

Stochastic homogenization of a class
of nonconvex viscous Hamilton-Jacobi
equations in one space dimension

Elena Kosygina

Baruch College and the CUNY Graduate Center
joint work with

Andrea Davini →

Sapienza University of Rome



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We consider a viscous HJ equation

$$\partial_t u^\varepsilon = \varepsilon a\left(\frac{x}{\varepsilon}, \omega\right) \partial_{xx}^2 u^\varepsilon + G(\partial_x u^\varepsilon) + \beta V\left(\frac{x}{\varepsilon}, \omega\right) \text{ in } (0, \infty) \times \mathbb{R};$$
$$u^\varepsilon \Big|_{t=0} = q(x), \quad x \in \mathbb{R}$$

Random medium:

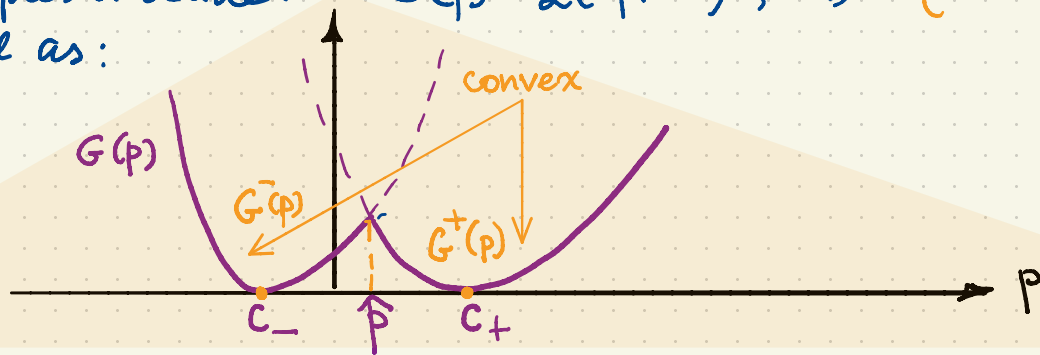
- $(\Omega, \mathcal{F}, \mathbb{P})$ probability space, Ω - Polish space, \mathcal{F} - Borel σ -algebra on Ω , \mathbb{P} invariant under the shifts by x and ergodic with respect to the shifts.
- $a, V : \mathbb{R} \times \Omega \rightarrow [0, 1]$ are stationary with respect to the shifts by $x \in \mathbb{R}$ and Lipschitz continuous in x .
- $\operatorname{ess\,inf}_{x \in \mathbb{R}} V(x, \omega) = 0$ and $\operatorname{ess\,sup}_{x \in \mathbb{R}} V(x, \omega) = 1$ a.s.

(an additional condition on V later)

$$(1) \quad \partial_t u^\varepsilon = \varepsilon a\left(\frac{x}{\varepsilon}, \omega\right) \partial_{xx}^2 u^\varepsilon + G(\partial_x u^\varepsilon) + \beta V\left(\frac{x}{\varepsilon}, \omega\right) \text{ in } (0, \infty) \times \mathbb{R}$$

$$u^\varepsilon|_{t=0} = g(x), \quad x \in \mathbb{R}.$$

- $\beta \geq 0$ is a constant;
 - G continuous, superlinear (precise conditions later)
- Examples include: $G(p) = \frac{1}{2}(|p| - c)^2$, $c \geq 0$ (as in A. Tilmaz's talk)
- as well as:



- "(1) homogenizes" if $\exists \bar{H}$ a continuous coercive function such that w.p. 1 $\forall g \in UC(\mathbb{R})$ $u^\varepsilon(t, x, \omega) \xrightarrow[\text{loc}]{\Rightarrow} \bar{u}(t, x)$ as $\varepsilon \downarrow 0$ where $\bar{u}_t = \bar{H}(\partial_x \bar{u})$ in $(0, \infty) \times \mathbb{R}$, $\bar{u}(0, x) = g(x)$ in \mathbb{R} .

