

An overview of transfer operator methods in nonautonomous dynamics: geometry, spectrum, and data

Gary Froyland

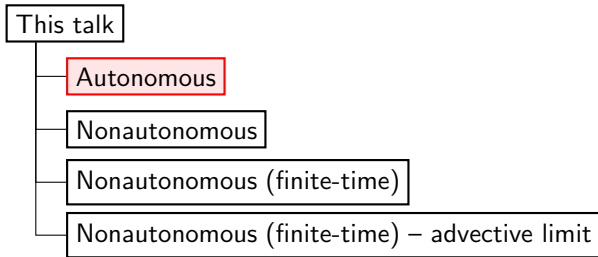
School of Mathematics and Statistics
University of New South Wales, Sydney



UNSW
SYDNEY

**Workshop on Operator Theoretic Methods
in Dynamic Data Analysis and Control**

IPAM, UCLA, 11–15 February 2019



Key tool: the transfer operator

- Suppose I have a dynamical system $T : X \rightarrow X$.
- The transformation T tells me how to evolve points, or more generally, sets of points.
- One can canonically identify a subset $A \subset X$ with its indicator function $\mathbf{1}_A$ contained in some function space $\mathcal{B}(X)$ ($= \mathcal{B}$).
- For simplicity, if T is invertible and volume preserving, then the **transfer operator** (or Perron-Frobenius operator), $\mathcal{P} : \mathcal{B} \rightarrow \mathcal{B}$ is defined by $\mathcal{P}f = f \circ T^{-1}$ for all $f \in \mathcal{B}$.
- Why composition with T^{-1} and not with T ?

	Set	Function
Object	A	$\mathbf{1}_A$
Evolved object	$T(A)$	$\mathcal{P}(\mathbf{1}_A) = \mathbf{1}_A \circ T^{-1} = \mathbf{1}_{T(A)}$

More generally, the transfer operator is designed to be the **natural push forward of a density under T to another density.**

Key tool: the transfer operator

- Suppose I have a dynamical system $T : X \rightarrow X$.
- The transformation T tells me how to evolve points, or more generally, sets of points.
- One can canonically identify a subset $A \subset X$ with its indicator function $\mathbf{1}_A$ contained in some function space $\mathcal{B}(X)$ ($= \mathcal{B}$).
- For simplicity, if T is invertible and volume preserving, then the **transfer operator** (or Perron-Frobenius operator), $\mathcal{P} : \mathcal{B} \rightarrow \mathcal{B}$ is defined by $\mathcal{P}f = f \circ T^{-1}$ for all $f \in \mathcal{B}$.
- Why composition with T^{-1} and not with T ?

	Set	Function
Object	A	$\mathbf{1}_A$
Evolved object	$T(A)$	$\mathcal{P}(\mathbf{1}_A) = \mathbf{1}_A \circ T^{-1} = \mathbf{1}_{T(A)}$

More generally, the transfer operator is designed to be the natural push forward of a density under T to another density.

Key tool: the transfer operator

- Suppose I have a dynamical system $T : X \rightarrow X$.
- The transformation T tells me how to evolve points, or more generally, sets of points.
- One can canonically identify a subset $A \subset X$ with its indicator function $\mathbf{1}_A$ contained in some function space $\mathcal{B}(X)$ ($= \mathcal{B}$).
- For simplicity, if T is invertible and volume preserving, then the **transfer operator** (or Perron-Frobenius operator), $\mathcal{P} : \mathcal{B} \rightarrow \mathcal{B}$ is defined by $\mathcal{P}f = f \circ T^{-1}$ for all $f \in \mathcal{B}$.
- Why composition with T^{-1} and not with T ?

	Set	Function
Object	A	$\mathbf{1}_A$
Evolved object	$T(A)$	$\mathcal{P}(\mathbf{1}_A) = \mathbf{1}_A \circ T^{-1} = \mathbf{1}_{T(A)}$

More generally, the transfer operator is designed to be the **natural push forward of a density under T to another density.**

Key tool: the transfer operator

- Suppose I have a dynamical system $T : X \rightarrow X$.
- The transformation T tells me how to evolve points, or more generally, sets of points.
- One can canonically identify a subset $A \subset X$ with its indicator function $\mathbf{1}_A$ contained in some function space $\mathcal{B}(X)$ ($= \mathcal{B}$).
- For simplicity, if T is invertible and volume preserving, then the **transfer operator** (or Perron-Frobenius operator), $\mathcal{P} : \mathcal{B} \rightarrow \mathcal{B}$ is defined by $\mathcal{P}f = f \circ T^{-1}$ for all $f \in \mathcal{B}$.
- Why composition with T^{-1} and not with T ?

	Set	Function
Object	A	$\mathbf{1}_A$
Evolved object	$T(A)$	$\mathcal{P}(\mathbf{1}_A) = \mathbf{1}_A \circ T^{-1} = \mathbf{1}_{T(A)}$

More generally, the transfer operator is designed to be the **natural push forward of a density under T to another density.**

Key tool: the transfer operator

- Suppose I have a dynamical system $T : X \rightarrow X$.
- The transformation T tells me how to evolve points, or more generally, sets of points.
- One can canonically identify a subset $A \subset X$ with its indicator function $\mathbf{1}_A$ contained in some function space $\mathcal{B}(X)$ ($= \mathcal{B}$).
- For simplicity, if T is invertible and volume preserving, then the **transfer operator** (or Perron-Frobenius operator), $\mathcal{P} : \mathcal{B} \rightarrow \mathcal{B}$ is defined by $\mathcal{P}f = f \circ T^{-1}$ for all $f \in \mathcal{B}$.
- Why composition with T^{-1} and not with T ?

	Set	Function
Object	A	$\mathbf{1}_A$
Evolved object	$T(A)$	$\mathcal{P}(\mathbf{1}_A) = \mathbf{1}_A \circ T^{-1} = \mathbf{1}_{T(A)}$

More generally, the transfer operator is designed to be the **natural push forward of a density under T to another density.**

Key tool: the transfer operator

- Suppose I have a dynamical system $T : X \rightarrow X$.
- The transformation T tells me how to evolve points, or more generally, sets of points.
- One can canonically identify a subset $A \subset X$ with its indicator function $\mathbf{1}_A$ contained in some function space $\mathcal{B}(X)$ ($= \mathcal{B}$).
- For simplicity, if T is invertible and volume preserving, then the **transfer operator** (or Perron-Frobenius operator), $\mathcal{P} : \mathcal{B} \rightarrow \mathcal{B}$ is defined by $\mathcal{P}f = f \circ T^{-1}$ for all $f \in \mathcal{B}$.
- Why composition with T^{-1} and not with T ?

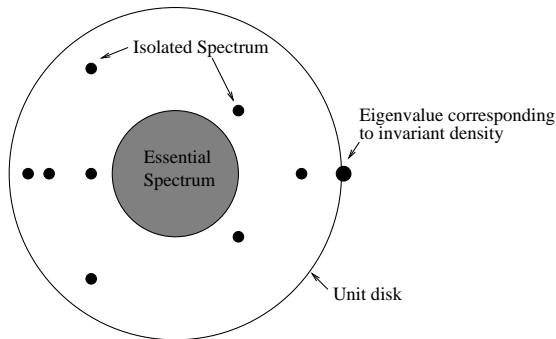
	Set	Function
Object	A	$\mathbf{1}_A$
Evolved object	$T(A)$	$\mathcal{P}(\mathbf{1}_A) = \mathbf{1}_A \circ T^{-1} = \mathbf{1}_{T(A)}$

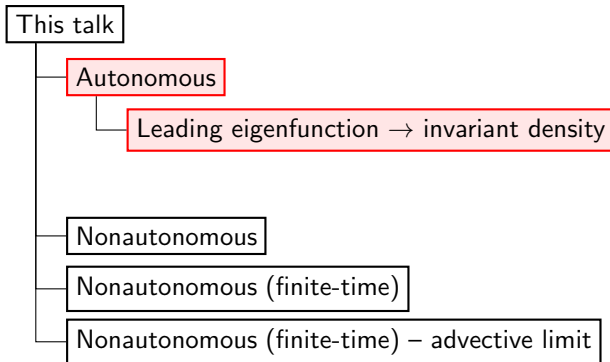
More generally, the transfer operator is designed to be the **natural push forward of a density under T to another density**.

Spectrum of the transfer operator

Typically one wants \mathcal{P} to act on a Banach space \mathcal{B} :

- 1 containing $L^1(X)$ (which itself contains densities),
- 2 for which the spectral radius of the transfer operator is 1,
- 3 and on which the transfer operator is *quasi-compact*, meaning that there is an *essential spectral radius* $r_{\text{ess}} \geq 0$ outside which there are finitely many eigenvalues of finite multiplicity.





Eigenfunctions of the transfer operator

- The most important eigenfunction of \mathcal{P} is the (often unique) fixed point h satisfying $\mathcal{P}h = h$, which is the **invariant density** of T .
- The eigenfunction h defines a probability measure $\mu(A) = \int_A h \, d\text{Leb}$, which is the **absolutely continuous invariant measure** of T , and satisfies $\mu = \mu \circ T^{-1}$.
- The eigenfunction h describes the **time-asymptotic distribution of trajectories** of T . That is, for an arbitrary $g \in L^1(X)$, by Birkhoff $\lim_{n \rightarrow \infty} \frac{1}{n} \sum_{k=0}^{n-1} g \circ T^k = \int_X g \cdot h \, d\text{Leb} = \int_X g \, d\mu$, μ -a.e.
- There is a long history of **rigorous numerical approximation of h** beginning with [Li'76] and Didier will talk about this shortly.

