

**A new approach to statistical closure for  
complex deterministic dynamics**

Bruce Turkington  
Univ. of Massachusetts Amherst

Petr Plechac  
Univ. of Tennessee / Oak Ridge National Lab.

## Motivation

“Coarse-graining” and “subgrid-scale parameterization” abstracted to their mathematical essence:

- Choose a set of resolved variables that describe the macroscopic states of a complex dynamical system
- Identify macrostates with the ensemble-averaged resolved variables, and relegate unresolved variables to an appropriate statistical description
- Derive a closed set of equations for the evolution of those macrostates from the given microscopic dynamics

Statistical mechanics should furnish the natural tools for connecting microscopic dynamics to macroscopic behavior.

But a general theory of nonequilibrium statistical mechanics is not yet developed, and known techniques tend to focus on specially designed models.

For these reasons, we address the following generic problem:

\* Consider a nonlinear Hamiltonian system with many degrees of freedom, and choose resolved dynamical variables. For instance,

- For a coupled system of oscillators, the coordinates of a few heavy particles interact with many light particles
- For a dispersive wave system, the energy spectrum in some selected bands of the many interacting modes

\* Derive a statistical closure for the resolved dynamics that is consistent with the chaotic deterministic dynamics, without interposing a stochastic model of the unresolved variables.

Many multiscale problems that fall under the broad category of “turbulence” require such statistical closures, systematic model reductions and approximation schemes.

## Background

The microstate is a point  $z$  in a *phase space*  $\Gamma$ :

$$z = (q_1, p_1, \dots, q_n, p_n)^* \in \Gamma = R^{2n}, \quad n \text{ is large}$$

The microscopic dynamics is *Hamiltonian*:

$$\frac{dz}{dt} = J \nabla_z H(z), \quad \text{that is,} \quad \frac{dq_j}{dt} = \frac{\partial H}{\partial p_j}, \quad \frac{dp_j}{dt} = -\frac{\partial H}{\partial q_j},$$

Any *dynamical variable*  $F : \Gamma \rightarrow R$  evolves under

$$\frac{dF}{dt} = \{F, H\} = (\nabla_z F)^* J \nabla_z H = \sum_j \frac{\partial F}{\partial q_j} \frac{\partial H}{\partial p_j} - \frac{\partial F}{\partial p_j} \frac{\partial H}{\partial q_j}$$

The Hamiltonian dynamics defines a *phase flow* on  $\Gamma$ :

$$\Phi(t) : \Gamma \rightarrow \Gamma, \quad \text{where} \quad z(t) = \Phi(t)(z(0))$$

Probability on  $\Gamma$  flows with  $\Phi$ : an *ensemble* of microscopic paths described by a probability measure  $p(dz, t)$  satisfies

$$p(\Phi(t)(G), t) = p(G, 0) \quad \text{for every } G \subset \Gamma.$$

In terms of probability density  $\rho(z, t) = dp/dz$ , the ensemble flow is governed by *Liouville's equation*:

$$\frac{\partial \rho}{\partial t} + L\rho = 0, \quad \text{with } L\cdot = \{\cdot, H\}$$

The exact solution,  $\rho(t) = e^{-tL}\rho(0)$ , is extremely intricate and expensive to compute unless the dynamics is low-dimensional.

Instead we desire an approximation to  $\rho(z, t)$  that is parametrized by the statistical averages of some *resolved variables*

$$A = (A_1, \dots, A_m)^* \quad (\text{each } A_j : \Gamma \rightarrow R)$$

## Equilibrium and nonequilibrium ensembles

Very long time average behavior is described by invariant densities such as the equilibrium canonical ensemble

$$\rho_{eq}(z) = \exp(-\beta[H(z) - f(\beta)])$$

with inverse temperature  $\beta > 0$  and free energy

$$f(\beta) = -\beta^{-1} \log \int_{\Gamma} \exp(-\beta H(z)) dz$$

For a *vector of resolved variables*  $A : \Gamma \rightarrow R^m$  that are *not* invariants, a natural choice for a nonequilibrium ensemble is

$$\tilde{\rho}(z, \lambda) = \exp[\lambda^* A(z) - \phi(\lambda)] \rho_{eq}(z)$$

where

$$\phi(\lambda) = \log \int_{\Gamma} \exp(\lambda^* A(z)) \rho_{eq}(z) dz \quad \text{for } \lambda \in R^m$$

Provided that  $A$  contains the “slow” dynamical variables, we attempt to approximate the exact density  $\rho(t)$  by the *trial density*  $\tilde{\rho}(\lambda(t))$  with slowly evolving parameter vector  $\lambda(t)$ .

