

Fundamentals of estimation theory applied to wavefront reconstruction and adaptive optics control

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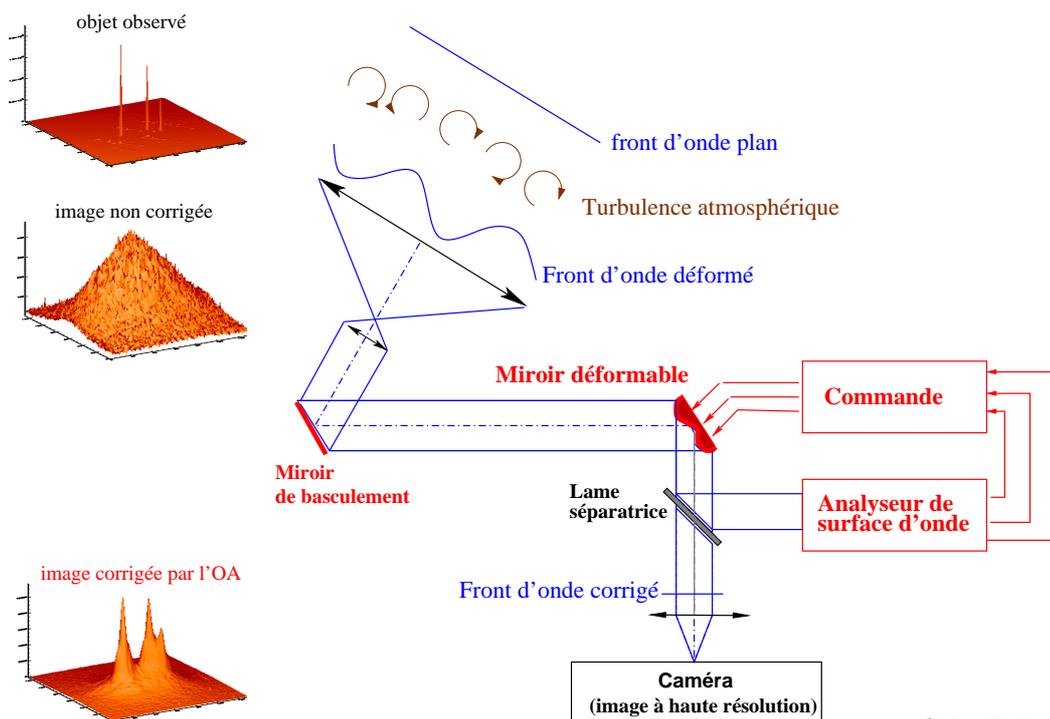
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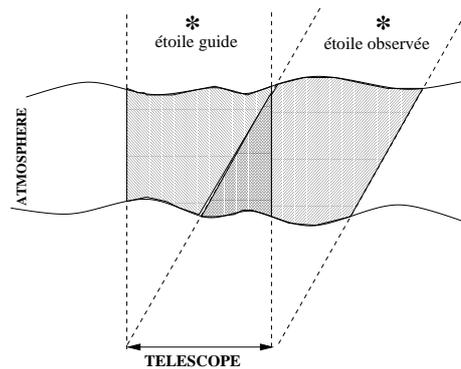
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Principle of Adaptive Optics



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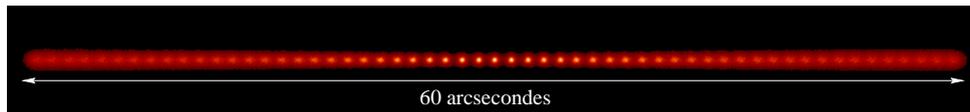
Adaptive Optics and Anisoplanatism



Anisoplanatism → evolution of the turbulent phase in the field of view

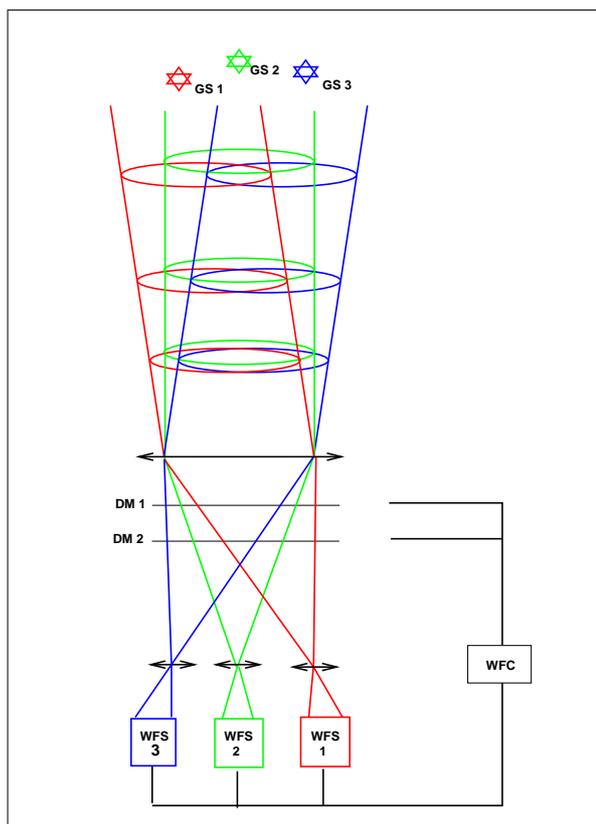
Classical Adaptive Optics (AO) :

