITY OF WASHINGTON

(Video by Petros Vrellis)

MACHINE LEARNING FOR FLUID DYNAMICS

Nathan Kutz



Josh Proctor



Bernd Noack



JC Loiseau



Eurika
Kaiser



Bethany
Lusch



Alan
Kaptanoglu



Isabel
Scherl



Sam
Rudy



Jared
Callaham



Benjamin
Herrmann



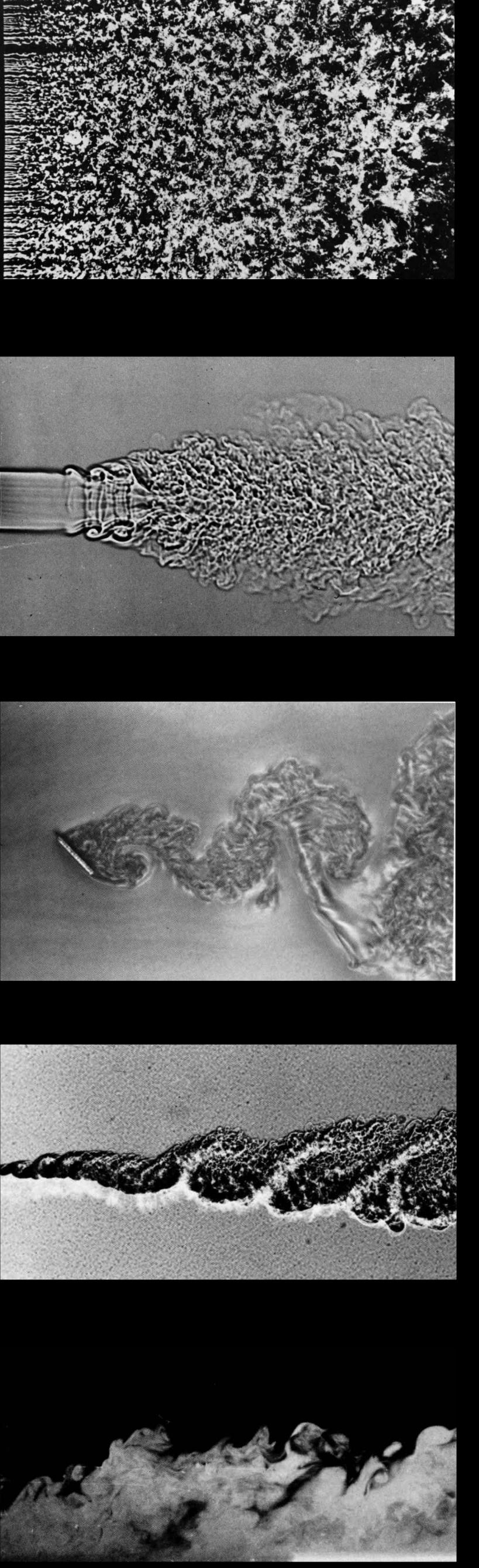
Kathleen
Champion





**ANY SUFFICIENTLY ADVANCED TECHNOLOGY
IS INDISTINGUISHABLE FROM MAGIC.**

Arthur C. Clarke



MACHINE LEARNING: MODELS FROM DATA VIA OPTIMIZATION

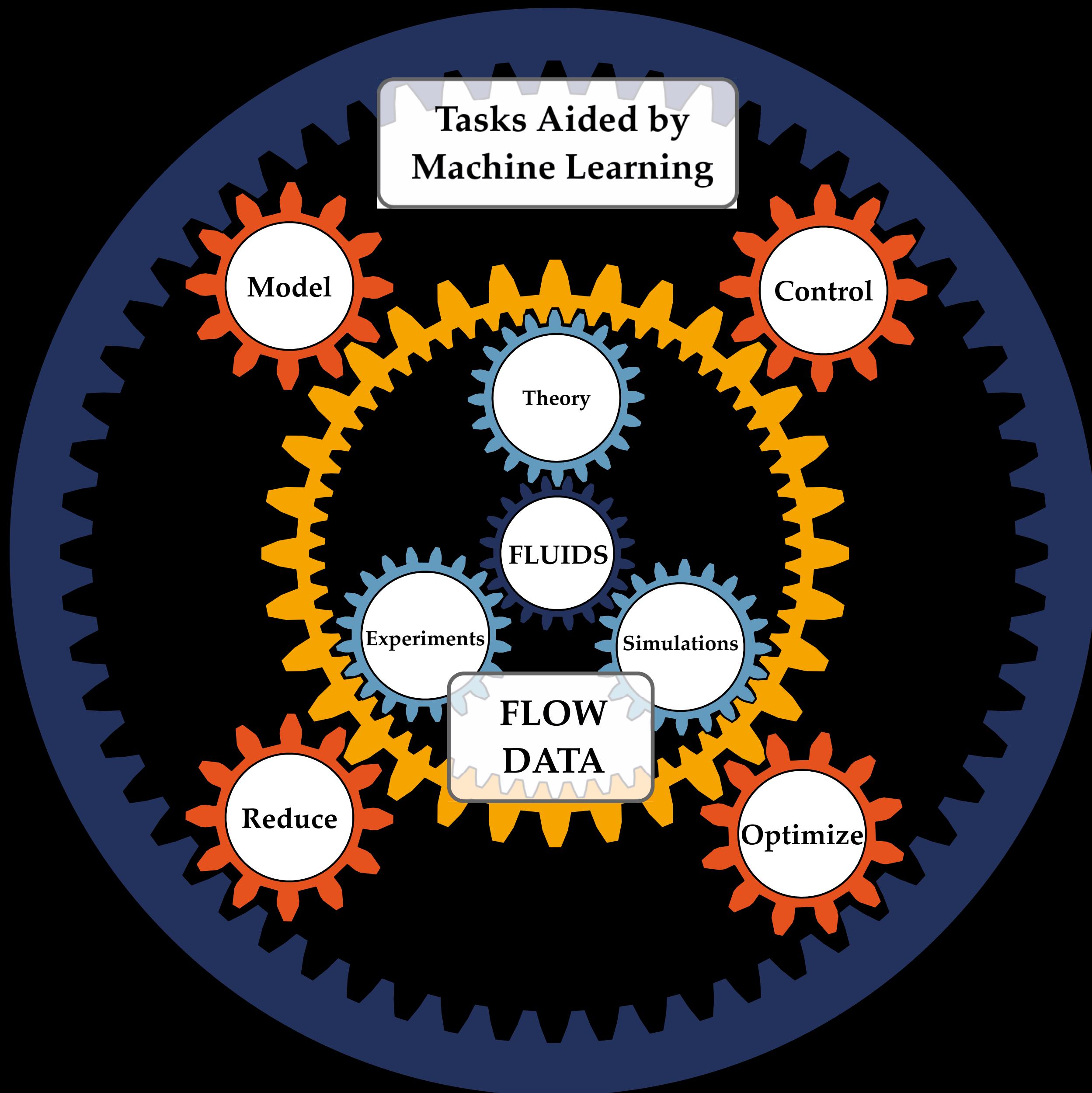


Fluid dynamics tasks:

- ▶ Reduction
- ▶ Modeling
- ▶ Control
- ▶ Sensing
- ▶ Closure

Machine Learning for Fluid Mechanics

Steven L. Brunton,¹ Bernd R. Noack,² and Petros Koumoutsakos^{3,4}



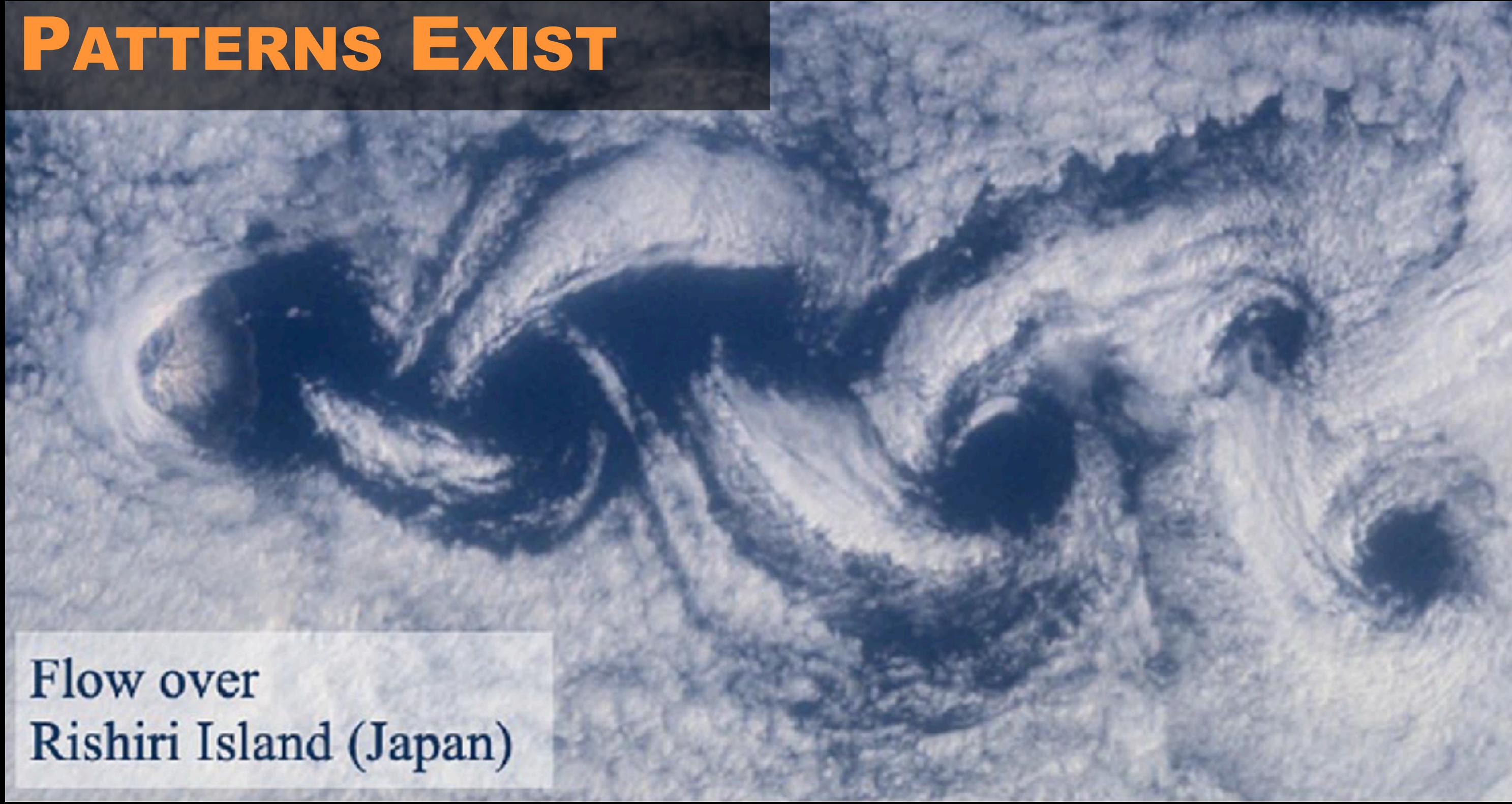
Keywords

machine learning, data-driven modeling, optimization, control

Abstract

The field of fluid mechanics is rapidly advancing, driven by unprecedented volumes of data from experiments, field measurements, and large-scale simulations at multiple spatiotemporal scales. Machine learning presents us with a wealth of techniques to extract information from data that can be translated into knowledge about the underlying fluid mechanics. Moreover, machine learning algorithms can augment domain knowledge and automate tasks related to flow control and optimization. This article presents an overview of past history, current developments, and emerging opportunities of machine learning for fluid mechanics. We outline fundamental machine learning methodologies and discuss their uses for understanding, modeling, optimizing, and controlling fluid flows. The strengths and limitations of these methods are addressed from the perspective of scientific inquiry that links data with modeling, experiments, and simulations. Machine learning provides a powerful information processing framework that can augment, and possibly even transform, current lines of fluid mechanics research and industrial applications.

PATTERNS EXIST



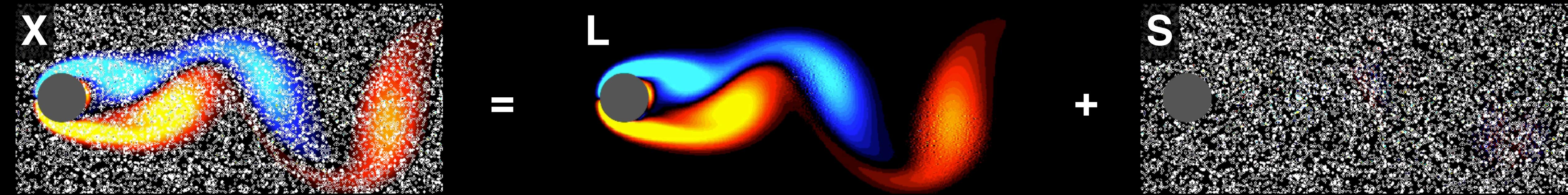
Flow over
Rishiri Island (Japan)



Flow over a cylinder
($Re = 100$)

Taira et al., AIAA J. 2017

ROBUST PROPER ORTHOGONAL DECOMPOSITION



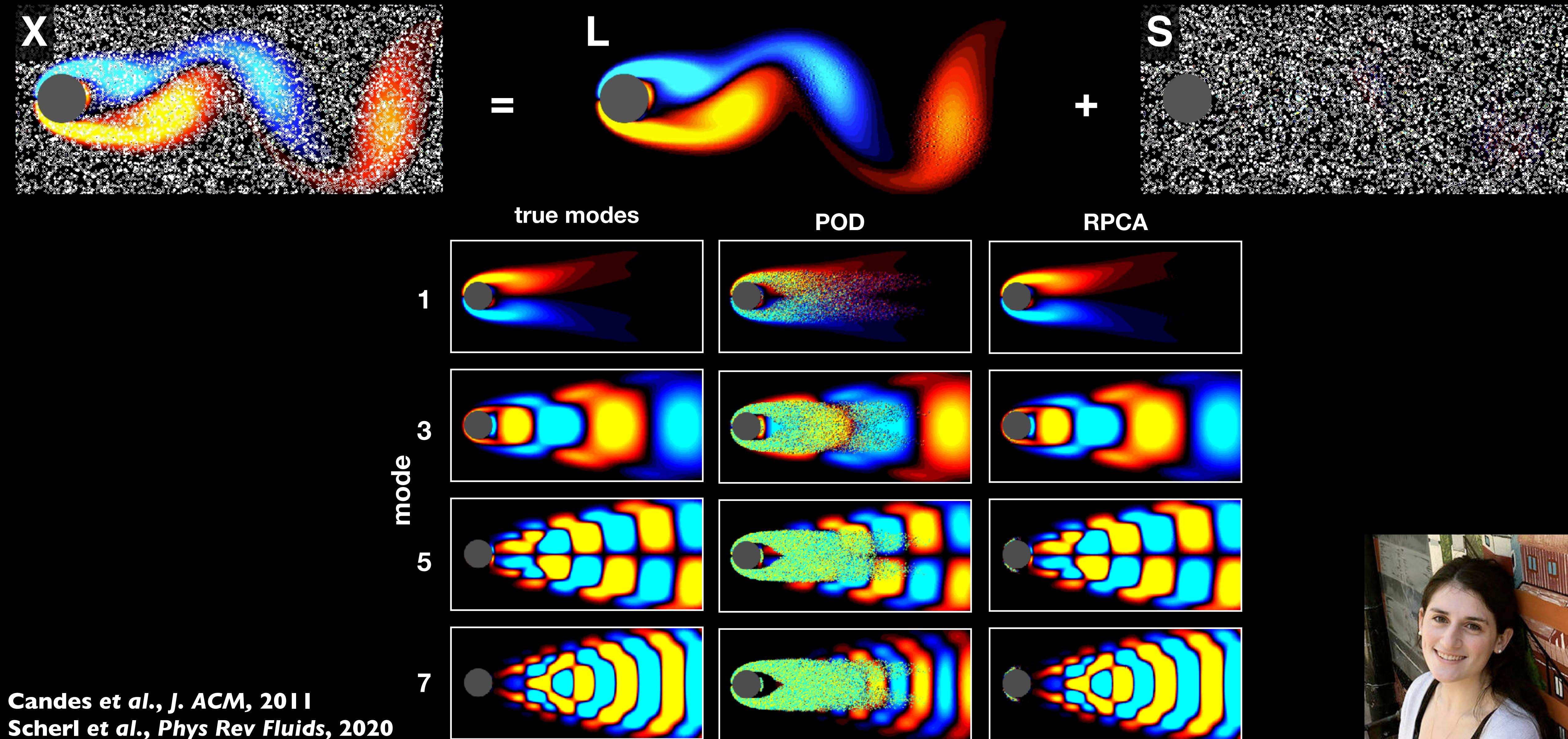
$$\min_{L,S} \text{rank}(L) + \|S\|_0 \text{ subject to } L + S = X$$

Convex Relaxation

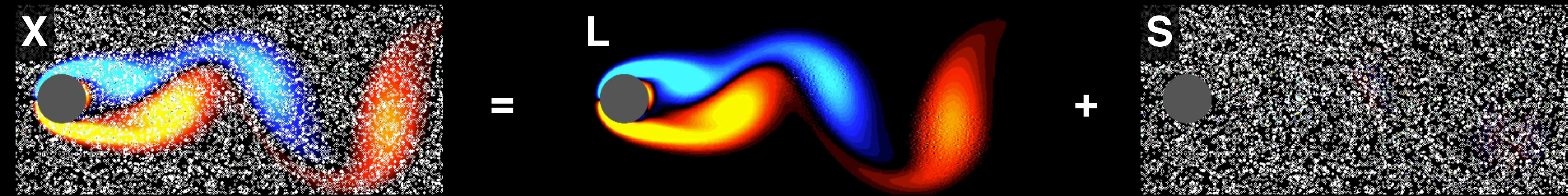
$$\min_{L,S} \|L\|_* + \lambda_0 \|S\|_1 \text{ subject to } L + S = X$$