Eigenfunctions of the transfer operator

- The most important eigenfunction of \mathcal{P} is the (often unique) fixed point h satisfying $\mathcal{P}h = h$, which is the **invariant density** of T .
- The eigenfunction h defines a probability measure $\mu(A) = \int_A h \, d\text{Leb}$, which is the **absolutely continuous invariant measure** of T , and satisfies $\mu = \mu \circ T^{-1}$.
- The eigenfunction h describes the **time-asymptotic distribution of trajectories** of T . That is, for an arbitrary $g \in L^1(X)$, by Birkhoff $\lim_{n \rightarrow \infty} \frac{1}{n} \sum_{k=0}^{n-1} g \circ T^k = \int_X g \cdot h \, d\text{Leb} = \int_X g \, d\mu$, μ -a.e.
- There is a long history of **rigorous numerical approximation of h** beginning with [Li'76] and Didier will talk about this shortly.

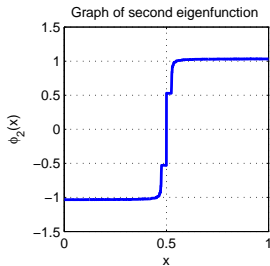
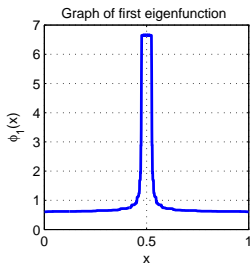
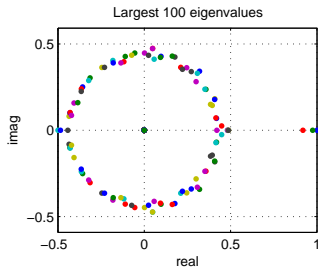
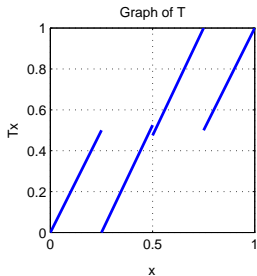
Eigenfunctions of the transfer operator

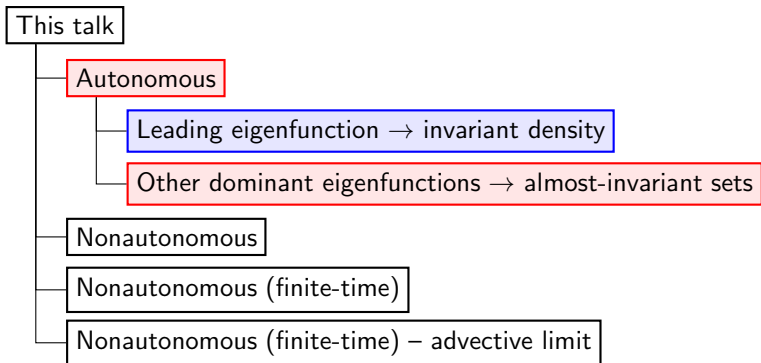
- The most important eigenfunction of \mathcal{P} is the (often unique) fixed point h satisfying $\mathcal{P}h = h$, which is the **invariant density** of T .
- The eigenfunction h defines a probability measure $\mu(A) = \int_A h \, d\text{Leb}$, which is the **absolutely continuous invariant measure** of T , and satisfies $\mu = \mu \circ T^{-1}$.
- The eigenfunction h describes the **time-asymptotic distribution of trajectories** of T . That is, for an arbitrary $g \in L^1(X)$, by Birkhoff $\lim_{n \rightarrow \infty} \frac{1}{n} \sum_{k=0}^{n-1} g \circ T^k = \int_X g \cdot h \, d\text{Leb} = \int_X g \, d\mu$, μ -a.e.
- There is a long history of **rigorous numerical approximation of h** beginning with [Li'76] and Didier will talk about this shortly.

Eigenfunctions of the transfer operator

- The most important eigenfunction of \mathcal{P} is the (often unique) fixed point h satisfying $\mathcal{P}h = h$, which is the **invariant density** of T .
- The eigenfunction h defines a probability measure $\mu(A) = \int_A h \, d\text{Leb}$, which is the **absolutely continuous invariant measure** of T , and satisfies $\mu = \mu \circ T^{-1}$.
- The eigenfunction h describes the **time-asymptotic distribution of trajectories** of T . That is, for an arbitrary $g \in L^1(X)$, by Birkhoff $\lim_{n \rightarrow \infty} \frac{1}{n} \sum_{k=0}^{n-1} g \circ T^k = \int_X g \cdot h \, d\text{Leb} = \int_X g \, d\mu$, μ -a.e.
- There is a long history of **rigorous numerical approximation of h** beginning with [Li'76] and Didier will talk about this shortly.

Example





The second eigenfunction

- The next most important eigenvalue of \mathcal{P} is the one with second largest magnitude denoted by Λ_2 .
- One reason for its importance is that it quantifies the **rate at which functions f in \mathcal{B} converge to h** as they are pushed forward by the dynamics, i.e.

$$\left\| \mathcal{P}^n f - \left(\int f \, d\text{Leb} \right) h \right\| \leq C(f) |\Lambda_2|^n, \text{ with } |\Lambda_2| < 1.$$

- Further, the eigenfunction f_2 of \mathcal{P} corresponding to Λ_2 is the **non-equilibrium distribution** of (signed) mass in phase space that **mixes most slowly** to the equilibrium distribution given by h .
- Indeed, the sign [Dellnitz/Junge'99] (or more generally, extreme values) of this signed mass distribution describe **almost-invariant sets**.

The second eigenfunction

- The next most important eigenvalue of \mathcal{P} is the one with second largest magnitude denoted by Λ_2 .
- One reason for its importance is that it quantifies the **rate at which functions f in \mathcal{B} converge to h** as they are pushed forward by the dynamics, i.e.

$$\left\| \mathcal{P}^n f - \left(\int f \, d\text{Leb} \right) h \right\| \leq C(f) |\Lambda_2|^n, \text{ with } |\Lambda_2| < 1.$$

- Further, the eigenfunction f_2 of \mathcal{P} corresponding to Λ_2 is the **non-equilibrium distribution** of (signed) mass in phase space that **mixes most slowly** to the equilibrium distribution given by h .
- Indeed, the sign [Dellnitz/Junge'99] (or more generally, extreme values) of this signed mass distribution describe **almost-invariant sets**.

The second eigenfunction

- The next most important eigenvalue of \mathcal{P} is the one with second largest magnitude denoted by Λ_2 .
- One reason for its importance is that it quantifies the **rate at which functions f in \mathcal{B} converge to h** as they are pushed forward by the dynamics, i.e.

$$\left\| \mathcal{P}^n f - \left(\int f \, d\text{Leb} \right) h \right\| \leq C(f) |\Lambda_2|^n, \text{ with } |\Lambda_2| < 1.$$

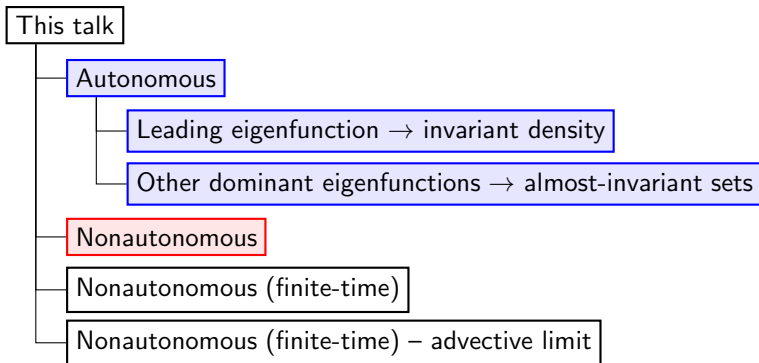
- Further, the eigenfunction f_2 of \mathcal{P} corresponding to Λ_2 is the **non-equilibrium distribution** of (signed) mass in phase space that **mixes most slowly** to the equilibrium distribution given by h .
- Indeed, the sign [Dellnitz/Junge'99] (or more generally, extreme values) of this signed mass distribution describe **almost-invariant sets**.

The second eigenfunction

- The next most important eigenvalue of \mathcal{P} is the one with second largest magnitude denoted by Λ_2 .
- One reason for its importance is that it quantifies the **rate at which functions f in \mathcal{B} converge to h** as they are pushed forward by the dynamics, i.e.

$$\left\| \mathcal{P}^n f - \left(\int f \, d\text{Leb} \right) h \right\| \leq C(f) |\Lambda_2|^n, \text{ with } |\Lambda_2| < 1.$$

- Further, the eigenfunction f_2 of \mathcal{P} corresponding to Λ_2 is the **non-equilibrium distribution** of (signed) mass in phase space that **mixes most slowly** to the equilibrium distribution given by h .
- Indeed, the sign [Dellnitz/Junge'99] (or more generally, extreme values) of this signed mass distribution describe **almost-invariant sets**.



Nonautonomous dynamical systems

- **Driving system:** let $(\Omega, \mathcal{F}, \mathbb{P})$ be a probability space and assume that $\sigma: \Omega \rightarrow \Omega$ is invertible, ergodic transformation preserving \mathbb{P} .
- One thinks of Ω as a configuration space, evolving with the passage of time (iteration of σ).
- **ω -dependent maps:** Consider a collection $\{T_\omega\}_{\omega \in \Omega}$ of maps.
- **Map cocycle:** for $\omega \in \Omega$ and $n \in \mathbb{N}$, set
$$T_\omega^n = T_{\sigma^{n-1}\omega} \circ \dots \circ T_{\sigma\omega} \circ T_\omega.$$

Some trivial warm-up examples:

- 1 *Autonomous dynamics:* $\Omega = \{\omega\}$, σ is the trivial map, \mathbb{P} is the probability measure supported on ω , $T_\omega = T$.
- 2 *Periodic dynamics:* $\Omega = \{\omega_0, \dots, \omega_{p-1}\}$, $\sigma(\omega_i) = \omega_{i+1} \pmod{p}$, $\mathbb{P}(\omega_i) = 1/p, i = 0, \dots, p-1$, $T_{\omega_i} = T_i, i = 0, \dots, p-1$.