- 1 deformable mirror [DM] in pupil → ϕ_{corr} independent of position in the field
- 1 guide star with ϕ_{corr} optimized in guide star direction



Correction quality degrades away from the guide star

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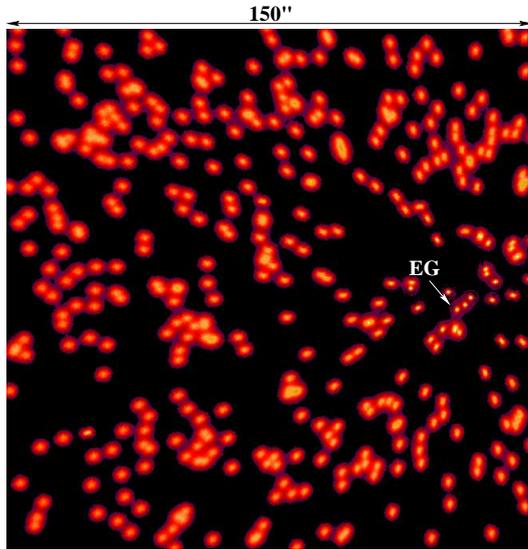
Inverse Problems in AO/MCAO

- Wavefront Reconstruction from WFS data
- Optimal Mirror Control derived from WFS data
 - static mode : open loop, one data sample
 - dynamic mode : closed loop with delay, time series
- Corrected Image Processing : deconvolution.

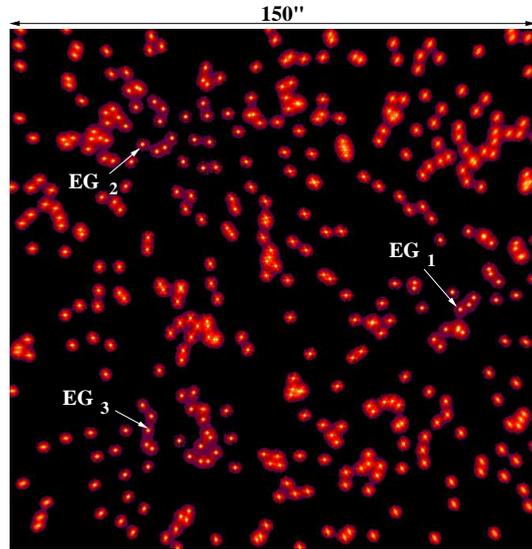
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Expected Performance

- Observation at $2.2\mu m$ on a 8 m telescope.
- 3 Guide Stars, 2 Deformable Mirrors



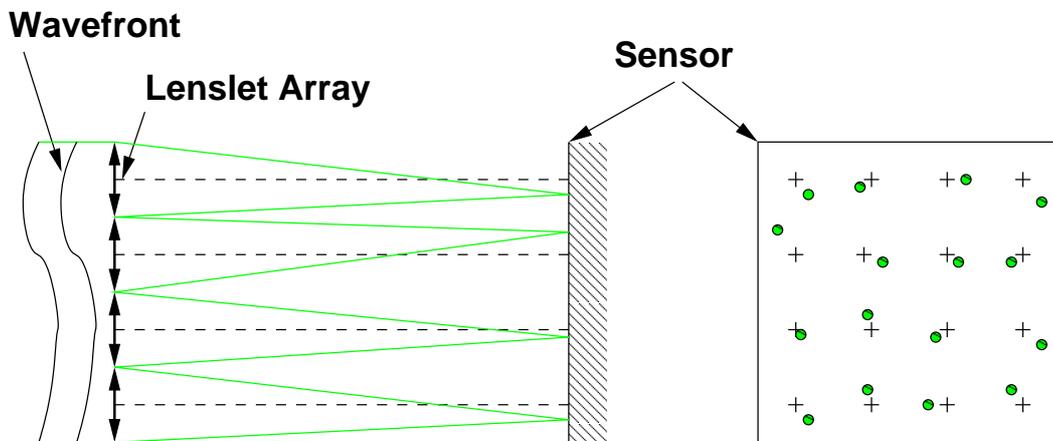
regular AO



MCAO

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Principle of the Shack-Hartmann WFS



K sub-apertures $\longrightarrow 2 K$ slopes $\{s_{x/y,i}\} = s$

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Shack-Hartmann Model

- Shack-Hartmann measurements :

$$s_{x,i} = \frac{\lambda f}{2 \pi S_i} \int_{S_i} \frac{\partial \phi(x, y)}{\partial x} dx dy + noise$$

- Linear model :

$$s = D\phi + w$$

with for instance : $\phi = \{\phi_j\}$ and $\phi(x, y) = \sum_{j=2}^{j_{max}} \phi_j Z_j(x, y)$

$$D = 2K \begin{pmatrix} \leftarrow j_{max} \rightarrow \\ \cdot \\ \cdot \\ \cdot \end{pmatrix}$$

