

Kinetic Theory for Hamilton-Jacobi PDEs

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IPAM May 2020: Stochastic Analysis Related to
Hamilton-Jacobi PDEs

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(Stochastic) Growth Models

In many models of interest we encounter an interface that separates different phases and is evolving with time. The interface at a location x and time t changes with a rate that depends on (x, t) , and the inclination of the interface at that location. If the interface is represented by a graph of a function $u : \mathbb{R}^d \times [0, \infty) \rightarrow \mathbb{R}$, then a natural model for its evolution is a Hamilton-Jacobi PDE:

$$u_t + H(x, t, u_x) = 0, \quad u(x, 0) = g(x).$$

(In discrete setting some of the variables x , t or u are discrete; examples SEP, HAD, etc.) H is often random (hence u is random), and we are interested in various scaling limits of solutions.

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A Natural Question/Strategy

Select g according to a (reasonable) probability measure μ^0 .

Let us write μ^t for the law of $u(\cdot, t)$ at time t . Note: If Φ_t is the flow (in other words $u(\cdot, t) = (\Phi_t g)(\cdot)$), then $\mu^t = \Phi_t^* \mu^0$.

Question: Can we find a nice/tractable/explicit evolution equation for μ^t ?

We may also keep track of $\rho = u_x$ (more natural). The law of $\rho(\cdot, t)$ is denoted by ν^t . **Equilibrium Measure:** $\nu^t = \nu^0$.

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Some Examples

- ▶ Some exactly solvable discrete models are **determinantal**: The finite dimensional marginals of ν^t can be expressed as a determinant of an explicit matrix. **Example: TASEP** A. Borodin, P. L. Ferrari, M. Prähofer, T. Sasamoto (2007), G. M. Schütz (1997)
- ▶ $d = 1$, $H(x, t, p) = p^2/2$, $\rho(\cdot, 0)$ is a Lévy process. Then $\rho(\cdot, t)$ is also a Lévy process (Bertoin 1998). Associated Lévy measures solve a kinetic-type equation (Smoluchowsky Equation with additive kernel). When $\rho(\cdot, 0)$ is White Noise ($g =$ Brownian Motion), then $x \mapsto \rho(x, t)$ is a Markov process: Linear motion interrupted by stochastic jumps with an explicit kernel (Groeneboom 1989).

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- ▶ $b(\cdot, t)$ solves $b_t(\rho, t) = -H''(\rho)b(\rho, t)^2$. Trivially solved. Note that if $b^0 \geq 0$, then no blow up.
- ▶ $f(\rho_-, \rho_+, t)$ solves a kinetic equation (resembles Smoluchowski but far more complicated) of the form

$$f_t + C(f) = Q(f, f) = Q^+(f, f) - Q^-(f, f),$$

$C(f)$ a first order differential operator (transport type).

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- ▶ Assume $d = 1$, $H(x, t, p) = H(p)$ independent of (x, t) and convex, $\rho^0(x) = \rho(\cdot, 0)$ is a Markov process: An ODE $\dot{\rho}^0 = b^0(\rho^0)$ interrupted by random jumps with jump rate $f^0(\rho_-, \rho_+) d\rho_+$. Then this picture persists at later times: $x \mapsto \rho(x, t)$ is a Markov process of the same type: An ODE $\dot{\rho} = b(\rho, t)$ that is interrupted with random jumps with jump rate $f(\rho_-, \rho_+, t) d\rho_+$. This was conjectured by Menon-Srinivasan (2010), and rigorously established by Kaspar and FR (2016,2019).
- ▶ $b(\cdot, t)$ solves $b_t(\rho, t) = -H''(\rho)b(\rho, t)^2$. Trivially solved. Note that if $b^0 \geq 0$, then no blow up.
- ▶ $f(\rho_-, \rho_+, t)$ solves a kinetic equation (resembles Smoluchowski but far more complicated) of the form

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Main Result I

Setting

- ▶ Assume $d = 1$, $H(x, t, \rho)$ is convex in ρ . The function $\rho(x, t)$ solves

$$\rho_t + H(x, t, \rho)_x = 0, \quad \rho(x, 0) = \rho^0(x).$$

(Or $\rho = u_x$, and u solves $u_t + H(x, t, u_x) = 0$.)