Remarks:

- It is known that (under conditions which we check) it is sufficient to show that for each $\theta \in \mathbb{R}$

$$u_{\theta}^{\varepsilon}(1, 0, \omega) \xrightarrow{\varepsilon \rightarrow 0} \bar{H}(\theta) \quad \text{a.s.} \quad (2)$$

where u_{θ}^{ε} is a solution of (1) with $g(x) = \theta x$.

Recall that $t\bar{H}(\theta) + \theta x$ solves $\partial_t \bar{u} = \bar{H}(\partial_x \bar{u})$ with $\bar{u}(0, x) = \theta x$.

- $u_{\theta}^{\varepsilon}(t, x, \omega) = \varepsilon u_{\theta}\left(\frac{t}{\varepsilon}, \frac{x}{\varepsilon}, \omega\right)$ where u solves

$$\begin{aligned} \partial_t u_{\theta} &= a(x, \omega) \partial_{xx} u_{\theta} + G(\partial_x u_{\theta}) + \beta V(x, \omega) \quad \text{in } (0, \infty) \times \mathbb{R} \\ u_{\theta}|_{t=0} &= \theta x \end{aligned}$$

$$\bar{H}(\theta) = \lim_{\varepsilon \rightarrow 0} \varepsilon u_{\theta}\left(\frac{1}{\varepsilon}, 0, \omega\right) = \lim_{t \rightarrow \infty} \frac{1}{t} u_{\theta}(t, 0, \omega) \quad \text{if (2) holds}$$

Notation: when the limit in (2) exists it defines a map: $\beta, G(\cdot) \longmapsto \bar{H}(\cdot)$; $\bar{H} = \mathcal{H}_{\beta}(G)$

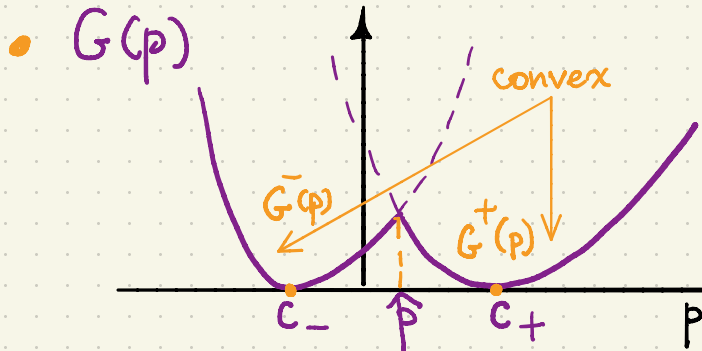
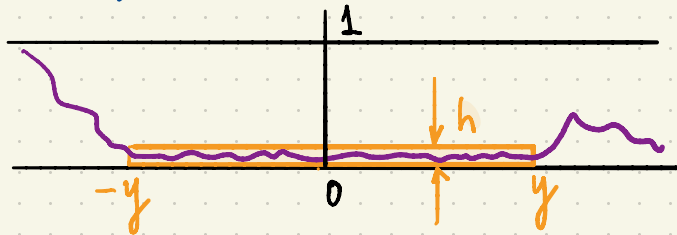
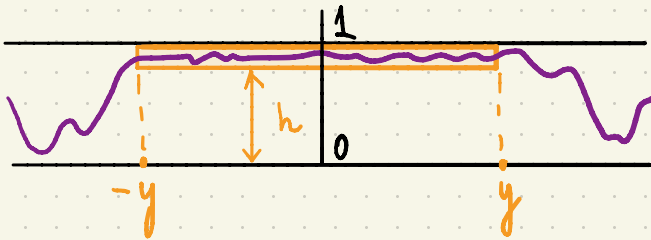
Conditions on V and $G(\cdot)$:

- Valley & hill: $\forall h \in (0, 1) \forall y > 0$

(V&H)

$P(\{[-y, y] \text{ is a valley (resp. hill)}\}) > 0$

where an interval I is said to be an h -valley (resp. h -hill) if $V(x, \omega) \leq h$ (resp. $V(x, \omega) \geq h$) $\forall x \in I$.