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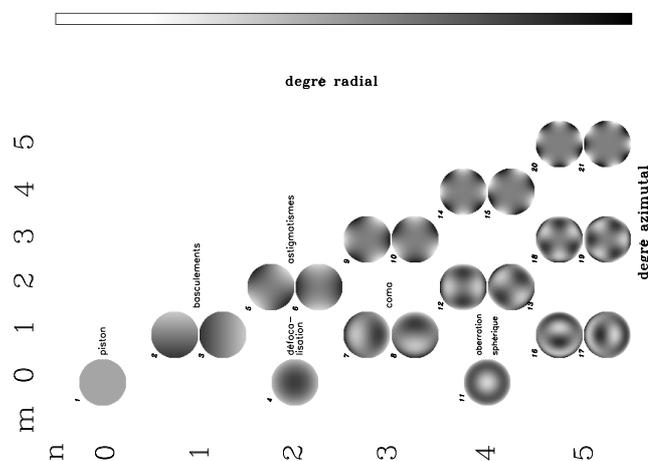
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Zernike Polynomials

Decomposition on a modal basis $\{Z_i\}$:

$$\phi(\mathbf{r}) = \sum_i \phi_i Z_i(\mathbf{r})$$

polynômes de Zernike



Radial Degree n \nearrow \longleftrightarrow Spatial Frequency \nearrow

WaveFront Reconstruction Least Square Solution

- Looking for phase giving a best fit to the measurements :

$$\hat{\phi} = \arg \min_{\phi} \|s - D\phi\|^2$$

- Analytical solution :

$$\hat{\phi} = (D^t D)^{-1} D^t s = R s$$

- Noise propagation : noise covariance matrix

$$C_{\phi \text{ noise}} = R C_w R^T$$

⚠ If $D^t D$ ill conditioned \iff badly seen modes
 \implies noise amplification

Maximum Likelihood Reconstruction a Weighted Least Square Solution

- Likelihood : probability of the measurement (slopes) with a known phase,

$$p(s|\phi) \propto \exp\left(-\frac{1}{2}(s - D\phi)^t C_w^{-1} (s - D\phi)\right)$$

- We look for the phase that makes the measurements the most probable ones :

$$\hat{\phi}_{\text{ML}} = \arg \max_{\phi} p(s|\phi) = \arg \min_{\phi} (s - D\phi)^t C_w^{-1} (s - D\phi)$$

- Analytical solution :

$$\hat{\phi}_{\text{ML}} = (D^t C_w^{-1} D)^{-1} D^t C_w^{-1} s$$

- Particular Case $C_w = \sigma_w^2 Id$:

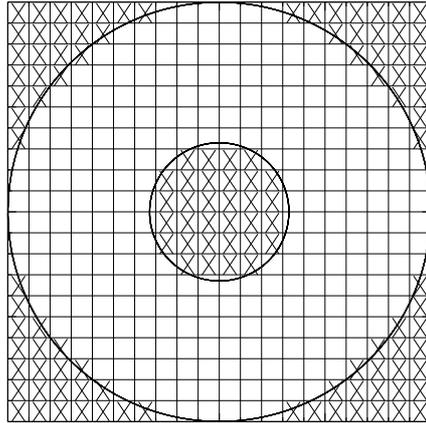
$$\hat{\phi}_{\text{ML}} = \arg \min_{\phi} \|s - D\phi\|^2 = (D^t D)^{-1} D^t s,$$

least square fit on the measurements

In general, $D^t C_w^{-1} D$ badly conditioned \implies ML unacceptable
 \implies "Truncated" ML : TSVD on $D^t C_w^{-1} D$
 or limit the dimension of the phase space

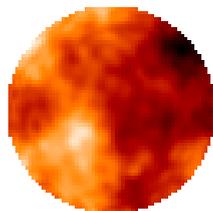
Numerical Simulation : Shack-Hartmann WFS Geometry

- 20×20 sub-apertures
- central occultation $d/D = 0.33$
- $K = 276$ valid sub-apertures
 $\implies 2 \times 276 = 552$ slope measurements

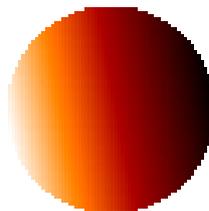


Truncated Maximum Likelihood

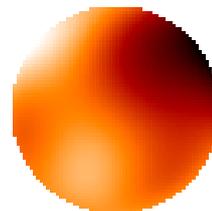
$SNR_{slopes} = 1.$, $K = 276$ sub-apertures



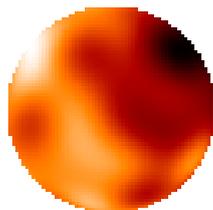
True Phase



ML $j_{max} = 3$



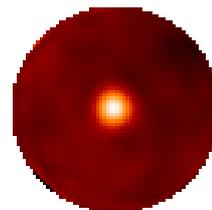
ML $j_{max} = 21$



ML $j_{max} = 55$



ML $j_{max} = 105$



ML $j_{max} = 210$

Reconstruction quality highly dependent of j_{max}
optimum j_{max} depends on SNR_{slopes}

Optimal Reconstruction : Maximum A Posteriori

- **Probability A Posteriori**: probability of the phase for a given measurement

$$p(\phi|s) \propto p(s|\phi) \times p(\phi)$$

$$\propto \exp\left(-\frac{1}{2}(s - D\phi)^t C_n^{-1}(s - D\phi)\right) \times \exp\left(-\frac{1}{2}\phi^t C_\phi^{-1}\phi\right)$$

