

PCA IS NOT DEAD:
VECTORIZED PERSISTENT HOMOLOGY AND
FLAG MEDIANS
(PLUS OTHER STUFF)

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Mathematical Advances for Multi-Dimensional Microscopy
IPAM, Los Angeles
October 26, 2022



multi-dimensional microscopy mathematics



Google Search

I'm Feeling Lucky



multi-dimensional microscopy mathematics



Google Search

I'm Feeling Lucky

Optimist's view:

This talk will be 100% controversy-free.

TENSOR DECOMPOSITION?

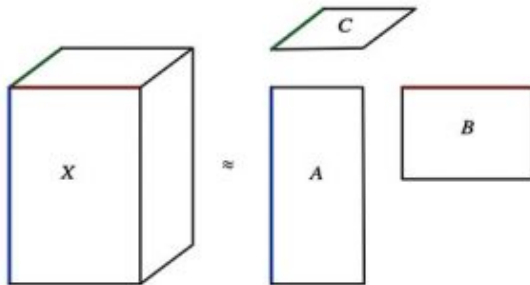


Figure from IPAM workshop page. Apparently because of **Paul**?

TENSOR MATRIX DECOMPOSITION

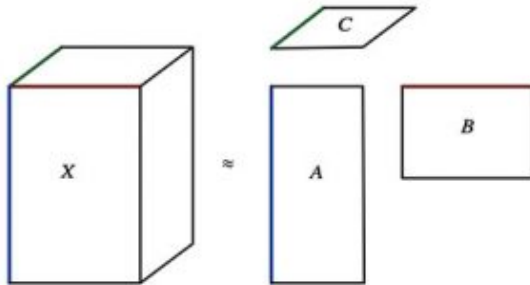
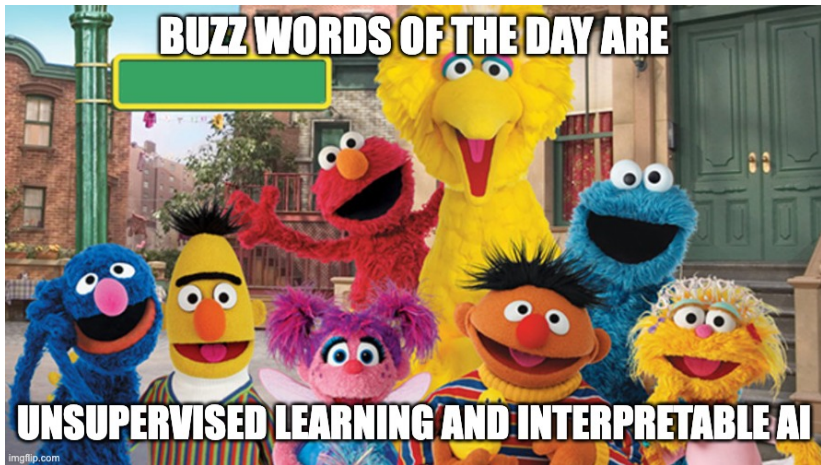


Figure from IPAM workshop page. Apparently because of Paul?



Generated using <https://imgflip.com/>

Unsupervised learning:

Can a model be learned without a large set of labeled data?

Interpretable AI:

Can a human gain intuition behind model outputs?

Desirable in fields like atmospheric/environmental science **and multidimensional microscopy?**, where the amount of (labeled) training data can be small but they don't trust black boxes.

Key idea of principal component analysis (PCA):

Schmidt-Eckart-Mirsky-Young Theorem:

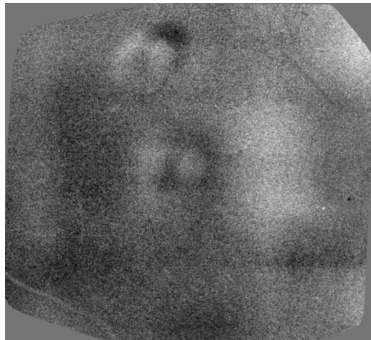
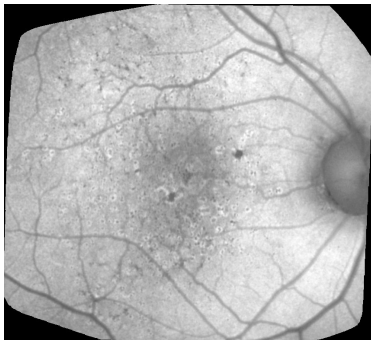
If USV^* is the singular value decomposition (SVD) of A , then