and G^\pm satisfy for some $\alpha_0, \alpha_1 > 0$ and $\gamma > 1$

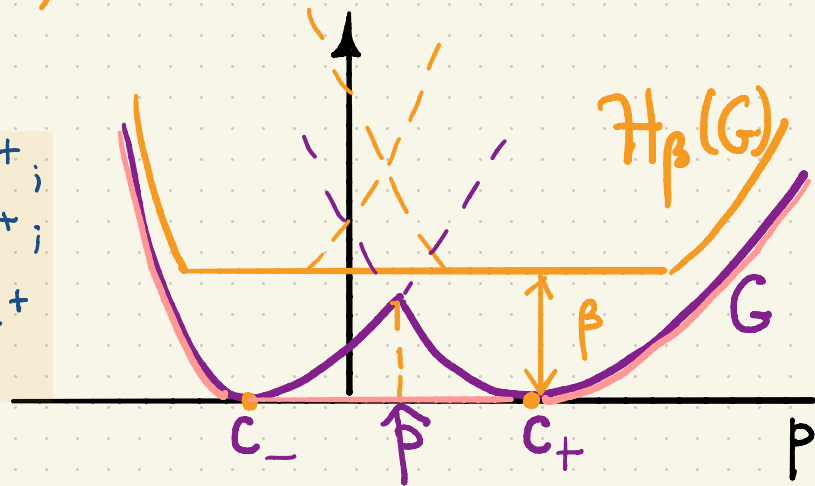
- $\alpha_0 |p|^\gamma - \frac{1}{\alpha_0} \leq G^\pm(p) \leq \alpha_1 (|p|^\gamma + 1)$
- $|G^\pm(p) - G^\pm(q)| \leq \alpha_1 (|p|^\gamma + |q|^\gamma + 1)^{\gamma-1} |p - q|$
 $\forall p, q \in \mathbb{R}$

Theorem 1 (Davini, K, 2020+)

Under the above conditions on a , V , and G (1) homogenizes and the effective Hamiltonian $H_\beta(G)$ is characterized as follows:

- if $\beta \geq G(\beta)$ (strong potential) then

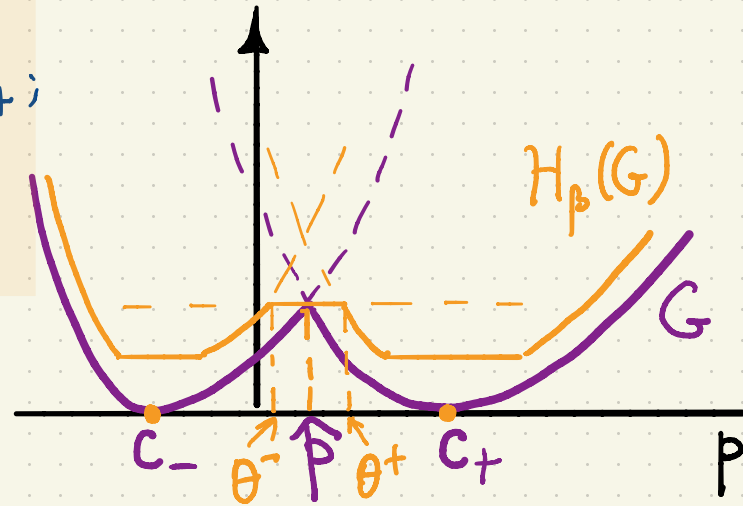
$$H_\beta(G)(\theta) = \begin{cases} H_\beta(G^+)(\theta) & \text{if } \theta > c^+; \\ \beta & \text{if } c^- \leq \theta \leq c^+; \\ H_\beta(G^-)(\theta) & \text{if } \theta < c^- \end{cases}$$



$$= \text{conv}(H_\beta(G^+) \wedge H_\beta(G^-)) = H_\beta(\text{conv}(G^+ \wedge G^-))$$

- if $\beta < G(\hat{p})$ (weak potential) then

$$H_{\beta}(G)(\theta) = \begin{cases} H_{\beta}(G^{+}) & \text{if } \theta > \theta_{+}; \\ G(\hat{p}) & \text{if } \theta_{-} \leq \theta \leq \theta_{+}; \\ H_{\beta}(G^{-}) & \text{if } \theta < \theta_{-}, \end{cases}$$