- **MAP solution** : most probable phase for a given measurement

$$\hat{\phi}_{\text{MAP}} = \arg \max_{\phi} p(\phi|s) = \arg \min_{\phi} -2 \cdot \ln(p(\phi|s))$$

$$= \arg \min_{\phi} (s - D\phi)^t C_n^{-1}(s - D\phi) + \phi^t C_\phi^{-1}\phi$$

$$= \left(D^t C_n^{-1} D + C_\phi^{-1}\right)^{-1} D^t C_n^{-1} s = C_\phi D^t (D C_\phi D^t + C_n)^{-1} s$$

If Gaussian priors justified, MAP solution is also the MMSE solution $\hat{\phi}_{\text{mmse}}$:

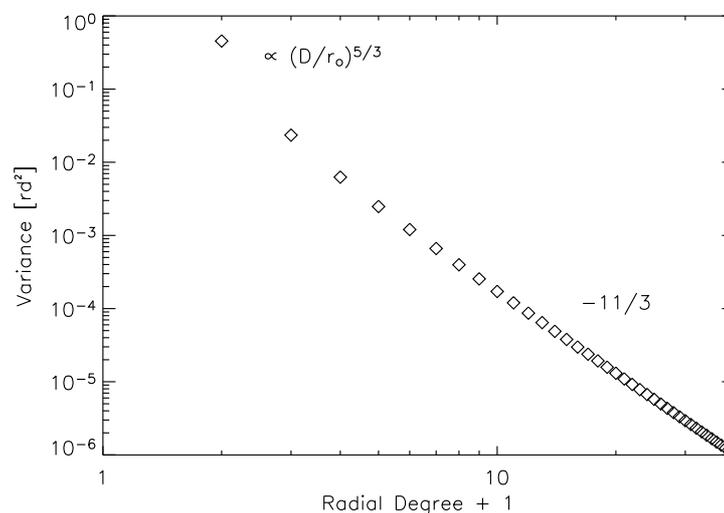
$$\left\langle \|\phi - \hat{\phi}_{\text{mmse}}\|^2 \right\rangle_{\phi, w} = \left\langle \int_{Pup} [\phi(x, y) - \hat{\phi}_{\text{mmse}}(x, y)]^2 dx dy \right\rangle_{\phi, w}$$

minimum mean square error on the phase!

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Statistical Characteristics of the Turbulent Phase

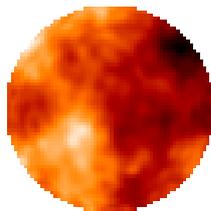
- Kolmogorov spectrum \longrightarrow covariance matrix C_ϕ .
- $C_\phi(j, j) = \sigma_{\phi_j}^2$, energy distribution on Zernikes :



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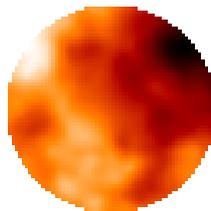
Optimal Reconstruction

$SNR_{slopes} = 1. , K = 276$ sub-apertures



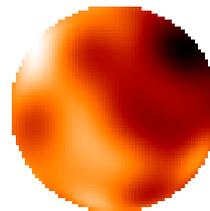
True Phase

$$[\sigma_{\phi}^2 = 3.0 \text{ rd}^2]$$



MAP/MMSE

$$[\sigma_{error}^2 = 0.7 \text{ rd}^2]$$

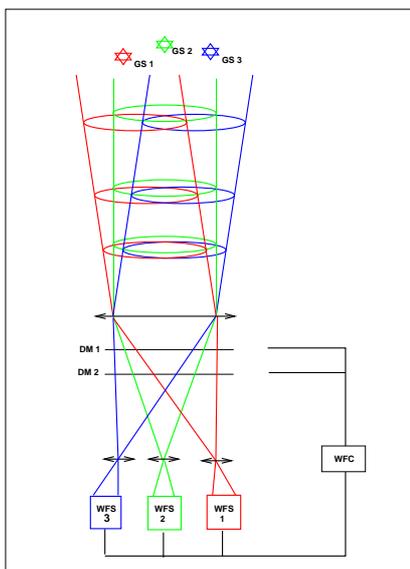


ML $j_{max} = 55$

$$[\sigma_{error}^2 = 0.8 \text{ rd}^2]$$

Optimal estimation : minimal phase error variance

Phase Reconstruction in MCAO



- N_{gs} GS in direction $\beta = \{\beta_i\}$
- N_{gs} WFS measurements $S = \{s_i\}$
- L layers for volumic phase $\varphi = \{\varphi_k\}$
- Phase covariance matrix C_{φ} :
 bloc diagonal, independent Kolmogorov layers
 with $[C_n^2 \delta h]_k \quad k \in \{1, L\}$
- Resulting phase in a given direction α :
 $\phi_{\alpha} = M_{\alpha}^L \varphi$