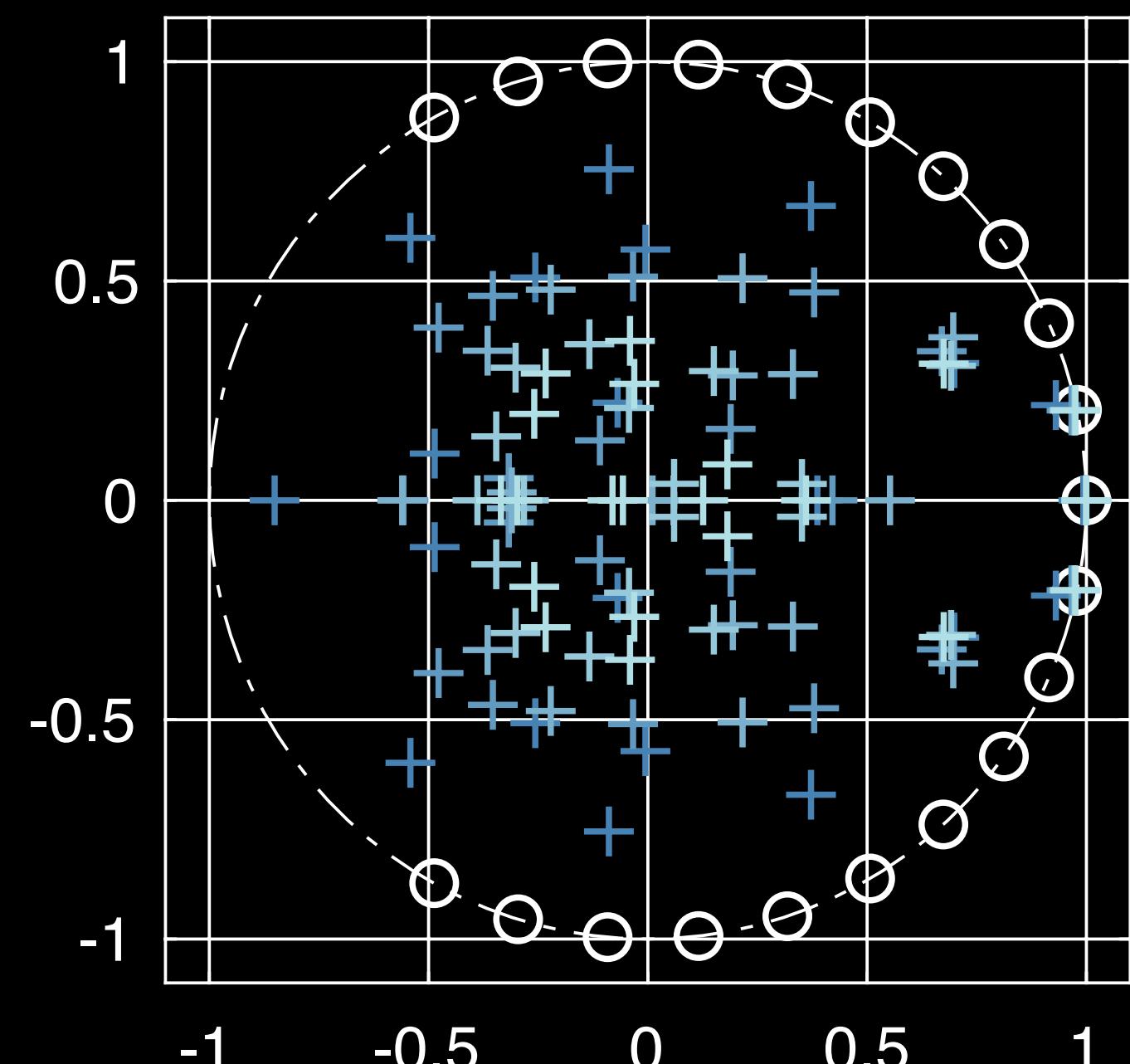
ROBUST PROPER ORTHOGONAL DECOMPOSITION



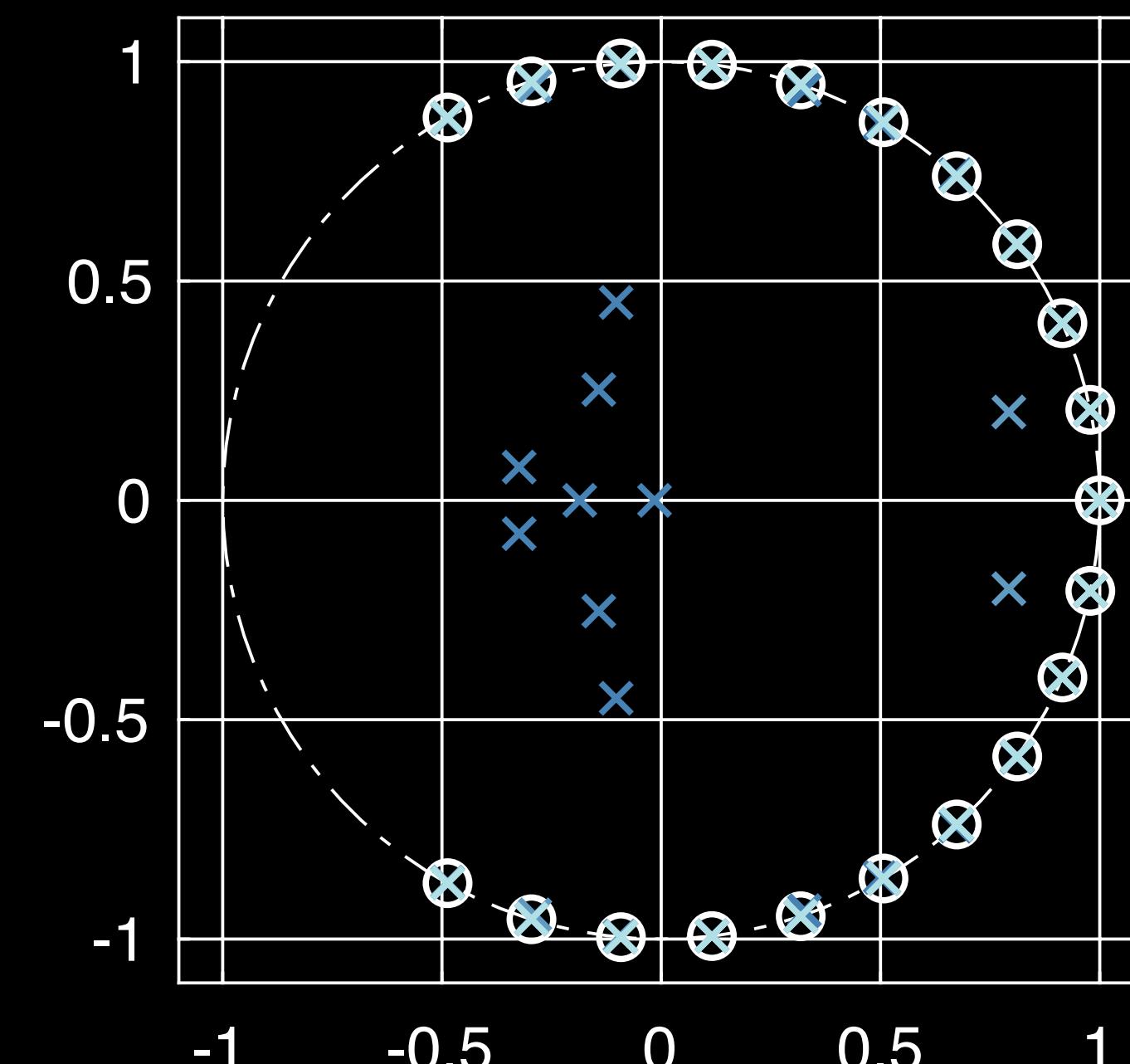
ROBUST PROPER ORTHOGONAL DECOMPOSITION



DMD Before



DMD After RPCA

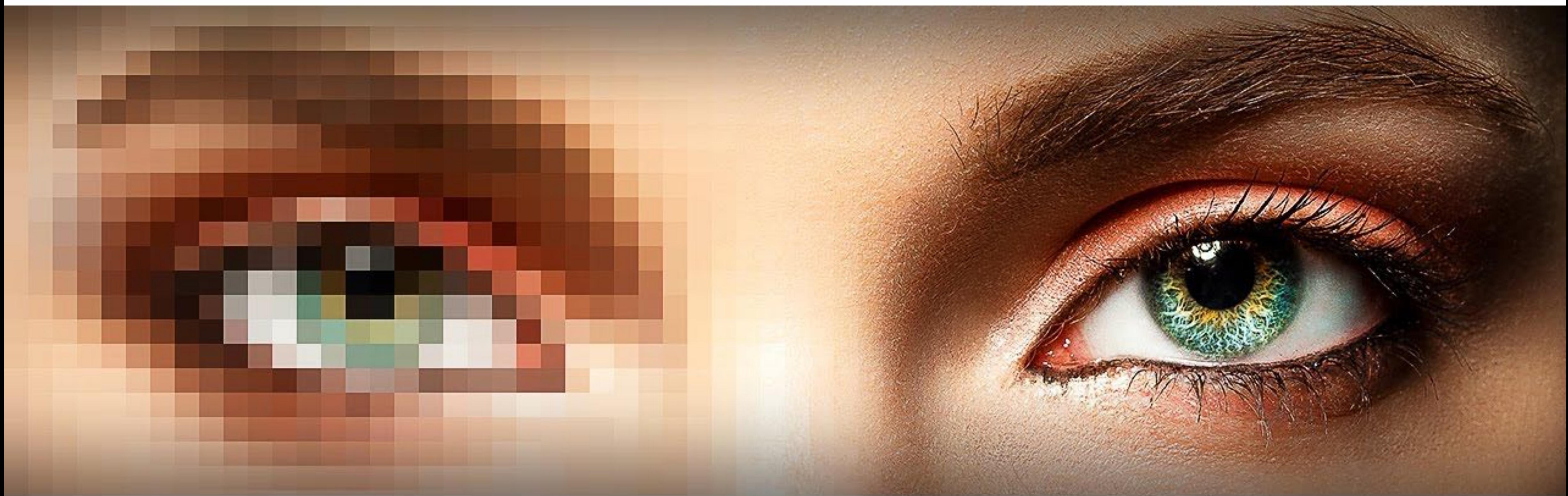


SUPER RESOLUTION

LOW-RES

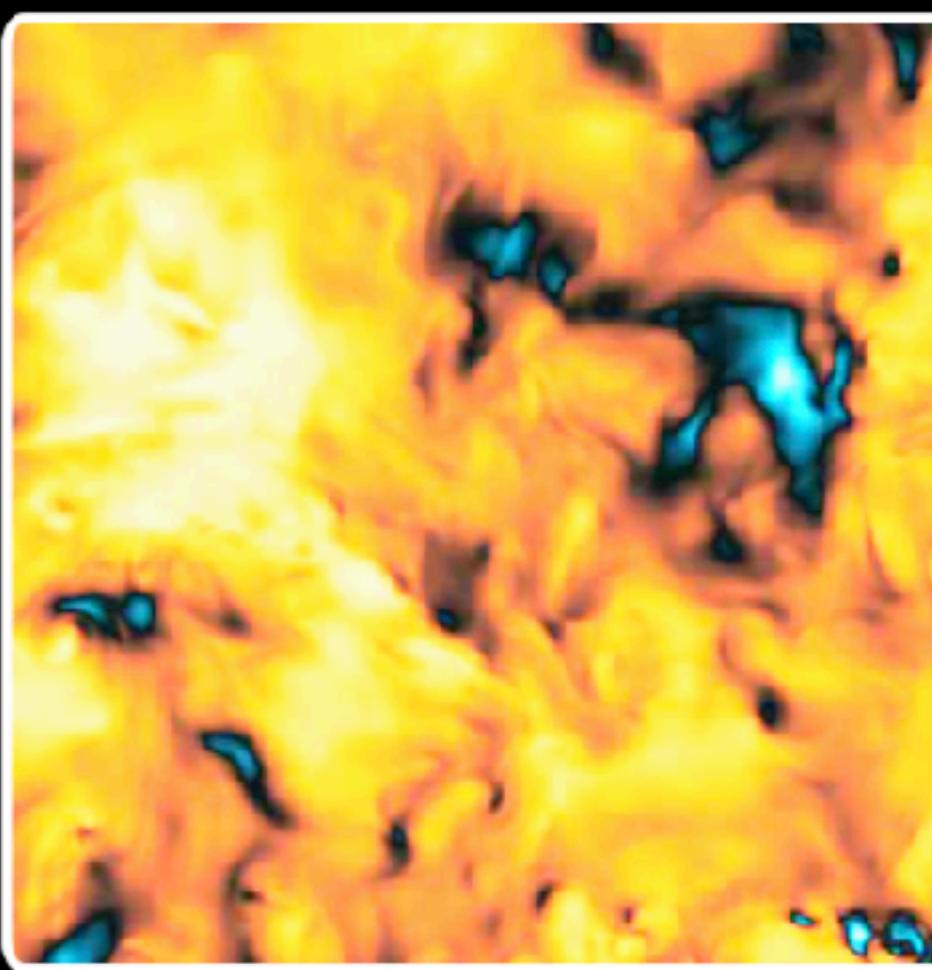


HIGH-RES

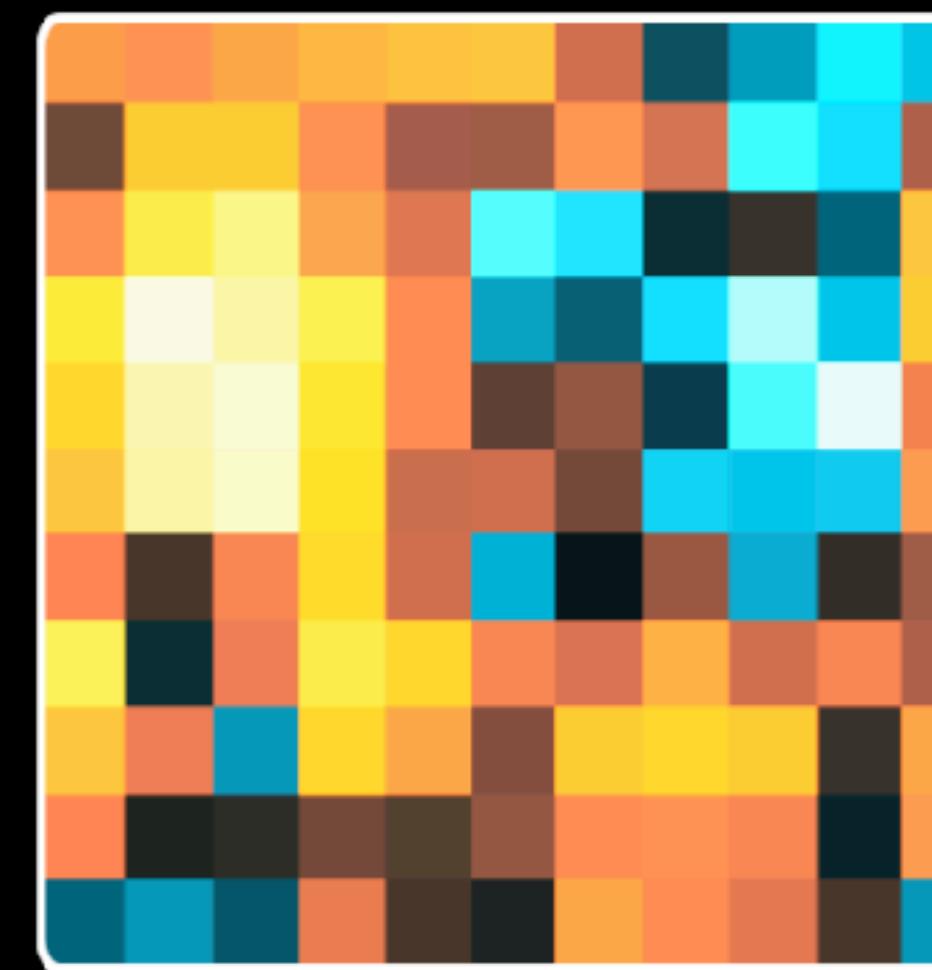


Google RAISR

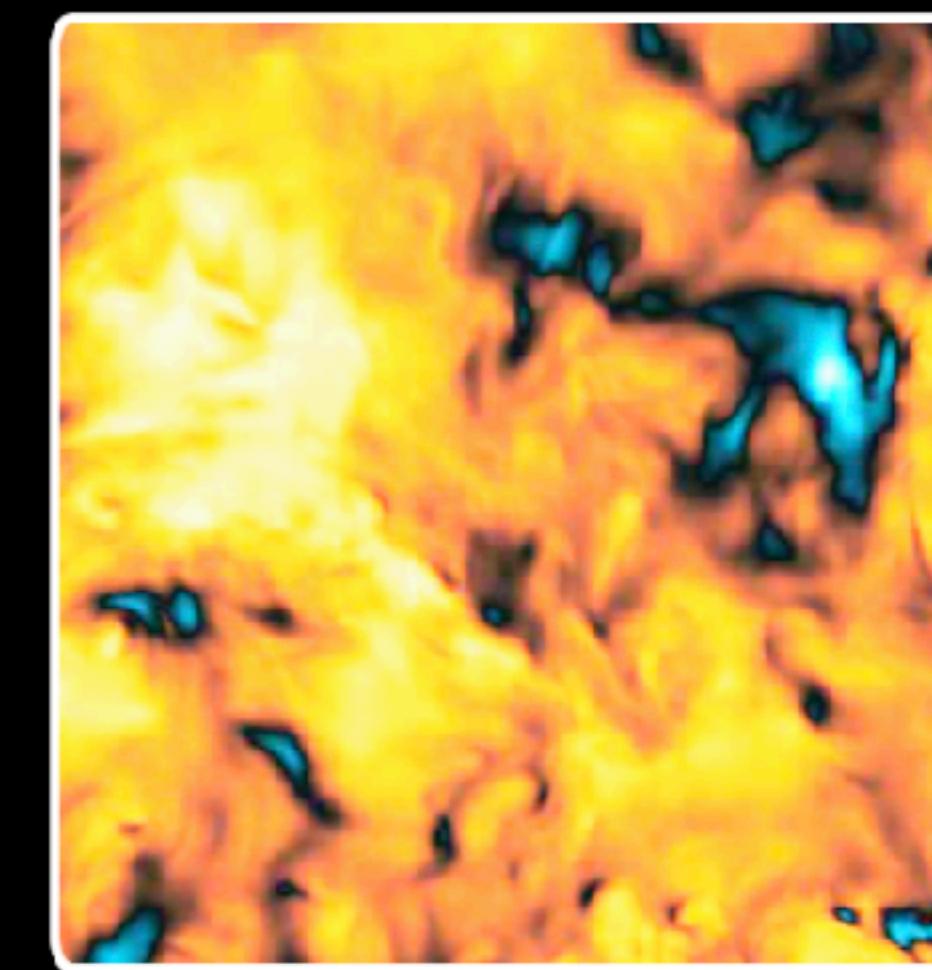
SUPER RESOLUTION



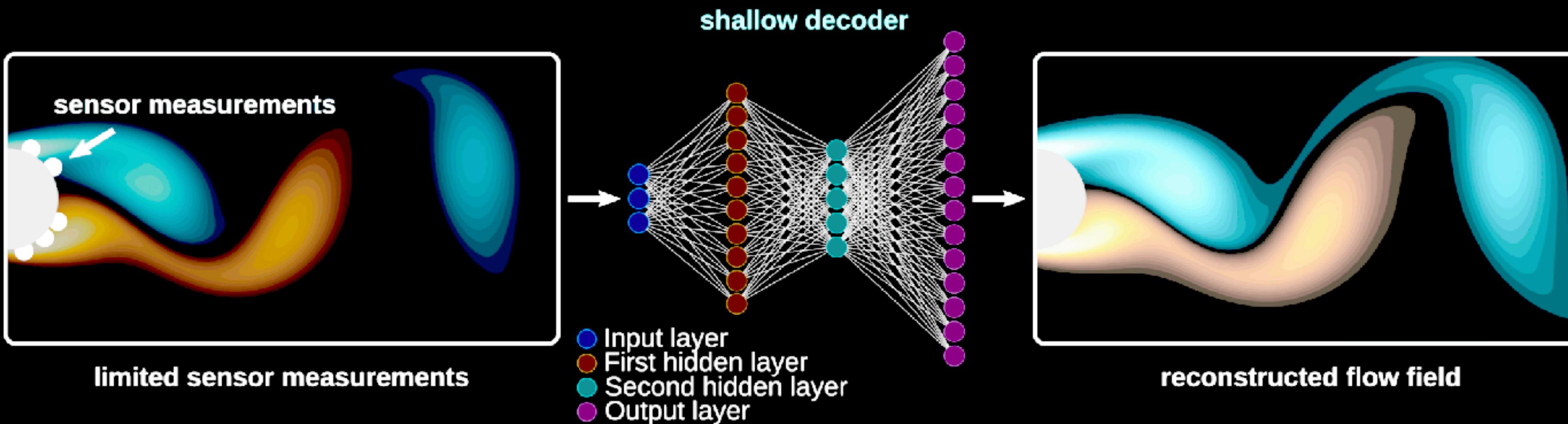
(a) Snapshot



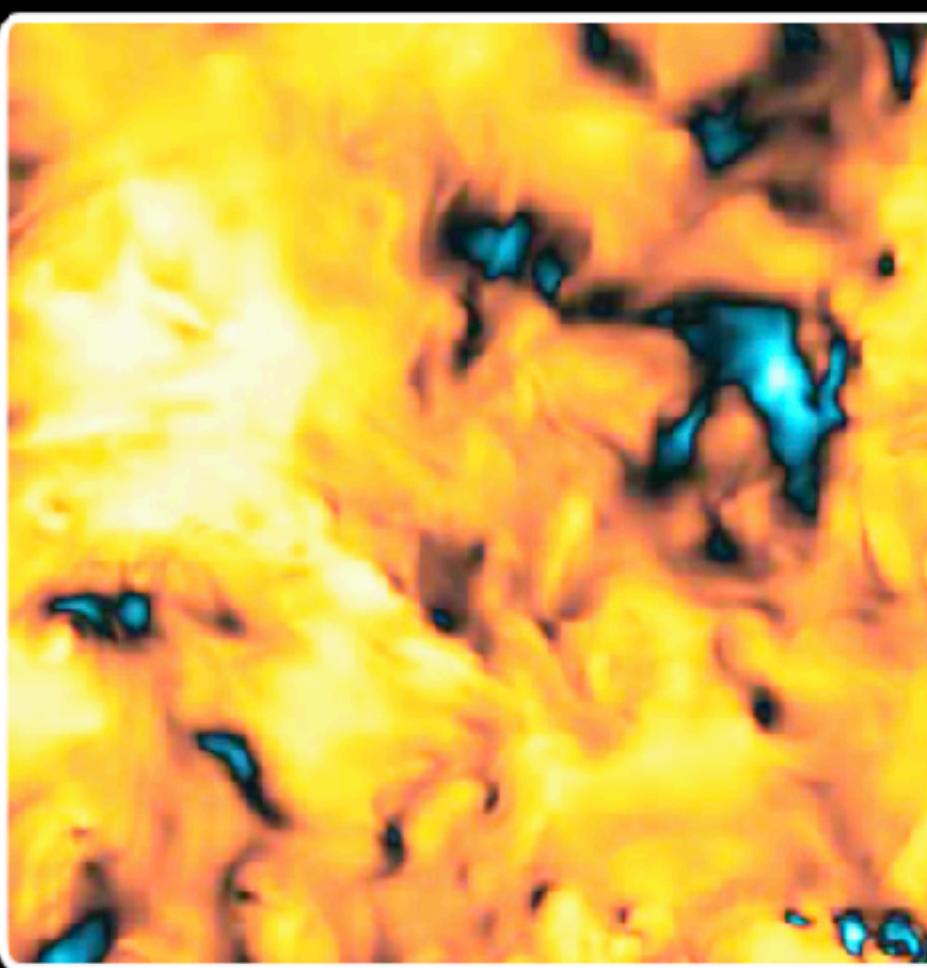
(b) Low resolution



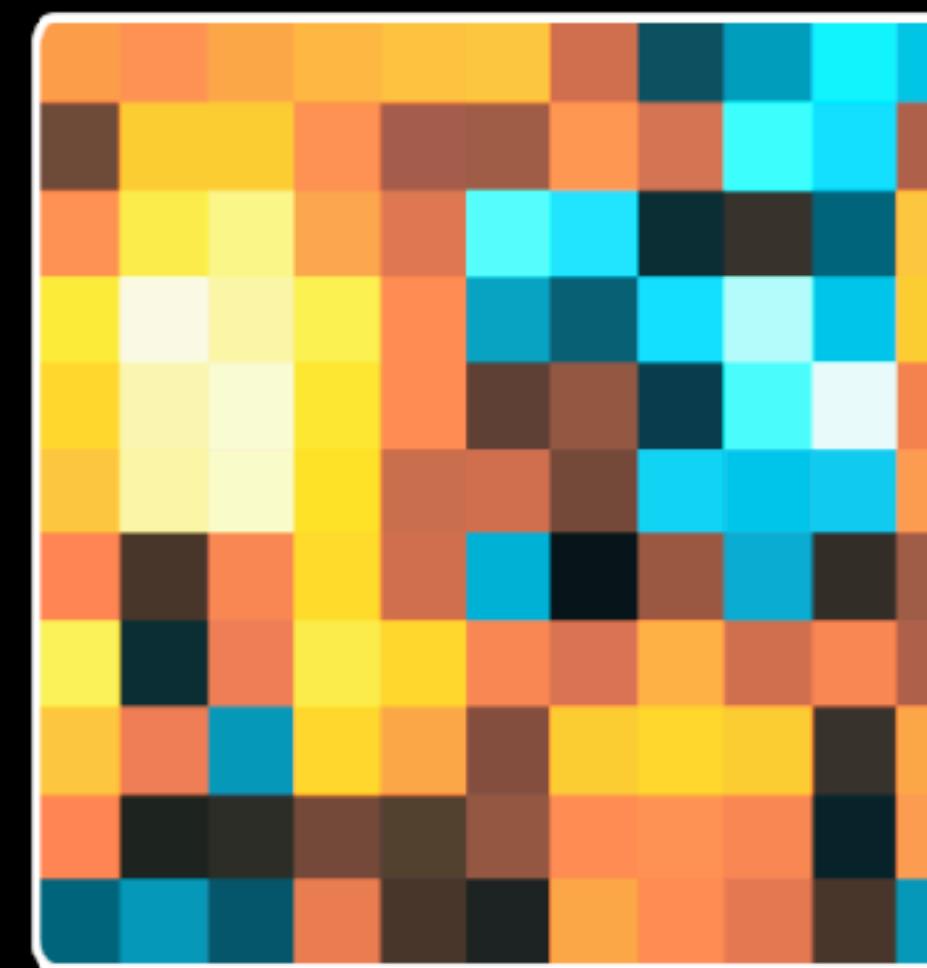
(c) Shallow Decoder



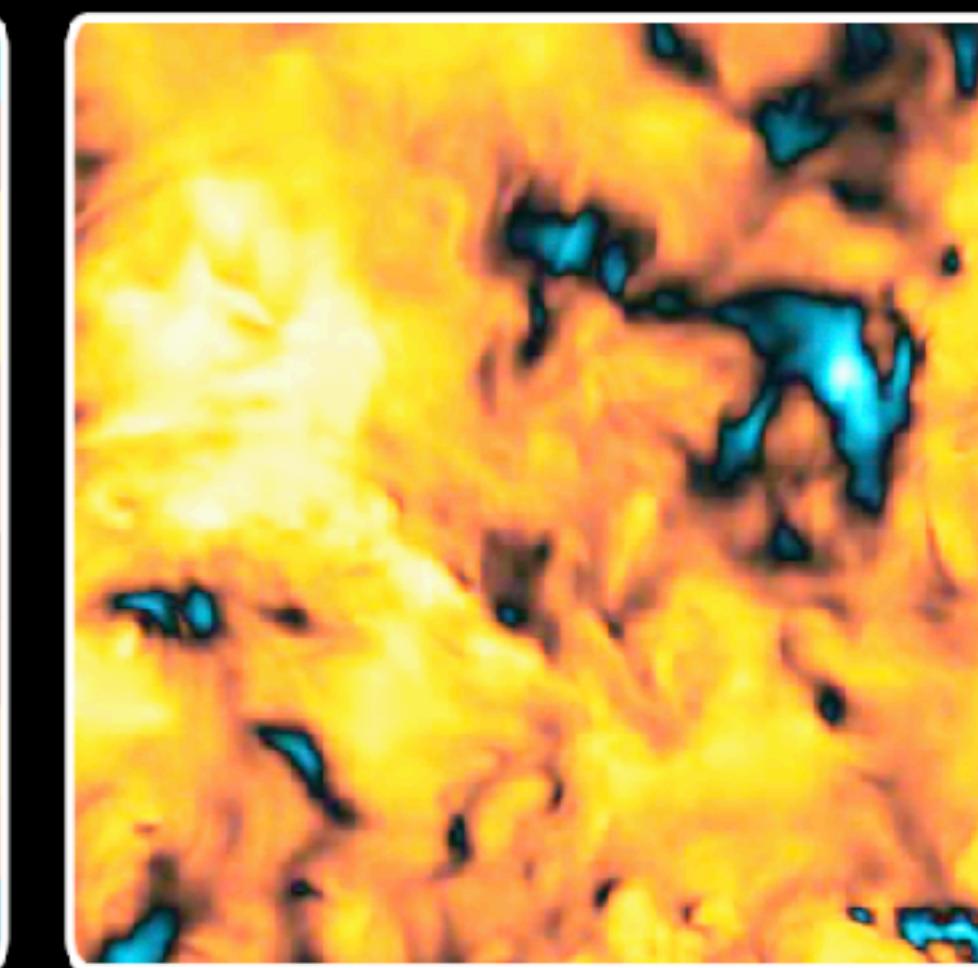
SUPER RESOLUTION



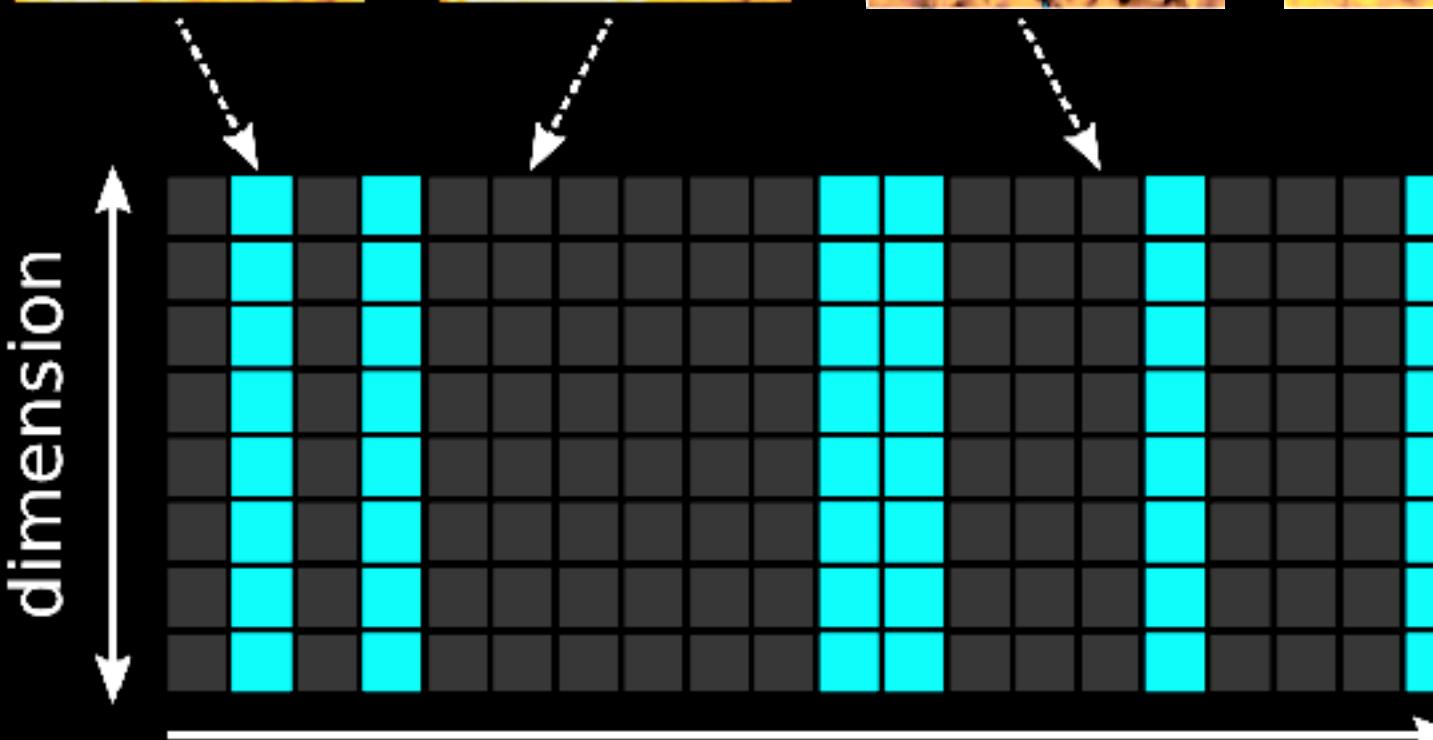
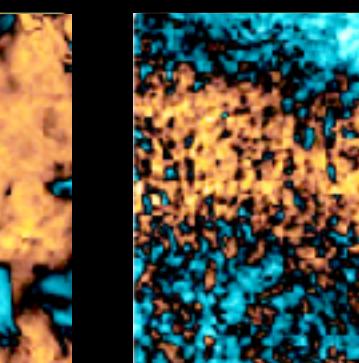
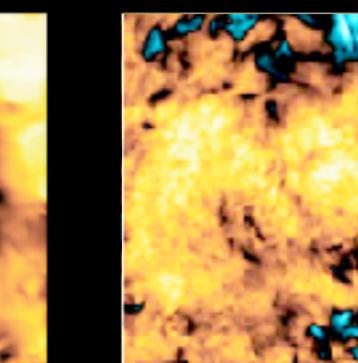
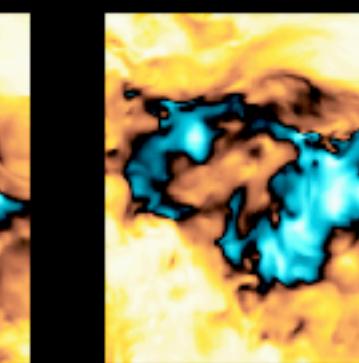
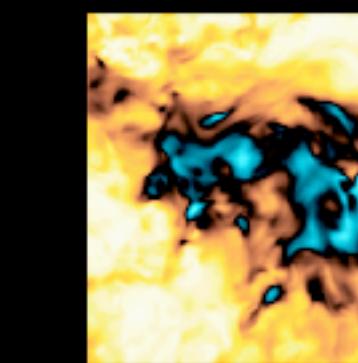
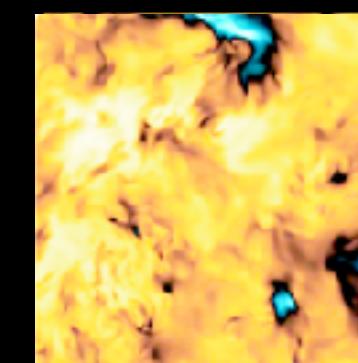
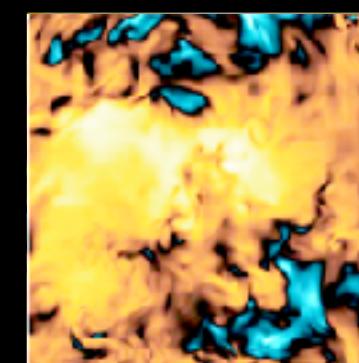
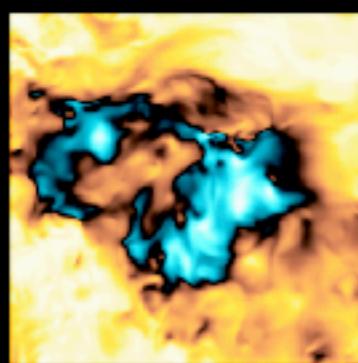
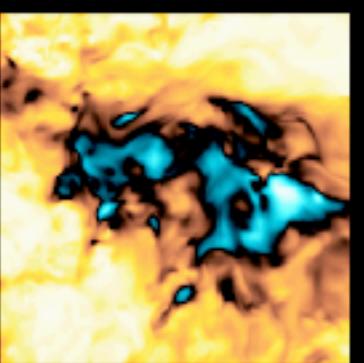
(a) Snapshot