Two interpretations of  $\tilde{\rho}(z, \lambda) = \exp[\lambda^* A(z) - \phi(\lambda)] \rho_{eq}(z)$ :

**Physics:** Each  $\tilde{\rho}$  is a *quasi-equilibrium ensemble*, which results from maximizing entropy

$$S(\tilde{\rho}) = - \int_{\Gamma} \tilde{\rho}(z) \log \frac{\tilde{\rho}(z)}{\rho_{eq}(z)} dz$$

given instantaneous mean values of the resolved variables

$$\int_{\Gamma} A(z) \tilde{\rho}(z) dz \doteq \langle A | \tilde{\rho} \rangle = a$$

The vector observable  $a \in R^m$  is the macrostate in the coarse-grained description.

**Statistics:**  $\tilde{\rho}$  is an *exponential family with natural parameter*  $\lambda$ .  $A$  is a minimal sufficient statistic for this parametric model.

## Adiabatic closure

A naive way to evolve the parameter  $\lambda(t) \in R^m$  is to impose  $A_1, \dots, A_m$  moments of the Liouville equation:

$$\frac{d}{dt} \langle A | \tilde{\rho} \rangle - \langle LA | \tilde{\rho} \rangle = \int_{\Gamma} A \left( \frac{\partial}{\partial t} + L \right) \tilde{\rho} dz = 0.$$

But this closed reduced dynamics conserves entropy exactly:

$$\frac{d}{dt} S(\tilde{\rho}) = - \frac{d}{dt} [ \lambda^* a - \phi(\lambda) ] = \int_{\Gamma} L e^{\lambda^* A - \phi(\lambda)} \rho_{eq} dz = 0.$$

The fundamental deficiency is that this closure is memoryless, whereas unresolved fluctuations influence macroscopic evolution over a finite time until they equilibriate.

Zubarev (1970s) proposed using “nonequilibrium statistical operators” with decaying memory

$$\rho(t) = \exp \left( \int_0^{+\infty} \lambda(t - \tau) A \circ \Phi(-\tau) e^{-\alpha\tau} \alpha d\tau - \psi[\lambda](t) \right) \rho_{eq}$$

## Best-fit closure

Retain the trial densities  $\tilde{\rho}$ , and evaluate the *Liouville residual*:

$$R \doteq \left( \frac{\partial}{\partial t} + L \right) \log \tilde{\rho}(\lambda(t)) = \dot{\lambda}(t)^*(A - a(t)) + \lambda(t)^*LA$$

Two expressions for  $R = R(z; \lambda, \dot{\lambda})$ :

(1) At any microstate  $z \in \Gamma$ , consider the information for discrimination between the exact density and the trial density after a time increment  $\theta$ :

$$\log \frac{e^{-\theta L} \tilde{\rho}(z, \lambda(t))}{\tilde{\rho}(z, \lambda(t + \theta))} = -\theta R(z) + O(\theta^2) \quad \text{as } \theta \rightarrow 0.$$

(2) For any observable  $B$ , consider the evolution of the ensemble-averaged  $B$  with respect to the trial density:

$$\frac{d}{dt} \langle B | \tilde{\rho}(\lambda(t)) \rangle - \langle LB | \tilde{\rho}(\lambda(t)) \rangle = \langle BR | \tilde{\rho}(\lambda(t)) \rangle$$

The statistic  $R$  represents instantaneous “information loss rate” for  $\tilde{\rho}(\lambda)$  along a parameter trajectory  $\lambda(t)$ .