Optimal Reconstruction in MCAO

- Measurement Equation :

$$\mathbf{s} = \mathbf{D} \mathbf{M}_\beta^L \boldsymbol{\varphi} + \mathbf{w} = \mathbf{D}' \boldsymbol{\varphi} + \mathbf{w}$$

- MMSE of the phase in the volume :

$$\hat{\boldsymbol{\varphi}}_{mmse} = \mathbf{G}(\mathbf{s}) \quad \text{so that} \quad \langle \|\boldsymbol{\varphi} - \hat{\boldsymbol{\varphi}}_{mmse}\|^2 \rangle_{\boldsymbol{\varphi}, \mathbf{w}} \quad \text{minimal :}$$

$$\begin{aligned} \hat{\boldsymbol{\varphi}}_{mmse} &= \left(\mathbf{D}'^t \mathbf{C}_w^{-1} \mathbf{D}' + \mathbf{C}_\varphi^{-1} \right)^{-1} \mathbf{D}'^t \mathbf{C}_w^{-1} \mathbf{s} \\ &= \mathbf{R}_{mmse} \mathbf{s} \end{aligned}$$

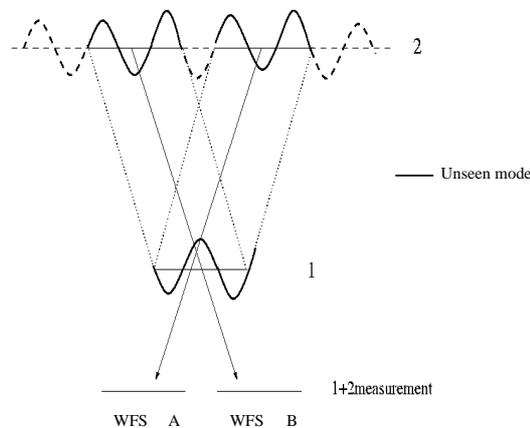
- MMSE of the phase in a given direction α :

$$\phi_\alpha = \mathbf{M}_\alpha^L \hat{\boldsymbol{\varphi}}_{mmse}$$

Optimal estimation of the phase in the volume
hence best interpolation of the phase between GSs

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Unseen modes in MCAO



Good interpolation of the resulting phase between GSs

=> estimation of unseen modes

=> MMSE approach using statistical priors

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Estimation/Control in AO

- DM model :

$$\phi_{cor} = \mathbf{N}u$$

- Control problem : find $u = F(s)$ that minimizes the stochastic criterion

$$\left\langle \left\| \phi - \mathbf{N}u \right\|^2 \right\rangle_{\phi, w}$$

- Separation Principle : u also minimizes the deterministic criterion :

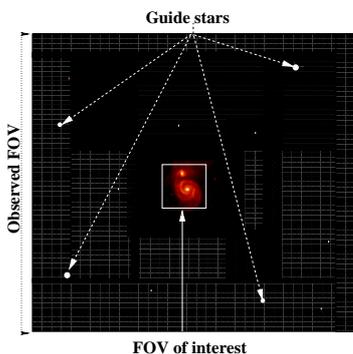
$$\left\| \hat{\phi}_{mmse} - \mathbf{N}u \right\|^2$$

- Analytical solution :

$$u = \mathbf{P} \hat{\phi}_{mmse} = \mathbf{P} \mathbf{R}_{mmse} s$$

with $\mathbf{P} = (\mathbf{N}^t \mathbf{N})^+ \mathbf{N}^t$

Estimation/Control in MCAO



Objective : estimate u to optimize the mean performance in the FoV of Interest $\{\alpha_i\}$

- criterion to be minimized :

$$\left\langle \sum_i \left\| \phi_{\alpha_i} - \phi_{\alpha_i}^{cor} \right\|^2 \right\rangle_{\phi, w} = \left\langle \sum_i \left\| \mathbf{M}_{\alpha_i}^L \varphi - \mathbf{M}_{\alpha_i}^{DM} \mathbf{N}u \right\|^2 \right\rangle_{\varphi, w}$$

- solution : $u = \mathbf{P} \hat{\phi}_{mmse} = \mathbf{P} \mathbf{R}_{mmse} s$

$$\text{with } \mathbf{P} = \left(\sum_i \left(\mathbf{M}_{\alpha_i}^{DM} \mathbf{N} \right)^t \mathbf{M}_{\alpha_i}^{DM} \mathbf{N} \right)^+ \left(\sum_i \left(\mathbf{M}_{\alpha_i}^{DM} \mathbf{N} \right)^t \mathbf{M}_{\alpha_i}^L \right)$$

Standard Reconstruction in MCAO

- Measurement Equation : identification of turbulence space and DM space :

$$\mathbf{s} = \mathbf{D} \mathbf{M}_{\beta}^L \mathbf{N} \mathbf{u} + \mathbf{w} = \mathbf{D}_{inter} \mathbf{u} + \mathbf{w}$$

- Truncated ML estimation :

$$\begin{aligned} \hat{\mathbf{u}}_{ml} &= (\mathbf{D}_{inter}^t \mathbf{D}_{inter})^{-1} \mathbf{D}_{inter}^t \mathbf{s} \\ &= \mathbf{R}_{ml} \mathbf{s} \end{aligned}$$

- no explicit turbulence estimation
- brutal filtering of unseen modes
- no account of Kolmogorov statistics and turbulence profile
- no specification of a FoV of interest

