

Cycles, Communities, Ergodicity and Communications in Network Topologies

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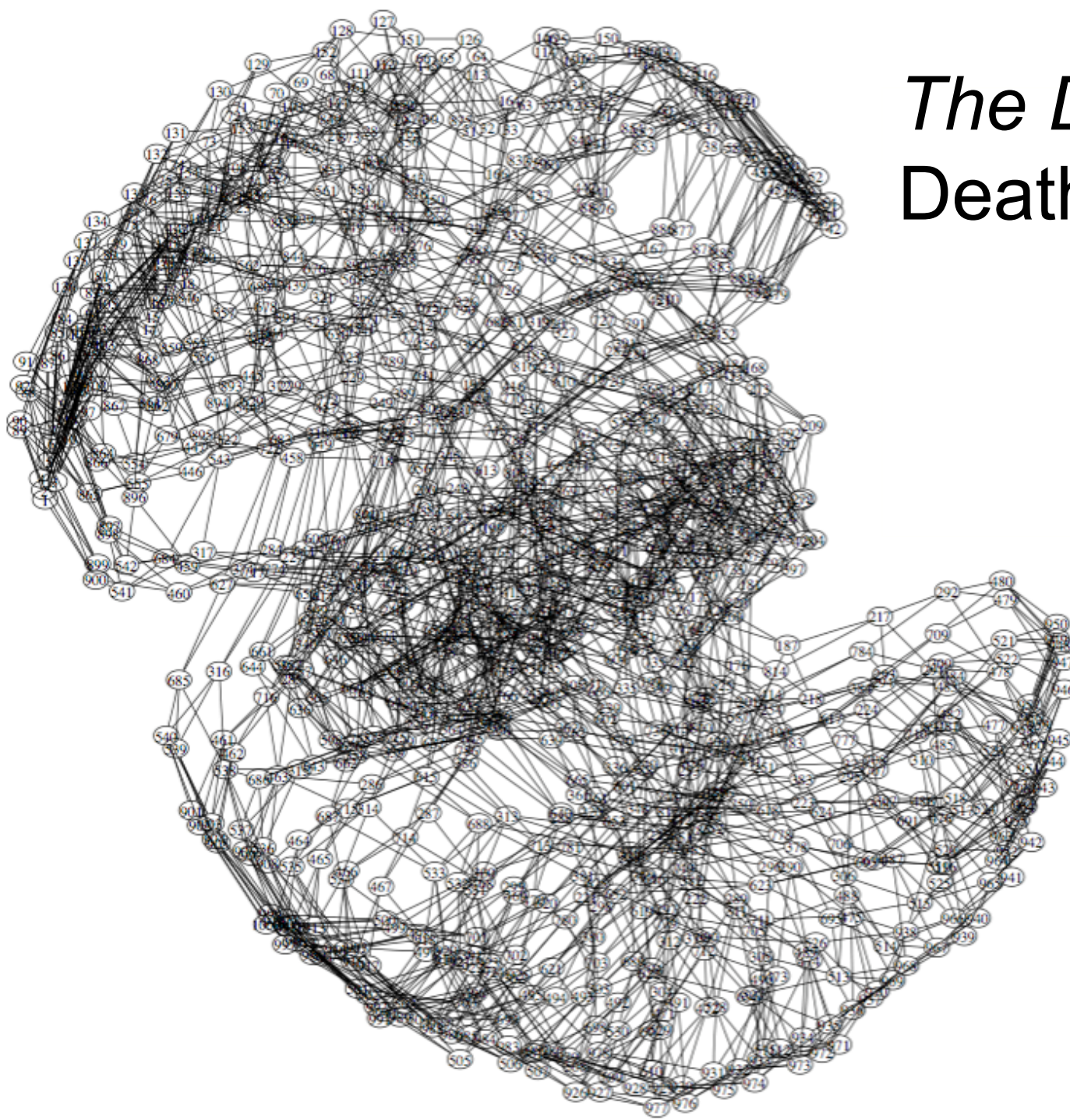
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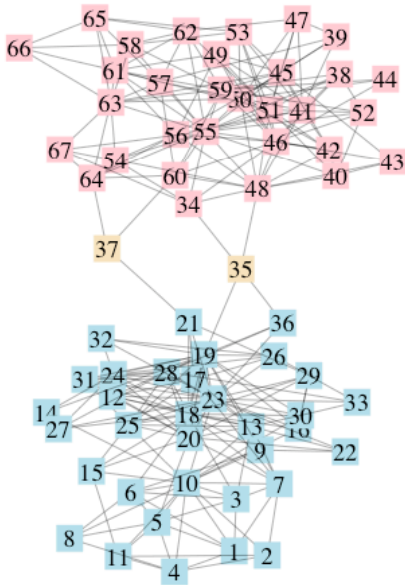
Structure of Talk

1. About Community Partitions and Finding them.
2. About the Loopy Cycles Backbone.
3. About information propagation and sufficiency in dynamically evolving networks.



*The Dreaded
Death Star*

What are Communities?



- Groups of vertices that are densely connected amongst themselves while being loosely connected to the rest of the graph
- Detection can be difficult (expensive)

Why Find Communities?

- Social networks, epidemiology
 - Parallel computing, VLSI
 - Drug dependency in protein-protein interaction networks
 - etc
- ..and visualizing interrelationships

Detection Methods

- Most are either agglomerative, divisive, or spectral
1. ● rewiring the network from scratch while optimizing some parameter
 2. ● selectively removing edges, splitting the network apart
 3. ● analysis of graph Laplacian
 - Our local method is unlike these

3. Spectral Bisection

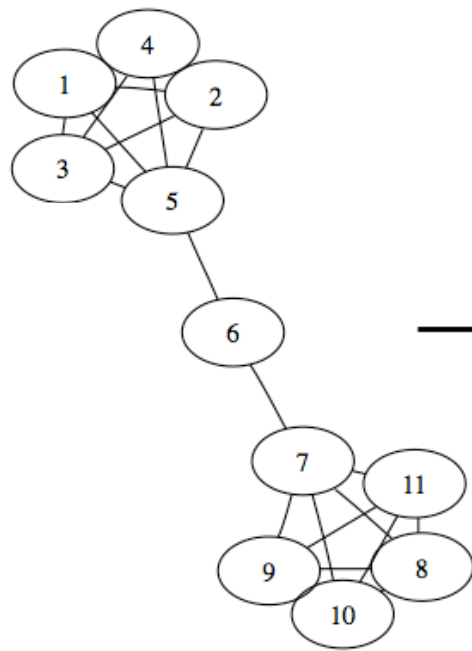
- Fiedler, 1970s. Pothen, Simon, Liou, 1990.
- Use eigenvalues and eigenvectors of graph Laplacian to split graph in half

graph Laplacian, $L(G)$

$$L = \text{diag}(d) - A$$

- $L(G)_{i,i} = \text{degree of node } i$
- $L(G)_{i,j} = -1$ if $i \neq j$ and there is an edge (i,j)
- $L(G)_{i,j} = 0$ otherwise

Example $L(G)$



4	-1	-1	-1	-1	0	0	0	0	0	0	0
-1	4	-1	-1	-1	0	0	0	0	0	0	0
-1	-1	4	-1	-1	0	0	0	0	0	0	0
-1	-1	-1	4	-1	0	0	0	0	0	0	0
-1	-1	-1	-1	5	-1	0	0	0	0	0	0
0	0	0	0	-1	2	-1	0	0	0	0	0
0	0	0	0	0	-1	5	-1	-1	-1	-1	-1
0	0	0	0	0	0	-1	4	-1	-1	-1	-1
0	0	0	0	0	0	-1	-1	4	-1	-1	-1
0	0	0	0	0	0	-1	-1	-1	4	-1	-1
0	0	0	0	0	0	-1	-1	-1	-1	4	4

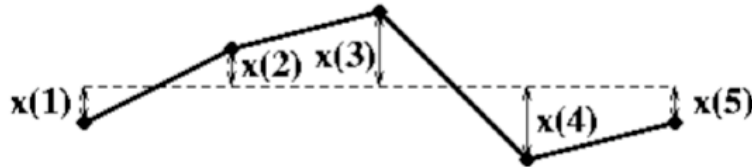
Some Properties of $L(G)$

- Symmetric
- eigenvalues are non-negative.
 - First eigenvalue always zero
- number of connected components in graph equals number of eigenvalues equal to zero
- $\lambda_2 \neq 0$ i.f.f. G is connected

Partition based on 2nd eigenvector (v_2)

- For each node n in G :
 - if $v_2(n) < 0$, put n in partition N_- .
 - else put n in partition N_+

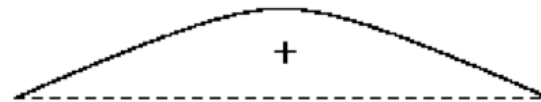
Motivation: vibrating string analogy



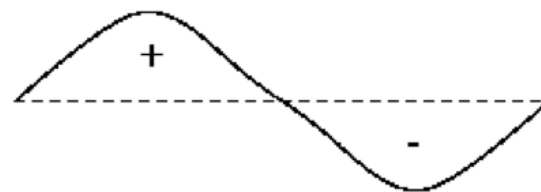
$$m\ddot{u}(x, t) = -k\Delta u(x, t)$$

$$m \frac{d^2}{dt^2} \begin{pmatrix} u_1 \\ u_2 \\ \dots \\ u_j \\ \dots \\ u_n \end{pmatrix} = -k \begin{pmatrix} 2u_1 - u_2 \\ -u_1 + 2u_2 - u_3 \\ \dots \\ -u_{j-1} + 2u_j - u_{j+1} \\ \dots \\ 2u_{n-1} + u_n \end{pmatrix} = k \begin{pmatrix} 2 & -1 & & & \\ -1 & 2 & -1 & & \\ & & \dots & & \\ & & & -1 & 2 \end{pmatrix} \begin{pmatrix} u_1 \\ u_2 \\ \dots \\ u_j \\ \dots \\ u_n \end{pmatrix}$$

- split graph based on second mode

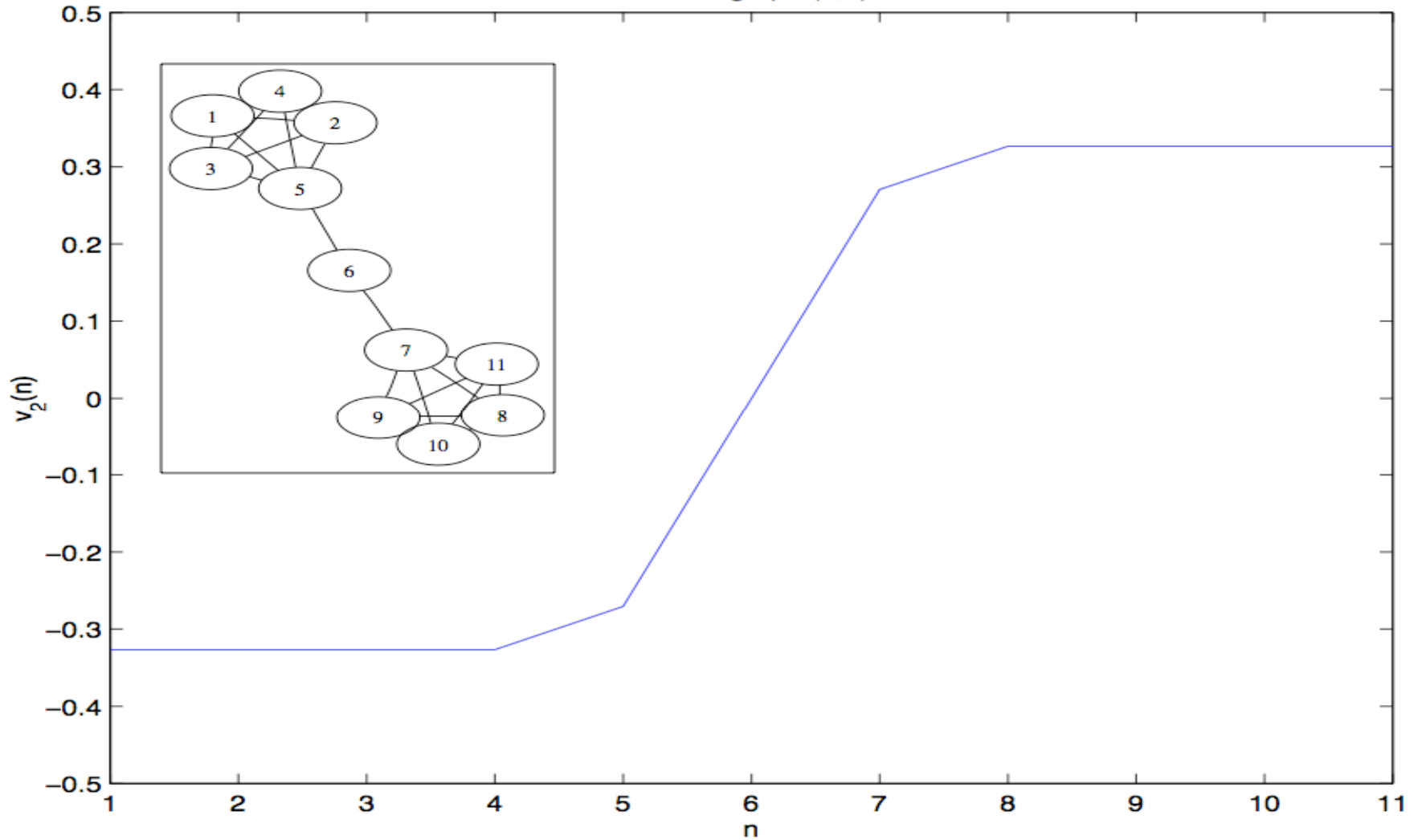


Lowest Frequency



Second Frequency

barbell graph (5,1)

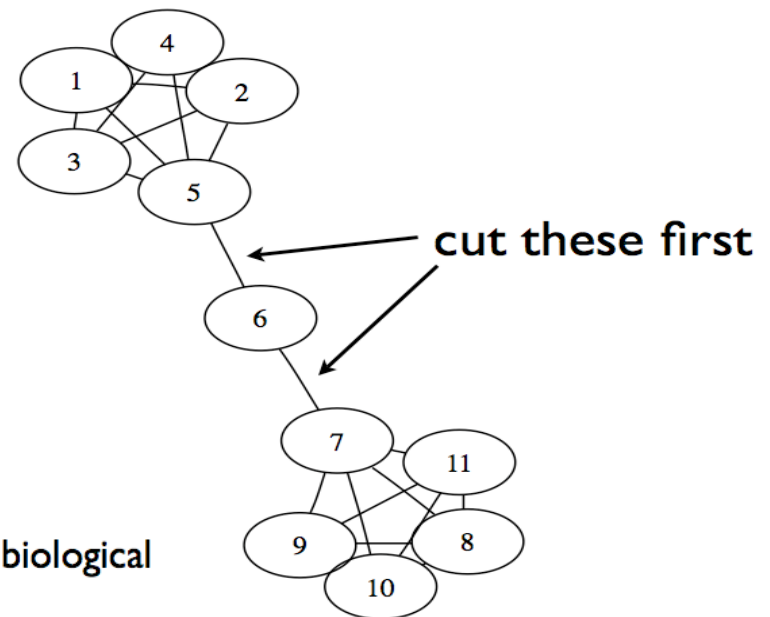


- Need entire Laplacian (could be big)
- Splits graph into two (equal) partitions
- may not be natural