Nonautonomous dynamical systems

- **Driving system:** let $(\Omega, \mathcal{F}, \mathbb{P})$ be a probability space and assume that $\sigma: \Omega \rightarrow \Omega$ is invertible, ergodic transformation preserving \mathbb{P} .
- One thinks of Ω as a configuration space, evolving with the passage of time (iteration of σ).
- **ω -dependent maps:** Consider a collection $\{T_\omega\}_{\omega \in \Omega}$ of maps.
- **Map cocycle:** for $\omega \in \Omega$ and $n \in \mathbb{N}$, set
$$T_\omega^n = T_{\sigma^{n-1}\omega} \circ \dots \circ T_{\sigma\omega} \circ T_\omega.$$

Some trivial warm-up examples:

- 1 *Autonomous dynamics:* $\Omega = \{\omega\}$, σ is the trivial map, \mathbb{P} is the probability measure supported on ω , $T_\omega = T$.
- 2 *Periodic dynamics:* $\Omega = \{\omega_0, \dots, \omega_{p-1}\}$, $\sigma(\omega_i) = \omega_{i+1} \pmod{p}$, $\mathbb{P}(\omega_i) = 1/p, i = 0, \dots, p-1$, $T_{\omega_i} = T_i, i = 0, \dots, p-1$.

Nonautonomous dynamical systems

- **Driving system:** let $(\Omega, \mathcal{F}, \mathbb{P})$ be a probability space and assume that $\sigma: \Omega \rightarrow \Omega$ is invertible, ergodic transformation preserving \mathbb{P} .
- One thinks of Ω as a configuration space, evolving with the passage of time (iteration of σ).
- **ω -dependent maps:** Consider a collection $\{T_\omega\}_{\omega \in \Omega}$ of maps.
- **Map cocycle:** for $\omega \in \Omega$ and $n \in \mathbb{N}$, set
$$T_\omega^n = T_{\sigma^{n-1}\omega} \circ \dots \circ T_{\sigma\omega} \circ T_\omega.$$

Some trivial warm-up examples:

- 1 *Autonomous dynamics:* $\Omega = \{\omega\}$, σ is the trivial map, \mathbb{P} is the probability measure supported on ω , $T_\omega = T$.
- 2 *Periodic dynamics:* $\Omega = \{\omega_0, \dots, \omega_{p-1}\}$, $\sigma(\omega_i) = \omega_{i+1} \pmod{p}$, $\mathbb{P}(\omega_i) = 1/p, i = 0, \dots, p-1$, $T_{\omega_i} = T_i, i = 0, \dots, p-1$.

Nonautonomous examples

The types of driving we can model are extremely general, e.g.:

- 1 $\Omega = [0, 1]^{\mathbb{Z}}$, σ is the left shift, $\mathbb{P} = \prod_{i=-\infty}^{\infty} \text{Leb}$, $T_{\omega} : \mathbb{R} \circlearrowright$ is given by $T_{\omega} = T + 2\epsilon(\omega_0 - 1/2)$. This setup models **iid** uniformly distributed noise in the range $[-\epsilon, \epsilon]$.
- 2 $\Omega = S^1$, $\sigma(\omega) = \omega + \alpha$, $\alpha \notin \mathbb{Q}$, $\mathbb{P} = \text{Leb}$, $T_{\omega} : \mathbb{R} \circlearrowright$ is given by $T_{\omega} = T + 2\epsilon(\omega - 1/2)$. This setup models **highly correlated** uniformly distributed noise in the range $[-\epsilon, \epsilon]$.
- 3 $\Omega = \text{Lorenz attractor}$, $\sigma = \text{time-1 map of Lorenz flow}$, $\mathbb{P} = \text{SRB measure of Lorenz flow}$, $T_{\omega}(\cdot) = T(\omega, \cdot)$ a family of general measurable maps parameterised in some general way by the (three-dimensional) parameter $\omega \in \mathbb{R}^3$.

In a similar way one can consider continuous-time aperiodic driving and continuous-time phase space dynamics.

Nonautonomous examples

The types of driving we can model are extremely general, e.g.:

- 1 $\Omega = [0, 1]^{\mathbb{Z}}$, σ is the left shift, $\mathbb{P} = \prod_{i=-\infty}^{\infty} \text{Leb}$, $T_{\omega} : \mathbb{R} \curvearrowright$ is given by $T_{\omega} = T + 2\epsilon(\omega_0 - 1/2)$. This setup models **iid** uniformly distributed noise in the range $[-\epsilon, \epsilon]$.
- 2 $\Omega = S^1$, $\sigma(\omega) = \omega + \alpha$, $\alpha \notin \mathbb{Q}$, $\mathbb{P} = \text{Leb}$, $T_{\omega} : \mathbb{R} \curvearrowright$ is given by $T_{\omega} = T + 2\epsilon(\omega - 1/2)$. This setup models **highly correlated** uniformly distributed noise in the range $[-\epsilon, \epsilon]$.
- 3 $\Omega = \text{Lorenz attractor}$, $\sigma = \text{time-1 map of Lorenz flow}$, $\mathbb{P} = \text{SRB measure of Lorenz flow}$, $T_{\omega}(\cdot) = T(\omega, \cdot)$ a family of general measurable maps parameterised in some general way by the (three-dimensional) parameter $\omega \in \mathbb{R}^3$.

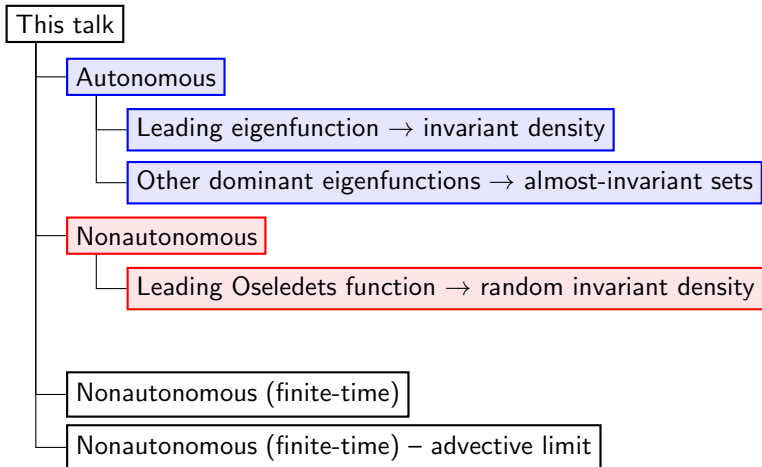
In a similar way one can consider continuous-time aperiodic driving and continuous-time phase space dynamics.

Nonautonomous examples

The types of driving we can model are extremely general, e.g.:

- 1 $\Omega = [0, 1]^{\mathbb{Z}}$, σ is the left shift, $\mathbb{P} = \prod_{i=-\infty}^{\infty} \text{Leb}$, $T_{\omega} : \mathbb{R} \curvearrowright$ is given by $T_{\omega} = T + 2\epsilon(\omega_0 - 1/2)$. This setup models **iid** uniformly distributed noise in the range $[-\epsilon, \epsilon]$.
- 2 $\Omega = S^1$, $\sigma(\omega) = \omega + \alpha$, $\alpha \notin \mathbb{Q}$, $\mathbb{P} = \text{Leb}$, $T_{\omega} : \mathbb{R} \curvearrowright$ is given by $T_{\omega} = T + 2\epsilon(\omega - 1/2)$. This setup models **highly correlated** uniformly distributed noise in the range $[-\epsilon, \epsilon]$.
- 3 $\Omega = \text{Lorenz attractor}$, $\sigma = \text{time-1 map of Lorenz flow}$, $\mathbb{P} = \text{SRB measure of Lorenz flow}$, $T_{\omega}(\cdot) = T(\omega, \cdot)$ a family of general measurable maps parameterised in some general way by the (three-dimensional) parameter $\omega \in \mathbb{R}^3$.

In a similar way one can consider continuous-time aperiodic driving and continuous-time phase space dynamics.



Nonautonomous/Random ACIMS

- Clearly, for a general nonautonomous system, one cannot expect a **fixed** invariant density. Instead, the natural object is a random invariant density, **parameterised by the driving configuration** ω .
- From the map cocycle, one builds a **transfer operator cocycle**:
$$\mathcal{P}_\omega^n = \mathcal{P}_{\sigma^{n-1}\omega} \circ \dots \circ \mathcal{P}_{\sigma\omega} \circ \mathcal{P}_\omega$$
- An ω -measurable family of densities $\{h_\omega\}_{\omega \in \Omega}$ satisfying $\mathcal{P}_\omega h_\omega = h_{\sigma\omega}$ will be called a **(quenched) random absolutely continuous invariant measure (ACIM)** [Buzzi'99,'00]; see also [Bogenschuetz/Gundlach'95, Khanin/Kifer'96, Baladi'97].
- In terms of probability measures, define a family $\{\mu_\omega\}_{\omega \in \Omega}$ by $\mu_\omega(A) = \int_A h_\omega d\text{Leb}$; this family is **equivariant**: $\mu_{\sigma\omega} = \mu_\omega \circ T_\omega^{-1}$.

- Clearly, for a general nonautonomous system, one cannot expect a **fixed** invariant density. Instead, the natural object is a random invariant density, **parameterised by the driving configuration** ω .
- From the map cocycle, one builds a **transfer operator cocycle**:
$$\mathcal{P}_\omega^n = \mathcal{P}_{\sigma^{n-1}\omega} \circ \dots \circ \mathcal{P}_{\sigma\omega} \circ \mathcal{P}_\omega$$
- An ω -measurable family of densities $\{h_\omega\}_{\omega \in \Omega}$ satisfying $\mathcal{P}_\omega h_\omega = h_{\sigma\omega}$ will be called a **(quenched) random absolutely continuous invariant measure (ACIM)** [Buzzi'99,'00]; see also [Bogenschuetz/Gundlach'95, Khanin/Kifer'96, Baladi'97].
- In terms of probability measures, define a family $\{\mu_\omega\}_{\omega \in \Omega}$ by $\mu_\omega(A) = \int_A h_\omega d\text{Leb}$; this family is **equivariant**: $\mu_{\sigma\omega} = \mu_\omega \circ T_\omega^{-1}$.

