# The Mathematics of Geographic Profiling

#### Towson University Applied Mathematics Laboratory

#### Dr. Mike O'Leary

Crime Hot Spots: Behavioral, Computational and Mathematical Models Institute for Pure and Applied Mathematics January 29 - February 2, 2007

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### **Project Participants**

- Towson University Applied Mathematics Laboratory
  - Undergraduate research projects in applied mathematics.
  - Founded in 1980
- National Institute of Justice
- Special thanks to Stanley Erickson (NIJ) and Andrew Engel (SAS)

## **Students**

- 2005-2006:
  - Paul Corbitt
  - Brooke Belcher
  - Brandie Biddy
  - Gregory Emerson
- 2006-2007:
  - Chris Castillo
  - Adam Fojtik

- Laurel Mount
- Ruozhen Yao
- Melissa Zimmerman
- Jonathan Vanderkolk
- Grant Warble

# **Geographic Profiling**

The Question:

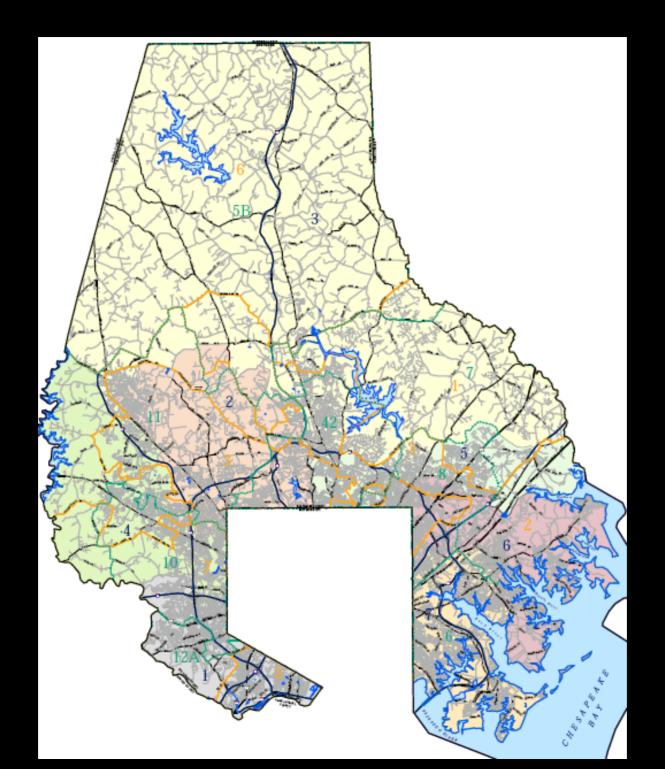
Given a series of linked crimes committed by the same offender, can we make predictions about the anchor point of the offender?

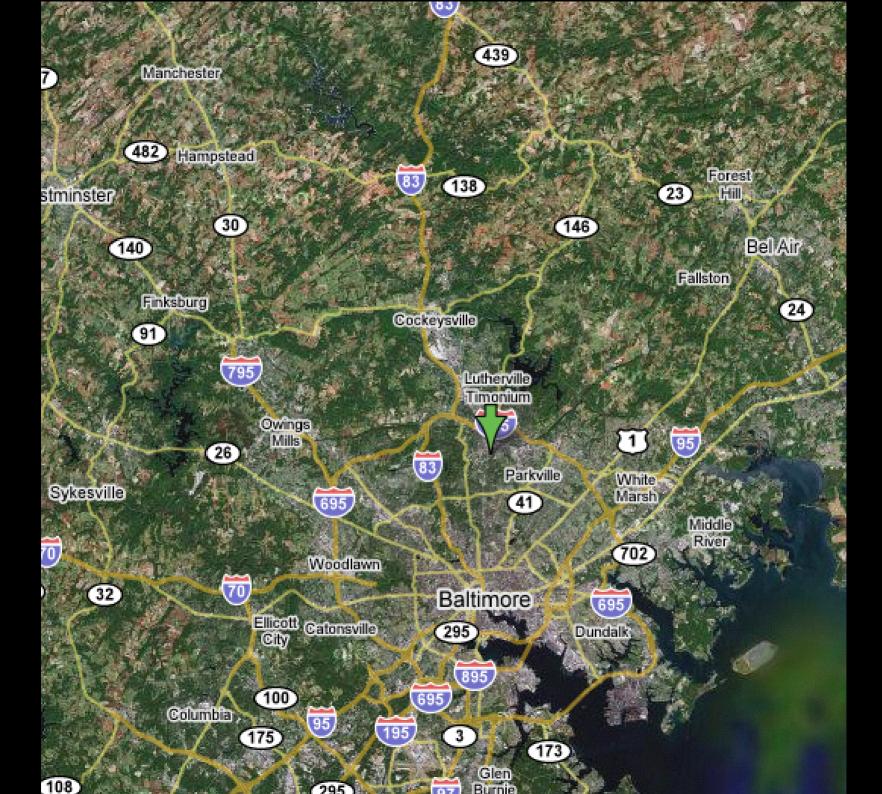
 The anchor point can be a place of residence, a place of work, or some other commonly visited location.

# **Geographic Profiling**

- Our question is *operational*.
  - This places limitations on available data.