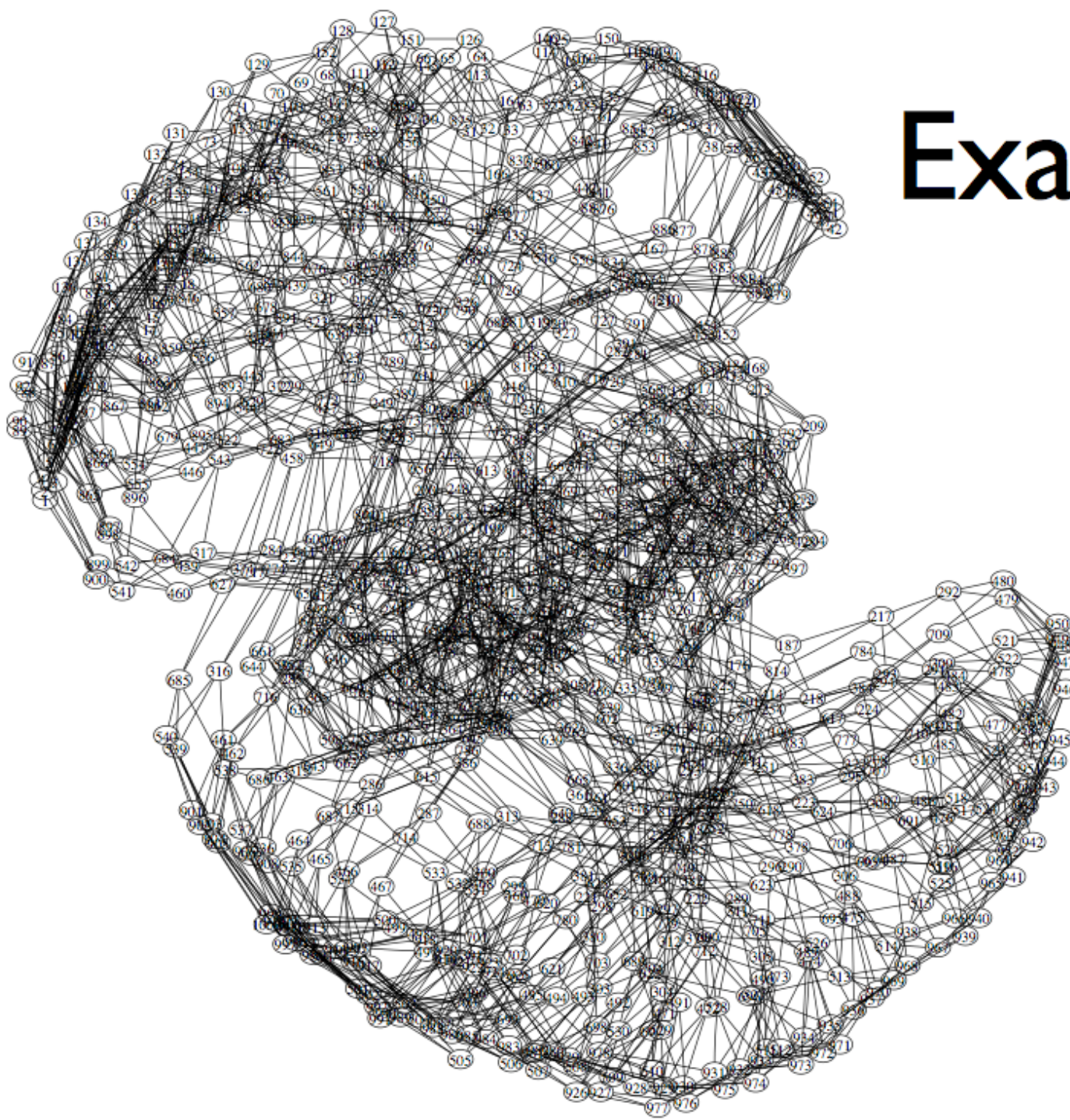
2. Divisive Methods

- Cut edges with maximum centrality to split graph. Repeat
- Edge betweenness most popular measure
 - number of times an edge is used in all-pairs shortest paths
- expensive, $O(n^3)$ at best

Maximum Betweenness



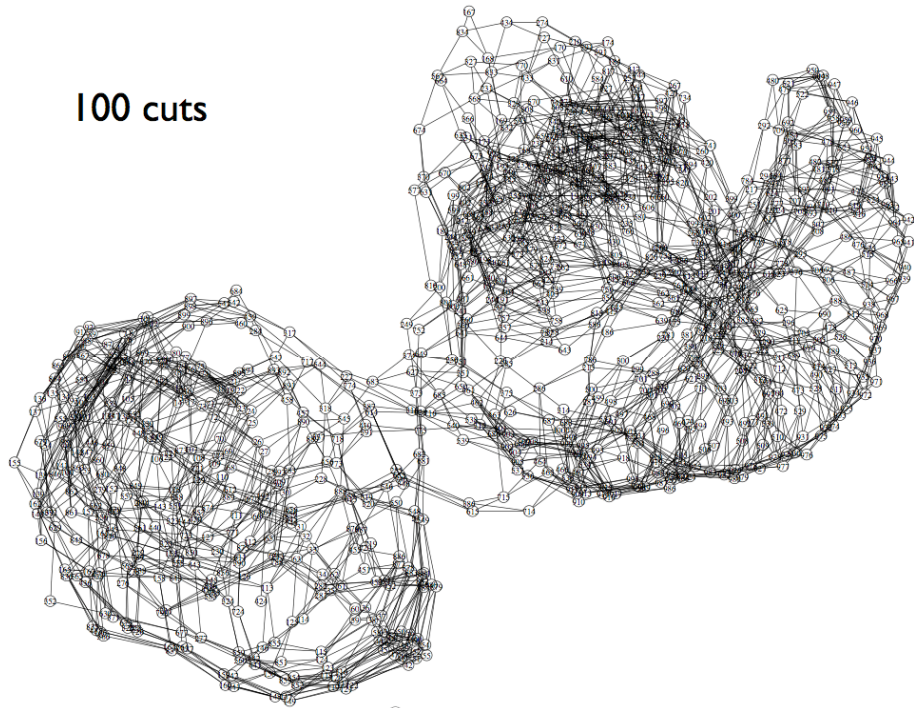
M. Girvan and M.E.J. Newman, Community structure in social and biological networks. Proc. Natl. Acad. Sci. USA 99, 7821-7826 (2002).



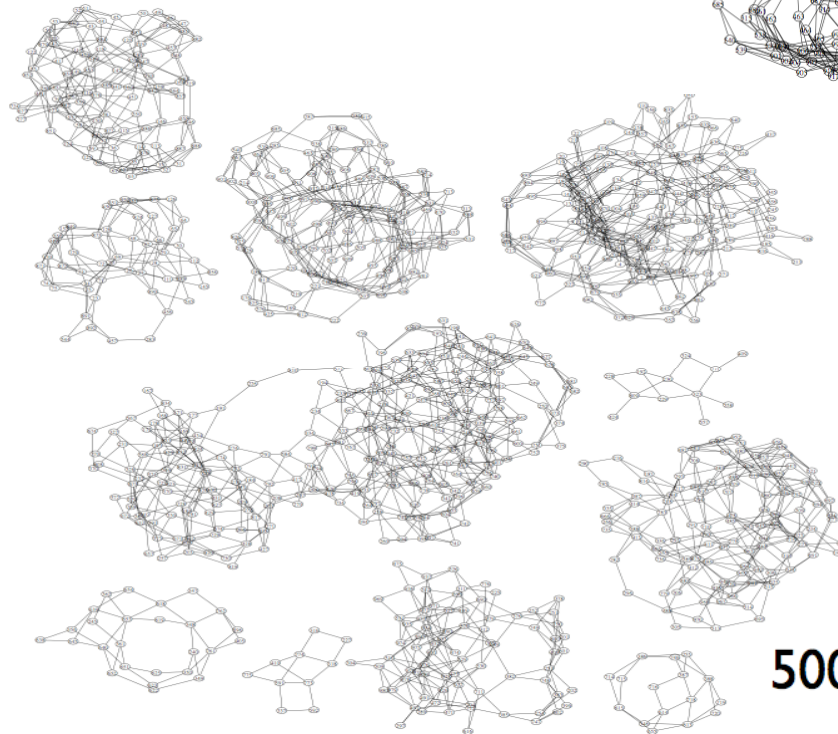
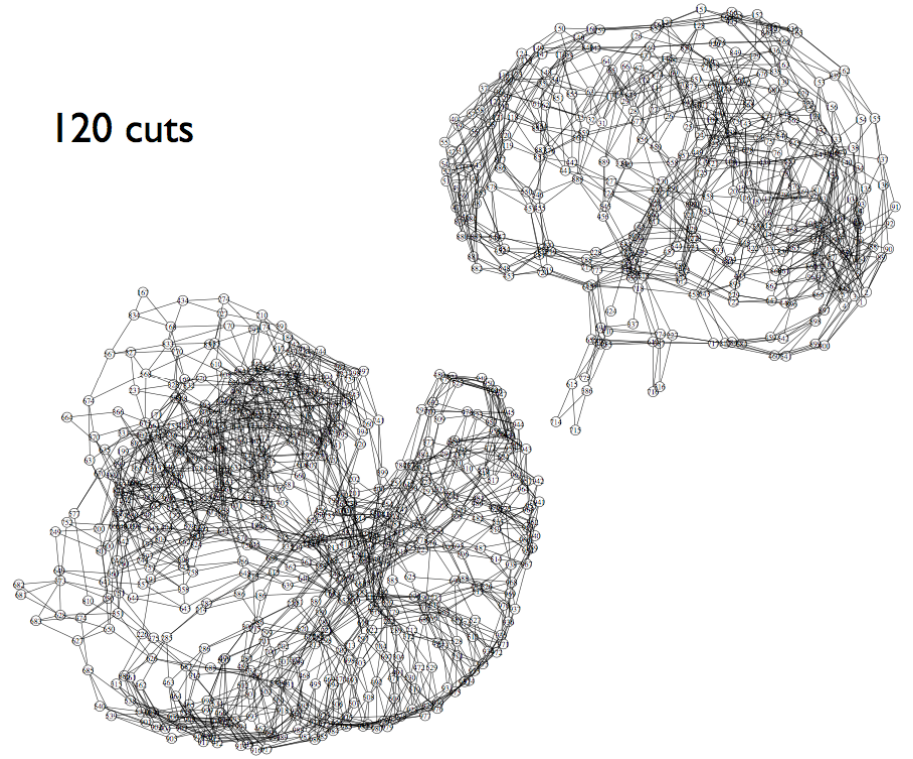
Example

0 cuts

100 cuts



120 cuts



500 cuts

1. Agglomerative Methods

- Start with the empty graph, adding edges that maximize some statistic at each step
- Modularity: most common statistic
- Can be very cheap

Modularity, Q

- Property of graph and a given partition
 - evaluates a partitioning, doesn't find it
- Measure number of within-community edges
 - compared to randomly distributed edges

A. Clauset, M. Newman, C. Moore. Finding community structure in very large networks. Phys. Rev. E 70, 066111 (2004).

Modularity, notation

Adjacency Matrix:

$$A_{vw} = \begin{cases} 1 & \text{if vertices } v \text{ and } w \text{ are connected,} \\ 0 & \text{otherwise} \end{cases}$$

Partition:

vertices divided such that vertex v belongs to community c_v

Total Number of edges: $m = \frac{1}{2} \sum_{vw} A_{vw}$

Degree of vertex v : $k_v = \sum_w A_{vw}$

then, the fraction of edges within communities:

$$\frac{\sum_{vw} A_{vw} \delta(c_v, c_w)}{\sum_{vw} A_{vw}} = \frac{1}{2m} \sum_{vw} A_{vw} \delta(c_v, c_w)$$

This value is large for good divisions (many in-community edges) but is not, on its own, a good measure

It takes its largest value of 1 in the trivial case where all vertices belong to a single community

To correct this: subtract the expected value of the same quantity in the case of a randomized network

The probability of an edge existing between vertices v and w if connections are made at random (respecting vertex degrees) $= \frac{k_v k_w}{2m}$

Then the modularity is defined to be:

$$Q = \frac{1}{2m} \sum_{vw} \left(A_{vw} - \frac{k_v k_w}{2m} \right) \delta(c_v, c_w)$$

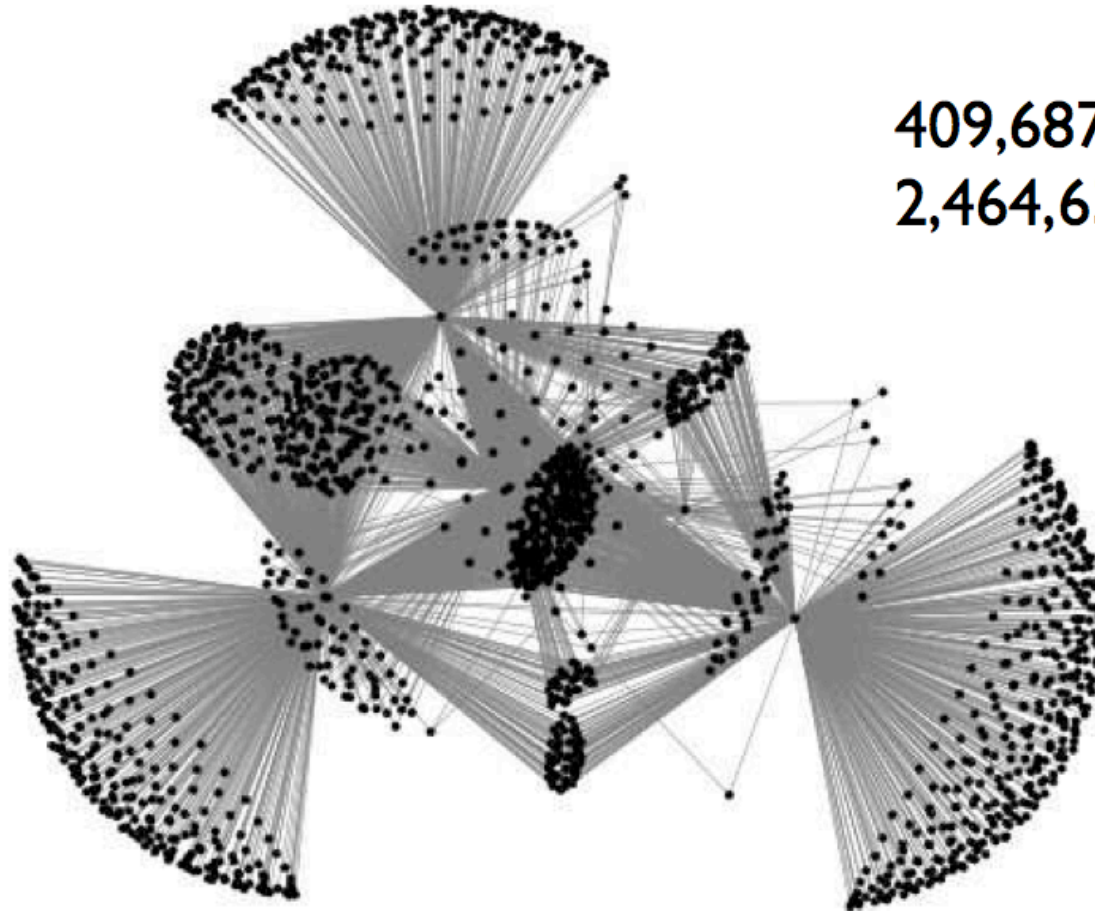
If the fraction of within-community edges is no different from what's expected for a randomized network, then Q will be zero.

Non-zero values represent deviations from randomness. In practice, values above ~ 0.3 show significant community structure

Using Q to get partition

- Start with empty graph
- Add edge (i,j) that leads to maximum ΔQ
- Repeat for next edge
- Can be very efficient: $O(n^2) \rightarrow O(n \cdot \log n)$

Example: Amazon.com



409,687 nodes
2,464,630 edges

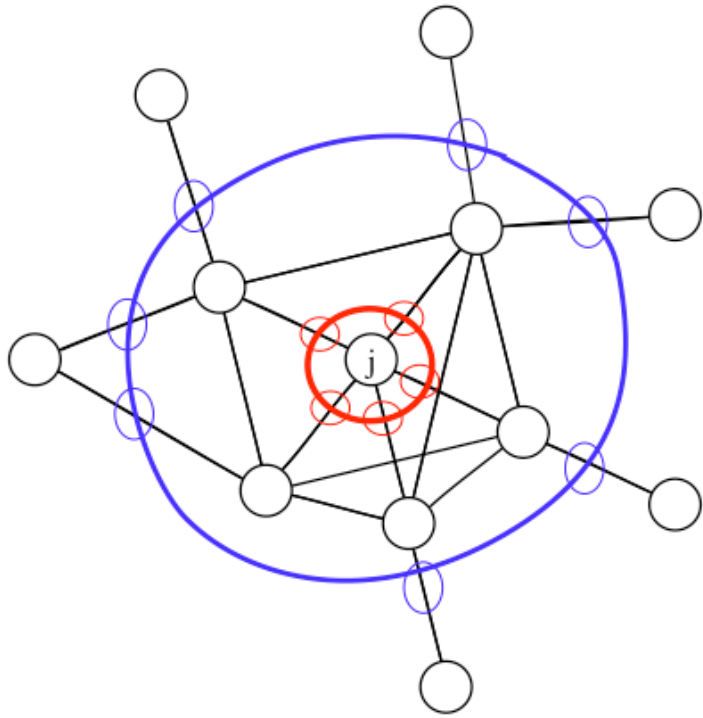
Our local method

- Choose a starting vertex
- Spread outward until some criteria has been met, then stop
- Does not require knowledge of graph beyond spread

J. P. Bagrow and E. M. Bollt. A local method for detecting communities. [arXiv/cond-mat:0412482](https://arxiv.org/abs/cond-mat/0412482), 2004.