$$U \left(\begin{array}{cccc|c} \sigma_1 & 0 & \dots & 0 & \\ 0 & \sigma_2 & \dots & 0 & \\ \vdots & \vdots & \ddots & \vdots & \\ 0 & 0 & \dots & \sigma_k & \\ \hline & & 0 & & 0 \end{array} \right) V^*$$

is the best (at most) rank k approximation¹ of A .

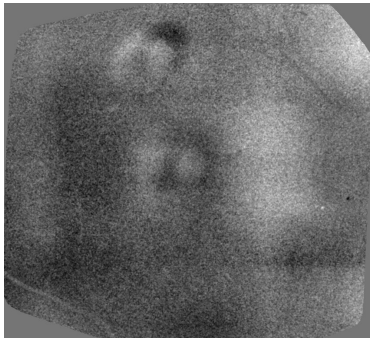
¹with respect to Frobenius and spectral norms

PCA: DOESN'T HURT TO TRY



The first and second principal components of a stack of four fundus camera images of the retina of a patient with age-related macular degeneration.

PCA: DOESN'T HURT TO TRY*



The first and second principal components of a stack of four fundus camera images of the retina of a patient with age-related macular degeneration.

* It obviously doesn't always work, see [Ivan's talk](#).

LECTURE OUTLINE

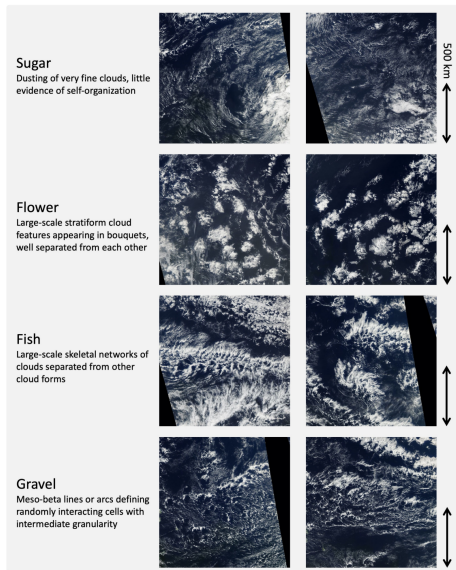
VECTORIZED PERSISTENT HOMOLOGY (ATMOSPHERIC SCIENCE)

OTHER STUFF (Y'ALL'S SCIENCE?)

More Persistence of Topology and Geometry
Shearlet-Based Feature Extraction and Inpainting
Geometry of Adversarial Attacks

FLAG MEDIANS (COMPUTER VISION)

MESOSCALE ORGANIZATION OF CLOUDS



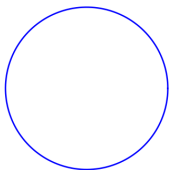
Examples of the four cloud types from the Sugar, Fish, Flowers, and Gravel dataset,
Rasp et al. 2019

BETTI NUMBERS: LEARN HOMOLOGY IN ONE SLIDE



b_0
 b_1

1
0



1
1

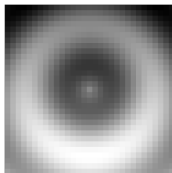


2
2



1
2

SUPERLEVELSET PERSISTENT HOMOLOGY



(a)



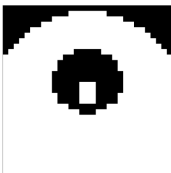
Cutoff: 209

(b)



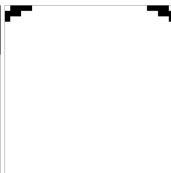
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(c)



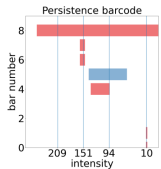
Cutoff: 94

(d)

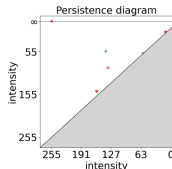


Cutoff: 10

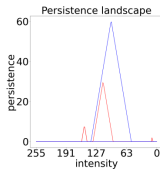
(e)