- Clearly, for a general nonautonomous system, one cannot expect a **fixed** invariant density. Instead, the natural object is a random invariant density, **parameterised by the driving configuration** ω .
- From the map cocycle, one builds a **transfer operator cocycle**:
$$\mathcal{P}_\omega^n = \mathcal{P}_{\sigma^{n-1}\omega} \circ \dots \circ \mathcal{P}_{\sigma\omega} \circ \mathcal{P}_\omega$$
- An ω -measurable family of densities $\{h_\omega\}_{\omega \in \Omega}$ satisfying $\mathcal{P}_\omega h_\omega = h_{\sigma\omega}$ will be called a **(quenched) random absolutely continuous invariant measure (ACIM)** [Buzzi'99,'00]; see also [Bogenschuetz/Gundlach'95, Khanin/Kifer'96, Baladi'97].
- In terms of probability measures, define a family $\{\mu_\omega\}_{\omega \in \Omega}$ by $\mu_\omega(A) = \int_A h_\omega d\text{Leb}$; this family is **equivariant**: $\mu_{\sigma\omega} = \mu_\omega \circ T_\omega^{-1}$.

- Clearly, for a general nonautonomous system, one cannot expect a **fixed** invariant density. Instead, the natural object is a random invariant density, **parameterised by the driving configuration** ω .
- From the map cocycle, one builds a **transfer operator cocycle**:
$$\mathcal{P}_\omega^n = \mathcal{P}_{\sigma^{n-1}\omega} \circ \dots \circ \mathcal{P}_{\sigma\omega} \circ \mathcal{P}_\omega$$
- An ω -measurable family of densities $\{h_\omega\}_{\omega \in \Omega}$ satisfying $\mathcal{P}_\omega h_\omega = h_{\sigma\omega}$ will be called a **(quenched) random absolutely continuous invariant measure (ACIM)** [Buzzi'99,'00]; see also [Bogenschuetz/Gundlach'95, Khanin/Kifer'96, Baladi'97].
- In terms of probability measures, define a family $\{\mu_\omega\}_{\omega \in \Omega}$ by $\mu_\omega(A) = \int_A h_\omega d\text{Leb}$; this family is **equivariant**: $\mu_{\sigma\omega} = \mu_\omega \circ T_\omega^{-1}$.

Quenched vs Physical vs Annealed

- Our quenched random ACIMs $\{h_\omega\}_{\omega \in \Omega}$ describe **limiting distributions after pushing forward to time** ω e.g. Lebesgue from the distant past. They are equivariant: $\mathcal{P}h_\omega = h_{\sigma\omega}$.
- Define a **non-random physical invariant measure** [Buzzi'99] $\mu := \lim_{n \rightarrow \infty} \frac{1}{n} \sum_{i=1}^{n-1} \delta_{T_\omega^{(i)}(x)}$ for *Leb* a.e. $x \in [0, 1]$ and \mathbb{P} a.e. $\omega \in \Omega$ where weak convergence is meant.
The density of μ is $\int h_\omega d\mathbb{P}(\omega)$.
- **IF** $\sigma : \Omega \rightarrow \Omega$ were Bernoulli, it would make sense to form an averaged transfer operator $\bar{\mathcal{P}} = \int_\Omega \mathcal{P}_\omega d\mathbb{P}(\omega)$. An **annealed invariant density** is a fixed point of $\bar{\mathcal{P}}$; [Ohno'83, Pelikan'84, Morita'85].

Quenched vs Physical vs Annealed

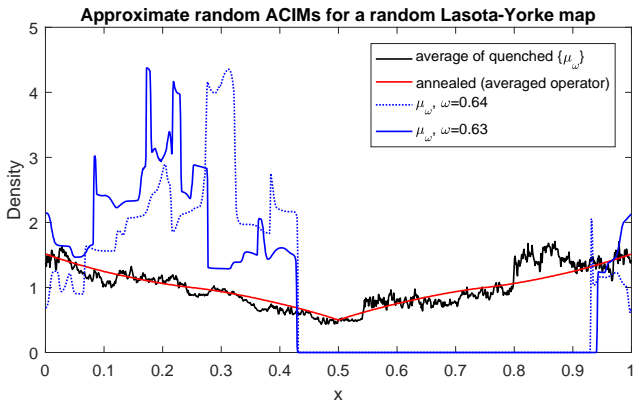
- Our quenched random ACIMs $\{h_\omega\}_{\omega \in \Omega}$ describe **limiting distributions after pushing forward to time** ω e.g. Lebesgue from the distant past. They are equivariant: $\mathcal{P}h_\omega = h_{\sigma\omega}$.
- Define a **non-random physical invariant measure** [Buzzi'99] $\mu := \lim_{n \rightarrow \infty} \frac{1}{n} \sum_{i=1}^{n-1} \delta_{T_\omega^{(i)}(x)}$ for *Leb* a.e. $x \in [0, 1]$ and \mathbb{P} a.e. $\omega \in \Omega$ where weak convergence is meant.
The density of μ is $\int h_\omega d\mathbb{P}(\omega)$.
- **IF** $\sigma : \Omega \rightarrow \Omega$ were Bernoulli, it would make sense to form an averaged transfer operator $\bar{\mathcal{P}} = \int_{\Omega} \mathcal{P}_\omega d\mathbb{P}(\omega)$. An **annealed invariant density** is a fixed point of $\bar{\mathcal{P}}$; [Ohno'83, Pelikan'84, Morita'85].

Quenched vs Physical vs Annealed

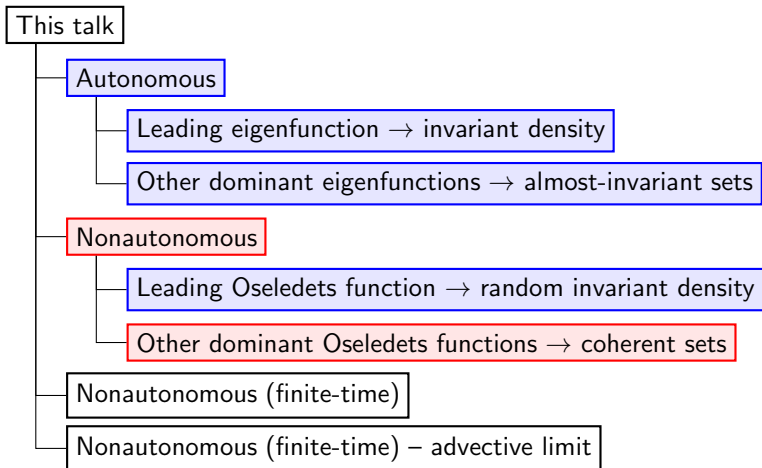
- Our quenched random ACIMs $\{h_\omega\}_{\omega \in \Omega}$ describe **limiting distributions after pushing forward to time** ω e.g. Lebesgue from the distant past. They are equivariant: $\mathcal{P}h_\omega = h_{\sigma\omega}$.
- Define a **non-random physical invariant measure** [Buzzi'99] $\mu := \lim_{n \rightarrow \infty} \frac{1}{n} \sum_{i=1}^{n-1} \delta_{T_\omega^{(i)}(x)}$ for *Leb* a.e. $x \in [0, 1]$ and \mathbb{P} a.e. $\omega \in \Omega$ where weak convergence is meant.
The density of μ is $\int h_\omega d\mathbb{P}(\omega)$.
- **IF** $\sigma : \Omega \rightarrow \Omega$ were Bernoulli, it would make sense to form an averaged transfer operator $\bar{\mathcal{P}} = \int_{\Omega} \mathcal{P}_\omega d\mathbb{P}(\omega)$. An **annealed invariant density** is a fixed point of $\bar{\mathcal{P}}$; [Ohno'83, Pelikan'84, Morita'85].

Quenched vs Physical vs Annealed

- Quenched random ACIMs, the non-random physical measure, and the annealed measure are **all different** in general.
- The physical measure encodes fluctuations **not captured by the annealed measure**.



(see [F/González-Tokman/Quas'14,F/GT/Murray'18] for random ACIM stability)



Spectrum for nonautonomous systems

- **Autonomous case**

- We found the eigenfunction f_2 corresponding to the second largest eigenvalue Λ_2 . Thus,

$$\|\mathcal{P}^n f_2\| \leq C(f_2) |\Lambda_2|^n, \quad \text{for all } n \geq 0.$$

- *But what are “eigenvalues” and “eigenfunctions” in the nonautonomous setting?*

- **Nonautonomous case**

- The analogous growth rate expression is

$$\|\mathcal{P}_{T_{\sigma^{n-1}\omega}} \circ \cdots \circ \mathcal{P}_{T_{\sigma\omega}} \circ \mathcal{P}_{T_\omega} f\| \leq C(f) |\Lambda_2|^n.$$

- Or:

$$\lim_{n \rightarrow \infty} \frac{1}{n} \log \|\mathcal{P}_{T_{\sigma^{n-1}\omega}} \circ \cdots \circ \mathcal{P}_{T_{\sigma\omega}} \circ \mathcal{P}_{T_\omega} f\| \leq \log |\Lambda_2|.$$

- Note that the \mathcal{P}_{T_ω} are *linear* operators (or in numerical experiments, matrices), so $\lambda_2 := \log |\Lambda_2|$ is a **Lyapunov exponent**.
- Thus, **eigenvalues are replaced with Lyapunov exponents**, and the eigenspectrum is replaced with the Lyapunov spectrum.