Notation

$K_j^l \equiv$ Total Emerging Degree of an l-shell starting from vertex j



- $K_j^0 = 5$
- $K_j^1 = 7$
- $K_j^2 = 0$

$$\Delta K_j^l = \frac{K_j^l}{K_j^{l-1}}$$

$$\Delta K_j^1 = \frac{7}{5}$$

$$\Delta K_j^2 = \frac{0}{7}$$

The Algorithm

- Choose a starting vertex j
- Center an l -shell around j ($l=0$) and spread outward
 - compute the total emerging degree at each depth of the l -shell
- Continue until the current Change in Total Emerging Degree crosses some threshold
- All vertices covered by the last l -shell created are then members of vertex j 's community

Stopping Criteria

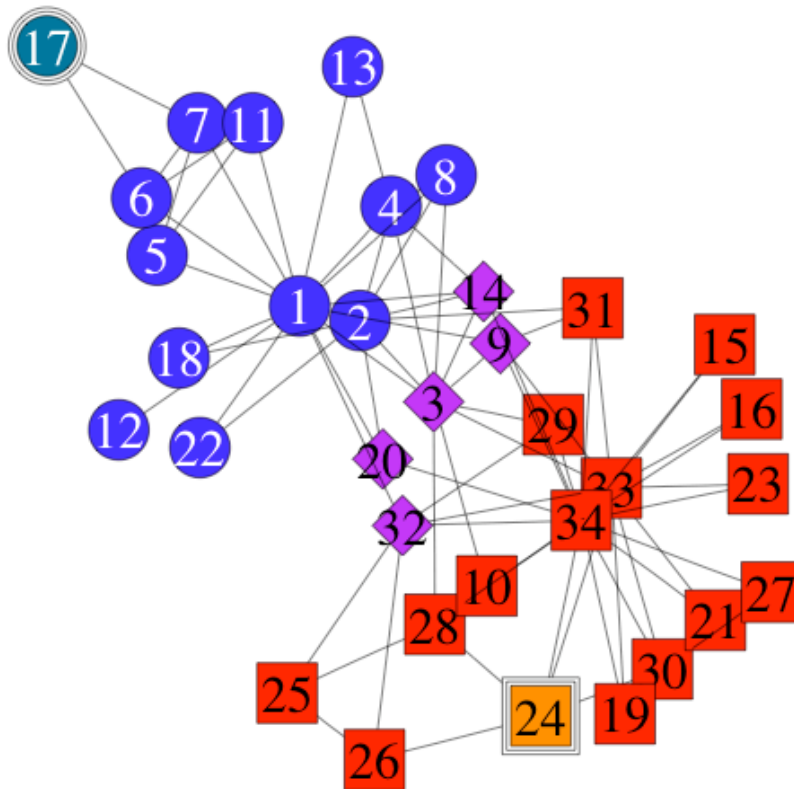
Stop when:

$$\Delta K_j^l < \alpha$$

where α is some arbitrary threshold, > 0

All vertices covered by shells of size l or less are then members of j 's community

Result: Karate Club



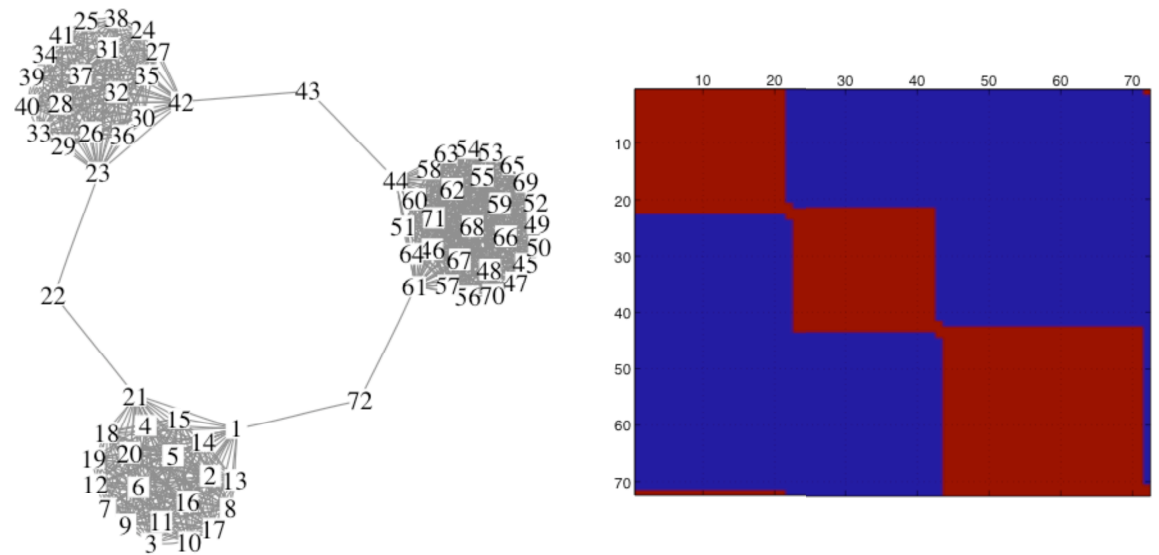
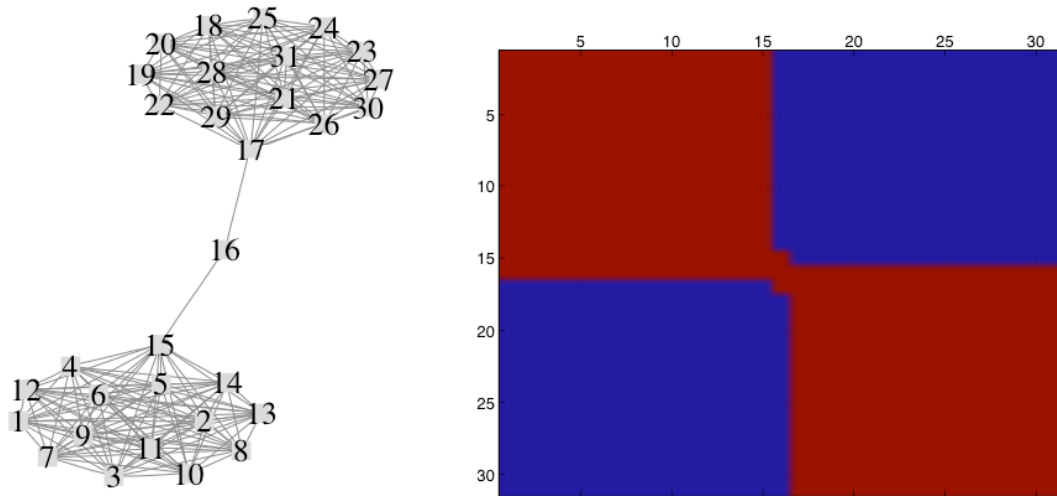
- Two Runs
- Starting from vertices 17 and 24
- $\alpha = 1.9$
- Indicates overlap vertices

Much ado about **THE** right answer. Can the graph **data** tell us?

A Global Application

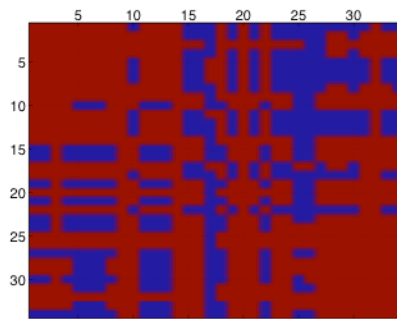
- Can start the algorithm from all n vertices
- Need some way to relate results from disparate runs
- Define Membership Matrix, M
 - $M_{ij} = 1$ if vertex j is a member of i 's community
 - 0 otherwise
 - M is of size $n \times n$ for a network of n vertices

Some example M's



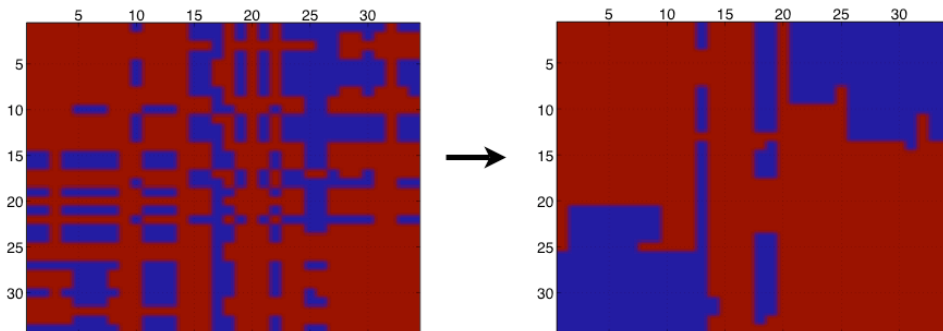
Problem with M

- These last results are trivial
 - the vertices are already numbered consecutively by community
- The Karate Club is not:



$$\alpha = 1.2$$

Sorting Example



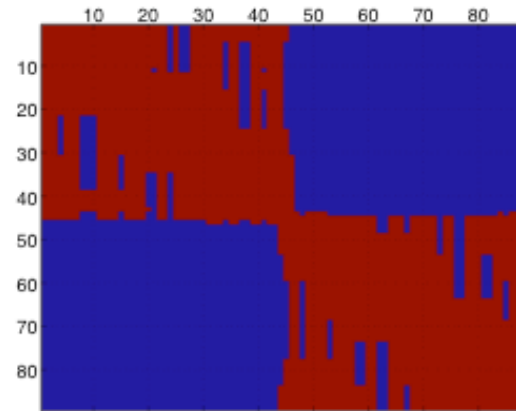
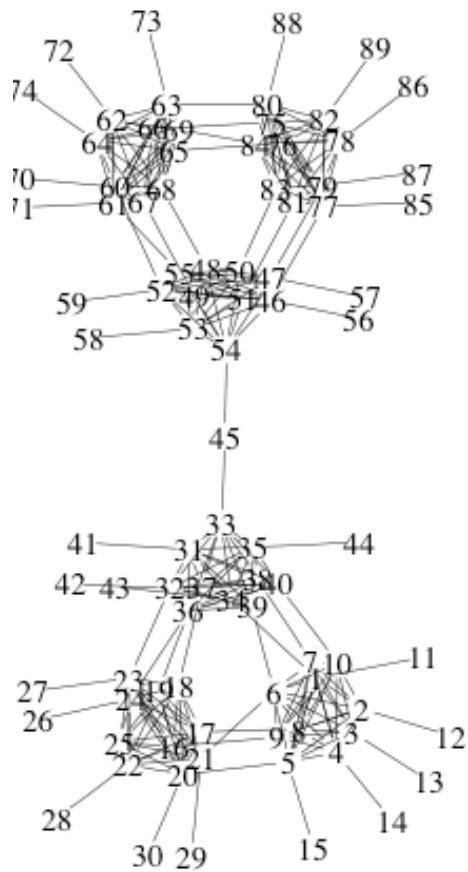
Solution: Sort M

Define the distance between rows:

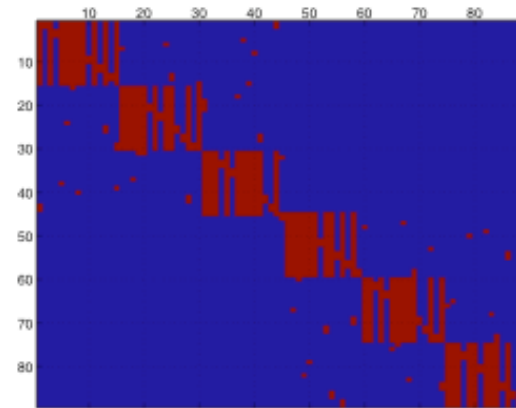
$$Distance(i, j) = n - \sum_{k=1}^n \delta(M_{ik}, M_{jk})$$

- To sort row i
 - Find $Distance(i, j)$ for all $j > i$
 - Choose “closest” row, call it k , and interchange rows (and columns) $i+1$ and k
- Repeat for $i+1$, etc.

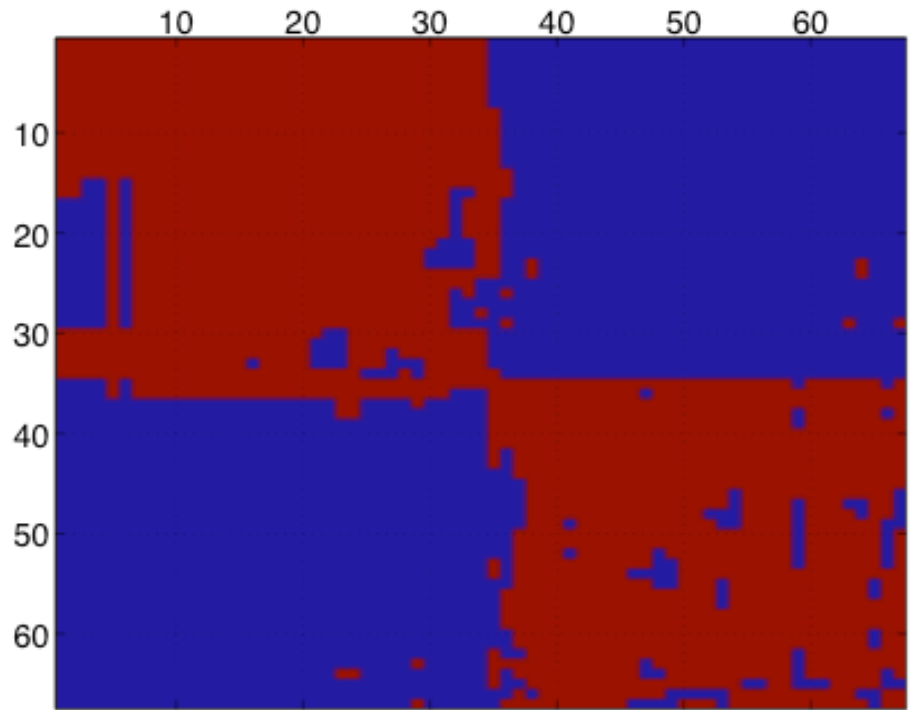
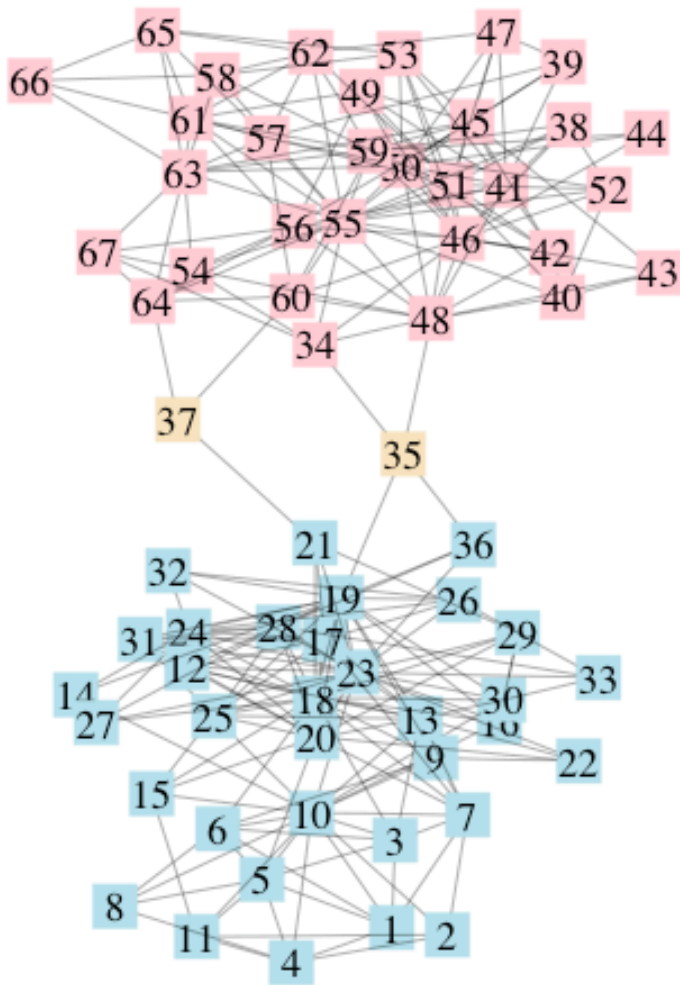
Results