Separate the Liouville residual into its orthogonal components along the resolved and unresolved subspaces of  $L^2(\Gamma, \tilde{\rho}(\lambda))$ :

$$\begin{aligned} R &= P_\lambda R + Q_\lambda R \\ &= [\dot{\lambda} - C(\lambda)^{-1} \langle LA | \tilde{\rho}(\lambda) \rangle]^* (A - a) + \lambda^* (Q_\lambda LA) \end{aligned}$$

where  $C(\lambda) = \langle (A - a)(A - a)^* | \tilde{\rho}(\lambda) \rangle$  (Fisher information matrix).

Define the following lack-of-fit functional for this residual:

$$\int_{t_0}^{t_1} \mathcal{L}(\lambda, \dot{\lambda}) dt = \frac{1}{2} \int_{t_0}^{t_1} \langle (P_\lambda R)^2 | \tilde{\rho}(\lambda) \rangle + \epsilon^2 \langle (Q_\lambda R)^2 | \tilde{\rho}(\lambda) \rangle dt.$$

$\epsilon \in (0, 1]$  is an adjustable parameter in the “Lagrangian”  $\mathcal{L}(\lambda, \dot{\lambda})$ .

Our *best-fit closure* minimizes this “action” over trajectories  $\lambda(t)$ ,  $t_0 \leq t \leq t_1$ , in the coarse-grained parameter space  $R^m$ .

The predicted macrostate at time  $t_1$  corresponds to  $\lambda(t_1)$ .

Best-fit reduced dynamics is deduced from the *value function*:

$$v(\lambda_1, t_1) = \min_{\lambda(t_1)=\lambda_1} v_0(\lambda(t_0)) + \int_{t_0}^{t_1} \mathcal{L}(\lambda, \dot{\lambda}) dt$$

This minimization is over parameter trajectories  $\lambda(t) \in R^m$ ,  $t_0 \leq t \leq t_1$  having terminal point  $\lambda_1$  at terminal time  $t_1$ .

$v_0(\lambda)$  is a given penalty function on the initial parameter  $\lambda(t_0)$ .

$v(\lambda_1, t_1)$  assigns an optimal lack-of-fit to any feasible pair  $(\lambda_1, t_1)$ .

The value function  $v$  quantifies the propagation of uncertainty due to coarse-graining the Hamiltonian microdynamics via the resolved vector  $A$ .

$v$  depends on the “*relevance factor*”  $\epsilon$  in the lack-of-fit metric.

An analysis using the Mori-Zwanzig memory kernel relates  $\epsilon$  to the separation of relevant time scales:

$$\epsilon \sim \frac{\tau_{memory}}{\tau_{plateau}} \sim \frac{\tau_{plateau}}{\tau_{relaxation}}$$

The value function  $v(\lambda, t)$  solves the *Hamilton-Jacobi equation*

$$\frac{\partial v}{\partial t} + \mathcal{H}\left(\lambda, \frac{\partial v}{\partial \lambda}\right) = 0, \quad \text{with } v(\lambda, t_0) = v_0(\lambda),$$

where  $\mathcal{H}(\lambda, \mu)$  is the Legendre transform of  $\mathcal{L}(\lambda, \dot{\lambda})$ ,

$$\mu = \frac{\partial \mathcal{L}}{\partial \dot{\lambda}}, \quad \mathcal{H} = \dot{\lambda}^* \mu - \mathcal{L}(\lambda, \dot{\lambda}).$$

$\mathcal{H}$  is explicitly calculable because  $\mathcal{L}$  is quadratic in  $\dot{\lambda}$ .

The conjugate variable  $\mu = \langle AR | \tilde{\rho} \rangle$  is the irreversible flux of  $A$ .

The best-fit prediction is the  $v$ -minimizing parameter trajectory

$$\hat{\lambda}(t) = \arg \min_{\lambda} v(\lambda, t).$$

The best-fit macrostate is

$$\hat{a}(t) = \langle A | \tilde{\rho}(\hat{\lambda}(t)) \rangle = \frac{\partial \phi}{\partial \lambda}(\hat{\lambda}(t)).$$

## Summary of general closure scheme

Given a coarse-graining defined by the resolved vector  $A$ , and the associated family of trial densities  $\tilde{\rho}(\lambda)$ ,

- \* Construct the lack-of-fit Lagrangian  $\mathcal{L}$  and its Hamiltonian  $\mathcal{H}$ ;
- \* Solve the Hamilton-Jacobi equation for the value function  $v$ ;
- \* Derive the closed set of first-order differential equations for the best-fit parameter  $\hat{\lambda}(t)$ , and hence the predicted macrostate  $\hat{a}(t)$ .