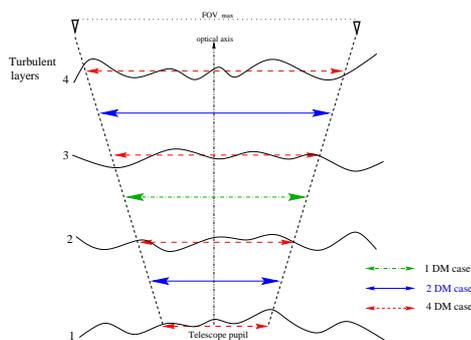
=> poor performance between guide stars

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MCAO Simulation Conditions

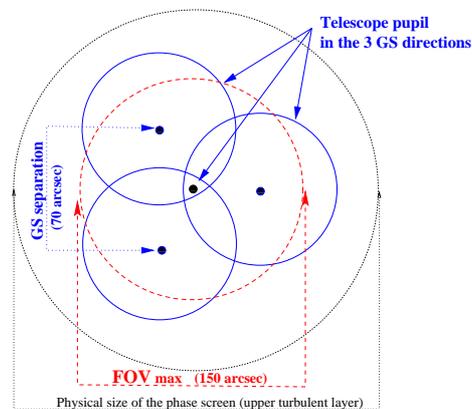
2 DM 3 GS Case

- Telescope diameter = 4 m
- 4 layer C_n^2 profile, $h = [0., 2.5, 5., 7.5 \text{ km}]$, FoV = 150''
- $D/r_0(@2.2\mu\text{m}) = 6.8$



(a) DM and layer positions

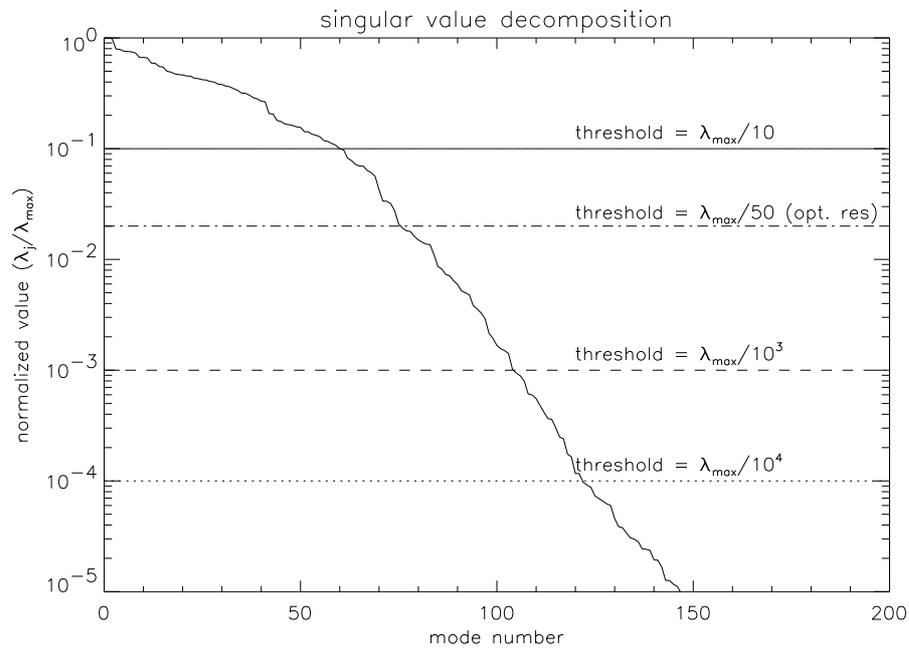
$$h = [1.25, 6.75 \text{ km}]$$



(b) beam section in upper layer

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Truncated Maximum Likelihood : choice of the threshold

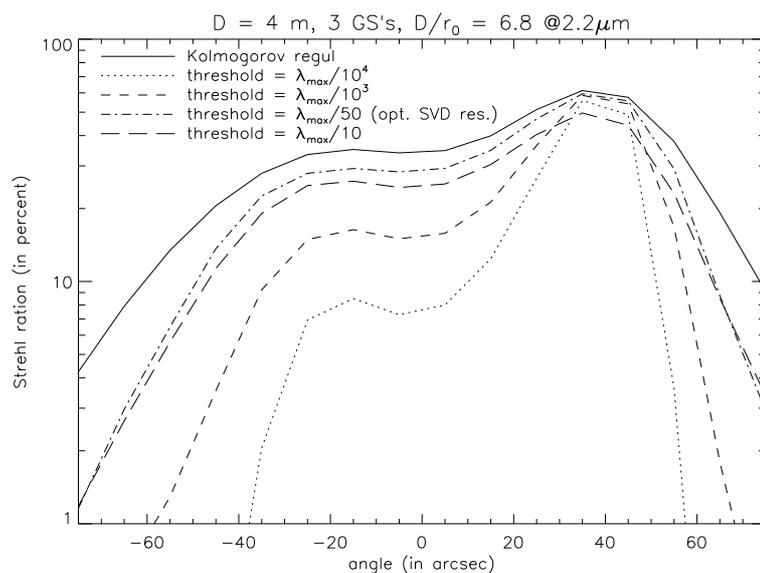


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Performance with Truncated ML and Optimal Control