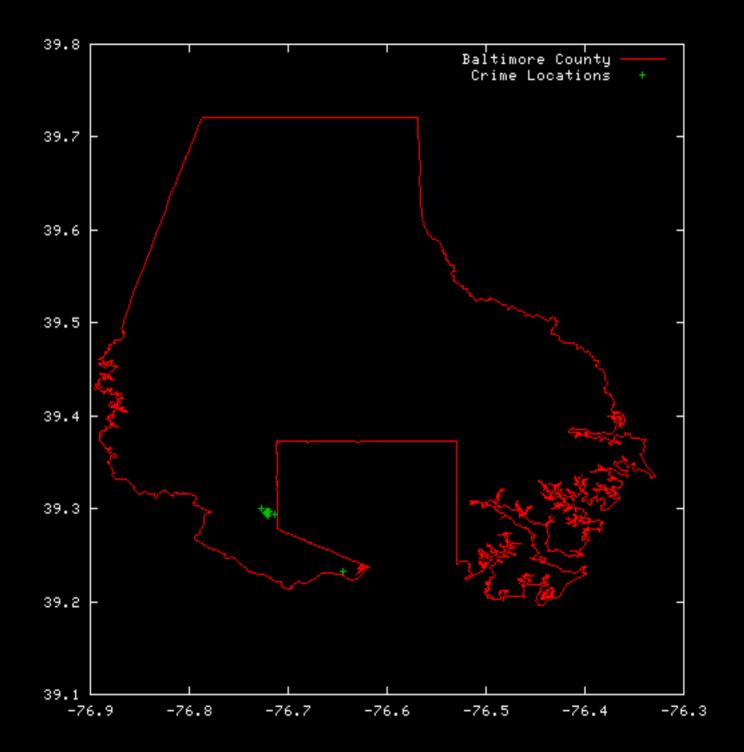
- Example
  - A series of 9 linked vehicle thefts in Baltimore County





# Example

ADDRESS	DATE_FROM	TIME	DATE_TO	TIME	REMARKS
918 M	01/18/2003	0800	01/18/2003	0810	VEHICLE IS O1 TOYT CAMRY, LEFT VEH RUNNING
1518 L	01/22/2003	0700	01/22/2003	0724	VEHICLE IS 99 HOND ACCORD STL-REC,B/M PAIR,DRIVING MAROON ACCORD.
731 CC	01/22/2003	0744	01/22/2003	0746	VEHICLE IS O2 CHEV MALIBU STL-REC
1527 K	01/27/2003	1140	01/27/2003	1140	VEHICLE IS 97 MERC COUGAR, LEFT VEH RUNNING
1514 G	01/29/2003	0901	01/29/2003	0901	VEHICLE IS 99 MITS DIAMONTE, LEFT VEH RUNNING
1415 K	01/29/2003	1155	01/29/2003	1156	VEHICLE IS OO TOYT 4RUNNER STL-REC, (4) ARREST NFI
5943 R	12/31/2003	0632	12/31/2003	0632	VEHICLE IS 92 BMW 525, WARMING UP VEH
1427 G	02/17/2004	0820	02/17/2004	0830	VEHICLE IS OO HOND ACCORD, WARMING VEH
4449 S	05/15/2004	0210	05/15/2004	0600	VEHICLE IS 04 SUZI ENDORO



### **Existing Methods**

- Spatial distribution strategies
- Probability distance strategies
- Notation:
  - Anchor point-  $z = (z^{(1)}, z^{(2)})$
  - Crime sites-  $x_1, x_2, \cdots, x_n$
  - Number of crimes- *n*

#### Distance

Euclidean

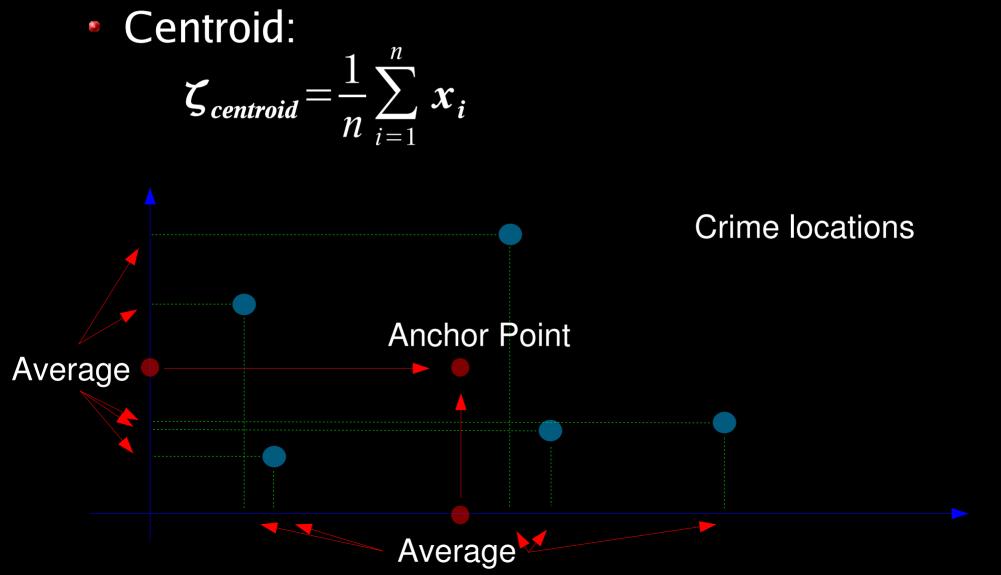
$$d_2(\mathbf{x}, \mathbf{y}) = \sqrt{(x^{(1)} - y^{(1)})^2 + (x^{(2)} - y^{(2)})^2}$$