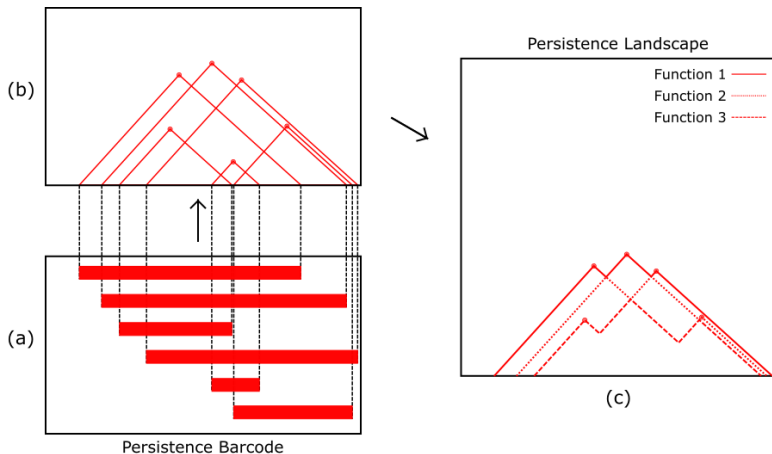
(f)



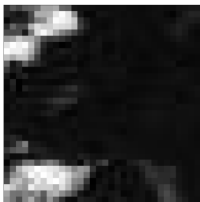
(g)



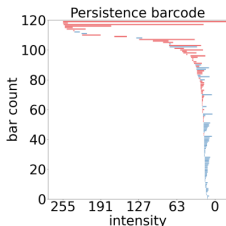
(h)



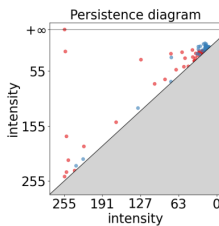
The process of computing a vectorized persistence landscape from a barcode. In (c), only the first three landscape functions are shown. In this case, the first function would be sampled, followed by the second then the third to create a vector.



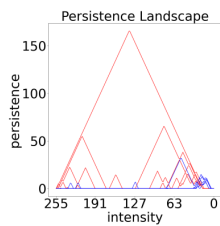
(a)



(b)



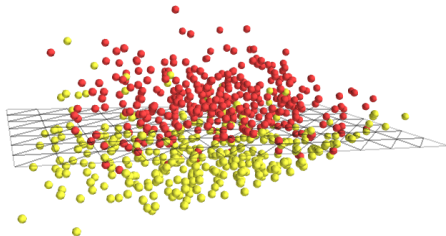
(c)



(d)

(a) A 32×32 sample image from the grayscale MODIS imagery used in the sugar, flowers, fish, and gravel dataset, along with (b) its persistence barcode, (c) persistence diagram, and (d) persistence landscape with the first 5 piecewise-linear functions for each of the H_0 and H_1 classes.

Key idea: PCA may be applied as an unsupervised learning method after using an interpretable method like superlevelset persistent homology.



After mapping to \mathbb{R}^{2000} by vectorizing superlevel set persistence landscapes to capture geometric traits, PCA performed down to \mathbb{R}^3 – capturing about **90%** of the variation – for separation.

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(Y'ALL'S SCIENCE?)

More Persistence of Topology and Geometry
Shearlet-Based Feature Extraction and Inpainting
Geometry of Adversarial Attacks

FLAG MEDIANS
(COMPUTER VISION)

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Key Idea:

Bryan and I had a few offline talks about the importance of mesoscale features,

on a larger scale than noise

on a smaller scale than curvature / average characteristics

PERSISTENT HOMOLOGY OF POINT CLOUDS

Key Idea: Track the birth and death of various dimensional holes to distinguish structure from chaos.