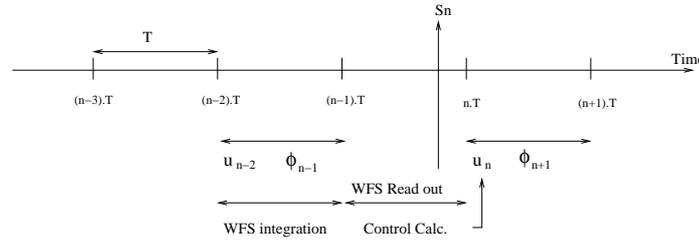
Optimal Reconstruction : significant gain, no ad-hoc threshold

[Fusco et al., "Optimal wavefront...", JOSA A, 18, 2527–253, 2001]

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Dynamic Control : Basic Equations



- Measurement Equation [closed loop, no mirror dynamics, two frame delay] :

$$\mathbf{S}_\eta = D \left(M_\beta^L \varphi_{\eta-1} - M_\beta^{DM} \mathbf{N} \mathbf{u}_{\eta-2} \right) + w$$

- Control problem : find $\mathbf{u}_\eta = F(\mathbf{S}_\eta, \mathbf{S}_{\eta-1} \dots)$ that minimizes the stochastic criterion :

$$\left\langle \sum_i \left\| M_{\alpha_i}^L \varphi_{\eta+1} - M_{\alpha_i}^{DM} \mathbf{N} \mathbf{u}_\eta \right\|^2 \right\rangle_{\varphi, w}$$

- solution : $\mathbf{u}_\eta = \mathbf{P} \hat{\varphi}_{\eta+1}$

back to an MMSE estimation problem : $\hat{\varphi}_{\eta+1/\eta} = G(\mathbf{S}_\eta, \mathbf{S}_{\eta-1} \dots)$ so that

$$\left\langle \left\| \varphi_{\eta+1} - \hat{\varphi}_{\eta+1/\eta} \right\|^2 \right\rangle_{\varphi, w} \text{ minimal}$$

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Dynamic Control : Optimal Estimation of the Turbulent Phase

- Temporal and spatial priors on turbulence :

$$\varphi_{\eta+1} = \mathcal{F} \left[\varphi_\eta, \varphi_{\eta-1}, \varphi_{\eta-2}, \dots \right] + \nu_n$$

ν white noise, covariance matrix \mathbf{C}_ν , imposes Kolmogorov statistics

\mathcal{F} linear function describing temporal behavior [Taylor].

- State space representation : $\mathbf{X}_\eta^t = \{\varphi_{\eta+1}, \varphi_\eta, \dots, \mathbf{u}_{\eta-1}, \mathbf{u}_{\eta-2} \dots\}$

$$\mathbf{X}_{\eta+1} = \mathbf{A} \mathbf{X}_\eta + \mathbf{B} \mathbf{u}_\eta + \mathbf{V}_\eta$$

$$\mathbf{S}_\eta = \mathbf{C} \mathbf{X}_\eta + \mathbf{w}_\eta,$$

- Recursive Kalman estimator :

$$\hat{\mathbf{X}}_{\eta+1/\eta} = \mathbf{A} \hat{\mathbf{X}}_{\eta/\eta-1} + \mathbf{B} \mathbf{u}_\eta + \mathbf{A} \mathbf{H}_\eta (\mathbf{S}_\eta - \mathbf{C} \hat{\mathbf{X}}_{\eta/\eta-1}),$$

\mathbf{H}_η , the observer gain, is deduced from \mathbf{C}_w and \mathbf{C}_ν .

$$\begin{pmatrix} \hat{\varphi}_{\eta+2/\eta} \\ \hat{\varphi}_{\eta+1/\eta} \\ \hat{\varphi}_{\eta/\eta} \end{pmatrix} = \mathbf{A} \begin{pmatrix} \hat{\varphi}_{\eta+1/\eta-1} \\ \hat{\varphi}_{\eta/\eta-1} \\ \hat{\varphi}_{\eta-1/\eta-1} \end{pmatrix} + \mathbf{H} \left[\mathbf{S}_\eta - \left(D \left(M_\beta^L \hat{\varphi}_{\eta-1/\eta-1} - M_\beta^{DM} \mathbf{N} \mathbf{u}_{\eta-2} \right) \right) \right]$$

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Control in Adaptive Optics : Standard Approach

- Control increment from residual measurements :

$$\begin{aligned}\delta \hat{\mathbf{u}}_{\eta} &= \left(D_{inter}^t D_{inter} \right)^{-1} D_{inter}^t \mathbf{S}_{\eta} \\ &= R_{ml} \mathbf{S}_{\eta}\end{aligned}$$