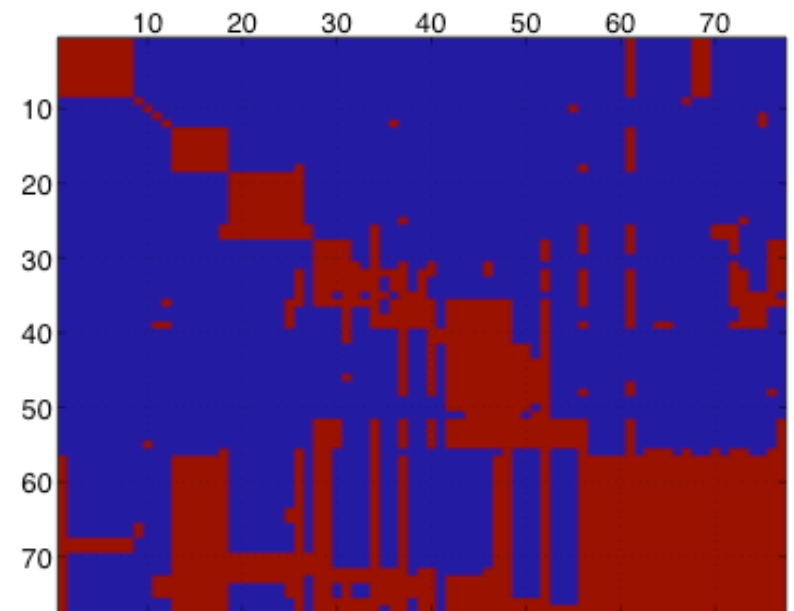
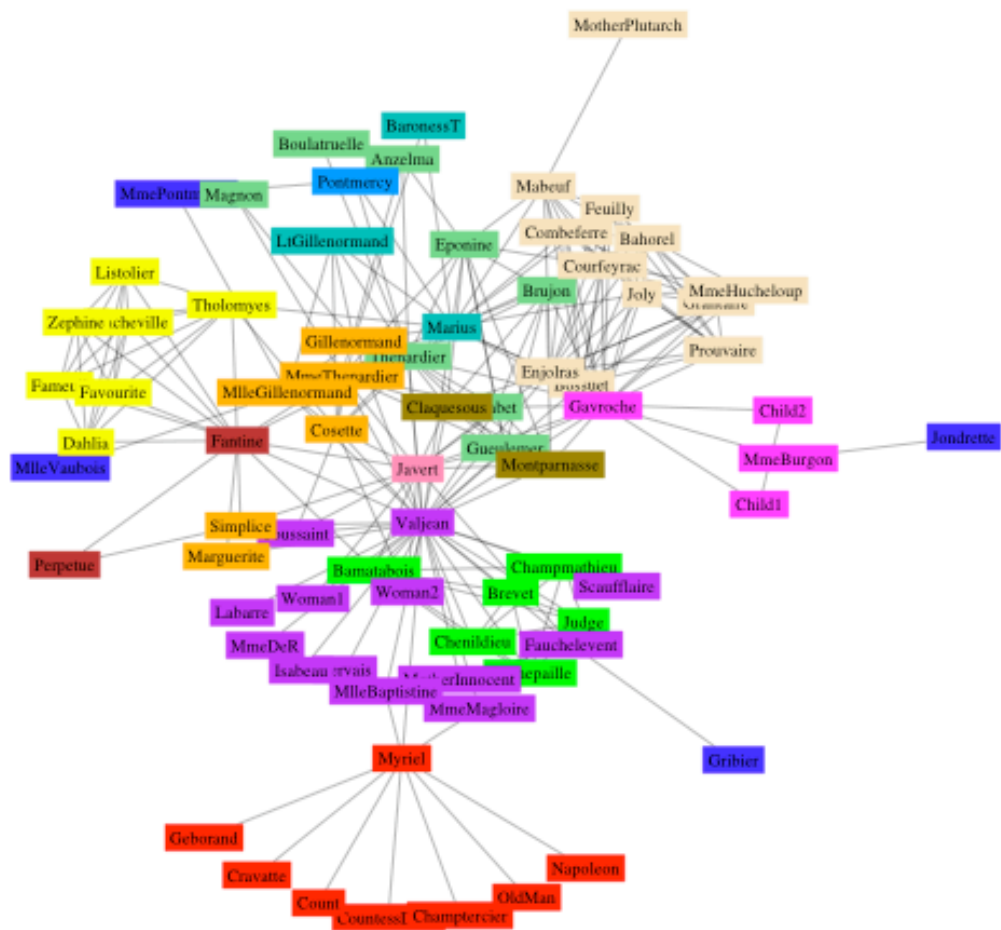
$$\alpha = 0.87$$



$$\alpha = 3$$



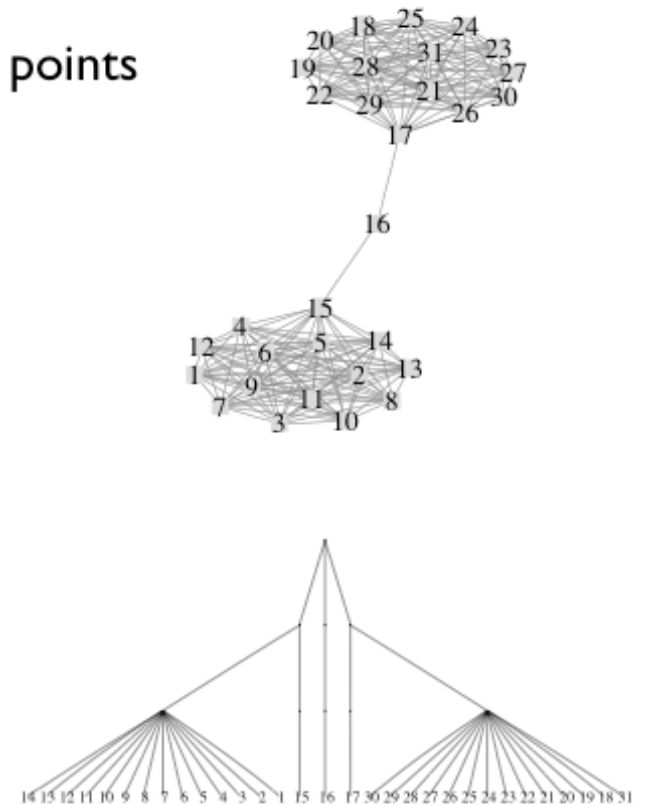
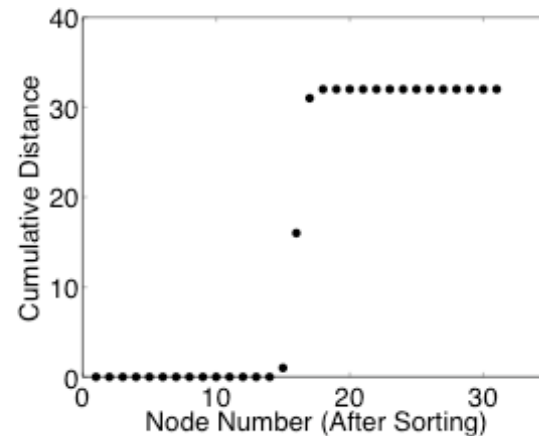
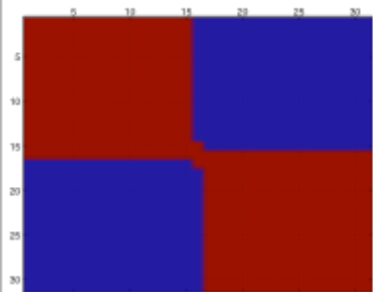
$$\alpha = 1.2$$



$$\alpha = 6.9$$

Towards a Dendrogram Visualization of Results

- Choose shortest difference between adjacent points
- cluster all nodes closer than that distance
- choose next shortest difference



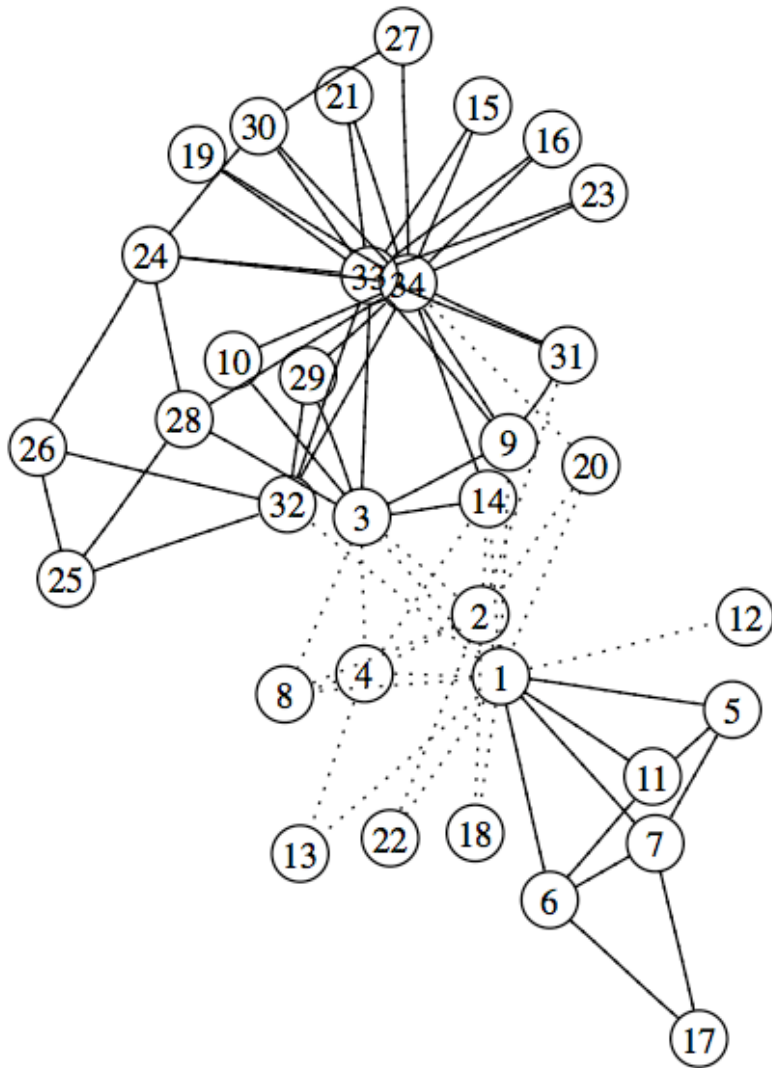
Cycles

- **Cycles are important.**
- **Cycles are the backbone of a network:**
- **Cycles can also be used to find communities.**

Mantras for pics which follow:

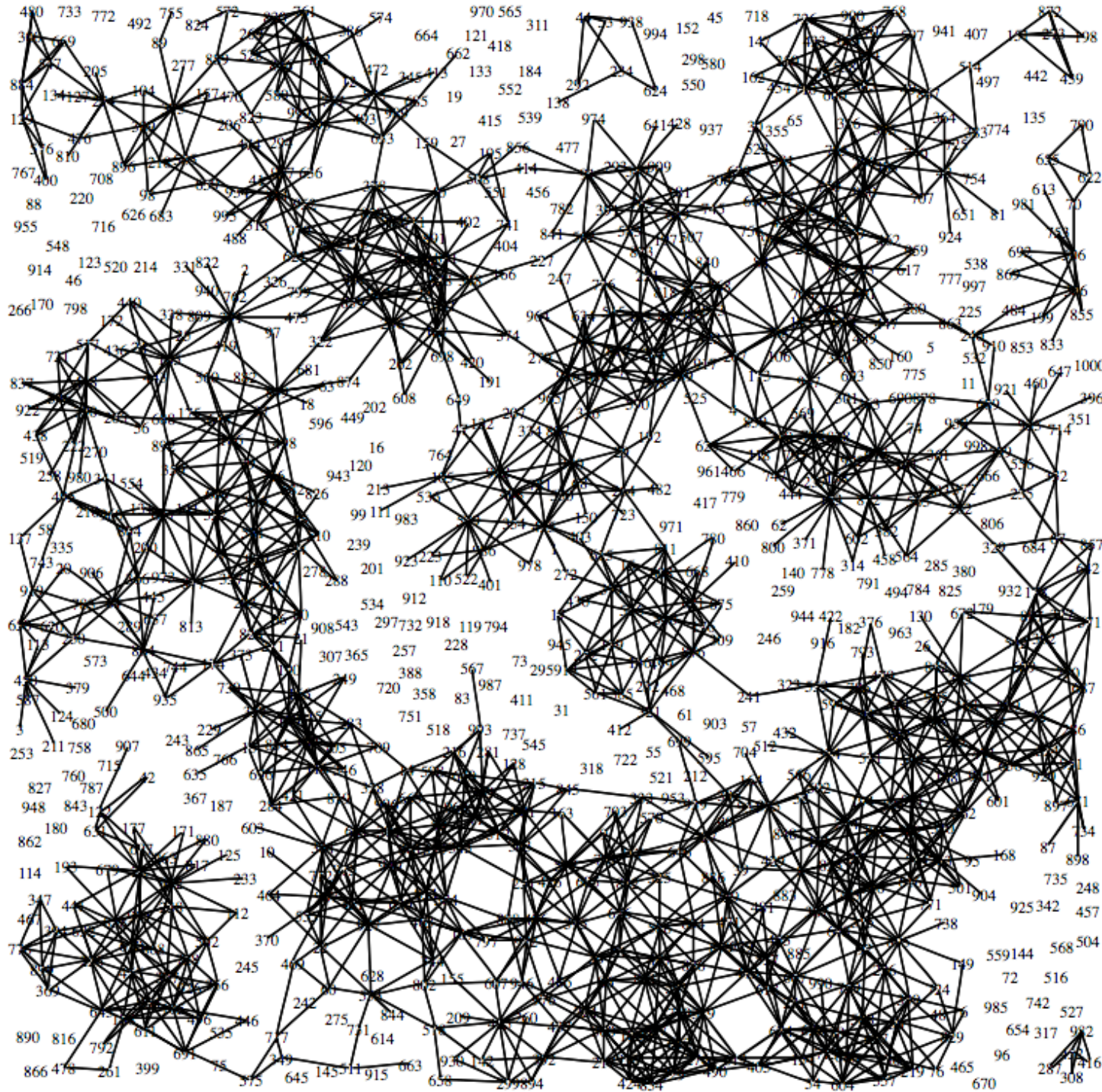
- *Vertices more closely connected to each other are more likely to be connected by short cycles.*
- *Density of cycles of different lengths can be used as an indicator of connectivity between subsets of vertices.*

Partition Zachary's Karate Club by Short Cycles



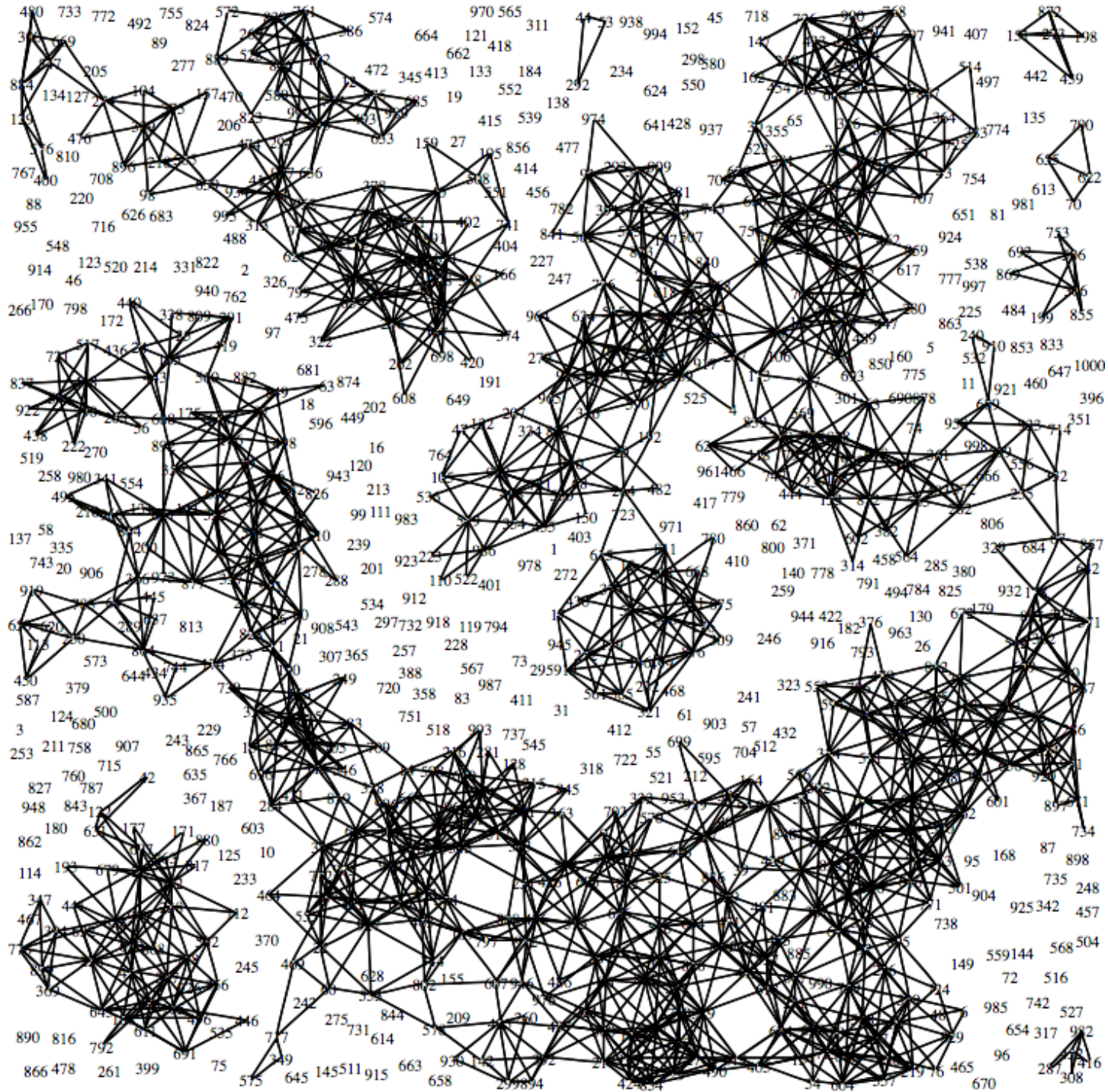
Components
with
3,4,or 5 - cycles

Starting at **17, or 24**



Preview:
On Loop
Communities.