The best-fit macroscopic dynamics is calculated without simulation of any microscopic solutions.

There is a single parameter  $\epsilon$  that is tuned to produce the correct dissipation.

The uncertainty in the best-fit prediction is quantified by the value function.

## Near equilibrium approximation

The best-fit reduced equations are linear relaxation equations near equilibrium.

Normalize  $A$  relative to equilibrium  $\rho_{eq}$ ,  $\langle A \rangle_{eq} = 0$ ,  $\langle AH \rangle_{eq} = 0$ , so that from any small initial disturbance  $\lambda_0 \neq 0$  the system relaxes toward equilibrium  $\rho_{eq}$ :  $\lambda(t) \rightarrow 0$  as  $t \rightarrow \infty$ .

Linear response approximation pertains to small  $|\lambda|$  :

$$\begin{aligned}\langle F | \tilde{\rho}(t) \rangle &= \langle F [1 + \lambda(t)^* A] \rangle_{eq} + O(|\lambda|^2) \\ &\approx \langle F A^* \rangle_{eq} \lambda(t)\end{aligned}$$

for any dynamical variable  $F$  with  $\langle F \rangle_{eq} = 0$ .

The Lagrangian (running cost) is a quadratic form

$$\mathcal{L}(\lambda, \dot{\lambda}) \approx \frac{1}{2} [\dot{\lambda} - C^{-1} J \lambda]^* C [\dot{\lambda} - C^{-1} J \lambda] + \frac{\epsilon^2}{2} \lambda^* D \lambda,$$

with coefficient matrices

$$C = \langle A A^* \rangle_{eq}, \quad J = \langle (L A) A^* \rangle_{eq}, \quad D = \langle (Q L A) (Q L A)^* \rangle_{eq}$$

## Best-fit linear irreversible reduced dynamics

The predicted evolution of the macrostate is governed by

$$\frac{d\hat{a}}{dt} = \left[ J - \epsilon^2 CG(t; \epsilon)D \right] C^{-1}\hat{a} \quad \text{with} \quad \hat{a}(0) = a_0,$$

where the matrix  $G = G(t; \epsilon)$  solves the Riccati equation

$$\frac{dG}{dt} = JC^{-1}G - GC^{-1}J - \epsilon^2 GDG + C^{-1} \quad \text{with} \quad G(0) = 0.$$

The value function is the time-varying quadratic form

$$v(\lambda, t) = \frac{1}{2}(\lambda - \hat{\lambda}(t))^* G(t; \epsilon)^{-1} (\lambda - \hat{\lambda}(t)) + \hat{v}(t)$$

If the variables  $A$  are even under time reversal, then  $J = 0$  and this closed reduced dynamics is analogous to *linear irreversible thermodynamics*:

- The matrix of transport coefficients  $\epsilon^2 CG(t; \epsilon)D$  is positive-definite and symmetric (Onsager reciprocity relations).
- The entropy  $\hat{s} = -\frac{1}{2}\hat{a}^* C^{-1}\hat{a}$  is monotonic increasing in time.

## Basic numerical test problem: Kac-Zwanzig model

Consider a coupled system of  $n = 1 + N$  classical oscillators, having Hamiltonian

$$H = \frac{1}{2M}P^2 + \frac{1}{2}Q^2 + \frac{\eta}{4}Q^4 + \sum_{k=1}^N \frac{1}{2}p_k^2 + \frac{1}{2}\omega_k^2 \left( q_k - \frac{\gamma}{\omega_k^2}Q \right)^2$$