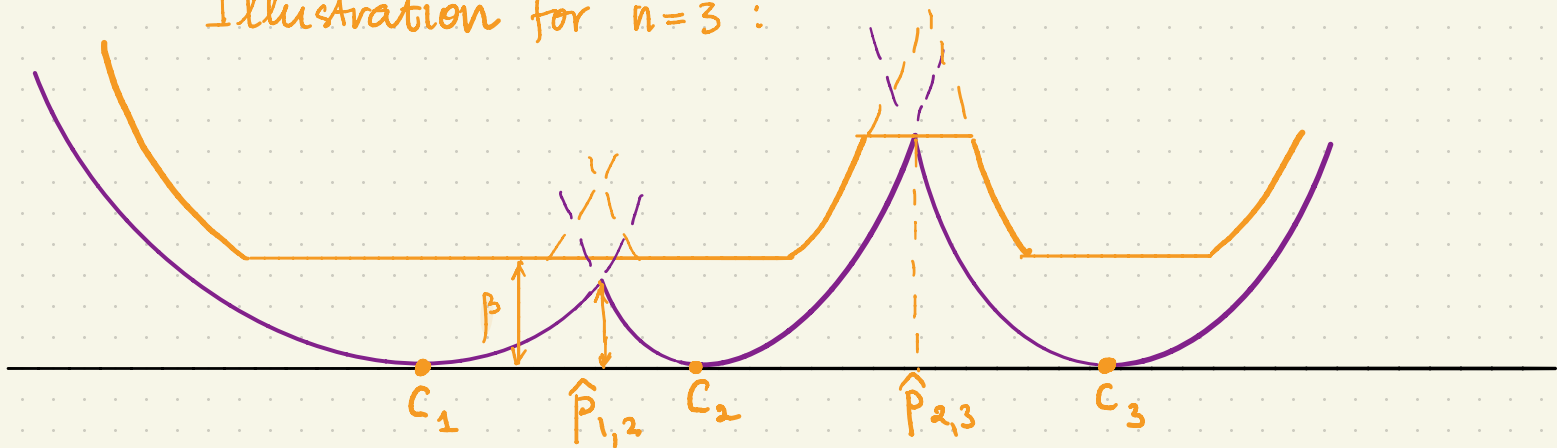
where θ_{+} (resp. θ_{-}) is the unique solution in $[\hat{p}, c_{+}]$ (resp. $[c_{-}, \hat{p}]$) of the equation

$$H_{\beta}(G^{+}) = G(\hat{p}) \quad (\text{resp. } H_{\beta}(G^{-}) = G(\hat{p}))$$

Theorem 2 (Darini, K, 2020+)

The last theorem generalizes to the case when G is a minimum of $n > 2$ convex functions with the same absolute minimum.

Illustration for $n=3$:

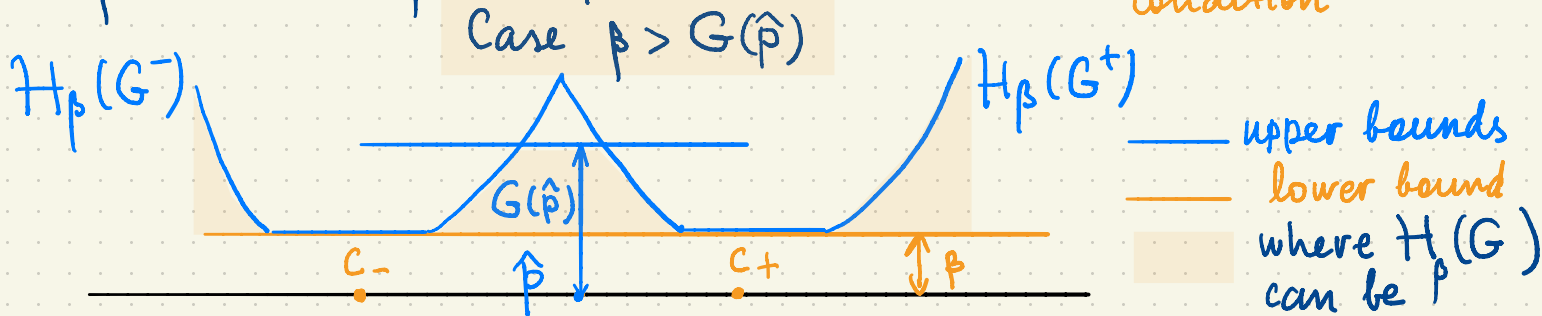


About proofs: for $\beta \geq 0$, $G(\cdot)$ let

$$H_\beta^U(G)(\theta) = \limsup_{\varepsilon \rightarrow 0} \varepsilon u_\theta(\frac{1}{\varepsilon}, \theta, \omega); \quad H_\beta^L(G)(\theta) = \liminf_{\varepsilon \rightarrow 0} \varepsilon u_\theta(\frac{1}{\varepsilon}, \theta, \omega)$$

We need to show that $H_\beta^U(G) \equiv H_\beta^L(G)$.

- $H_\beta^U(G) \leq H_\beta(G^+) \wedge H_\beta(G^-)$; - uniform upper bound
- Show that $\beta \leq H_\beta^L(G)(\theta) \forall \theta \in \mathbb{R}$; - uniform lower bound
uses the hill condition
- $H_\beta(G^\pm)(c_\pm) \leq \beta$; simple comparison: $\beta t + c_\pm x$ is a supersolution
since $G^\pm(c_\pm) = 0$
- $H_\beta^U(G)(\theta) \leq \beta \vee G(\hat{p})$ for $c_- \leq \theta \leq c_+$ - uses the valley condition



What happens in "shaded areas"?

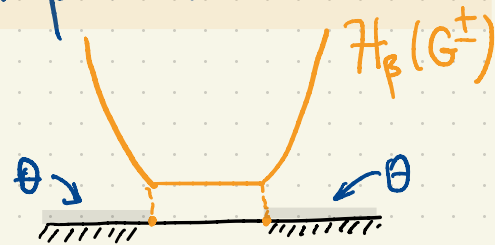
Correctors for convex "pieces". Consider G^\pm and check that the assumptions of Cardaliaguet and Souganidis (2017) hold. Argue that $\forall \theta$ such that $H_\beta(G^\pm)(\theta) > \beta$ and $\forall \omega \in \Omega_\theta$ of full measure there is a unique sublinear solution v_θ of

$$(3) \quad a(x, \omega) v_\theta'' + G^\pm(v_\theta' + \theta) + \beta V(x, \omega) = H_\beta(G^\pm) \text{ in } \mathbb{R}$$

satisfying $v_\theta(0, \omega) = 0 \quad \forall \omega \in \Omega_\theta$.

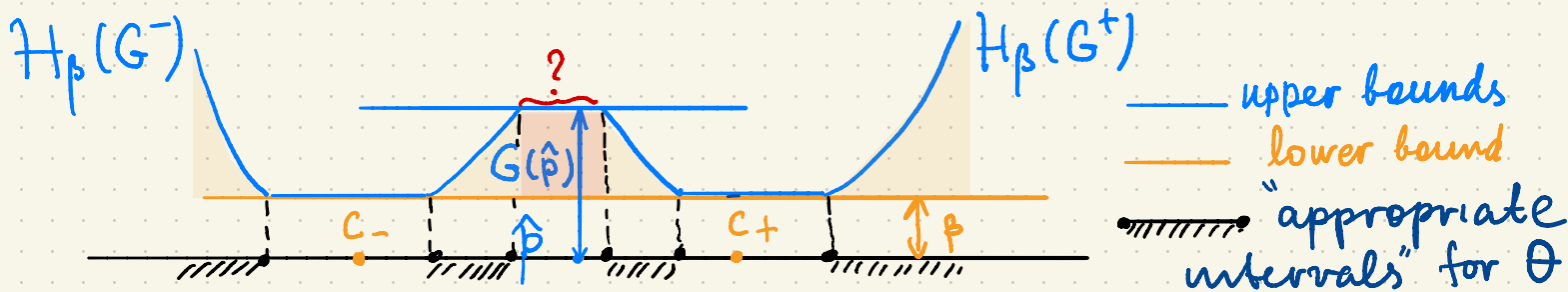
Moreover,

- Ω_θ is shift invariant;
- v_θ is $\kappa(\theta)$ -Lip, where κ is locally bounded;
- v_θ' is stationary (not used)



- We establish bounds on v_θ' which allow us to conclude that the same v_θ are correctors for G when θ is in "appropriate intervals".