A Particular
Random
Graph



Components
Minus those
w/o
3-cycles.

Statistics of Cycles: How Loopy is your Network?

In order to characterize Networks we need to study their properties.
Finding global characteristics and properties of Networks.

- Degree Distribution: Probability to find a node with degree k .

Delta Distribution: $P(k) = \delta_{k,k'}$ (lattices or Regular Graph).

Power-law Distribution: $P(k) \sim k^{-\lambda}$ (Barabasi – Albert).

- Average Clustering Coefficient.

- Diameter.

- *Complete Distribution of Cycles:*

- Important for propagation along the network.
- Understanding the structure and topology of the network.
- Characterization of networks.

H. D. Rozenfeld, J. E. Kirk, E. M. Bollt, and D. ben-Avraham "Statistics of Cycles: How Loopy is your Network?," cond-mat/0403536, J. Phys. A: Math. Gen. 38 (2005) 4589-4595.

Networks and Cycles

h -cycle: closed path through h connected links that is self-avoiding.

N_h : total number of distinct h -cycles in the network.

h_* : size of typical cycle in the network.

Finding cycles in Networks



Depth-First-Search Algorithm

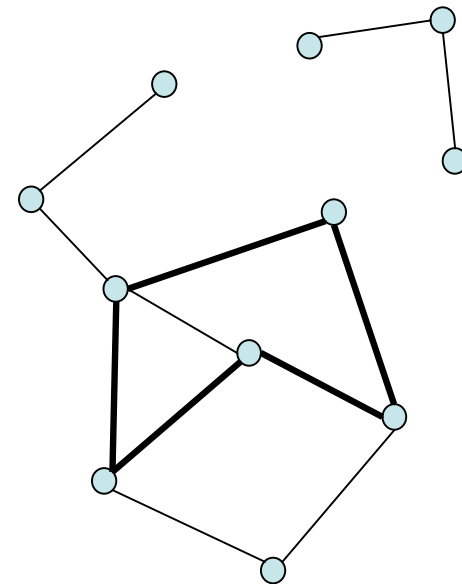


Full distribution of
cycles of all sizes



Extremely expensive:

N_h grows exponentially with the cycle size!



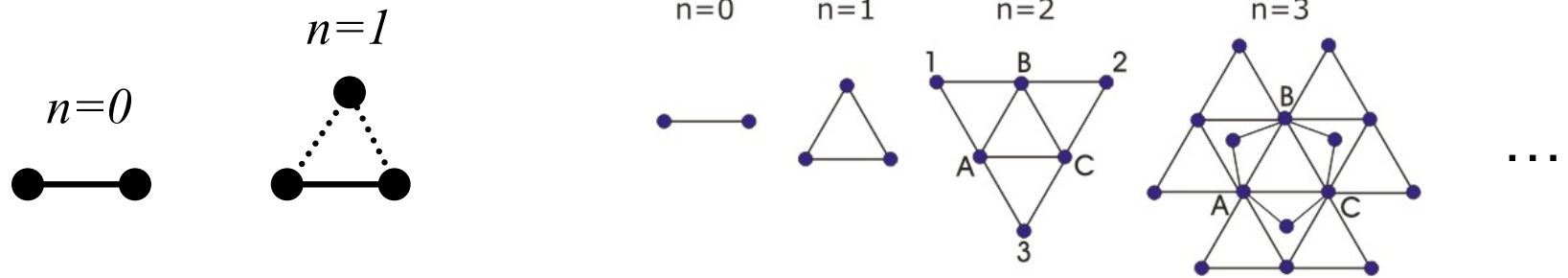
Networks and Cycles

This is the first time the complete distribution of cycles and the typical cycle size h_* are studied. As will be shown this quantity describes the distribution of cycles in the thermodynamic limit.

This topic is a very active field of research.
Some recent work on cycles:

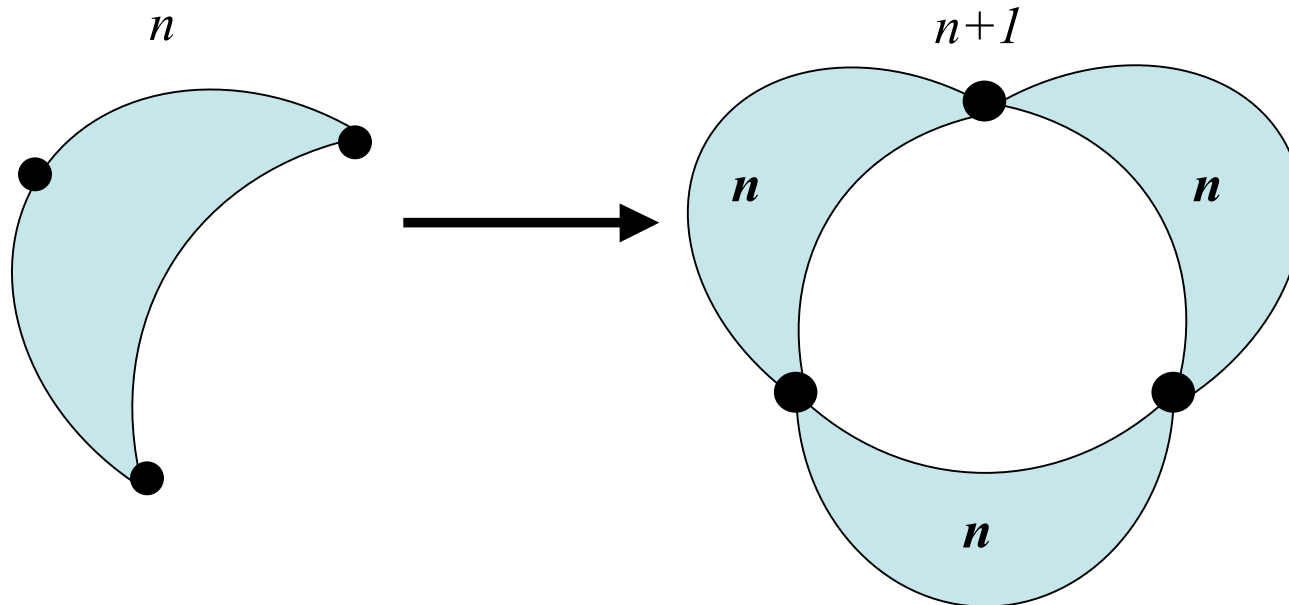
1. G. Bianconi, G. Caldarelli, A. Capocci. arXiv:cond-mat/0408349.
2. S. N. Dorogovtsev, J.F.F Mendes. arXiv:cond-mat/0404593.
3. E. Bollt, D. ben-Avraham. arXiv:cond-mat/0409465.
4. E. Marinari, R. Monasso. arXiv:cond-mat/0407253.
5. D. Sergi. arXiv:cond-mat/0412472.
6. A. Vazquez, J.G. Oliveira, A-L Barabasi. arXiv:cond-mat/0501399.
7. E. Ben-Naim, P.L. krapivsky. arXiv:cond-mat/0408620.
8. G. Bianconi, M. Marsili. arXiv:cond-mat/0502552.
9. S. N. Dorogovtsev, J.F.F. Mendes, J.G. Oliveira. arXiv:cond-mat/0411526.
10. H-J. Kim, J.M. Kim, S. N. Dorogovtsev, Mendes, J.F.F. arXiv:physics/0503168.
11. P.G. Lind, M.C. Gonzalez, H.J. Herrmann. arXiv:cond-mat/0504241.
- .
- .
- .

Cycles on a Deterministic Scale-Free Network



S.N. Dorogovtsev, A.V. Goltsev, and J.F.F. Mendes,
 Phys. Rev. E 65, 066122 (2002).

$$P(k) \sim k^{-\lambda}, \quad \lambda = 1 + \frac{\ln 2}{\ln 3}$$



And through orbits of the Kronecker Algebra

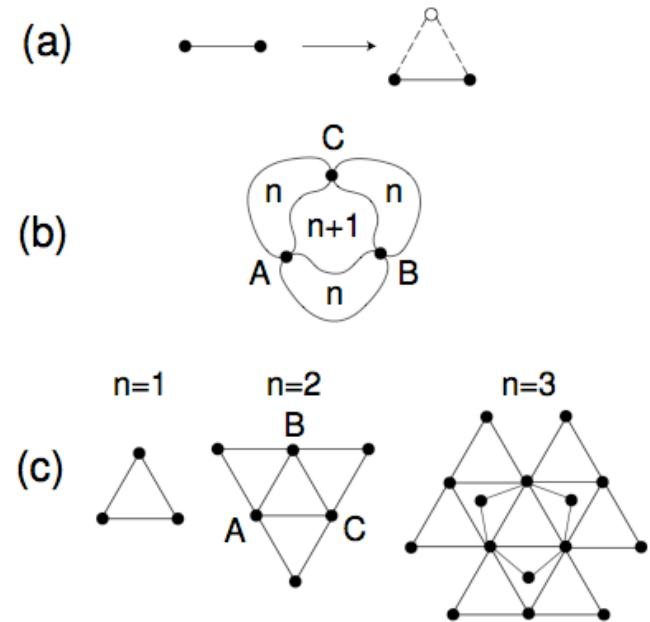
$$A_1 = \begin{pmatrix} 0 & 1 & 1 \\ 1 & 0 & 1 \\ 1 & 1 & 0 \end{pmatrix},$$

$$A_{n+1} = R_{n+1} \cdot [M \otimes (P_n \cdot A_n \cdot P_n^t)] \cdot R_{n+1}^t.$$

Copy instructions: $M = I_3$,

Assembly instructions

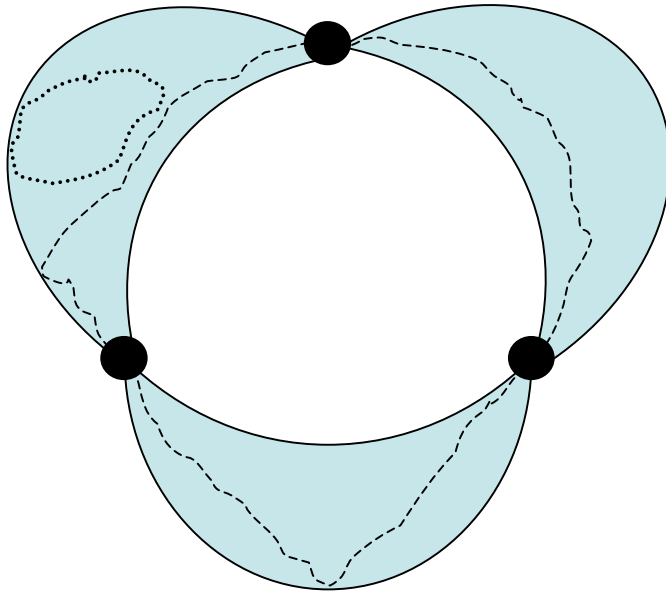
$$R_n = \begin{pmatrix} I_n(1, :) + I_n(n, :) \\ I_n(2 : (n/3 - 1), :) \\ I_n(n/3, :) + I_n((n/3 + 1), :) \\ I_n((n/3 + 2) : (2n/3 - 1), :) \\ I_n(2n/3, :) + I_n((2n/3 + 1), :) \\ I_n((2n/3 + 2) : (n - 1), :) \end{pmatrix}.$$



E.M. Bollt, D. ben-Avraham, “What is Special about Diffusion on Scale-Free Nets?”
New J. Phys. 7 (2005) 26.

Cycles on a Deterministic Scale-Free Network

Generation $n+1$



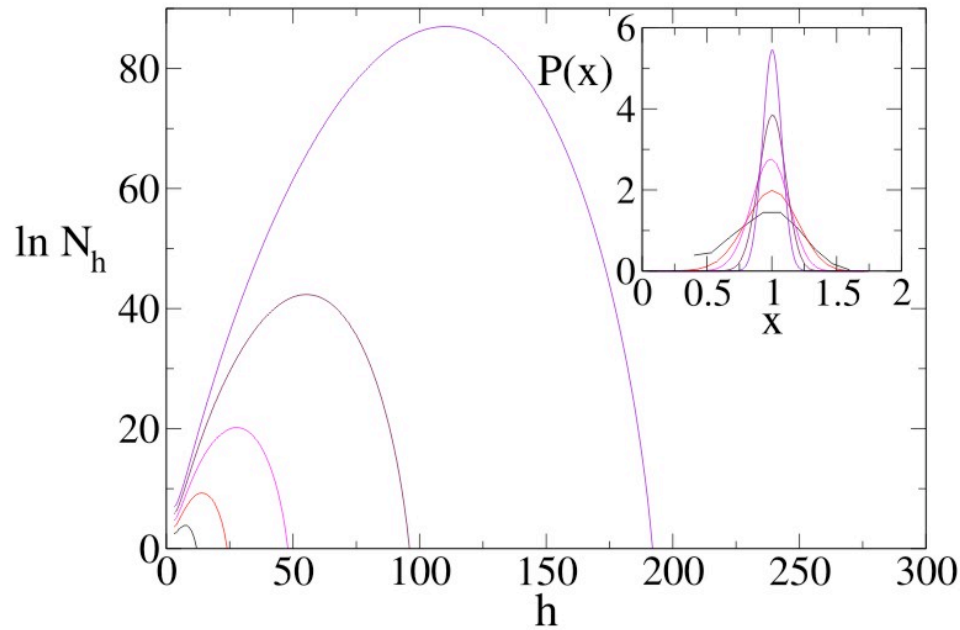
• $N_h(n)$: number of cycles of size h in generation n .

• $L_h(n)$: number of paths of size h between two hubs in generation n .

$$N_h(n+1) = 3N_h(n) + \sum_{\substack{h_1, h_2, h_3 \\ h_1 + h_2 + h_3 = h}} L_{h_1}(n) L_{h_2}(n) L_{h_3}(n)$$

$$L_h(n+1) = L_h(n) + \sum_{\substack{h_1, h_2 \\ h_1 + h_2 = h}} L_{h_1}(n) L_{h_2}(n)$$

Cycles on a Deterministic Scale-Free Network



- $f(x)$ is well approximated by a parabola about $x=1$ or $h=h_*$.

- The distribution of cycles is nearly a Gaussian of width $1/\sqrt{h_*}$

- In the thermodynamic limit $h_* \rightarrow \infty$ or $N \rightarrow \infty$ it converges to a delta function.

$$\ln N_h = h_* f\left(\frac{h}{h_*}\right), \quad h_* \sim 2^n$$



$$N(n) = \frac{3^n + 3}{2}$$



$$h_* \sim N^\alpha, \quad \alpha = \frac{\ln 2}{\ln 3}$$

A typical cycle length!

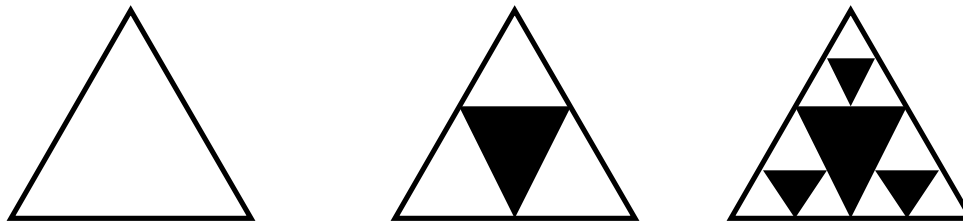
Why the phrase “ergodic” in the title?