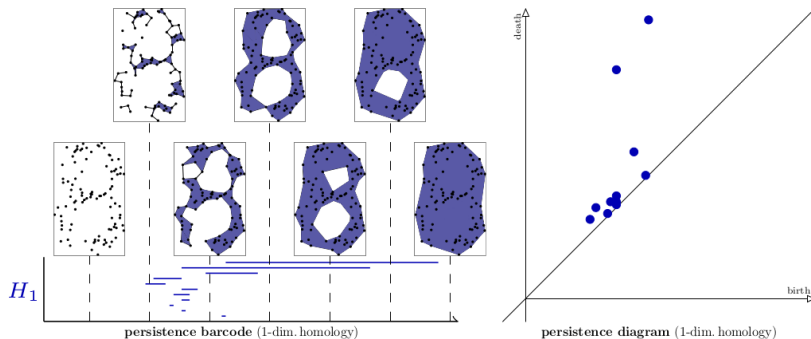
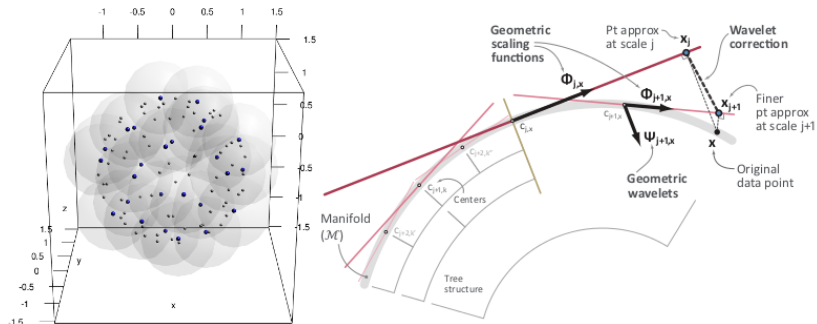


Image source: Jan Senge (Uni Bremen)

GEOMETRIC MULTIREOLUTION ANALYSIS

Geometric multiresolution analysis is local PCA plus multiscale structure.



Source: Strawn 2015; E. Monson via Allard, Chen, Maggioni 2011

Note! “Geometric multiresolution analysis” also used to describe shearlet/curvelet analysis, especially ≈ 10 years ago.

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Key idea of applied harmonic analysis:

For data f ,

$$|\langle f, \varphi_j \rangle|,$$

where $\{\varphi_j\}_j$ is often the orbit of a unitary representation, is the “amount” of a trait parameterized by j in f .

E.g.,

Fourier: $|\langle f, e^{2\pi i \gamma \cdot} \rangle|$ is the “amount” of frequency γ in f .

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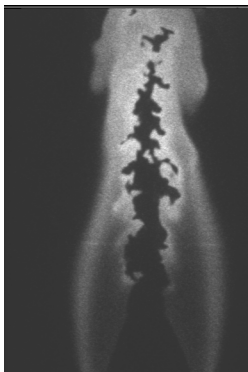
Fourier: $|\langle f, e^{2\pi i \gamma \cdot} \rangle|$ is the “amount” of frequency γ in f .

Shearlet: $|\langle f, 2^{3j/4} \psi(S_\ell A_{2^j} \cdot -k) \rangle|$ is the “amount” of features of scale j and orientation ℓ at position k in f .

Key idea of neural networks:

Pairing non-linearity with smartly chosen linear maps is very powerful.

FLAME IMAGE



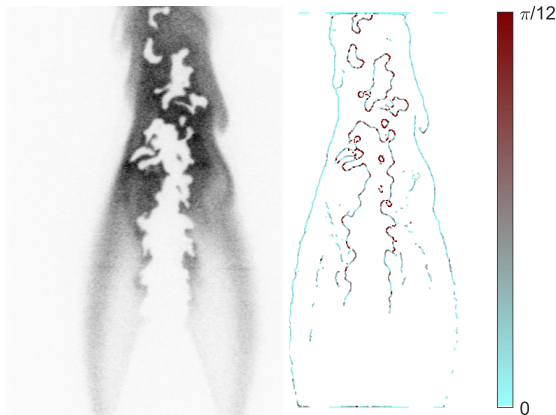
Planar Laser-Induced Fluorescence (PLIF) image of excited *OH*.

Data source: Johannes Kiefer

Understanding the **location** and **curvature** of flame fronts is critical to **better understand turbulence** and **verify computer simulations**.