- ▶ Assume that ρ^0 is a Markov process with a drift $b^0(\rho, x)$ and a jump rate $f^0(\rho_-, \rho_+; x) d\rho_+$. This means $x \mapsto \rho^0(x)$ solves an ODE $\dot{\rho}^0(x) = b^0(\rho^0(x), x)$, except at stochastic jump locations. When a jump occurs at a , it changes from ρ_- to $\rho_+ \in (-\infty, \rho_-)$, with a rate $f^0(\rho_-, \rho_+; x, t) d\rho_+$.

Result

This picture persists at later times: $x \mapsto \rho(x, t)$ is a Markov process with a drift $b(\rho; x, t)$ and a rate $f(\rho_-, \rho_+; x, t) d\rho_+$.

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- ▶ b satisfies the linear PDE:

$$b_t + \{H, b\} + H_{\rho\rho}b^2 + 2H_{\rho x}b + H_{xx} = 0,$$

where $\{H, b\} = H_{\rho}b_x - H_x b_{\rho}$. The solution b may blow up in finite time. We will discuss an important class of examples with no blowup.

- ▶ The function $f(\rho_-, \rho_+; x, t)$ satisfies a kinetic (integro-)PDE

$$f_t + (vf)_x + C(f) = Q(f, f),$$

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Main Result II

A scenario with no blowup

We now describe an important class of examples for which b is already determined and there is never a blowup. In this case, even the kinetic equation for f simplifies! Recall that the job of $b(\rho; x, t)$ was to produce a classical solution in between jump discontinuities. A natural candidate for a classical solution is the **fundamental solution**:

Given a pair (y, g) , define a fundamental solution associated with (y, g) by

$$w(x, t; y, g) = w(x, t) = g + \inf \left\{ \int_0^t L(\dot{z}(s), z(s), s) ds : z(t) = x \right\}$$

where $v \mapsto L(v, x, t)$ is the Legendre conjugate of $p \mapsto H(p, x, t)$.

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A scenario with no blowup

Given a discrete set $\{(y_i, g_i) : i \in I\}$, consider a solution of the form

$$u(x, t) = \inf_{i \in I} w(x, t; y_i, g_i).$$

Example: If $H(x, t, p) = H(p)$, we simply have

$$w(x, t; y, g) = g + tL\left(\frac{x - y}{t}\right).$$

Important Remark: For each t , there exists $I(t) \subseteq I$ such that

$$t < t' \implies I(t') \subseteq I(t),$$

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We can show that for each t , there are

$$\cdots < x_i(t) < x_{i+1}(t) < \cdots, \quad \cdots < y_i(t) < y_{i+1}(t) < \cdots,$$

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Main Result

Theorem

The process $x \mapsto \rho(x, t)$ is Markov if this is the case initially. At a discontinuity point $x_i(t)$, the position y_j jumps to $y_{i+1} \in (y_i, \infty)$ stochastically with rate $\hat{f}(y_i, y_{i+1}; x_i, t) dy_{i+1}$.

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- ▶ The function $\hat{f}(y_-, y_+; x, t)$ satisfies a kinetic PDE

$$\hat{f}_t + (\hat{v}\hat{f})_x = \hat{Q}(\hat{f}, \hat{f}),$$

where

$$\hat{v}(y_-, y_+, x, t) = \frac{H(x, t, \rho_-) - H(x, t, \rho_+)}{\rho_- - \rho_+},$$

with $\rho_{\pm}(x, t) = w_x(x, t; y_{\pm}, g_{\pm})$ (this does not depend on g).