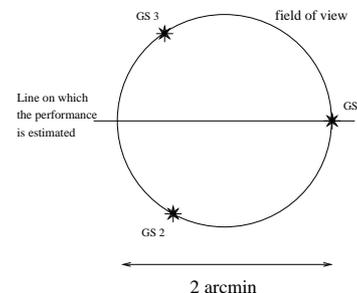
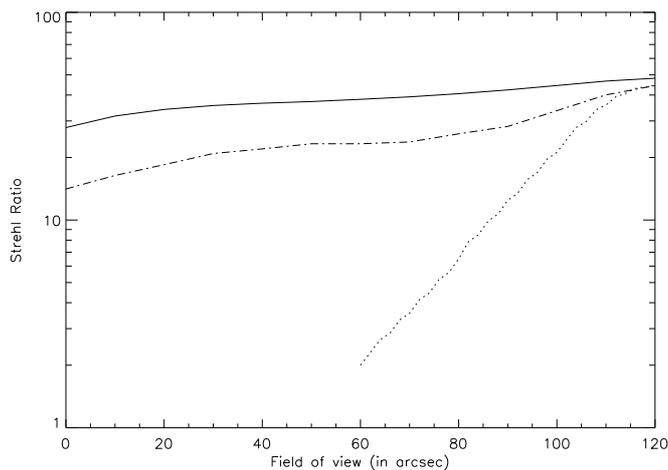
- Integrator control law :

$$\mathbf{u}_{\eta} = \mathbf{u}_{\eta-1} + g \delta \hat{\mathbf{u}} = \mathbf{u}_{\eta-1} + g R_{ml} \mathbf{S}_{\eta}$$

g loop gain, can be optimized globally or mode per mode.

- no explicit turbulence estimation
- brutal filtering of unseen modes
- no global optimization of the control law using Kolmogorov/Taylor statistics
- no specification of a FoV of interest

Performance with Optimal Kalman Control



- 2 turbulent layers : [0.5,5 km]

$$C_n^2 = [75\%, 25\%] \quad ; \quad \text{overall } D/r_o = 6.8 \quad ; \quad V/D = 2 \text{ Hz}$$

- 2 DMs and 3 GSs with 1 arcmin separation ; $\mathcal{M} \approx 15$
100 Hz sampling frequency

Image Deconvolution / Reconstruction and Control Similarities and Differences

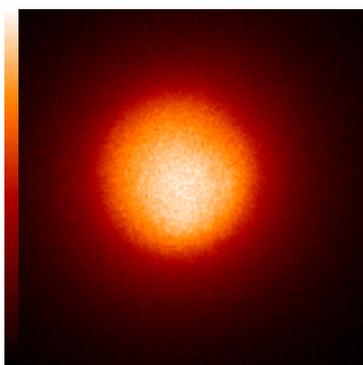
- s1: Linear direct problem : $i = H o + noise$
- s2: Badly conditioned problem : regularization is required!
- s3: Even if object o not really outcome of a stochastic process, the regularization corresponds to an implicit statistical prior
- d1: Operator H often circulant : $i = h \star o + noise$
all matrix expressions can be expressed with FFTs
- d2: Regularization (positivity, edge preserving)
non equivalent to Gaussian prior
- d3: Operator H sometimes not perfectly known (myopic deconvolution)
- d2 and d3 lead to non analytical linear solution
=> iterative minimization of a multi-term criterion

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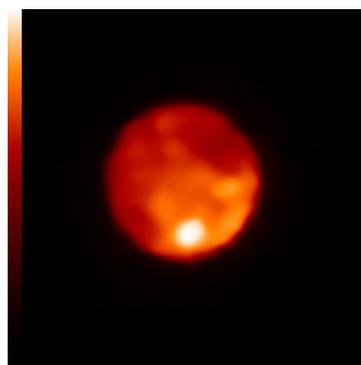


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Myopic Deconvolution of AO Corrected Images Ganymede deconvolved with our algorithm MISTRAL



AO corrected



myopic deconvolution



JPL data

courtesy : NASA/JPL/Caltech

$\lambda = 0.85 \mu m, D/r_o \simeq 23, SR \simeq 5\%, \text{Field} = 3.80''$

Exposure Time = 100 sec., Total Flux $\simeq 8.10^7$ photons

(28/09/1997, 20:18 UT) Observatoire de Haute Provence, 1.52 m telescope

[Mugnier et al., "MISTRAL: a myopic...", JOSA A, accepted]

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Onera Activities on MCAO/ELTs

- AO/MCAO [4 PhDs, 2 PostDocs] :
 - study of optimal control in MCAO [collab. L2TI]
 - comparison of multi-object WFS strategies [star/layer oriented, MFOV...]
 - FALCON : MCAO for large field spectro-imaging [collab. Obs. Paris]
 - experimental validation :
 - MonoCAO, off-axis optimization at Onera**
 - collab. ESO: test control algorithm on MAD**
 - Planet Finder : design study of XAO for VLT
 - collab. Obs. Grenoble/Marseille/Nice... [ESO contract]**
 - AGN study with NAOS/MISTRAL data
- ELTs [1 PhD, 1 PostDoc] :
 - AO/MCAO for ELTs : AO/MCAO/GLAO design and simulations
 - for 20 m class telescope: NGCFHT study with Obs. Marseille**
 - for 50 m and larger : collab. ESO/Arcetri [EC contract]**
 - turbulence characterization on large scales: collab. Arcetri [EC contract]
 - Paranal campaigns with NAOS/VLT/Scidar/Balloons + specific WFS expe. on VLT**
 - two campaigns planned in 2005/2006**