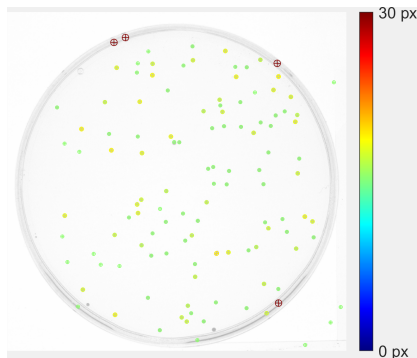
FLAME FRONT DETECTION WITH SHEARLETS

$$E_{\psi}(f, x, s) = \max \left\{ 0, \frac{\left| \sum_{a \in A} \langle f, \psi^{(o)}_{a,s,x} \rangle \right| - \sum_{a \in A} \left| \langle f, \psi^{(e)}_{a,s,x} \rangle \right| - \beta |A| K_{\psi}}{|A| \max_{a \in A} \left| \langle f, \psi^{(o)}_{a,s,x} \rangle \right| + \epsilon} \right\},$$



L: PLIF visualization of OH. R: Detected flame front with curvature using shearlets.

CELL COLONY DETECTION



Estimated colony widths. **Source of original petri dish image:** Quentin Geissmann 2013

In comparison with three other automated cell colony counting methods, SymFD is best or second best.

(Handles webcam images uniformly better.)

INPAINTING EXAMPLES

An issue in data analysis is that of incomplete data. Some examples of desired **inpainting / image completion / data recovery** are

- ▶ the repair of scratched photos and audio recordings,
- ▶ the completion of microscopy data,
- ▶ the filling in of webcam videos of your grad student, and
- ▶ the removal of overlaid text in images, or ...

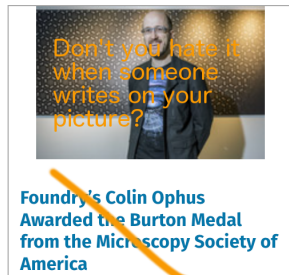
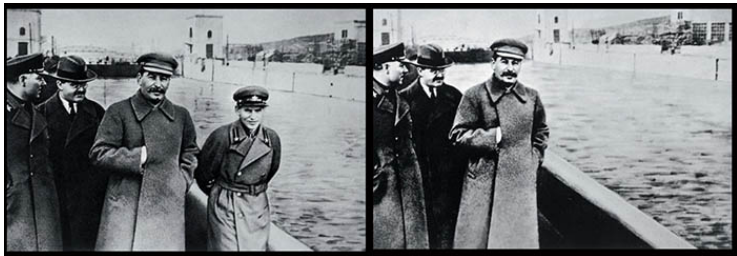


Image source: Hadn't yet brought up
Colin.

INPAINTING EXAMPLES, CONT.

- ...the erasure of people from history who got in your way.



Original photo Gazeta 1937. Doctored photo unknown source. Downloaded from <https://www.indexoncensorship.org/2017/08/commissar-vanishes/>.

Key Idea:

Assume that

Φ_1, Φ_2 “nice” dictionaries incoherent to each other but coherent to desired structures in the data

P_K throws away data from known degraded region

Solve

$$\begin{aligned}(x_1^*, x_2^*) = \operatorname{argmin}_{y_1, y_2} & \|\Phi_1^* y_1\|_1 + \|\Phi_2^* y_2\|_1 \\ \text{s.t. } & P_K x = P_K(y_1 + y_2).\end{aligned}$$

SHEARLET-BASED MCA



(a) Masked image



(b) MCA, SSIM = 0.7978



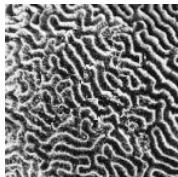
(c) Iterative thresholding, SSIM = 0.8813



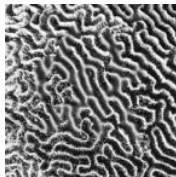
(d) Shearlet-based MCA, SSIM = 0.8831

Stürck 2015 (M.S. thesis from my group),
cf. inpainting of similar degradation in Nigel's talk and Juan-Carlos's excitement