(b) Low resolution

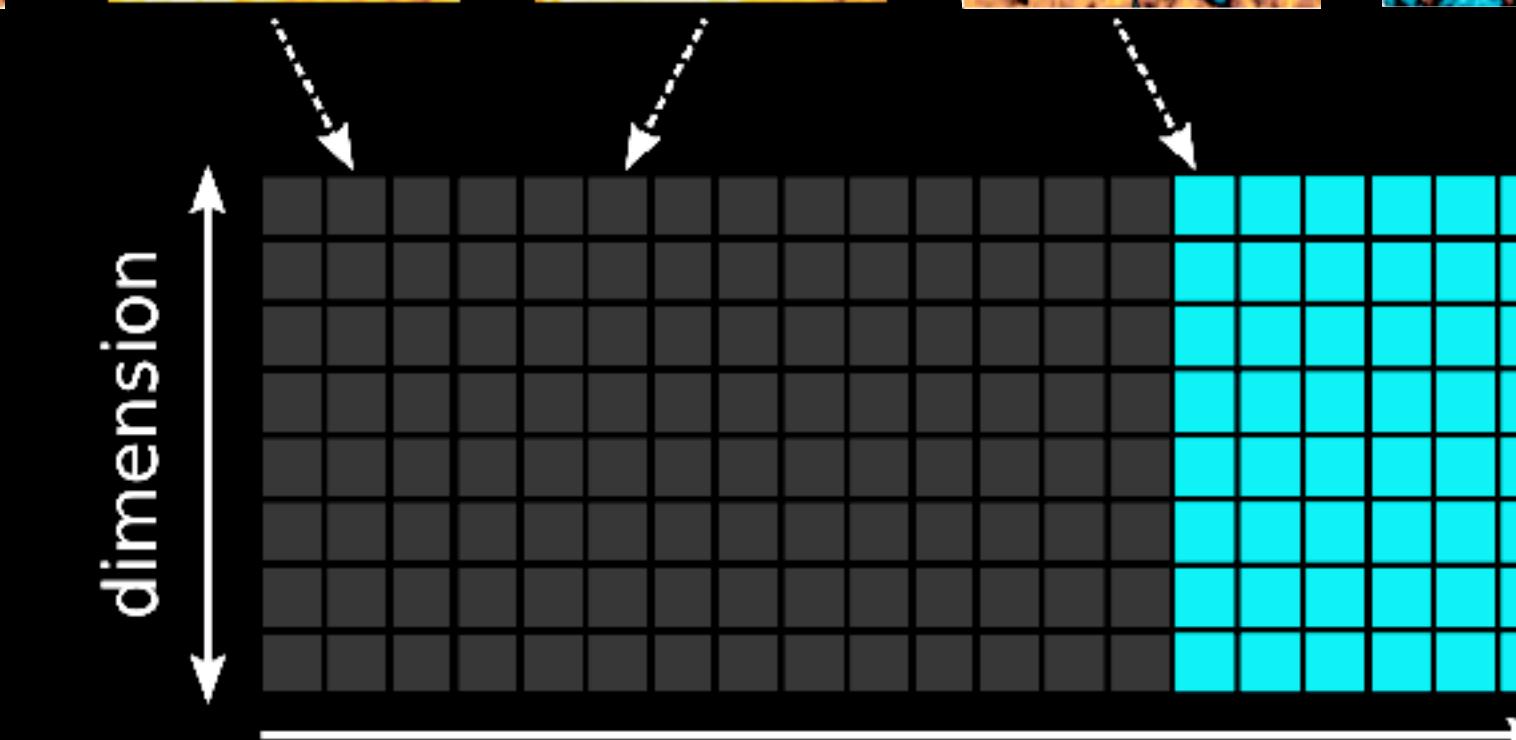


(c) Shallow Decoder



snapshot index, t

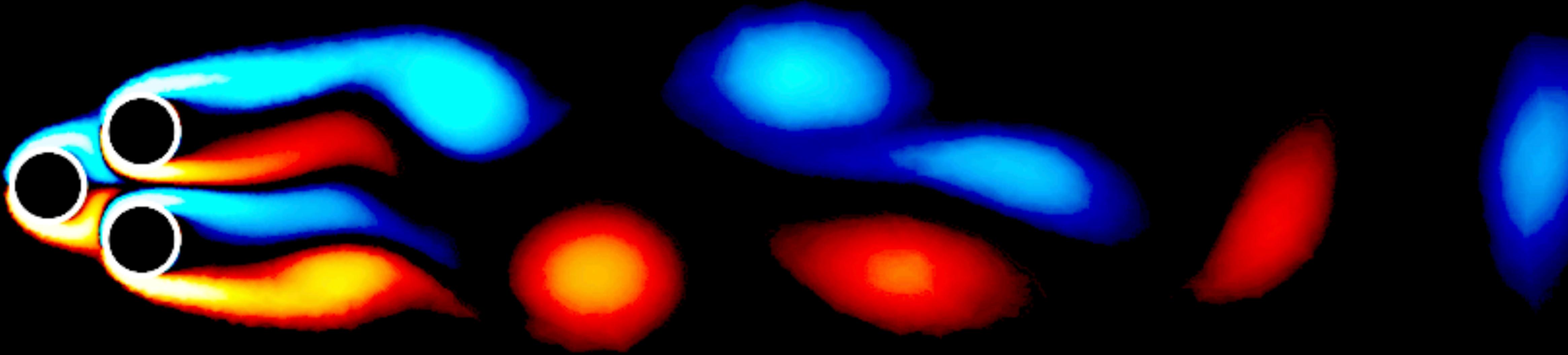
(a) Interpolation



snapshot index, t

(b) Extrapolation

REDUCED ORDER MODELS





**There is a need for
INTERPRETABLE and GENERALIZABLE
Machine Learning**

© Ilya Nesterov

$$\mathbf{F} = m\mathbf{a}$$



**There is a need for
INTERPRETABLE and GENERALIZABLE
Machine Learning**

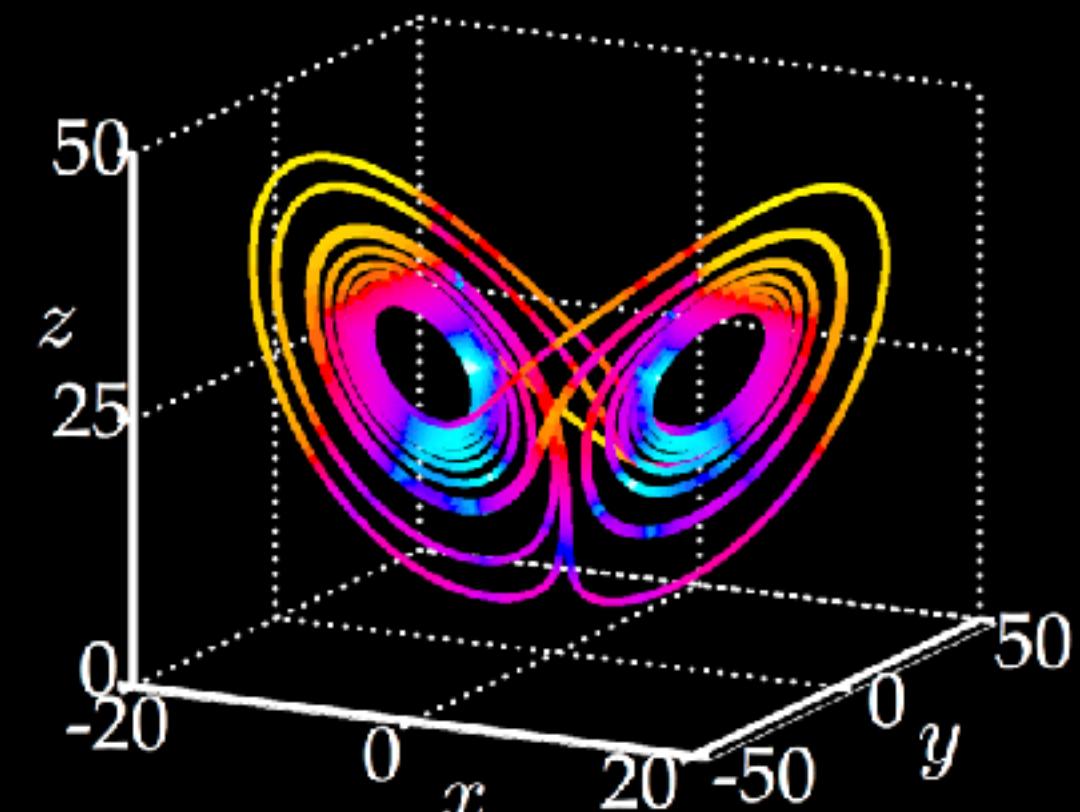
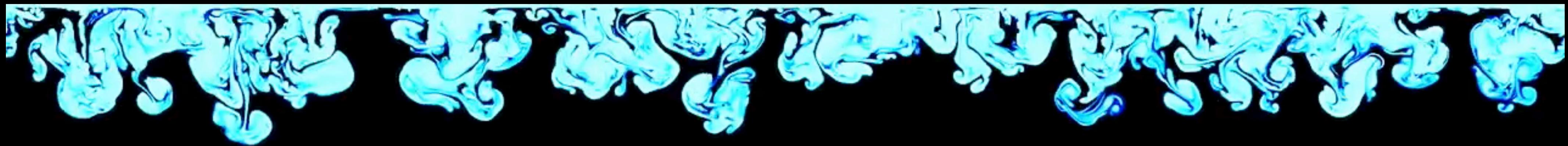
**EVERYTHING SHOULD BE MADE
AS SIMPLE AS POSSIBLE,
BUT NOT SIMPLER.**

Albert Einstein

There is a need for INTERPRETABLE and GENERALIZABLE Machine Learning

- **SPARSE**
- **LOW-DIMENSIONAL**
- **ROBUST**

CHAOTIC THERMAL CONVECTION



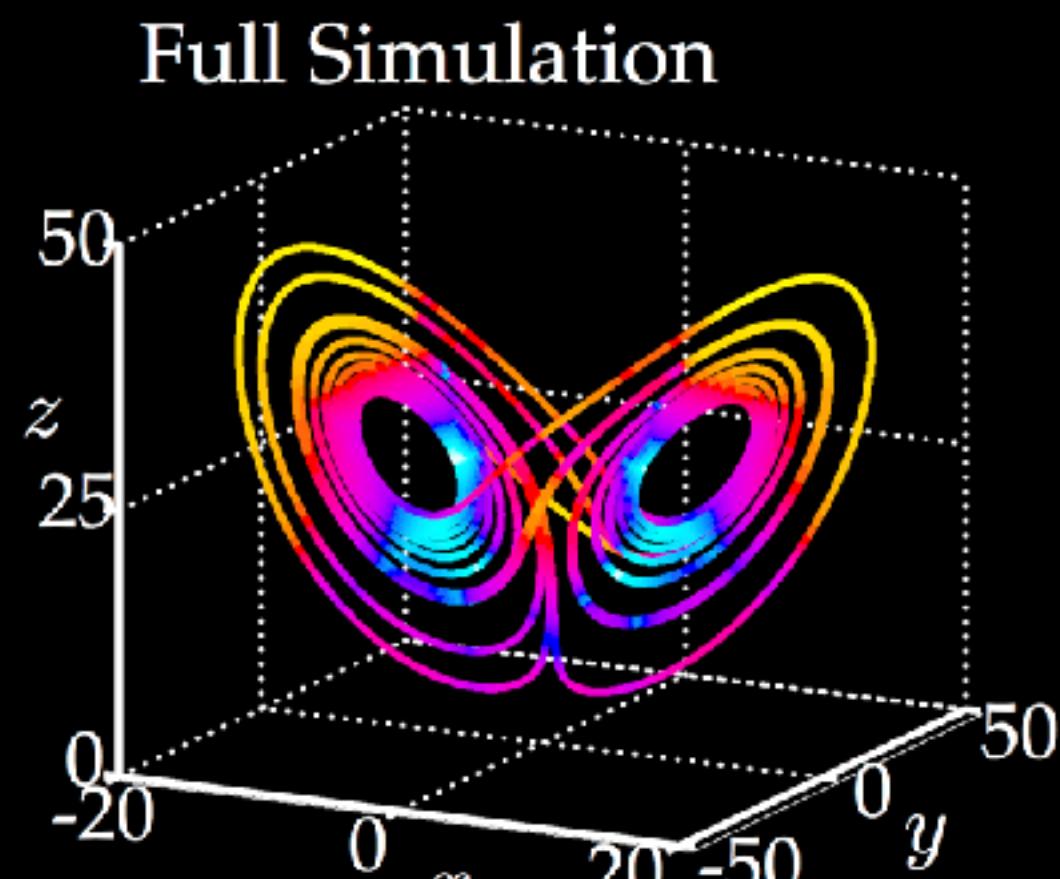
$$\dot{x} = \sigma(y - x)$$

$$\dot{y} = x(\rho - z) - y$$

$$\dot{z} = xy - \beta z.$$

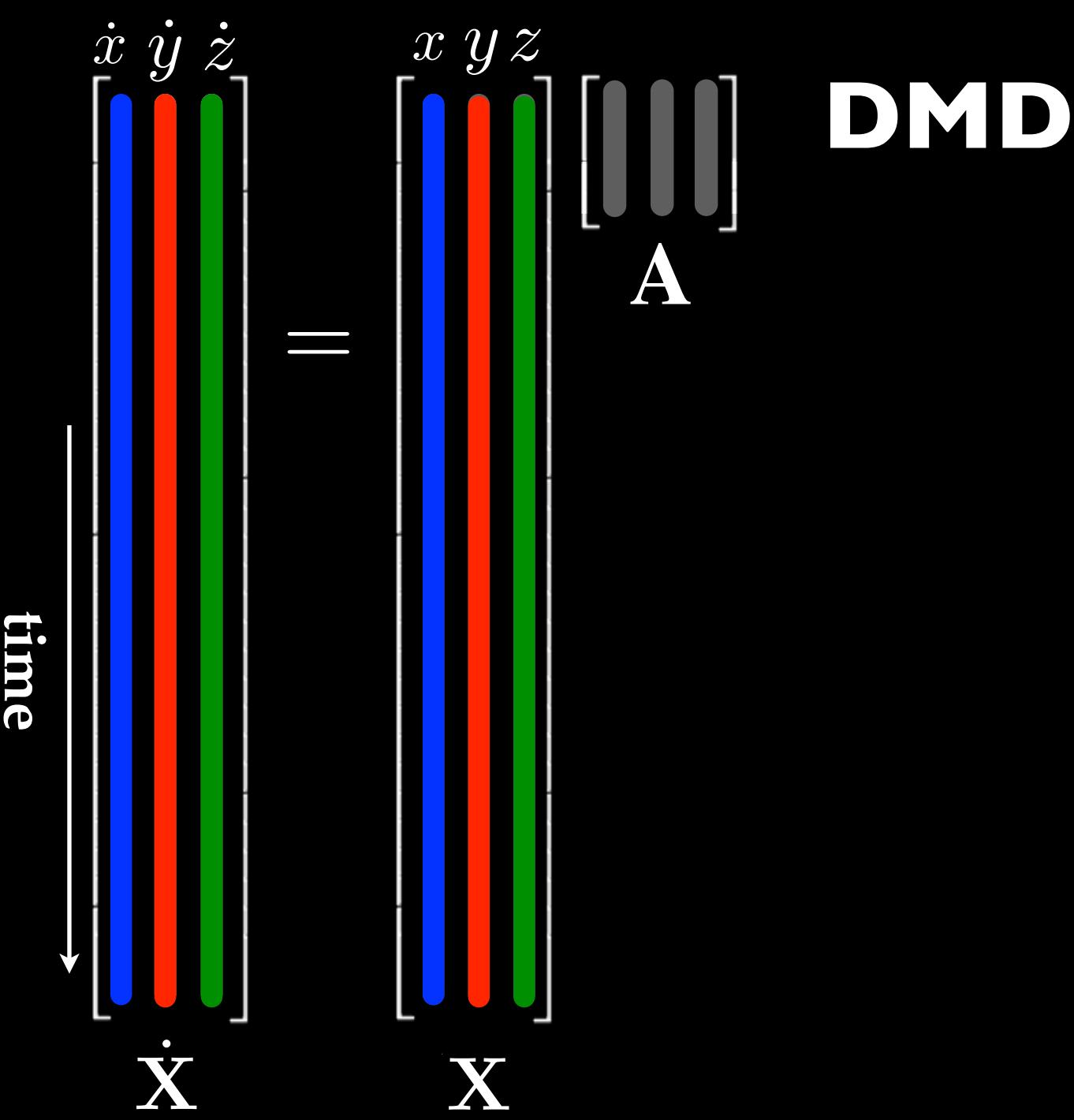


Sparse Identification of Nonlinear Dynamics (SINDy)



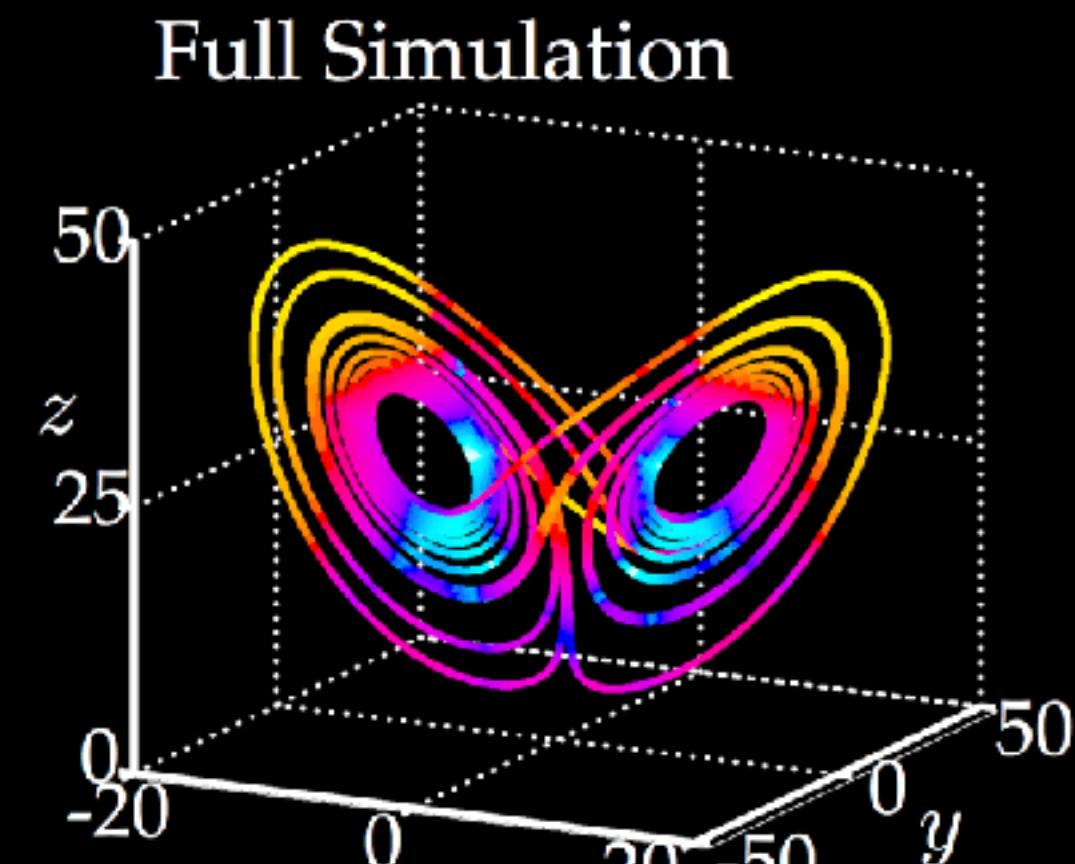
$$\begin{aligned}\dot{x} &= \sigma(y - x) \\ \dot{y} &= x(\rho - z) - y \\ \dot{z} &= xy - \beta z.\end{aligned}$$

Data



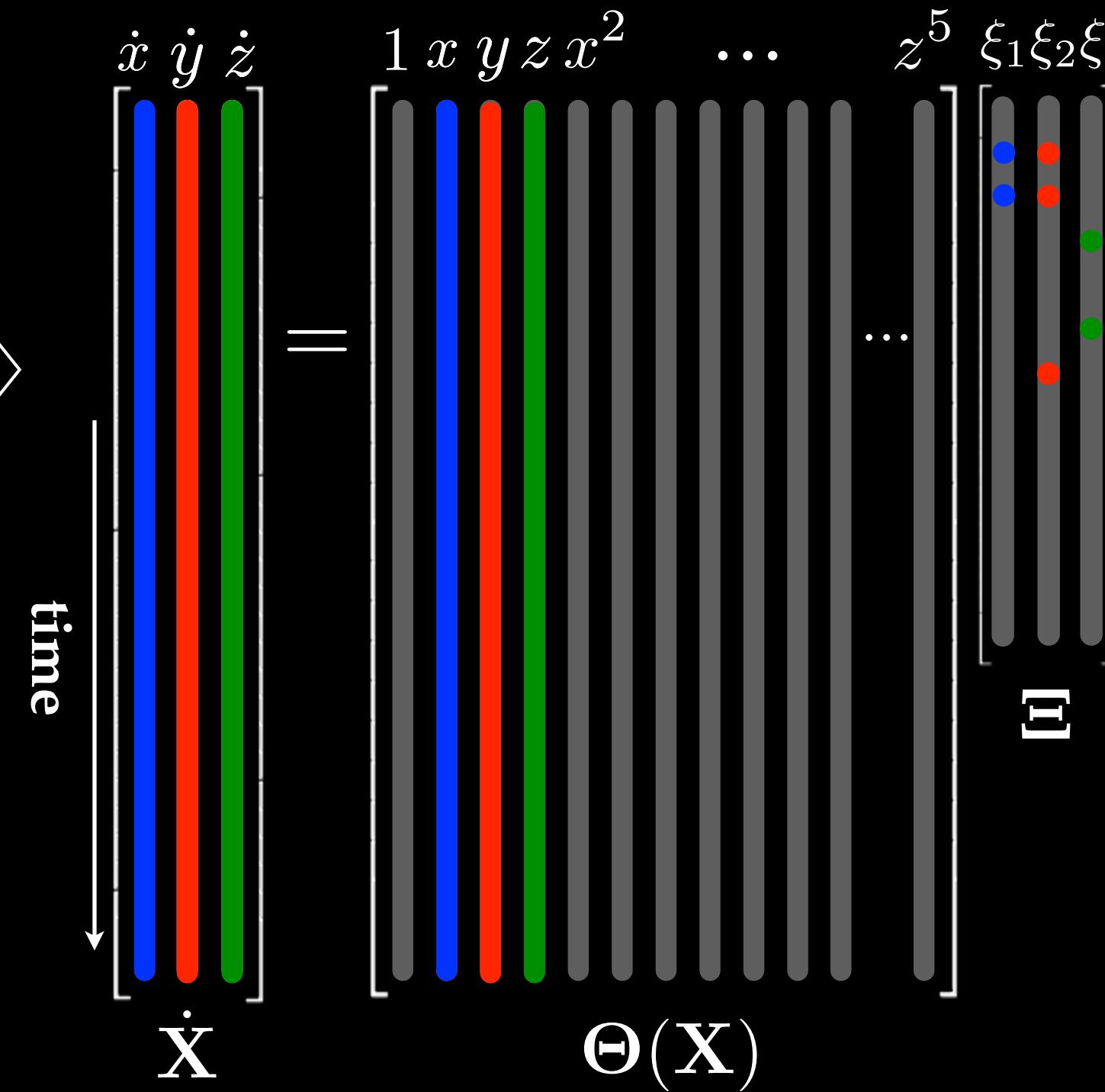
DMD

Sparse Identification of Nonlinear Dynamics (SINDy)