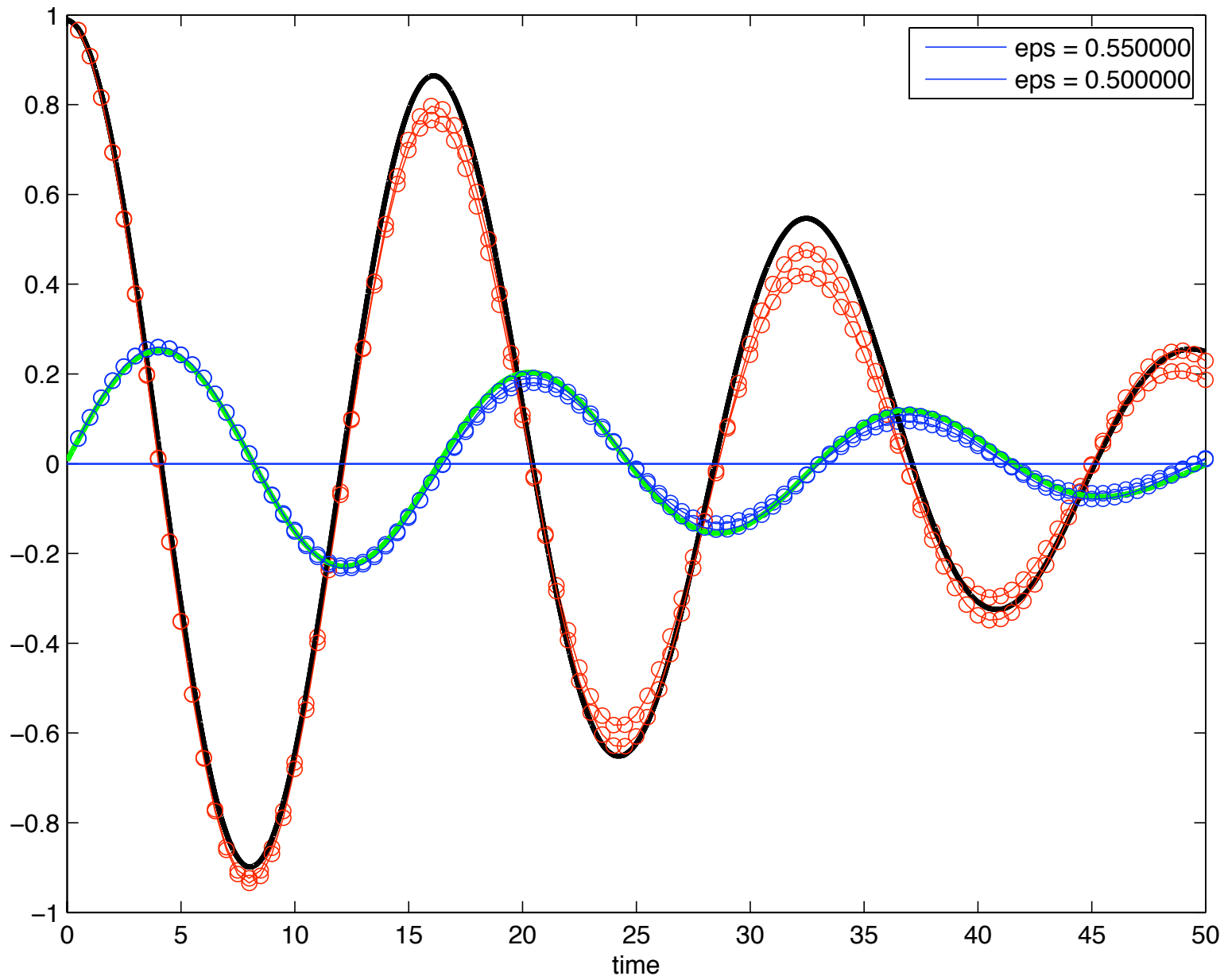
A single slow quartic oscillator is linearly coupled to  $N$  fast harmonic oscillators.

Select the resolved vector to be  $A = (P, Q)^*$  for the single particle with mass  $M > 1$ . “Heat bath” of  $N = 20$  particles with coordinates  $(p_k, q_k)$  and unit mass are unresolved.