Case $\beta > G(\hat{p})$

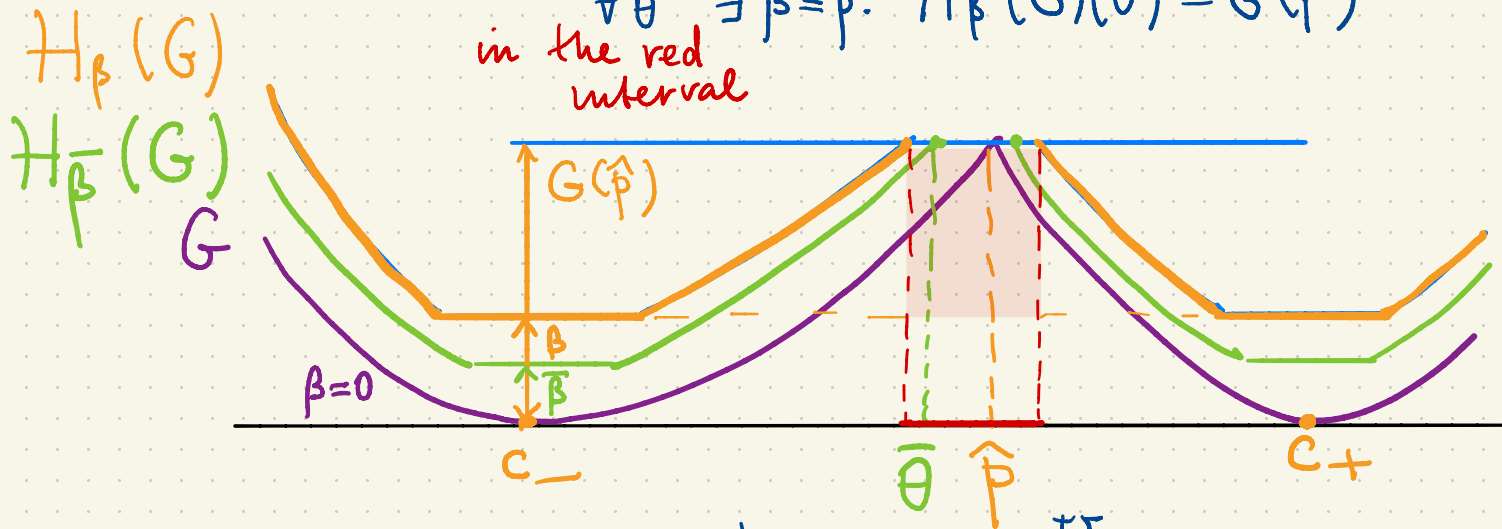


- We conclude that on these "appropriate intervals" $H_\beta^U(G) = H_\beta^L(G) = H_\beta(G)$ and this common value coincides with $H_\beta(G^-)(\theta)$ if $\theta < \hat{p}$ and with $H_\beta(G^+)(\theta)$ if $\theta > \hat{p}$.