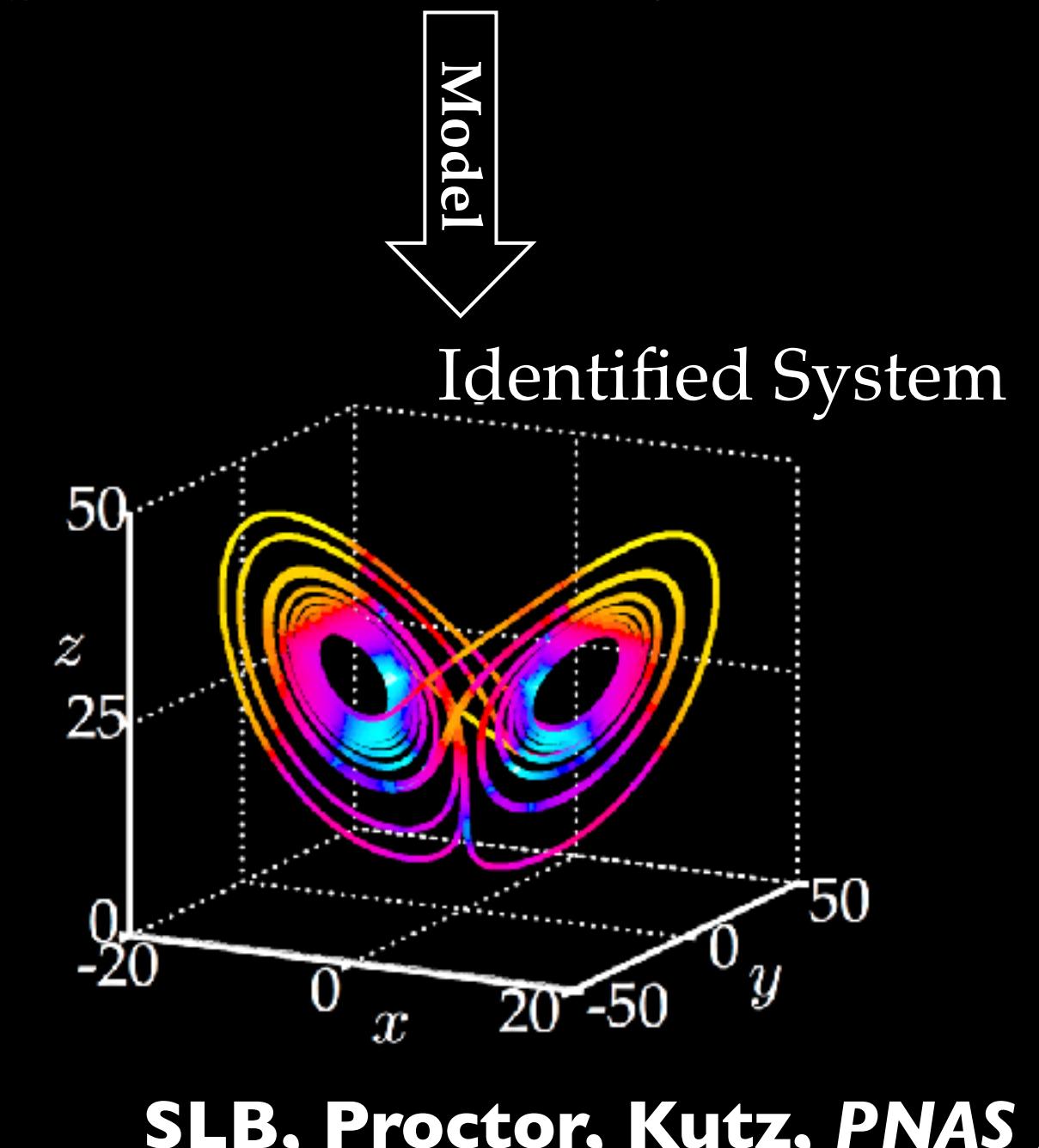
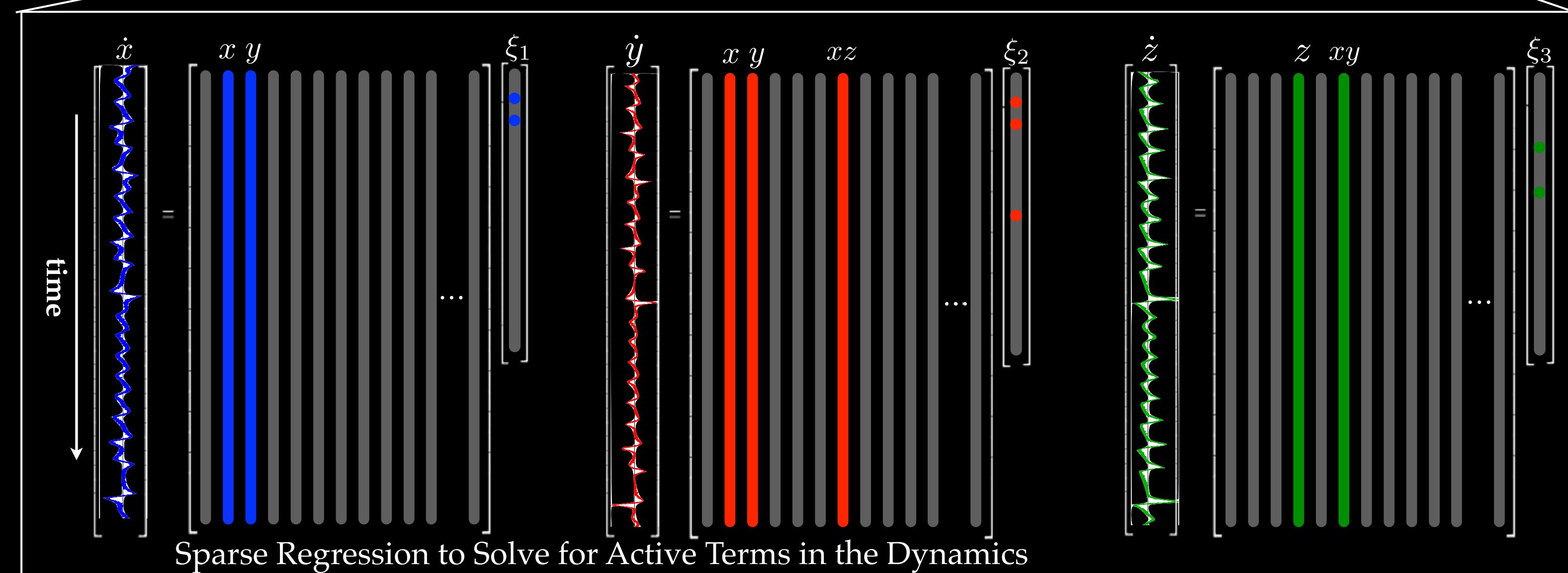
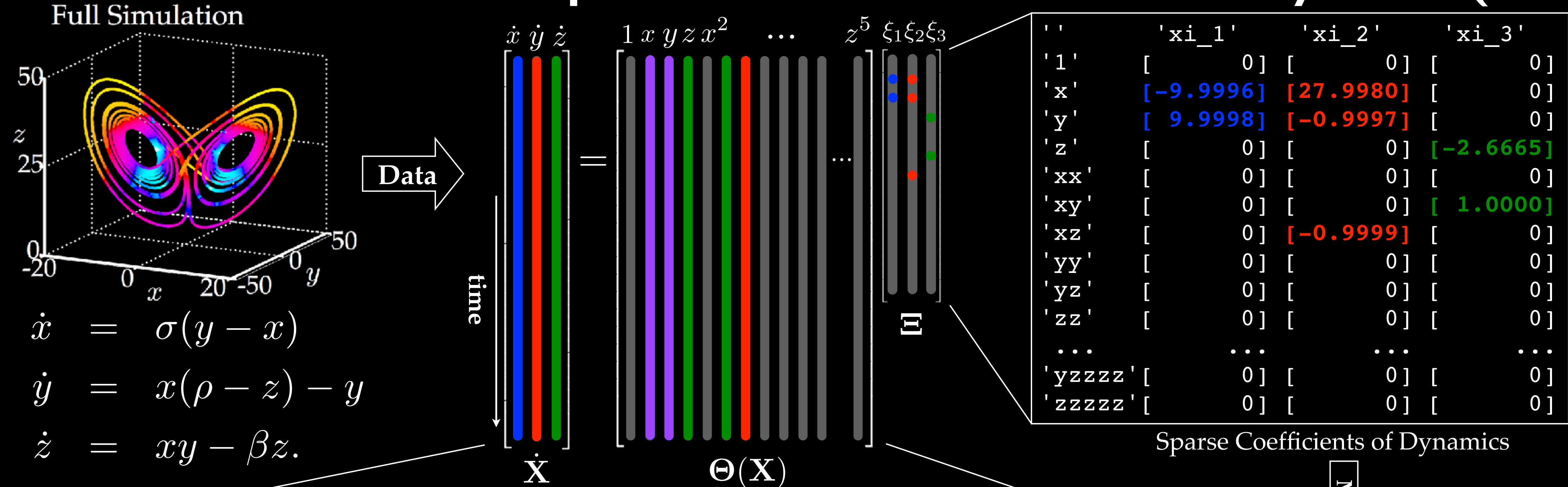


$$\begin{aligned}\dot{x} &= \sigma(y - x) \\ \dot{y} &= x(\rho - z) - y \\ \dot{z} &= xy - \beta z.\end{aligned}$$

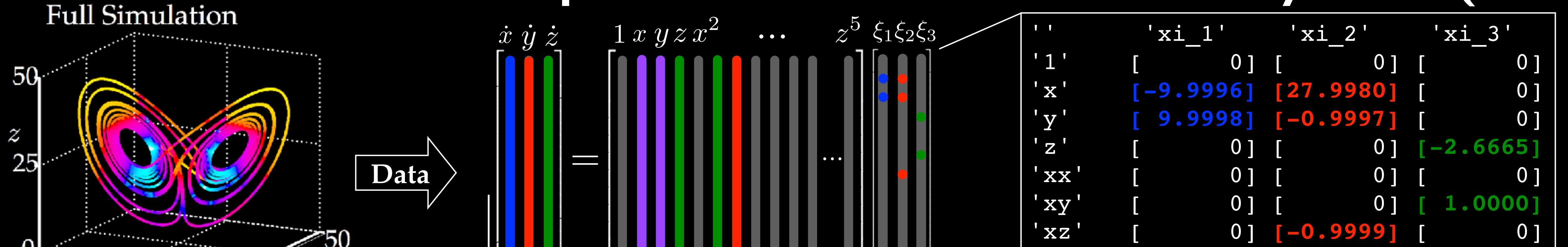
Data



Sparse Identification of Nonlinear Dynamics (SINDy)



Sparse Identification of Nonlinear Dynamics (SINDy)

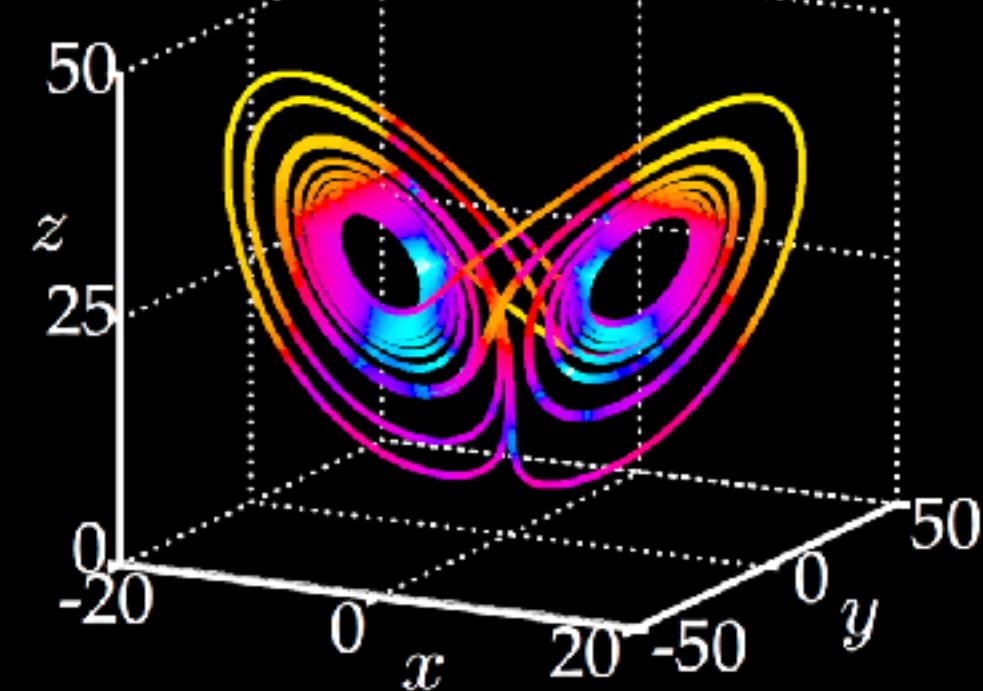
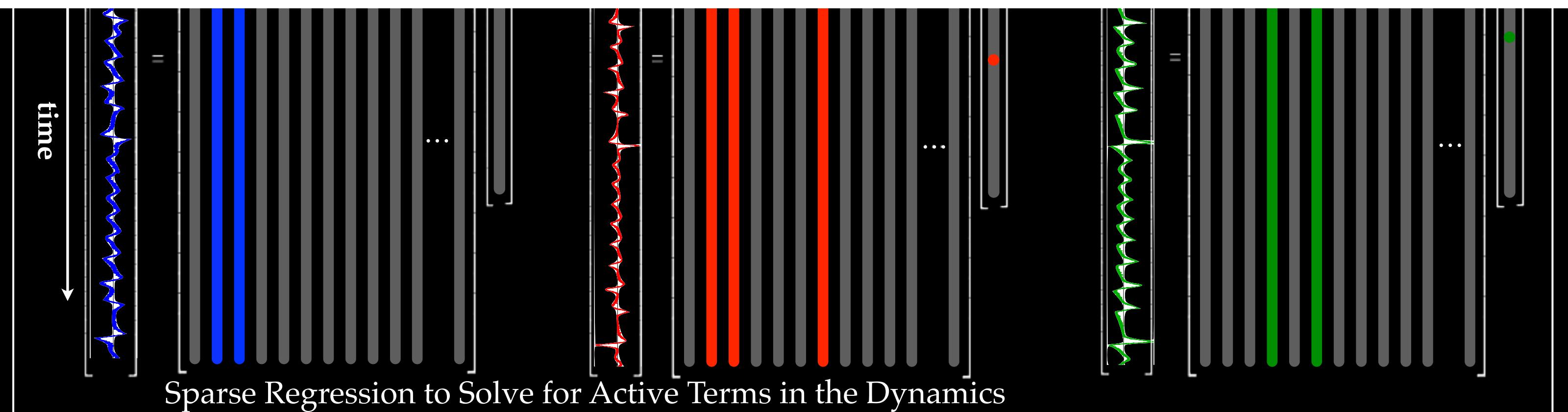


PySINDy

OPEN-SOURCE SOFTWARE

Build CI passing docs passing pypi package 1.0.0 codecov 95% JOSS 10.21105/joss.02104 DOI 10.5281/zenodo.3832319

PySINDy is a sparse regression package with several implementations for the Sparse Identification of Nonlinear Dynamical systems (SINDy) method introduced in Brunton et al. (2016a), including the unified optimization approach of Champion et al. (2019) and SINDy with control from Brunton et al. (2016b). A comprehensive literature review is given in de Silva et al. (2020).



SLB, Proctor, Kutz, PNAS 2016.

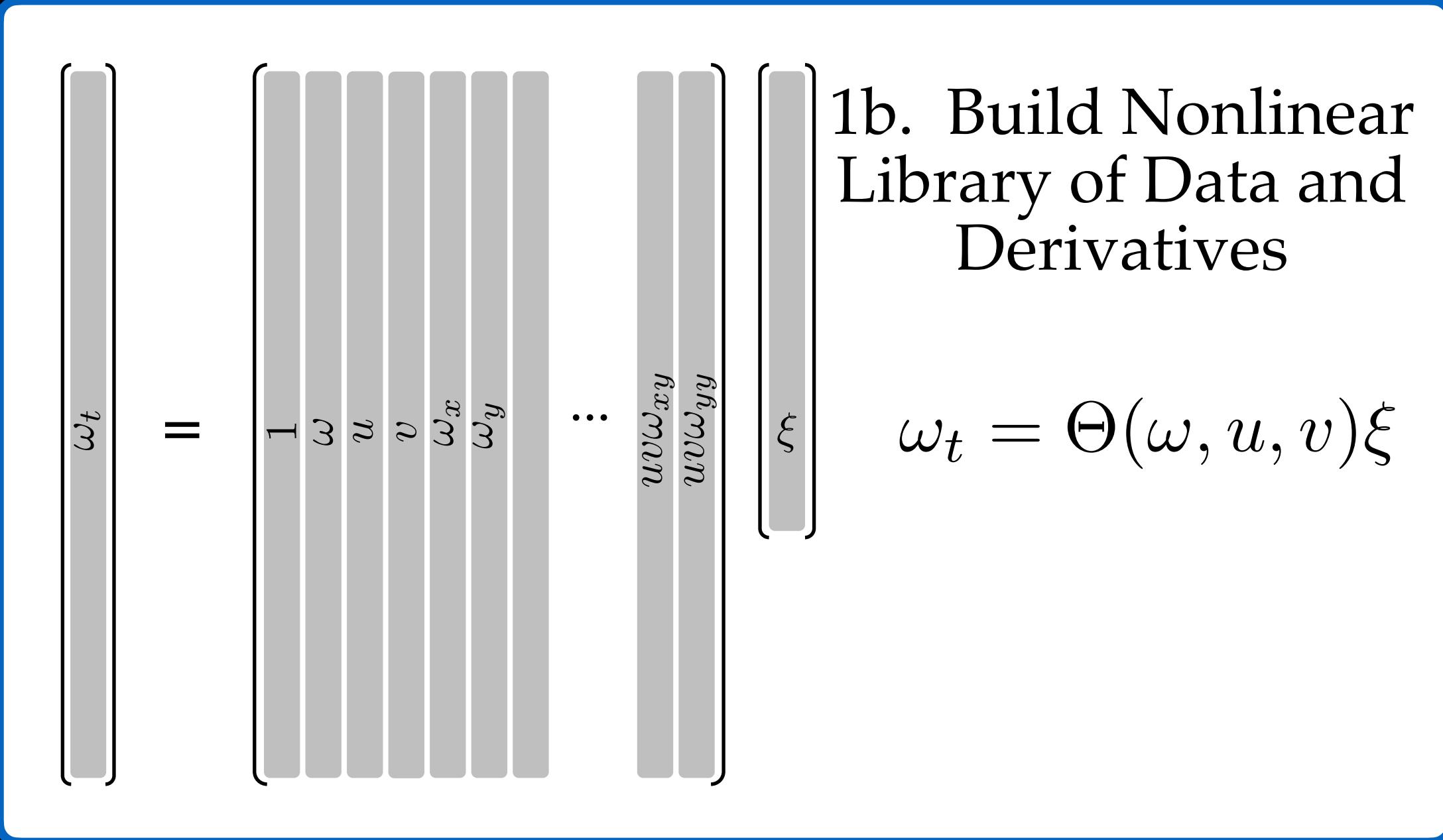
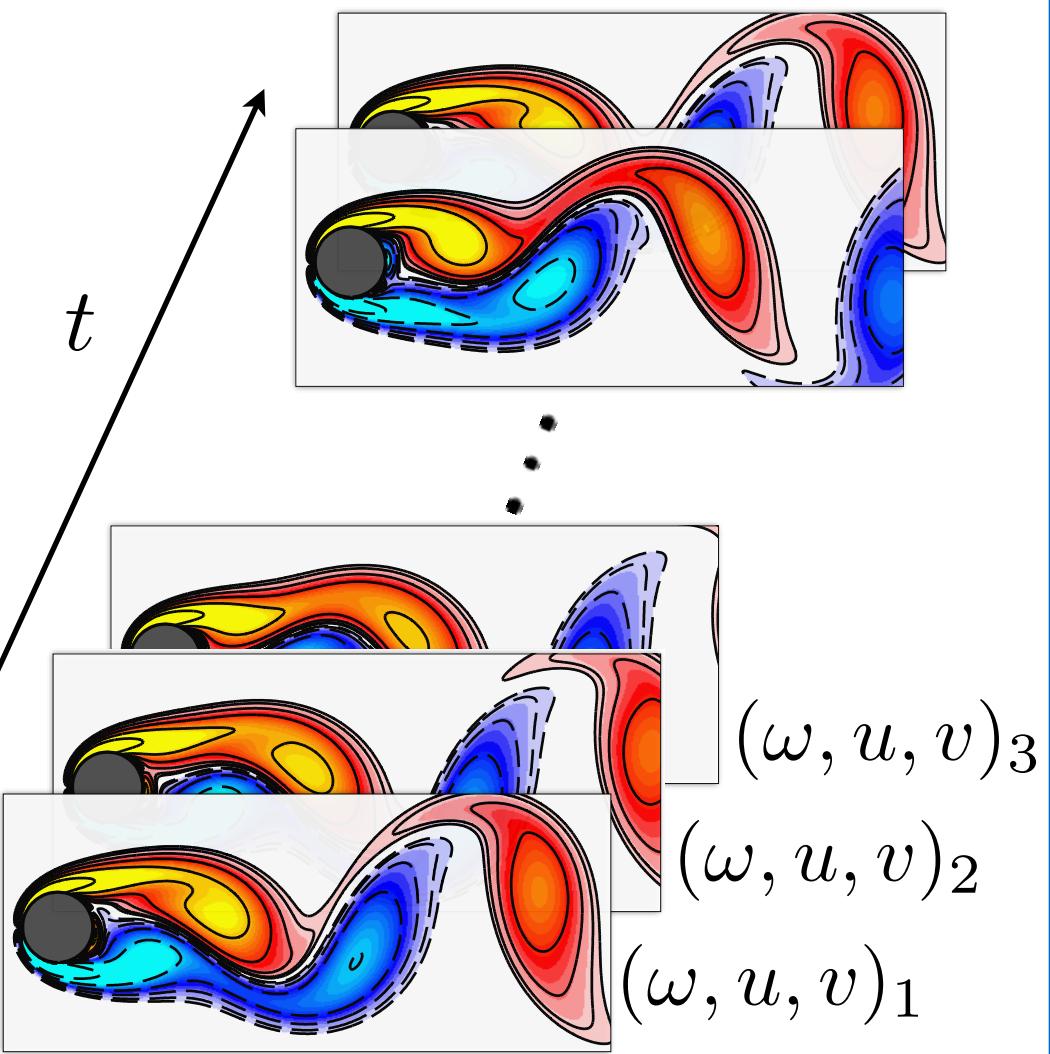
PDEs

Rudy, SLB, Proctor, Kutz
Science Advances, 2017



Full Data

1a. Data Collection



1c. Solve Sparse Regression

$$\arg \min_{\xi} \|\Theta \xi - \omega_t\|_2^2 + \lambda \|\xi\|_0$$



d. Identified Dynamics

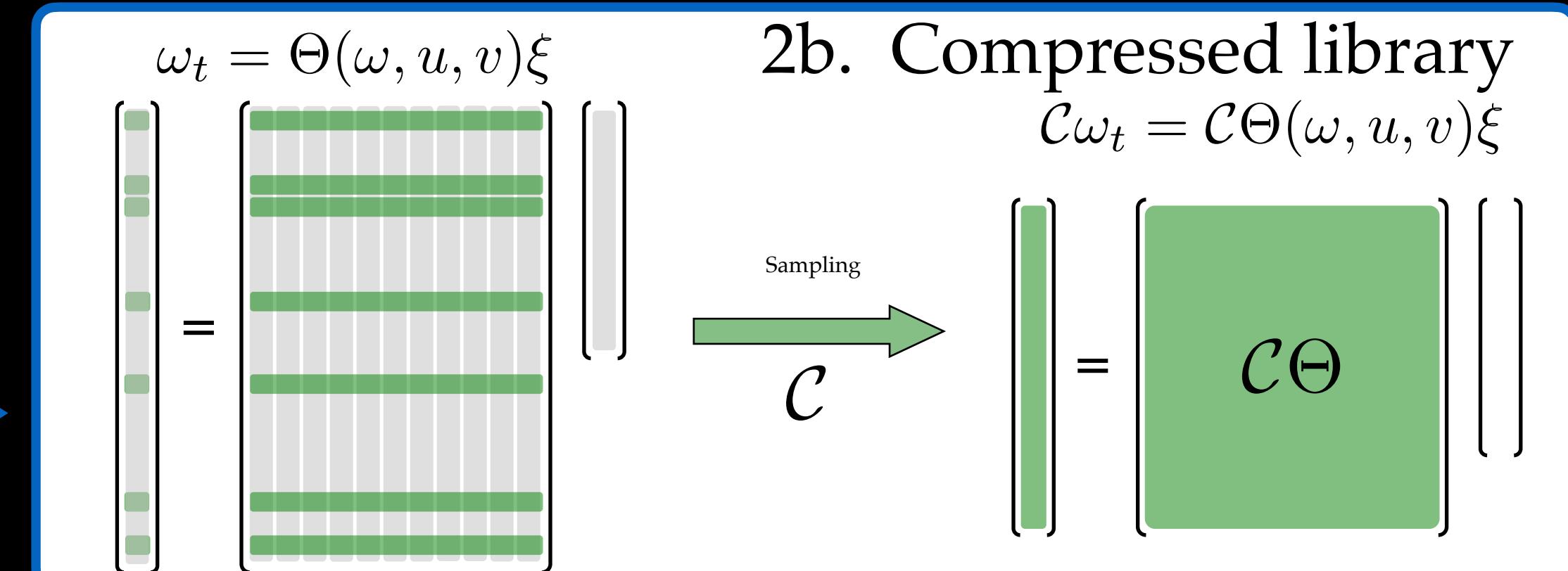
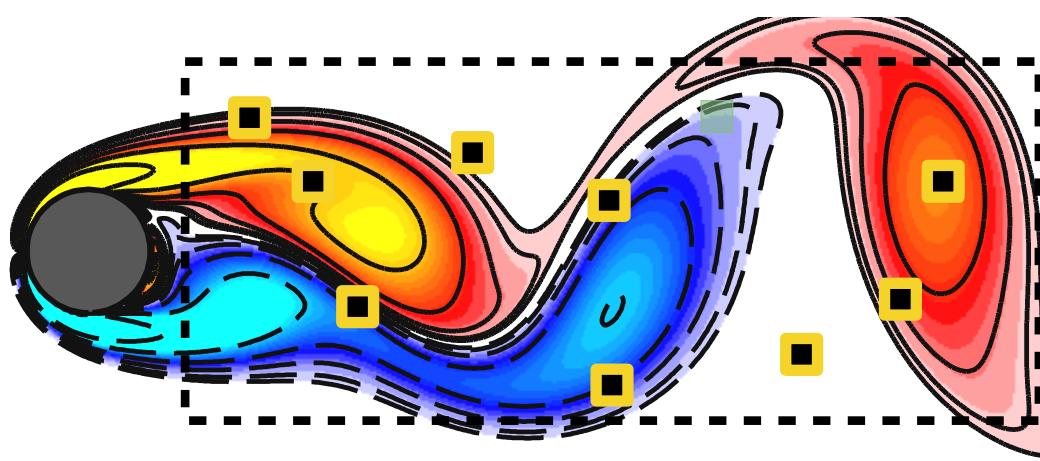
$$\begin{aligned} \omega_t + 0.9931u\omega_x + 0.9910v\omega_y \\ = 0.0099\omega_{xx} + 0.0099\omega_{yy} \end{aligned}$$