Manhattan

$$d_1(\mathbf{x}, \mathbf{y}) = |x^{(1)} - y^{(1)}| + |x^{(2)} - y^{(2)}|$$

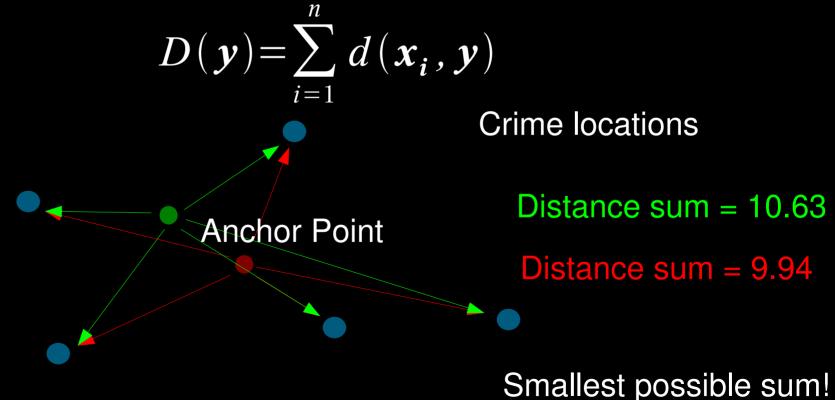
Street grid

#### **Spatial Distribution Strategies**



#### **Spatial Distribution Strategies**

• Center of minimum distance:  $\zeta_{cmd}$  is the value of y that minimizes



## **Spatial Distribution Strategies**

- Circle Method:
  - Anchor point contained in the circle whose diameter are the two crimes that are farthest apart.

Crime locations

Anchor Point

### **Probability Distribution Strategies**

- The anchor point is located in a region with a high "hit score".
- The hit score S(y) has the form

$$S(\mathbf{y}) = \sum_{i=1}^{n} f(d(\mathbf{y}, \mathbf{x}_{i}))$$
  
=  $f(d(\mathbf{z}, \mathbf{x}_{1})) + f(d(\mathbf{z}, \mathbf{x}_{2})) + \dots + f(d(\mathbf{z}, \mathbf{x}_{n}))$ 

where  $x_i$  are the crime locations and f is a decay function and d is a distance.

# **Probability Distribution Strategies**

#### Linear:

• 
$$f(d) = A - Bd$$



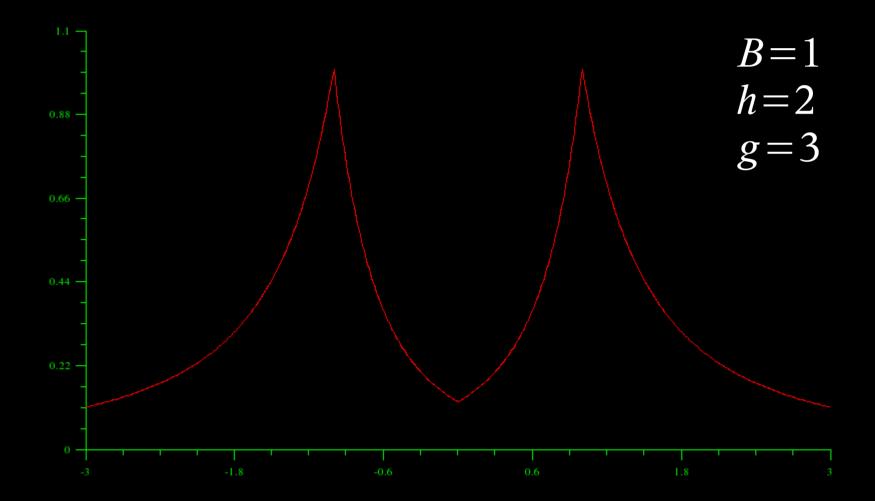
#### Rossmo

- Manhattan distance metric.
- Decay function

$$f(d) = \begin{cases} \frac{k}{d^{h}} & \text{if } d > B \\ \frac{k B^{g-h}}{(2B-d)^{g}} & \text{if } d \leq B \end{cases}$$

The constants k, g, h and B are empirically defined

#### Rossmo



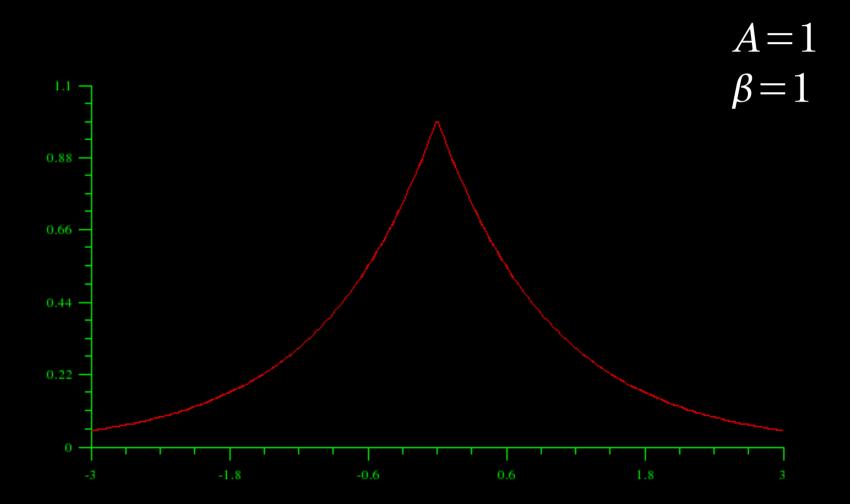
## Canter, Coffey, Huntley & Missen

- Euclidean distance
- Decay functions

$$f(d) = A e^{-\beta d}$$

$$f(d) = \begin{cases} 0 & \text{if } d < A, \\ B & \text{if } A \le d < B, \\ Ce^{-\beta d} & \text{if } d \ge B. \end{cases}$$