- **Autonomous case**

- We found the eigenfunction f_2 corresponding to the second largest eigenvalue Λ_2 . Thus,

$$\|\mathcal{P}^n f_2\| \leq C(f_2) |\Lambda_2|^n, \quad \text{for all } n \geq 0.$$

- *But what are “eigenvalues” and “eigenfunctions” in the nonautonomous setting?*

- **Nonautonomous case**

- The analogous growth rate expression is

$$\|\mathcal{P}_{T_{\sigma^{n-1}\omega}} \circ \cdots \circ \mathcal{P}_{T_{\sigma\omega}} \circ \mathcal{P}_{T_\omega} f\| \leq C(f) |\Lambda_2|^n.$$

- Or:

$$\lim_{n \rightarrow \infty} \frac{1}{n} \log \|\mathcal{P}_{T_{\sigma^{n-1}\omega}} \circ \cdots \circ \mathcal{P}_{T_{\sigma\omega}} \circ \mathcal{P}_{T_\omega} f\| \leq \log |\Lambda_2|.$$

- Note that the \mathcal{P}_{T_ω} are *linear* operators (or in numerical experiments, matrices), so $\lambda_2 := \log |\Lambda_2|$ is a **Lyapunov exponent**.
- Thus, **eigenvalues are replaced with Lyapunov exponents**, and the eigenspectrum is replaced with the Lyapunov spectrum.

Equivariant (not eigen-) functions in nonautonomous dynamics

- Because the nonautonomous driving is aperiodic, it **does not make sense to talk about eigenfunctions** of the transfer operator cocycle.
- In the quasi-compact setting [Thieullen'87, F/Lloyd/Quas'10&'13, Gonzalez-Tokman/Quas'14, Blumenthal'16] one can show (via a Multiplicative Ergodic Theorem) that there is a finite or countable set of Lyapunov exponents $0 = \lambda_1 > \lambda_2 > \dots$ associated with the transfer operator cocycle and a family of **Oseledets (covariant) functions** $\{f_\omega\}_{\omega \in \Omega}$ satisfying:

$$\lim_{n \rightarrow \infty} \frac{1}{n} \log \|\mathcal{P}_\omega^n f_{k,\omega}\| = \lambda_k.$$

- Moreover, the $f_{k,\omega}$ are **equivariant**: $\mathcal{P}_\omega(f_{k,\omega}) = \lambda_{k,\omega} f_{k,\sigma\omega}$.
- The λ_k correspond to the Λ_k in the autonomous setting ($\lambda_k = \log |\Lambda_k|$).
- The $\{f_{k,\omega}\}_{\omega \in \Omega}$ are the nonautonomous family corresponding to the (single) k^{th} eigenfunction f_k in the autonomous setting.

Equivariant (not eigen-) functions in nonautonomous dynamics

- Because the nonautonomous driving is aperiodic, it **does not make sense to talk about eigenfunctions** of the transfer operator cocycle.
- In the quasi-compact setting [Thieullen'87, F/Lloyd/Quas'10&'13, Gonzalez-Tokman/Quas'14, Blumenthal'16] one can show (via a Multiplicative Ergodic Theorem) that there is a finite or countable set of Lyapunov exponents $0 = \lambda_1 > \lambda_2 > \dots$ associated with the transfer operator cocycle and a family of **Oseledets (covariant) functions** $\{f_\omega\}_{\omega \in \Omega}$ satisfying:

$$\lim_{n \rightarrow \infty} \frac{1}{n} \log \|\mathcal{P}_\omega^n f_{k,\omega}\| = \lambda_k.$$

- Moreover, the $f_{k,\omega}$ are **equivariant**: $\mathcal{P}_\omega(f_{k,\omega}) = \lambda_{k,\omega} f_{k,\sigma\omega}$.
- The λ_k correspond to the Λ_k in the autonomous setting ($\lambda_k = \log |\Lambda_k|$).
- The $\{f_{k,\omega}\}_{\omega \in \Omega}$ are the nonautonomous family corresponding to the (single) k^{th} eigenfunction f_k in the autonomous setting.

Equivariant (not eigen-) functions in nonautonomous dynamics

- Because the nonautonomous driving is aperiodic, it **does not make sense to talk about eigenfunctions** of the transfer operator cocycle.
- In the quasi-compact setting [Thieullen'87, F/Lloyd/Quas'10&'13, Gonzalez-Tokman/Quas'14, Blumenthal'16] one can show (via a Multiplicative Ergodic Theorem) that there is a finite or countable set of Lyapunov exponents $0 = \lambda_1 > \lambda_2 > \dots$ associated with the transfer operator cocycle and a family of **Oseledets (covariant) functions** $\{f_\omega\}_{\omega \in \Omega}$ satisfying:

$$\lim_{n \rightarrow \infty} \frac{1}{n} \log \|\mathcal{P}_\omega^n f_{k,\omega}\| = \lambda_k.$$

- Moreover, the $f_{k,\omega}$ are **equivariant**: $\mathcal{P}_\omega(f_{k,\omega}) = \lambda_{k,\omega} f_{k,\sigma\omega}$.
- The λ_k correspond to the Λ_k in the autonomous setting ($\lambda_k = \log |\Lambda_k|$).
- The $\{f_{k,\omega}\}_{\omega \in \Omega}$ are the nonautonomous family corresponding to the (single) k^{th} eigenfunction f_k in the autonomous setting.

Equivariant (not eigen-) functions in nonautonomous dynamics

- Because the nonautonomous driving is aperiodic, it **does not make sense to talk about eigenfunctions** of the transfer operator cocycle.
- In the quasi-compact setting [Thieullen'87, F/Lloyd/Quas'10&'13, Gonzalez-Tokman/Quas'14, Blumenthal'16] one can show (via a Multiplicative Ergodic Theorem) that there is a finite or countable set of Lyapunov exponents $0 = \lambda_1 > \lambda_2 > \dots$ associated with the transfer operator cocycle and a family of **Oseledets (covariant) functions** $\{f_\omega\}_{\omega \in \Omega}$ satisfying:

$$\lim_{n \rightarrow \infty} \frac{1}{n} \log \|\mathcal{P}_\omega^n f_{k,\omega}\| = \lambda_k.$$

- Moreover, the $f_{k,\omega}$ are **equivariant**: $\mathcal{P}_\omega(f_{k,\omega}) = \lambda_{k,\omega} f_{k,\sigma\omega}$.
- The λ_k correspond to the Λ_k in the autonomous setting ($\lambda_k = \log |\Lambda_k|$).
- The $\{f_{k,\omega}\}_{\omega \in \Omega}$ are the nonautonomous family corresponding to the (single) k^{th} eigenfunction f_k in the autonomous setting.

Similar to the autonomous case, extreme values (red/yellow) of the ω -dependent family of Oseledets functions for large Lyapunov spectral values indicate **spatially mobile “coherent sets”**.

1536

G. Froyland et al. / Physica D 239 (2010) 1527–1541

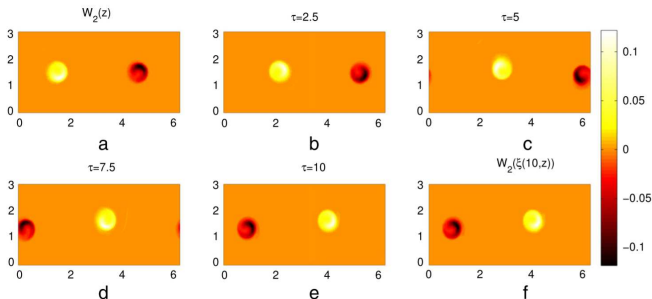
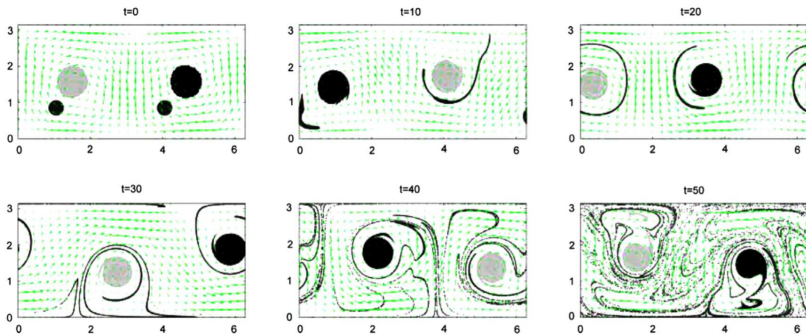


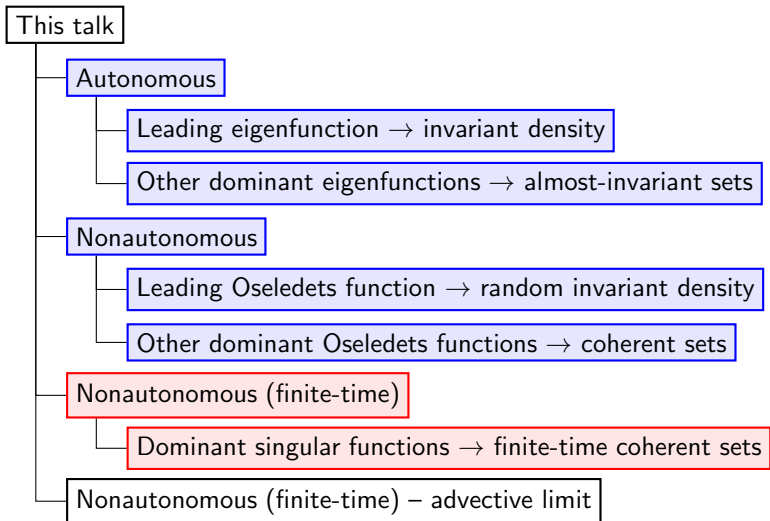
Fig. 11. (a) Graph of approximate Oseledets function $W_2^{(80,40)}(z)$ produced by Algorithm 4. (b)–(e) Push forwards of $W_2^{(80,40)}(z)$ via multiplication by $P^{(\tau)}(z)$ for $\tau = 2.5, 5, 7.5, 10$. (f) $W_2^{(80,40)}(\xi(10, z))$ produced independently by Algorithm 4; compare with (e).

Oseledets functions $f_{2,\omega}$, for a travelling wave flow with a perturbation that is driven aperiodically by the Lorenz equations.

Coherent sets



Evolution of coherent sets (and randomly chosen nearby sets) by the Lorenz-driven perturbation of a travelling wave flow (from [F/Lloyd/Santitissadeekorn'10]).