Compare to True
Navier Stokes ($Re = 100$)

$$\omega_t + (\mathbf{u} \cdot \nabla) \omega = \frac{1}{Re} \nabla^2 \omega$$

Compressed Data

2a. Subsample Data

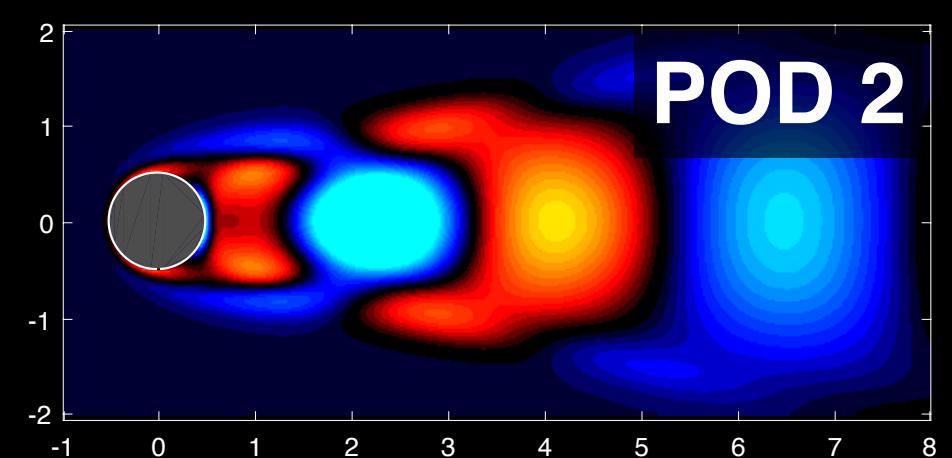
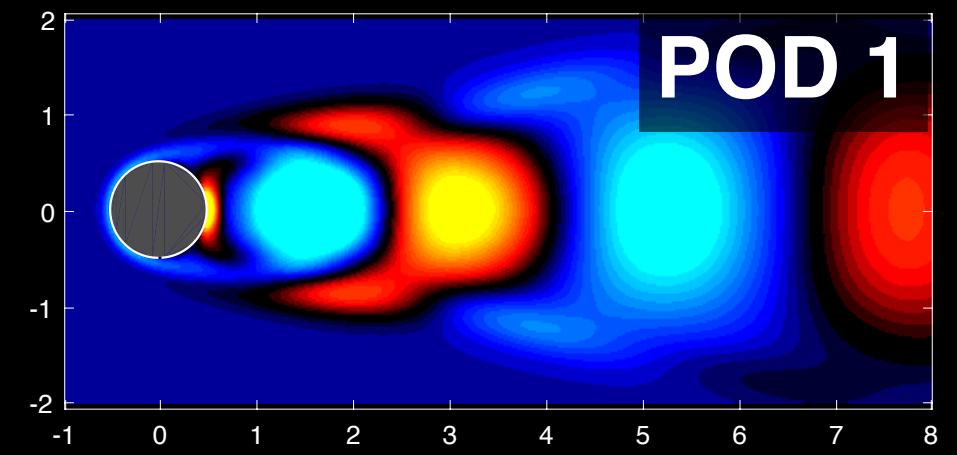
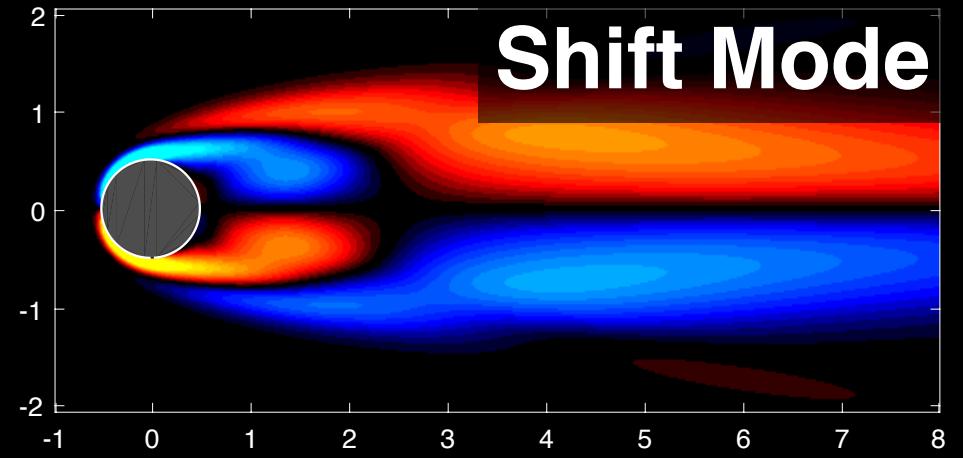


2c. Solve Compressed Sparse Regression

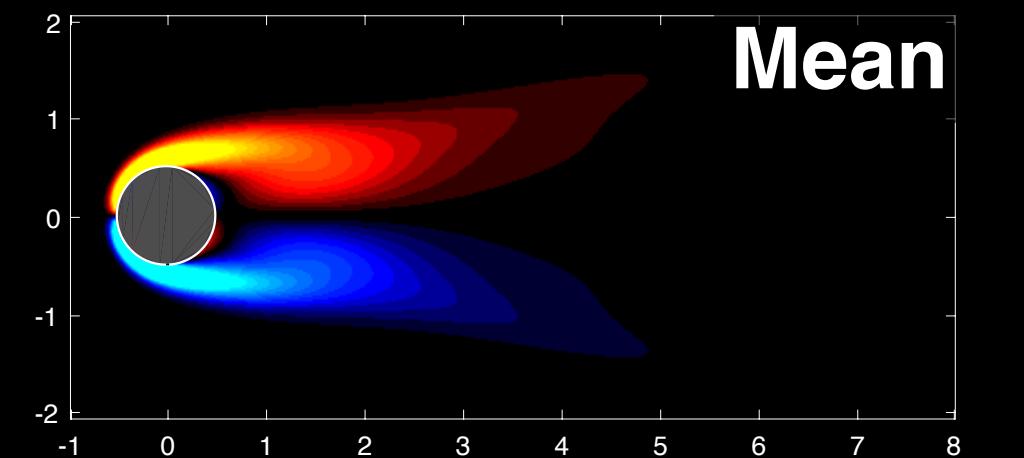
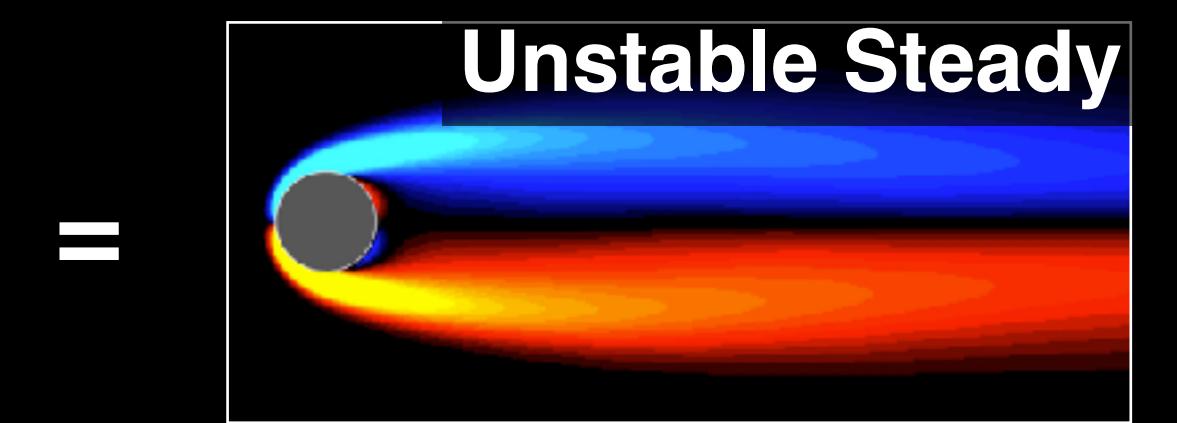
$$\arg \min_{\xi} \|C\Theta \xi - C\omega_t\|_2^2 + \lambda \|\xi\|_0$$



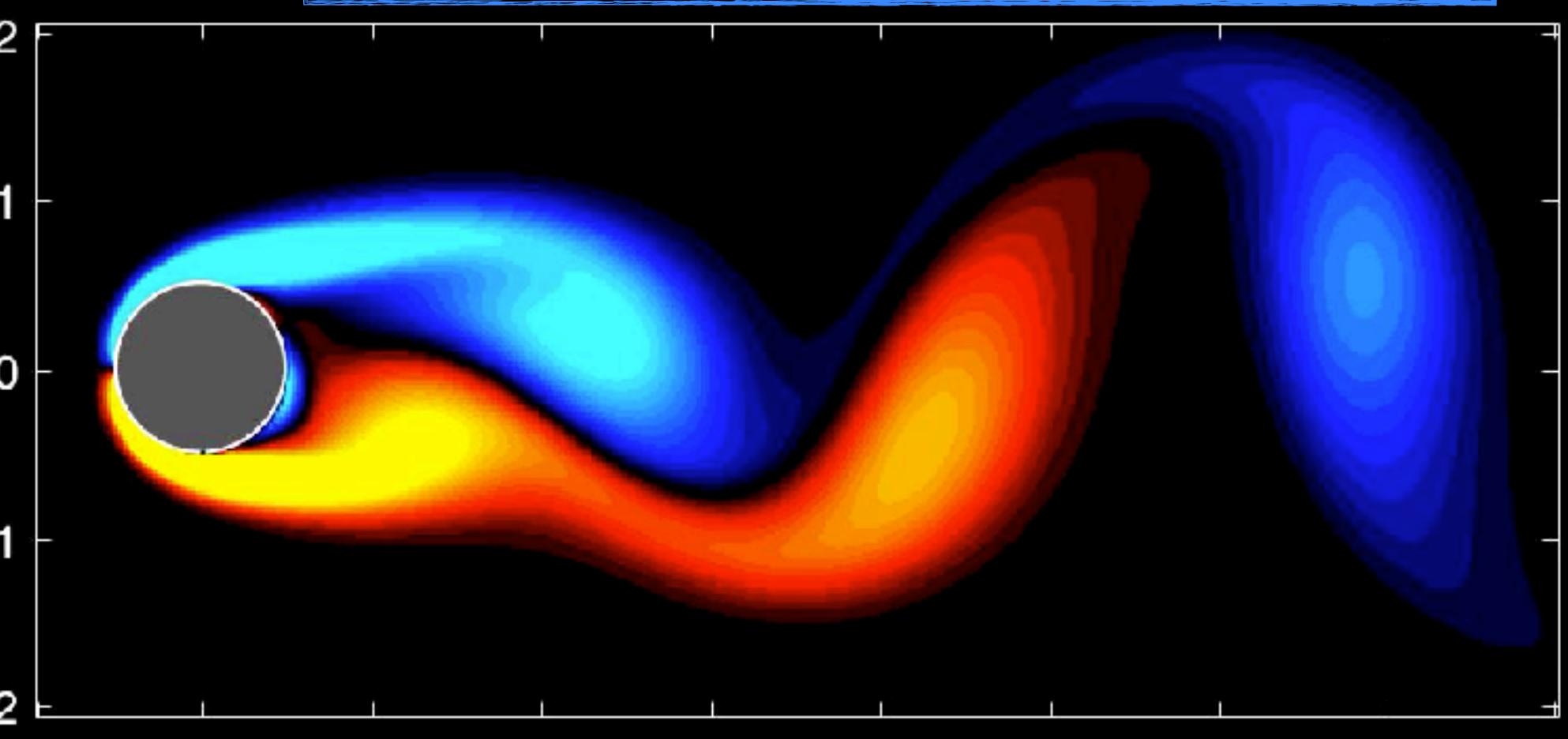
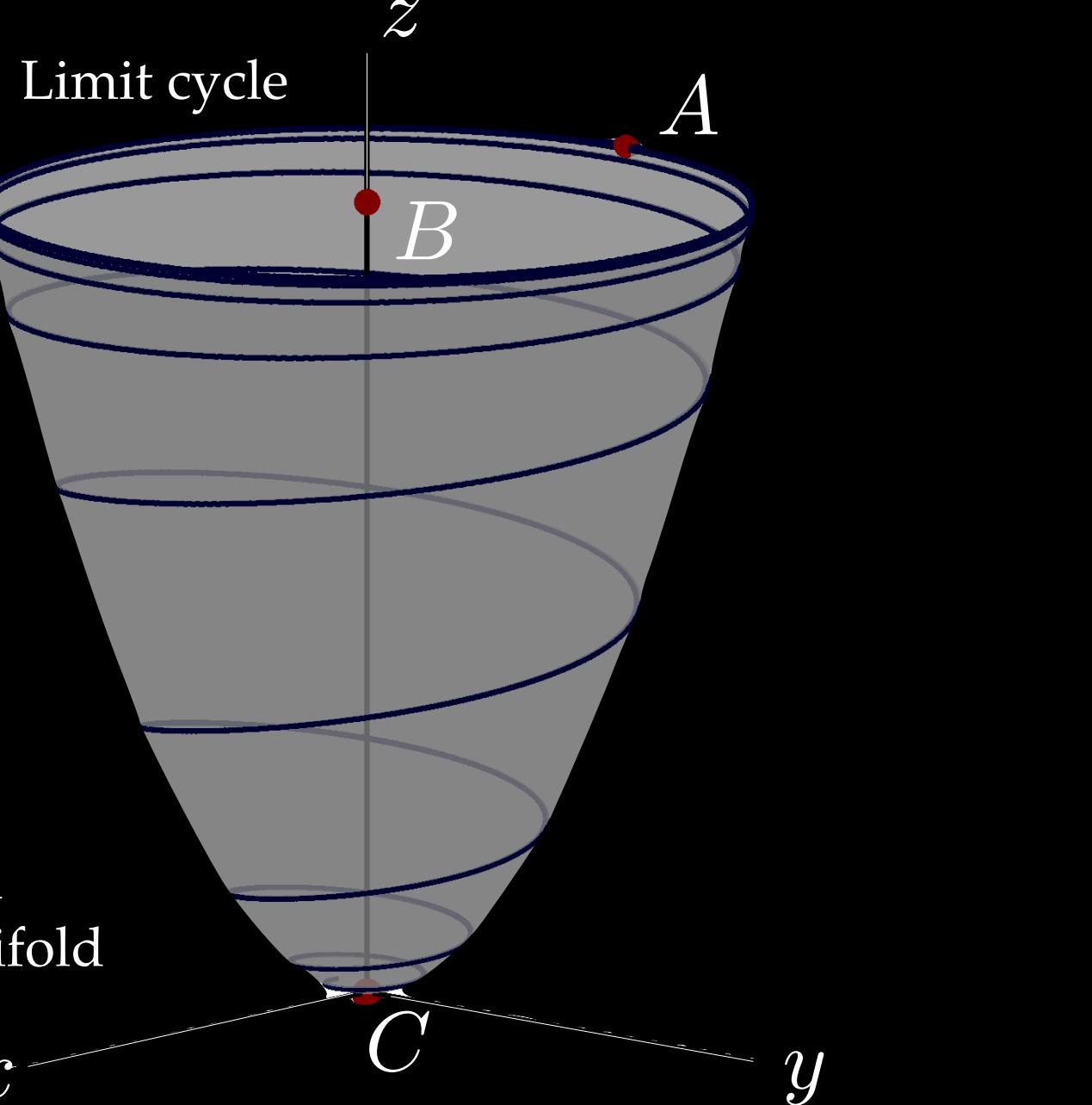
REDUCED ORDER MODELS



Noack et al., JFM 2003.

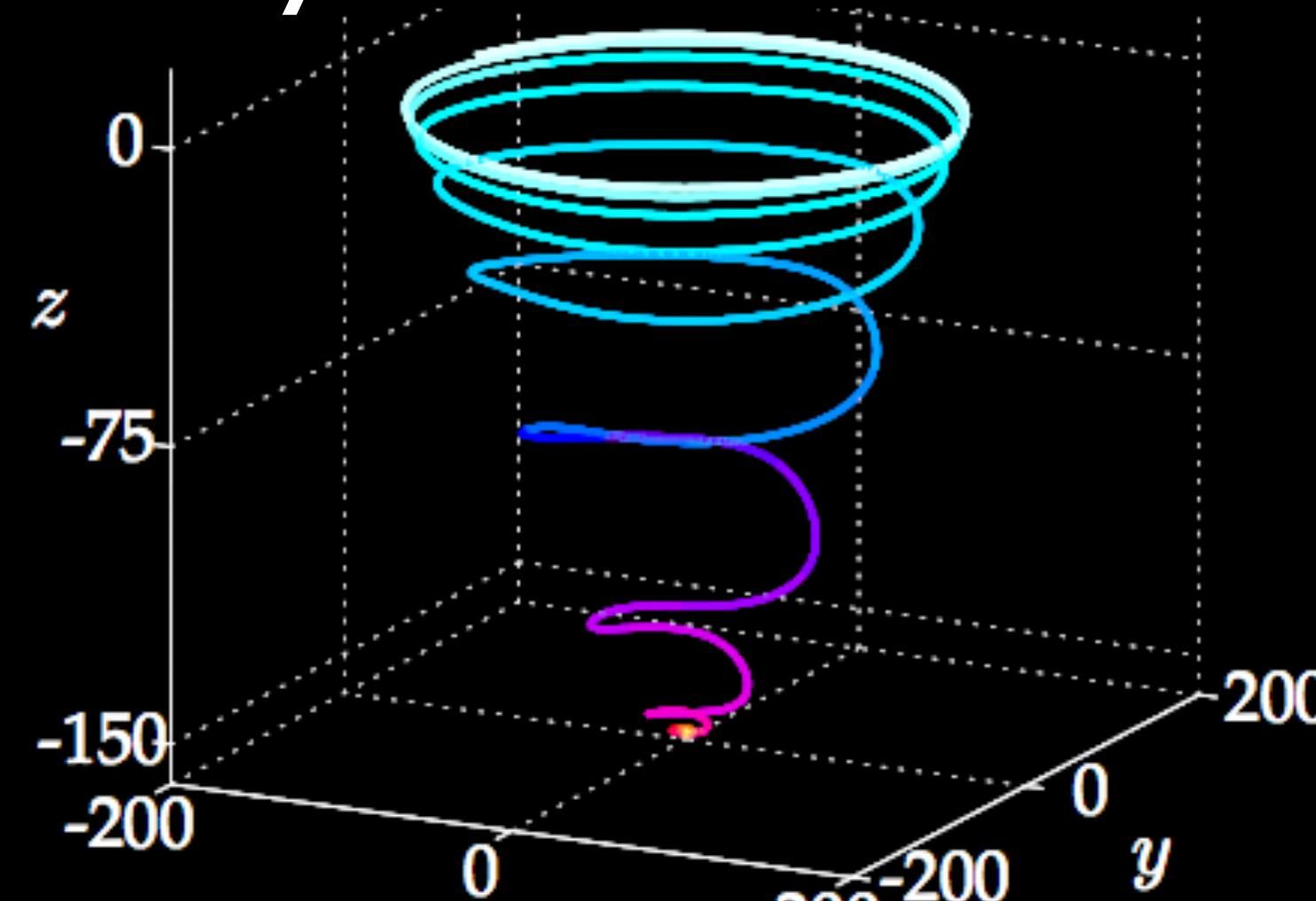


$$\begin{aligned}\dot{x} &= \mu x - \omega y + Axz \\ \dot{y} &= \omega x + \mu y + Ayz \\ \dot{z} &= -\lambda(z - x^2 - y^2).\end{aligned}$$

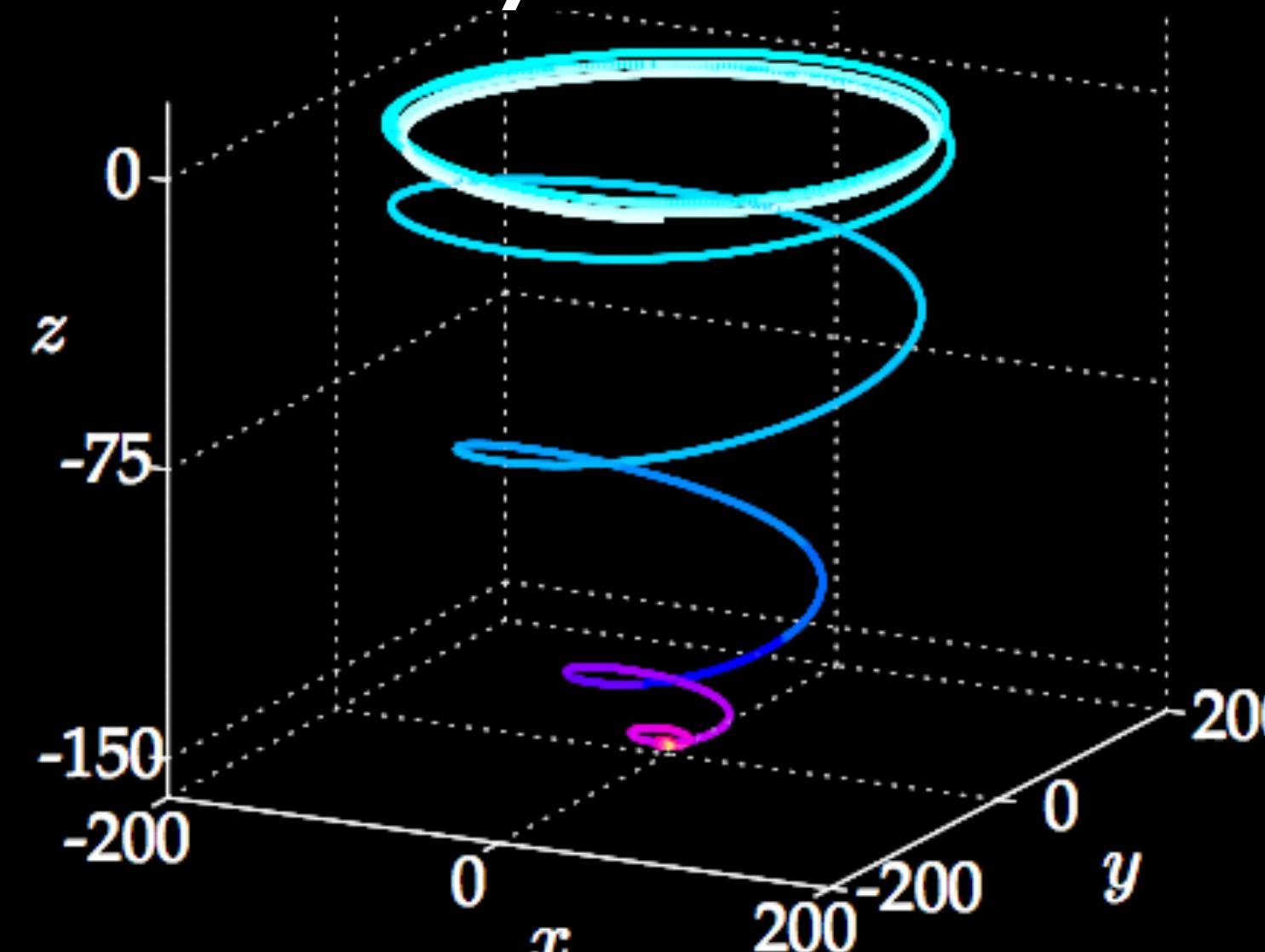


Sparse Identification of Nonlinear Dynamics (SINDy)

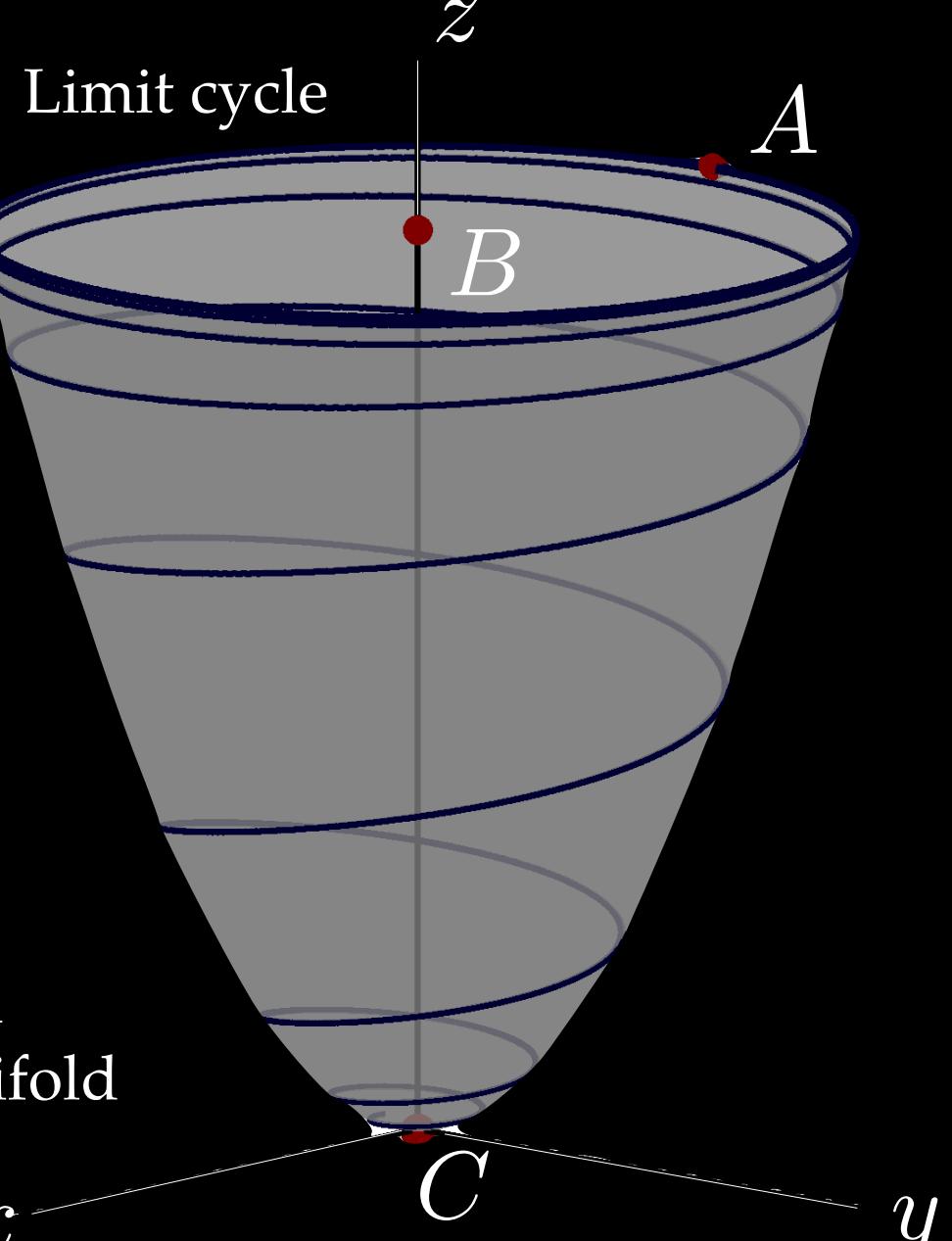
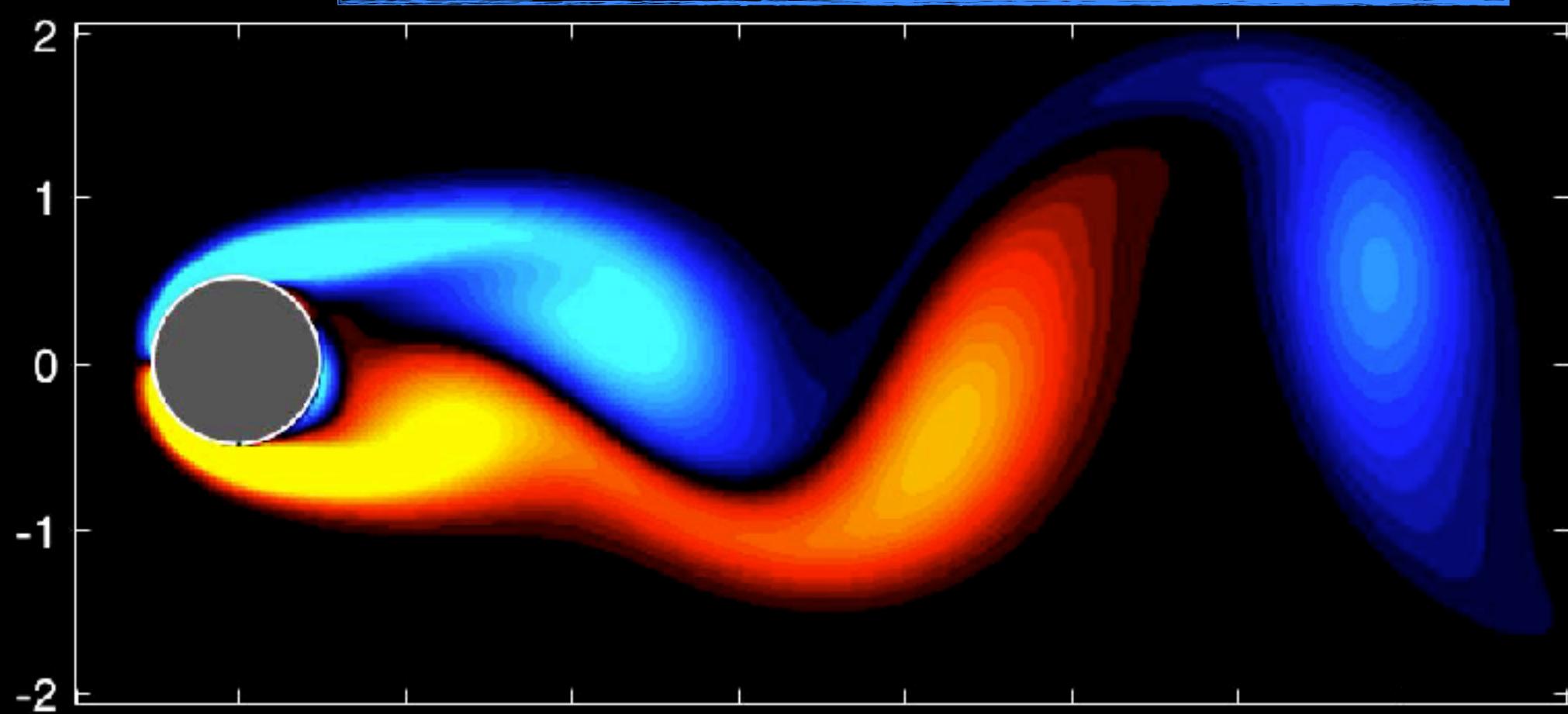
Full System