- The "final cut" (same as in Yilmaz, Zeitouni (2019))

$$\forall \bar{\theta} \exists \bar{\beta} \leq \beta: \mathcal{H}_{\bar{\beta}}(G)(\bar{\theta}) = G(\hat{p})$$

in the red interval



$$G(\hat{p}) = \underbrace{\mathcal{H}_{\bar{\beta}}(G)(\bar{\theta})}_{\text{monotonicity in } \beta} \leq \mathcal{H}_{\beta}^L(G)(\bar{\theta}) \leq \underbrace{\mathcal{H}_{\beta}^U(G)(\bar{\theta})}_{\text{upper bound for } c_- \leq \bar{\theta} \leq c_+} \leq G(\hat{p})$$

Conclusion: for θ in the red interval $\mathcal{H}_{\beta}(G)(\theta) = G(\hat{p})$



- Broader view

$$\begin{aligned} \partial_t u^\varepsilon &= \varepsilon \operatorname{tr} \left(A \left(\frac{x}{\varepsilon}, \omega \right) D_x^2 u^\varepsilon \right) + H \left(D_x u, \frac{x}{\varepsilon}, \omega \right) \text{ in } (0, \infty) \times \mathbb{R}^d \\ u^\varepsilon \Big|_{t=0} &= g(x), \quad x \in \mathbb{R}^d \end{aligned} \tag{4}$$

When $H(p, x, \omega)$ is not convex in p there are counterexamples to homogenization for $d \geq 2$.

- Ziliotto (2017): $d=2$, $A \equiv 0$, $H(p, x, \omega) = G(p) + V(x, \omega)$
Generalization by Feldman, Souganidis (2017): $d \geq 2$.

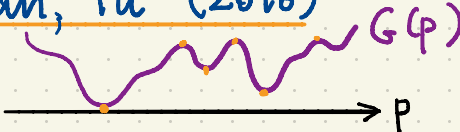
If $G(p)$ has a strict local saddle point then it is possible to construct a random environment (very slowly mixing) and a potential V so that homogenization fails.

- Feldman, Fermanian, Ziliotto (2019+): $A \equiv I$, $d=2$.
 $H(p, x, \omega) = G(p) + V(x, \omega)$; extension to the viscous case.

Stochastic homogenization for nonconvex Hamiltonians

Inviscid case ($A \equiv 0$)

$d=1$: Darini, Siconolfi (2009)
level set convex $H(p, x, \omega)$

Armstrong, Tran, Yu (2016)
 $G(p) + V(x, \omega)$ 

Gao (2019), extension to $H(p, x, \omega)$

$d \geq 1$: Armstrong, Souganidis (2013)
level set convex $H(p, x, \omega)$

($d \geq 1$ will be continued on the next page)

- Open problem for $d=1$: prove homogenization for a sufficiently general class of non-convex H in the viscous case
- Homogenization for level set convex H , $d \geq 1$, in the viscous case?

Viscous case ($A \geq 0$)

$d=1$ Darini, K (2017)
"pinned" Hamiltonians, such as
 $\sigma(x, \omega) |p|^\gamma - b(x, \omega) |p|$, $\gamma > 1$
 $\alpha_0 \leq \sigma, b \leq \frac{1}{2\alpha_0}$, $\alpha_0 \in (0, 1)$

Yilmaz, Zeitouni (2017); $A \equiv 1$
discrete case

$\frac{1}{2} p^2 - c|p| + \beta V(x, \omega)$ under $V \& H$ condition

K, Yilmaz, Zeitouni (2020); $A \equiv 1$
continuous case.

Stochastic homogenization for nonconvex Hamiltonians

Inviscid case ($A \equiv 0$)

$d \geq 1$ Armstrong, Tran, Yu (2015)

$$G(p) = (|p|^2 - 1)^2$$

Feldman, Sengulidis (2017)

H with strictly star-shaped sub-level sets.

Qian, Tran, Yu (2017)

$G(p) = |F(p)|$ where F is even, coercive, level set convex with $\min_{\mathbb{R}^d} F < 0$.

Viscous case ($A \geq 0$)

$d \geq 1$ Armstrong, Cardaliaguet (2018); finite range of dependence

$$\exists \gamma > 1 : H(te, x, \omega) \equiv t^\gamma H(e, x, \omega) \quad \forall t \geq 0 \\ \forall \|e\| = 1 \quad (\text{homogeneity})$$

Cardaliaguet, Sengulidis (2017)

$(A(p, x, \omega), H(p, x, \omega))$ with radially symmetric law;

A is 0-homogeneous in p

$$0 \leq H(\lambda p, x, \omega) \leq \lambda H(p, x, \omega)$$