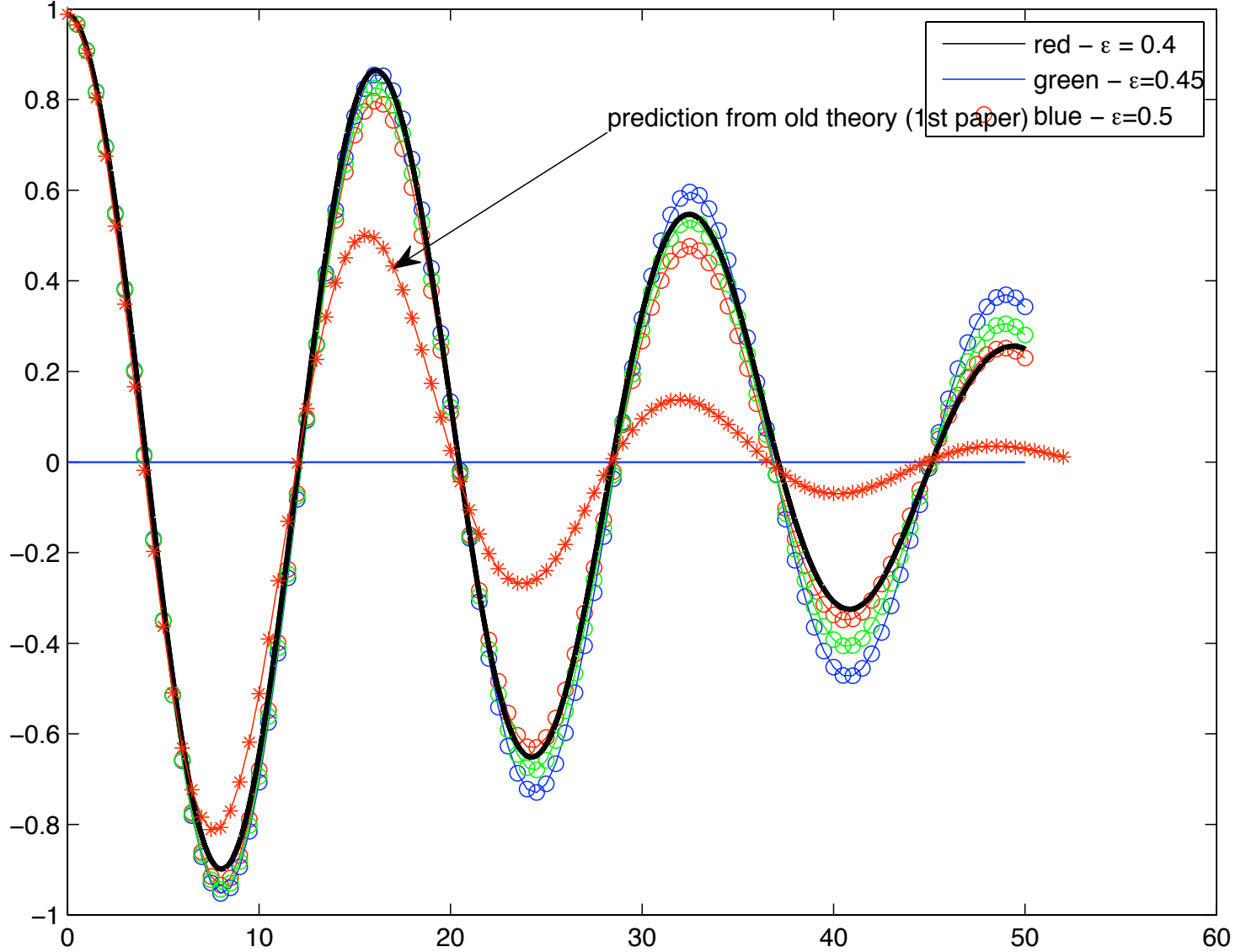
In computed examples, the frequencies  $\omega_k$  are sampled from a gamma distribution with mean  $\approx 30$  and shape factor 3; coupling  $\gamma = 1$ , and nonlinearity  $\eta = 0.5$ .

The equilibrium ensemble with  $\beta = 1$  is simulated using an MCMC algorithm with between  $10^4$  to  $10^5$  samples.