#### Levine

- Euclidean distance
- Decay functions
  - Linear f(d) = A + Bd
  - Negative exponential

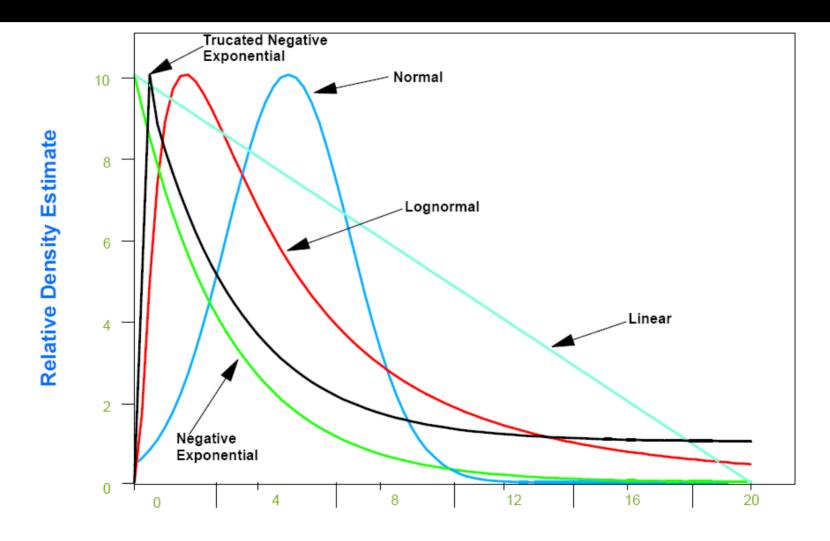
$$f(d) = A e^{-\beta d}$$

Normal

$$f(d) = \frac{A}{\sqrt{2\pi S^2}} \exp\left[\frac{-(d-d)^2}{2S^2}\right]$$

• Lognormal  $f(d) = \frac{A}{d\sqrt{2\pi S^2}} \exp\left[\frac{-(\ln d - \overline{d})^2}{2S^2}\right]$ 

#### **CrimeStat**



**Distance from Crime** 

From Levine (2004)

# CrimeStat

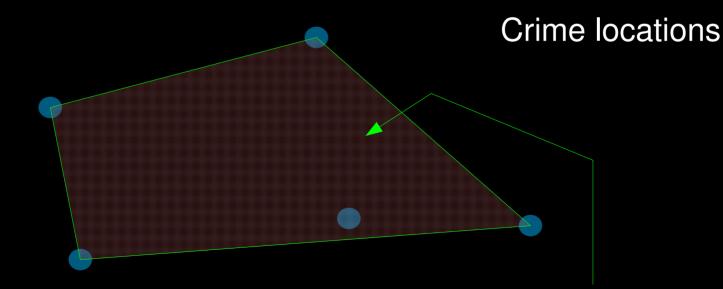
Section CrimeStat III							
Data setup Spatial description Spatial modeling Crime travel of	demand Options						
Interpolation       Space-time analysis       Journey-to-Crime         Calibrate Journey-to-crime function							
Journey-to-crime estimation (Jtc)     Incident file:     Primary     Use already-calibrated distance function	Save output to						
Image: Select data file	Files        Select Files         Origin coordinates       Edit       Remove         File       Column       Missing values         X       C:\Documents and Settings\moleary\My Docu        None>          Y       C:\Documents and Settings\moleary\My Docu            Destination coordinates       File       Column       Missing values         X       C:\Documents and Settings\moleary\My Docu            Destination coordinates       File       Column       Missing values         X       C:\Documents and Settings\moleary\My Docur           Y       C:\Documents and Settings\moleary\My Docur						
<u>C</u> ompute <u>Q</u> uit	Type of coordinate system       Data units            • Longtitude, latitude (spherical)         • Projected (Euclidean)         • Directions (angles)           • Decimal Degrees         • Miles         • Feet         • Kilometers         • Meters         • Nautical miles             • Directions (angles)           • Meters         • Nautical miles						

#### **Shortcomings**

- These techniques are all *ad hoc*.
- What is their theoretical justification?
  - What assumptions are being made about criminal behavior?
  - What mathematical assumptions are being made?
- How do you choose one method over another?

#### **Shortcomings**

- The convex hull effect:
  - The anchor point always occurs inside the convex hull of the crime locations.





#### **Shortcomings**

- How do you add in local information?
  - How could you incorporate socioeconomic variables into the model?

Snook, Individual differences in distance travelled by serial burglars
Malczewski, Poetz & lannuzzi, Spatial analysis of residential burglaries in London, Ontario
Bernasco & Nieuwbeerta, How do residential burglars select target areas?
Osborn & Tseloni, The distribution of household property crimes

#### A New Approach

- In previous methods, the unknown quantity was:
  - The anchor point (spatial distribution strategies)
  - The hit score

(probability distance strategies)

• We use a different unknown quantity.

#### A New Approach

- Let P(x;z) be the density function for the probability that an offender with anchor point z commits a crime at location x.
  - This distribution is our new unknown.
  - This has criminological significance.
    - In particular, assumptions about the form of P(x;z) are equivalent to assumptions about the offender's behavior.