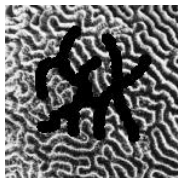
WHAT IS SUCCESSFUL INPAINTING?, I



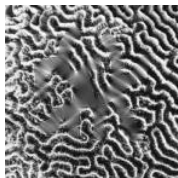
Patch-based, $t=3.74s$



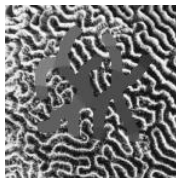
NLM, $t=210.75s$



Masked image

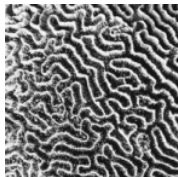


Shearlet (s12d1), $t=26.29s$

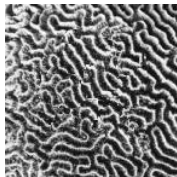


TV, $t=2.04s$

WHAT IS SUCCESSFUL INPAINTING?, I

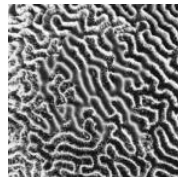


Original image



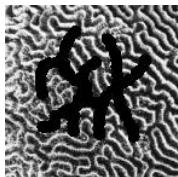
Patch-based, $t=3.74s$

PSNR=17.5652dB, SSIM=0.8555

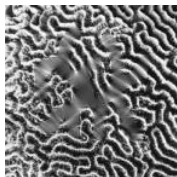


NLM, $t=210.75s$

PSNR=18.7336dB, SSIM=0.8720

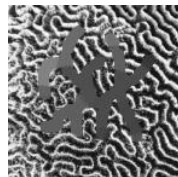


Masked image



Shearlet (s12d1), $t=26.29s$

PSNR=19.4429dB, SSIM=0.8542



TV, $t=2.04s$

PSNR=18.6828dB, SSIM=0.8241

WHAT IS SUCCESSFUL INPAINTING?, I



Original image



Patch-based, $t=3.74s$

PSNR=17.5652dB, SSIM=0.8555



NLM, $t=210.75s$

PSNR=18.7336dB, SSIM=0.8720



Masked image



Shearlet (s12d1), $t=26.29s$

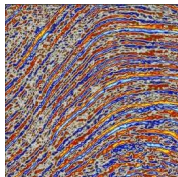
PSNR=19.4429dB, SSIM=0.8542



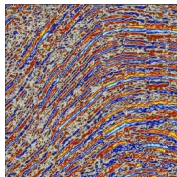
TV, $t=2.04s$

PSNR=18.6828dB, SSIM=0.8241

WHAT IS SUCCESSFUL INPAINTING?, II

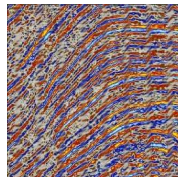


Original image



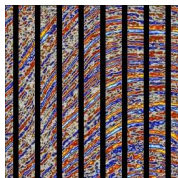
Patch-based, $t=67.07s$

PSNR=17.2594dB, SSIM=0.7658

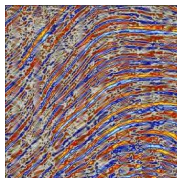


Non-local means, $t=887.89s$

PSNR=18.6481dB, SSIM =0.7957

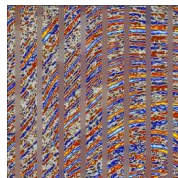


Masked image



Shearlet (s12d2), $t=400.48s$

PSNR=19.8313dB, SSIM=0.8209



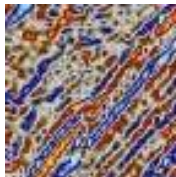
TV, $t=24.65s$

PSNR=19.1411dB, SSIM=0.7755

WHAT IS SUCCESSFUL INPAINTING?, II

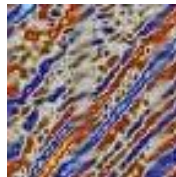


Original image



Patch-based, $t=67.07s$

PSNR=17.2594dB, SSIM=0.7658



Non-local means, $t=887.89s$

PSNR=18.6481dB, SSIM =0.7957



Masked image



Shearlet (s12d2), $t=400.48s$

PSNR=19.8313dB, SSIM=0.8209



TV, $t=24.65s$

PSNR=19.1411dB, SSIM=0.7755

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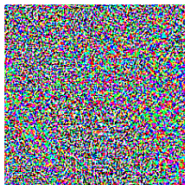
FLAG MEDIANS
(COMPUTER VISION)

Images input to neural networks performing classification tasks may be slightly perturbed to cause the network to **strongly misclassify** them.