Slowly decaying structures in finite time

- What about finite time durations (finite k)?
- We want to find a sequence of Λ_k and f_k so that $\|\mathcal{P}_{T_n} \circ \dots \circ \mathcal{P}_{T_2} \circ \mathcal{P}_{T_1} f_k\| = \Lambda_k^n \|f_k\|$ with $\Lambda_k \leq 1$ **as large as possible**.
- This is accomplished by setting $1 = \Lambda_1 > \Lambda_2 > \dots \geq 0$ to be **singular values** of (a suitably weighted version of) $\mathcal{P}_{T_n} \circ \dots \circ \mathcal{P}_{T_2} \circ \mathcal{P}_{T_1}$, and $\mathbf{1} = f_1, f_2, \dots$ to be the corresponding **singular vectors**.
- This leads to the **slowest decay in finite time** [F/Santitissadeekorn/Monahan'10,F'13].
- In particular, the singular value Λ_2 **exactly quantifies the slowest decay from time 1 to n** for the nonautonomous dynamics.

Slowly decaying structures in finite time

- What about finite time durations (finite k)?
- We want to find a sequence of Λ_k and f_k so that $\|\mathcal{P}_{T_n} \circ \cdots \circ \mathcal{P}_{T_2} \circ \mathcal{P}_{T_1} f_k\| = \Lambda_k^n \|f_k\|$ with $\Lambda_k \leq 1$ **as large as possible**.
- This is accomplished by setting $1 = \Lambda_1 > \Lambda_2 > \cdots \geq 0$ to be **singular values** of (a suitably weighted version of) $\mathcal{P}_{T_n} \circ \cdots \circ \mathcal{P}_{T_2} \circ \mathcal{P}_{T_1}$, and $\mathbf{1} = f_1, f_2, \cdots$ to be the corresponding **singular vectors**.
- This leads to the **slowest decay in finite time** [F/Santitissadeekorn/Monahan'10,F'13].
- In particular, the singular value Λ_2 **exactly quantifies the slowest decay from time 1 to n** for the nonautonomous dynamics.

Slowly decaying structures in finite time

- What about finite time durations (finite k)?
- We want to find a sequence of Λ_k and f_k so that $\|\mathcal{P}_{T_n} \circ \cdots \circ \mathcal{P}_{T_2} \circ \mathcal{P}_{T_1} f_k\| = \Lambda_k^n \|f_k\|$ with $\Lambda_k \leq 1$ **as large as possible**.
- This is accomplished by setting $1 = \Lambda_1 > \Lambda_2 > \cdots \geq 0$ to be **singular values** of (a suitably weighted version of) $\mathcal{P}_{T_n} \circ \cdots \circ \mathcal{P}_{T_2} \circ \mathcal{P}_{T_1}$, and $\mathbf{1} = f_1, f_2, \cdots$ to be the corresponding **singular vectors**.
- This leads to the **slowest decay in finite time** [F/Santitissadeekorn/Monahan'10,F'13].
- In particular, the singular value Λ_2 **exactly quantifies the slowest decay from time 1 to n** for the nonautonomous dynamics.

Slowly decaying structures in finite time

- What about finite time durations (finite k)?
- We want to find a sequence of Λ_k and f_k so that $\|\mathcal{P}_{T_n} \circ \cdots \circ \mathcal{P}_{T_2} \circ \mathcal{P}_{T_1} f_k\| = \Lambda_k^n \|f_k\|$ with $\Lambda_k \leq 1$ **as large as possible**.
- This is accomplished by setting $1 = \Lambda_1 > \Lambda_2 > \cdots \geq 0$ to be **singular values** of (a suitably weighted version of) $\mathcal{P}_{T_n} \circ \cdots \circ \mathcal{P}_{T_2} \circ \mathcal{P}_{T_1}$, and $\mathbf{1} = f_1, f_2, \cdots$ to be the corresponding **singular vectors**.
- This leads to the **slowest decay in finite time** [F/Santitissadeekorn/Monahan'10,F'13].
- In particular, the singular value Λ_2 **exactly quantifies the slowest decay from time 1 to n** for the nonautonomous dynamics.

Slowly decaying structures in finite time

- What about finite time durations (finite k)?
- We want to find a sequence of Λ_k and f_k so that $\|\mathcal{P}_{T_n} \circ \cdots \circ \mathcal{P}_{T_2} \circ \mathcal{P}_{T_1} f_k\| = \Lambda_k^n \|f_k\|$ with $\Lambda_k \leq 1$ **as large as possible**.
- This is accomplished by setting $1 = \Lambda_1 > \Lambda_2 > \cdots \geq 0$ to be **singular values** of (a suitably weighted version of) $\mathcal{P}_{T_n} \circ \cdots \circ \mathcal{P}_{T_2} \circ \mathcal{P}_{T_1}$, and $\mathbf{1} = f_1, f_2, \dots$ to be the corresponding **singular vectors**.
- This leads to the **slowest decay in finite time** [F/Santitissadeekorn/Monahan'10,F'13].
- In particular, the singular value Λ_2 **exactly quantifies the slowest decay from time 1 to n** for the nonautonomous dynamics.

Coherent transport in the presence of diffusion

- Consider a vector field $v(x, t)$ on a domain $X \subset \mathbb{R}^d$.
- For small $\epsilon > 0$ the SDE $dx = v(x, t)dt + \epsilon dW$ models paths of an advection-diffusion process.
- The corresponding advection-diffusion (or Fokker-Planck) equation for this SDE is

$$\frac{\partial f}{\partial t}(x, t) = -\nabla \cdot (f(x, t)v(x, t)) + \frac{\epsilon^2}{2} \Delta f(x, t) \quad (1)$$

- Solutions of the above PDE are given by the corresponding transfer operator:

$$f(x, t) = \mathcal{P}_{t_0, \epsilon}^t f(x, t_0),$$

where $\mathcal{P}_{t_0, \epsilon}^t : L^2(X) \rightarrow L^2(X)$ is the transfer operator evolving a mass distribution $f(x, t_0)$ at t_0 to the future distribution at t .

Coherent transport in the presence of diffusion

- Consider a vector field $v(x, t)$ on a domain $X \subset \mathbb{R}^d$.
- For small $\epsilon > 0$ the SDE $dx = v(x, t)dt + \epsilon dW$ models paths of an advection-diffusion process.
- The corresponding advection-diffusion (or Fokker-Planck) equation for this SDE is

$$\frac{\partial f}{\partial t}(x, t) = -\nabla \cdot (f(x, t)v(x, t)) + \frac{\epsilon^2}{2} \Delta f(x, t) \quad (1)$$

- Solutions of the above PDE are given by the corresponding transfer operator:

$$f(x, t) = \mathcal{P}_{t_0, \epsilon}^t f(x, t_0),$$

where $\mathcal{P}_{t_0, \epsilon}^t : L^2(X) \rightarrow L^2(X)$ is the transfer operator evolving a mass distribution $f(x, t_0)$ at t_0 to the future distribution at t .

Coherent transport in the presence of diffusion

- Consider a vector field $v(x, t)$ on a domain $X \subset \mathbb{R}^d$.
- For small $\epsilon > 0$ the SDE $dx = v(x, t)dt + \epsilon dW$ models paths of an advection-diffusion process.
- The corresponding advection-diffusion (or Fokker-Planck) equation for this SDE is

$$\frac{\partial f}{\partial t}(x, t) = -\nabla \cdot (f(x, t)v(x, t)) + \frac{\epsilon^2}{2}\Delta f(x, t) \quad (1)$$

- Solutions of the above PDE are given by the corresponding transfer operator:

$$f(x, t) = \mathcal{P}_{t_0, \epsilon}^t f(x, t_0),$$

where $\mathcal{P}_{t_0, \epsilon}^t : L^2(X) \rightarrow L^2(X)$ is the transfer operator evolving a mass distribution $f(x, t_0)$ at t_0 to the future distribution at t .

Coherent transport in the presence of diffusion

- Consider a vector field $v(x, t)$ on a domain $X \subset \mathbb{R}^d$.
- For small $\epsilon > 0$ the SDE $dx = v(x, t)dt + \epsilon dW$ models paths of an advection-diffusion process.
- The corresponding advection-diffusion (or Fokker-Planck) equation for this SDE is

$$\frac{\partial f}{\partial t}(x, t) = -\nabla \cdot (f(x, t)v(x, t)) + \frac{\epsilon^2}{2} \Delta f(x, t) \quad (1)$$

- **Solutions of the above PDE are given by the corresponding transfer operator:**

$$f(x, t) = \mathcal{P}_{t_0, \epsilon}^t f(x, t_0),$$

where $\mathcal{P}_{t_0, \epsilon}^t : L^2(X) \rightarrow L^2(X)$ is the transfer operator evolving a mass distribution $f(x, t_0)$ at t_0 to the future distribution at t .

Stratospheric polar vortex

- In the stratosphere over each pole, there is huge whirlpool of cold air centred over the pole.
- The boundary of the vortex (the polar front jet stream) is a barrier that stops polar air and subtropical air from mixing.
- The polar vortex and this mixing interface is constantly changing.

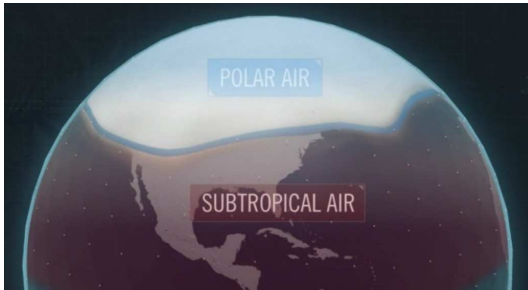
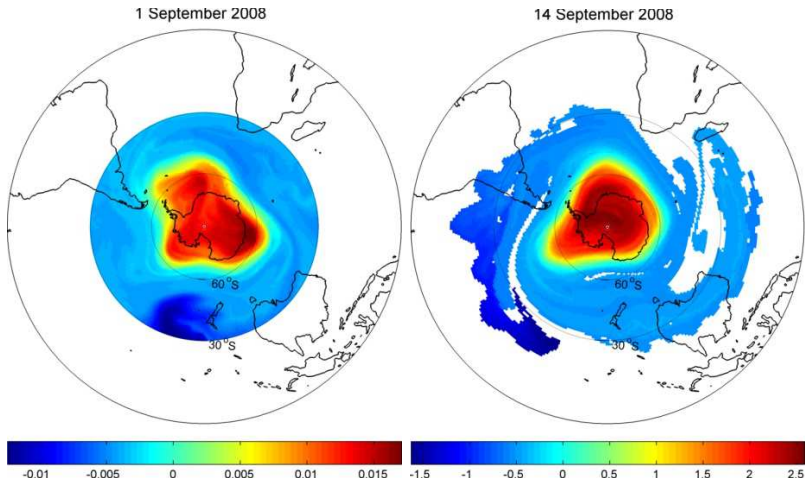


Image: National Geographic.