#### The Mathematics

• Given crimes located at  $x_1, x_2, \dots, x_n$  the *maximum likelihood estimate* for the anchor point  $\zeta_{mle}$  is the value of y that maximizes  $L(y) = \prod_{i=1}^{n} P(x_i, y)$   $= P(x_1, y) P(x_2, y) \cdots P(x_n, y)$ 

or equivalently, the value that maximizes  $\lambda(\mathbf{y}) = \sum_{i=1}^{n} \ln P(\mathbf{x}_i, \mathbf{y})$   $= \ln P(\mathbf{x}_1, \mathbf{y}) + \ln P(\mathbf{x}_2, \mathbf{y}) + \dots + \ln P(\mathbf{x}_n, \mathbf{y})$ 

# Relation to Spatial Distribution Strategies

 If we make the assumption that offenders choose target locations based only on a distance decay function in normal form, then

$$P(\boldsymbol{x};\boldsymbol{z}) = \frac{1}{2\pi\sigma^2} \exp\left[-\frac{|\boldsymbol{x}-\boldsymbol{z}|^2}{2\sigma^2}\right]$$

• The maximum likelihood estimate for the anchor point is the centroid.

# Relation to Spatial Distribution Strategies

 If we make the assumption that offenders choose target locations based only on a distance decay function in exponentially decaying form, then

$$P(\mathbf{x};\mathbf{z}) = \frac{1}{2\pi\sigma^2} \exp\left[-\frac{|\mathbf{x}-\mathbf{z}|}{2\sigma}\right]$$

 The maximum likelihood estimate for the anchor point is the center of minimum distance.

## Relation to Probability Distance Strategies

• What is the log likelihood function?

$$\lambda(\mathbf{y}) = \sum_{i=1}^{n} \left[ -\ln\left(2\pi\sigma^2\right) - \frac{|\mathbf{x}_i - \mathbf{y}|}{\sigma} \right]$$

• This is the hit score S(y) provided we use Euclidean distance and the linear decay f(d)=A+Bd for

$$A = -\ln(2\pi\sigma^2)$$
$$B = -1/\sigma$$

#### Parameters

 The maximum likelihood technique does not require a priori estimates for parameters other than the anchor point.

$$P(\mathbf{x};\mathbf{z},\sigma) = \frac{1}{2\pi\sigma^2} \exp\left[-\frac{|\mathbf{x}-\mathbf{z}|^2}{2\sigma^2}\right]$$

The same process that determines the best choice of z also determines the best choice of  $\sigma$  .

#### **Better Models**

- We have recaptured the results of existing techniques by choosing P(x;z) appropriately.
- These choices of P(x;z) are not very realistic.
  - Space is homogeneous and crimes are equi-distributed.
  - Space is infinite.
  - Decay functions were chosen arbitrarily.

#### **Better Models**

- Our framework allows for better choices of P(x; z).
- Consider

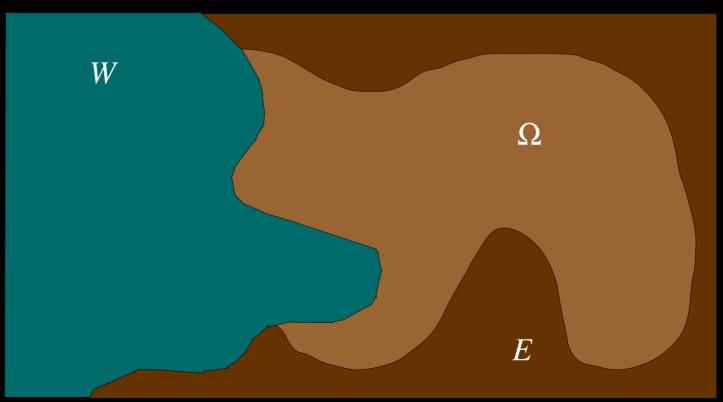
$$P(\mathbf{x}; \mathbf{z}) = D(d(\mathbf{x}, \mathbf{z})) \cdot G(\mathbf{x}) \cdot N(z)$$

Distance Decay (Dispersion Kernel) Geographic factors

Normalization

#### The Simplest Case

 Suppose we have information about crimes committed by the offender only for a portion of the region.



- Regions
  - Ω: Jurisdiction(s). Crimes and anchor points may be located here.
  - *E*: "elsewhere". Anchor points may lie here, but we have no data on crimes here.
  - W: "water". Neither anchor points nor crimes may be located here.
- In all other respects, we assume the geography is *homogeneous*.

• We set  

$$G(x) = \begin{cases} 1 & x \in \Omega \\ 0 & x \notin \Omega \end{cases}$$

# We choose an appropriate decay function $D(|\mathbf{x}-\mathbf{z}|) = \exp\left[-\frac{|\mathbf{x}-\mathbf{z}|^2}{2\sigma^2}\right]$

The required normalization function is

$$N(\mathbf{x}; \mathbf{z}) = \left[ \iint_{\Omega} \exp\left(-\frac{|\mathbf{y}-\mathbf{z}|^2}{2\sigma^2}\right) dy^{(1)} dy^{(2)} \right]^{-1}$$

Our estimate ζ<sub>mle</sub> of the anchor point is the choice of *y* that maximizes

$$\exp\left(-\sum_{i=1}^{n} \frac{|\boldsymbol{x}_{i} - \boldsymbol{y}|^{2}}{2\sigma^{2}}\right)$$
$$\left[\iint_{\Omega} \exp\left(-\frac{|\boldsymbol{\eta} - \boldsymbol{y}|^{2}}{2\sigma^{2}}\right) d\eta^{(1)} d\eta^{(2)}\right]^{n}$$