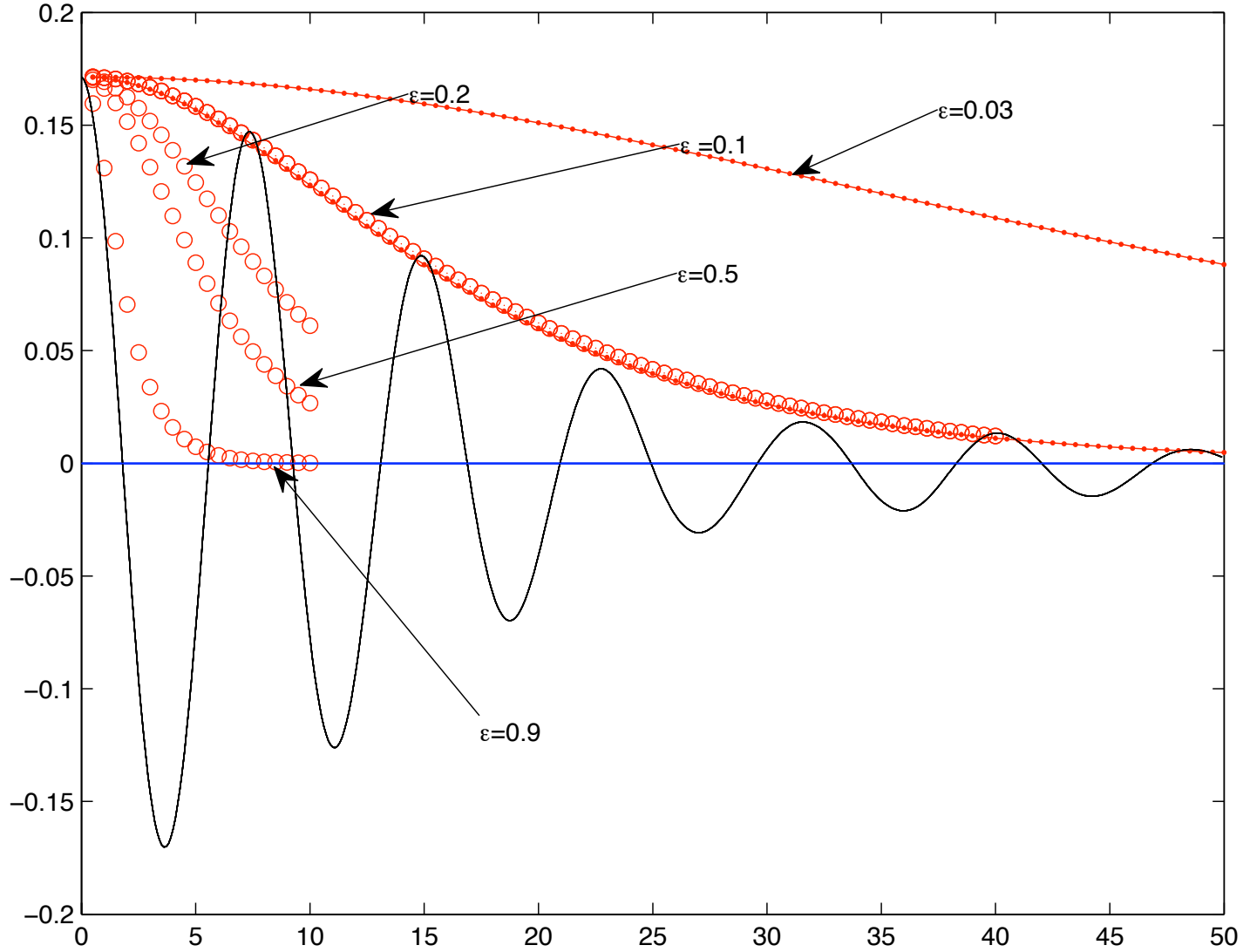
Relaxation of reduced system: Simulated (observables): k, Reduced system: blue o



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## Conclusions

- \* Best-fit closure using quasi-equilibrium ensembles offers a systematic alternative to the traditional closure schemes that truncate a moment hierarchy.
- \* Given a coarse-graining and a lack-of-fit metric, the best-fit prediction and its uncertainty are controlled by a value function, which propagates under a Hamilton-Jacobi PDE.
- \* In the near equilibrium regime, the theory produces linear relaxation equations whose transport matrices are derived from the underlying dynamics up to a single adjustable parameter.
- \* A future goal is to apply this approach to specific subgrid-scale parameterizations and turbulence problems, including geophysical fluid dynamics,