Identified System



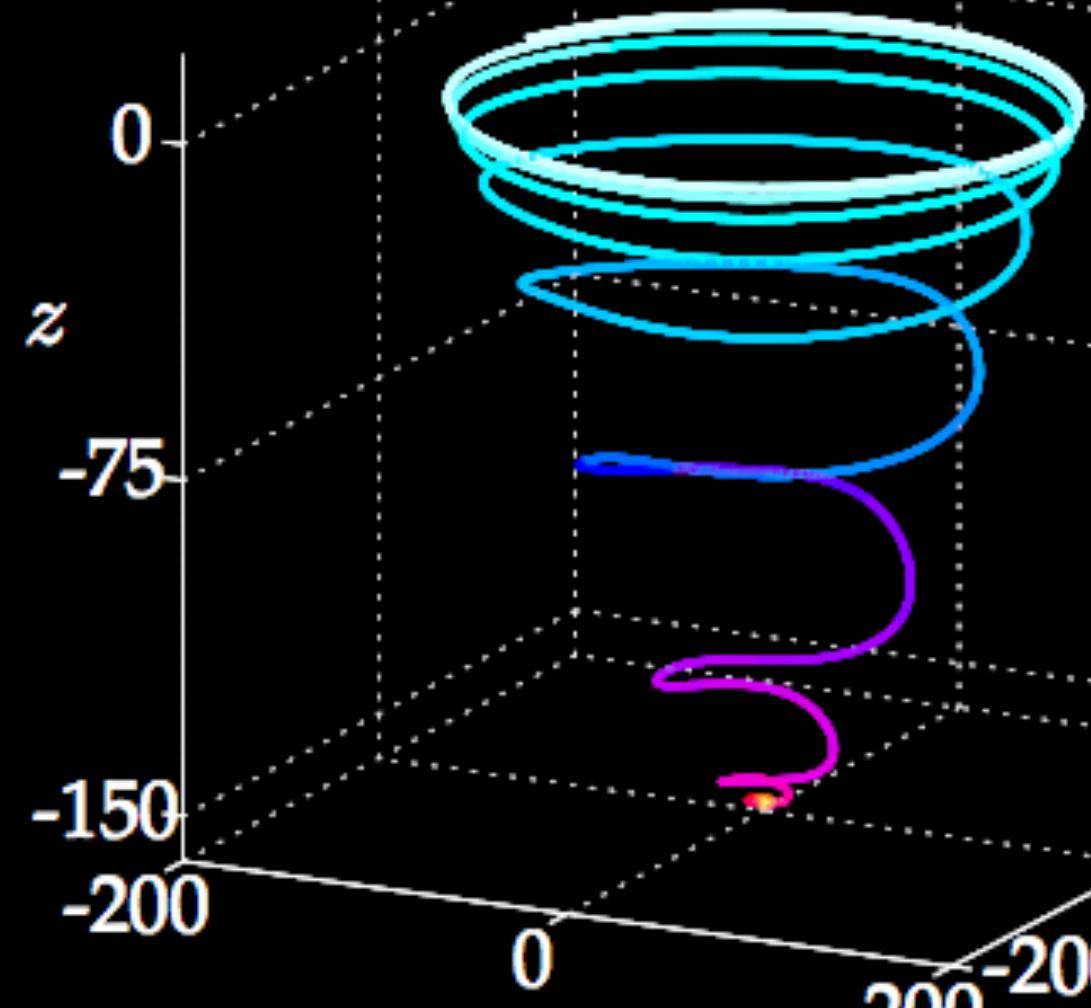
$$\begin{bmatrix} \dot{x} & \dot{y} & \dot{z} \\ \end{bmatrix} = \begin{bmatrix} 1 & x & y & z & x^2 & xy & xz & y^2 & yz & z^2 \\ \end{bmatrix} \begin{bmatrix} \xi_1 & \xi_2 & \xi_3 \\ \end{bmatrix} + \dots + \begin{bmatrix} \cdot & \cdot & \cdot \\ \end{bmatrix} [E] \Theta(X)$$



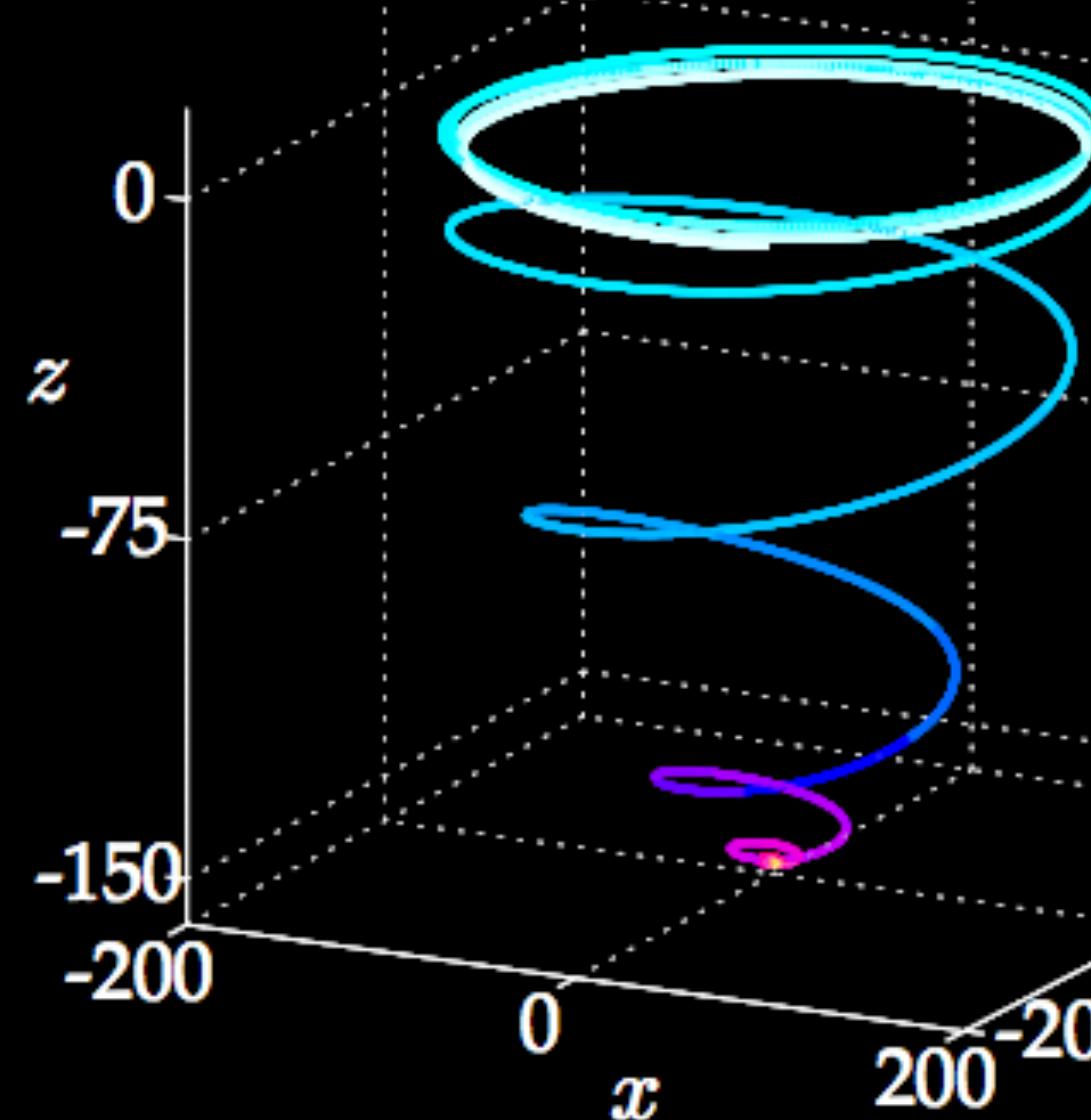
$$\begin{aligned} \dot{x} &= \mu x - \omega y + Axz \\ \dot{y} &= \omega x + \mu y + Ayz \\ \dot{z} &= -\lambda(z - x^2 - y^2). \end{aligned}$$

Sparse Identification of Nonlinear Dynamics (SINDy)

Full System



Identified System



Innovation 1: Enforcing known constraints

- ▶ Skew-symmetric quadratic nonlinearities to enforce energy conservation
- ▶ Improved stability

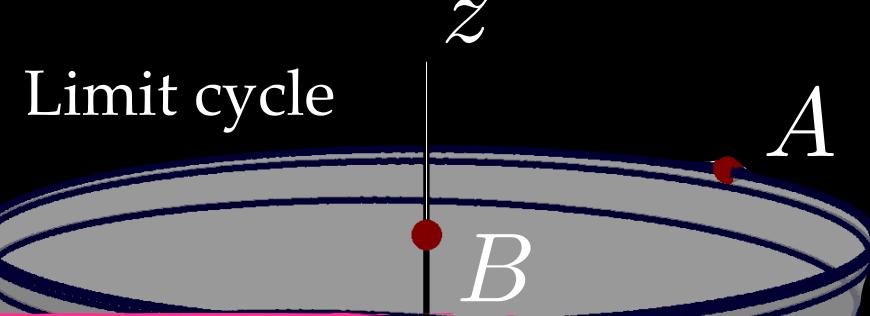
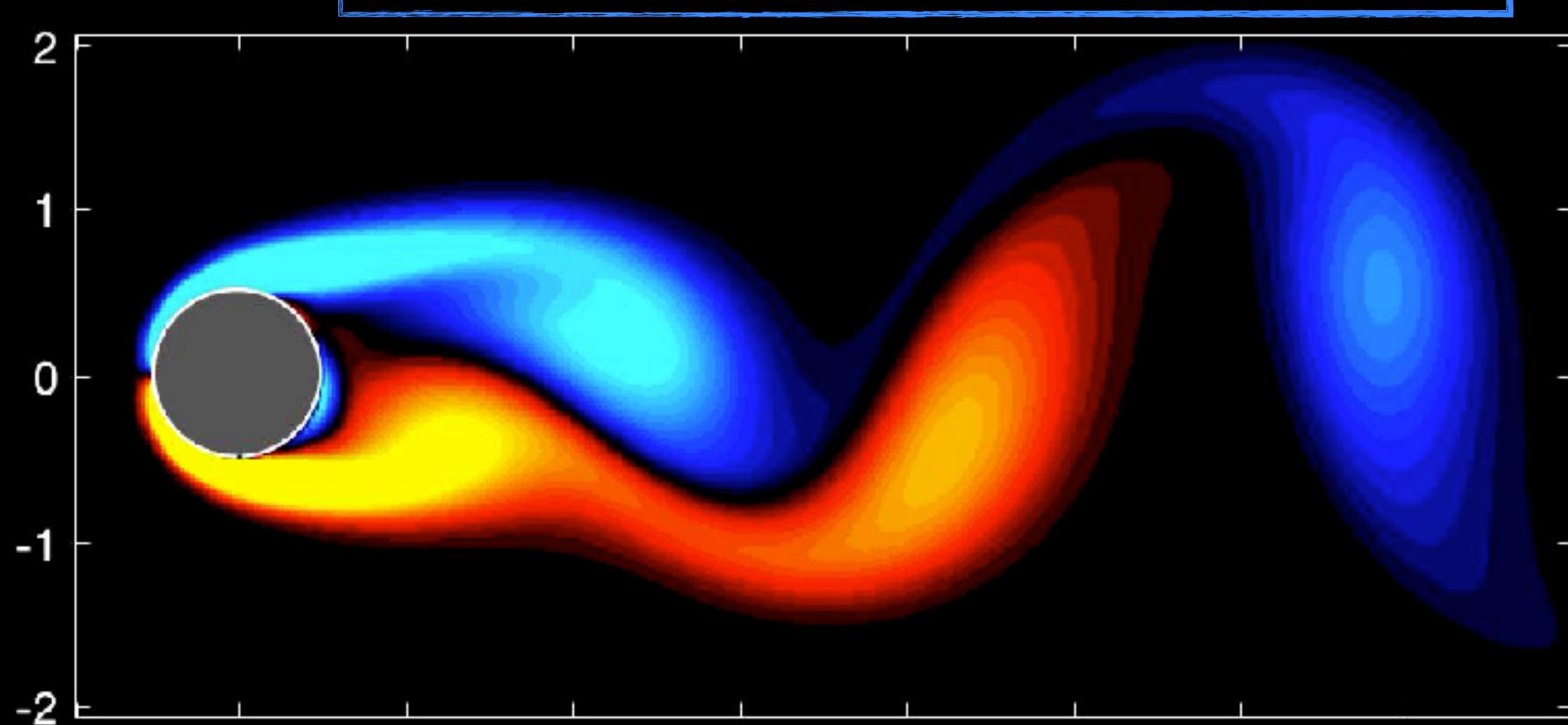
$$\min_{\xi, z} \|\Theta(X)\Xi - \dot{X}\|_2^2 + z^T(C\xi - d)$$



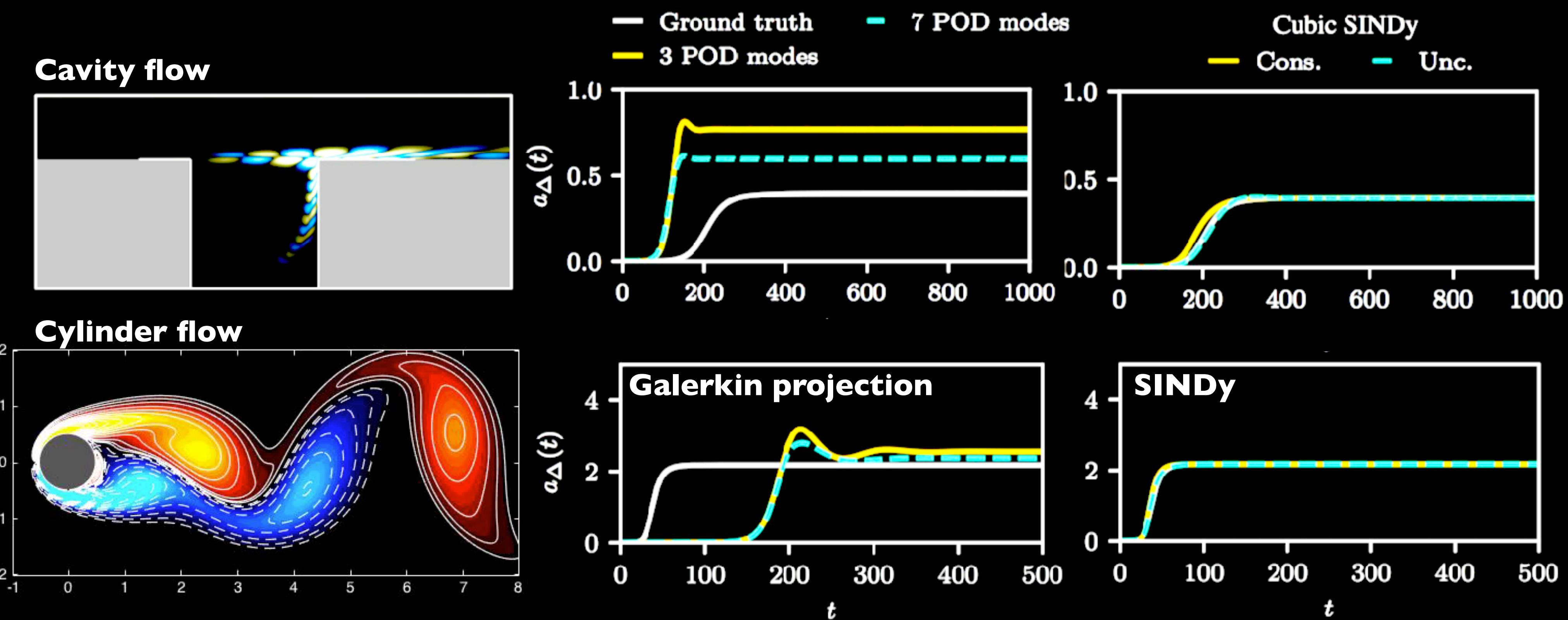
Innovation 2: Higher-order Nonlinearities

- ▶ Cubic, Quintic, Septic terms approximate truncated terms in Galerkin expansion

$$\begin{aligned} \dot{x} &= \mu x - \omega y + Axz \\ \dot{y} &= \omega x + \mu y + Ayz \\ \dot{z} &= -\lambda(z - x^2 - y^2). \end{aligned}$$



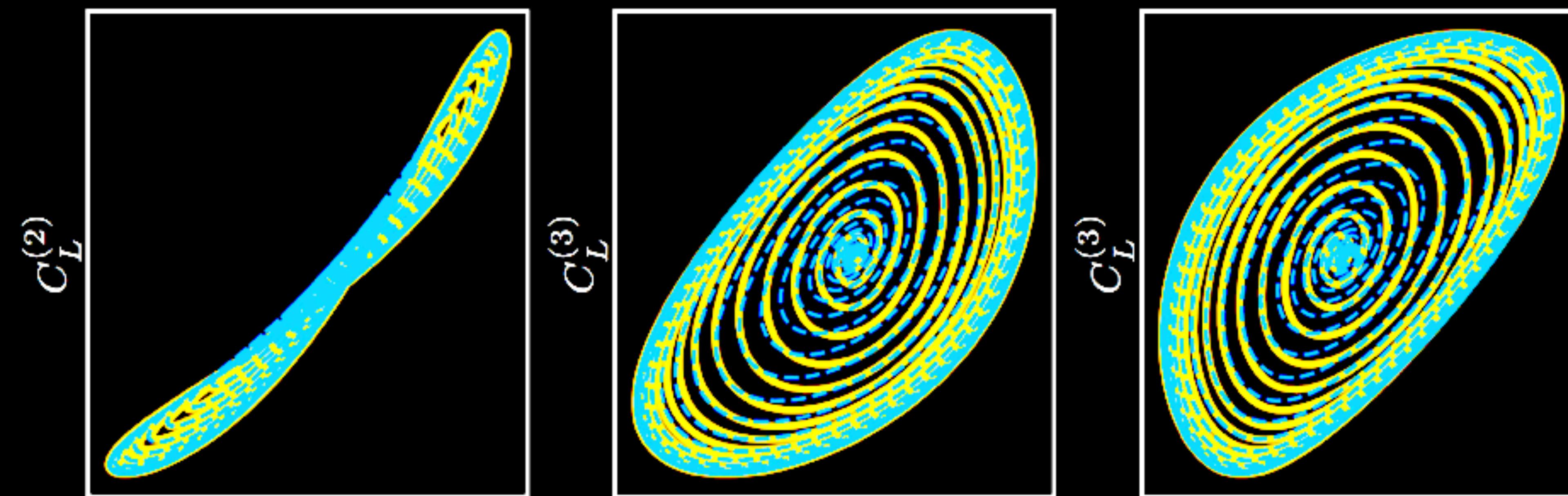
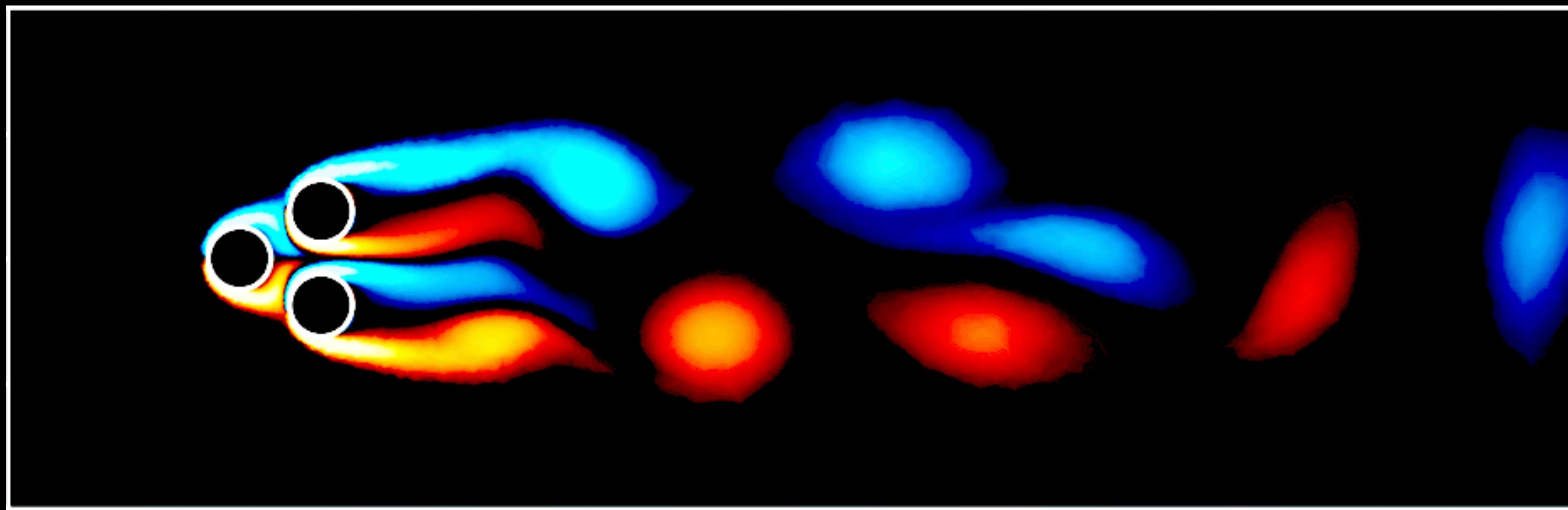
Constrained Sparse Galerkin Regression



$$\ddot{x} - \underbrace{(0.2 - 0.24x^2 - 0.15\dot{x}^2)}_{k(x, \dot{x})} \dot{x} + 1.26x = 0$$

Spring-Mass Damper with Nonlinear Damping!