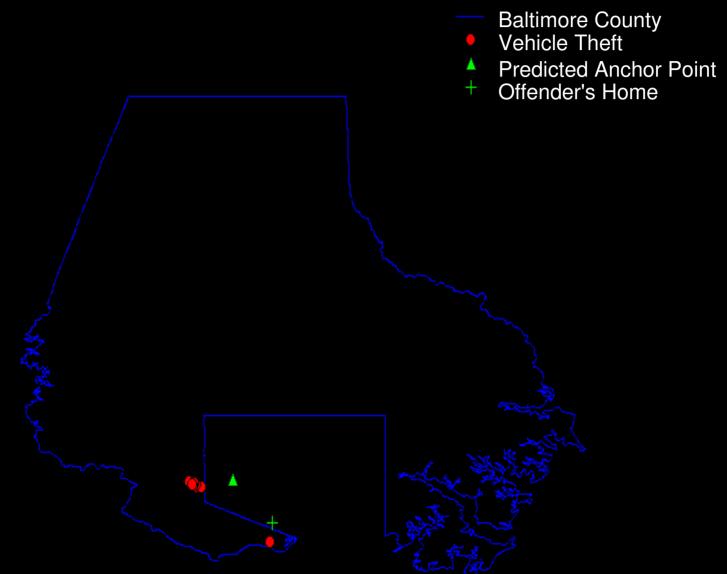
- Our students wrote code to implement this method last year, and tested it on real crime data from Baltimore County.
- We used Green's theorem to convert the double integral to a line integral.

$$\iint_{\Omega} \exp\left(\frac{-|\eta-y|^2}{2\sigma^2}\right) d\eta^{(1)} d\eta^{(2)} = \oint_{\partial\Omega} \frac{-\sigma^2}{|\eta-y|} \exp\left(\frac{-|\eta-y|^2}{\beta}\right) \left(\boldsymbol{e_r} \cdot \boldsymbol{n}\right) ds + \begin{cases} \beta \pi & z \in \Omega\\ 0 & z \notin \Omega \end{cases}$$

 Baltimore county was simply a polygon with 2908 vertices.

- To calculate the maximum, we used the BFGS method.
  - Search in the direction  $D_n \nabla f(\mathbf{y}_n)$  where  $D_{n+1} = D_n + \left(1 + \frac{\mathbf{g}^T D_n \mathbf{g}}{\mathbf{d}^T \mathbf{g}}\right) \frac{\mathbf{d}\mathbf{d}^T}{\mathbf{d}^T \mathbf{g}} - \frac{D_n \mathbf{g}\mathbf{d}^T + \mathbf{g}\mathbf{d}^T D_n}{\mathbf{d}^T \mathbf{g}}$   $\mathbf{d} = \mathbf{y}_{n+1} - \mathbf{y}_n$  $\mathbf{g} = \nabla f(\mathbf{y}_{n+1}) - \nabla f(\mathbf{y}_n)$
  - For the 1-D optimization we used the bisection method.

## Sample Results



#### **Better Models**

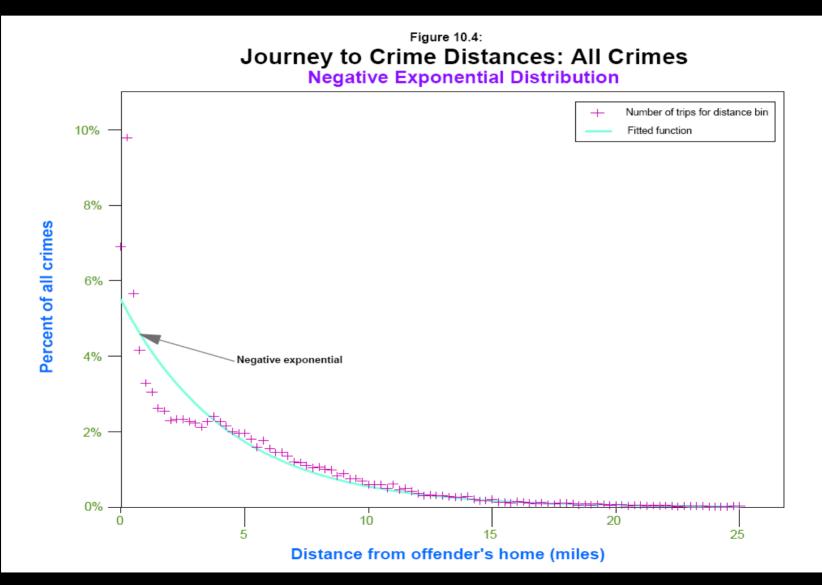
- This is just a modification of the centroid method that accounts for possibly missing crimes outside the jurisdiction.
- Clearly, better models are needed.

#### **Better Models**

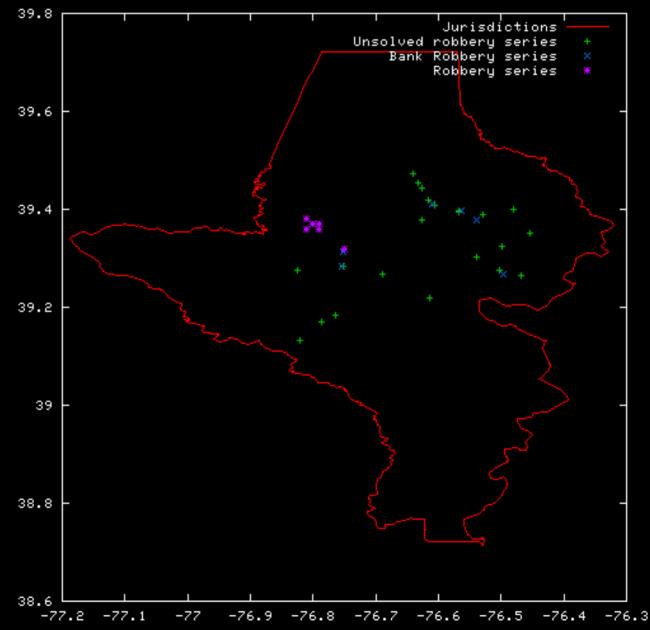
Recall our ansatz

$$P(\mathbf{x}; \mathbf{z}) = D(d(\mathbf{x}, \mathbf{z})) \cdot G(\mathbf{x}) \cdot N(\mathbf{z})$$

- What would be a better choice of *D*?
- What would be a better choice of *G*?