- ▶ Here is $\hat{Q} = \hat{Q}^+ - \hat{Q}^-$: $\lambda(y_-) = \int \hat{f}(y_-, y_+) dy_+$,
 $A(y_-) = \int (\hat{v}\hat{f})(y_-, y_+) dy_+$,

$$\hat{Q}^+ = \int (\hat{v}(y_+, y_*) - \hat{v}(y_*, y_-)) \hat{f}(y_-, y_*) \hat{f}(y_*, y_+) dy_*$$

$$\hat{Q}^- = [A(y_+) - A(y_-) - v(y_-, y_+)(\lambda(y_+) - \lambda(y_-))] \hat{f}(y_-, y_+)$$

Main Result

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$$\hat{f}_t + (\hat{v}\hat{f})_x = \hat{Q}(\hat{f}, \hat{f}),$$

where

$$\hat{v}(y_-, y_+, x, t) = \frac{H(x, t, \rho_-) - H(x, t, \rho_+)}{\rho_- - \rho_+},$$

with $\rho_{\pm}(x, t) = w_x(x, t; y_{\pm}, g_{\pm})$ (this does not depend on g).

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Since H is convex in momentum variable, one may use variational techniques to study the solutions. However for our results, we use a different approach.

Suppose ρ is a classical solution and solves an ODE associated with b . The compatibility of the two equations

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CLAIM: The picture we have initially persists at later times. The PDE reduces to an interacting particle system!

Particles Configuration

There are particles $\mathbf{q}(t) = \{(x_i(t), \rho_i(t)) : i \in \mathbb{Z}\}$ with $x_i(t) < x_{i+1}(t)$ (we may replace \mathbb{Z} with a finite set).

$x_i(t)$ represents the location of the i -th particle.

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$\rho(\cdot, t)$ solves the ODE $\dot{\rho} = b(\rho, x, t)$ in each (x_i, x_{i+1}) .

Dynamics

- **q motion** We can set up a collection of ODEs for the evolution of $\mathbf{q}(t)$. For example

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Dynamics

- ▶ **Coagulation/Loss of Particle** When two particles meet i.e. $x_i(t) = x_{i+1}(t)$, kill the i -particle, and relabel particles to its right.
- ▶ **The Birth of a Particle** At each blowup of b , a particle is created. How? Details! Can be worked out in some cases.

Our Results

- ▶ Our two results avoid particle births.
- ▶ If there is creation of particles (blowup of b), the kinetic equation for f must be modified. When H is also random, we need to add a term representing the creation.
- ▶ For a variant of our model, when a particle is created, it fragments into two particles.

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- ▶ **The Birth of a Particle** At each blowup of b , a particle is created. How? Details! Can be worked out in some cases.

Our Results

- ▶ Our two results avoid particle births.
- ▶ If there is creation of particles (blowup of b), the kinetic equation for f must be modified. When H is also random, we need to add a term representing the creation.
- ▶ For a variant of our model, when a particle is created, it fragments into two particles.

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In Progress, Joint work with Mehdi Ouaki

Moral

Assume $d = 1$. For a solution of the form

$u(x, t) = \inf_{i \in I(t)} w(x, t; y_i, g_i)$, there are two ways to examine it:

- (1) Examine the set $\{(y_i, g_i) : i \in I(t)\} \in \mathcal{I}(t)$. As t increases, the state space $\mathcal{I}(t)$ is changing with time. All particles (y_i, g_i) stay put. Occasionally a particle dies, because it becomes redundant. Or put it differently, because the set of allowed particles change with time. This point of view is not mathematically tractable.
- (2) Instead, we may switch to $\{(y_i, x_i) : i \in I(t)\} \in \mathcal{J}$ with x_i 's representing the locations of discontinuities. y_i stays put but x_i changes with time. Though the state space no longer changes with time (x_i 's and y_i 's are ordered). This is the point of view that we have successfully adopted in dimension one. We now have a billiard! Disappearance of a particle means that state has reached the boundary to jump to another component of state space

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Kinetic Description in Higher Dimensions

Higher Dimensions

What are the analogs of x_i 's in higher dimensions?

Answer:

There is a **Voronoi type tessellation** initially that evolves to a **Laguerre type tessellation** at a later time.

The vertices of this tessellation play the role of x_i 's. Each particle has a velocity. When two particles collide, two things can happen (different from what we had in the case of $d = 1$):

- ▶ They gain new velocities.
- ▶ They kind of coagulate! (For example, when $d = 2$, a triangular face collapses to a vertex; a particle dies.)

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