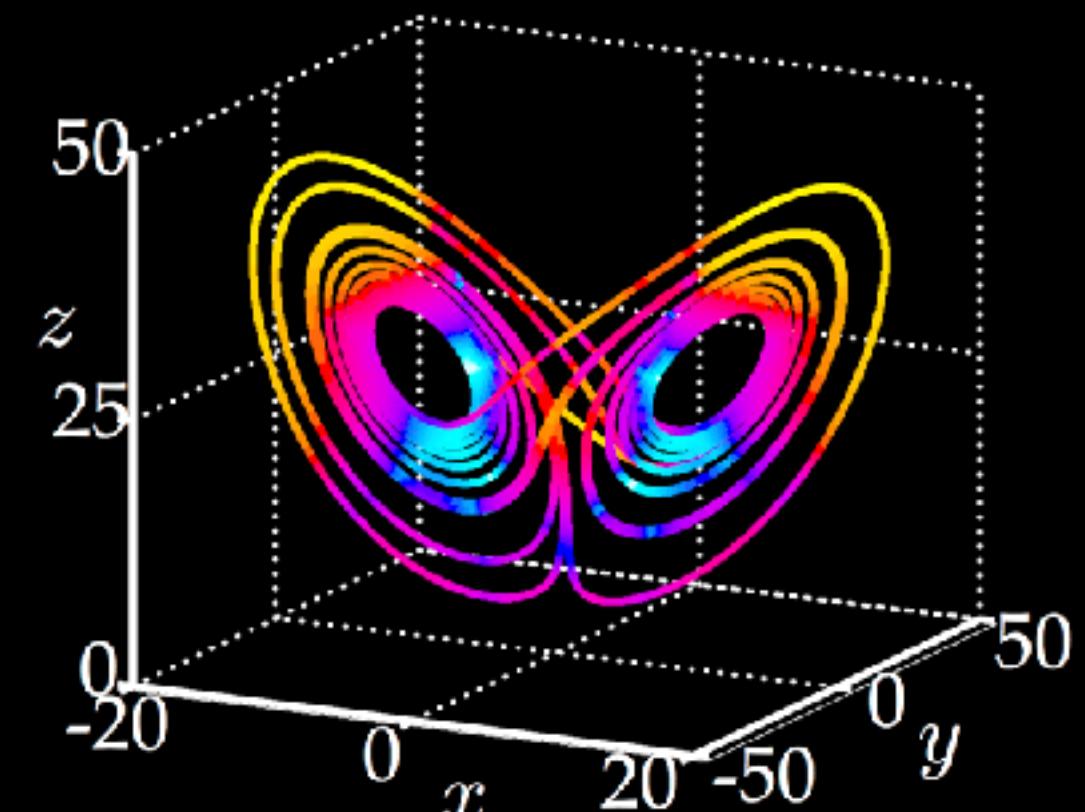
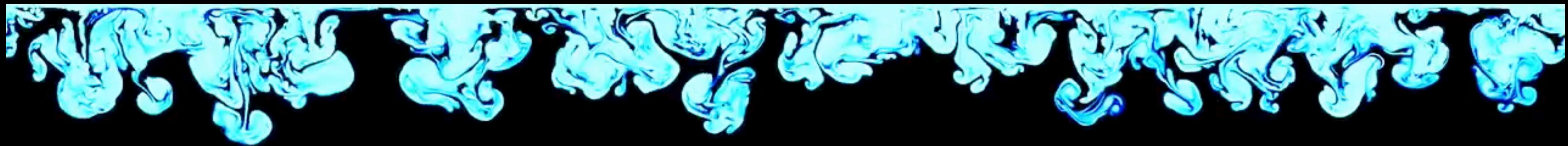
More Complex Flow: Fluidic Pinball



— DNS

- - - Low-order model

CHAOTIC THERMAL CONVECTION



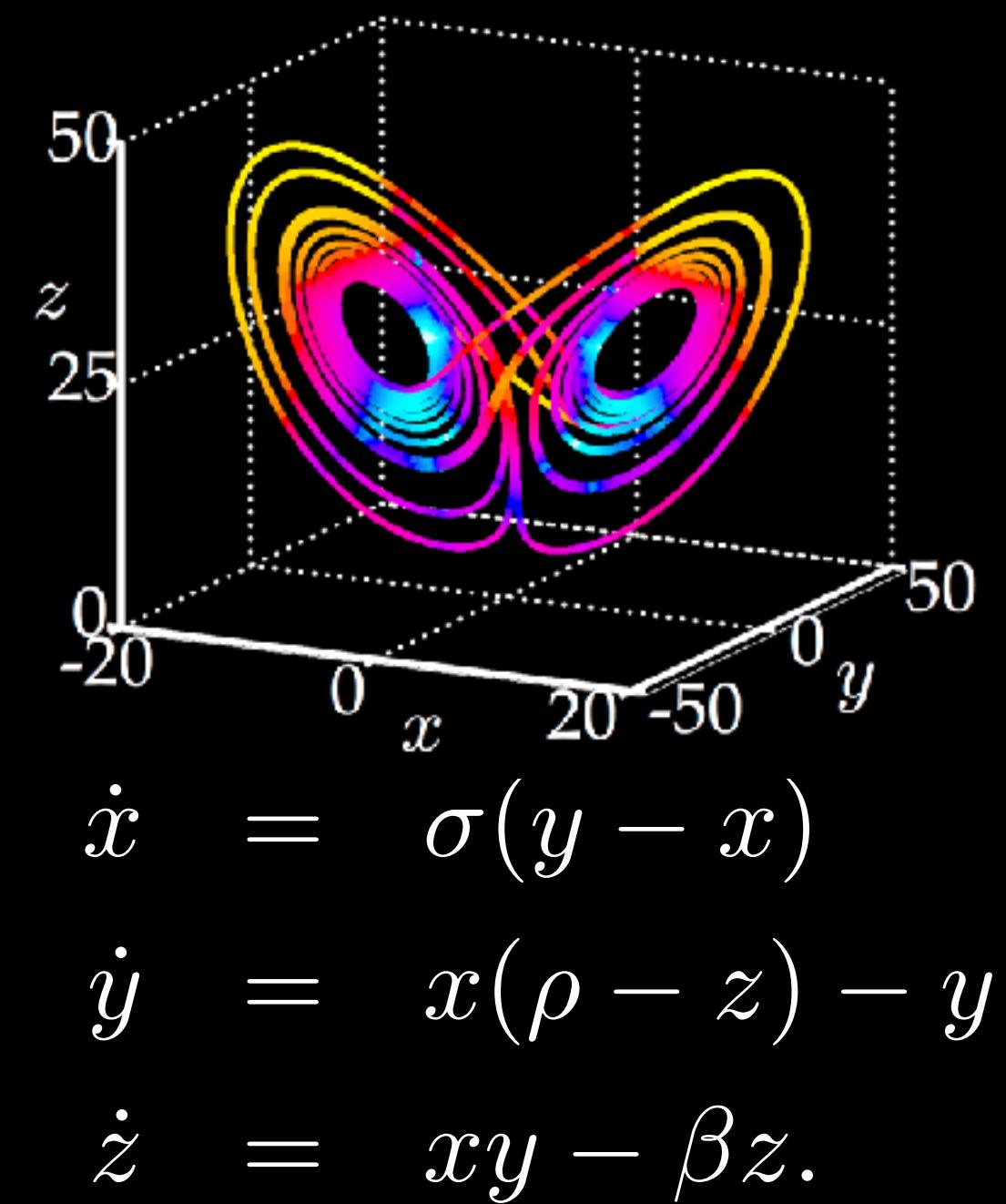
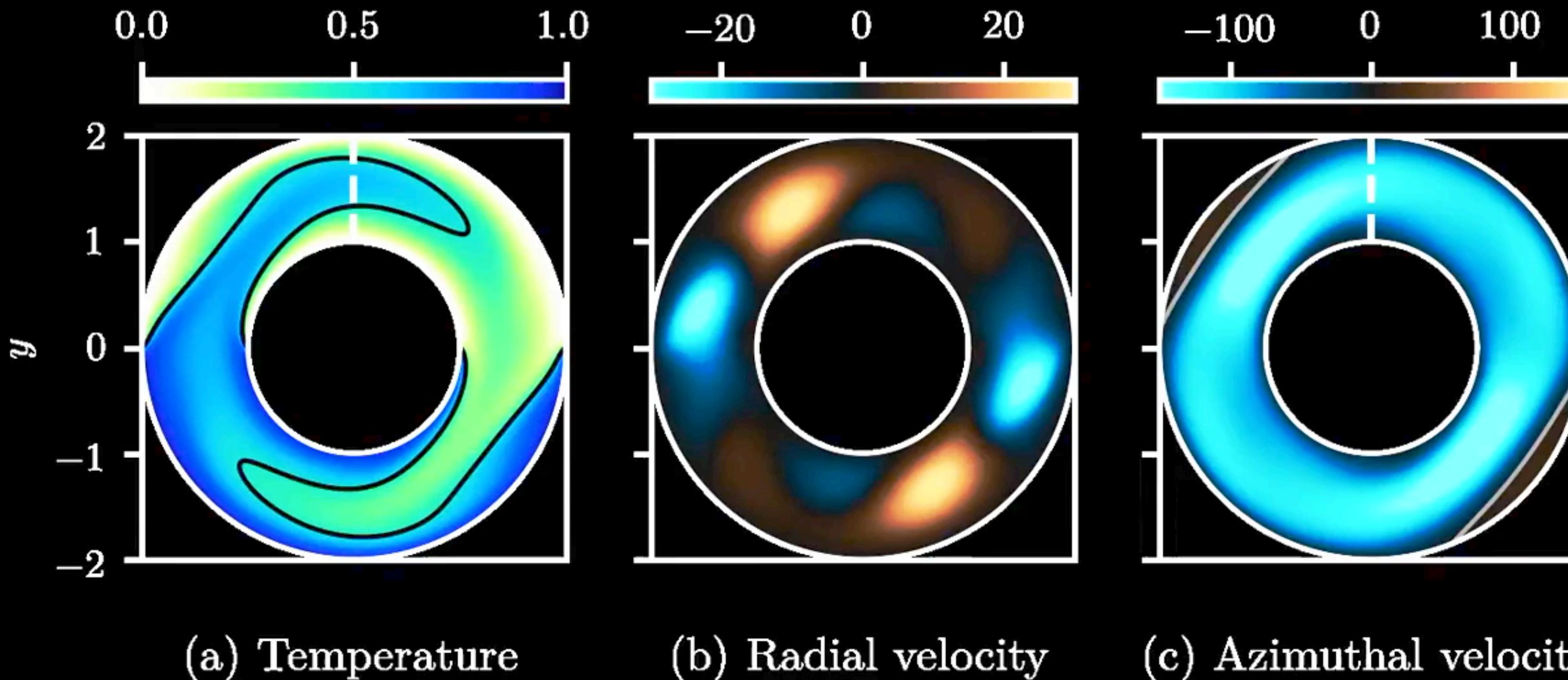
$$\dot{x} = \sigma(y - x)$$

$$\dot{y} = x(\rho - z) - y$$

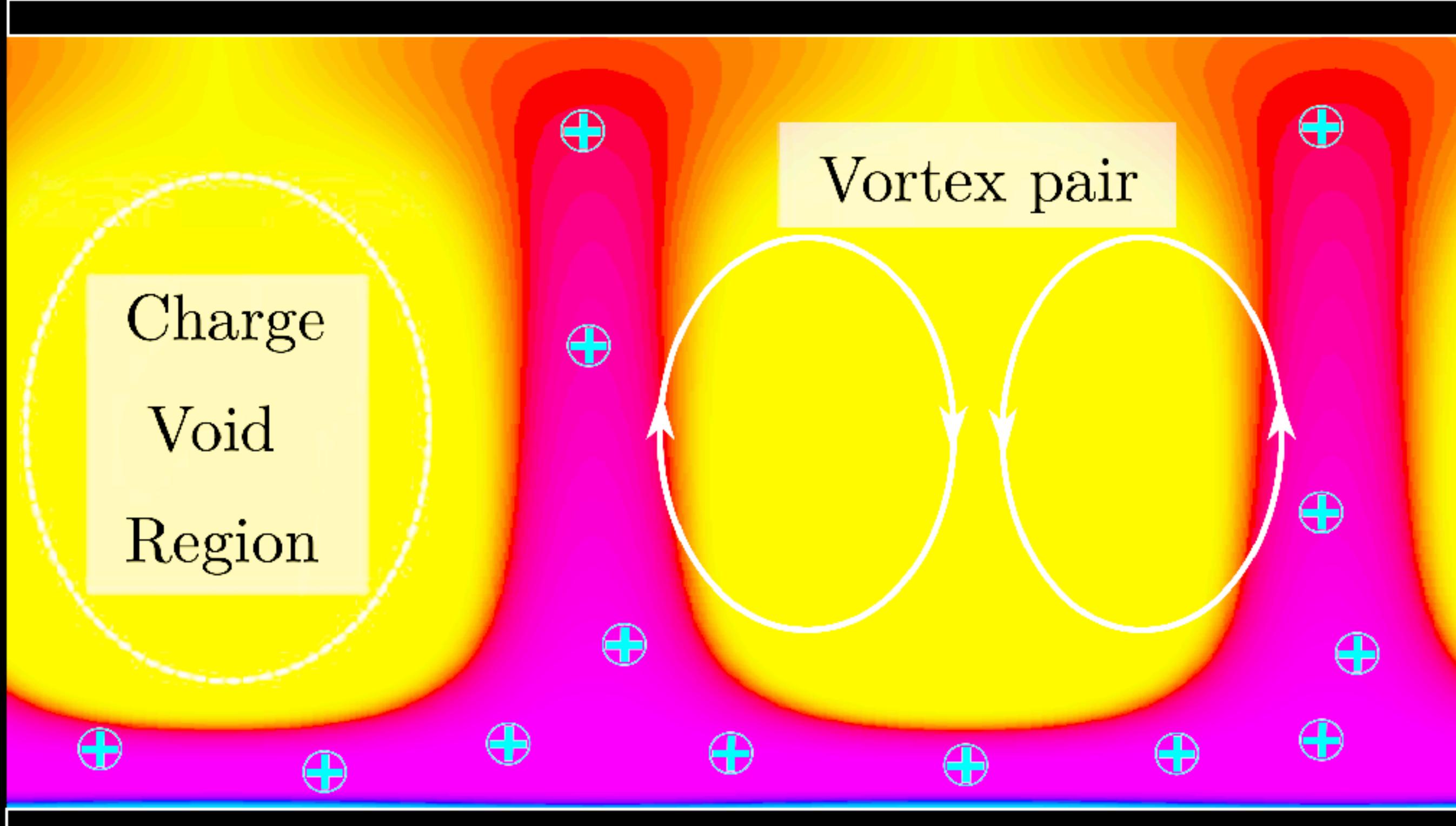
$$\dot{z} = xy - \beta z.$$



CHAOTIC THERMAL CONVECTION



CHAOTIC ELECTROCONVECTION



+

Three way coupling:

- **Fluid flow**
- **Charge density**
- **Electric field**

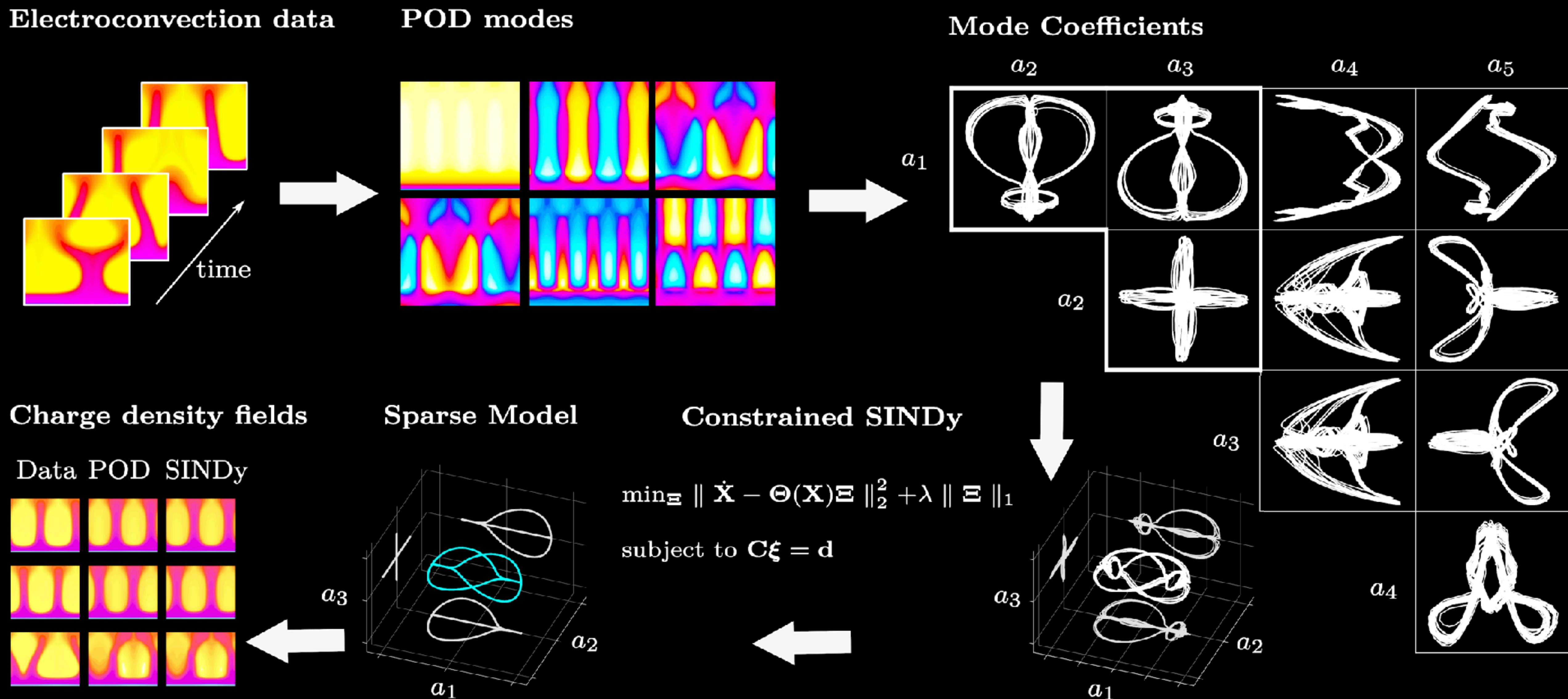
$$\nabla \cdot \mathbf{u}^* = 0$$

$$\rho \frac{D\mathbf{u}^*}{Dt^*} = -\nabla P^* + \mu \nabla^2 \mathbf{u}^* - \rho_c^* \nabla \phi^*$$

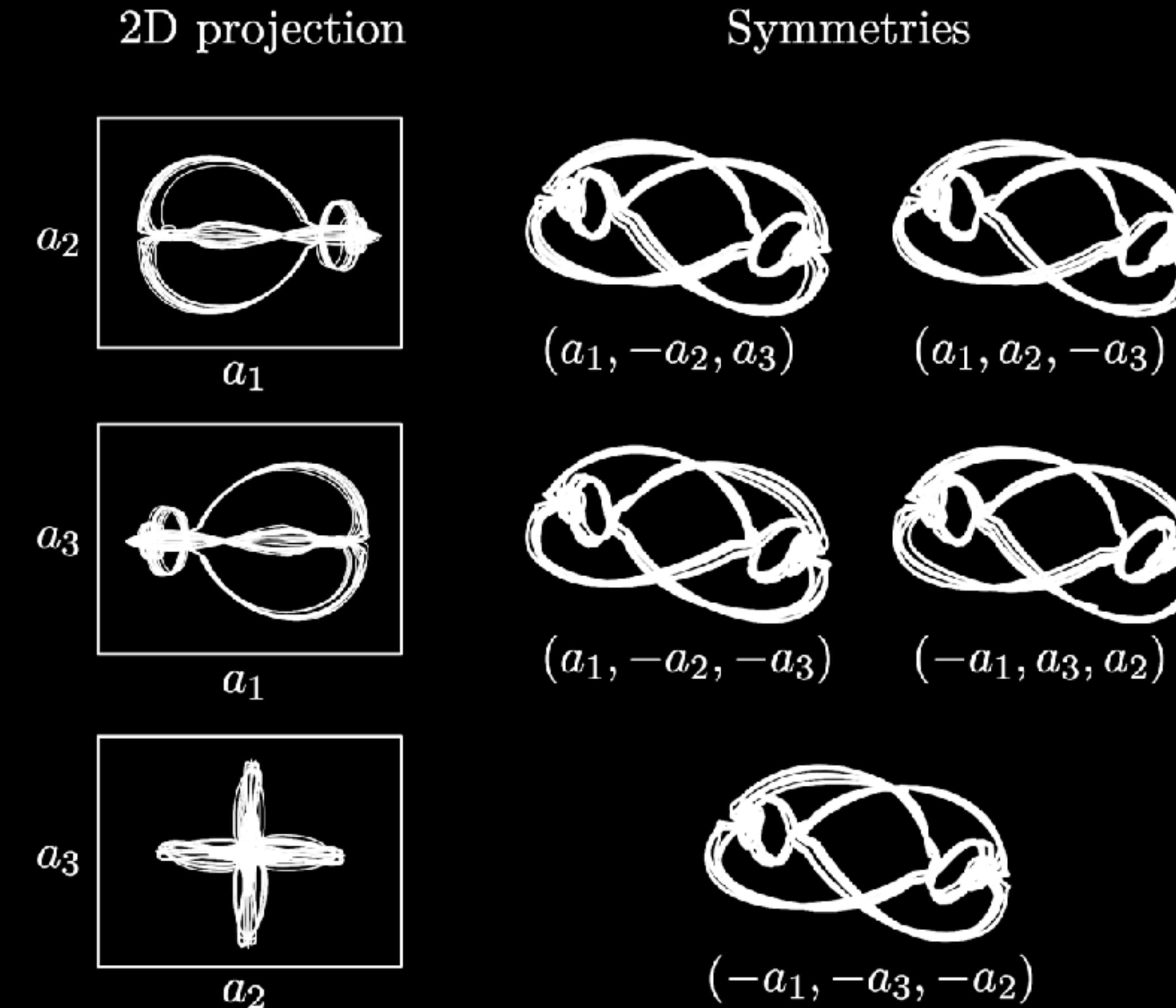
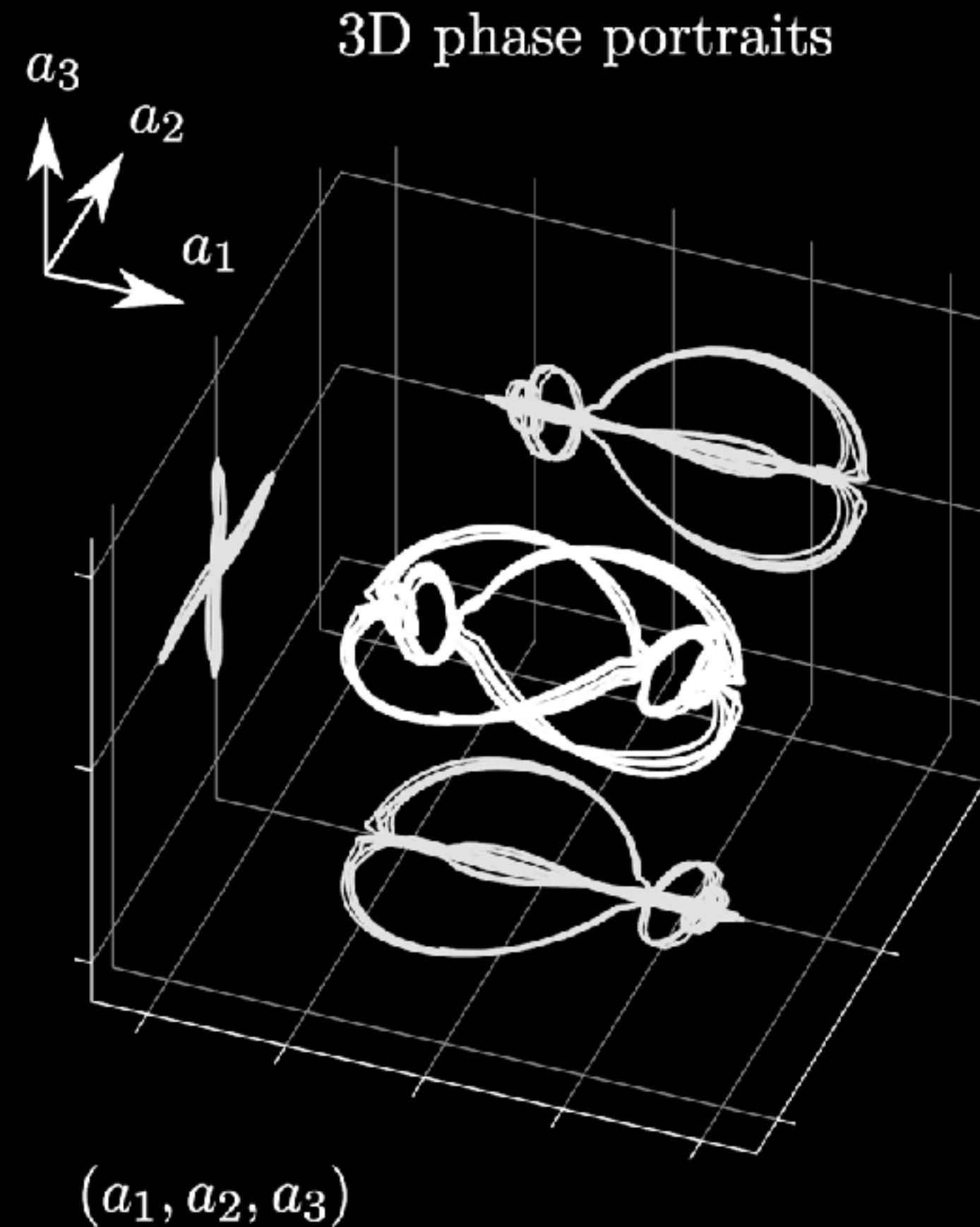
$$\frac{\partial \rho_c^*}{\partial t^*} = -\nabla \cdot [(\mathbf{u}^* - \mu_b \nabla \phi^*) \rho_c^* - D_c \nabla \rho_c^*]$$