x
 “panda”
 57.7% confidence

$+ .007 \times$



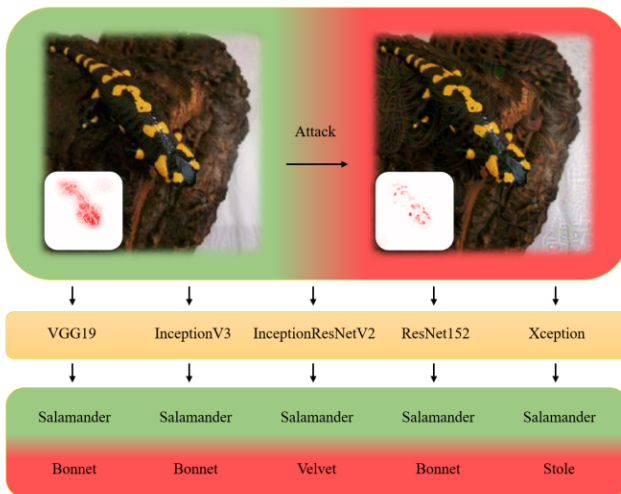
$\text{sign}(\nabla_x J(\theta, x, y))$
 “nematode”
 8.2% confidence

$=$



$x + \epsilon \text{sign}(\nabla_x J(\theta, x, y))$
 “gibbon”
 99.3 % confidence

A now “classic” example of an adversarial attack on GoogLeNet.



DAmageNet is a blackbox adversarial attack algorithm that generates perturbations of images, misclassified by many standard deep neural networks.

I am interested in leveraging manifold and polyhedral geometry and graph theory to better understand the success of adversarial attacks.

LECTURE OUTLINE

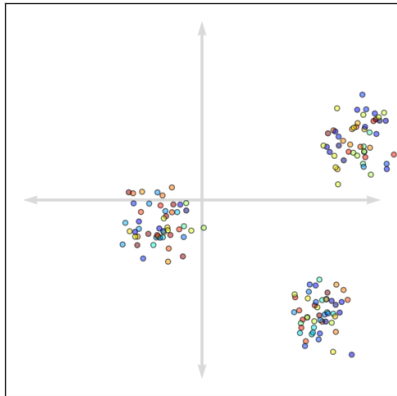
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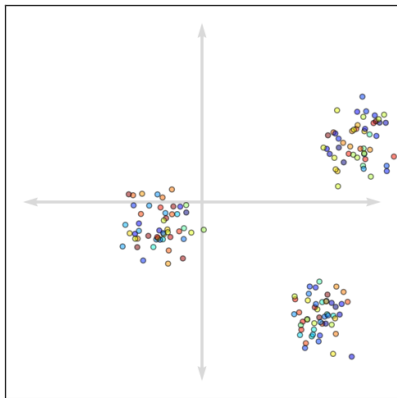
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FLAG MEDIANS
(COMPUTER VISION)

Given a data set(s) $X \subset \mathbb{R}^d$, what is (are) the point(s) in \mathbb{R}^d that best represents X ?



Given a data set(s) $X \subset \mathbb{R}^d$, what is (are) the point(s) in \mathbb{R}^d that best represents X ?



How sensitive should the **prototype** be to **outliers**?

Prototypes of data classes $X = \{x_i\}_{i=1}^s \subset \mathbb{R}^d$ often solve

$$\min_{y \in A} \sum_{i=1}^s \|x_i - y\|_2^p.$$

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$A = \mathbb{R}^d, p = 2$: centroid

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$A = \mathbb{R}^d, p = 2$: centroid
(just the component-wise average)

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$$\min_{y \in A} \sum_{i=1}^s \|x_i - y\|_2^p.$$

$A = \mathbb{R}^d, p = 2$: centroid
(just the component-wise average)

$A = \mathbb{R}^d, p = 1$: geometric median

Prototypes of data classes $X = \{x_i\}_{i=1}^s \subset \mathbb{R}^d$ often solve

$$\min_{y \in A} \sum_{i=1}^s \|x_i - y\|_2^p.$$

$A = \mathbb{R}^d, p = 2$: centroid
(just the component-wise average)

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$p = 2$: closed form solution as a least squares problem