Just suggestive. But in the presence of a typical cycle length, think of a typical averaged quantity across the network, which “mostly” tours the network. Such cycles do not have a sense of location. You should be able to pick up a cycle just about anywhere, and get the same idea of the network as a whole.

Think of averages of some statistic on the network, like clustering coefficient for example. Just a few large, “typical” Cycles will tend to carry the same statistics, and fast converging, as the network as a whole.

Cycles on a Lattice, Fractal, Complete Graph.

- It was found by Jensen and Guttman that the typical cycle length in a lattice (regular graph) with $\sqrt{N} \times \sqrt{N}$ sites follows $h_* \sim N$ or $\alpha=1$.
- For the Sierpinsky Gasket, a fractal lattice, all nodes have the same degree $k=4$ (except for three nodes). Again $h_* \sim N$ or $\alpha=1$.



- For the Complete Graph K_N the distribution of cycles can N_h be obtained analytically

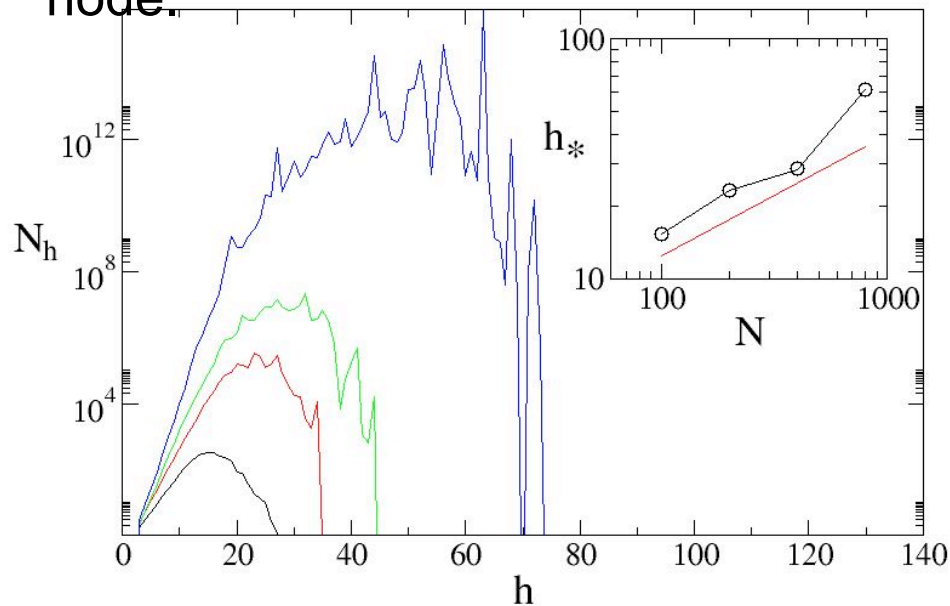
$$N_h = \frac{N!}{2h(N-h)!}$$

so $h_* \sim N$ or $\alpha=1$.

Cycles on Random Scale-Free Networks

Exact counting is not possible in random Networks.

Sampling Algorithm: self-avoiding walk. The walk is terminated when it comes back to the initial node.

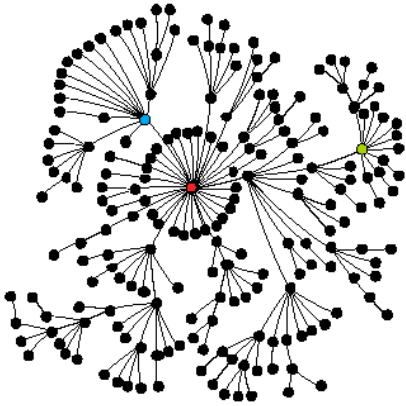


$$P(k) \sim k^{-\lambda}$$

$$N = 100, 200, 400, 800.$$

$$\lambda = 3.$$

$$h_* \sim N^\alpha, \quad \alpha = \frac{1}{2}$$



Cycles on Random Scale-Free Networks

We applied the sampling algorithm to Scale-Free Networks with degree exponent $\lambda=3$.

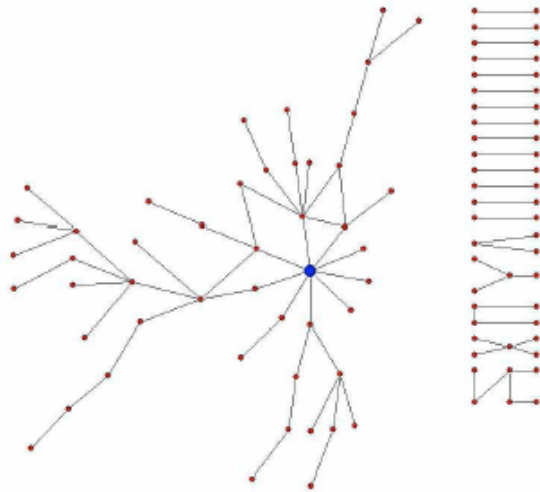
For Small Scale Free Networks $h_* \sim N^\alpha$, $\alpha = \frac{1}{\lambda-1}$.
 For large Networks h_* increases.

Why?

For $N \approx 100$ most cycles are formed between the hub and nodes in the first shell. The likely cycle length is then proportional to the degree of the hub.

$$h_* \sim K \sim N^{\frac{1}{\lambda-1}} \Rightarrow \alpha = \frac{1}{\lambda-1}$$

As N grows larger, nodes in higher shells form part of interconnected cycles and α increases.



Conclusions and open questions

- Cycles of small length have been studied before.
- Our study indicates that the full distribution of cycles, of all possible lengths, displays additional useful properties:
 - For large nets, the distribution resembles a delta function that peaks about a typical cycle size, $h \sim N^\alpha$.
 - The exponent α serves as a single figure of merit that characterizes the “loopiness” of the net in question.
 - For regular lattices and fractals, and for complete graphs and ER above criticality $\alpha=1$.
 - For small random scale-free nets $\alpha = 1/(\lambda-1)$, but increases as the nets become larger.
 - It remains an open question whether the loopy exponent saturates at $\alpha = 1$ as $N \rightarrow \infty$.
 - Ergodicity: the distribution of cycles that pass through a node is similar for most nodes of the net.

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Networks that change dynamically in time

Proof of Communication and Synchronization

in

Instantaneously **Disconnected**

But Fast

Moving-Neighborhood Networks

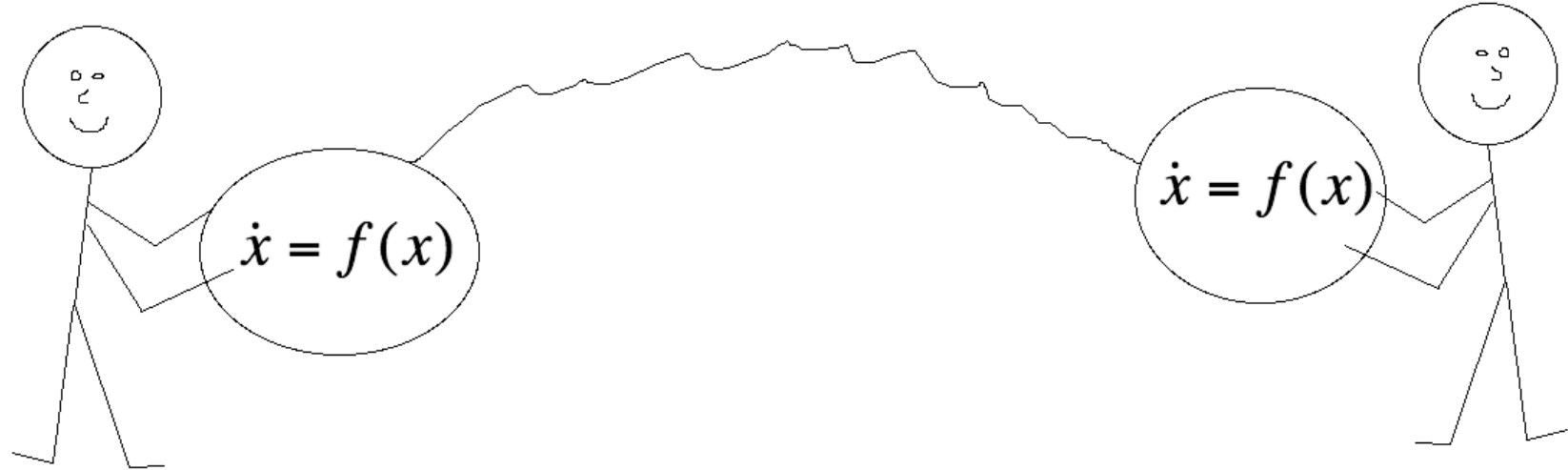
Erik Bollt, Clarkson University

Joe Skufca, USNA, U. MD, Clarkson U.

Dan Stilwell, Virginia Tech.

D. Gray Roberson, Virginia Tech.

Identical oscillators properly communicating can synchronize



Some Background: Identical Coupled Oscillators

Barahona-Pecora-'02,
master stability function

Suppose a “network” of n -identical oscillators which couple together according to a graph \mathbf{A} .

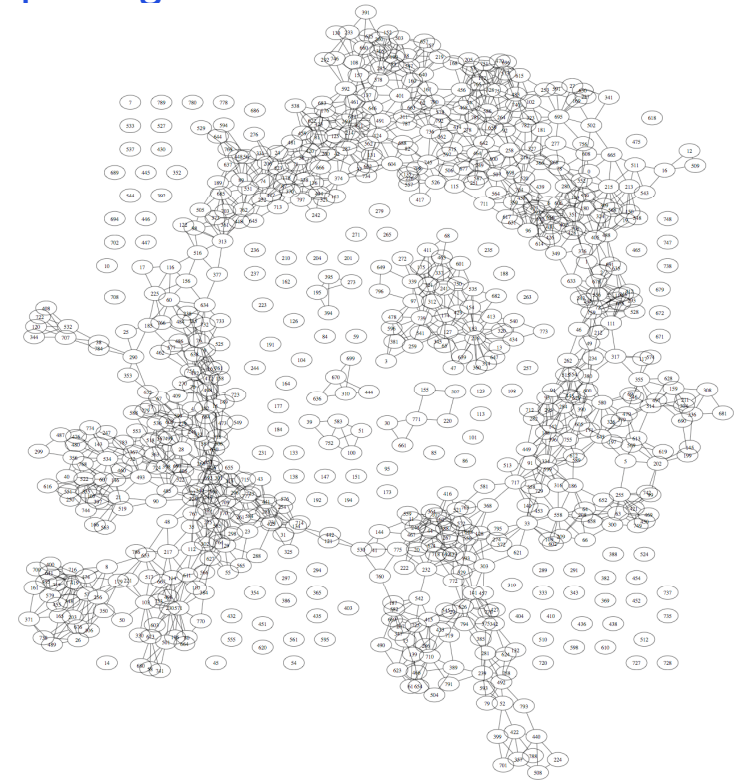
$$\dot{x}_i(t) = f(x_i(t)) + \sigma B \sum_{j=1}^n l_{i,j} x_j(t), i = 1, \dots, n$$

$x_i(t) \in \mathbb{R}^n$ is the state of oscillator i , $B \in \mathbb{R}^{n \times n}$,

\mathbf{A} is $n \times n$ Adjacency matrix.

Graph $A_{i,j} = 1$ corresponding to an edge (i,j) , else 0.

$L = \text{diag}(d) - A$ the graph-Laplacian



Considering growth of variations away from a solution on an identical synchronization manifold,

$z_i(t) = x_i(t) - x^o(t)$, **Variations from identical sync manifold**

$$\dot{z}(t) = (I_r \otimes F(t) + \sigma(I_n \otimes B)(L \otimes I_r)) z(t) = (I_r \otimes F(t) + \sigma L \otimes B) z(t)$$

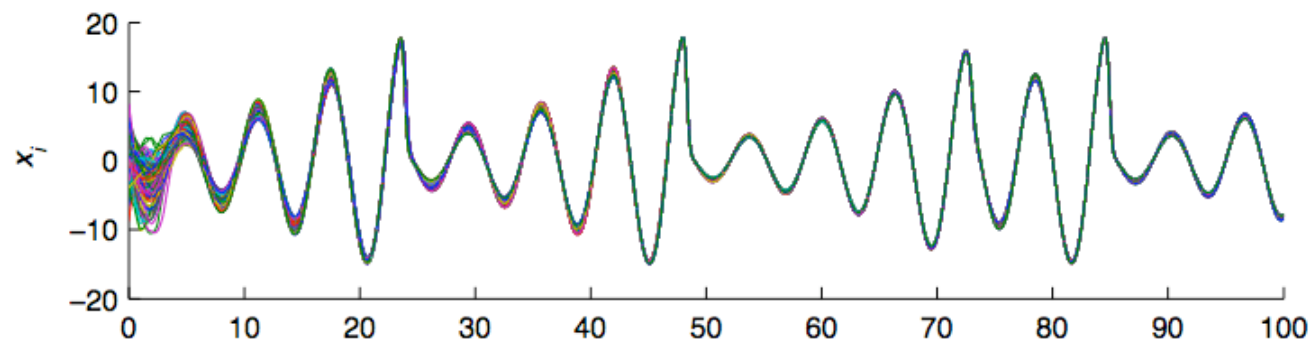
Synchronization of Static Networks of Identical Oscillators

stability of the subsystems, $\dot{\xi}_i(t) = (F(t) + \sigma \lambda_i B)\xi_i(t)$, $i = 1, \dots, r$
 $\lambda_1, \dots, \lambda_r$ are the eigenvalues of L . the row sums of L are zero, the spectrum
of L contains at least one zero eigenvalue, which we assign $\lambda_1 = 0$.

$\dot{\xi}_1(t) = F(t)\xi_1(t)$ evolves on the along the synchronization manifold,

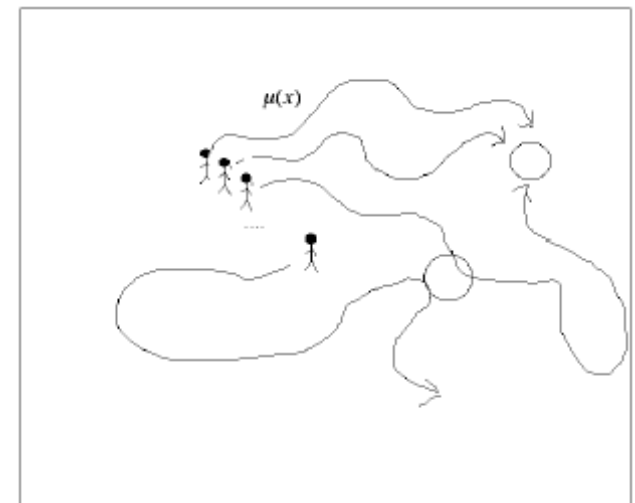
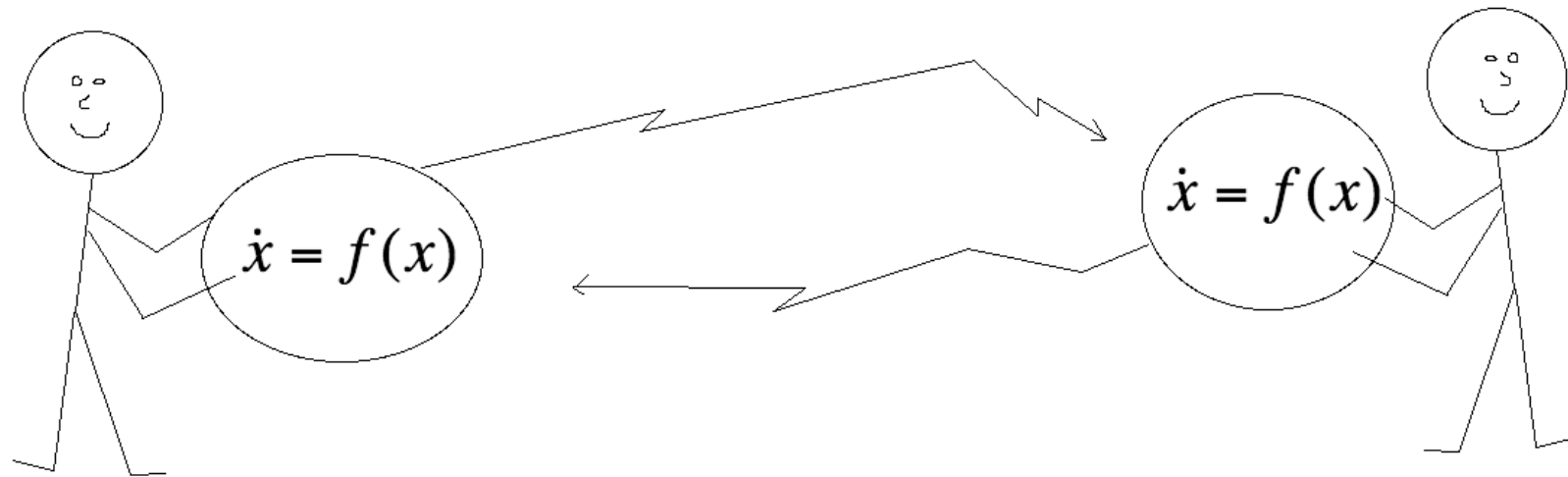
$i = 2, \dots, r$ evolves transverse

Since the oscillators are assumed identical, the (identity) synchronization manifold is invariant
for all couplings, the question being its stability.