$$\nabla^2 \phi^* = -\frac{\rho_c^*}{\epsilon}$$

CHAOTIC ELECTROCONVECTION

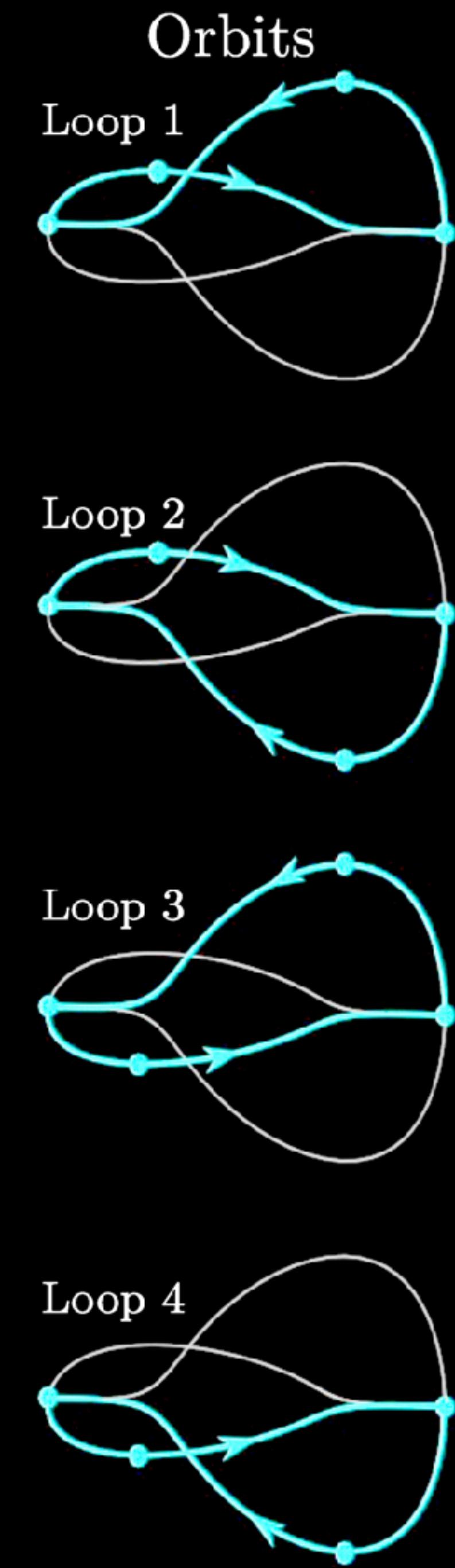
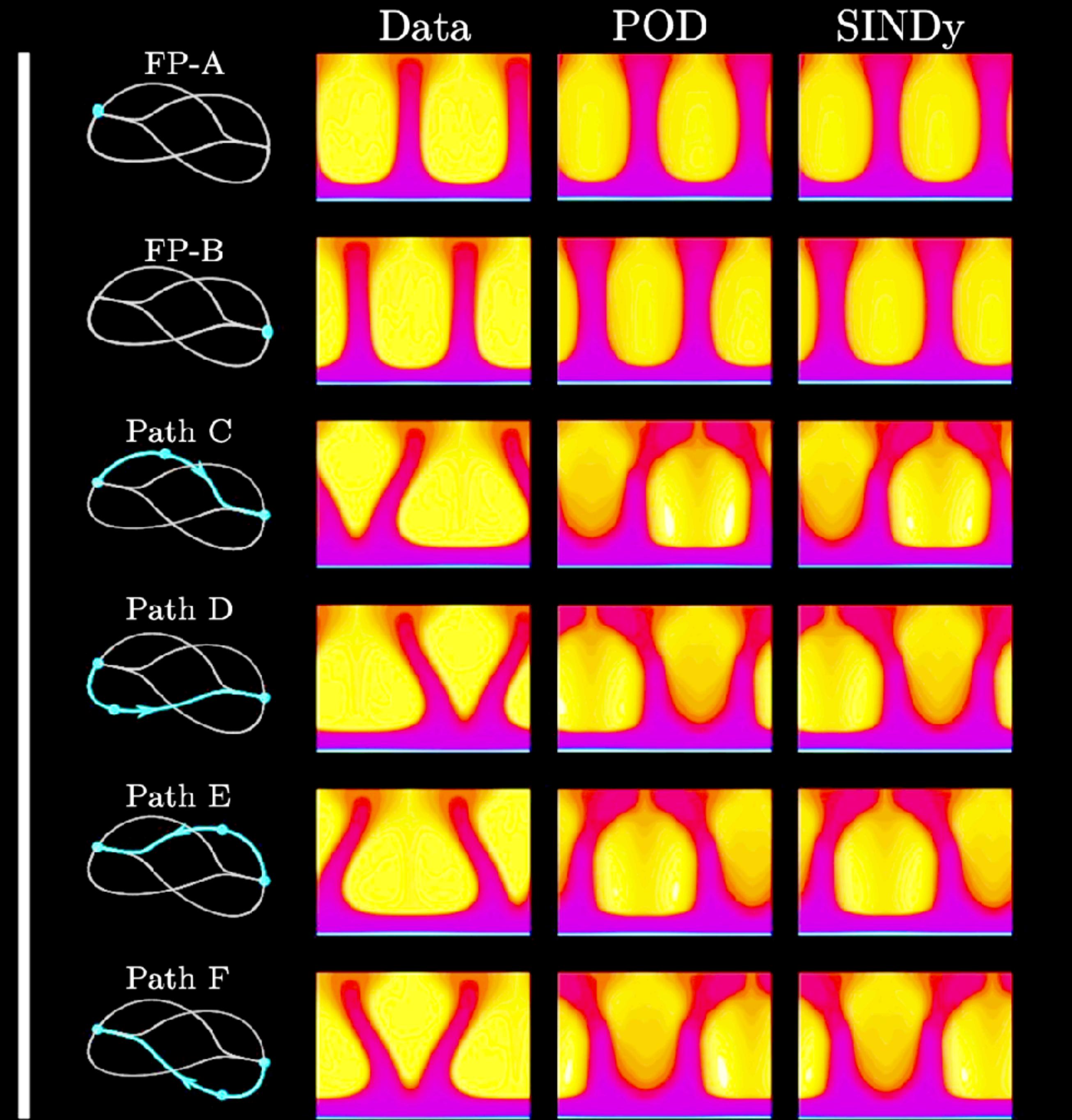
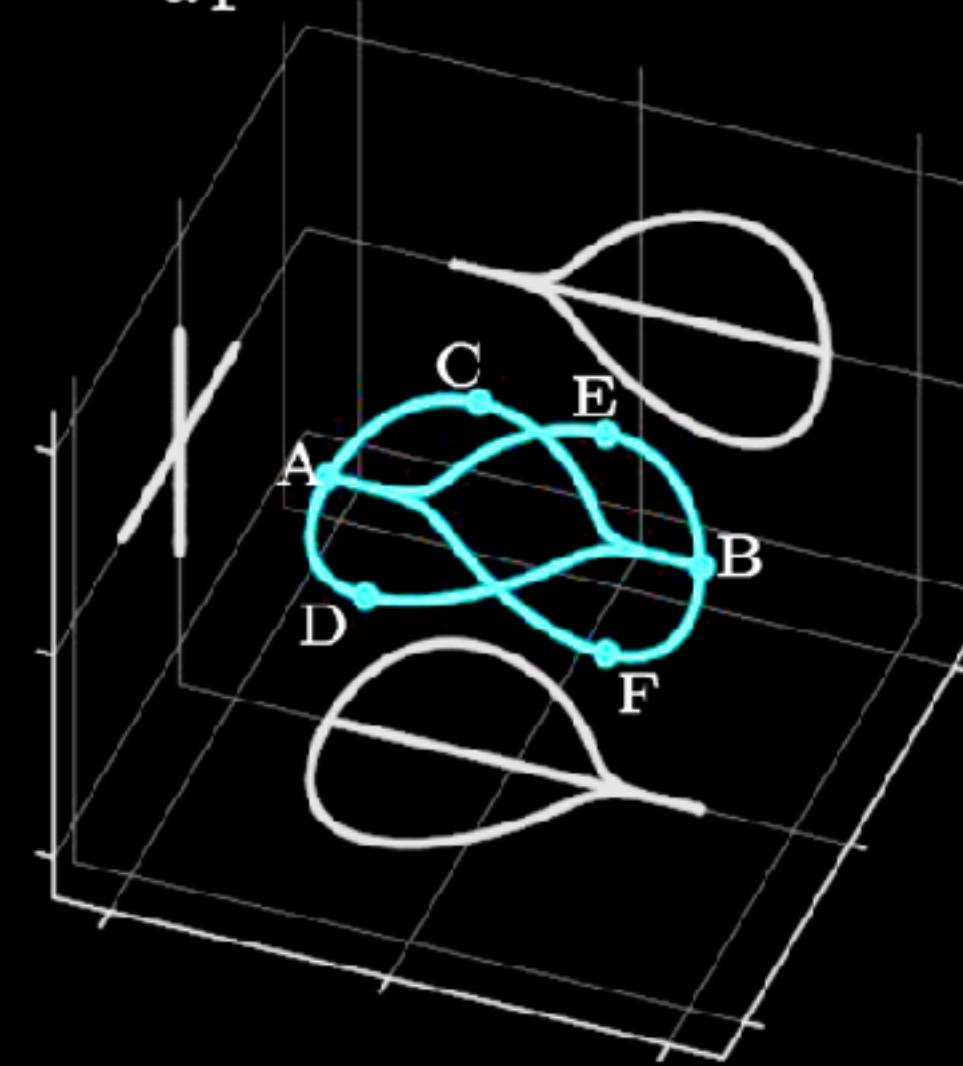
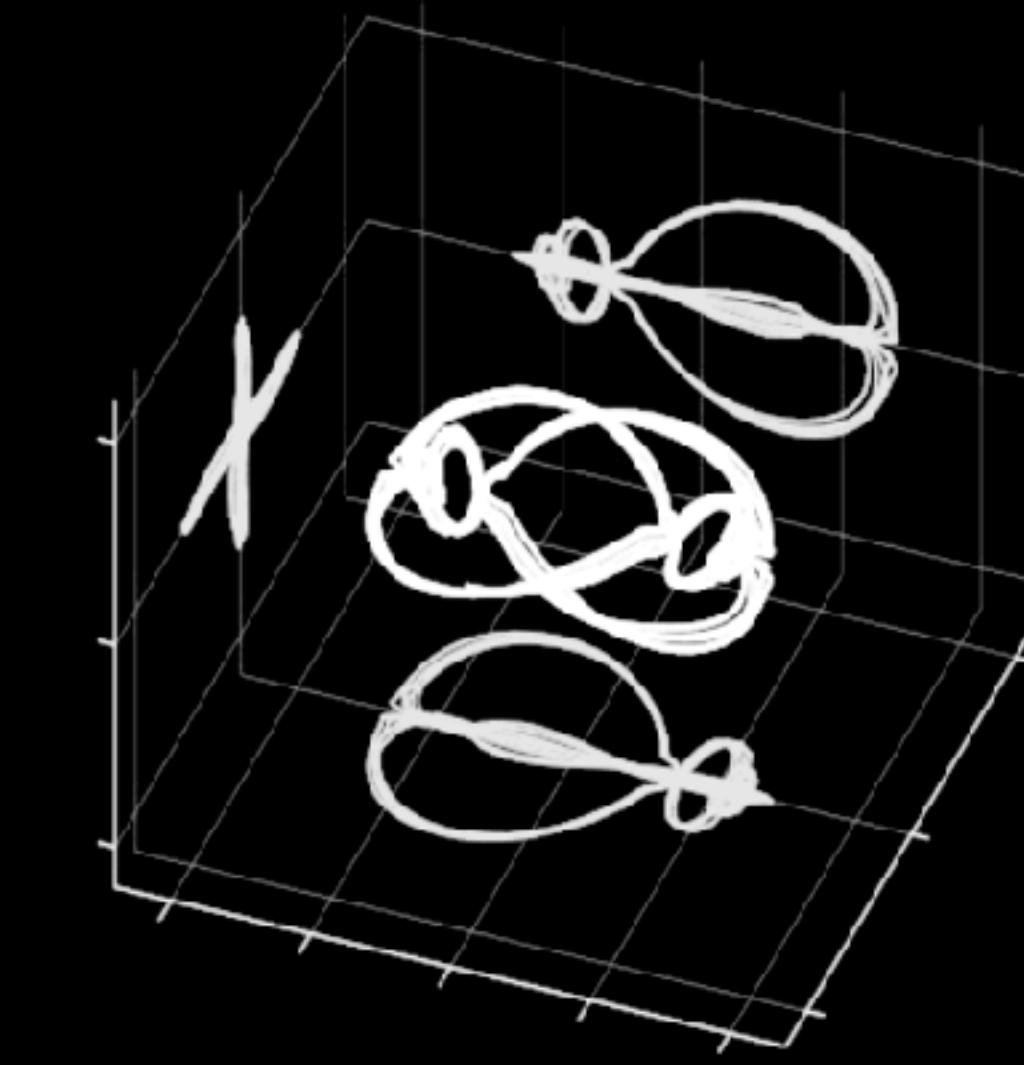


SYMMETRY IN THE DATA



	a_1	a_2	a_3	a_1^2	$a_1 a_2$	$a_1 a_3$	a_2^2	$a_2 a_3$	a_3^2	a_1^3	$a_1^2 a_2$	$a_1^2 a_3$	$a_1 a_2^2$	$a_1 a_2 a_3$	$a_1 a_3^2$	a_2^3	$a_2^2 a_3$	$a_2 a_3^2$	a_3^3
\dot{a}_1	ξ_1					ξ_2			$-\xi_2$	ξ_3			ξ_4		ξ_4				
\dot{a}_2		ξ_5		$-\xi_2$						ξ_6					ξ_7		ξ_8		
\dot{a}_3			ξ_5		ξ_2						ξ_6				ξ_8		ξ_7		

Data
Model

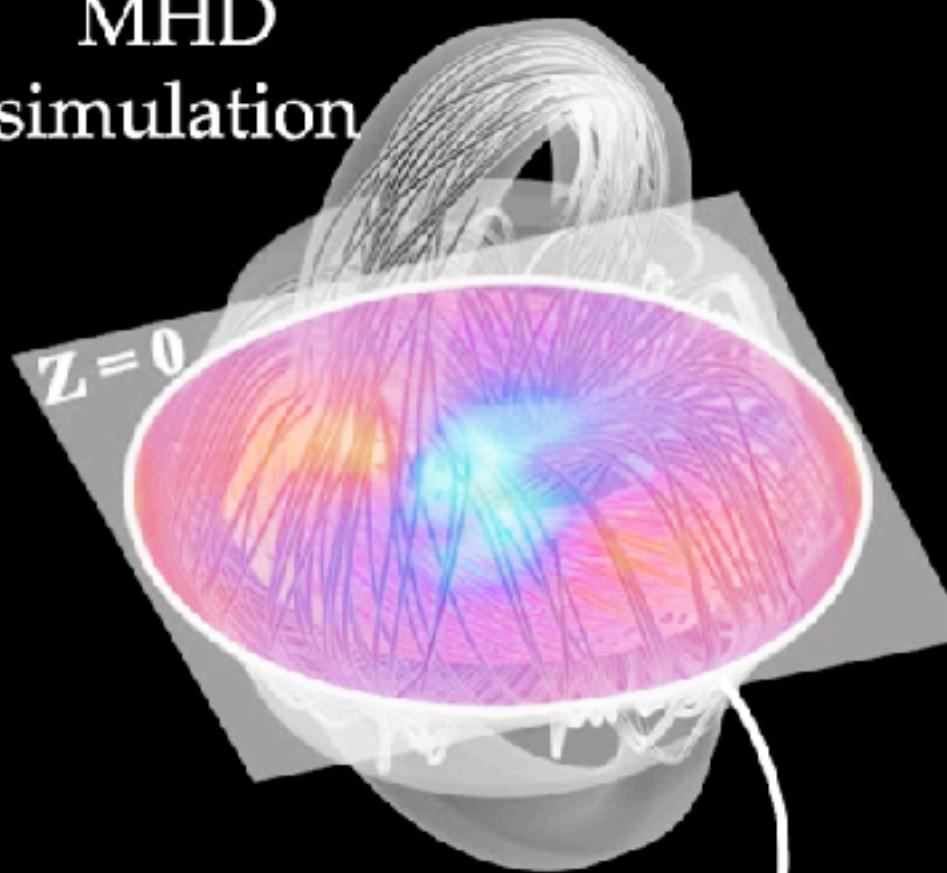


MAGNETOHYDRODYNAMICS (MHD)

(a) Measurement data

$$\mathbf{q}(\mathbf{x}, t) = \begin{bmatrix} \mathbf{B}_u \\ \mathbf{B} \end{bmatrix}$$

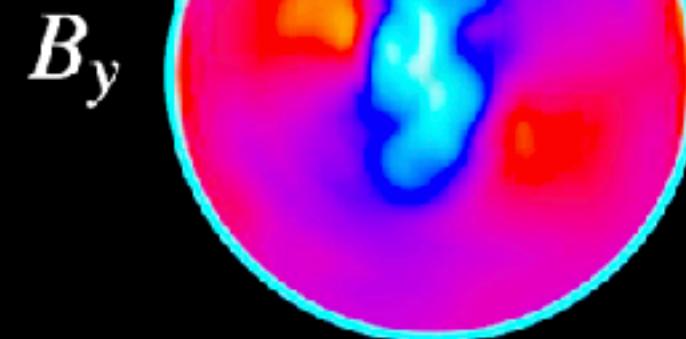
MHD
simulation



■ Simulation



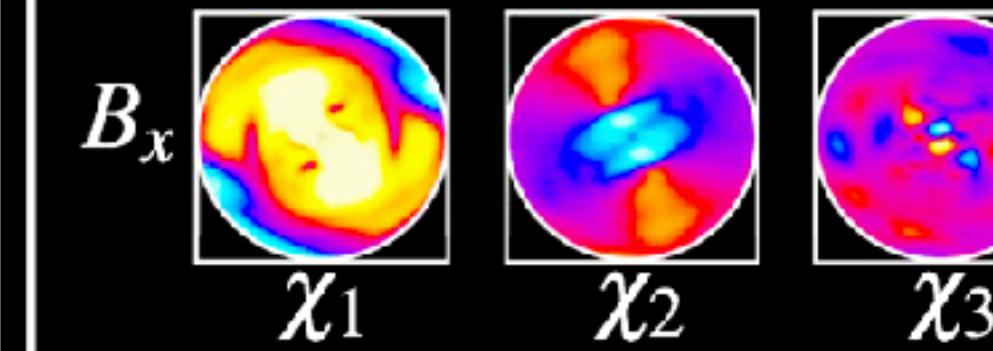
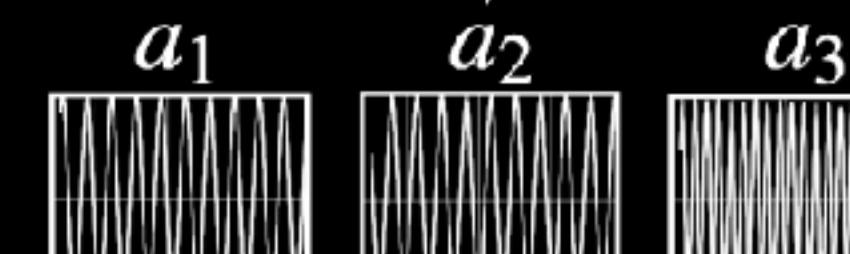
■ Model



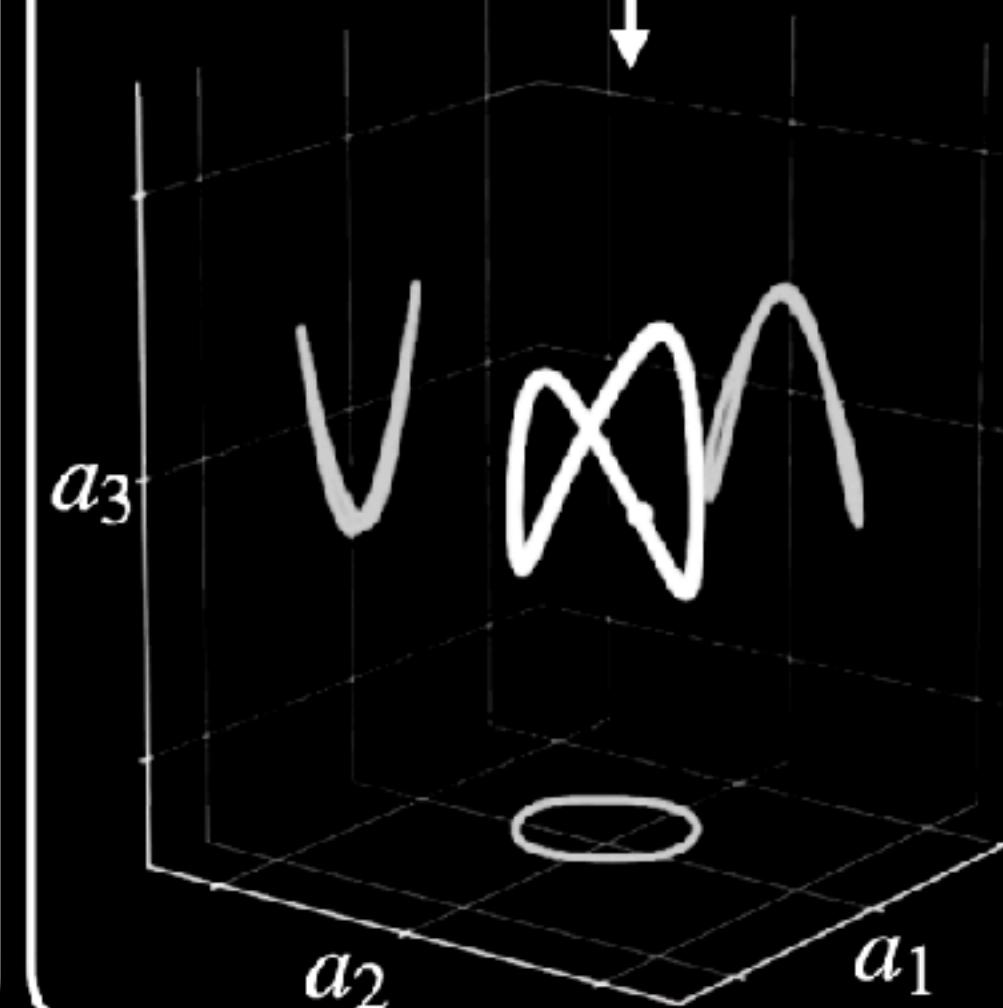
(b) POD-Galerkin

$$\mathbf{q}(\mathbf{x}, t_k) \approx \bar{\mathbf{q}}(\mathbf{x}) + \sum_j \boldsymbol{\chi}_j(\mathbf{x}) a_j(t_k)$$

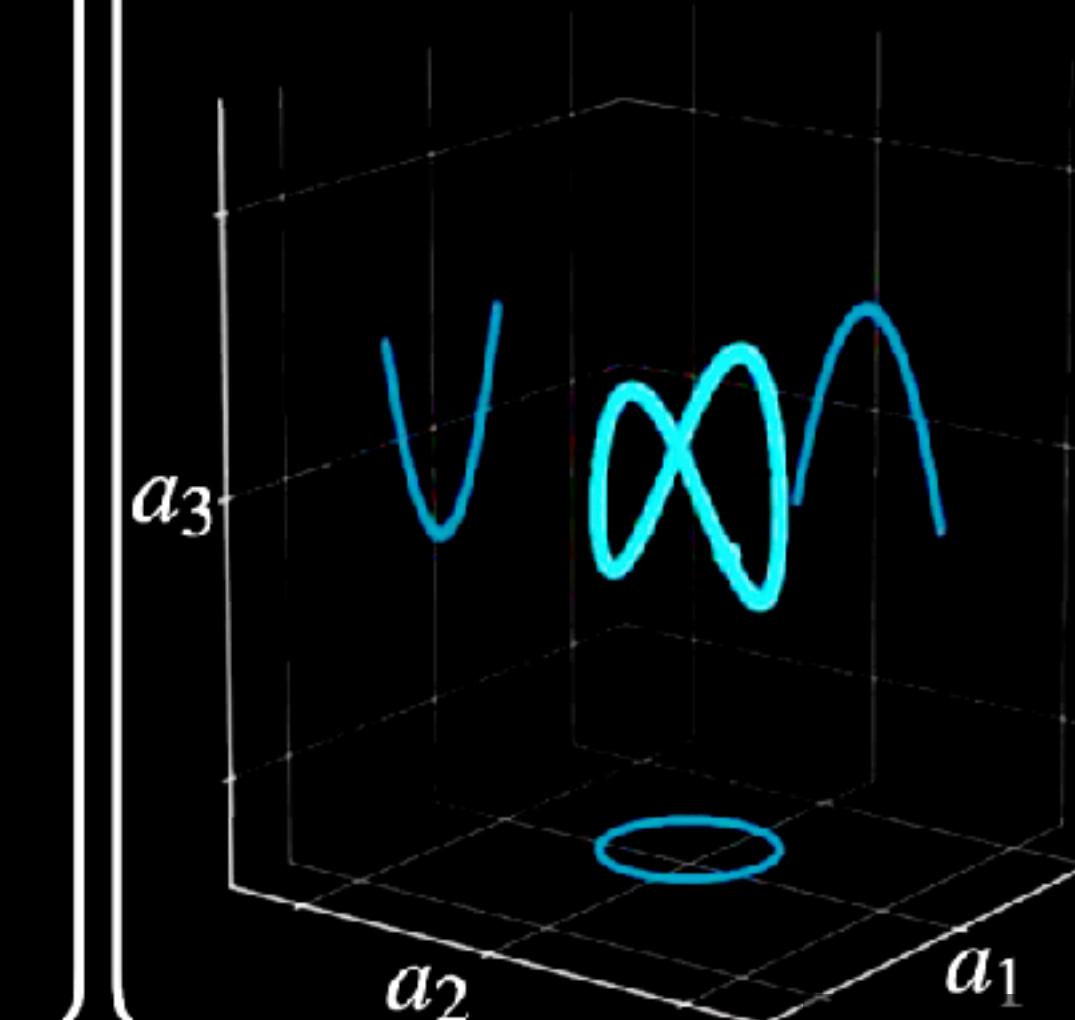
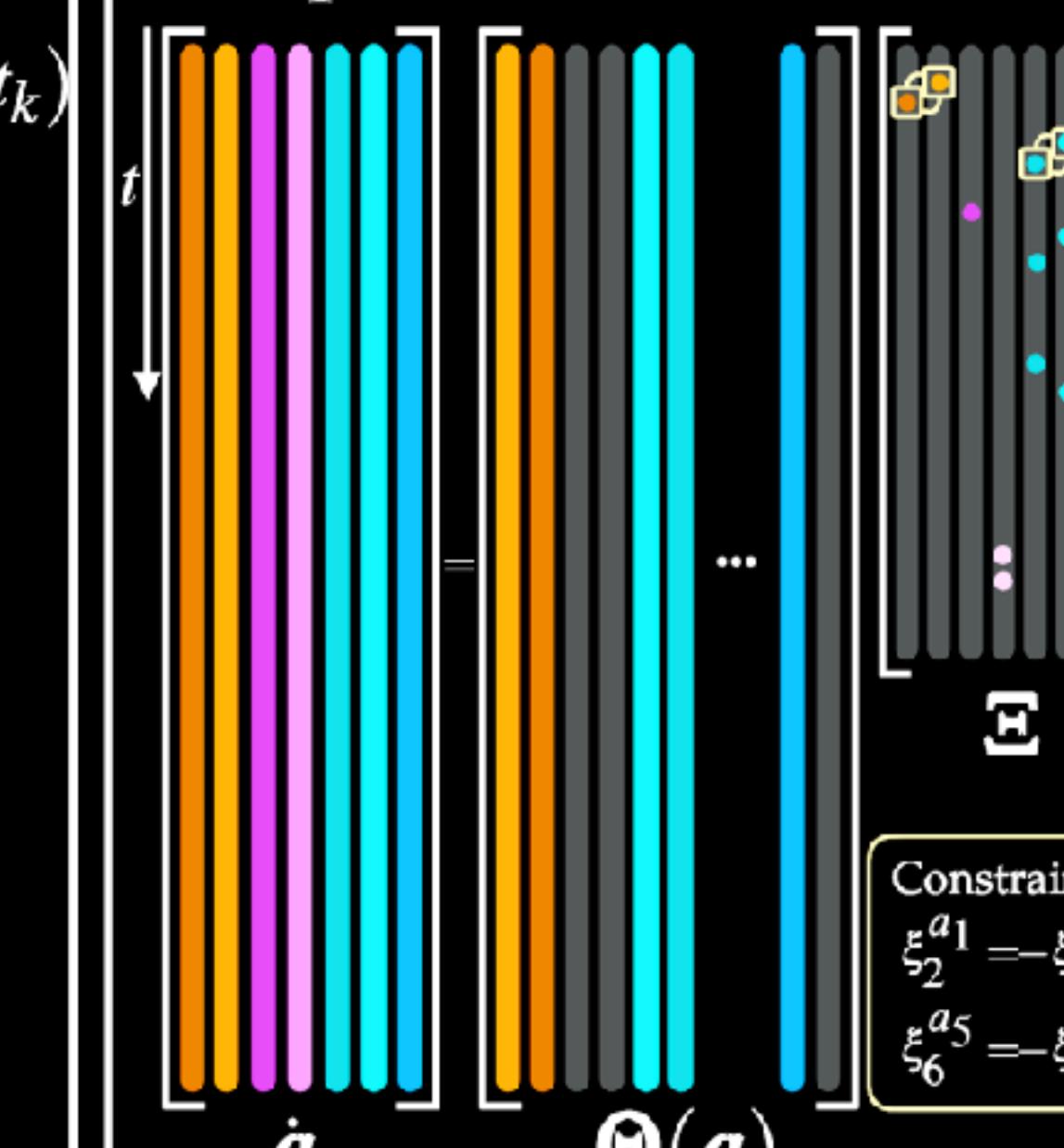
Dimensional
POD



$$\dot{\mathbf{a}} = f(\mathbf{a})$$



(c) Sparse model



The background of the image is Vincent van Gogh's painting "The Starry Night". It depicts a dark blue night sky filled with swirling, luminous yellow and white stars of various sizes. A large, bright yellow sun or moon is visible in the upper right corner. In the foreground, a dark, silhouetted town is nestled at the base of a tall, dark, craggy mountain. The style is characterized by thick, expressive brushstrokes.

QUESTIONS