$p = 1$: less sensitive to outliers

WEISZFELD ALGORITHM I

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A geometric median y of $\{x_i\}_{i=1}^s$ satisfies

$$y = \left(\sum_{i=1}^s \frac{x_i}{\|x_i - y\|_2} \right) \left(\sum_{k=1}^s \frac{1}{\|x_k - y\|_2} \right)^{-1}.$$

WEISZFELD ALGORITHM II

Given $\{x_i\}_{i=1}^s \subset \mathbb{R}^d$,

compute until converged:

$$y = \frac{1}{s} \sum_{i=1}^s \omega_i x_i, \quad \omega_i = \frac{p}{\|x_i - y\|_2} \left(\sum_{k=1}^s \frac{1}{\|x_k - y\|_2} \right)^{-1}.$$

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Such algorithms are called **iteratively reweighted least squares (IRLS)**.

GEOMETRY ON THE GRASSMANNIAN

Let $\mathbf{Gr}(r, d)$ denote the **Grassmannian** of r -dimensional subspaces of \mathbb{R}^d .

For $W_j \in \mathbf{Gr}(r, d)$, let P_j denote the orthogonal projection onto W_j .

Between W_j and W_k , the

- ▶ **chordal distance** is $\frac{1}{\sqrt{2}} \|P_j - P_k\|_{Fro}$ and the
- ▶ **geodesic distance** is $\|\Theta\|_2$,
where Θ is a vector of the square-root-arccos of the singular values of $P_j P_k$.

SUBSPACE PROTOTYPES

Given W_1, W_2, \dots, W_s where $W_i \in \text{Gr}(k_i, n)$ and d chordal or geodesic distance, what is

$$\min_{Y \in \text{Gr}(r, n)} \sum_{i=1}^s d(W_i, Y)^p?$$

d chordal distance, $p = 2$: flag mean
(r -dimensional PCA)

d geodesic distance, $p = 2$: Karcher mean
(only for $k_1 = \dots = k_s$)

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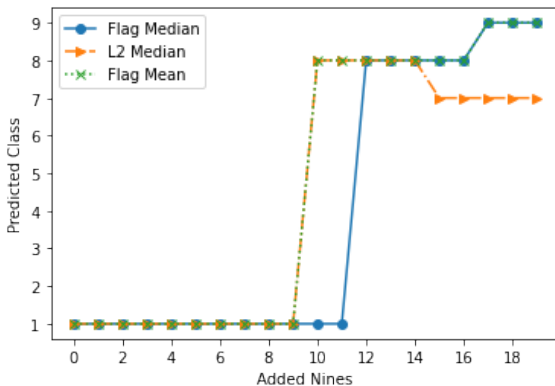
FLAGIRLS

Key Idea:

As with Weiszfeld, we leverage the fact that the flag mean solution has a closed form (here: via PCA).

We solve a sequence of flag mean problems with weighted subspace orthonormal bases (ONB).

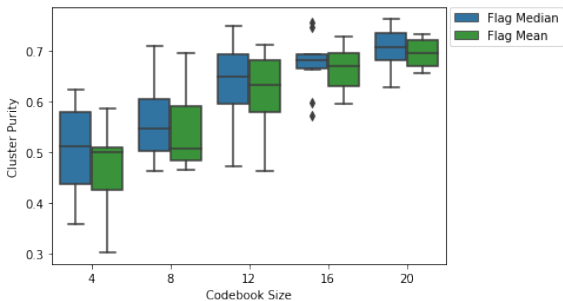
The weights were determined using Lagrangians.



The neural network predicted class of the prototype for the dataset with **20** examples of 1's and i examples of 9's from MNIST with $i = 0, 1, 2, \dots, 19$.



An example of frames from the YouTube dataset. Liu, Luo, Shah 2009



An LBG implementation on the YouTube dataset. The results of 2 different implementations of LBG for codebook sizes **4, 8, 12, 16** and **20**. The flag median outperforms flag mean for all codebook sizes.

CONCLUSION



Original meme downloaded from <https://memegenerator.net/instance/53842731/mark-twain-reports-of-my-death-are-greatly-exaggerated>

Thanks for your time
and tryphobia I now have!

For papers and software:

<https://www.math.colostate.edu/~king>

CodEx Seminar:

A pan-university, remote seminar on the theory and applications of harmonic analysis, combinatorics, and algebra

<https://www.math.colostate.edu/~king/codex>