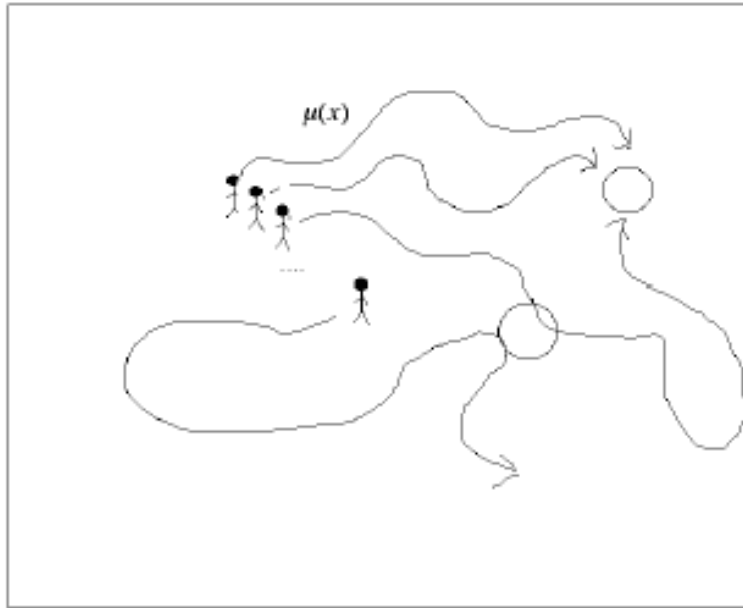


**What about
Time-Varying
Networks?**

Can the Identical oscillators synchronize if they only communicate **only sometimes**?

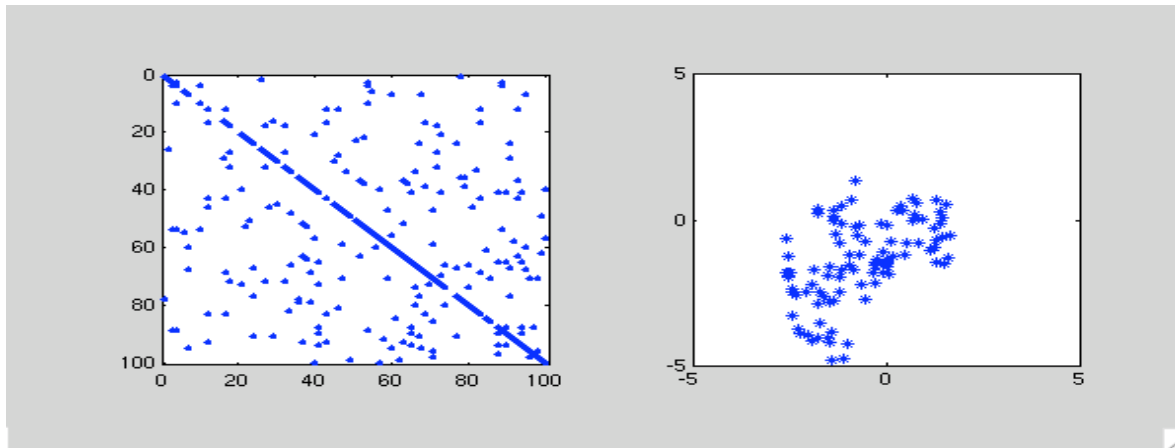


Communication and Synchronization in Disconnected Networks with Dynamic Topology: *Moving Neighborhood Networks*



Q: Can information propagate (in time) across an Ad-hoc network?

Applications: Diseases, Control, Cooperative behavior of swarms, Synchronization, Communication



Instantaneous Adjacency Matrices

Ergodic Evolution of n moving agents

Getting ready to State Main theorem: Rigorous near the end.

First, the *Moving Neighborhood Network* Skufca, Bollt, '04

Suppose a “network” of n -identical oscillators which couple together *occasionally* according to **an ergodic process**.

$$\dot{x}_i(t) = f(x_i(t)) + \sigma B \sum_{j=1}^n l_{ij}(t)x_j(t), \quad i = 1, \dots, n$$

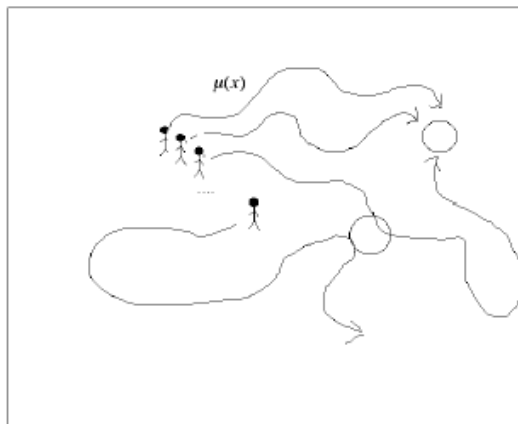
$x_i(t) \in \mathbb{R}^n$ is the state of oscillator i , $B \in \mathbb{R}^{n \times n}$,

$A(t)$ is $n \times n$ Time varying adjacency matrix.

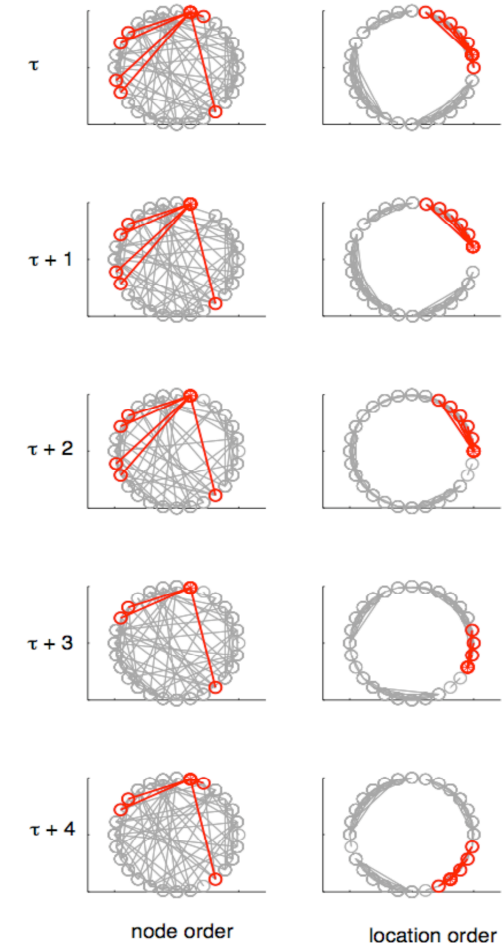
Graph corresponding to an edge (i,j) at time t when

$$|x_i(t) - x_j(t)| < \varepsilon$$

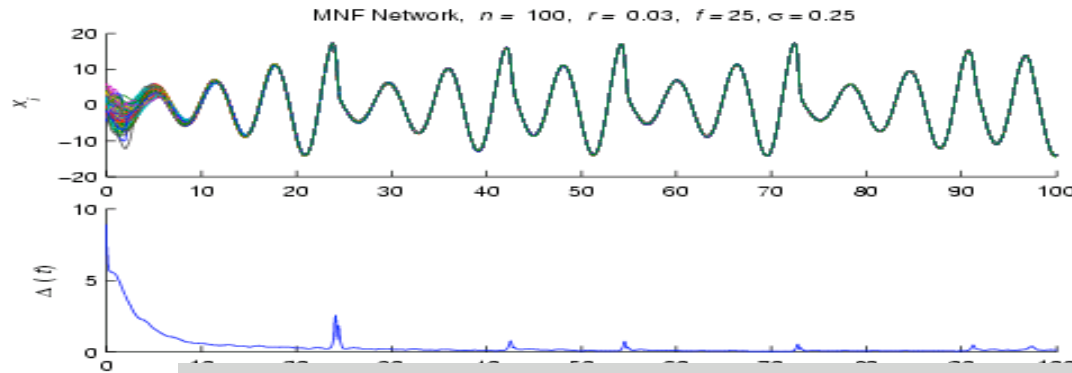
$L(t) = \text{diag}(d(t)) - A(t)$ the **time varying graph-Laplacian**



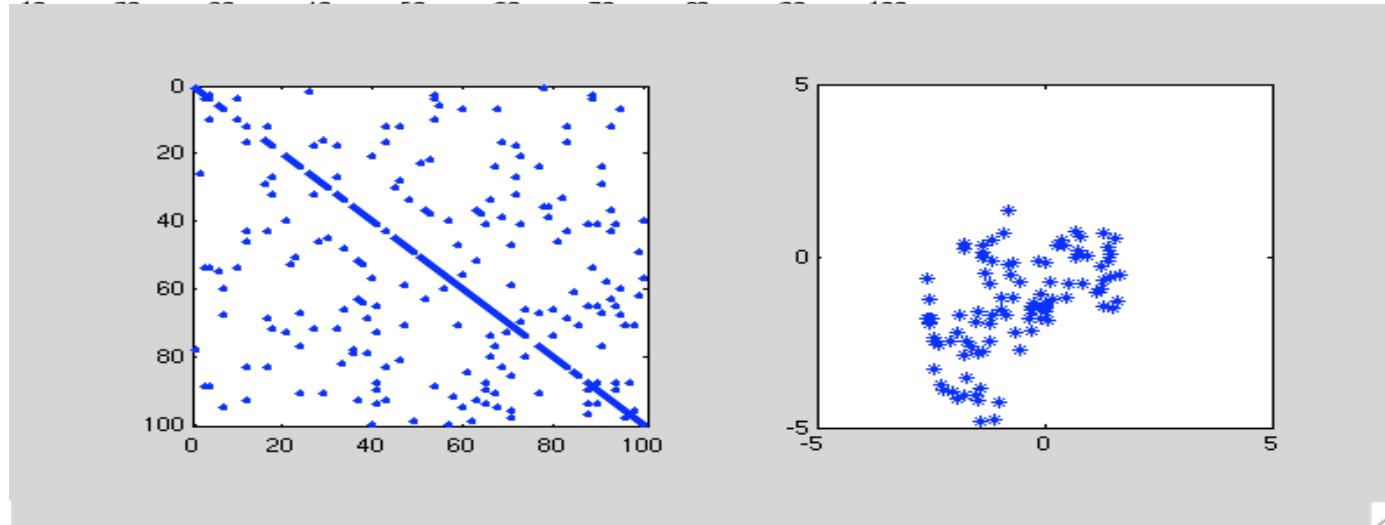
Reminds us of Barahona-Pecora-'02, master stability function



Synchrony Probes Moving-Average Network



BUT!!! Network is
(a.) Never Instantaneously
Connected!



Instantaneous Adjacency Matrices

Ergodic Evolution of n moving agents

Propagation of a message, biological disease, telecommunication, or any property, across a *dynamic network*, in which message relevance decays.

Two time-scales relevant for such networks:

- 1) Time-scale of the message
- 2) Time-scale of the validity of connection

Modify Master Stability Function

For dynamic networks

*Barahona-Pecora-'02,
master stability function*

Moving Average Laplacian, for time varying networks - Weighting Memory

Skufca, Bollt, '04

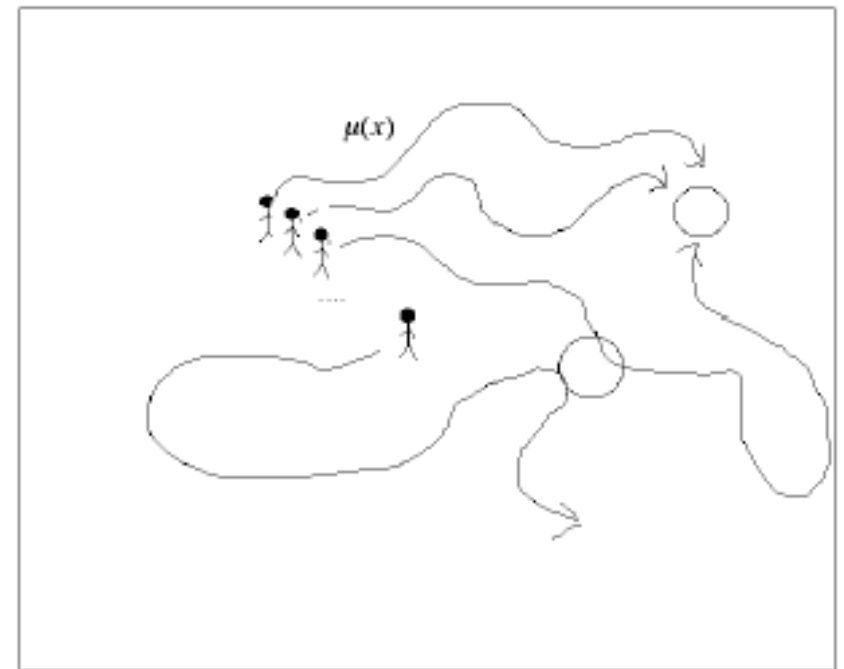
Instead of instantaneous adjacency matrix, $A(t)$, use a moving averaged adjacency matrix,

$$\Lambda(t) = e^{\int_0^t qA(\tau)d\tau} z_0$$

which solves, $\dot{z} = qA(\tau)z, z(0) = z_0$ and its Laplacian spectrum

A Time Varying Network

n-agents wandering **ergodically**.



Message propagation can persist in a network which is *instantaneously never connected*

We find:

- Time-average ER, or scale-free degree distribution if latency.
- Message propagation in network which instantaneously never connected.
- Tools for such dynamic network topology: latency measuring “average moving (graph) Laplacian,” generalization master-stability formalism, time-average degree distribution, ergodicity for time/space averages.

A Related Model of A Time Varying Network

Theorem *Suppose a set of coupled oscillators with linearized dynamics*

$$\dot{z}_s(t) = (I_r \otimes F(t) + \sigma \bar{L} \otimes B) z_s(t)$$

achieves synchronization. Then there exists a positive scalar ε^ such that the set of oscillators with linearized dynamics*

$$\dot{z}_a(t) = (I_r \otimes F(t) + \sigma L(t/\varepsilon) \otimes B) z_a(t)$$

and time-varying network connections $L(t)$ achieves synchronization for all fixed $0 < \varepsilon < \varepsilon^$ if $L(t)$ satisfies*

$$\frac{1}{T} \int_t^{t+T} L(\sigma) d\sigma = \bar{L}$$

and the column sums of $L(t)$ are all zero for all t .

If you “blink” connections fast enough, you can hope *on average* to transmit enough message to maintain synch.

Note: \bar{L} is generally not a graph Laplacian corresponding to any particular network.

Proof is based on showing:

Lemma *Suppose the matrix-valued function $E(t)$ is such that*

$$\frac{1}{T} \int_t^{t+T} E(\sigma) d\sigma = \bar{E}$$

for all t and

$$\dot{x}(t) = (A(t) + \bar{E})x(t), \quad x(t_0) = x_0, \quad t \geq t_0$$

is uniformly exponentially stable. Then there exists $\varepsilon^ > 0$ such that for all fixed $\varepsilon \in (0, \varepsilon^*)$,*

$$\dot{z}(t) = (A(t) + E(t/\varepsilon))z(t), \quad z(t_0) = z_0, \quad t \geq t_0$$

is uniformly exponentially stable.

By showing a shared Lyapunov function works sufficiently if switching is fast-enough.

Sufficient but not necessary: An example.

$$\dot{x}_i(t) = -y_i(t) - z_i(t) - \sigma \sum_{j=1}^r l_{ij}(t/\varepsilon)x_j(t)$$

$$\dot{y}_i(t) = x_i(t) + ay_i(t)$$

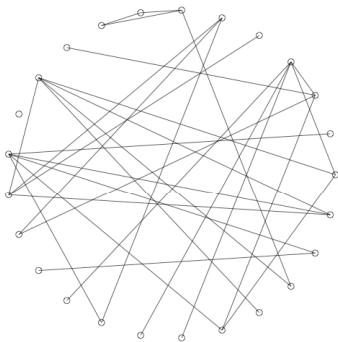
$$\dot{z}_i(t) = b + z_i(t)(x_i(t) - c)$$

$i = 1, \dots, r$, $a = 0.165$, $b = 0.2$, $c = 10$, and $\sigma = 0.3$.