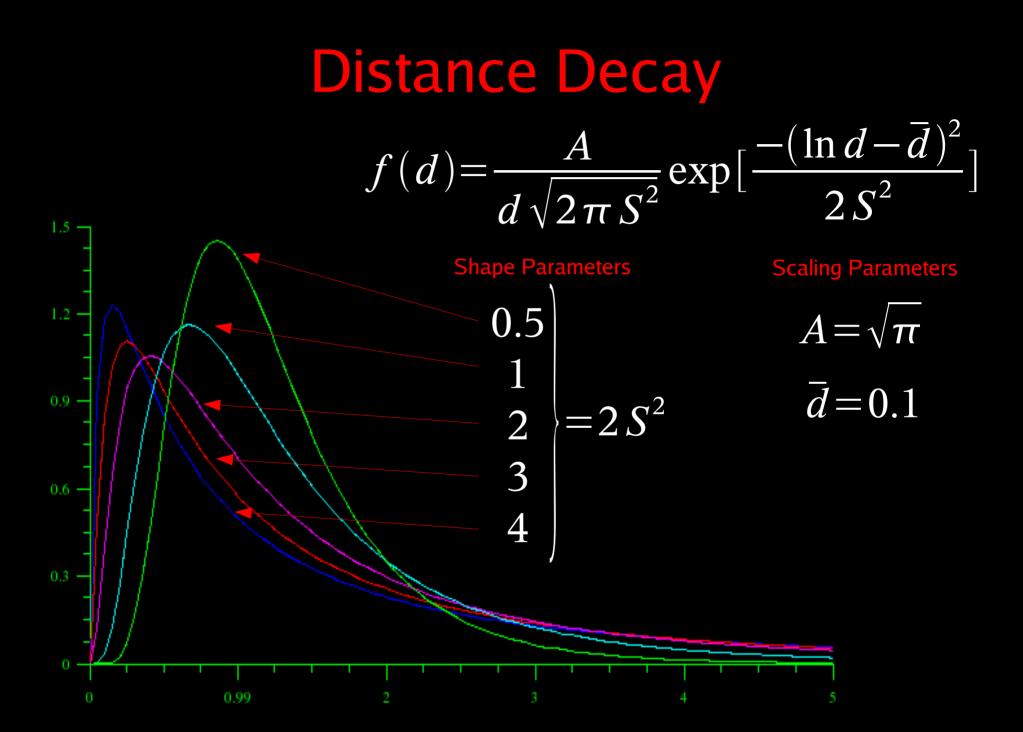


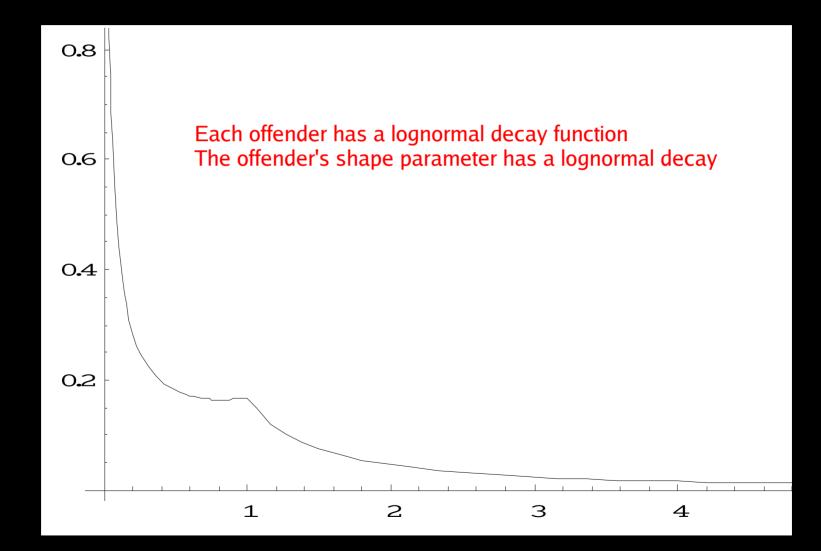
From Levine (2004)