The polar vortex is a slowly mixing object

- We wish to **resolve the polar vortex as the slowest decaying object** in the vicinity of the pole.
- We do this by **numerically approximating transfer operators** \mathcal{P} using ECMWF vector fields, and computing the second singular vectors (left and right).
- Our initial domain is a 475K isentropic surface and we **follow the flow for two weeks** from September 1, 2008 until September 14, 2008.
- Other work on resolving the polar vortex includes Boffetta *et al.* '01, Koh/Legras '02, Rypina *et al.* '07, Lekien/Ross '10, de la Cámara *et al.* '12, Padberg-Gehle/Schneide'17, Serra *et al.*'17

The left & right second singular vectors f_2 & $\mathcal{P}f_2$



See [F/Santitissadeekorn/Monahan'10].

Particle simulation demonstrating the identified vortex inhibits global mixing

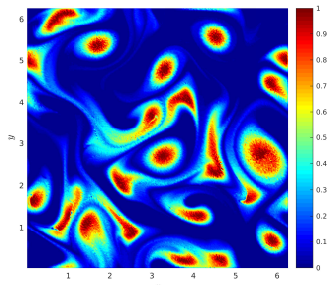
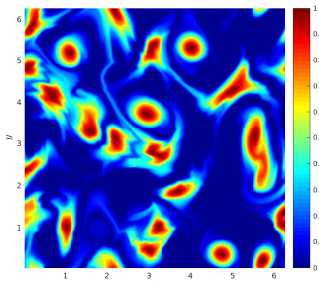
Multiple sets: 2D turbulence

Consider the velocity field $u : \mathbb{T}^2 \times \mathbb{R} \rightarrow \mathbb{R}^2$ that solves

$$\partial_t u + u \cdot \nabla u = -\nabla p + \nu \Delta u + f; \quad \nabla \cdot u = 0$$

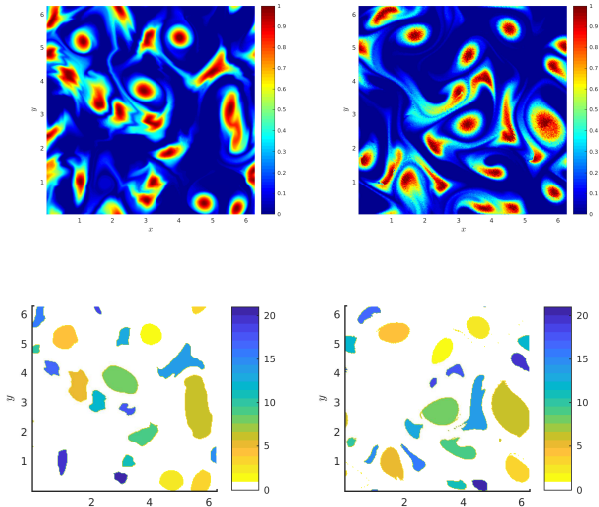
where the toral domain $\mathbb{T}^2 = [0, 2\pi] \times [0, 2\pi]$.

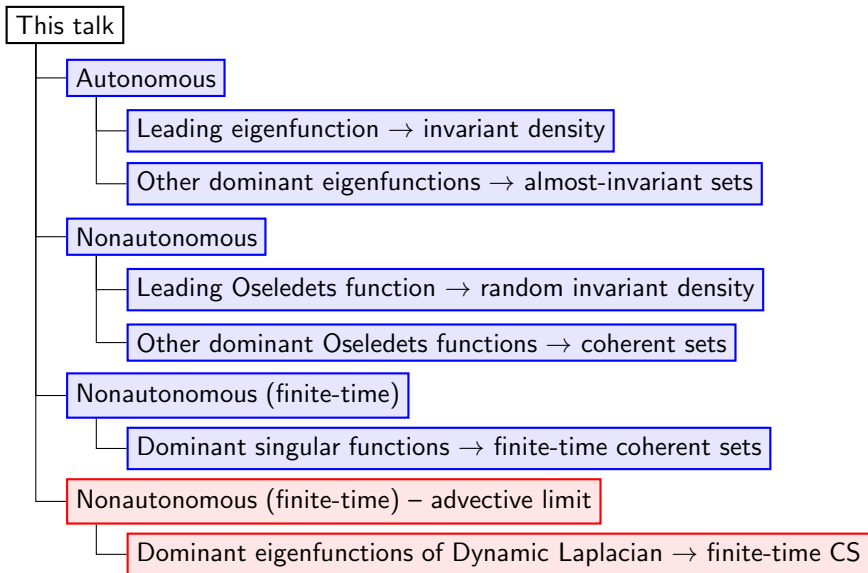
Using data from [Hadjighasem *et al.*'17] and techniques from [F/Rock/Sakellariou, *subm.*]: a superposition of 21 rotated singular vectors of the transfer operator are shown below (left singular vector, $t = 0$; right singular vector $t = 50$).



2D turbulence

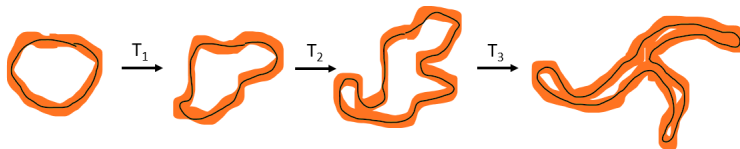
From these singular vectors we can extract individual sets that are coherent under 50 time units of turbulent flow.





Small diffusion regime

- In geophysical flow, one is often interested in the regime where advection plays a stronger role than diffusion.
- In the presence of small diffusion, the only region in which mixing across the boundary can occur is in the **orange** neighbourhood of the boundary interface.

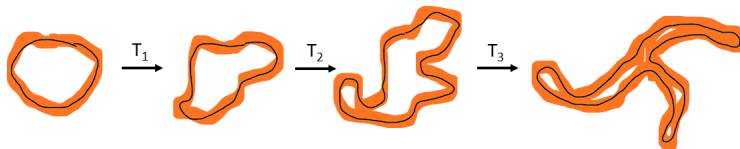


- The amount of mixing occurring is proportional to the **area of the orange region**. This area is **minimised** by the singular vectors of the transfer operator [F'13].



Small diffusion regime

- In geophysical flow, one is often interested in the regime where advection plays a stronger role than diffusion.
- In the presence of small diffusion, the only region in which mixing across the boundary can occur is in the **orange** neighbourhood of the boundary interface.

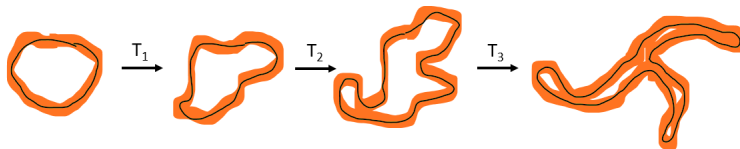


- The amount of mixing occurring is proportional to the **area of the orange region**. This area is **minimised by the singular vectors of the transfer operator** [F'13].



Small diffusion regime

- In geophysical flow, one is often interested in the regime where advection plays a stronger role than diffusion.
- In the presence of small diffusion, the only region in which mixing across the boundary can occur is in the **orange** neighbourhood of the boundary interface.

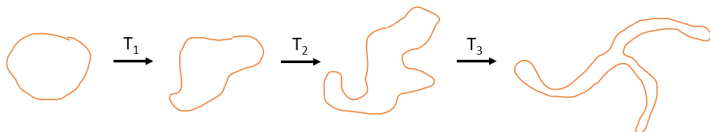


- The amount of mixing occurring is proportional to the **area of the orange region**. This area is **minimised by the singular vectors of the transfer operator** [F'13].



Small diffusion regime

- In oceanography, one is often interested in the regime where advection plays a stronger role than diffusion.
- In the presence of small diffusion, the only region in which mixing across the boundary can occur is in the **orange** neighbourhood of the boundary interface.



- The amount of mixing occurring is proportional to the **area of the orange region**. This area is **minimised by the singular vectors of the transfer operator**.
- In the **pure advection limit**, as the diffusion amplitude goes to zero, (the orange band narrows), the **length of the boundary/interface determines the amount of “mixing”**. ([Mathew *et al*'05, Thiffeault'12])

Small diffusion regime

- A limiting form of the earlier transfer operator constructions yields the **dynamic Laplace operator** $\Delta_{t_0,t}^D$ [F'15,F/Kwok'17]:

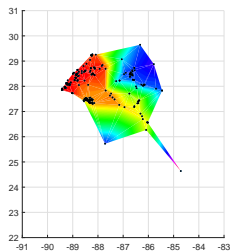
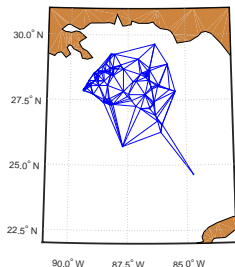
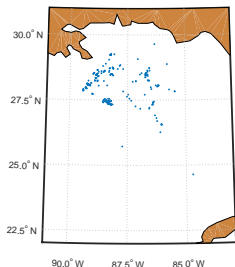
$$\lim_{\epsilon \rightarrow 0} \frac{((\mathcal{L}_{t_0,\epsilon}^t)^* \mathcal{L}_{t_0,\epsilon}^t - \text{Id})f}{\epsilon^2} = c \underbrace{(\Delta + (T_{t_0}^t)^* \circ \Delta \circ (T_{t_0}^t)_*)}_{:= \Delta_{t_0,t}^D} f,$$

where $\mathcal{L}_{t_0,\epsilon}^t$ is a weighted version of $\mathcal{P}_{t_0,\epsilon}^t$, c is a constant, $(T_{t_0}^t)^* f = f \circ T_{t_0}^t$, and $(T_{t_0}^t)_* f = f \circ (T_{t_0}^t)^{-1}$.