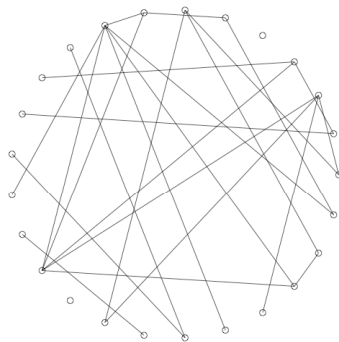
$$L(t) = \sum_{i=1}^5 L_i \chi_{[(i-1)T/5, iT/5)}(t)$$

Time-averaged **OF** Laplacian

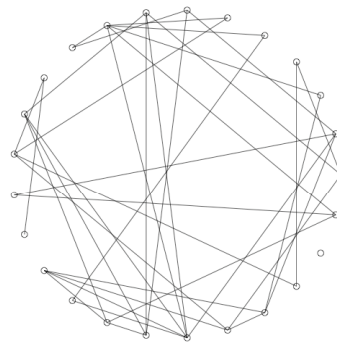
$$\begin{aligned} \bar{L} &= \frac{1}{\varepsilon T} \int_0^{\varepsilon T} L(t/\varepsilon) dt \\ &= \frac{1}{5} \sum_{i=1}^5 L_i \end{aligned}$$



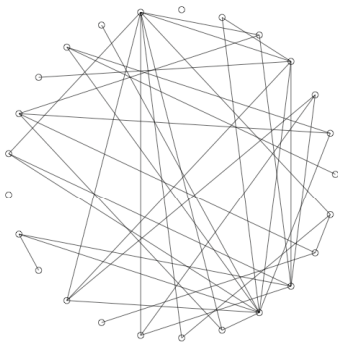
(a)



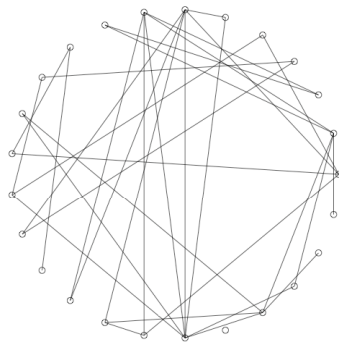
(b)



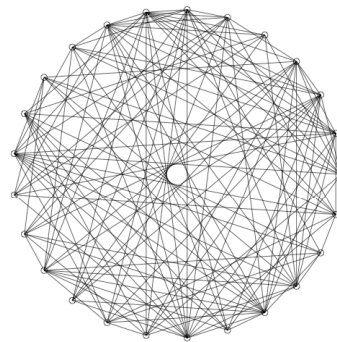
(c)



(d)

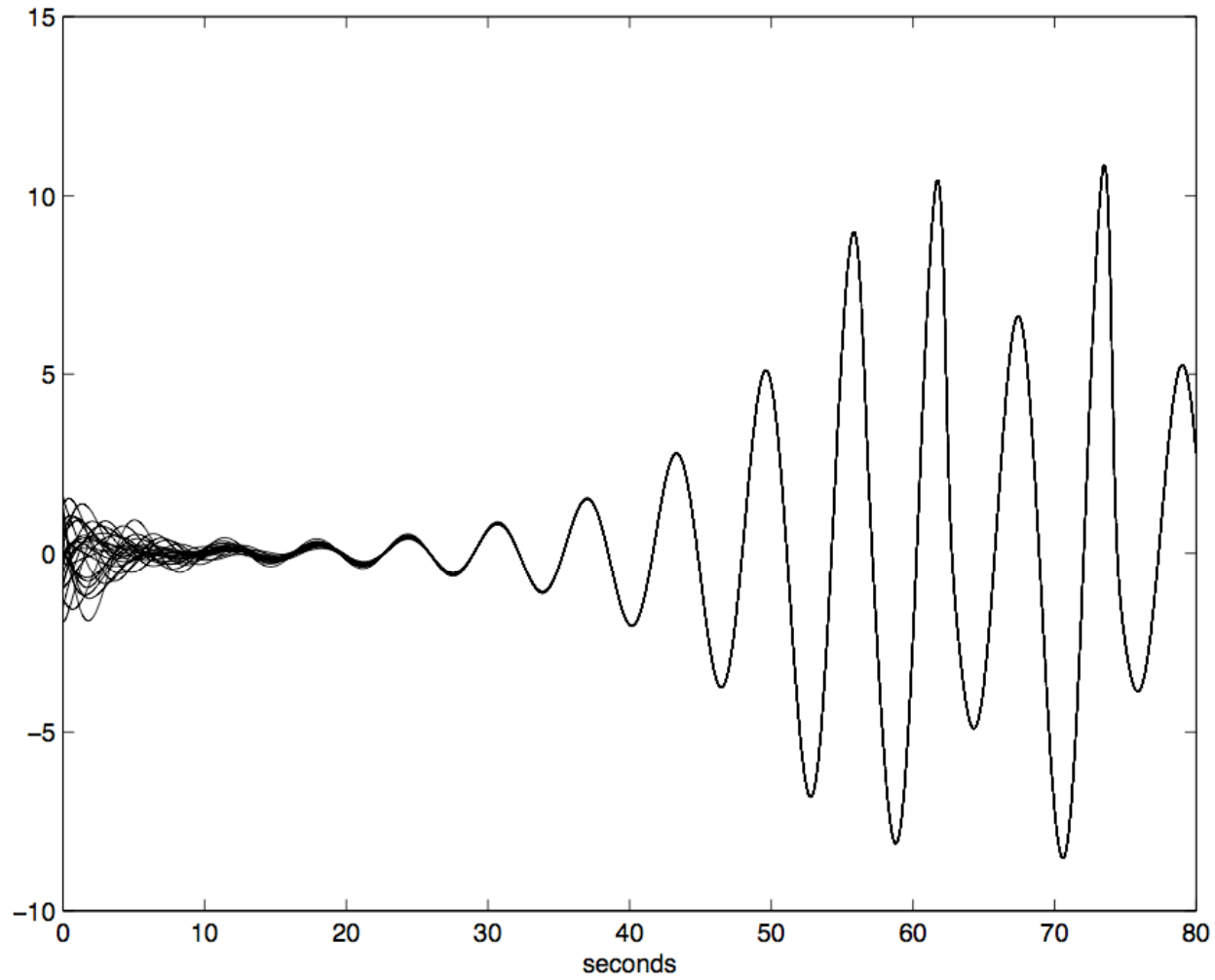


(e)

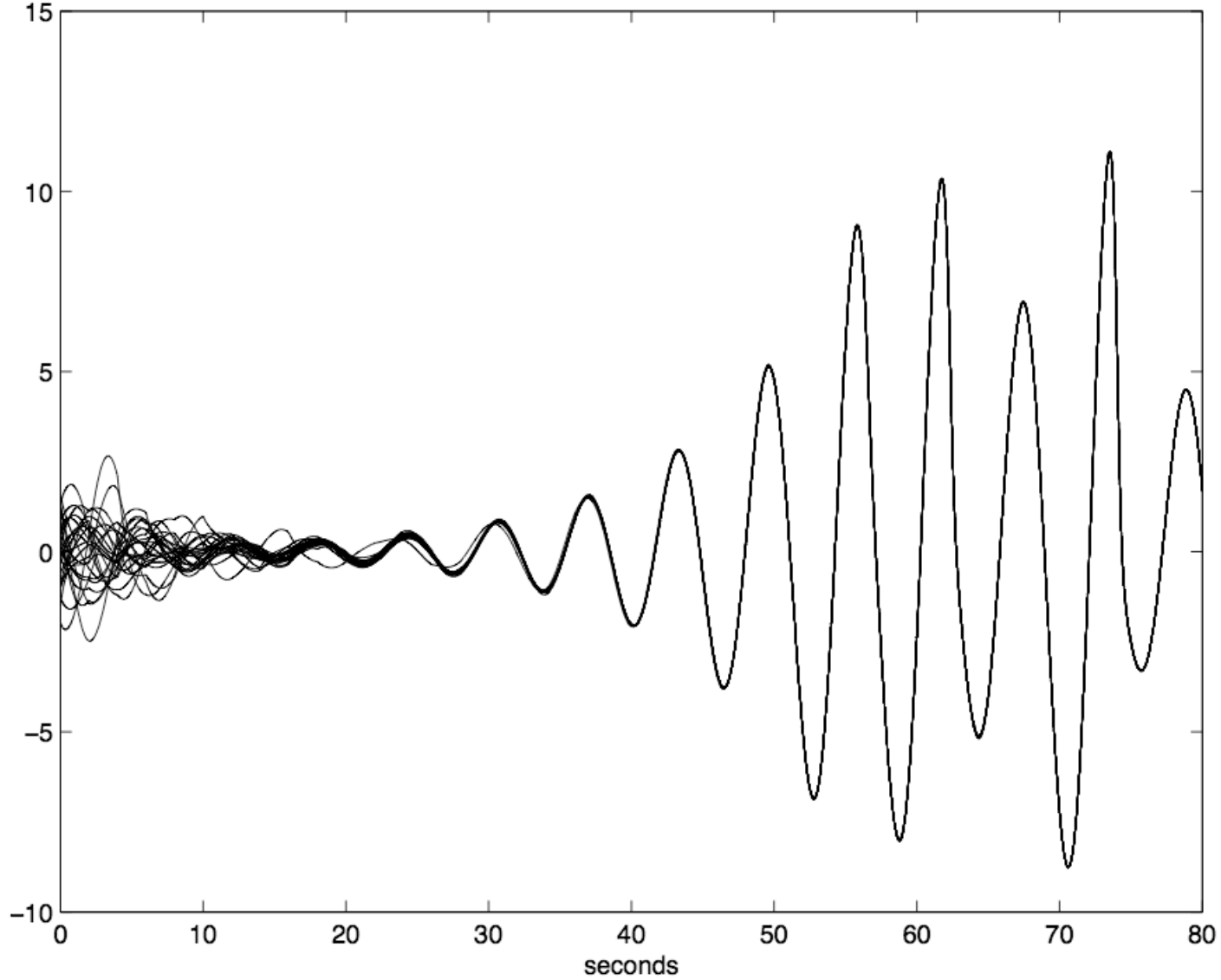


(f)

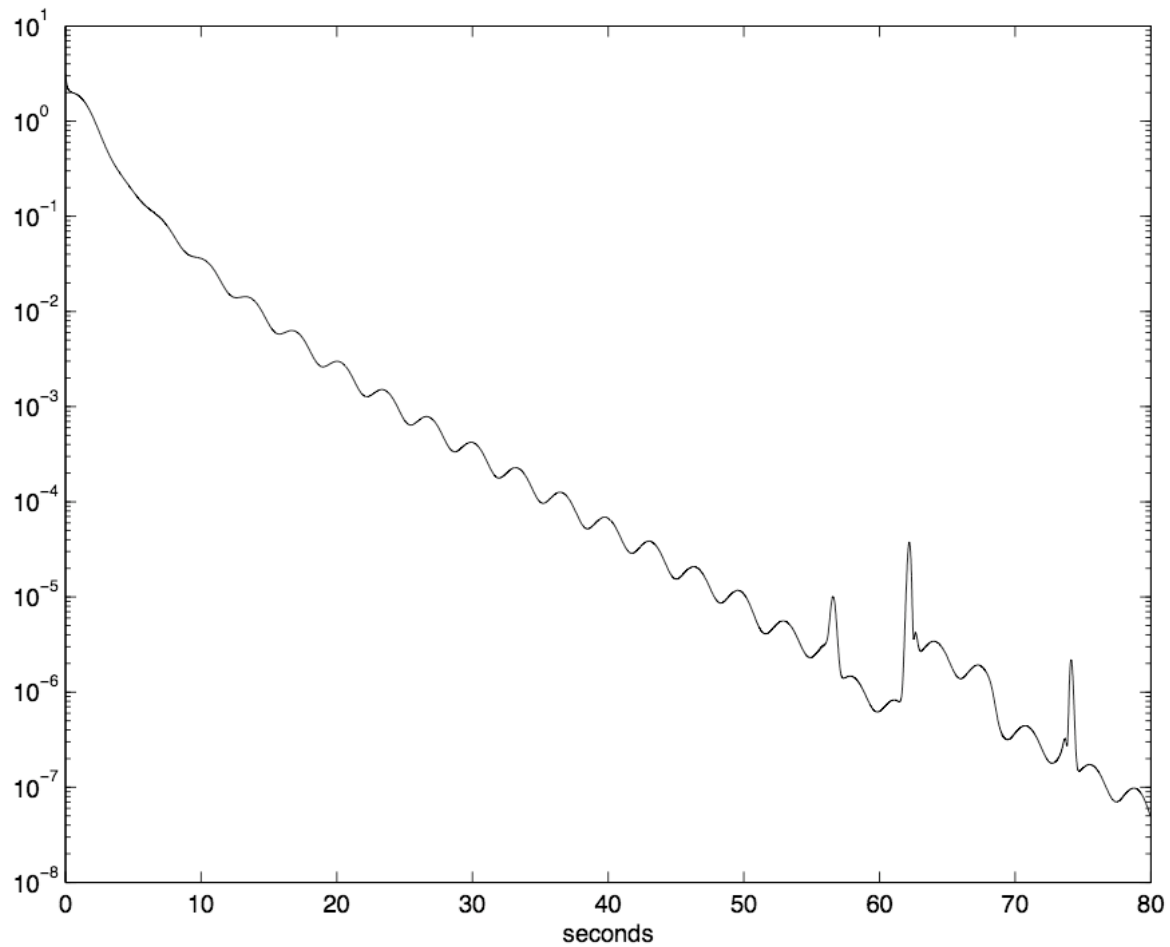
Notice that here, average over the 5 graphs is a connected Graph.



The x -coordinate for the set of coupled Rossler attractors using the average graph Laplacian.



The x -coordinate for the set of coupled Rossler attractors using the switched network where $\varepsilon = 1$.



Root-mean-squared error in for the set of coupled Rossler attractors using the average network \bar{L} .

$$\sum_{i=1}^r (x_i(t) - \mu_x(t))^2 + (y_i(t) - \mu_y(t))^2 + (z_i(t) - \mu_z(t))^2$$

Conclusions

- Fast switching. Sufficient but not necessary.
- Recent average must have some hope of communicating.

Future

- Stochastic and ergodic
- Other information bearing networked systems where connections are only sometimes good.
- Networked blinking control systems

Daniel J. Stilwell, Erik M. Bollt, D. Gray Roberson "Sufficient Conditions for Fast Switching Synchronization in Time Varying Network Topologies ,"
StilwellBolltGray05.pdf nlin.CD/0502055, Submitted to SIAM J. Dynamical Systems, (2005).

J.D. Skufca, E. Bollt, "Communication and Synchronization in Disconnected Networks with Dynamic Topology: Moving Neighborhood Networks,"
nlin.CD/0307010, Mathematical Biosciences and Engineering (MBE), 1 (2) 347 (2004).

More on Master Stability Function For static networks

*Barahona-Pecora-'02,
master stability function*

Graph Laplacian matrix L has n -eigenvalues

$$0 = \lambda_0 \leq \dots \leq \lambda_{n-1} = \lambda_{\max}$$

Stability reduces by linear perturbation analysis to a constraint on eigenvalues of the Laplacian,

$$\sigma \lambda_i \in (\alpha_1, \alpha_2), \forall i = 1, \dots, n-1 \quad (\alpha_1, \alpha_2) \text{ depends on specific oscillator}$$

For small, σ sync. unstable if, $\sigma \lambda_1 < \alpha_2$ As

$\sigma \uparrow$ instability arises if $\sigma \lambda_{\max} > \alpha_2$

So, there is a synchron coupling parameter σ if $\frac{\lambda_{\max}}{\lambda_1} < \frac{\alpha_2}{\alpha_1} := \beta$

Moving Average Laplacian, for time varying networks - Weighting Memory

Skufca, Bollt, '04

Instead of instantaneous adjacency matrix, $A(t)$, use a moving averaged adjacency matrix,

$$\Lambda(t) = e^{\int_0^t qA(\tau) d\tau} z_0 \quad \text{which solves, } \dot{z} = qA(\tau)z, z(0) = z_0 \quad \text{and its Laplacian spectrum}$$