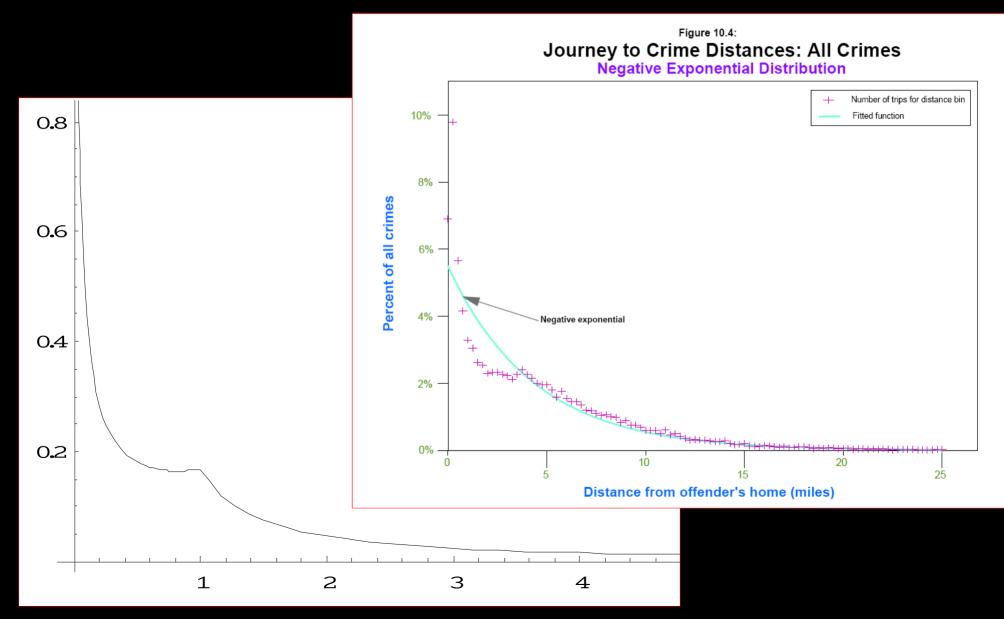


- Suppose that each offender has a decay function  $f(d;\lambda)$  where  $\lambda \in (0,\infty)$  varies among offenders according to the distribution  $\phi(\lambda)$ .
- Then if we look at the decay function for all offenders, we obtain the aggregate distribution

$$F(d) = \int_{0}^{\infty} f(d;\lambda) \cdot \phi(\lambda) \, d\,\lambda$$





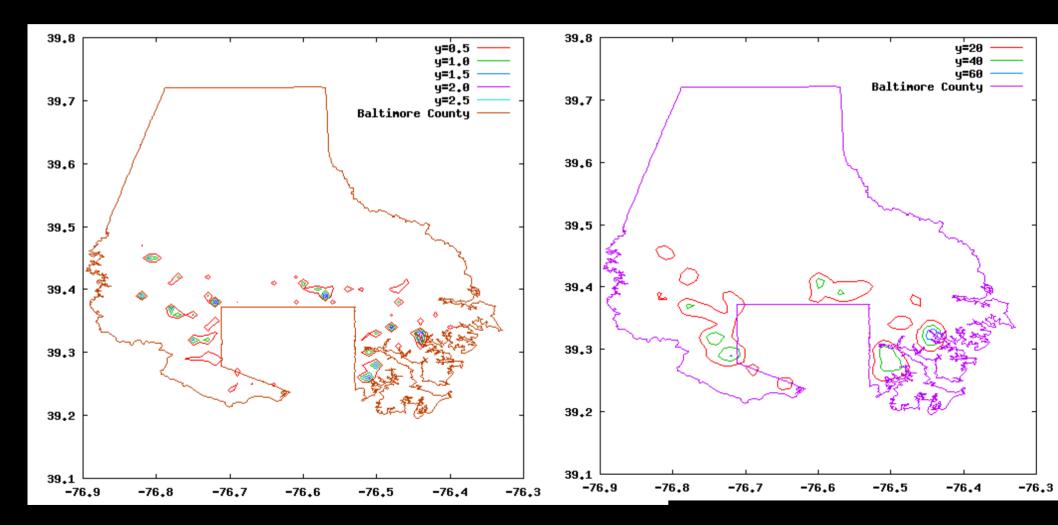


- Is this real, or an artifact?
- How do we determine the "best" choice of decay function?
  - This needs to be determined in advance.
- Will it vary depending on
  - crime type?
  - Iocal geography?

## Geography

- Let G(x) represent the local density of potential targets.
  - Rather than look for features (demographic, geographic) to predict it, we can use historical data to measure it.
  - G(x) could then be calculated in the same fashion as hot spots; e.g. by kernel density parameter estimation.
    - Issues with boundary conditions

## Geography



## Geography

- No calibration is required if G(x) is calculated in this fashion.
  - An analyst can determine what historical data should be used to generate the geographic target density function.
  - Different crime types will necessarily generate different functions G(x).

## Strengths of this Framework

- All of the assumptions on criminal behavior are made in the open.
  - They can be challenged, tested, discussed and compared.

## Strengths

- The framework is extensible.
  - Vastly different situations can be modelled by making different choices for the form and structure of P(x;z).

• *e.g.* angular dependence, barriers.

 The framework is otherwise agnostic about the crime series; all of the relevant information must be encoded in P(x;z).

## Strengths

- This framework is mathematically rigorous.
  - There are mathematical and criminological meanings to the maximum likelihood estimate  $\zeta_{\rm mle}$  .

## Weaknesses of this Framework

#### GIGO

- The method is only as accurate as the accuracy of the choice of P(x;z).
- It is unclear what the right choice is for P(x;z)
  - Even with the simplifying assumption that

 $P(\mathbf{x}; \mathbf{z}) = D(d(\mathbf{x}, \mathbf{z})) \cdot G(\mathbf{x}) \cdot N(\mathbf{z})$ 

this is difficult.

#### Weaknesses

- There is no simple closed mathematical form for  $\zeta_{\rm mle}$ 
  - Relatively complex techniques are required to estimate  $\zeta_{mle}$  even for simple choices of P(x;z).
- The error analysis for maximum likelihood estimators is delicate when the number of data points is small.

#### Weaknesses

- The framework assumes that crime sites are independent, identically distributed random variables.
  - This is probably false in general!
- This should be a solvable problem though...

#### Weaknesses

- We only produce the point estimate of  $\zeta_{mle}$ .
  - Law enforcement agencies do not want "X Marks the Spot".
  - A search area, rather than a point estimate is far preferable.
- This should be possible with some Bayesian analysis

#### **Questions?**

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