- The **orthogonal eigenfunctions of the dynamic Laplacian** $\Delta_{t_0,t}^D$ provide independent solutions to the **persistently smallest interface (isoperimetric) problem**.
- In the small diffusion regime, eigenvectors of $\Delta_{t_0,t}^D$ correspond to singular vectors of \mathcal{L}_ϵ and the two approaches coincide.
- There is a **formal dual interpretation of coherent sets** in terms of **mixing properties** and **small interfaces** [F'15,F/Kwok'17], (also [Karrasch/Keller,subm.]).

Implementation

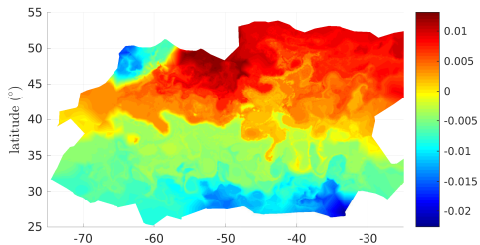
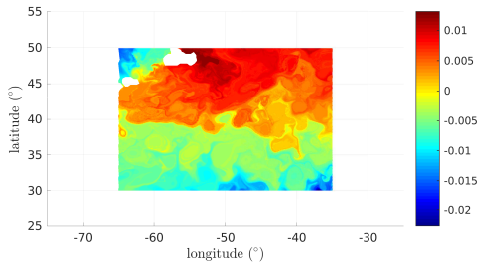
- A convenient, flexible, and accurate way to approximate the operator Δ^D is using a specialised **finite element method** [F/Junge'18] (see Oliver's talk on Friday).
- The **only input data are the positions of trajectories**; these can be **sparse, scattered**, and have **missing elements**.
- As in the transfer operator approaches, **no derivative information is required**, but if present, it can be used. There are **no free parameters** to select, and estimates of mixing barriers and persistently small interfaces are provided on the **full phase space**.



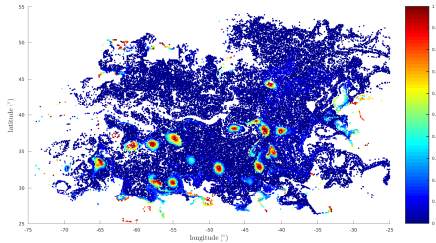
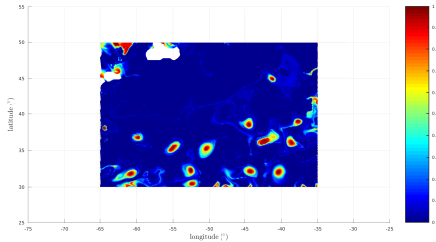
SST in the North Atlantic

- The following movies use AVISO satellite altimetry to derive time-dependent velocity fields.
- I used 56205 nonautonomous trajectories (positions only, no derivatives!) over a flow period from 15 January 2015 to 15 April 2015 (90 days) [trajectory data courtesy of Irina Rypina].
- The movies show daily evolution.
- Techniques from [F/Junge'18] combined with [F/Rock/Sakelleriou, subm.].

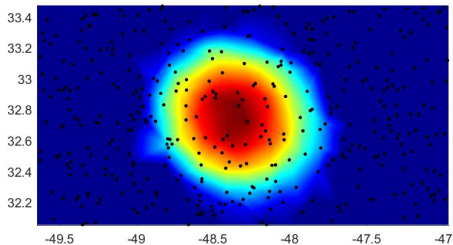
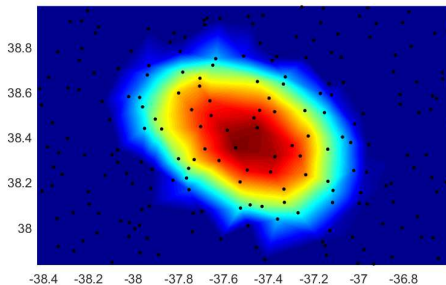
Large-scale features



Small-scale features



High-resolution eddies vs sparse data



This talk

Autonomous

Leading eigenfunction \rightarrow invariant density

Other dominant eigenfunctions \rightarrow almost-invariant sets

Nonautonomous

Leading Oseledets function \rightarrow random invariant density

Other dominant Oseledets functions \rightarrow coherent sets

Nonautonomous (finite-time)

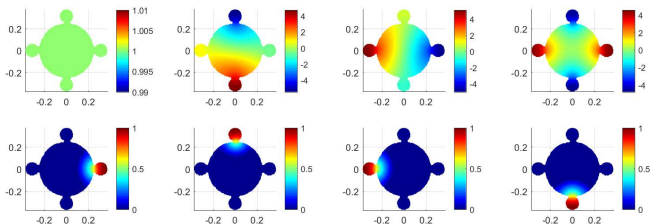
Dominant singular functions \rightarrow finite-time coherent sets

Nonautonomous (finite-time) – advective limit

Dominant eigenfunctions of Dynamic Laplacian \rightarrow finite-time CS

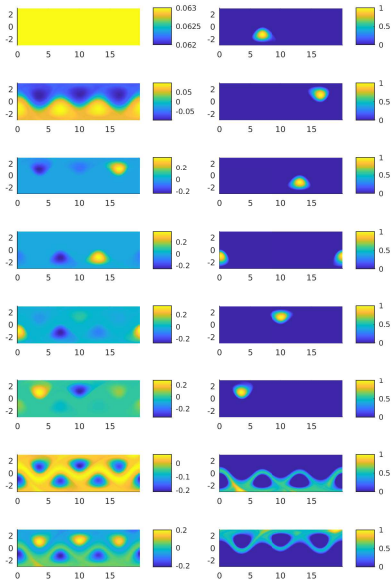
Automatic feature separation – Sparse Eigenbasis Approximation (SEBA)

SEBA – Sparse Eigenbasis Approximation



- The **features captured in extreme values** of eigen-(singular-)(Oseledets-) vectors of transfer operators, eigenvectors of the Koopman operator, and eigenvectors of the (Dynamic) Laplace operator, are often **“mixed” between different eigenvectors** (*first row, standard Laplace eigenfunctions*).
- We would like to highlight the 4 geometric “knobs” on the outside of the large disk, (*second row*).
- The second row is a solution of a sparse eigenbasis approximation problem, where **one rotates the (four-dimensional) eigenbasis** to find the **best-approximating sparse basis**; see [F/Rock/Sakellariou].

SEBA – Sparse Eigenbasis Approximation



(Left:) SEBA applied to leading 8 eigenfunctions of Dynamic Laplacian of Bickley jet.

See also [F/Rock/Sakellariou] for:

- 1 **automatic feature separation** procedure based on SEBA,
- 2 **a rescaling of the spectrum** to better identify eigengaps,
- 3 **determining natural spatial scales** from eigenfunctions, in contrast to temporal scales given by eigengaps.

See my webpage for code.

Other nonautonomous analysis with transfer operators

- **(Quenched)** statistical limit laws for **nonautonomous** systems, e.g. (Quenched) Central Limit Theorem, (Quenched) Local Central Limit Theorem, (Quenched) Large Deviation Principle.
- Obtained by differentiating leading Lyapunov of twisted transfer operator cocycles wrt the twist parameter
[Dragicevic/F/Gonzalez-Tokman/Vaianti'18].

Other nonautonomous analysis with transfer operators

- **(Quenched)** statistical limit laws for **nonautonomous** systems, e.g. (Quenched) Central Limit Theorem, (Quenched) Local Central Limit Theorem, (Quenched) Large Deviation Principle.
- Obtained by differentiating leading Lyapunov of twisted transfer operator cocycles wrt the twist parameter [Dragicevic/F/Gonzalez-Tokman/Vaianti'18].

Other nonautonomous analysis with transfer operators

- **(Quenched)** statistical limit laws for **nonautonomous** systems, e.g. (Quenched) Central Limit Theorem, (Quenched) Local Central Limit Theorem, (Quenched) Large Deviation Principle.
- Obtained by differentiating leading Lyapunov of twisted transfer operator cocycles wrt the twist parameter [Dragicevic/F/Gonzalez-Tokman/Vaianti'18].
- Mixing optimisation – **manipulating the transfer operator spectrum to optimally perturb time-dependent vector fields** to enhance mixing.
- Periodic case treated in [F/Santitissadeekorn'17] and nonautonomous case to be submitted shortly with P. Koltai and M. Plonka.

Other nonautonomous analysis with transfer operators

- **(Quenched)** statistical limit laws for **nonautonomous** systems, e.g. (Quenched) Central Limit Theorem, (Quenched) Local Central Limit Theorem, (Quenched) Large Deviation Principle.
- Obtained by differentiating leading Lyapunov of twisted transfer operator cocycles wrt the twist parameter [Dragicevic/F/Gonzalez-Tokman/Vaianti'18].
- Mixing optimisation – **manipulating the transfer operator spectrum to optimally perturb time-dependent vector fields** to enhance mixing.
- Periodic case treated in [F/Santitissadeekorn'17] and nonautonomous case to be submitted shortly with P. Koltai and M. Plonka.

Thanks go to:



Australian Government

Australian Research Council



**UNIVERSITIES
AUSTRALIA**

and my collaborators:

C. González-Tokman (Queensland), S. Lloyd (X'ian-Liverpool),
O. Junge (TU Munich), A. Monahan (Victoria),
R. Murray (Canterbury), A. Quas (Victoria), C. Rock (UNSW),
K. Sakellariou (UNSW), N. Santitissadeekorn (Surrey),